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PREFACE

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This issue contains the information published during **February, 2018**. The arrangement of the contents is alphabetical. The full text of the article which is either subscribed by the university or available in the web is provided in this bulletin.

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A Grey Wolf Optimization Based Algorithm for Optimum Camera Placement

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Abstract
Camera placement is very important for surveillance applications. Proposed work presents a new method of optimum placement of visual sensors for maximum coverage of the predefined surveillance space. The surveillance space is modeled as priority areas (PAs), obstacles and feasible locations for placement of cameras. We are using PTZ (pan, tilt, zoom) cameras, which not only reduces occlusion due to randomly moving objects in the PA but also increases the covered area compared to pin hole cameras. The proposed approach will be useful for crowd monitoring in a big surveillance space holding multiple events and having multiple entrances. The problem of optimum camera placement for maximum coverage considering both static and randomly moving obstacles is mapped as a Grey Wolf Optimization (GWO) problem. The proposed algorithm is computationally lighter and converges faster as compared to Genetic Algorithm (GA) based camera placement and Particle Swarm Optimization (PSO) based camera placement algorithm. The concept is validated using simulation as well as the experimental results.

Keywords Camera placement · GWO · Obstacles · Pan · Tilt · Zoom · Priority area · Visual sensors · FoV · Surveillance

1 Introduction

The use of video surveillance has become very popular for investigation purpose as they act as a deterrent of crime. Therefore, surveillance cameras are installed in both indoor and outdoor environments [1, 2]. A camera network is essential for surveillance of indoor or outdoor spaces, as a single camera cannot cover discrete events in a large surveillance

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space. The major challenge for such a camera network is to cover PAs in a surveillance space, like multiple entrances and locations of various important activities, with optimum number of cameras and minimum predefined resolution, considering both static and dynamic occlusion. To cover such multiple distributed events with minimum required resolution, we need an algorithm that determines optimum locations of the cameras along with their pan, tilt and zoom levels [3, 4].

Identifying optimum configuration of camera network for such coverage is a combinatorial optimization problem. It will be difficult for simple search techniques to determine optimum placement configurations [5]. GA [4, 6] and PSO [7] have been used in the past for camera placement problem. Apart from GA and PSO, meta heuristics approach GWO [8] has shown good results in a variety of fields such as relay node (RN) placement problem [9–13], channel estimation in wireless communication [14], photovoltaic systems [15], wireless body area networks [16] and image processing [17]. GWO is inspired by the behaviour of grey wolves to attack the prey for hunting and is preferred by many researchers for optimization purpose because of its fast rate of convergence and robust behaviour [8, 15]. As compared to other optimization algorithms, GWO requires fewer operators and parameters to adjust. GWO has performed better than algorithms like ACO (Ant Colony Optimization), GA and PSO for general optimization problems. This motivated us to use GWO as an optimization algorithm for developing an optimum camera placement strategy. Author's contributions to the paper are as follows.

- In this paper, we propose a camera placement algorithm for covering each PA at least by 3 cameras so as to enhance the information content of images and to reduce the effect of occlusion due to randomly moving obstacles. Even if randomly moving obstacle blocks the PA covered by one camera, the other two cameras will surface our requirement.
- The paper proposes a meta-heuristics approach GWO that optimizes the coverage of discrete PAs in a surveillance space by calculating optimum coordinates of the cameras along with their pan, tilt and zoom levels. GWO is computationally lighter as compared to GA and PSO and is faster in execution.

The article is divided into 7 sections. A literature review is presented in Sect. 2. The problem statement is explained in Sect. 3. Mathematical formulation of the floor plan and coverage matrix are discussed in Sect. 4. GWO mapping with the current problem and GWO implementation are discussed in Sect. 5. Results are explained in Sect. 6. We conclude our work in Sect. 7.

2 Literature Review

Several approaches have been proposed in the past to solve optimum guard location problem for a polygon area, for example, art gallery problem (AGP) [5] [18–20] that aims to visualize maximum area with minimum number of guards. The solutions presented to AGP were based on assumptions like unlimited field of view and infinite servo precision that makes them unsuitable for real world applications. The effects of random occlusion in offline camera placement were initially addressed by [21] which was later continued by [22] using a pin hole camera. Authors in [23] used binary integer programming (BIP) method for optimizing the orientations of a PTZ camera. The BIP method is computationally

complex and is not useful for large number of cameras. Authors in [24] used cheap motion sensors for real time control of PTZ cameras, but they did not optimize pan and tilt angles of a PTZ camera and also compromised with the image quality. Authors in [25] addressed the problem of detecting an unexpected activity from a large surveillance space. Foreground extraction method was adopted to mark people and objects in a surveillance space. Outliers from the daily surveillance patterns of a city were identified and considered as unexpected activity or area of interest. Authors in [26] used GA for optimizing pan and tilt angles of a PTZ camera for photogrammetric network. However, the algorithm is too complex to be used for 3D spaces. Authors in [4] used GA to optimally cover discrete PAs in a surveillance space with minimum required zoom incorporating the static obstacles. Authors in [7] used PSO to find the optimum camera orientations for 2D space by keeping the camera location fixed. Authors in [27] presented a camera placement approach that aims at minimizing the occlusion for object detection and tracking applications. Authors in [28] presented a framework that finds optimum number of sensors with their locations and orientations in a 3D terrain having multiple objectives. The framework finds a trade-off between conflicting objectives of covering maximum area at a low acquisition cost of sensor deployment. Authors in [29] proposed a video surveillance system based on face detection and recognition method that collects videos from multiple surveillance cameras to track and detect people over space and time. Authors in [30] used simulated annealing to find optimum camera configurations in a multi-camera system. The algorithm performs similar to BIP for small scale problems but performs better than BIP for large scale problems. Authors in [31] proposed a two phase camera placement algorithm based on BIP to find optimum camera coordinates in a large surveillance space. Phase 1 finds minimum number of cameras to cover a surveillance space while phase 2 achieves maximum coverage with the cameras established from phase 1. A low cost camera placement algorithm for bridge surveillance was proposed in [32]. They used uniqueness score and local search algorithm (ULA) that gives greater importance to the areas often left uncovered by other cameras. ULA yields better results than greedy algorithm and GA in terms of coverage and average surveillance cost.

Camera placement problem in a surveillance space is analogous to RN placement problem in WSN. Authors in [9–13] addressed RN placement problem using meta heuristic algorithms. In [9], if a part of network is damaged, the number of packets reaching the sink is decreased. So for correcting such cases, RNs are optimally placed using GWO to reactivate the network. GWO was used again in [10] to optimize the placement of RNs in a WSN. They used convex hull approach to restrict the deployment area of RNs and used alpha shapes to identify the structure and boundary of obstacles. Authors in [11] used BAT algorithm, interior search algorithm and moth flame optimizer to find the optimum location of RNs to achieve full coverage. Among the three bio-inspired algorithms used in [11], MFO required the least number of RNs to cover the entire deployment region. Authors in [12] used PSO to optimally place RNs in a WSN. They focused on minimizing the average distance between a RN and a sensor node to achieve an energy efficient network. An enhanced Ant Bee Colony (ABC) based RN deployment algorithm was proposed in [13] to extend the lifetime of a network. The first phase of the algorithm includes construction of network backbone structure by deploying RNs in the network, while in the second phase; the RNs are optimally placed using ABC. Although similar, relay node placement does not use directional sensors like a camera. We consider camera sensor that involves optimization of a variety of parameters like its location, pan angle, tilt angle and zoom level.

The proposed camera placement algorithm enhances the information content of images as well as reduces the effects of randomly moving obstacles. Also, the proposed method

is using a better optimization technique (GWO) which converges faster than the existing methods.

3 Problem Statement

Monitoring large surveillance space having distributed multiple activities with a predefined resolution is a challenging task. The aim of the proposed work is to determine the optimum location, pose (pan and tilt angles) and zoom level of each camera to achieve maximum coverage of all predefined PAs of a large surveillance space satisfying the task-based constraints which may be static or dynamically varying according to the requirements. The major constraint is covering all distributed PAs by at least 3 cameras for capturing maximum information content in the images. This problem is mapped as an optimization problem. The proposed algorithm is computationally simple as the methodology is based neither on calibration of cameras nor on learning environment.

3.1 Coverage of Priority Points

Past research [4] had considered only static obstacles and the effects of randomly moving obstacles were overlooked. In order to achieve optimum coverage of the PAs in a large surveillance space with N cameras and randomly moving obstacles, we propose each PA to be covered by a minimum of 3 cameras. Let us consider the PAs in a large surveillance space covered by 3 cameras (Fig. 1), the following cases may occur.

3.1.1 Case I—Pillar as an Obstacle

In Fig. 1a we have 4 PAs, 3 cameras and one obstacle. Even with the presence of big obstacle like a pillar, we could place the cameras in such a way that all PAs are covered by 3 cameras from different angles.

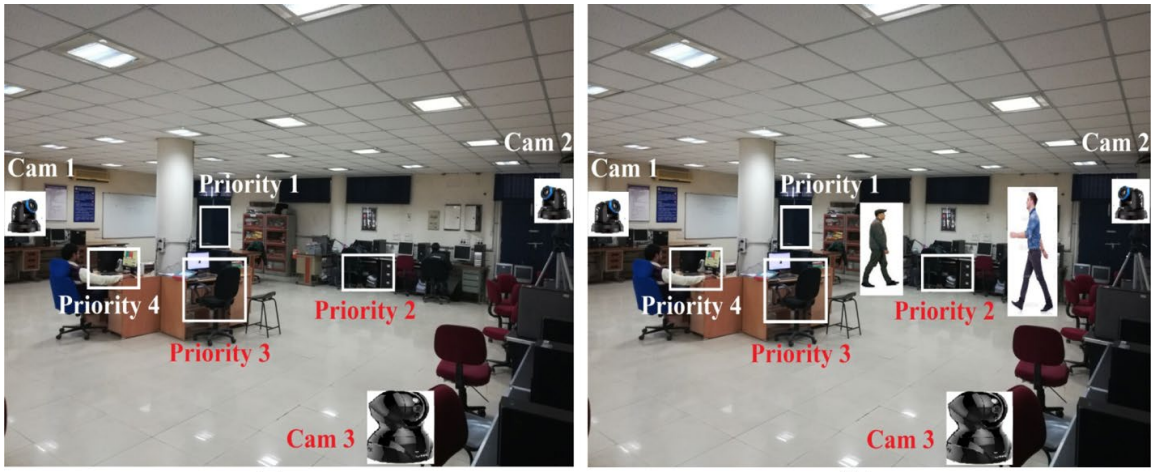


Fig. 1 **a** All PAs covered by 3 cameras. **b** FoV of cam 1 and cam 2 blocked by randomly moving obstacles (men)

3.1.2 Case II—View of 2 Cameras Blocked by Random Obstacles at Different Times

Figure 1b shows that the randomly moving obstacles (men in this case) block the view of cam 1 and cam 2 at time t_1 and t_2 respectively ($t_1 \neq t_2$). In this case, cam 3 and either of cam 1 or cam 2 cover PA 2 from different angles.

3.1.3 Case III—View of 2 Cameras Blocked by Random Obstacles at the Same Time

Figure 1b shows the worst case scenario where randomly moving obstacles (men) block the view of cam 1 and cam 2 at the same time t. Even in the worst-case scenario, PA 2 is covered by one camera (cam 3).

We propose a camera placement algorithm that covers all predefined PAs with minimum 3 cameras to reduce the effects of occlusion due to randomly moving obstacles. This also improves information content in images as the surveillance area is covered from 3 different angles. The angle between field of view (FoV) of adjacent cameras is equal to or slightly greater than 60 degrees to allow cameras to cover a larger space.

3.2 Camera Model

PTZ camera is used to capture images as it can cover bigger space in comparison to a pin hole camera as it is panning continuously. Some of the important parameters of PTZ camera are following.

FoV of a simple camera is presented in Fig. 2a. PTZ camera can rotate at an angle of $\pm\theta$ along its tilt and pan axis to have an extended FoV as shown in Fig. 2b.

Figure 3a shows the camera model used in [23]. A rotation along x-axis corresponds to tilt (θ_1) while a rotation around y-axis corresponds to pan (θ). Figure 3b shows the camera model used in this work incorporating zoom limits as a function of depth of view. The depth of view is the distance between the nearest and the farthest object appearing in the FoV of a camera. The nearest and the farthest distance are denoted by near focus plane and far focus plane respectively as shown in Fig. 3b.

In the proposed algorithm, we aim to cover each PA by 3 cameras. Figure 4a shows that the PA c is covered by FoV of 3 cameras Cam 1, Cam 2, and Cam 3. We introduce the concept of line of sight of a camera that helps us to figure out the effect of an obstacle on the

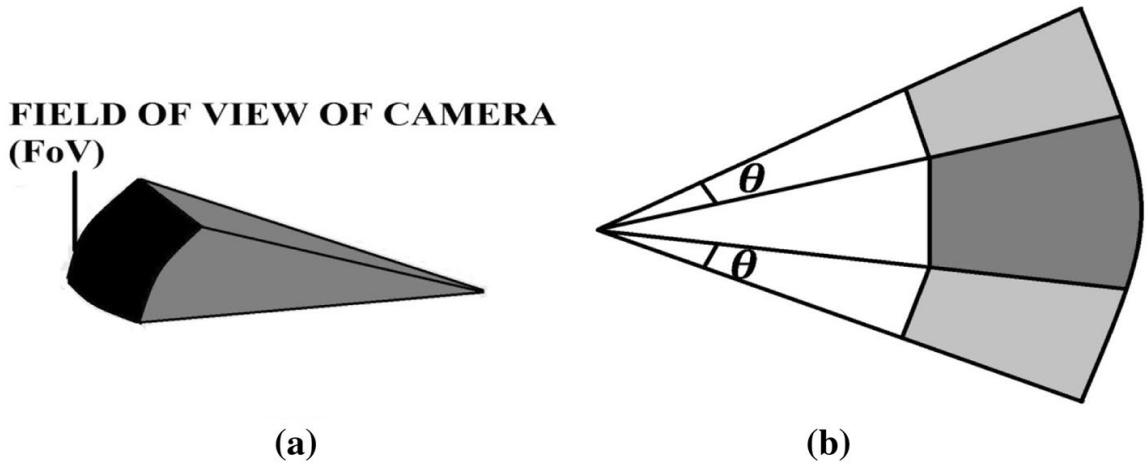


Fig. 2 **a** FoV of a simple camera. **b** Extended FoV of a PTZ camera

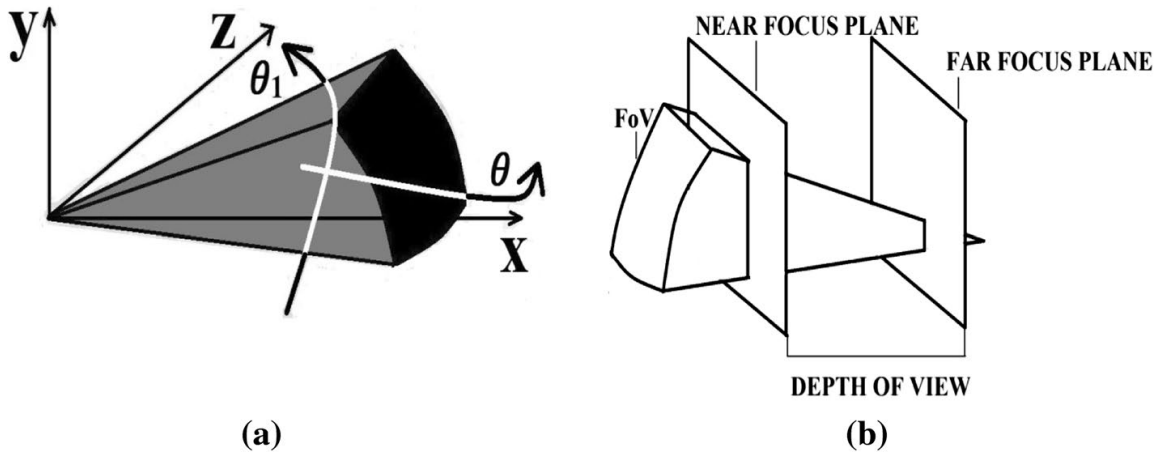


Fig. 3 **a** Camera model used in [23]. **b** The depth of view of a PTZ camera

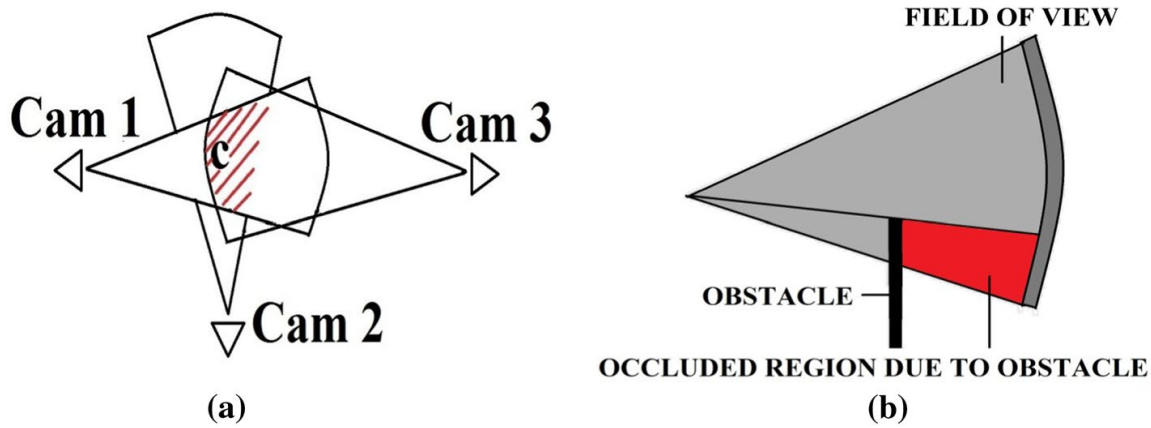


Fig. 4 **a** PA c covered by 3 cameras. **b** FoV occluded by an obstacle

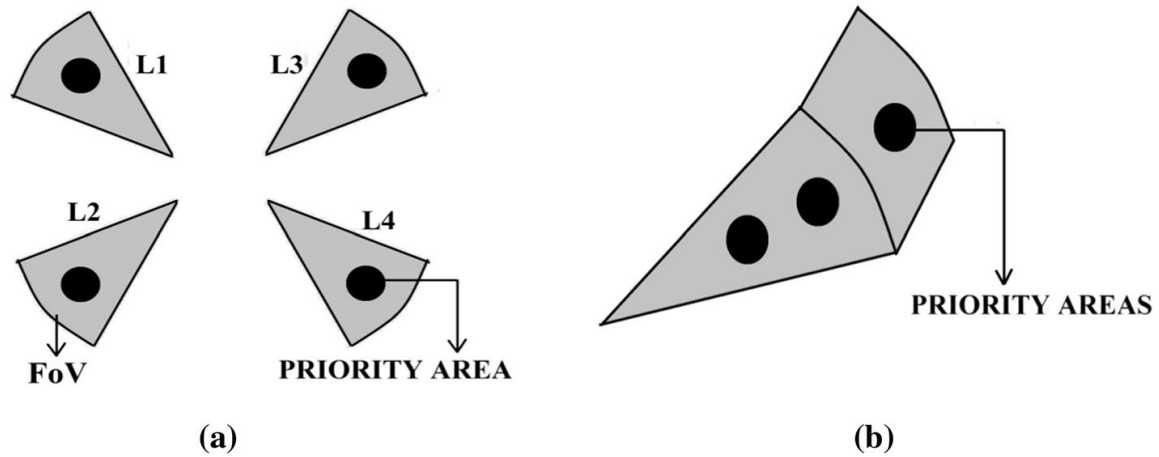


Fig. 5 **a** Multiple cameras required to cover distributed PAs. **b** Single camera covering all PAs

FoV of a camera. If an obstacle occludes the FoV of a camera from the line of sight, the occluded coverage area is removed from the FoV as shown in Fig. 4b.

Let us imagine there are 4 discrete PAs located at L1, L2, L3 and L4 in the surveillance space as shown in Fig. 5a. Coverage of these discrete PAs depends on their distribution in the

surveillance space and location of the cameras. For instance, we need 4 cameras to cover the PAs shown in Fig. 5a while the PAs in Fig. 5b can be covered using a single camera. The proposed work aims to achieve optimum location of the camera for covering maximum such PAs.

3.3 Surveillance Space Model

Surveillance space is modeled in terms of cubical grids. A point in the surveillance space is considered to be covered if it lies in the FoV of three cameras with minimum required resolution. In this paper, user defines a set of high activity PAs, location of the obstacles with its shape and size and feasible locations for camera placement using a user friendly graphical user interface (GUI). A GUI shown in Fig. 6 defines PAs, obstacles and feasible locations for camera placement with cubical dimensions $m * m * m$ where m is the largest side of the PA/obstacle.

4 Mathematical Formulation of the Floor Model

We consider a floor plan of $m * m * m$ grid points. PAs are denoted by matrix P as shown in Eqs. 1 and 2.

$$P = \left| p_{xyz} \right|_{m*m*m} \tag{1}$$

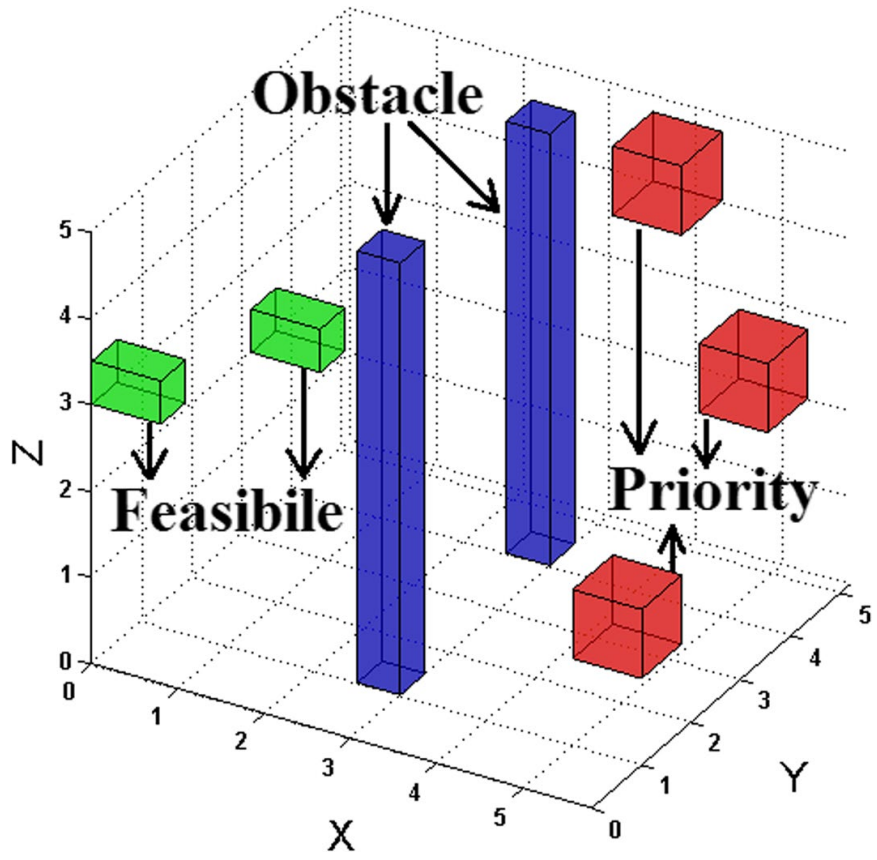


Fig. 6 Feasible locations for camera placement, obstacles (pillars) and PAs defined with help of GUI

$$p_{xyz} = \begin{cases} 1, & if \quad x, y, z \text{ is the priority area} \\ 0, & else \end{cases} \tag{2}$$

Feasible location for camera placement is denoted by matrix F as shown in the Eqs. 3 and 4.

$$F = \left| f_{xyz} \right|_{m*m*m} \tag{3}$$

$$f_{xyz} = \begin{cases} 1, & if \quad x, y, z \text{ is a feasiblity area} \\ 0, & else \end{cases} \tag{4}$$

Obstacles are denoted by matrix O as shown in Eqs. 5 and 6.

$$O = \left| o_{xyz} \right|_{m*m*m} \tag{5}$$

$$o_{xyz} = \begin{cases} 1, & if \quad x, y, z \text{ is a obstacle} \\ 0, & else \end{cases} \tag{6}$$

For each camera location, visibility measurement of all points covered by the camera is determined and defined as visibility matrix. Let a camera located at $(x_c,\ y_c,\ z_c)$ with a pan angle p_c, tilt angle t_c and a zoom level Z_m covers a 3D point $(x_p,\ y_p,\ z_p)$. Visibility matrix of the 3D point viewed by a camera with different pose (p_c, t_c) and zoom levels can be defined by 9 dimensional matrix (Eq. 7).

$$A = [x_p, y_p, z_p, x_c,\ y_c, z_c, p_c,\ t_c, Z_m] \tag{7}$$

The 9D matrix is reduced to 4D matrix using Eqs. 8–10 as 9D matrix is very inconvenient to work with. We use array indexing to convert 3D coordinates $\left(x_c, y_c, z_c\right)$ of a camera into 1D point (i) as shown in Eq. 8.

$$i = \left(x_c - 1\right) * N * N + \left(y_c - 1\right) * N + z_c \tag{8}$$

N in Eq. 8 represents the total number of cameras. Similarly, each pose can be mapped into 1D point, represented by j in Eq. 9. These functions are effectively creating a one-dimensional index for multi-dimensional points.

For each pose (p_c, t_c)

$$j = M * \left(p_c - 1\right) + t_c \tag{9}$$

M in Eq. 9 represents various pan or tilt angles of a camera.

$$Zoom\left(Z_m\right) = \left(high\, Z_m L - low\, Z_m L\right) * \frac{Z_m}{Z_m L} \tag{10}$$

$Z_m L$ in Eq. 10 represents the number of various zoom levels of a camera and 'Z_m' range from 1 to $Z_m L$. Now the visibility matrix shown in Eq. 7 is reduced to 4 dimensional

matrix. The performance measure of all visible points due to the camera pose are calculated and represented as 4D visibilty matrix A in Eq. 11. Each term in the matrix A denotes the visibility measure of a point k viewed by a camera located at point i with pose j and zoom level Z_m.

$$A = \left[a_{ijkZ_m}\right]_{m^3 * M^2 * m^3 * Z_m L} \tag{11}$$

where

$$a_{ijkZ_m} = \begin{cases} 1, & if \quad point\ k\ is\ covered \\ 0, & else \end{cases} \tag{12}$$

From the visibility matrix of all cameras, we should be able to calculate the number of cameras covering a point k. The covered points are now classified into priority and non priority areas. The PAs are further classified into PAs covered by 3 cameras, 2 cameras, 1 camera and placed in A_3, A_2, and A_1 respectively. A point k is assumed to be covered by 3 cameras if it lies in the FoV of 3 cameras placed at different locations with differant pose and zoom levels.

Figure 7 represents the FoV of 3 cameras cam 1, cam 2 and cam 3 to cover the PAs P1, P2, P3, P4, P5 and P6. The visibility matrix of the PAs P1 and P2 covered by 3 cameras (cam1, cam 2 and cam 3) will be denoted by $A_3\left(i,j,k,Z_m\right)$, visibility matrix of the PAs P3 and P4 covered by 2 cameras (cam 1 and cam 3) will be denoted by $A_2\left(i,j,k,Z_m\right)$, visibility matrix of the PAs P5 and P6 covered by 1 camera (cam 3) will be denoted by $A_1\left(i,j,k,Z_m\right)$ and visibility matrix of non PAs NP1 and NP2 will be denoted by $A_n\left(i,j,k,Z_m\right)$.

4.1 Coverage Matrix

We define the coverage matrix based on following inferences

1. A single lens is used as an optical sensor. Focal distance from the object is measured from the center of the lens.

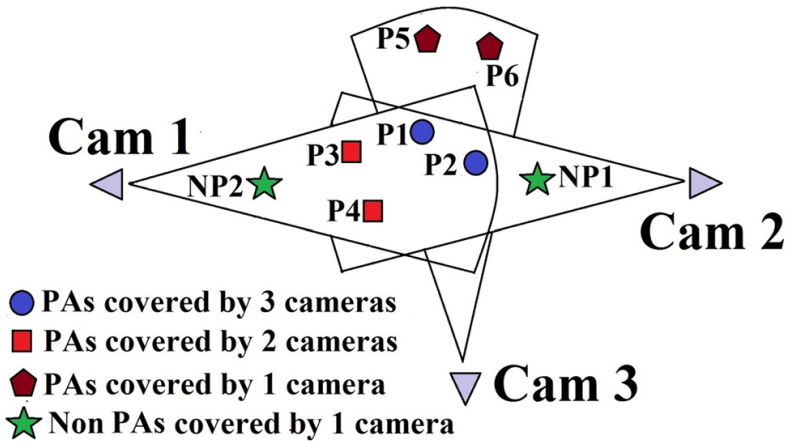


Fig. 7 Priority areas (PAs) covered by 3 cameras, 2 cameras, 1 camera and Non PAs covered by 1 camera

2. Lens aperture is assumed to be constant throughout the process.
3. Geometric distortion effect and blurring of objects has been ignored.

Coverage matrix is defined in Eqs. 13–18.

$$C = n \sum_{priority(3-cam)} P_x + u \sum_{priority(2-cam)} Q_y + v \sum_{priority(1-cam)} R_z + w \sum_{nonpriority} H_s, 0 < n, u, v, w, C < 1 \tag{13}$$

where

$$P_x = A_3\left(i, j, k, Z_m\right) \quad if \quad priority\ area\ is\ covered\ by\ 3\ cameras \tag{14}$$

$$Q_y = A_2\left(i, j, k, Z_m\right) \quad if \quad priority\ area\ is\ covered\ by\ 2\ cameras \tag{15}$$

$$R_z = A_1\left(i, j, k, Z_m\right) \quad if \quad priority\ area\ is\ covered\ by\ 1\ cameras \tag{16}$$

$$H_s = A_n\left(i, j, k, Z_m\right) for\ non\ priority\ areas \tag{17}$$

$A\left(i, j, k, Z_m\right)$ denotes the visibility matrix at a point in the surveillance space calculated in Eq. 11. n, u and v denotes the weightage given to the PAs covered by 3 cameras, 2 cameras and 1 camera respectively and w denotes the weightage given to the non PAs that are covered.

$$n + u + v + w = 1 \tag{18}$$

The coverage matrix (or fitness function) in Eqs. 13–18 should maximize the PAs covered by 3 cameras and minimize the PA covered by 2 cameras and 1 camera respectively. To achieve this objective, relative measure of the weighing functions is kept as n > u > v > w which give higher weight to the PAs covered by 3 cameras thus reducing the probability of occlusion. We maximize the value of C (Eq. 13) using GWO.

The coverage matrix is subject to the constraint

$$\theta_{\text{adjacent}} \geq 60^0 \tag{19}$$

where θ_{adjacent} is the angle between 2 adjacent cameras in the surveillance space. Equation 19 ensures that all cameras in a surveillance space are separated by a minimum angle and allows the cameras to cover a larger space.

5 GWO Mapping

The proposed work uses meta heuristic algorithm GWO [8] to find optimum locations, pose and zoom levels for visual sensors to cover each PA in a surveillance space by at least 3 cameras. A wolf ($W_{i,}$, $1 < i < N$, N = total number of cameras) in GWO denotes a candidate solution and the entire population comprises of N number of wolves searching for the prey or the optimum solution. Each wolf (W_i) in the proposed algorithm represents a camera location (x, y, z coordinates), pose (pan and tilt angles) and zoom level in form of a vector shown in Eq. 20.

$$\boldsymbol{W_i} = \left|\boldsymbol{X_{coord}(i)}\right| \boldsymbol{Y_{coord}(i)}\left|\boldsymbol{Z_{coord}(i)}\right| \boldsymbol{Pan(i)}\left|\boldsymbol{Tilt(i)}\right| \boldsymbol{Zoom(i)}| \tag{20}$$

where $1 < i < N$.

Each wolf will be assigned a weightage according to the fitness function (coverage matrix in Eq. 13). The values of the vector (Eq. 20) will be the optimum solution which gives optimum position, pose and zoom of a camera to achieve maximum coverage of all PAs with

each PA being covered by at least 3 cameras. The algorithm converges when the value of C in Eq. 20 becomes maximum.

From Eq. 20, we have

$$X_{coord}(i) = [x_1, x_2, \ldots\ldots..x_N] \tag{21}$$

$$Y_{coord}(i) = [y_1, y_2, \ldots\ldots..y_N] \tag{22}$$

$$Z_{coord}(i) = [z_1, z_2, \ldots\ldots..z_N] \tag{23}$$

Variable values $x_1, x_2, \ldots\ldots..x_N$ in Eq. 21 represent the set of x coordinates for N cameras. Similarly variable values $y_1, y_2, \ldots\ldots..y_N$ and $z_1, z_2, \ldots\ldots..z_N$ in Eqs. 22 and 23 represent the set of y and z coordinates for N cameras.

$$Pan(i) = [p_1, p_2, \ldots\ldots..p_N] \tag{24}$$

$$Tilt(i) = [t_1, t_2, \ldots\ldots..t_N] \tag{25}$$

$$Zoom(i) = [Z_{m1}, Z_{m2}, \ldots\ldots..Z_{mN}] \tag{26}$$

Variable values $p_1, p_2, \ldots\ldots..p_N$ and $t_1, t_2, \ldots\ldots..t_N$ in Eqs. 24 and 25 represent the set of pan angles and tilt angles for N cameras. Variable values $Z_{m1}, Z_{m2}, \ldots.Z_{mN}$ in Eq. 26 represent the set of zoom level for N cameras.

In this way, a population of wolves in GWO represents a set of cameras belonging to the solution space. Our problem is now redefined to search for the fittest individual from solution space. The fitness function for each wolf is obviously the coverage matrix calculated in Eq. 13. The optimization criterion is set for maximization. A GWO population comprising of N wolves (each wolf representing a camera) is shown in Fig. 8.

$$\boldsymbol{W_1} = \left| \boldsymbol{X_{coord}(1)} \right| \boldsymbol{Y_{coord}(1)} \left| \boldsymbol{Z_{coord}(1)} \right| \boldsymbol{Pan(1)} \left| \boldsymbol{Tilt(1)} \right| \boldsymbol{Zoom(1)}$$

$$\boldsymbol{W_2} = \left| \boldsymbol{X_{coord}(2)} \right| \boldsymbol{Y_{coord}(2)} \left| \boldsymbol{Z_{coord}(2)} \right| \boldsymbol{Pan(2)} \left| \boldsymbol{Tilt(2)} \right| \boldsymbol{Zoom(2)}$$

$$\boldsymbol{W_3} = \left| \boldsymbol{X_{coord}(3)} \right| \boldsymbol{Y_{coord}(3)} \left| \boldsymbol{Z_{coord}(3)} \right| \boldsymbol{Pan(3)} \left| \boldsymbol{Tilt(3)} \right| \boldsymbol{Zoom(3)}$$

$$\boldsymbol{W_4} = \left| \boldsymbol{X_{coord}(4)} \right| \boldsymbol{Y_{coord}(4)} \left| \boldsymbol{Z_{coord}(4)} \right| \boldsymbol{Pan(4)} \left| \boldsymbol{Tilt(4)} \right| \boldsymbol{Zoom(4)}$$

$$\vdots$$

$$\boldsymbol{W_N} = \boldsymbol{X_{coord}(N)} \ \boldsymbol{Y_{coord}(N)} \ \boldsymbol{Z_{coord}(N)} \ \boldsymbol{Pan(N)} \ \boldsymbol{Tilt(N)} \ \boldsymbol{Zoom(N)}$$

Fig. 8 GWO population of N wolves

5.1 GWO Implementation

The search process of GWO is initialized by a set of wolves (candidate solutions) searching for the prey (optimum solution). The position of each wolf is represented by a vector shown in Eq. 27 where N denotes the number of wolves in the population

$$\overrightarrow{X} = \{x[1], x[2], x[3] \ldots \ldots .x[N]\} \tag{27}$$

The fitness of a candidate solution/wolf in GWO is calculated using Eq. 13. The top 3 fittest wolves in the population are denoted by α, β and δ and the rest of the population is denoted by ω. In most cases, α decides the hunting, sleeping and walk decisions for a pack of wolves and entire pack follows the decision made by α. In some democratic cases, α is seen to follow the decisions made by β and δ. The next level in the hierarchy is β. They help α to make decisions. The lower level in the hierarchy is ω. They simply follow the rules. The hunting behavior of the wolves consists of 3 major steps namely chasing the prey, encircling the prey, and finally attacking the prey.

5.1.1 Encircling the Prey (Exploration)

Wolves encircle the prey in order to stop its movement. The encircling process can be mathematically formulated in Eqs. 28–29.

$$\vec{D} = \left|\vec{C}.\vec{X}_p(t) - \vec{X}(t)\right| \tag{28}$$

$$\vec{X}(t+1) = \vec{X}_p(t) - \vec{A}.\vec{D} \tag{29}$$

Here t shows the current iteration, $\vec{X}_p$ denotes the position vector of the prey and $\vec{X}$ denotes the position vector of the wolf, $\vec{X}(t+1)$ is the updated position of the wolf towards the prey. The coefficients $\overrightarrow{A}$ and $\overrightarrow{C}$ are calculated as per Eqs. 30 and 31.

$$\overrightarrow{A} = 2\vec{a}.\vec{r}_1 - \vec{a} \tag{30}$$

$$\overrightarrow{C} = 2\vec{r}_2 \tag{31}$$

The value of $\vec{a}$ is reduced from 2 to 0 over the iterations. Vectors $\vec{r}_1$ and $\vec{r}_2$ varies randomly in the interval [0,1].

5.1.2 Hunting the Prey (Exploitation)

We assume that the position of the prey is best known to first three best solutions α, β and δ. Therefore, we save the position of the first three best solutions as $\vec{X}_\alpha$, $\vec{X}_\beta$ and $\vec{X}_\delta$ for the current iteration *t* and oblige all other wolves in the population (ω) to update their positions according to $\vec{X}_\alpha$, $\vec{X}_\beta$ and $\vec{X}_\delta$ as shown in Eqs. 32–34.

$$\vec{D}_\alpha = \left|\vec{C}_1.\vec{X}_\alpha - \vec{X}_{W_i}\right|, \vec{D}_\beta = \left|\vec{C}_2.\vec{X}_\beta - \vec{X}_{W_i}\right|, \vec{D}_\delta = \left|\vec{C}_3.\vec{X}_\delta - \vec{X}_{W_i}\right| \tag{32}$$

In Eq. 32, X_{W_i} denotes the position of wolf W_i, $\vec{X}_\alpha$ is α wolf's position and $\vec{D}_\alpha$ is updated α position. Similarly, $\vec{X}_\beta$ is β wolf's position and $\vec{D}_\beta$ is the updated β position. $\vec{X}_\delta$is δwolf′s position and $\vec{D}_\delta$ denotes the updated δ position.C_1, C_2, C_3 are calculated as per

Eq. 31. The positions ($\vec{X}_1$, $\vec{X}_2$, $\vec{X}_3$) of a wolf for the current iteration are evaluated as per Eq. 33 [8].

$$\vec{X}_1 = \left|\vec{X}_\alpha - \vec{A}_1.(\overrightarrow{D}_\alpha)\right|, \quad \vec{X}_2 = \left|\vec{X}_\beta - \vec{A}_2.(\overrightarrow{D}_\beta)\right|, \quad \vec{X}_3 = \left|\vec{X}_\delta - \vec{A}_3.(\overrightarrow{D}_\delta)\right| \tag{33}$$

Coefficients $A_{1,}A_2, A_3$ are calculated as per Eq. 30. The wolf (W_i) finally updates its position towards the prey (optimum solution) as shown in Eq. 34.

$$\vec{X}(t+1) = \left(\vec{X}_1 + \vec{X}_2 + \vec{X}_3\right)/3 \tag{34}$$

GWO hunt the prey on basis of α, β, and δ, therefore it is prone to be stuck at local optima. Although some exploration was done during encircling the prey, GWO needs more operators to carry out exploration and to search for better solutions.

5.1.3 Searching for the Prey (Exploration)

Coefficient vector $\overrightarrow{A}$ plays an important role in movement of a wolf towards the prey (Eqs. 29–30). Figure 9 shows that $\overrightarrow{A}$ take random values greater than 1 to enable the wolves diverge from the prey and search for better solutions [8].

Vector $\overrightarrow{C}$ is another important factor used for exploration in GWO. As evident from Eq. 28, the value of distance ($\vec{D}$) depends on $\overrightarrow{C}$ while encircling the prey. Instead of decreasing $\overrightarrow{C}$ linearly, we deliberately keep $\overrightarrow{C}$ as random as possible in the interval [0, 2] to emphasize exploration [8]. This factor is very important for avoiding local optima in both initial as well as final iterations.

5.1.4 Convergence of GWO

During optimization of GWO, ω wolves iteratively improve their fitness according to α, β, and δ. When the improvement in the fitness of ω wolves reaches a threshold and

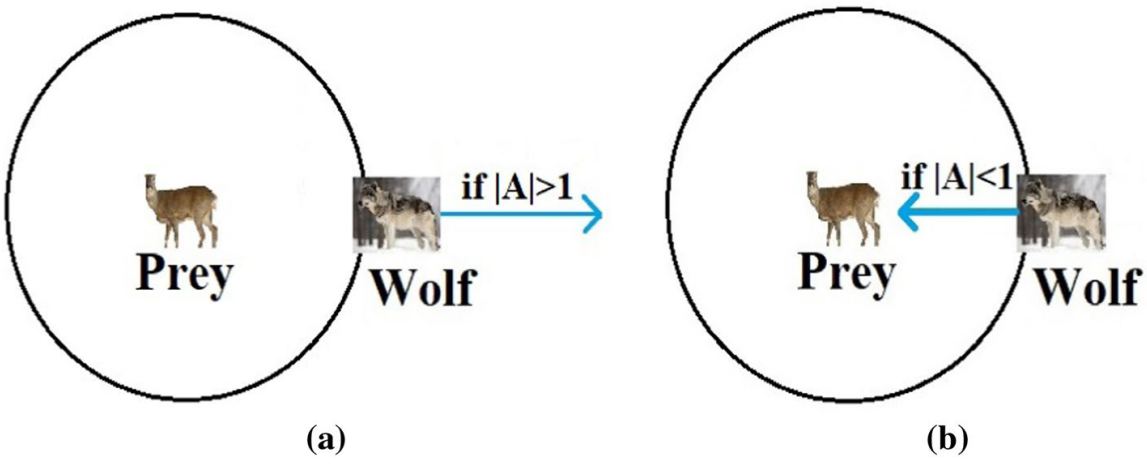


Fig. 9 **a** wolf diverging away from the prey to search for better solutions when |A| > 1. **b** wolf moving towards the prey when |A| < 1

fitness of ω wolves cannot be further improved on the basis of the fittest solutions α, β and δ, GWO is said to converge [8]. The pseudo code for the proposed work is shown by Algorithm 1.

Algorithm 1 – GWO implementation for optimum camera placement

1. Initialize the population size P_i, Initialize the max numbers of iteration I_{max}.
2. **while** $I < I_{max}$, **for each** iteration **do**
3. **for each** wolf W_i **do**
4. Clone the camera position, pose and zoom to W_i as per equation 20.
5. Compute the fitness function of each wolf using equation 13.
6. Update leader wolves X_α, X_β, X_δ. - three best wolves.
7. Use Eq 30 and Eq. 31 to calculate the coefficient vectors.
8. Update the wolves' (W_i) position using Eq. 34.
9. **end**
10. **end**
11. Optimum camera configurations are obtained after final iteration/convergence.

6 Experimental Results

The proposed algorithm is implemented using Python and the floor plan is of size 100*100*5 m^3 which is divided into cubical grids of size 1*1*1 ft^3. For simulation, we place 50 cameras throughout the surveillance space to cover 60, 80 and 100 distributed PAs with static and dynamic obstacles. The locations of the static obstacles are shown in Table 1.

Figure 10a shows the random camera placement of 50 cameras in the surveillance space. The FoV of the cameras is represented by cones. The locations and pose of all cameras are calculated for maximum coverage of PAs at least by 3 cameras using the proposed algorithm. The optimum camera locations after implementing the algorithm are shown in Fig. 10b–d respectively for 60, 80 and 100 PAs. It is seen that all PAs are covered by at least one camera, some are covered by 2 cameras, but maximum PAs are covered by 3 cameras. The result is shown in Fig. 11.

Table 1 Static obstacles used for simulation

Obstacle no.	x	y	Z
1	62	45	5
2	34	22	5
3	24	76	5
4	91	49	5
5	56	68	5

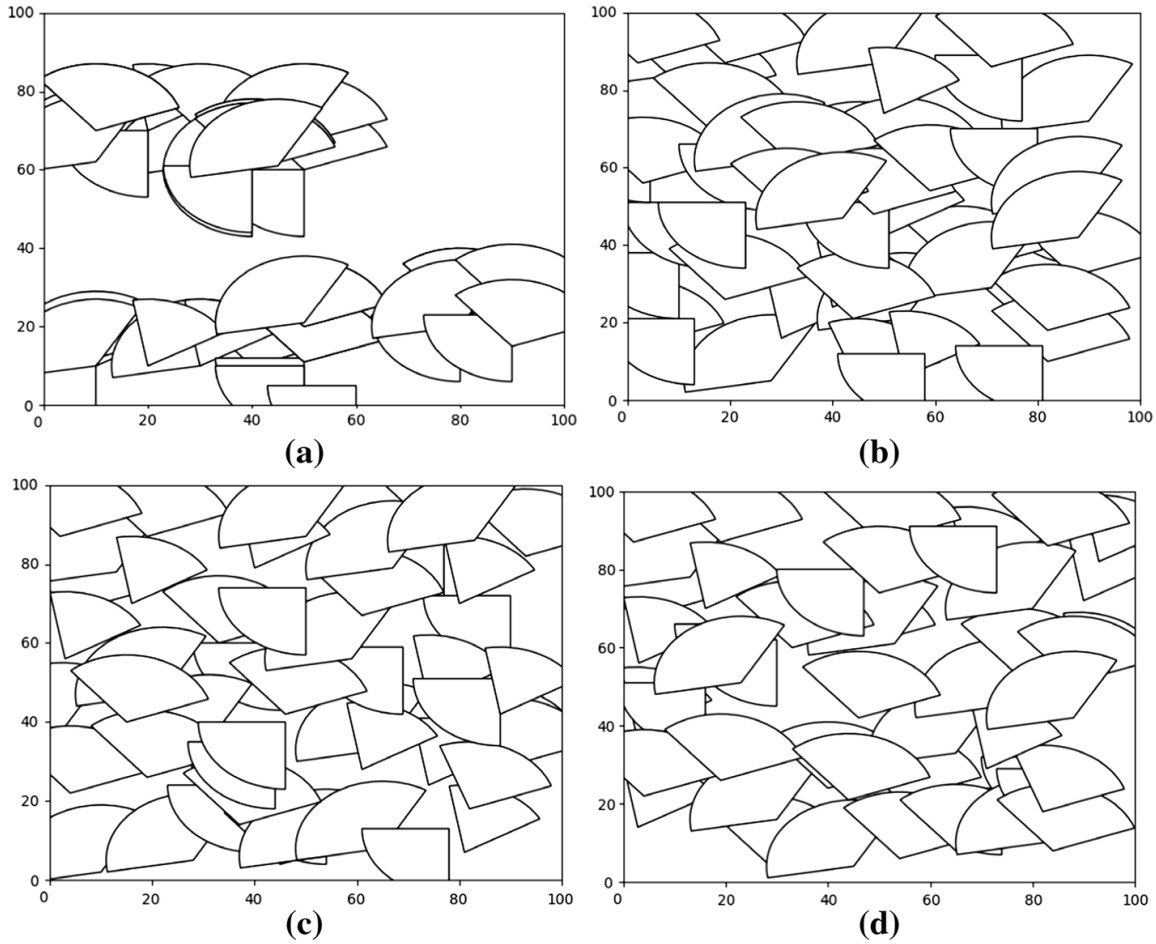


Fig. 10 **a** Random camera placement. **b** GWO based camera placement for coverage of 60 PAs. **c** GWO based camera placement for coverage of 80 PAs. **d** GWO based camera placement for coverage of 100 PAs

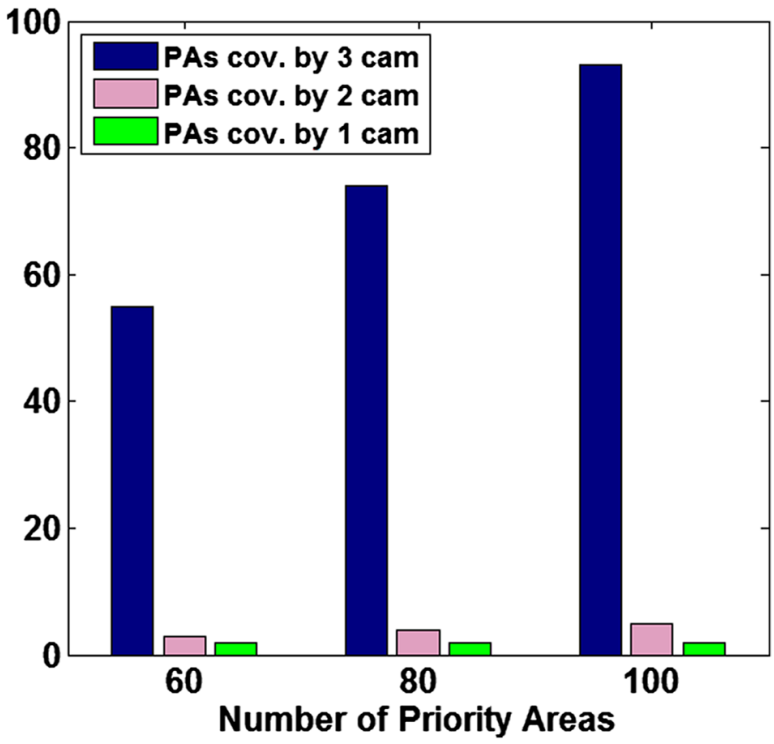


Fig. 11 Maximum PAs are covered by 3 cameras in GWO camera placement

Table 2 shows the optimum camera coordinates and poses of 25 (out of 50) PTZ cameras calculated using the proposed algorithm.

GWO based camera placement is compared with random camera placement, GA camera placement [4] and PSO camera placement [7] for surveillance space coverage. Figure 12 shows that 50 cameras provide a coverage of 29, 66 and 78% for random camera placement, GA camera placement and PSO camera placement respectively; while in the proposed GWO camera placement algorithm, only 45 cameras provide 100 percent coverage which significantly reduces the hardware cost of any surveillance application.

6.1 Experimental Evaluation

We conducted 3 experiments to validate the proposed algorithm. The aim of all experiments was to cover distributed PAs in a surveillance space of size 10*10*5 m^3, at least with 3 cameras per PA. We use 4 PTZ cameras for the experiments with static as well as random obstacles in the surveillance space. The use of 5 discrete clusters of PAs and 4 PTZ cameras covers all important activities in a big surveillance hall from different angles. The experimental evaluations are performed in Senior Machine Lab, DTU, DBMS Lab, DTU and Machine Shop, DTU which are cubical in shape. Senior Machine Lab, DTU has 2

Table 2 Optimum parameters of 25 cameras obtained from GWO implementation

Cameras	x	y	Z	Pan	Tilt	Zoom
1	38	42	4	15	45	2
2	53	86	3	50	15	9
3	73	41	2	47	33	8
4	8	7	3	−54	−48	1
5	5	74	3	−30	84	2
6	25	87	2	65	−64	2
7	47	80	5	−17	15	6
8	67	79	2	38	−39	9
9	23	51	4	10	−41	6
10	2	87	5	−42	85	4
11	45	6	4	36	45	5
12	30	16	5	58	−62	7
13	39	52	2	−48	−80	8
14	47	32	3	36	39	2
15	54	8	4	−34	60	5
16	52	18	4	−50	65	7
17	71	29	5	60	−80	8
18	13	78	3	75	44	6
19	27	66	3	15	35	5
20	19	87	5	−18	65	8
21	46	42	3	60	−77	7
22	53	61	2	−39	−38	2
23	33	60	3	45	−76	4
24	2	87	4	−44	66	6
25	47	80	4	37	45	4

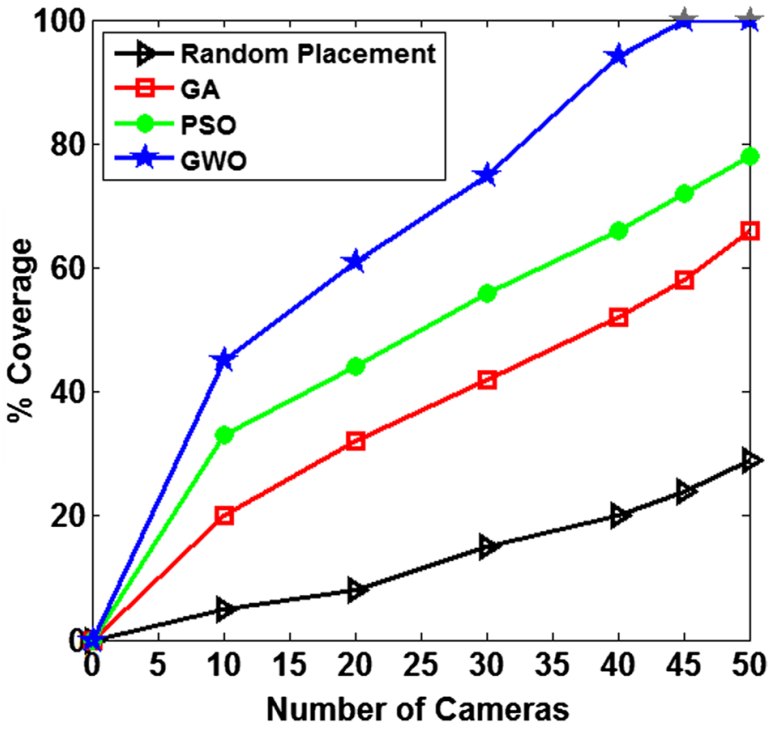


Fig. 12 Performance of GWO based camera placement compared with random camera placement, GA based camera placement and PSO based camera placement in terms of % coverage

pillars at the center of the hall which we consider as obstacles. DBMS Lab, DTU has one obstacle at the center of the hall and has 2 high activity main doors. Machine shop DTU has 2 obstacles at the center of the shop and has 3 high activity main doors. Experimental evaluation of the proposed algorithm in 3 diversely structured surveillance halls with distributed PAs and obstacles allows us to validate our algorithm. We considered all locations on the wall as feasible location for camera placement. Main doors of a hall need to be covered with adequate number of cameras for any surveillance purpose as multiple doors are high activity areas. The PTZ camera used is shown in Fig. 13.



Fig. 13 PTZ camera used for experimental evaluation of the proposed algorithm

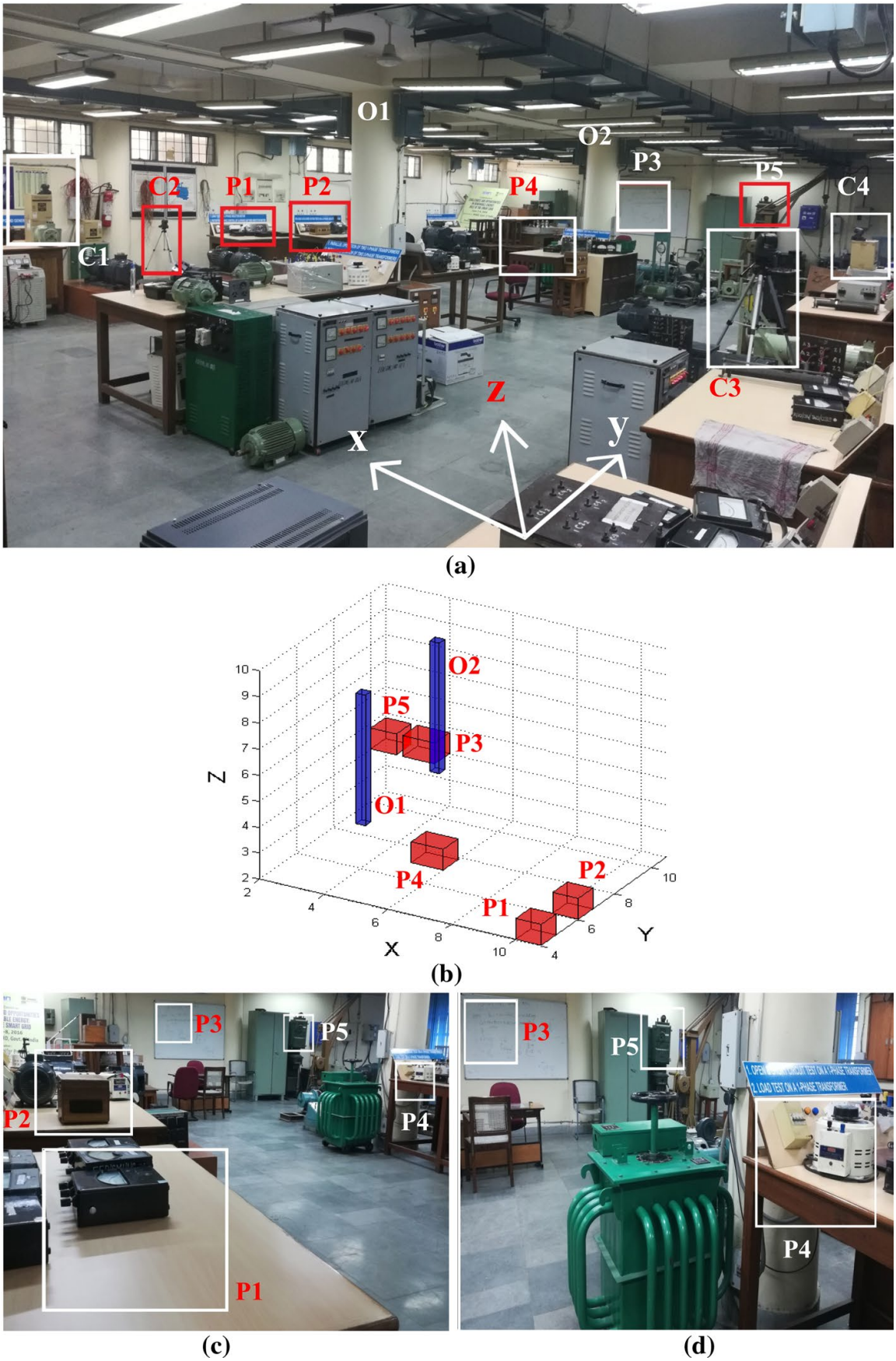


Fig. 14 Camera coverage performance for experiment 1. **a** Experimental Setup **b** GUI mapping of the experimental setup viewed from 30° angle, **c** Image taken from camera 1. **d** Image taken from camera 2. **e** Image taken from camera 3. **f** Image taken from camera 4

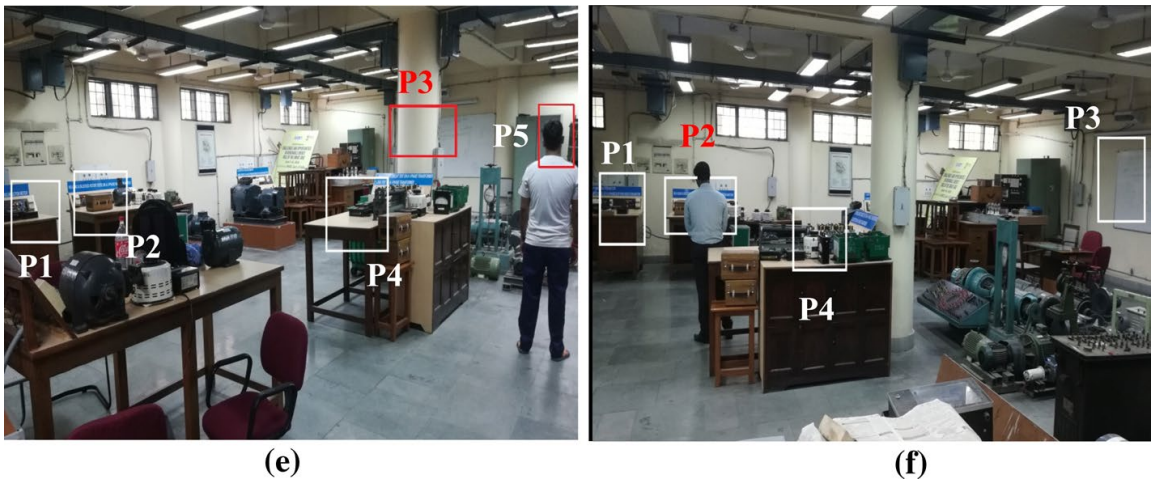


Fig. 14 (continued)

Table 3 Obstacle and PA coordinates for experiment 1

Areas	x	y	Z
Obstacle 1 (Pillar O1)	5	4	5
Obstacle 2 (Pillar O2)	5	8	5
Priority 1 (P1)	10	4	2
Priority 2 (P2)	10	6	2
Priority 3 (P3)	5	10	4
Priority 4 (P4)	5	7	2
Priority 5 (P5)	2	10	4

6.1.1 Experiment 1

We consider 5 distributed PAs (P1, P2, P3, P4 and P5) to be covered by 4 PTZ cameras (C1, C2, C3 and C4) in Senior Machine Lab, DTU of size 10*10*5 m^3, having 2 static obstacles (O1 and O2) and 2 randomly moving obstacles as shown in Fig. 14a. GUI mapping of PAs and obstacles in the surveillance space viewed from an angle of 30^0 is shown in Fig. 14b. The obstacle and priority area coordinates are shown in Table 3.

We are considering P3 occluded by a pillar (Fig. 14e) and P5 and P2 occluded by randomly moving obstacles (Fig. 14e, f). We aim to cover all PAs with at least 3 cameras by optimally placing 4 PTZ cameras. The camera coordinates obtained from the proposed algorithm are shown in Table 4.

The images captured by 4 cameras are shown in Fig. 14c–f. From Fig. 14c–f, it is seen that all PAs are covered by at least 3 different cameras with static occlusion.

Table 4 Camera coordinates for experiment 1

Cameras	x	y	Z	Pan	Tilt	Zoom
C1	10	1	3	33	4	5
C2	10	3	2	46	− 82	6
C3	0	3	3	64	30	5
C4	0	7	2	26	− 12	4

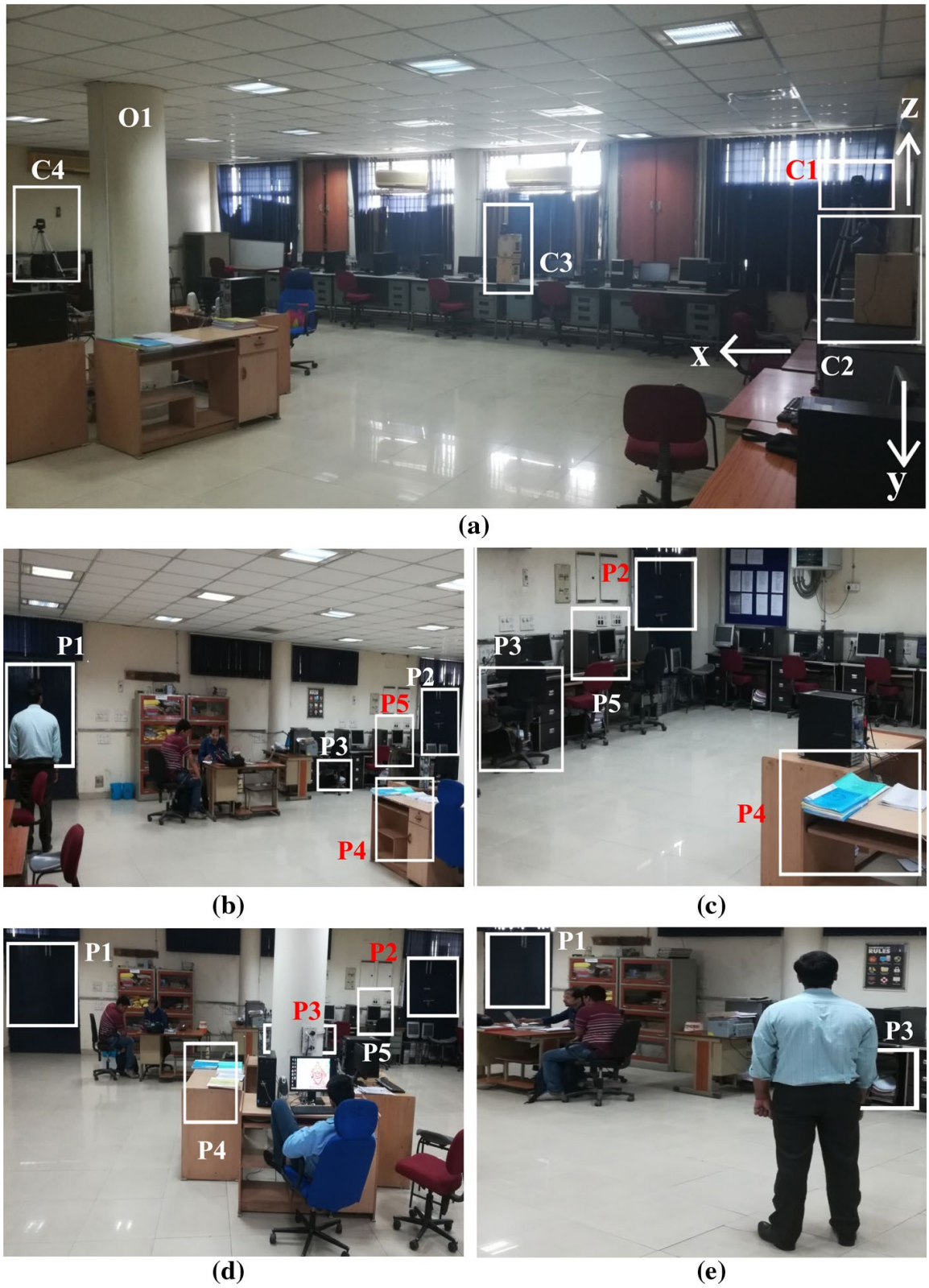


Fig. 15 Camera coverage performance for experiment 2. **a** Experimental setup. **b** Image taken from of camera 1. **c** Image taken from camera 2. **d** Image taken from camera 3. **e** Image taken from camera 4

However, after incorporating the dynamic occlusion, P2 and P5 are covered by 2 cameras. Dynamic occlusion will not last for long duration as our camera is continuously panning.

Table 5 Obstacle and PA coordinates used for experiment 2

Areas	x	y	z
Obstacle (Pillar O1)	5	5	5
P1	0	10	4
P2	10	10	4
P3	5	9	1
P4	4	5	2
P5	7	10	2

Table 6 Camera coordinates used for experiment 2

Cameras	x	Y	z	Pan	Tilt	Zoom
C1	0	2	4	55	12	4
C2	0	5	2	44	78	5
C3	5	0	2	33	−20	4
C4	10	3	3	54	−25	6

6.1.2 Experiment 2

In experiment 2, we consider 5 distributed PAs (P1, P2, P3, P4 and P5) to be covered by 4 PTZ cameras (C1, C2, C3 and C4) in DBMS Lab, DTU of size 10*10*5 m^3, having 1 static obstacle (O1) and 2 randomly moving obstacles as shown in Fig. 15a. The obstacle and PA coordinates are shown in Table 5.

We are considering P3 occluded by a pillar (Fig. 15d) and P1 and P3 occluded by randomly moving obstacles (Fig. 15b, e). We aim to cover all the PAs with at least 3 cameras by optimally placing 4 PTZ cameras. Camera coordinates obtained from the proposed algorithm are shown in Table 6.

The images taken by 4 cameras are shown in Fig. 15b–e. It is visible from Fig. 15b–e that all the PAs are covered by at least 3 cameras considering static obstacles. However, after incorporating the randomly moving obstacles, P1 and P3 are covered by 2 cameras.

6.1.3 Experiment 3

We consider 5 distributed PAs (P1, P2, P3, P4 and P5) to be covered by 4 PTZ cameras (C1, C2, C3 and C4) in Machine shop, DTU of size 10*10*5 m^3, having 2 static and 2 randomly moving obstacles and 3 main doors as shown in Fig. 16a. The obstacle and priority area coordinates are shown in Table 7.

We are considering P5 occluded by a pillar (Fig. 16d) and P3 and P5 occluded by randomly moving obstacles (Fig. 16d, e). We aim to cover all PAs with at least 3 cameras. The camera coordinates obtained from the proposed algorithm to optimally cover all PAs are shown in Table 8.

The images captured by 4 cameras are shown in Fig. 16b–e. From the Fig. 16b–e, it is seen that all PAs are covered by at least 3 different cameras with static obstacles. However, after incorporating the randomly moving obstacles, P5 is covered by only 2 cameras. Since PA 5 is viewed from 2 different angles, most of the information in the PA 5 is covered.

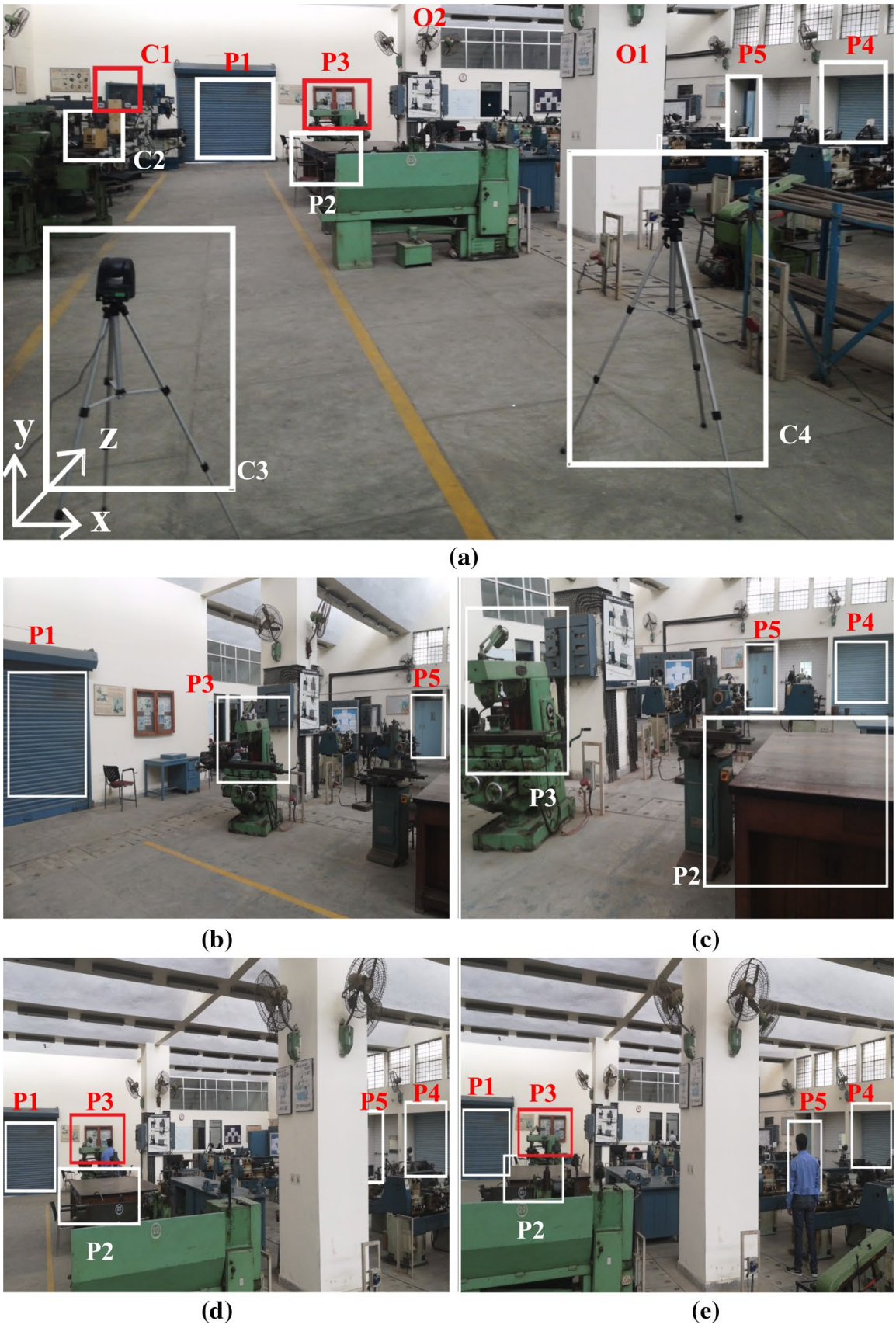


Fig. 16 Camera coverage performance for experiment 3. **a** Experimental Setup. **b** Image taken from camera 1. **c** Image taken from camera 2. **d** Image taken from camera 3. **e** Image taken from camera 4

Table 7 Obstacle and PA coordinates for experiment 3

Areas	X	y	Z
Obstacle 1 (Pillar O1)	5	4	5
Obstacle 2 (Pillar O1)	5	8	5
P1	1	10	4
P2	2	7	1
P3	2	10	3
P4	10	6	3
P5	10	9	3

Table 8 Camera coordinates for the experiment 3

Cameras	x	Y	Z	Pan	Tilt	Zoom
C1	0	8	2	22	54	3
C2	0	6	2	22	34	4
C3	1	0	3	−64	56	5
C4	3	0	3	12	−60	5

From the experimental evaluation, we made the following observations

1. Coverage of different sets of PAs by camera 1, 2, 3 and 4 is shown in Figs. 14, 15 and 16. All the PAs are covered by at least 3 cameras.
2. In case of randomly moving obstacle(s) blocking the view of one or more cameras, the PA is always covered by at least 1 camera.
3. For the PTZ cameras that are placed far away from the PA (Fig. 14d), a higher degree of zoom is used to get an accurate image. This explains the accuracy of the model used.
4. Experiment 1, 2 and 3 are a testimony to the fact that all the PAs are covered for a longer duration and with optimum image resolution.

7 Conclusion

In this work, we present a new method for optimizing the coverage of visual sensors by adjusting their locations, pose and zoom levels using a meta heuristic algorithm GWO. The proposed GWO based approach is computationally lighter and faster in execution. Since we are using priority areas, obstacles and feasibility areas, our approach will be useful in practical applications. Zoom level as a parameter ensures good quality and resolution of the images. The proposed algorithm covers each PA by 3 cameras which not only enhances the information content in the images but also reduces the possibility of occlusion due to static and randomly moving obstacles. We have shown the experimental evaluation of our work using PAs, obstacles, and feasible camera locations. The proposed work gives an economical and cost-effective solution for any surveillance application.

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A Particle Swarm Optimized Learning Model of Fault Classification in Web-Apps

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ABSTRACT The term web-app defines the current dynamic pragmatics of the website, where the user has control. Finding faults in such dynamic content is challenging, as to whether the fault is exposed or not depends on its execution path. Moreover, the complexity and uniqueness of each web application make fault assessment an extremely laborious and expensive task. Also, artificial fault injection models are run in controlled and simulated environments, which may not be representative of the real-world fault data. Classifying faults can intelligently enhance the quality of the web-apps by the assessment of probable faults. In this paper, an empirical study is conducted to classify faults in bug reports of three open-source web-apps (*qaManager*, *bitWeaver*, and *WebCalendar*) and reviews of two play store web-apps (*Dineout: Reserve a Table and Wynk Music*). Five supervised learning algorithms (naïve Bayesian, decision tree, support vector machines, K-nearest neighbor, and multi-layer perceptron) have been first evaluated based on the conventional term frequency–inverse document frequency (tf-idf) feature extraction method, and subsequently, a feature selection method to improve classifier performance is proposed using particle swarm optimization (a nature-inspired, meta-heuristic algorithm). This paper is a preliminary exploratory study to build an automated tool, which can optimally categorize faults. The empirical analysis validates that the particle swarm optimization for feature selection in fault classification task outperforms the tf-idf filter-based classifiers with an average accuracy gain of about 11% and nearly 26% average feature reduction. The highest accuracy of 93.35% is shown by the decision tree after feature selection.

INDEX TERMS Classification, fault, feature selection, particle swarm, web-apps.

I. INTRODUCTION

With the increasing size of indexed Web, superior technology, and optimal browser performance, the development of Web has seen significant transformation from being an anachronistic static content repository to a turbulent, interactive, responsive content space. The websites now rely on programmatic user input and data processing. The term web-based applications or simply web-app [1] defines the current dynamic pragmatics of the website where the user has control. Technologically, the current generation websites are more like web-based software which store data/interact with a database on the back end, and process business logic and information in a more convoluted way. They have a web interface but web development here is just not limited to developing an alluring interface but creating web-based software. Thus, the web-based software development primarily consists of three ingredients, namely the development of websites, web application development and development of web services [2].

"Agile development practices", "big-data", "security", "open source" and "customer-first design" are some of the key terms that characterize the latest technology trends in the software development. A typical web application development workflow is similar to the conventional software development (Figure 1). It involves five phases, (i) *brainstorm:* for requirement analysis (ii) *design:* design document & prototype (iii) *development:* iterations, demo and feedback

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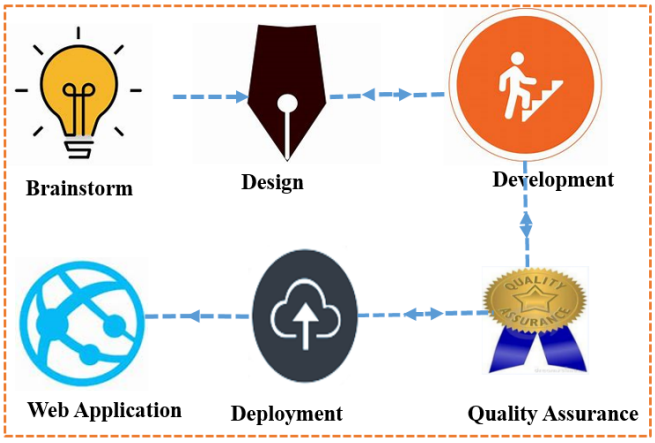


FIGURE 1. Web-app development workflow.

(iv) *quality assurance*: identify defects and resolve bugs (v) *deployment:* production and technical support.

Web quality is defined as the degree to which the web-based software meets the specified requirements, is accessible, provides the reliable information and meets the user needs & expectations [2]. Quality assurance (QA) popularly known as QA testing is a systematic process of determining whether a product or service meets specified requirements and customer expectations. This process-driven approach is the key to ensure the performance and reliability of the product. QA's primary goal is tracking and resolving deficiencies prior to product release, that too in a proactive way. That is, the purpose of QA is to prevent defects from entering into the system. Thus, the quality assessment models in this new development setting call for a set of acceptance criteria which define accessibility and usability of the web-apps, demonstrating its effectiveness in terms of user-experience. The acceptance of websites/apps by the end-user depends on a variety of factors. The most measurable aspect of software quality is the number of faults, or bugs, that are discovered in a software product. It is an absolute quantifier of quality. Formally, a fault is defined as an ''incorrect step, process, or data definition in a computer program'' [3]. For example, attributes such as dead-links or browser compatibility [2] are direct indicators of faults and a quality compromise.

The source code and bug reports for the open-source projects are readily available but are awfully structured and unlabeled. Similarly, the Google and Apple play store allow users to give feedback in the form of reviews. An app review typically includes star rating followed by a comment. Negative opinion polarity within these reviews is strong indicator of a fault/drawback/short-coming. For example, the comment *''The link for few songs are dead…play now and download both not working for them!!! The text is not readable as the font is too small. Moreover, the premium version is a waste of money as compared to….''*, clearly conveys the opinion of the reviewer(negative in this case) and the aspects of negative opinion. These reviews possess a vital source of information that can be used by the app developers and the vendors for de-bugging and version control. But here too, most of the reviews are in an unstructured form and mining useful analytical information from them requires a great effort. Pro-actively finding categories of faults in such open-source projects and real-time data that too manually is arduous and expensive. Researchers have recognized the limits of manual fault classification and have investigated automation solutions. Empirical fault detection is one such promising research direction which is based on fault classification as an imperative prerequisite task [4]. An automated tool to classify faults into pre-defined categories can assist in fault-based testing of web-apps. The primary purpose of any such tool is to prevent faults and find as many faults as possible, as early as possible.

The vital sub-task of the fault classification process is feature extraction, which converts the input data (unstructured textual data indicative of faults), into an array of representative features. Commonly, the feature extraction task is done using intrinsic 'filtering' methods which are fast, classifier-independent methods that rank features according to predetermined numerical functions based on the measure of the ''importance'' of the terms. A variety of scoring functions such as, tf-idf, chi-square, mutual information, information gain, cross-entropy etc., have been used as statistical measures to pick features with the highest scores [5]. Further, past literature conforms that an optimal feature selection [6] improves the classifier performance (in terms of speed, predictive power and simplicity of the model), reduces dimensionality, removes noise and helps visualizing the data for model selection. In feature selection the features are kept intact and n best features are chosen among them, removing the redundant and co-linear features. This sub-task of selecting the relevant subset of features and discarding the non-essential ones is computationally challenging and expensive task. Population-based meta-heuristics, especially the ones inspired by nature have been proposed for feature selection in relevant and prominent literature work as wrapper methods to select the best possible subset of features for a given model.

Swarm intelligence algorithms (SI) are contemporary computational and behavioral metaphors for solving search and optimization problems which take collective biological patterns provided by social insects (ants, termites, bees, wasps, moths etc.) and other animal societies (fish, birds, grey wolves etc.) as stimulus to model algorithmic solutions. Several algorithms inspired by natural phenomena have been proposed in the past years and among them, some meta-heuristic search algorithms with population-based framework have shown satisfactory capabilities to handle high dimension optimization problems. The work presented in this paper is an insight to this research trend which comprehends the adaptive learning and collective intelligence behavioral models of swarm-based algorithms. Swarm-based feature optimization using particle swarm optimization (PSO) is demonstrated to

cater to the dimensionality; complexity and fuzziness in the unstructured data.

The research presented in this paper, is an empirical study to put forward an optimized learning model to reduce the feature dimensionality in order to optimize fault prediction in real-time web-apps. Bug reports of three open-source web-app projects (*qaManager*[1], *bitWeaver*,[2] *WebCalendar*)[3] and reviews from two play store applications (*Dineout: Reserve a Table*,[4] *Wynk Music*)[5] have been considered to intelligently mine faults which are annotated based on seven categories as given by Sampath *et al*. [7]. A comparative analysis using five supervised learning algorithms, namely naïve Bayesian (NB), decision tree (DT), support vector machine (SVM), K-nearest neighbor (K-NN) and multi-layer perceptron (MLP) is done to find the best predictive classifier. Thus the contribution of this research is to build an optimal fault prediction model as follows:

- Implement five supervised learning algorithms to predict faults using tf-idf feature extraction: NB, DT, SVM, K-NN, MLP
- Implement five supervised learning algorithms using feature selection method: tf-idf +PSO
- Performance analysis on the basis of accuracy

The predictive model will give insights to the testing practitioners to seed similar types of faults for comprehending fault-based testing of Web-Apps. This study does not compare various feature selection algorithms, but it demonstrates the benefit of adding the feature selection optimization process together with the fault classification task to enhance the accuracy of classifier.

The organization of the paper is as follows: Section 2 discusses the related work in the domain of research. Section 3 describes the system architecture along with the details of the proposed optimal predictive learning model using particle swarm optimization. Section 4 discusses the results and finally, section 5 presents the conclusion of the empirical study.

II. RELATED WORK

Few pertinent studies have been conducted in the area of fault classification in web applications. Sampath *et al.* [7] conducted experiments for fault detection and by seeding realistic faults and classified them into five categories namely data store faults, logic faults, form faults, appearance faults and link faults. Guo and Sampath [4] have carried out an exploratory study on web application fault classification using the induction method wherein they state the classification dimension and used the work in [7] as the baseline. They used the actual location of the fault as a dimension for classification taking into consideration presentation, logic and data store faults. They defined a new fault type known as compatibility fault and fine grained the classification of logic faults into browser interaction faults, session faults, paging faults, server side faults, encoding-decoding faults, locale faults and others and calculated the frequency of faults on Roller Weblogger and qaManager.

Elbaum *et al.* [8] seeded the three types of faults namely scripting, forms and database query faults to evaluate the performance of web testing techniques. Li and Tian [9] adapted an orthogonal defect classification approach (ODC) like problems related to timing, interface or algorithms. Kumar *et al.* [10] have used supervised machine learning techniques on three open source web applications. They used area under ROC curve to analyze and compare the performance of various machine learning techniques and reached the conclusion that multinomial naïve Bayesian gave the best results. A review on the application of computational evolutionary method, the genetic algorithm to automatically search software errors was given by Mantere and Alander [11]

III. SYSTEM ARCHITECTURE

The longer the fault goes without detection, the more expensive the fault is to repair. Fault classification intends to offer feedback about the web development process. Based on this, this research puts forward a fault prediction model using optimal feature selection. A variety of supervised learning algorithms are evaluated to find the best model for fault classification. The goal of using classification schemes is to devise a preventive strategy for finding as many faults as possible and that too as early as possible.

The preliminary step is to gather the required data, which are: bug-reports of open source web-apps and reviews of play store apps. Pre-processing is then done for cleaning the dataset from noise. Noise here basically connotes the language irregularities often present in text, as this noisy and unstructured data affects the quality of the fault classification task. Thus, after pre-processing, the representative features are extracted using the tf-idf filter. Particle swarm optimization (PSO) is then applied on this resulting matrix to generate an optimal feature matrix. These optimal features are then used to train the classifier. The figure 2 shows the systematic flow of the model.

The following sub-sections expound the details:

A. DATASET ACQUISITION

To evaluate the system two types of datasets have been considered. Firstly, three open source web-app projects, namely *qaManage*r, *bitWeaver* and *WebCalendar*have been considered. The bug reports for the same have been acquired from sourceforge.net. A bug is an evidence of fault in the program. And so considering the bug report is an obvious choice for fault diagnosis. We deliberately consider Java/PHP based applications as both these languages are the most popular and widely used ones for web development. The applications with larger number of closed bugs were considered since

[1]qaManager: https://sourceforge.net/projects/qamanager/
[2]bitWeaver: https://sourceforge.net/projects/bitweaver/
[3]WebCalendar: https://sourceforge.net/projects/webcalendar/
[4]Dineout App: https:// play.google.com/ store/ apps/ details?id=com.dineout.book&hl=en_IN
[5]Wynk Music App: https://itunes.apple.com/lk/app/wynk-music/id845083955?mt=8

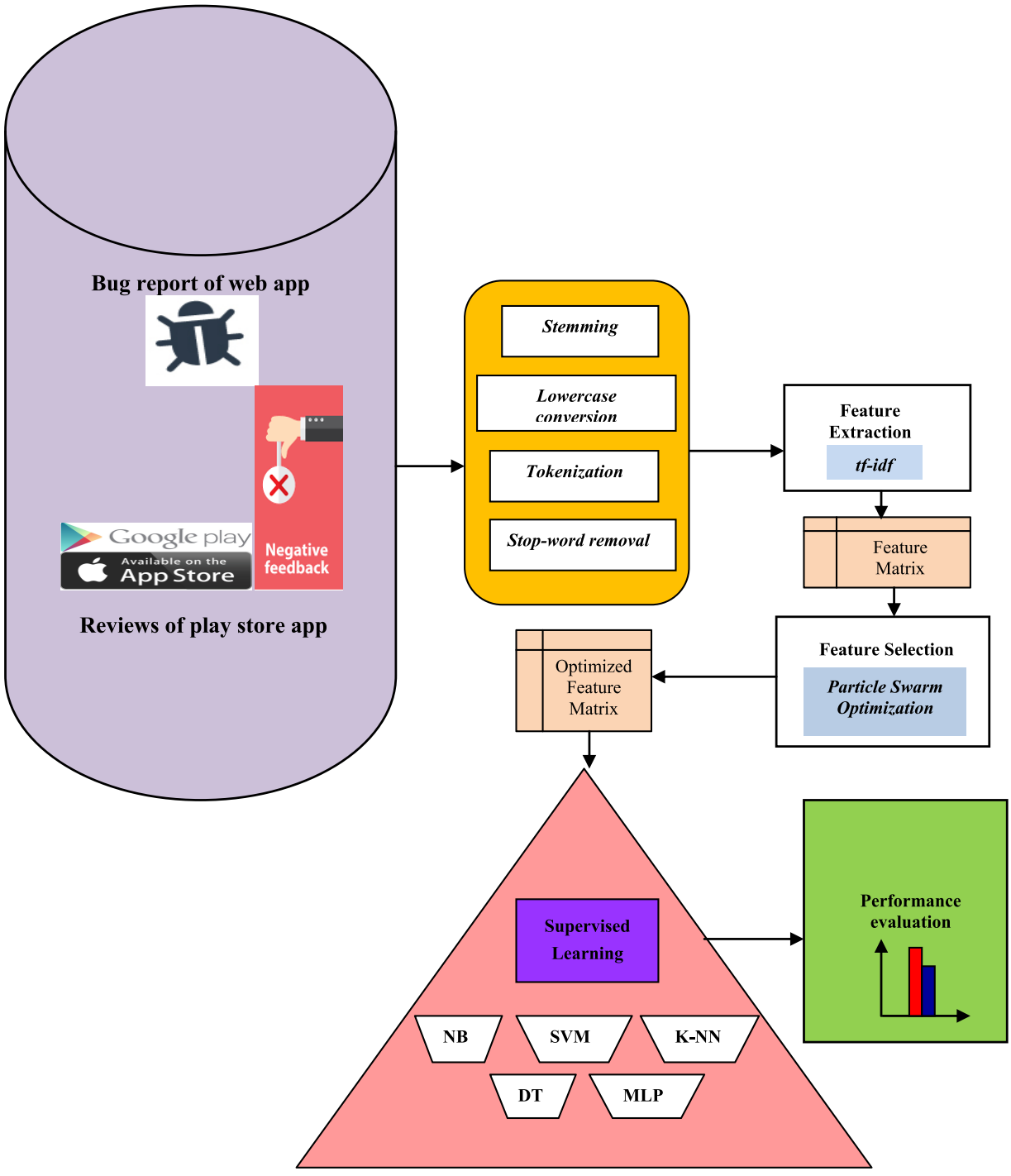


FIGURE 2. System Architecture.

comments given in the closed bug section facilitated easy bug identification. The number of total bugs was also a significant selection criterion.

Secondly, reviews of two play store (1 Google and 1 Apple) apps, namely, *Dineout: Reserve a Table*and *Wynk Music* were acquired. The *Dineout* app had 1135 reviews whereas the *Wynk Music* app has 8470 reviews. The reviews typically include star rating followed by a comment. Negative opinion polarity within these reviews is strong indicator of a fault/drawback/short-coming. These reviews possess a vital source of information that can be used by the app developers and the vendors for de-bugging and version control. Thus, these reviews are analyzed for negative opinion polarity using AFINN-111 sentiment lexicon, which is a list of 2477 English words labeled with sentiment strength [12]. Sentiment refers to the use of polarities (positive and/or negative) in written text [13]–[16]. Each word is assigned with an integer in a range of polarity from -5 up to $+5$, negative to positive.

It includes a number of words frequently used on the Internet such as LOL (Laughing Out Loud), which are indicative of emotions of the user, especially on social media portals. The negative reviews were then analyzed for faults.

Five different web-apps were especially considered to determine the robustness of the learning model. To analyze the faults within the application's bug report and negative reviews, the bugs were scraped using Google Web Scraper[6] and the reports was annotated for faults from seven categories as given by Sampath *et al.* [7]. The categorization was based on physical location of fault as data store, form, logic, link, appearance, compatibility and others. (Figure 3).

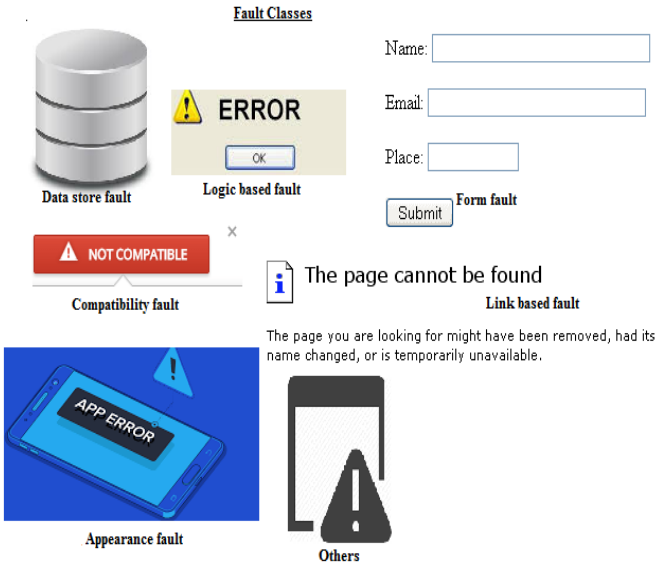


FIGURE 3. Fault categories.

The following table 1 depicts the number of faults for the five web-apps.

TABLE 1. No. of faults in Web-Apps.

Web Apps / Faults	qaMa nager	Bitwea ver	Webcale ndar	Dineou t	Wynk Music
Logic	166	217	1199	34	102
Appearance	29	83	375	15	65
Data Store	19	81	170	22	598
Link	12	51	79	18	234
Form	20	5	5	5	8
Compatibility	5	20	72	24	74
Others	39	75	268	34	354
Total	290	532	2168	152	1435

B. PRE-PROCESSING

To extract the structured text for analytics from the unstructured bug reports/reviews, pre-processing is done [17]. The bag-of-words model [18] is used to transform and represent the text. The method takes into account the words and their frequency of occurrence in the sentence or the document. The data is firstly tokenized to identify tokens and then cleaned by removing punctuations, numbers, special characters, stop words. Stemming is carried out too, to reduce words to their root word. University of Glasgow stop word list[7]and the Porter stemming algorithm [19] are used for stop-word removal and stemming respectively.

C. FEATURE EXTRACTION AND SELECTION

In this work, tf-idf is used a filter method whereas, the PSO is used for optimal feature subset selection. These are briefly described as follows:

The conventional term frequency - inverse document frequency (tf-idf) method is used for calculating the weights and extracting the features. "Term frequency - inverse document frequency is a conventional statistical weight which measures how important a word is to a document" [20]. Moreover, it checks how relevant the keyword is throughout the corpus [21], [22].

The term frequency, tf (t,d) is the raw count of a term in a document and is calculated using equation (1)

$$\text{tf}(t, d) = \frac{\text{No. of times term t appears in a document d}}{\text{Total no. of terms in the document}} \quad (1)$$

The inverse document frequency, idf (t, D) is the measure of how much information is provided by a specific word or term, i.e. whether the word is rare or common across the corpus. idf is calculated using equation (2)

$$\text{idf}(t, D) = \log\left(\frac{\text{Total no. of documents}}{\text{No. of documents with term t in it}}\right) \quad (2)$$

Thus, tf-idf is calculated as given in equation (3)

$$\text{tf} - \text{idf}(t, d, D) = \text{tf}(t, d) * \text{idf}(t, D) \quad (3)$$

where t denotes the terms; d denotes each document and D denotes the collection of documents.

Feature selection is done to reduce the size of problem for learning algorithms which may improve classification accuracy due to reduction in computation requirement. This also increases the speed of classification task as the size of data to train the classifier is reduced [23], [24]. Many feature selection algorithms are available across pertinent literature. Swarm intelligence (SI) algorithms have proven capabilities of computational intelligence for dealing with the complex real world problems [6]. They often utilize the guidance of nature to search for the optimal solution. They are a class of nature inspired meta-heuristics and are population based algorithms. They are based on the hunting, breeding, etc. behaviors of birds, insects and the like. Ant colony optimization, cuckoo search, particle swarm optimization are examples of some popular swarm intelligence algorithms.

[6]Google Web Scraper: https://chrome.google.com/webstore/detail/webscraper.

[7]University of Glasgow stop-word list: http://ir.dcs.gla.ac.uk/resources/linguistic_utils/

Motivated by the adaptive learning and collective intelligence behaviors of SI algorithms, in this work, the use of particle swarm optimization (PSO) for enhancing fault classification accuracy is demonstrated. PSO is an evolutionary computation algorithm which aims to find a globally optimized solution. It was developed in 1995 by Kennedy and Eberhart [25], [26] based on the imitating social behaviors and random movements similar to that of a flock of birds or a school of fish. The original version of PSO was proposed by modifying these initial imitations. Later, inertia weight was introduced by Shi and Eberhart [27] to illustrate the standard PSO algorithm. Initially, the algorithm is flooded with a population of random solutions. These random solutions are called 'particles'. Each particle is a point in an S-dimensional search space. The i^{th} particle is represented as $X_i = (X_{i1}, X_{i2}, X_{i3}, \ldots.., X_{iS})$. Every particle has a memory to store its own best position denoted by "pbest" (personal best). The best experience of any particle i at a particular time t is denoted by P_i (t). The best previous position (pbest, the position giving the best fitness value) of any particle is represented as $P_i = (P_{i1}, P_{i2}, P_{i3}, \ldots\ldots P_{iS})$ and is recorded by the particles in their memory. The index of particle with the best position among all the particles in the population is represented by the symbol 'gbest' (global best). At any moment t the global best experience of swarm is denoted by g(t). So, at any point of time, we have pbest for every particle and gbest for complete swarm of particles. The concept of a flying particle is illustrated in figure 4.

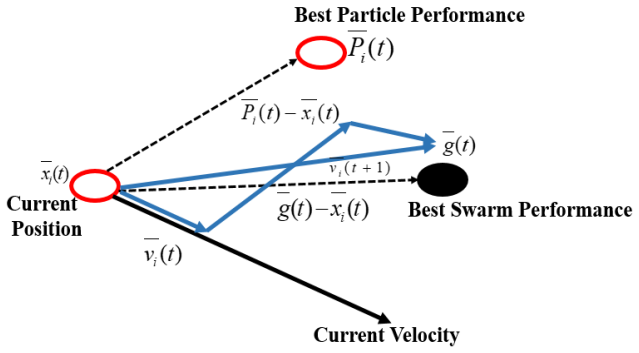


FIGURE 4. The concept of flying particle.

Some considerations are necessary to fulfill the equations for the standard PSO model. These are as follows:

- r_1 and r_2 are uniformly distributed random functions, and r_1 and $r_2 \varepsilon$ [0, 1].
- d = 1, 2, 3, ……, S is the dimension.
- The term $w.V_{id}$ (t) is the inertia term, and the coefficient w is the inertia coefficient or the inertia weight. This term provides the particles a memory capability for the exploration of new positions in the search space while flying. The original version of PSO proposed in 1995 [25], [26] did not have any inertia term. However, in 1998 Shi and Eberhart [27] added this term to formulate the standard PSO model.
- c_1 and c_2 are the acceleration coefficients.
- The term $r_1.c_1.(P_{id}(t) - X_{id}(t))$ is called cognitive component and it represents private thinking of an individual particle.
- The term $r_2.c_2.(g_d(t) - X_{id}(t))$ is called social component and it represents the collaboration among the particles.
- The two components, cognitive component and social component pull each particle towards pbest and gbest positions respectively.
- The three components, inertia term, cognitive component, and social component are combined to create a new velocity vector V_{id} (t + 1).
- This new velocity vector translates a particle position to a new updated position in the search space X_{id} (t + 1) which is probably a better location for the particle i.

This way all particles are cooperating to find out the best solution for an optimization problem. These rules are guaranteed to be obeyed by all the particles of the swarm. After a particle flies toward a new position, the performance of particle is measured according to a pre-defined fitness function. A maximum velocity, denoted by Vmax is use to limit particle's velocity on each dimension. The length of steps taken by particle through the solution space in each iteration is determined by Vmax. Small value of Vmax may lead to less exploration beyond locally good regions causing the algorithm to move towards the target slowly and particles could become trapped in local optima, whereas, if greater value has been taken for Vmax particles in the swarm will move faster towards the global optimum as they are able to move with bigger step in each iteration. Under such circumstances particles might fly past good solutions. The pseudo code for standard PSO is given in the following figure 5.

D. SUPERVISED LEARNING ALGORITHMS

Five supervised learning algorithms, namely, naïve Bayesian, decision tree, support vector machine, K-nearest neighbors and multi-layer perceptron (neural network) have been implemented and analyzed to find the best predictive learning model for fault classification. The objective is to analyze the bug report data and negative reviews and classify it into seven pre-defined categories as given by Sampath *et al.* [7]. The following table 2 gives the description of these fault types in application code.

A total of 4577 bugs were scrutinized from the five web-apps as given in table 1. The description of the classification algorithms used in this work is available across pertinent literature on machine learning [28], [29]. The training: test data split was 80:20 with a 10-fold cross validation.

Python 2.7 was used for implementation of the work. The experimentation used open source Python library, Natural Language Toolkit (NLTK)[8] for the natural language processing tasks. Open source libraries Tensorflow and Keras were used to build the neural network classifier. Other classifiers were implemented through Scikit-Learn library.

[8]Natural Language Toolkit: https://www.nltk.org

FOR each particle i
FOR each dimension d
Initialize position X_{id} randomly within range
Initialize velocity V_{id} randomly within range
End FOR
END FOR
Iteration t = 1
DO

FOR each particle i
Calculate Fitness Value
IF Fitness $(X_{id}(t))$ > Fitness $(P_{id}(t))$
$P_{id} = X_{id}$
End IF
End FOR
Chose the particle having the best Fines value as the $g_d(t)$
FOR each particle i
FOR each dimension d
Calculate velocity according to the equation

$$V_{id}(t+1) = w.V_{id}(t) + r_1.c_1.\left(P_{id}(t) - X_{id}(t)\right) + r_2.c_2.\left(g_d(t) - X_{id}(t)\right)$$

Update particle position according to the equation

$$X_{id}(t+1) = X_{id}(t) + V_{id}(t+1)$$

END FOR
END FOR
t = t + 1
WHILE maximum iterations or minimum error criteria are not attained

FIGURE 5. Pseudo code for PSO.

TABLE 2. Faults types in application codes.

Fault	Type
Data Store	Query or data manipulation fault in database
Form	Pertaining to the form fields, missing and incorrect values and validation
Logic	Flow of event or control
Link	URL's and links: deadlink etc
Appearance	Display and presentation.
Compatibility	Compatibility issues: variety and versions of browsers and operating system or any other client environment.
Miscellaneous	Installation problem, security issues, others not covered in any of the above mentioned categories.

IV. RESULTS AND DISCUSSION

The empirical analysis has been divided into four parts; (i) parameter setting for PSO (ii) feature selection results (iii) comparison of accuracy with and without feature selection (iv) reduction in time for training the classifier and building the model

A. PARAMETER SETTING FOR PSO

All the parameters were set to the best values as claimed & demonstrated by Aghdam and Heidari [30]. These values are as given in table 3.

The maximum iteration and fitness function were set to 100 and 0.95 respectively. The cognitive coefficient (c_1) and the social coefficient (c_2) were set between 0.3 and 0.4 since these two values ($c_1 + c_2$) are normally limited to 4 as given by Aghdam and Heidari [30].

TABLE 3. Parameters for PSO.

Parameter	Value
Particles	20
w	0.33
c_1	0.34
c_2	0.33

B. FEATURE SELECTION RESULTS

In the proposed work, initially 956 features were extracted using tf-idf. Feature selection was carried out using PSO to obtain the reduced feature subset. The following Table 4 depicts the number of features selected using tf-idf and tf-idf + PSO.

TABLE 4. Feature selection vs feature extraction.

Algorithm	Feature Extraction (tf-idf) #Features	Feature Selection (tf-idf+PSO) #Features	Features Selected (%)
NB	956	515	53.87
DT	956	809	84.62
SVM	956	883	92.36
K-NN	956	442	46.23
MLP	956	883	92.36

The basic feature extraction based on tf-idf filter used the same number of features, i.e., 956 for all classification algorithms. Applying PSO, the minimum number of features selected were 442 for K-NN, which is 53.77 % reduction in features. The maximum was 883 features for both SVM and NN which show only 7.64% reduction in features. The figure 6 depicts the average of feature selection.

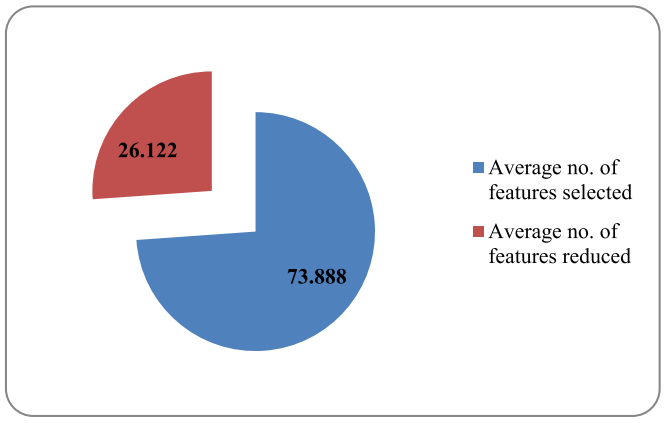


FIGURE 6. Feature reduction using PSO.

C. EFFECT OF FEATURE SELECTION ON CLASSIFICATION ACCURACY

This sub-section gives a comparison of the classification algorithms used, based on performance accuracy

(misclassification-error). It also demonstrates the advantage of using PSO based feature selection technique over the conventional tf-idf technique. Table 5 depicts the accuracy results.

TABLE 5. Accuracy obtained using before and after optimization.

Algorithm	tf-idf	tfidf + PSO	Accuracy Gain (%)
NB	75.158	88.256	13.098
DT	67.721	93.354	25.633
SVM	90.038	91.554	1.516
K-NN	79.905	90.759	10.854
MLP	89.829	92.452	2.623

The results indicate the maximum accuracy without optimization is achieved by SVM, i.e., 90.038%. The maximum accuracy gain was obtained by decision tree (25.633%). It can be clearly observed the classification performance is improved with the feature subset using PSO. The average improvement of 10.74% has been observed using PSO. Figure 7 shows the accuracy comparison graphically.

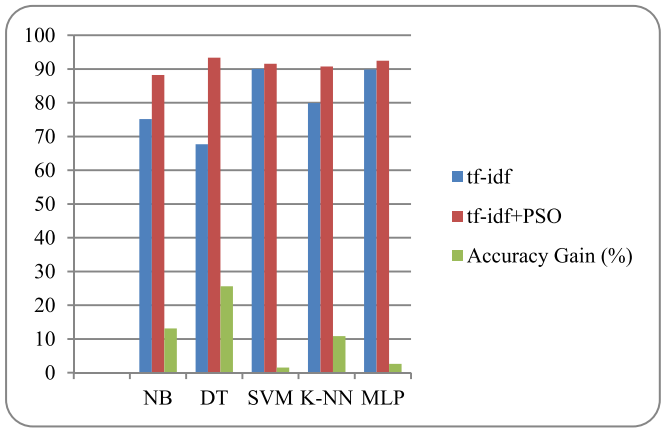


FIGURE 7. Comparison of accuracy with and without optimization.

The gain is accuracy is graphically depicted by figure 8.

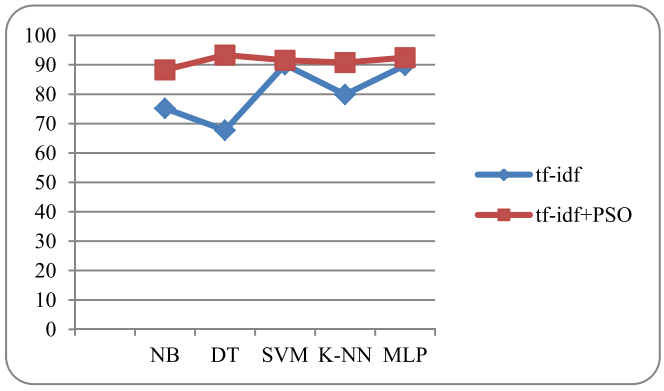


FIGURE 8. Accuracy Gain.

The performance of the training models is further evaluated using sensitivity (true positive recognition rate) and specificity (the true negative recognition rate). The following figure 9 depicts the result. DT has the highest true positive recognition rate of 98.9%.

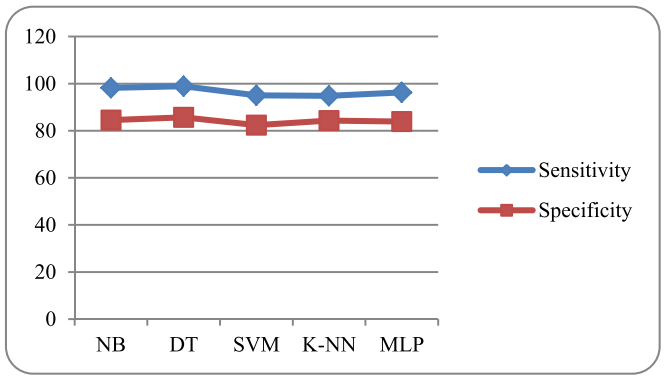


FIGURE 9. Sensitivity and Specificity of training models.

D. REDUCTION IN TIME

The aim of feature selection and optimization methods is to reduce the computational time and complexity of the prediction model. After feature selection, the five baseline classifiers are trained with the reduced feature subset and comparative analysis of the time for building the models has been done in order to evaluate reduction in time and to evaluate the effectiveness of the feature selection approach. The following figure 10 gives comparative results of the time for building various classification models thus evaluating the reduction in time.

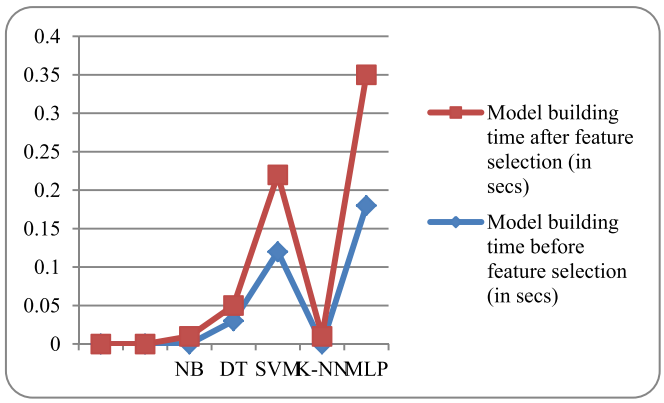


FIGURE 10. Reduction in model building time.

Maximum reduction in time is observed in building SVM with the value of 0.02 seconds whereas in all other classification models a reduction of 0.01 seconds is observed.

V. CONCLUSION

The effectiveness of fault-based testing depends on the quality of the fault model and analyzing faults in previous designs, to predict and avert similar faults in future product designs. This research proposed a predictive learning model to classify

faults which assists assessment of probable faults thus enhancing the quality of the web-apps. An empirical study to classify faults in bug reports of three open-source web applications and reviews of two play store applications using five baseline classifiers was conducted. These baselines were initially trained using conventional tf-idf feature extraction method and subsequently using an optimal feature selection method, particle swarm optimization algorithm. A total of 4577 bugs were analyzed based on accuracy as the performance metric of the classifier. The average accuracy gain is of about 11% was observed with nearly 74% features were selected on average. The empirical analysis validates that the PSO algorithm for feature selection optimization in fault classification task outperforms the elementary classification task based on feature extraction.

The results demonstrate and motivate to explore the use of other meta-heuristic algorithms, such as elephant search, bacterial foraging, cuckoo search, firefly algorithm and wolf search algorithms etc. The results can also be analyzed by using other intrinsic filters such as, information gain, chi-square and their hybrids with swarm-based wrapper algorithms. Fuzzy-logic and evolutionary algorithms can also be investigated to built optimal and robust predictive learning models for fault classification in web-apps.

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AN EXPLORATORY FACTOR ANALYSIS FOR DEVELOPING A SCALE OF ETHICS

A KNOWLEDGE MANAGEMENT PERSPECTIVE

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Vikas Gupta**

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PURPOSE
ETHICS has been broadly analyzed and explored from work-place perspective. However, research on ethics from knowledge management (KM) perspective is weak; very few empirical studies have been done in this regard. The paper aims to create scale for ethics to fill the gap. The scale which has been developed by the author(s) is aimed to be used for testing the relationship between ethics and KM in future.

Design/Methodology/Approach: *In this study, the existing literature was examined and it was then administered and investigated to 278 employees in different organizations. Exploratory Factor Analysis (EFA) was employed to determine the scale and further reliability of factors.*

Findings: *Five factors of ethics have been identified. These factors are: F1: Organizational Values and Ethical Climate; F2: Commitment, Responsibility, and Team Working Morale; F3: Intellectual Capital and Trusteeship; F4: Ethical Issues, and F5: Obstacles to Ethical Behavior.*

Research Limitations/Implications: *The scale is perceptual to assess and evaluate ethical dimensions, which may or may not be authentic indicator of ethical dimensions existing in the organization.*

Practical Implications: *The scale can be used as an instrument for investigating the effectiveness in KM process, KM ownership, and KM practices.*

Originality/Value: *The scale is a valid and reliable measure of ethical constructs. It is a credible tool to investigate ethical behavior and framework that the employees feel, think, and believe exists within their organization.*

Key Words: *Knowledge Management (KM), Ethics.*

Introduction

Ethics, in simple words, is all about right and wrong. As a field of study, there are two schools of thoughts that have emerged, teleological and deontological. Teleological perspective (Hume, 1750; Smith, 2002) refers to the consequence of an action as indicator of good or bad and deontology perspective (Kant, 1991) refers to the action as an ethical indicator. The other perspective to ethics is individual's behavior as ethical (Crisp, 2011).

In this era of knowledge based competition, organizations use unique, creative, and innovative techniques

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to improve their structure and enhance their performance (Michael, Mckeen, & Singh, 2009). In this endeavor to become successful, these organizations overlook the ethical issues. It has been noted that knowledge of ethics is derived more from employees' experience as compared to academic knowledge (Lee, 2010). With globalization and rapid technological changes, there is a need to address ethical issues, as the world is experiencing compromise on ethics like knowledge hoarding, manipulation, and misappropriation. Personal ethics, interpersonal behavior in moral ecology, and articulation and dissemination of ethical standards plays pivot role in addressing ethical concerns. There are various socio economical, technological, and legalistic issues which are obstacles for sustaining ethical culture in an organization. The ethics provide the organization with guiding principles for KM and facilitate effective implementation and execution of KM practices resulting in a win-win situation for all the stakeholders. The ethics is the independent variable which impacts the dependent variable KM. The available literature is limited for ethics impacting KM. The current study focuses on developing and testing research questionnaire for ethics from KM perspective.

Literature Review

Ethics

Ethics are behavioral codes which are recognized as right and good at individual level as well as societal level. Ethics provide a guideline for individual practice as well as collective practice in community (Tseng & Fan, 2011). The understanding of ethics in a community is dependent on value system of that particular community (Macintyre, 1985). Individuals being a member of organization as well as community are guided to respect ethical norms of organization and society to which they belong (Tseng & Fan, 2011). The ethics can be referred to as ideals embedded in a group or community of people and are reflected through their culture (Akhavan, Ramezan, & Moghaddam, 2013). Collective ethics of society or nation are referred to as ethos. Ethics are referred to good and bad attributes, conducts, intentions or moral duties, and commitments towards organization or society. Akhavan et al. (2013) has listed four dimensions of ethical principles: organizational value and justice; team working morale; intellectual ownership and trusteeship; and commitment and responsibility. Organizational values and justice is the most vital aspect of ethical principles constituting collective trust and organizational trust; fair, honest, and humble behavior of employees; criticism taking, and perseverance in works. Team working morale refers to ethical conduct while working in a team which involves cooperation, empathy, self-awareness, self-control, affability, and council with others. Intellectual ownership and trusteeship refers to obeying intellectual property rights, maintaining confidentiality, and trusteeship. Other ethical dimension includes responsibility, commitment, and loyalty towards organization. It also includes working conscience and being foresighted at work.

PRIMES model is explained by Huff (2010) as "a model comprising of several ethical parameters from individual and surrounding perspective. It constitutes personality, integration of morality, moral ecology, and skills" (p. 19). "Personality depicts work that people prefer and the path they choose to accomplish it" (John & Srivastava, 1999, p. 102). Integration of morality refers to moral commitment of individuals and gives direction to individual action in diverse situations. Moral ecology is the surrounding environment of an individual which influences and dominates individual action in diverse situation. Moral skills and knowledge is awareness that individual possess about different moral actions and content.

Obstacles to ethical behavior depict that behavior which individual persists to restrain share of knowledge and also includes manipulation of knowledge for individual interest or personal gain. Different obstacles to ethical behavior are knowledge hoarding, plagiarism, manipulation, misappropriation, and property and privacy right conflict. Sharing of tacit knowledge, that is, personal knowledge in form of ideas and experiences is dependent on owner's willingness to share as it serves as economic means to the employee. When employee hesitates in knowledge sharing

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with organization, it leads to knowledge hoarding. The knowledge is sometimes modified, altered, suppressed, amplified, and omitted for some personal interests or individual gain leading to manipulation and misappropriation of knowledge. There is also conflict among employee and organization over knowledge ownership. The former consider knowledge as a phenomenon carried in the mind of individuals whereas, the latter view knowledge as an asset created by providing the employees resources both financial & technological, infrastructure, and reward. Ethical issues comprise of technical issue, socio economic issue, and legalistic issue. Technical team responsible for designing and implementing of KM system come across a number of unethical aspects. In these situations, technical staff can act as a whistleblower to make management aware about the unethical aspects. Also, there is a hidden agenda for implementation of KM in an organization that accounts for socio economic issue in ethical practices. The underlying motivation to implement KM system is to capture employee's knowledge to reduce human resource cost by carrying out retrenchment in the organization (Bryant, 2006). Legalistic aspect in KM based organization is concerned with conflict over knowledge ownership right between employees and organization (Baskervile & Dullipovici, 2006) (as shown in table no. 1).

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Linking Ethics and KM

It is necessary to have ethical framework or collaborative ethical tool for KM system constituting several ethical parameters and constructs, as KM system might adopt unethical path to accomplish objectives and goals for profit and wealth maximization (Glisby & Holden, 2003). "Ethical approach to KM is built on trust, fairness, and justice as they stimulate individuals to participate in KM process. Trust prevents employees from knowledge hoarding" (Delong & Fahey, 2000, p. 113). "Trust facilitates sharing and creation of knowledge" (Burchell & Cook, 2008, p. 36). Trustworthiness among individuals in a group impacts the extent to which knowledge is shared. Where there is trust in an organization, individual can depend on organization to care for them. Trust enables colleagues and managers to freely share knowledge instead of hiding or protecting that knowledge. Patel & Ragsdell (2011) highlighted the need for a fair and ethical behavior.

Tseng & Fan (2011) highlighted the significance of an ethical organizational climate for facilitating knowledge processes. "The ethical approach to KM supports an organization to engage individuals in knowledge process and also to build database acquiring and retaining individual knowledge and experience" (Liebowitz, 1999, p. 37). Fair KM practices rewards individuals for their knowledge contributions (Baskerville & Dullipovici, 2006). According to Sen (1993), the organizations are rewarded for treating its employees in fair and equitable manner. "Organizations rewarding individuals with incentives for knowledge contribution encourages fairness" (Bock & Kim, 2002, p. 16). As suggested by Wang & Noe (2010), "knowledge processing behavior can prove to be motivational when it provides the benefits of recognition, promotion, and salary hike to the employees and also contributes in expanding their expertise and knowledge base" (p. 115). Also, "KM practices need to be fair and unbiased. The knowledge which individual possesses is an intellectual capital of the individual and organizations may refrain from controlling it" (Chen & Choi, 2005, p. 107; Gorman, 2004). According to Da Costa, Prior, & Rogerson, (2010), "atmosphere of fairness and equality can be seen where individuals feel driven to share, create, and process knowledge" (p. 580). On the basis of above discussion, it is proposed to link ethics and KM.

There are various Indian research studies on knowledge (Tomblin & Maheshwari, 2004), Leadership (Singh & Kumar, 2013), Organizational Culture (Kumar, 2012), Technology (Kumar, 2012), knowledge management (Singh, 2001; Grover & Banerjee, 2005; Sharma, 2005; Sharma, 2008; Singh & Sharma, 2008a; Singh & Sharma, 2008b; Singh & Sharma, 2008c; Singh & Sharma, 2008d; Kumar, 2014) per se and the factors affecting knowledge management, for example, technology (Kumar, 2012), Organizational Culture (Sharma, 2005; Singh & Sharma, 2011a; Singh & Sharma, 2011b; Kumar, 2014), leadership (Kumar, 2013), knowledge manager (Dutt, 2006), and how knowledge management results into higher employees satisfaction (Singh & Sharma, 2011b).

Table No. 1: Ethics Dimensions and Respective Indicators

S. No.	Dimensions	Indicators/Areas	Sources
1.	Organizational Value and Justice	Collective trust	Suhonen, Stolt, Katajisto, Charalambous, & Olson (2015), Akhavan et al. (2013), Azmi (2010a), Khenifer & Moghimi (2009), Ali (2008), Raps (2005), Inkpen & Tsang (2005), Hutchings & Michailova (2004), Galford & Drapeau (2003)
		Organizational trust	
		Honesty	
		Fair behaiviour	
		Humility	
		Criticism taking	
		Perseverance in works	
2.	Commitment and Responsibility	Responsibility	Suhonen et al. (2015), Akhavan et al. (2013), Bove & Jhonson (2012), Calof & Smith (2012), Michie & Johnston (2012), Jordan & Troth (2011), Azmi (2010b), Huysmans & Wit (2004), Chua (2002), Nahapiet & Ghosal (1998)
		Working conscience	
		Commitment	
		Loyalty	
		Foresight	
3.	Intellectual Ownership and Trusteeship	Secrecy	Sayce (2012), Azmi (2010b), Khenifer & Moghimi (2009), Akhavan et al. (2013)
		Intellectual property right	
		Trusteeship	
		Care in authenticity	
		Council with others	
4.	Team Working Morale	Helping and empathy with others	Akhavan, et al. (2013), Azmi (2010b), Meng-Hsiang & Fang-Yang (2003), Ferris (2008), Huysmans & Wit (2004), Chua (2002)
		Affability	
		Self-control	
		Self-control	
5.	PRIMES (Ethical Action Model)	Personality	Huff (2010)
		Integration of morality	
		Moral ecology	
		Skills & knowledge	
6.	Ethical Issues	Socio economic issue	Suhonen et al. (2015), Bryant (2006)
		Technical issue	
		Legalistic issue	
7.	Obstacles to Ethical Behaviour	Knowledge hoarding	Zyngier & Nagpal (2015)
		Manipulation	
		Misappropriation	
		Plagiarism	
		Property & privacy right conflict	
		Autonomy in knowledge sharing	

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Conceptual Model

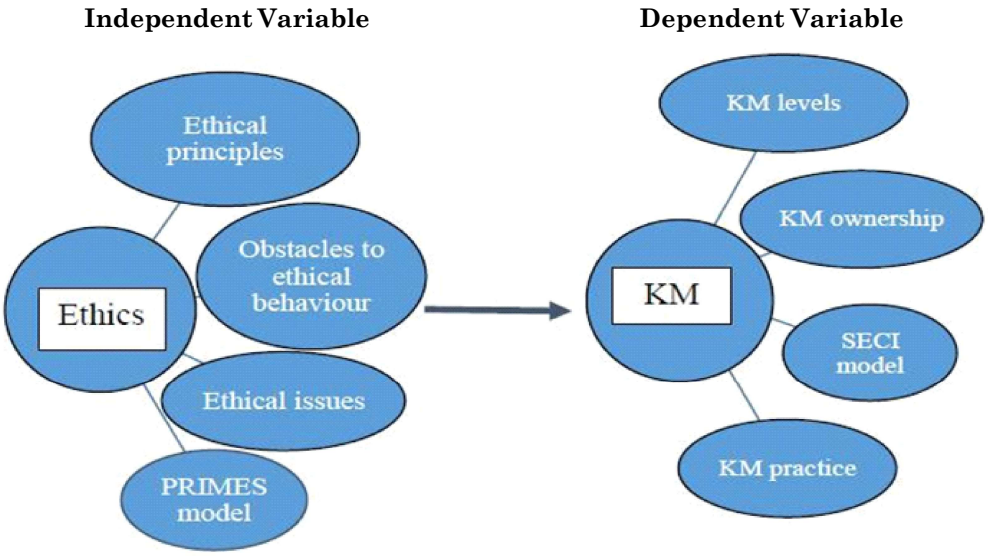


Figure No.1: Ethics impacting KM System

Source: Compiled by authors

Research Methodology

Study Design

An exploratory factor analysis was carried out with the primary objective of reducing the number of items and investigating that the factors/constructs stated in the literature are appropriate according to the present scenario. Also, grouping provided by the literature needed to be reviewed or regrouped. Initially, the process of Factor Analysis was considered to be used for identifying the ethical dimensions outlined in the literature. Subsequently, Exploratory Factor Analysis was used because of the possibility of identification of other meaningful factors involving combination of items. The factors resulted from the EFA were then tested for the reliability.

Research Instrument

The preliminary section of questionnaire demanded respondents to fill demographic details like age, gender, qualification, and work experience. The research instrument with 36 questions was created covering variables grouped under the constructs discussed in literature which includes organizational values and justice, commitment and responsibility, intellectual ownership and trusteeship, team working morale, ethical issues, obstacles to ethical behavior, individual ethics, and moral ecology. The variables so derived at the end were used after approval from various experts in the field of ethics, human resource, and compliance.

Participants

A convenience method of sampling was employed. The questionnaire was sent to 300 participants. There were 278 respondents to the questionnaire. All participants were assured of anonymity and confidentiality.

Analysis

The demographic details of the respondents are shown in table no. 2.

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Table No. 2: Demographic Details

Sample Characteristics	Frequency (n=278)	Percentage
Gender		
Male	186	67%
Female	92	33%
Age		
18-25	85	30%
26-35	119	43%
35-59	69	25%
60 and above	5	2%
Education		
Graduate	129	46%
Post Graduate	133	48%
Doctorate	16	6%
Experience		
Freshers	18	6%
1-5 years	120	43%
6-10 years	50	18%
10-20 years	72	26%
Above 20 years	18	7%

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The Exploratory Factor Analysis (Principle Component Analysis) employed a rotated component matrix to identify and reduce the number of factors and to make interpretation of analysis easier. Minimum factor loadings were set at 0.40 (Nunnally, 1978).

Principal-Axis Factor Analysis was employed using SPSS 22 to examine the dimensions of the constructs. The rotation method used in the paper is varimax rotation. The goal of varimax rotation is to simplify and clarify the data structure. The main goal of EFA is to extract the smallest number of interpretable factors contributing to the correlation among of variables. The items that are grouped together after applying EFA are said to measure the same underlying construct (Kerlinger, 1986). EFA is helpful when the researchers are trying to understand the dimensions of a construct. It also helps in identifying the variables which do not have any contribution in the construct.

EFA is the first step to identify and extract important variables which could be further tested using Confirmatory Factor Analysis. The 33 scale items loaded on to 5 factors accounts for 60.61% of the explained variance (as shown in table no. 3).

Extraction Method: Principal Component Analysis

The Kaiser-Meyer Olkin measure (Cerny & Kaiser, 1977; Kaiser, 1970) of sampling adequacy was 0.910 as shown in table no. 4. The 'p' value is less than 0.01, so it could be construed that EFA is an appropriate strategy. Further, the Bartlett's Test of Sphericity (Bartlett, 1950, 1951) yielded a Chi-Square value of 4851.993, with 528 df.

Table No. 3: Total Variance Explained

Component	Initial Eigen Values			Extraction Sums of Squared Loadings			Rotation Sums of Squared Loadings		
	Total Variance	% of Variance	Cumulative %	Total Variance	% of Variance	Cumulative %	Total Variance	% of Variance	Cumulative %
1.	10.72	32.47	32.47	10.72	32.47	32.47	8.05	24.40	24.40
2.	4.38	13.28	45.76	4.38	13.28	45.76	4.75	14.40	38.80
3.	2.07	6.27	52.03	2.07	6.27	52.03	3.03	9.18	47.98
4.	1.66	5.02	57.04	1.66	5.02	57.04	2.51	7.61	55.59
5.	1.18	3.57	60.61	1.18	3.57	60.61	1.66	5.02	60.61
6.	0.97	2.94	63.55						
7.	0.89	2.70	66.25						
8.	0.83	2.53	68.78						
9.	0.77	2.33	71.11						
10.	0.75	2.27	73.38						
11.	0.67	2.03	75.41						
12.	0.62	1.88	77.29						
13.	0.60	1.81	79.10						
14.	0.58	1.75	80.85						
15.	0.56	1.71	82.56						
16.	0.55	1.66	84.22						
17.	0.47	1.41	85.63						
18.	0.46	1.38	87.01						
19.	0.41	1.25	88.26						
20.	0.41	1.24	89.51						
21.	0.38	1.15	90.65						
22.	0.37	1.14	91.79						
23.	0.36	1.11	92.89						
24.	0.33	1.01	93.90						
25.	0.30	0.92	94.82						
26.	0.28	0.83	95.65						
27.	0.26	0.80	96.45						
28.	0.25	0.76	97.21						
29.	0.22	0.66	97.88						
30.	0.20	0.61	98.48						
31.	0.19	0.58	99.06						
32.	0.18	0.54	99.60						
33.	0.13	0.40	100.00						

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Table No. 4: KMO and Bartlett's Test

Kaiser-Meyer-Olkin Measure of Sampling Adequacy.		0.910
Bartlett's Test of Sphericity	Approx. Chi-Square	4851.993
	Df	528
	Sig.	0.000

Factors were extracted with the Eigen Values more than 1. Items were removed when communalities were less than 0.40 as shown in table no. 5. This resulted in the deletion of 3 items, reducing the total number of items to 33. Communalities displays variance that variable has been accounted for extracted factors. In the communalities 31 variables out of 33 variables displayed more than 0.5 variance.

Table No. 5: Communalities

S. No.	Items/Variables	Initial	Extraction
1.	Employees take social responsibility of their actions.	1.00	0.59
2.	My colleagues are available for counseling at the time of confusion.	1.00	0.60
3.	Employees do not modify or change the information for their personal gain.	1.00	0.59
4.	It is important for employees to have fair and impartial behavior with each other.	1.00	0.66
5.	Employees behave honestly with each other.	1.00	0.71
6.	Consultation with others in tasks and decisions is important for employees.	1.00	0.40
7.	Care in Authenticity (assessing the accuracy of a subject) is important.	1.00	0.62
8.	The behavior of employees in my organization is fair and friendly.	1.00	0.49
9.	Employees have high work consciousness.	1.00	0.68
10.	Employees are responsible and accountable for their tasks.	1.00	0.64
11.	Employees moral actions are influenced by surrounding people in organization	1.00	0.66
12.	Employee's personal characteristics & skills guide their moral actions.	1.00	0.62
13.	Having good manners and openness is admired.	1.00	0.56
14.	Information confidentiality of employees and organization is very important and emphasized.	1.00	0.53
15.	Self-control is important for employees and its emphasized by the organization.	1.00	0.46
16.	Employees do not keep their personal knowledge with themselves rather they share it.	1.00	0.54
17.	Too much autonomy in knowledge sharing is a barrier.	1.00	0.59
18.	Employees trust each other and deal with each other in good faith.	1.00	0.56
19.	Manipulation and misappropriation hinders knowledge sharing.	1.00	0.60

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S. No.	Items/Variables	Initial	Extraction
20.	Sharing knowledge and legal issues are inter-related.	1.00	0.57
21.	The boundaries of my knowledge and organizational knowledge are sometimes confusing.	1.00	0.66
22.	Employees feel committed towards organization's goals & mission and their responsibilities.	1.00	0.63
23.	Employees are sympathetic to each other and are willing to help each other.	1.00	0.73
24.	Trusteeship is important and considerable for all members.	1.00	0.76
25.	Employee designing & implementing KMS can act as Whistle-blower.	1.00	0.65
26.	Considers Intellectual Property Right as important and it is emphasized.	1.00	0.63
27.	Employees are loyal to organization and to each other.	1.00	0.71
28.	Employees trust that organizational policies will be done according to given promises.	1.00	0.61
29.	Employees have foresight in their actions and decisions, according to organization's vision.	1.00	0.50
30	Employees and managers trust each other and deal with each other in good faith.	1.00	0.59
31.	Tolerance and perseverance of people in tasks is valuable.	1.00	0.72
32.	Modesty and courtesy is value and virtue.	1.00	0.65
33.	Capturing employees' knowledge into information system leads to downsizing or retrenchment.	1.00	0.50

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Table no. 6 has the five factors with the variables and their respective factor loadings. The final 33 items that comprised the independent variable, 'Ethics' are also presented in the same table. The five factors identified are: F1: Organizational Values and Ethical Climate; F2: Commitment, Responsibility, and Team Working Morale; F3: Intellectual Capital and Trusteeship; F4: Ethical Issues, and F5: Obstacles to Ethical Behavior. A factor with fewer than three items is generally weak and unstable; the factors identified have at-least three variables.

In order to estimate reliability, the value of Cronbach Alpha was calculated for each construct (factor) identified through Factor Analysis. As per Nunnally (1978), factors having alpha below 0.70 should be deleted. However, various scholars have also pointed that in exploratory studies alpha less than 0.70 can also be considered, i.e., between 0.50 and 0.70 (Frazier & Rody, 1991; Katabe, 1990; Kohli, 1989; Noordewier, John, & Nevin, 1990). The threshold 0.50 is used in this research (F1-F5). The Cronbach Alpha for all 33 variables is 0.910, that is, above minimum threshold of 0.7 as suggested by Nunnally (1978). There are five constructs and four constructs have been above the minimum threshold of 0.7. The reliability statistics is given in table no. 7.

Discussion and Conclusions

The main objective of the study is to examine that constructs derived from the literature are valid as per the current sample statistics or they need to be reframed by regrouping of the variables according to the obtained statistics. According to the literature, there were seven constructs formed from the

Table No. 6: Factor Loadings

Factor No.	Item No.	Variables/Items	Component				
			1	2	3	4	5
F1	**S16**	Employees do not keep their personal knowledge with themselves rather they share it.	0.696				
F1	**S3**	Employees do not modify or change the information for their personal gain.	0.726				
F1	**S18**	Employees trust each other and deal with each other in good faith.	0.671				
F1	**S28**	Employees trust that organizational policies will be done according to given promises.	0.758				
F1	**S5**	Employees behave honestly with each other.	0.712				
F1	**S4**	It is important for employees to have fair and impartial behaviour with each other.	0.704				
F1	**S32**	Modesty and courtesy is value and virtue.	0.665				
F1	**S31**	Tolerance and perseverance of people in tasks is valuable.	0.842				
F1	**S8**	The behavior of employees in my organization is fair and friendly.	0.840				
F1	**S1**	Employees take social responsibility of their actions.	0.736				
F1	**S30**	Employees and managers trust each other and deal with each other in good faith.	0.762				
F1	**S13**	Having good manners and openness is admired.	0.815				
F1	**S12**	Employee's personal characteristics & skills guide their moral actions.	0.713				
F1	**S11**	Employees moral action are influenced by surrounding people in organization	0.572				
F2	**S10**	Employees are responsible and accountable for their tasks.		0.582			
F2	**S9**	Employees have high work consciousness.		0.581			
F2	**S22**	Employees feel committed towards organization's goals and mission and their responsibilities.		0.813			
F2	**S27**	Employees are loyal to organization and to each other.		0.783			
F2	**S29**	Employees have foresight in their actions and decisions, according to organization's vision.		0.793			
F2	**S6**	Consultation with others in tasks and decisions is important for employees.		0.770			
F2	**S23**	Employees are sympathetic to each other and are willing to help each other.		0.562			

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Factor No.	Item No.	Variables/Items	Component				
			1	2	3	4	5
F2	**S15**	Self-control is important for employees and its emphasized by the organization.		0.685			
F2	**S2**	My colleagues are available for counselling at the time of confusion.		0.553			
F3	**S26**	Considers Intellectual Property Right as important and it is emphasized.			0.709		
F3	**S24**	Trusteeship is important and considerable for all members.			0.771		
F3	**S7**	Care in Authenticity (assessing the accuracy of a subject) is important.			0.732		
F3	**S14**	Information confidentiality of employees and organization is very important and emphasized.			0.592		
F4	**S25**	Employee designing & implementing KMS can act as Whistle-blower.				0.748	
F4	**S33**	Capturing employee's knowledge into information system leads to downsizing or retrenchment.				0.818	
F4	**S20**	Sharing knowledge and legal issues are interrelated.				0.727	
F5	**S19**	Manipulation and misappropriation hinders knowledge sharing.					0.662
F5	**S21**	The boundaries of my knowledge and organisational knowledge are sometimes confusing.					0.633
F5	**S17**	Too much autonomy in knowledge sharing is a barrier.					0.575

Table No. 7: Reliability Statistics

Factor No.	Factors/Dimensions	No. of Items	No. of Cases	Cronbach's Alpha
	Overall Reliability	33	278	0.91
F1	Organizational values and ethical climate	14	278	0.95
F2	Commitment, responsibility and team working morale	9	278	0.89
F3	Intellectual capital and trusteeship	4	278	0.81
F4	Ethical issues	3	278	0.75
F5	Obstacles to ethical behavior	3	278	0.53

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grouping of different variables. The EFA in the current study resulted in five constructs (factors) comprising of 33 variables. The five factors resulted from EFA are named as, F1: Organizational Values and Ethical Climate; F2: Commitment, Responsibility, and Team Working Morale; F3: Intellectual Capital and Trusteeship; F4: Ethical Issues, and F5: Obstacles to Ethical Behavior.

The study deliberates on ethical constructs specifically from KM perspective. There is deliberation on various obstacles to ethical behavior in KM. These obstacles comprises of knowledge hoarding, manipulation, misappropriation, and privacy rights. The various ethical issues from KM perspective which includes socio economic, legal, and technical issues have also been discussed. The knowledge management in ethical context can be effective in an organization if individual's personality, his environment, commitment towards morality, and moral skills and knowledge are studied in depth. When all these parameters of ethics discussed in the paper would be embedded in the culture of an organization, it will support KM processes, KM practices, and all KM initiatives.

Limitations of the Study

This study does not cover any specific population or profession, neither any specific industry. Thus, this is a generalized research for all professions or industries. The sample of the study constituted 278 respondents from different professions and industries. The sample size could have been larger as larger sample size would have given more appropriate findings. This study has focused on quantitative methodology of data collection and thus, it is restrictive. Moreover, the scale facilitates employees to assess and evaluate ethical dimensions, which may or may not be authentic indicator of ethical dimensions existing in the organization. As it is according to what employee feel, think, and believe about a particular ethical framework that exists within their organization which may or may not be authentic.

Future Research

Research could be conducted to establish the relationship between ethics and KM. The link between ethics and KM may be established for ethical conceptualization of KM. Ethical framework supporting KM initiatives and KM process should be developed and implemented. Further, the impact of ethics on KM processes and activities can be accessed and measured. The scale can be used as an ethical instrument for investigating effectiveness in KM process, KM ownership, and KM practices. For practical implications, managers should understand that adoption of KM processes will not guarantee success until supported by the ethical framework. KM systems can be implemented and executed more successfully in those organizations where there is more emphasis on ethics by the organizations.

The research instrument developed through this study, that is, ethical constructs created using EFA will help to link ethics and KM in future studies. The current research will also add to the literature and knowledge domain in the area of ethics and KM.

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Classification of Fish Species Using Deep Learning Based Hybrid Model

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Abstract

The establishment of a Fish Classification System for estimating the population of fish species and understanding their interactions amongst themselves has grown into an undeniable necessity in the past few years. In order to accurately classify fishes in underwater videos with inconsistency in illumination and uncontrolled environments, scaling to a larger dataset and using appropriate features is of foremost importance. Most researchers have presented either a static or a small-scaled solution to the existing problem of Fish Classification. Our Approach, Deep Convolutional Networks Driven Classification Algorithm (DCNDCA) incorporates the efficiency of Deep Convolutional Neural Networks with the scalability and flexibility of other algorithms, making it a reliable and adaptable system in various scenarios. DCNDCA gives promising results in the classificiation of fish species when evaluated against a standard dataset.

Keywords: Fish Classification, Convolutional Neural Networks, Ensemble Techniques, Hidden Markov Model, Naive Bayes

1 Introduction

With a humongous increase in the number of endangered fish species, oil spill accidents and other activities which pose a potential threat to marine species, enumerating and categorizing fish species is of vital significance in marine sciences. The evaluation and classification of fish species, therefore provide crucial insights into the population of individual fish species, their interactions amongst themselves and with the shared biological environment.

Significant amount of work has been carried out to accurately classify fishes outside water bodies [1-4] or in areas with controlled environmental factors such as sufficient lighting[5], backgrounds and so on. However, the problem of accurate classification of fishes taken from underwater videos is still devoid of remarkable solutions. The major challenges include inconsistent illumination, altering colours, inherent blur and noisy overlaps in the images. Therefore, characterizing this multi-class fish classification problem as a fascinating machine learning and computer vision problem. The existing work in the field of fish classification either incorporates a meagre dataset with less number of fish species or results in an unsatisfactory accuracy.

Our proposed approach **Deep Convolutional Networks Driven Classification Algorithm (DCNDCA)** uses a larger dataset, and incorporates a composition of various classification techniques including Averaging Ensemble techniques such as Random Forests and Extremely Randomized Trees, Hidden Markov Models and Multinomial Naive Bayes with a deep learning module of Convolutional Neural Networks[6]. These classification techniques, when applied on the dataset directly resulted in low accuracy solutions, thereby making them inefficient for real time application. The accuracy of the classification techniques saw a substantial upsurge when incorporated with partially trained CNN, thereby making our hybrid model adaptable and robust to larger datasets.

The efficiency of Deep CNNs in learning features of a large dataset, combined with the intrinsic randomness of ensemble methods, the scalability of Multinomial Naive Bayes or with the flexibility of Hidden Markov Models with regard to unobserved variables makes our proposed model adaptable and reliable in versatile scenarios.

The rest of the paper is organized as follows. In Section II, we describe the existing algorithms and approaches in the domain of fish classification. In Section III, we present the approach and architecture of our proposed section. Section IV summarizes the performance

of our model and compares it with the results of previously proposed solutions. The conclusions for the paper are drawn in Section V.

2 Related Work

Several systems have been developed for classifying fishes, however they aren't adequete for scaling to a larger dataset or working with a satisfactory accuracy.

Andres Hernandez-Serna et al. [7] realised an ANN (Artificial Neural Network) model for the identification of fish species. They used deep learning on 697 geography specific fish images as the dataset and the accuracy for that model was found to be 91.65%. It was concluded that the deep learning image recognition methods were useful but their transferability and resolution are poor because species differ between geographic regions and the classifier requires a varied dataset to improve such parameters.

Andrew Rova et al. [8] implemented underwater classification of two fish species using videos shot by a standard uncalibrated camera. Their paper presented a deformable template object recognition approach where texture parameters were used for classification however parameters such as colour and shape were not used for the particular types of fishes. A support vector machine model was trained on a dataset of 320 images and the model achieved a 90% accuracy for two fish species.

Contrarily, D. J. Lee et al. [9] developed an algorithm to analyse shape. They removed redundant data points and located the critical points by performing curvature analysis. The contour points were understood as points of interest and were used for training the classifier. Contours of each image were extracted to form a closed curve for shape analysis. A small set of 22 images was used to implement the model for 9 target fish species.

Yun-Heh Chen-Burger et al. [10] also proposed an automated video processing system for classification. They used fish texture and colour properties of each frame as the basis for classification. Properties such as brightness, smoothness, hue, saturation and value were combined with a tracking system. The dataset of 360 images was converted to a gray level histograms and an average accuracy of 85% was reported.

Rodrigues et al. [11] worked with a small dataset of 162 images and implemented fish classification through a feature-extraction, preprocessing based approach. PCA (Principal component analysis) and SIFT (Scale Invariant Feature Transform) were used to perform feature extraction and parameterize shape, appearance, and motion. Clustering of training data was implemented using Artificial Immune Network and Adaptive Radius Immune Algorithm. Query data was processed using the extraction techniques and a simple nearest neighbor classification was used over the clustered trained data. The accuracy was observed as 92% for 6 species.

Also using nearest neighbor classifier for classification, Snigdhaa Hasija et al. [12] proposed representation of training image data as Grassmannian manifolds on a larger dataset of 840 images. The approach was to represent different species of fish as different image sets and execute image set matching. Each image set has been modelled as a subspace and a graph embedding discriminant analysis algorithm is used to classify fish species on the modelled data. The accuracy achieved was 91.66%.

Yi-Haur Shiau et al. [13] provided an approach for fish recognition and verification using sparse representation-based classification (SRC) based on comprehensive sensing. Maximum probability of partial ranking method is applied over the SRC method. A dataset of 1000 fish images of 180 rows and 130 columns is trained for 25 species. The maximum accuracy that could be achieved was 81.8% through this approach.

D. Joo et al. [14] implemented automatic classification of cichlid fishes by extracting features of colour and stripe patterns from a large dataset of images. The extracted features were evaluated using Support Vector Machine, Random Forest algorithms. 594 cichlid fishes from 12 classes were successfully classified in the evaluation stage, achieving an accuracy of 78%. The accuracy is low given that the classifier is only trained for cichlid fishes.

SÃľbastien Cadieux et al. [15] presented an automatic system for counting fish by species in their paper. An infrared silhouette sensor is used i.e. the approach involves classification using fish shape. Bayes maximum likelihood classification and OCON neural network are used to produce a combined result. The maximum accuracy achieved is 72% which is low. The input features are not robust and are susceptible to noise with addition of new species.

M. S. Nery et al. [16] proposed a finding for appropriate feature set for fish classification. For each fish species, 47 different features are determined. An effort is made to determine the most robust features from this set based on discrimination provided by the feature and its uncorrelatedness/independence from other features. The author reports the future scope of extracting robust features using FCA and PCA.

These proposed approaches do not meet the required accuracy standards for real-time usage. Besides that, the existing work learns from an inadequate dataset with a smaller number of fish species, thereby reducing their applicability. Our proposed approach, DCNDCA learns from a larger dataset, and uses a composition of various techniques, resulting in higher accuracy than previously proposed approaches. It incorporates the positive features of various approaches, thereby resulting in an adaptable and reliable model capable of producing promising results in various scenarios.

3 Problem Specification

Fish Classification holds indispensable significance in order to understand the interaction of species amongst themselves and with the surrounding marine environment. While notable work has been carried out in classifying fish species in a controlled environment and sufficient lighting, the problem of classifying fishes in in underwater videos, devoid of constant illumination and stable colours poses a significant challenge to researchers. We aim to develop a reliable model, which classifies fish species with high accuracy.

4 Proposed Approach

We propose a hybrid classification algorithm, Deep Convolutional Networks Driven Classification Algorithm (DCNDCA) that uses Deep CNNs in conjugation with state-of-the-art classification techniques. The proposed approach is chosen to exploit the 2-dimensional structure of the input image using CNN and extract easily separable, fully-connected vectors for different classes. Our approach is novel in comparison to previously proposed approaches because it combines the deterministic and discriminative model of CNNs with the probabilistic characteristics of Multinomial Naive Bayes and HMM, and decreased variance in Ensemble techniques; thereby resulting in reduced overfitting, higher adaptability and increased flexibility of the classification module.

In the following subsections, we explain the architecture of our approach and the working of each phase in detail.

4.1 System Architecture

The architecture of the proposed system contains three segments - the Preprocessing phase, Deep Learning phase and Composition phase in classification. The pre-processing phase is used to remove interdependencies in the images of the fish species. The pre-processed images are then passed on to the Deep Learning phase which attempts to learn the intrinsic characteristics for each fish species. Finally, the composition algorithm is used to classify the incoming image to the respective output class.

4.2 Preprocessing Input Data

A nonlinear dimensionality reduction technique **Locally Linear Embedding using Hessian Eigenmaps**[17] was used to visualize the dataset, after segmenting the fishes from the background by using the available masks.

Locally Linear Embedding Using Hessian Eigenmaps can be optimized faster while using sparse matrix algorithms. It doesn't necessarily requires the subsets to be convex, and the resulting global embedding is approximately linear in the set of local tangent coordinates.

First, n nearest neighbours of a point is found, and then it is re-centred around the average of its neighbouring points. The next step is to perform Singular Value Decomposition to obtain matrices U, V and D. After that Hessian Eigenmaps based optimization technique is used to find embedding of the points.

Using the Algorithm 1, the accuracy of the feature extraction process increased, along with minimizing the noise.

Algorithm 1: Locally Linear Embedding using Hessian Eigenmaps

Data: Training Dataset
Result: Transformed Dataset
1 Find n nearest neighbours for a given point.
2 Recentre the points w.r.t its neighbours and perform singular value decomposition.
3 Determine the Hessian Estimator and develop its quadratic form.
4 Find the corresponding Null Space and its Basis.

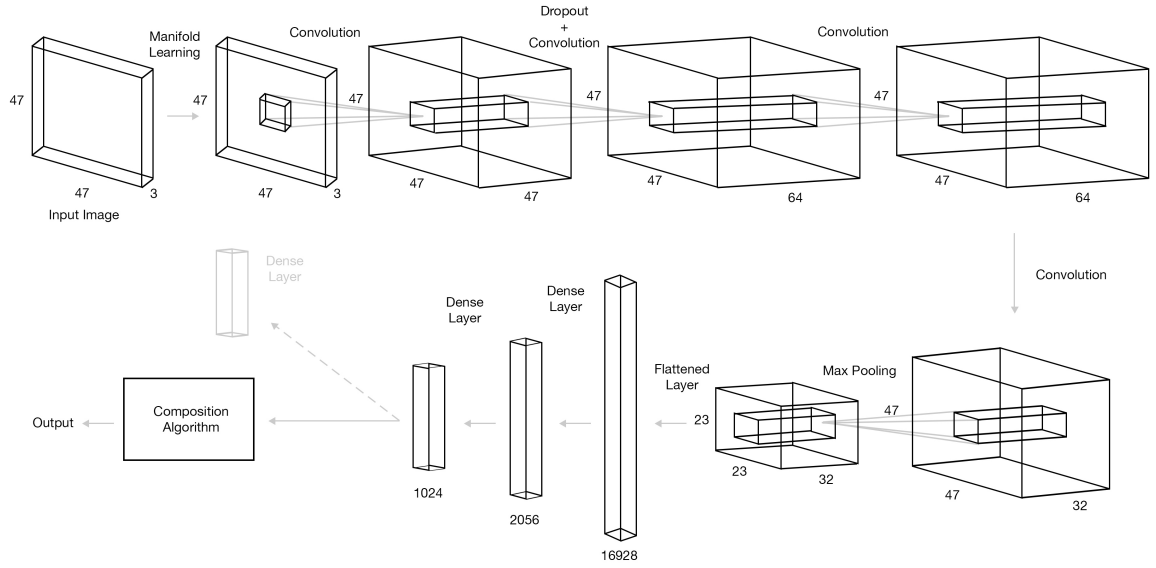


Figure 1: System Architecture

4.3 Deep Learning Phase - Training Convolutional Neural Networks

We describe the process of partially training our image data using deep learning convolutional neural networks. [6] Our aim from the CNN model is to derive a hidden layer in the form of a vector that represents the image data. We use the preprocessed image from the manifold algorithm as the input layer to the CNN model. The hidden layers consists of convolutional layers,pooling layers, dropout layers, and flattening layers. The layer parameters are chosen to such that there is a balanced trade-off between computation, complexity, and efficiency.

Convolutional Layer

A convolution layer, that forms the basic building block of deep CNN, performs a dot product operation between various filters and local spatial units of the input matrix. A filter is a small region with small height, width dimensions, but equal depth compared to the input. These filters slide across the input volume with a value parameter known as stride. The convolution computes two-dimensional activation maps of the filters over the input volume. These filters are hence used as learned patterns which get activated when a visual feature (corresponding to the filter) is found in the test image.

ReLU Layer

The rectified linear unit layer is used to rectify the input to a neuron. A ReLU layer hence activates the input and is a preferred approach over sigmoid or hyperbolic functions since such functions tend to saturate and lower the accuracy of the network. It is defined as:

$$f(x) = max(0, x) \tag{1}$$

By rectification, it sets all negative valued units of the convolution layer to zero.

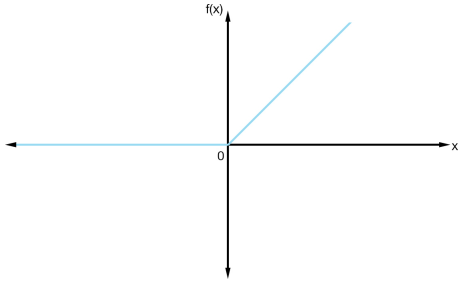


Figure 2: ReLU Function

Pooling Layer

We use a pooling layer of window size 2x2 and stride of 2 to reduce the spatial size and computation for the hidden layers, thereby reducing

overfitting and computational cost. We use a max-pool layer that extracts the maximum value from the defined window in the hidden layer. Since the stride for pooling is specified as two, the height and width of our hidden layer gets halved.

Dropout Layer

A dropout layer is a regularisation layer that prevents overfitting by avoiding the adaptation of neurons with each other. Here, we switch off one or more neural network nodes in the learning phase to make the connected nodes insensitive to these mute nodes. This enhances the generalisability of the model as the influence of nodes decreases by the dropout.An ideal dropout of 0.2 and 0.5 (20% and 50% of the neurons) is chosen to decrease codependency of these nodes and enhance accuracy in the convolutional and dense layer respectively.

Flattening Layer

This layer is used to flatten the convolution layer of the model to a one-dimensional feature vector that is further used by the neural network (ANN) layer. This step is crucial as it provides a vector layer that can be processed and used as input to other composition models, thereby allowing the extraction of layer from a partially trained CNN model and creation of a hybrid modelled system.

Fully Connected Layer

This layer has full connections to all the activations present in its previous layer. We use this layer to represent the output of the CNN model using softmax activation function. For the last Fully Connected Layer, the number of nodes in this layer represents the number of output class labels. The softmax function compresses the input vector to a k-dimensional vector having real values in the range [0,1] whose sum is 1. Since the sum of the output values is 1, it is suitable to use this as the activation for the output layer that would represents the probabilities of the given input belonging to each class label. The softmax function is given as:

$$\theta(z_j) = \frac{e_j^z}{\sum_{l=1}^{k} e_l^z} \tag{2}$$

Here k represents the number of output classes. The Algorithm 2 specifies the architecture of our solution. The first layer being the convolutional layer, followed by a dropout layer. After that, three convolutional layers follow, and then the features are pooled and converted into a fully connected layer. Lines 8-9 specify dense layers, which is followed by another dropout layer. A dense layer with Softmax Activation function is then used to classify the input.

Algorithm 2: Deep Learning Module

Data: Set of images obtained after applying Manifold Learning

Result: A 1024 x 1 vector which represents each image and is fed as an input to other algorithms

1 Add a convolutional layer with 47 filters, relu activation function and a kernel size of (3,3).
2 Add a dropout layer, by setting 20% of the output of the previous layer to 0. This is done to prevent overfitting.
3 Add a convolutional layer with 64 filters, relu activation function and a kernel size of (3,3).
4 Add a convolutional layer with 64 filters, relu activation function and a kernel size of (3,3).
5 Add a convolutional layer with 32 filters, relu activation function and a kernel size of (3,3).
6 Add a pooling layer with pool size = (2,2)
7 Convert it into a fully connected layer.
8 Add a dense layer with 2056 units with relu activation function.
9 Add a dense layer with 1024 units with relu activation function.
10 Add a dropout layer, by setting 50% of the output of the previous layer to 0.
11 Add a dense layer representing the number of classes with softmax activation function.

4.4 Composition with other algorithms

We propose various algorithms which are used in composition with the partially trained Convolutional Neural Nets. The last layer of the partially trained CNN is fed as an input to the following algorithms which further classify the input into one of the possible fish classes.

Averaging Ensemble Methods

We briefly describe the working of averaging ensemble methods which gives us an average of the results of numerous independent estimators. The pre-eminence of this method lies in the reduction of variance in comparison to using estimators independently. In our paper, we implemented two of these techniques - **Extremely Randomized Trees** [18] and **Random Forests**[19]. These methods are build upon randomization of decision trees[20].

Metrics: Since, at each step of individual trees, we have to determine the best split, the following metrics were incorporated:

Gini Impurity
It determines the frequency of inaccurately labeling the selected sample based upon the inherent distribution of samples in the chosen subset. It is defined as the sum of product of probability of a sample belonging to a label i and the probability of inaccurate classification. For labels in 1,2,....L and ρ_i being the percentage of samples belonging to class i.

$$G(\rho_i) = \sum_{i=1}^{L} \rho_i \sum_{k!=i} \rho_k \tag{3}$$

Information Gain
This metric is based upon the phenomenon of entropy, which is defined as follows: For ρ_i being the percentage of class i existing in child node in a tree Γ,

$$\xi(\Gamma) = -\sum_{i=1}^{L} \rho_i log_2(\rho_i) \tag{4}$$

Information Gain is defined as the difference of Entropy of the parent node and the weighted sum of children nodes. For α children nodes of a node in a tree Γ, Information gain is defined as follows:

$$I(\Gamma, \alpha) = \xi(\Gamma) - \xi(\Gamma|\alpha) \tag{5}$$

Random Forests: The best split is determined over a random set of features, rather than amongst all features. This, therefore results in increase in the bias of forest, but the corresponding decrease in the variance compensates the bias increment.

Algorithm 3: Composition with Random Forest

Data: A N x 1024 matrix, where each row represents a unique input
Result: Output Class of the Fish

```
1 num(trees) = 0
2 while (num(trees) ≠ η) do
3 |   while (num(nodes) ≠ γ) do
4 |   |   Randomly Select β features
5 |   |   Calculation of node Θ using
  |   |    ScoringCriterion; where Scoring
  |   |    Criterion ⊆ ⟨ Gini, InformationGain ⟩
6 |   |   Split Θ into daughter nodes
7 |   end
8 end
```

From lines 2-5, the algorithm 3 generates new trees, till they are equal to η number of trees. From lines 3-5, the algorithm keeps on splitting nodes based upon the ScoringCriterion by randomly selecting β features till the number of nodes aren't equal to γ
The use of Random Forests reduces the risk of overfitting by averaging over several trees. At the same time, it results in less variance, thereby providng a solution with higher accuracy.

Extremely Randomized Trees: By using Extremely Randomized Trees, variance of the algorithm can further be diminished by drawing random thresholds for every prospective feature and then choosing the best amongst them to split parent node. Following is the algorithm for Composition of Partially Trained CNN with Extremely Randomized Trees:

Algorithm 4: Composition with Extremely Randomized Trees

Data: A N x 1024 matrix, where each row represents a unique input
Result: Output Class of the Fish

```
1  RandomSplit (Batch Ω, Input Θ){
2  Find minimal value of Θ_min and Θ_max in the
     input Θ in Ω.
3  Select a random split point Θ_c in [Θ_min,
     Θ_max]
4  Split input at Θ_c
5  Return [Θ < Θ_c]
6  }
7   Stop (Batch Ω) {
8  if ( length(Ω < η_min || AreInputsConstant(Ω)
     || IsOutputConstant(Ω)) then
9  |   Return True
10 end
11 else
12 |   Return False
13 end
14 }
15  NodeSplit (Batch Ω correlating to
     Input Node){
16 Possible-Splits = Empty-MaxHeap with
     Scoring Criterion ⊆ ⟨ Gini, InformationGain
     ⟩
17 Return-Split = φ if (!Stop(Ω)) then
18 |   Choose P features in Ω among all non
   |    constant features.
19 |   for (j in (1,2...P)) do
20 |   |   Possible-Splits.insert(RandomSplit (Ω,
   |   |    Θ_j))
21 |   end
22 |   Return-Split = Possible-Split[0]
23 end
24 Return Return-Split
25 }
```

The **RandomSplit** Procedure randomly splits an input Θ in batch Ω across the value Θ_c The **Stop** Procedure stops further tree-building procedure if the inputs or outputs in the batch Ω are constant or the size of the batch Ω is

less than the minimum defined size η_{min}. The **NodeSplit** Algorithm splits a node randomly for each candidate feature and returns the one with maximum score. A heap can be used to implement the same.

The algorithm 4 results in smoother decision boundaries, and at the same time reduces the variance of the classifier because of the presence of extra-randomized trees, which results in higher accuracy of the solution.

Hidden Markov Model

We aim to perform classification by making probabilistic models of a linear sequence using Hidden Markov Models [21] to determine the output class of the vector obtained from the partially trained CNN layer. Given a sequence input to a Hidden Markov Model, it can compute the probability of a new input sequence belonging to the model. If each class is modelled using HMM, the probabilities of a new input vector belonging to each class can be computing using each model. This provides an approach that assumes the flattened vector as sequential data and becomes a unique, promising candidate for comparison along with other models.

For each output class label, we define a HMM model and obtain its emission and transition probabilities in the training phase using Baum Welch algorithm. The HMM system consists for visible states and hidden states that are derived from the observed visible states. The probability that the system makes a transition from one hidden state to another in a sequence is referred as transition probability. Each hidden state in a hidden markov model emits one of the possible visible states. The probability that a hidden state emits a particular visible state at a given instance is referred as the emission probability.

The probabilities, i.e. model parameters, are initially set at random values and are learned for each model (belonging to a different class). Following equations were executed to update the model parameters for the given training data:

$$\gamma_{ij}(t) = \frac{\alpha_i(t-1) \times a_{ij} \times b_{jk} \times \beta_j(t)}{P(V|\Theta)} \quad (6)$$

$\gamma_{ij}(t)$ denotes the transition probability of hidden state i to hidden state j at position t in the sequence, $\alpha_i(t)$ is the probability of a model to be at hidden state i at position t, given the sequence from position (Θ - (t -1)), whereas $\beta_i(t)$ is the probability that the sequence will generate the sequence from position t to T. Here, T is the length of the sequence, n is the number of hidden states in the model.P(V|Θ) represents the probability that the visible sequence V belongs to the hidden markov model Θ.

a_{ij} denotes the transition probability from hidden state i to j.

$$a_{ij} = \frac{\sum_{t=1}^{T} \gamma_{ij}(t)}{\sum_{t=1}^{T} \sum_{k=1}^{n} \gamma_{jk}(t)} \quad (7)$$

b_{jk} is the emission probability of of hidden state j to visible state k.

$$b_{jk} = \frac{\sum_{t=1}^{T} \sum_{l=1}^{n} \gamma_{jl}(t)[v(t) = v_k]}{\sum_{t=1}^{T} \sum_{l=1}^{n} \gamma_{jl}(t)[\forall v(t)]} \quad (8)$$

After training the model parameters for each class, we predict the class label for a new unlabelled sequence input. We compute the probabilities of the given sequence belonging to each model and the model with the maximum output probability is labelled as the predicted class. To evaluate the probability for any sequence belonging to a particular class model, we use Viterbi algorithm [22], to compute values for α and β given by the following equations:

$$\alpha(t) = [\sum_{i=1}^{n} \alpha_i(t-1) \times a_{ij}] \times b_{jkv}(t) \quad (9)$$

$$\beta_i(t) = \sum_{j=1}^{n} \beta_i(t+1) \times a_{ij} \times b_{jkv}(t) \quad (10)$$

In training phase, from lines 4 to 16, the algorithm 5 computes the transition and emission probability of the âĂŸnâĂŹ hidden states for one training model. Line 3 repeats this process for âĂŸKâĂŹ hidden markov models, defined for each output class label. Line 18 returns a list of the âĂŸKâĂŹ trained models, with a model instance at each index of the list.
Int the test phase, Line 21 initialises the variables that denote maximum probability and predicted output class. From lines 22- 30, the probability of the test sequence belonging to model θ is computed and compared to the previous maximum probability. If the probability is higher, the maximum value is replaced with the current value, and the output class is set to the current model.

Multinomial Naive Bayes

We compute the most probable output class label using Multinomial Naive Bayes Model [23].The Naive Bayes model can provide a probabilistic

Algorithm 5: Composition with Hidden Markov Model

Data: A N x 1024 matrix, where each row represents a unique input
Result: Output Class of the Fish

1 **Training Phase**{
2 Initializing the number of hidden states âĂŸnâĂŹ and Model
3 **for** *(k class labels)* **do**
4 **for** *(each hidden state j)* **do**
5 Randomly initialise transition probability matrix a i.e. Model[K].a[i][j]
6 **end**
7 **for** *(each hidden state j)* **do**
8 Randomly initialise emission probability matrix b i.e. Model[K].b[j][k]
9 **end**
10 Use forward-backward (Baum Welch) algorithm to compute probabilities α, β.
11 $\alpha(0)$ = initial state matrix.
12 **for** *(i in 1,2...iter)* **do**
13 Recursively compute α_j(t) and β_i(t).
14 Use that to compute γ_{ij}(t).
15 Refine and update the value of transition probability a_{ij} and emission probability b_{jk}.
16 **end**
17 **end**
18 Return Model
19 }
20 **Test Phase (Test Data of size n (Visible States))**{
21 Initializing Max = INT-MAX and PredClass = -1
22 **for** *test data* V^T *for model* Θ *in range 1 to K* **do**
23 **while** t *!=* T **do**
24 Compute $\alpha_j(t)$
25 **end**
26 **if** *Max ¡* $\alpha_0(t)$ **then**
27 PredClass = $Theta$
28 Max = $\alpha_0(t)$
29 **end**
30 **end**
31 Return PredClass
32 }

approach to classification with faster computation compared to other algorithms. The model is simple and isnâĂŹt sensitive to irrelevant features, hence becomes a crucial algorithm for testing and comparison.

In this model, we assume each trial to be independent with an outcome from one of the k classes. Each fish image is represented as a multinomial distribution of d features obtained through the partially trained CNN model. The most probable class is obtained by selecting the class with maximum posterior probability using the computed likelihoods of the features and prior probabilities for each class. We formulate these probabilities using Bayes theorem:

$$P(\omega|\Theta) = \frac{P(\Theta|\omega) \times P(\omega)}{P(\Theta)} \tag{11}$$

Here $P(\omega|\Theta)$ denotes the prior probability for class label ω for input feature vector Θ. Deriving the most probable class:

$$y = argmax P(\omega_j) \prod_{i=1}^{d} P(\Theta_i|\omega_j) for j = (1, 2...k) \tag{12}$$

To avoid multiplication by zero, we regularize the Naive Bayes model using Laplace smoothing with pseudocount parameter (α) for d dimensional input vector Θ:

$$\Theta_j = \frac{\Theta_j + \alpha}{N + \alpha \times d} \tag{13}$$

Here i = (1,2...d) and N represents the number of trials

In training phase, from line 2 - 6, the algorithm 6 initialises a hash table to store each class as a unique key. From line 9 - 14, the likelihood and prior probabilities are computed for each class using additive smoothing functions.

In the testing phase, from lines 16-30, the product of likelihood probabilities for each dimension in the feature vector θ for test data i is calculated. This value is proportional to the posterior probability. The algorithm, from lines 19-29, checks if the product is greater than the existing maximum product. If greater, the new maximum product is stored and the predicted class gets the index value ω_i

5 Results

The performance of the proposed algorithms was tested in Python and analyzed on a dataset of with 1502 Training Images and 265 Testing Images taken from Fish4Knowledge[24] Project. Using these images, we calculated True Positives

Algorithm 6: Composition with Multinomial Naive Bayes

Data: A N x 1024 matrix, where each row represents a unique input
Result: Output Class of the Fish

Training Phase
Organise a hash table T.
l = 1
while *(l <= N)* **do**
  For class as key, push feature values Θ_j for each j in range (1,d)
  l+=1
end
i = 1
while *(i <= k)* **do**
  Prior-Prob[i] = len(T[i])/N
  Likelihood-Prob[i][j] = (sum of all Θ_j for class key ω_i)/(len(T[ω_i])
  Avoid zero sum by using additive smoothing for the likelihood probability values.
  i+=1
end
Testing Phase
while *(i <= M)* **do**
  Max-Probability = 0
  Predicted-Class = 0
  for *(each class ω_i in range (1,k))* **do**
    Prob-Product = Prior-Prob[i]
    for *(each Θ_j in d-dimensional feature vector Θ)* **do**
      Prob-Product = Prob-Product * Likelihood-Prob[i][j]
    end
    if *((Prob-Product ¿ Max-Probability)* **then**
      Max-Probability = Prob-Product
      Predicted-Class = i
    end
  end
  Return Predicted-Class
end

and False Positives to determine and compare the accuracy of the various algorithms. The Deep Convolutional Network was built using Keras Library[25], while the ensemble methods, HMM and Multinomial Naive Bayes were implemented using scikit learn.[26]

Figures 3 and 4 represent the variation in model loss and accuracy of the testing and training dataset for Deep Convolutional Neural Network with number of epochs. It can be

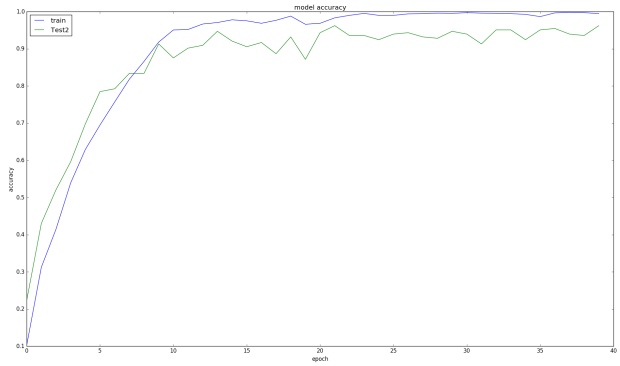


Figure 3: Accuracy of Partially Training Convolutional Networks

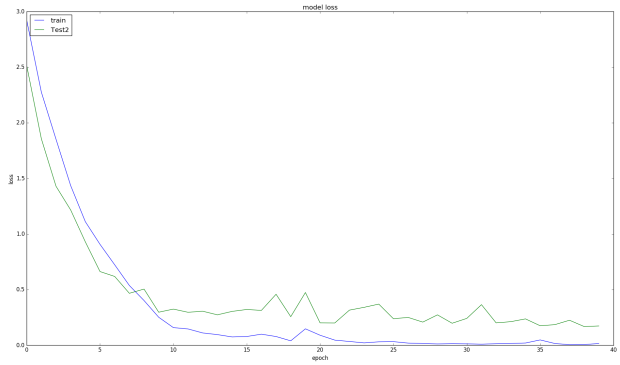


Figure 4: Loss in Partially Training Convolutional Networks

inferred that the loss and accuracy converges with the increase in number of epochs with loss minimizing and accuracy maximizing.

Figure 5 compares the accuracy of the proposed hybrid CNN-ExtremelyRandomizedTreeAlgorithm with Information Gain as the criterion with the Standard ExtremelyRandomizedTreeAlgorithm when applied on the images directly. Figure 6 compares the accuracy of the proposed hybrid CNN-ExtremelyRandomizedTreeAlgorithm with Gini Index as the criterion with the Standard ExtremelyRandomizedTreeAlgorithm. From the figures it can be inferred that the accuracy of both our proposed hybrid method is better than the standard algorithm by approximately 3%.

Figure 7 compares the accuracy of the proposed hybrid CNN-RandomForestAlgorithm with Information Gain as the criterion with the Standard RandomForestAlgorithm when applied on the images directly. Figure 8 compares the accuracy of the proposed hybrid CNN-RandomForestAlgorithm with Gini Index as the

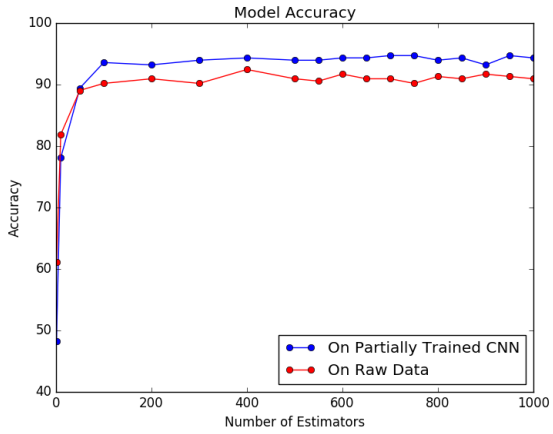


Figure 5: Comparison of Accuracy in hybrid CNN-ExtremelyRandomizedTreeAlgorithm with Standard ExtremelyRandomizedTreeAlgorithm

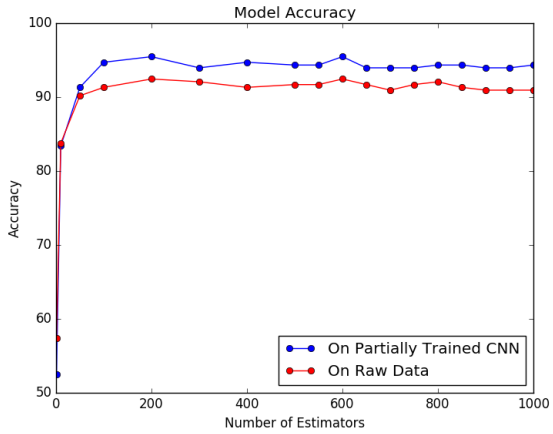


Figure 6: Comparison of Accuracy in hybrid CNN-ExtremelyRandomizedTreeAlgorithm with Standard ExtremelyRandomizedTreeAlgorithm

criterion with the Standard RandomForestAlgorithm. From the figures it can be inferred that the accuracy of both our proposed hybrid method is better than the standard algorithm by approximately 4%.

Figure 9 compares the accuracy of all 4 ensemble methods used.

Figure 10 compares the accuracy of the proposed hybrid CNN-MultinomialNaiveBayesAlgorithm with the Standard MultinomialNaiveBayesAlgorithm when applied on the images directly. From the figure it can be inferred that the accuracy of both our proposed hybrid method is better than the standard algorithm by approximately 47%.

Figure 11 compares the accuracy of the proposed hybrid CNN-HMM with the Standard

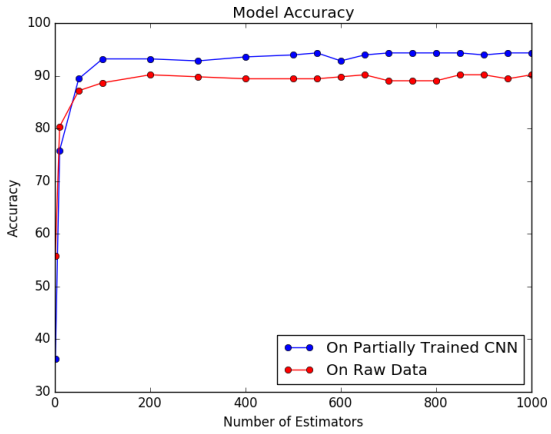


Figure 7: Comparison of Accuracy in hybrid CNN-RandomForestAlgorithm with Standard RandomForestAlgorithm

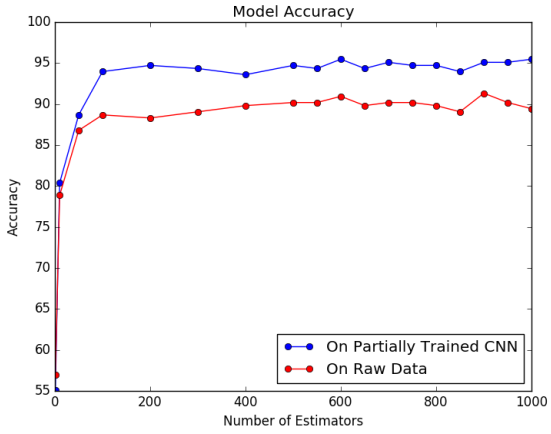


Figure 8: Comparison of Accuracy in hybrid CNN-RandomForestAlgorithm with Standard RandomForestAlgorithm

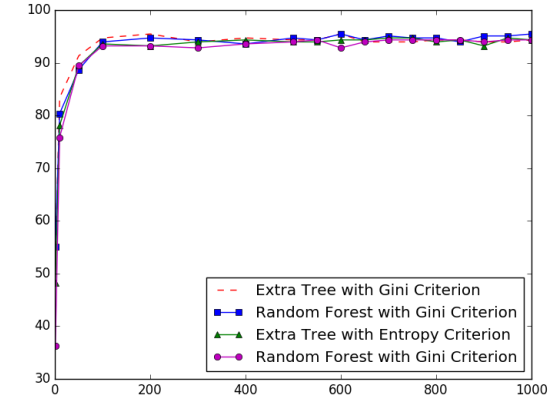


Figure 9: Comparison of Accuracy of Ensemble Methods

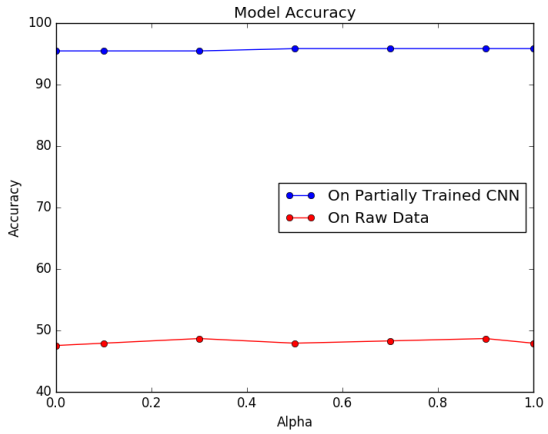


Figure 10: Comparison of Accuracy of CNN-MultinomialNaiveBayesAlgorithm with Standard MultinomialNaiveBayesAlgorith

HMM when applied on the images directly. From the figure it can be inferred that the accuracy of both our proposed hybrid method is better than the standard algorithm by approximately 38%. Also the accuracy with number of states = 1 is the maximum

Table 1 summarizes the resulting accuracy

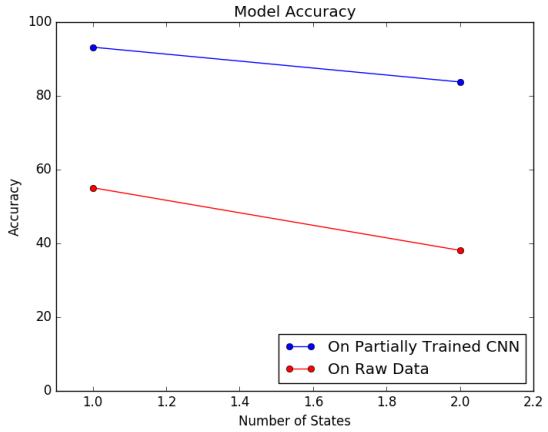


Figure 11: Comparison of Accuracy of CNN-HMM with Standard HMM

of our proposed hybrid algorithms and their comparison with standard Algorithms on the test dataset. From the table, we can observe that there is a considerable improvement in accuracies of the hybrid model over standard approaches. The maximum accuracy achieved is 95.8%, with partially trained CNN model being trained on a multinomial naive bayes classifier in cascade.

Table 2 compares the results of our proposed model with previously established

Algorithm	Accuracy	
	Without Convolutional Neural Network	With Convolutional Neural Network
Extremely Randomized Tree Algorithm with Information Gain	91.32%	94.72%
Extremely Randomized Tree Algorithm with Gini Index	90.94%	94.34%
Random Forest Algorithm with Information Gain	90.18%	94.34%
Random Forest Algorithm with Gini Index	89.43%	95.47%
Multinomial Naive Bayes	47.92%	95.85%
Hidden Markov Model	55.09%	93.21%

Table 1: Comparison of Accuracy of various proposed approaches

Algorithm	Accuracy
Yun-Heh Chen-Burger et al. [10]	92%
Yutaka Nagashima et al. [27] with Japanese Horse Mackerel (ma-aji) dataset	88%
Andrew Rova et al.[8]	90%
Andres Hernandez- Serna et al. [7]	91.65%
Arjun Kumar Joginpelly et al. [28] with Epinephelus morio Dataset	70.6%
Yi-Haur Shiau et al.[13]	81.8%
Deokjin Joo et al.[29]	72%
S.O. Ogunlana et al.[30]	78.59%
Snigdhaa Hasija et. al. [12]	91.66%
DCNDCA	**95.85%**

Table 2: Comparison of Accuracy of previously proposed approaches

techniques used for classification of fish classification. The accuracies of the hybrid approaches proposed through this paper surpasses the performance of these previously proposed approaches.

From the Table 1 and 2, we can conclude that the performance of our system surpasses the performance of the previously defined mechanisms for fish classification.

6 Conclusion

We presented a novel approach DCNDCA tailored for multi-class fish classification based on a Deep Convolutional Neural Network Architecture, combined with the features of Ensemble Techniques, Hidden Markov Model and Multnomial Naive Bayes Algorithm. The proposed system was tested on a database with 1502 Training Images and 265 Testing Images, giving an accuracy of 93 - 95% based upon the technique used. Our future work will emphasize on extending the technique to multi-species classification, and focusing on an

improvised feature extraction, thereby further improving the accuracy of our model and scaling it to larger applications.

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DEVELOPING AND STANDARDIZING A SCALE TO MEASURE COMPETENCY DEVELOPMENT PRACTICES

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PURPOSE
THE present research paper seeks to develop and validate a construct for mapping Competency Development Practices.

Design/Methodology/Approach: *Literature was reviewed extensively and six major practices were synthesized. These practices were Training and Development, Competency Analysis, Mentoring, Capability Development, Competency based Assets, and Continuous Capability Development. A questionnaire of 46 items was standardized on a sample of 1068 managers working at different levels in various organizations.*

Findings: *The 46 item questionnaire was validated using Confirmatory Factor Analysis. Composite reliability of the practices were Training and Development (0.886); Competency Analysis (0.859); Mentoring (0.832); Competency Based Assets (0.920); Capability Development (0.893), and Continuous Capability Development (0.921). Also, convergent and discriminant validity were established.*

Research Limitation/Implication: *The present questionnaire is meant to be used for Indian organizations as it is standardized on Indian working population. It can be adapted in different countries.*

Practical Implications: *The questionnaire can be used to measure Competency Development Practices in the organizations and to ascertain the maturity level of these practices in line with Capability Maturity Model (CMM) framework.*

Originality/Value: *This study provides a scale to measure Competency Development Practices in organizations which is not available in current relevant literature.*

Key Words: *Competency Development, Training and Development, Competency Analysis, Mentoring, Capability Development, Competency Based Assets, and Continuous Capability Development.*

Introduction

Dramatically changing business environment is constantly pushing organizations into the transition phase. These transitioning have updated the perception of career and are partly responsible for the development of new career management models (Arthur, Inkson, & Pringle, 1999). Lifetime employability

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has become an essence for employees to create their own career success. It means, employees need to concentrate on acquiring new skills, maintaining a continuous fulfilment with the potentials, and also creating new opportunities through excellent use of their competencies.

Competency is the fundamental attribute required for carrying out a given role, activity or task successfully (Sahu, 2009). The term 'Competence' sparked into the literature way back in 1970s and from then onwards, it has assumed distinct magnitude. The traditional methods of knowledge tests, school grades and credentials were not perceived to be sufficient enough to predict the performance of a person on a job. Alternatively, "Competencies" was the term that was made known as the key to success. An approach to identify these competencies was formulated in which a comparison of people was made on the basis of their success in their jobs. This approach was laid on the assumptions that, some people execute the jobs more effectively than others. These exceptional performers have different approaches and behaviours to get their jobs done. Thus, the best to identify the competencies which would drive superior performance is to study these exceptional performers (McClelland, 1973). Subsequently, McClelland (1976) characterized this innate and distinctive element of superior performance as 'Competency' and introduced this approach to a consulting firm which came to be known worldwide as Hay McBer.

Boyatzis (1982) contemplated an integrated model of managerial competence which not only reveals the interrelationship of the distinct characteristics of managers which facilitate them to be effective in different managerial jobs but also, their relationship with both management and internal organisational environment. Mangham (1986) asserts that competence is related to a number of personal models in which benchmarking is of prime importance such as outcome models, education, and training models. Burgoyne (1988) identified and explained the distinction between 'being competent' and having 'competencies'. The former means *meeting the job demands* while the latter means *possessing the necessary attributes to perform competently*. Dulewicz (1989) argued that, by assessing the performance one can reach at the optimum level of competencies required to perform a task. On the contrary, it was found that out of the total Competency basket, the firm specific competencies makeup to only 30 percent while, the remaining 70 percent are common to a broad spectrum of organizations.

Human resource, these days, are primarily focussing on Competency Development. Efficient employees seek opportunities to learn new things and expand their skill set and organisations are providing these employees with proper resources which would in turn enhance the value of the organisation.

Competencies possessed by employees in an organisation can be utilized in two ways. They can be used for on-boarding orientation and other employee communications or they can be integrated into hiring practices, performance appraisal, succession planning, etc. Competencies not only address the technical skills of a job but, also the behavioural aspect of the job. Thus, a properly defined combination of competencies aid organisations to effectively measure and evaluate employee performance.

Competence Development is competence and proficiency development of an individual all through his working career. In general, Competency Development is to update, expand, deepen, and completely redirect an individual's competence.

Hyland (1994) elucidated competence development as "the broad expansion of knowledge, cognition and understanding in an employee with respect to a specific domain. Competence Development has four characteristics. Firstly, it is about individual perception and thus, the emphasis is on the individual learner; secondly, it is a continuous process throughout life, thus, is firmly associated with lifelong learning; thirdly, all activities that an individual undertakes may contribute to competence development and finally, Competence Development is not associated with specific types of learning activities. Thus, Competence Development necessarily comprises of basic elements of both formal and informal learning" (p. 331).

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The purpose of Competency Development is to comprehensively develop the work community and organisation as a whole. The strategic operations planning of an organisation takes into account Competency Development as one of the key areas to be focussed. Managers from the top management have acknowledged that Competency Development is significantly important for changes in job description and duties, renewal of information and work methods, and information based society. The prime objective of Competency Development is to embellish the success of employees.

Deficient planning and detachment of Competency Development from goals and strategies of the organisation are the major challenges of Competency Development at workplace. Also, many a times organisations do not give due weightage to the investment in Competency Development for achieving competitiveness. Another challenge of Competency Development is involved with decision making and perception on the relationship between employees working capacity, occupational well-being, and coping at work with profitability of the organisation. As far as employees are concerned, the challenge is mainly of resources, which includes lack of time and inadequate information and planning.

While other common challenges in Competency Development involve wide range of training and development service providers and provision as well as their diversity in terms of quality, a lack of instruction targeted at adults and a partial mismatch between demand and supply. This paper aim to provide the researchers with a proper scale of Competency Development which can be used across industries.

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Literature Review

The dynamic business environment is pressurizing organizations to challenge the old organizational designs which were based on job structures by competency based approaches (Dwivedula & Madan, 2010). The strength of growth in today's environment can only be attained through performance. Only employees who have the right blend of competencies can perform their tasks better. Competencies are a "set of skills and abilities, both technical as well as behavioural, which are essential for desired level of performance'. Right mix of competencies is prerequisite for superior performance" (Sahu, 2009, p. 118).

The main purpose of competency management is to identify the knowledge, skills, and process abilities that employers and employees must have to attain their respective goals. It is rightly said that, there exists a strong positive relationship between organizational efforts and workforce empowerment to gain competitive advantage. Organizations are making efforts towards their workforce. Employees, nowadays, are not considered as a part of organization rather they are treated as competitive assets of the organization who aligns their competencies and abilities with their performance and ultimately to the vision, mission, and core values (Dwivedula & Madan, 2010).

Many organizations have recognized the significance of Competency Development to the sustainability and vitality of their organization (Pascale, 2013). It was highlighted in his study that, one third of the organizations are making efforts to develop competencies. Organizations which are developing or planning to develop must also incorporate Competency Development in their development process to achieve desired goals. Tampoe (1994) also recommended that, organizations which have a strong focus on continuous development of their employees must focus their efforts in building competencies among their employees as this would give them a chance to have an edge over their competitors. Many authors have acknowledged the significance of Competency Development in increasing the performance and competitiveness of the organization. Thus, making the concept of Competency Development critical strategic management tool in the present business environment (Bergenhenegouwen, Horn, & Mooijman, 1997; Nyhan, 1998). The underlined role of Competency Development is to enhance the success of both the organization as well as the employees. Therefore, organizations must pave ways to establish Competency Development as a core part in their HR practices (Delamare & Winterton, 2005; Lawler,

1994). This is the reason why in today's western organizations the use of competencies has become extensive and imperative. (Heinsman, Hoogh, Koopman, & Muijen, 2006; Nybo, 2004; Athey & Orth, 1999). Organizations, nowadays, have augmented their focus on skills and behavioural attitudes of employees. They are developing ways to strengthen their pool of talent by laying emphasis on employee's skills and core competencies (Dwivedula & Madan, 2010). Core competencies, as defined by Hamel & Prahalad (1990) are, *"the collective learning in the organization, especially how to co-ordinate diverse production skills and integrate multiple streams of technologies"* (p. 80).

Barrett & Depinet (1991) reassessed the concept of *competence,* professed by McClelland. They construed competence as '*the predictive power of the conventional intelligence tests'*. They also accentuated that, competence approach is an inverted approach. It starts with identifying outstanding performers to assess the unique competencies which differentiate them from average performers. Boak (1991) conducted a research which revealed that, according to UK occupational standards this concept is termed as '*Competence*' while, in US it is termed as '*Competency*'. Thus, largely making the terms synonymous across the world. Woodruffe (1991) solicited a comprehensive and precise explanation to the concept of competence as *"the facets of the work which an individual can perform with competency, with reference to the individual's behaviour grounded by competent performance"* (p. 31). Lado, Boyd, & Wright (1992) conceptualized a competency-based model to gain competitive advantage from the resources based perspective. This model specifically links the four factors of firm's *'distinctive competencies'*, these are transformation-based, output based, resource-based competencies, and managerial competencies & strategic focus.

Dulewicz & Herbert (1992) conducted a job Competency survey which validated that the skills which a manager needs to perform his job are generic across occupations to permit generalization even though there are differences in the managerial functions. Mansfield (1993) suggested that key roles are identified by occupational standards which can be fragmented into units of competence. These units can further be divided into elements of competence. Each element has performance criteria which are defined on the basis assessment. The occupational standards are strongly entrenched in the practicality of the job to be undertaken, which are validated by employers predominantly. Although, very few employers participate in formal vocational qualification system, either because the needs of specific employer are not relevant or for a simple reason that the assessment procedures are bureaucratic (Spencer & Spencer, 1993) A study of 650 jobs was undertaken to propose a generic job model which exhibited and validated the use of McClelland's/McBer's job competence assessment methodology. Competencies in their outlook include each and every individual attribute, the magnitude of which can be calculated reliably and can easily differentiate between the superior and average performers or effective and ineffective performers. These may include self-concepts, attitudes, values, traits, motives, content knowledge, or cognitive or behavioural skills, etc. They also highlighted the fact that, it is far more difficult to differentiate competencies rather than knowledge and skills with a valid Competency Development methodology. Competency model which encompasses scales elucidate different degrees of a given competency. This will assist in defining, measuring, and rewarding these competencies. These *behavioural anchors* are rank-ordered descriptions of the behavioural manifestations of the attributes described in the Competency model. Typical dimensions of Competency scales include the degree of impact of the action, the intensity of action, the amount of effort expended, and complexity.

Tucker & Cofsky (1994) had put forth a competency based pay system which was universally recognized as an upcoming technology. It is referred to as one of the most powerful and adequate compensation strategies. It accentuates the organisation's goals and at the same time empowers and drives individuals to enhance performance and manage change. To implement this approach one needs to have a detailed understanding of the organisation's goals, strategies, competencies, pay grades, assessment, and salary administration programs. This approach grouped competencies into five areas. These are skill, knowledge, self-concept, motive, and traits. And further these competencies were divided into *Essential* and

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Distinguishing competencies. The former means the basic requirement of the competencies without which an individual would not be able to perform the work, while the latter means, the competencies which makes an individual a superior performer than others. To build and implement a competency model, one needs to first determine the core competencies, then identify a sample of superior performers, after which data are collected, validated, and evaluated based on the competencies.

Barnett (1994) contemplated the relationship between knowledge, higher education, and society. The preeminent ideology of curriculum was analysed to determine its constituents as capability and competence. It also differentiated among the two ideologies of competence, that is, operational and academic and came up with a new definition of human being. This idea of human being is relatively unconstrained by sectional interests, contains a sense of knowing, not derived from mere instrumentality, and looks to promote human beings in situations and conditions unimaginable because the human beings concerned will be doing the imagining.

Lado & Wilson (1994) probed the "potential of human resource system to promote and prohibit the advancement and application of organizational competencies. These competencies include: managerial competencies, input-based competencies, transformational competencies and output-based competencies which are considered to produce competitive advantage to the organization. The competency-based perspective is complemented by behavioural perspective which enhances the understanding of strategic human resource management." (p. 599)

Mansfield (1996) argued that there is a need to develop a competency model which comprise of basic minimum competencies, it should be flexible enough to customize competencies as per individual job requirements, it should also specify the performance benchmark for each competency, and, finally it should be a cost effective approach. Antonacopoulou & Fitzgerald (1996) argued that, it is a nomenclature of most organizations to adopt same wordings to explain a set of managerial characteristics, but this does not mean that these characteristics form part universal management competencies. It is not possible to identify a set of universal management competencies.

Rothwell & Lindholm (1999) focused their study on identifying competencies, formulating suitable models, and assessment in United States. They established a relationship between individual capabilities and core competence of the organisation. Competency models gained importance and were widely used to align individual capabilities with the core competence of the organization.

To gain insight into the concept of competence, Delamare & Winterton (2005) explored "the definitions and application of competence, in the context of Training and Development initiatives in the USA, UK, France, and Germany, to clarify the concept by consolidating knowledge, skills, and competencies within a holistic competence typology" (p. 27). The typology of competence includes: *Cognitive Competence, Functional Competence, Meta Competence, and Social Competence*. One-dimensional framework of competence is no longer adequate, thus, a multi-dimensional approach is considered. In US, a part from behavioural competencies, functional and cognitive competencies are also being considered. While, in UK, an addition of cognitive and behavioural competencies are made to functional competence model. France, Germany, and Austria opted for a more holistic approach. On comparing the approaches, they argued that the holistic approach is the most suitable one as it can identify different combinations of competencies that are significant for a specific occupation and to promote labour mobility.

Draganidis & Mentzas (2006) examined the Competency management attributes of 22 Competency management systems and 18 learning management systems. Competency management is gaining importance in both public as well as private organizations. It helps in attracting and retaining talented employees, identifies right person for the right job, performs succession planning, training need analysis etc. They identified four macro-phases of Competency lifecycle in a Competency management system:

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Competency mapping; diagnosis; development, and monitoring. Sanghi (2009) also propounded a competency model to outline every single job incumbent on these competencies. This model expounded a blend of knowledge, skills, and attributes which are necessary for superior performance and combined them into the conventional human resource functions of recruitment, selection, training and development, succession planning, and performance management. This model was formulated to focus on two main aspect, these were- *what skills, knowledge, and characteristics are required to do the job and what behaviour has the most direct impact on performance and success in the job.* Competency models focus on the position while competency mapping focuses on assessing the individual on each competency of his position. Shahhosseini & Sebt (2011) proposed a "decision making model which can provide assistance in selection of different types of competent personnel. For designing this model, human resources were classified into four main types of personnel: *project manager, engineer, technician, and labourer*. After classifying the groups, a competency criteria model was developed for each type. Decision making was performed in two stages: *a fuzzy Analytic Hierarchy Process (AHP)* for evaluating the competency criteria, and *an Adaptive Neuro-Fuzzy Inference System (ANFIS*) for establishing competency IF-THEN rules of the fuzzy inference system. The model integrated a fuzzy logic qualitative approach with neural network adaptive capabilities to evaluate and rank construction personnel based on their competency. The model had high capability in making quality personnel selection" (p. 163).

Shikari (2011) proposed a competency framework which maps various competencies of companies against the internal or outsourced assessment centres. Assessment centres have become one of the most admissible for companies to make better decision on recruitment, selection, training and development of employees at different levels of their work life with the help of procedures which would align the roles and the business objectives. Assessment contributing to professional development was more in-depth than for those contributing to selection. The framework also demonstrated the validity and utility of assessment and with the advancing technology, assessment processes can also be enhanced.

Campbell & Luchs (1997) threw light on the concept of competence, competency, and core competency, so as to clearly describe the terms. Competence, according to them, is the functional area in which an individual performs the work. While on the other hand, they described competency as behavioural area. Core competence is regarded as the most critical resource which if exploited effectively and efficiently would gain a competitive advantage to the organisation McClelland (1998). Essentially, competencies are behavioural in nature, which means they can be learned through Training and Development in contrast to personality and intelligence. Skills and predisposition beyond cognitive abilities like self-regulation, self-awareness, social skills, etc. make up what is called competency.

Athey & Orth (1999) revealed that Competency based human resource management became comprehensive in United States. It not only touched the human resource development but, also the other dimensions of human resource management like selection, retention, remunerations, etc. in the behavioural approach, competency not only includes the skills and knowledge apace with behavioural or psycho-social characteristics but also, behaviours, work habits, attitudes, abilities, and personal characteristics.

Competency Development is "an important characteristics of the wider concept of competency management. Competency management is defined as *"a significant human resource tool that is usually used within organizations to oversee human resource practices such as selection, assessment, career management, employee development, and performance appraisal*." (Heinsman, et al., 2006, p. 293). Also, it is to be noted that according to Forrier, Sels, & Stynen (2009), Competency Development is "a significant characteristic of competency management which envelops all activities carried out by the organization and the employee to maintain or enhance the employee's functional, learning and career competencies".

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"The concept of competencies and strong managerial interest in Competency Development was not fully translated into the academic world, leading to a gap between theory and practice (Athey & Orth, 1999; Barrett & Depinet, 1991). In particular, a lack of insight into the organizational process of Competency Development can be detected at the theoretical level. In addition, previous research only focused on one aspect of Competency Development, indicating the absence of an integrated approach that discusses the interrelations between different HR-practices involved in Competency Development (Lai & Kapstad, 2009; Nybo, 2004). To fill these gaps, a qualitative case study was conducted in 22 Belgian organizations wherein not only the different aspect of Competency Development within an organization is assessed, but also assessments are made on interconnections between these aspects, putting Competency Development in a broader perspective" (Vos, Hauw, & Willemse, 2011).

Another study was undertaken to gain knowledge on the impact of Competency-based learning in liberal education on student learning in the US (Schneider, 2013). Competency-based learning programs support the students to frame dimensions and magnitude for continuous and life-long learning. It also provides ample opportunities to the faculty to map Competency expectations across their educational programs. The key to achieve success is the students own hard work dedicated towards reaching specific goals.

Trivellas & Drimoussis (2013) also differentiated the competencies through a behavioural competency profile and revealed that the superior performing managers are attributable to high levels of emotional, behavioural, and managerial competencies and they enjoy better project's accomplishment. They highlighted the competencies which distinguishes superior performers from their counterparts, which are "teamwork, efficiency, values appreciation, and openness (behavioural competencies), customer service and system control (managerial), and social awareness (emotional) as well as the task leadership style" (p. 693). Moreover, CVM played as a diagnostic tool in providing assistance to project managers to identify and cultivate the skills and competencies that are required to foster individual effectiveness and project's success.

Succar, Sher, & Williams (2013) focussed on identifying and building information modelling competencies, which are building blocks of organisational capabilities. To improve performance, one needs to learn, apply, and measure these competencies. An integrated approach to identify, classify, and aggregate these competencies facilitated a comprehensive and flexible Competency-based system for assessment, learning, and performance-improvement in industry as well as in academics.

According to Curtis, Hefley, & Miller (1995, 2001, & 2009), the initiative to build capability starts with the identification of the training needs of each employee and addressing these needs in all departments of the organization (Training and Development). Employees possessing requisite knowledge and skills to perform tasks or a given role can be trained for future role and assignments. The purpose is to make sure employees have the right skills to perform their tasks. After the organization has reached at this level the major priority is to understand the workforce competencies required by the organization as a whole to achieve its goals and strategic business objectives. For this, knowledge, skills, and abilities are properly identified which establishes the overall workforce competencies of the organization (Competency Analysis). After this competency based information, processes and artefacts of workforce competencies are preserved as assets which can be further used for future references in case of transferring knowledge and capabilities to others (Competency-Based Assets). Development programs are conducted in the organization across all units and departments to build capabilities among employees as per the benchmark competencies to carry out their given tasks appropriately. Further, mentoring programs are also simultaneously conducted to assist in building capabilities of those employees who are less experienced and need guidance in support with the competency based assets. Finally, organization empowers its employees to continuously develop and improve their capabilities by setting their own objectives and working to attain them (Continuous Capability Improvement).

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Constructs of Competency Development Practices

There is not much literature available on Competency Development Practices. Many researchers have linked Competency management to different constructs. After an extensive review of literature, it was evident that following are the different practices relating to Competency Development.

Table No. 1: Different Practices to Develop Competencies by Researchers and Practitioners

S. No.	Dimensions	Authors
1.	Performance Management	Rothwell & Wellins (2004); Sanghi (2009)
2.	Career Planning/Development	Rothwell & Wellins (2004)
3.	Succession Planning	Rothwell & Wellins (2004); Draganidis & Mentzas (2006); Sanghi (2009)
4.	Compensation System	Tucker & Cofsky (1994); Aquila & Rice (2017)
5.	Credentialing	Rothwell & Wellins (2004)
6.	Coaching and Feedback	Rothwell & Wellins (2004)
7.	Learning Management	Draganidis & Mentzas (2006)
8.	Selection	Athey & Orth (1999); Rothwell & Wellins (2004); Sanghi (2009); Shikari (2011); Shahhosseini & Sebt (2011)
9.	Promotion	Rothwell & Wellins (2004)
10.	Recruitment Management	Sanghi (2009); Shikari (2011)
11.	Training and Development	McClelland (1998); Delamare & Winterton (2005); Sanghi (2009); Shikari (2011); Curtis et al. (1995, 2001, 2009); Arokyamary & Ramasesh (2013)
12.	Competency Analysis	Curtis et al. (1995, 2001, 2009); Arokyamary & Ramasesh (2013)
13.	Mentoring	Curtis et al. (1995, 2001, 2009); Arokyamary & Ramasesh (2013)
14.	Capability Development	Curtis et al. (1995, 2001, 2009); Succar et al. (2013)
15.	Competency Based Assets	Curtis et al. (1995, 2001, 2009); Trivellas & Drimoussis (2013)
16.	Continuous Capability Development	Curtis et al. (1995, 2001, 2009)

Also, it should be noted that among these dimensions, there are a few practices which are established as talent management practice. These are Performance Management (Mirji & Mane, 2012; Tuncq & Schmidt, 2013; Aned, Zainal, & Alya, 2013; Oladapo, 2014; Cooke, Saini, & Wang, 2014; Tymon, Stumpf, & Doh, 2010; Lewis & Heckman, 2006); Career Development (Mirji & Mane, 2012; Mishra & Jha, 2012; Oladapo, 2014; Cooke et al., 2014; Lewis & Heckman, 2006; Farndale, Pai, Sparrow, & Scullion, 2014); Succession Planning (Tuncq & Schmidt, 2013; Oladapo, 2014; Cooke et al., 2014; McDonnell, Lamare, Gunnigle, & Lavelle, 2010); Compensation Management (Mirji & Mane, 2012; Mishra & Jha, 2012; Kumar & Arora, 2012; Oladapo, 2014; Cooke et al., 2014; Tymon et al., 2010; Lewis & Heckman, 2006); Learning (Mirji & Mane, 2012; Mishra & Jha, 2012; Tuncq & Schmidt, 2013; Klein, 2014; Oladapo, 2014; Cooke et al., 2014; Lewis & Heckman, 2006; Farndale

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et al., 2014); and Recruitment and Selection. Thus, to avoid the overlapping of efforts by the organisations in building competencies among employees and managing talent, the focus would be on Competency Development Practices given by Curtis et al. (1995, 2001, and 2009) in the People Capability Maturity model. These are: Training and Development; Competency Analysis; Capability Development; Mentoring; Competency Based Assets; and Continuous Capability Development. Although many researchers have also pointed out that, Training and Development is also a talent management practice (Mirji & Mane, 2012; Mishra & Jha, 2012; Tuncq & Schmidt, 2013; Klein, 2014; Oladapo, 2014; Cooke et al., 2014; Lewis & Heckman, 2006; Farndale et al., 2014) but there are evidences that instead of Training and Development, organisations are these days focussing on Learning and Development as a talent management practice. As talent is innate and cannot be created in an employee through training and practices (Meyers, Woerkom, & Dries, 2013). To nurture talent, organisations need to provide learning avenues, while Competency can be developed in employees through training and practice.

Many researchers have studies these practices individually but not much research has been conducted to understand the relationship of these practices put together to develop competencies among employees (Van der Heijde & Van der Heijden, 2006; Garavan, Morley, Gunnigle, & Collins, 2001; Sandberg, 2000). Therefore, it is imperative to develop a scale to measure the Competency Development practices in an organization at different levels of management. In the light of this scenario, the present research is an attempt to formulate a standardized construct of Competency Development in Indian context.

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Objectives

- To define the construct of Competency Development Practices on the basis of literature review.
- To validate and revalidate the constructs of the Competency Development Practices.

Research Methodology

The present study was conducted in two phases:

Phase I: Extensive literature review was done to define the construct of Competency Development.

Phase II: The questionnaire was developed, validated, and re-validated.

Sampling: In Phase II, a sample of 683 managers was taken from different organizations to validate the questionnaire. Criterion referenced norms were developed for the questionnaire. Again, a sample of 1068 was taken to revalidate the questionnaire. Both the samples were drawn from managers working at different levels in public and private sector organizations ranging between the ages of 20-55 years using systematic sampling.

Results and Discussions

Phase - I: After an extensive review of literature in phase-I, six practices were synthesized leading to Competency Development. These were: Training & Development, Competency Analysis, Mentoring, Capability Development, Competency Based Assets, and Continuous Capability Development (as shown in table no. 2).

Phase - II: A questionnaire comprising of 150 items was constructed out of which 18 items were pertaining to Training and Development, 22 items were of Competency Analysis, 24 items were related to Mentoring, 21 items were pertaining to Capability Development, 32 items were related to Competency Based Assets, and 33 items appropriating Continuous Capability Development. This questionnaire was administered on 683 managers from different levels of various organizations. The data were then

Table No. 2: Defining the Constructs of Competency Development Practices Scale

Construct	Definition
Training & Development	Training and Development here implies identification of training needed in critical skills, conducting periodical development discussions, advising, ensuring, and measuring the Training and Development activities.
Competency Analysis	Competency Analysis here means identifying, analyzing, and documentation of organization's workforce competency and benchmarking the best competencies for other employees and constantly measuring and updating the competency information.
Competency Based Assets	Competency Based Assets here means competency based information and artifacts which are integrated and updated into competency based process and related technologies.
Capability Development	Capability Development here implies developing and documenting the competencies among employees based on the Competency Based Assets
Mentoring Practices	Mentoring practices here implies that there is proper communication between mentors and mentees or workgroups with respect to mentoring programs and practices and appropriate measurements are used to determine the effectiveness of mentoring activities.
Continuous Capability Development	Continuous Capability Development here means empowering the employees to continuously improve their capabilities by identifying improvement objectives between Competencies based processes and process performance baselines.

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analyzed using Confirmatory Factor Analysis, since each dimension here is a separate construct. Out of 18 items of Training and Development only 7 items were retained, out of 22 items of Competency Analysis only 6 items were retained, out of 24 items of Mentoring only 5 items were retained, out of 21 items of Capability Development 7 items were retained, out of 32 items of Competency Based Assets 10 were retained, and finally out of 33 items of Continuous Capability Development 11 items were retained. Thus in all, a total of 46 items were retained for the final questionnaire.

Evaluation of Psychometric Properties of Questionnaire

To establish the psychometric properties of the questionnaire, a measurement model was evaluated. A confirmatory factor analysis (CFA) was conducted using AMOS 21.0. The measurement models shows an acceptable model fit (table no. 3) as chi-square to degree of freedom ratio (CMIN/df) was less than 5 as suggested by Wheaton, Muthen, Alwin, & Summers (1977). Other fit indices were also taken into consideration. Byrne (2013) argued that, the data is evaluated on a number of goodness and badness of fit indices. Goodness of fit indices are GFI (Goodness of Fit Index), AGFI (Adjusted Goodness of Fit Index), CFI (Comparative Fit Index), and NFI (Normed Fit Index) while, badness of fit indices include SRMR (Standardized Root Mean Residual) and RMSEA (Root Mean Square Error of Approximation). Table no. 3 shows the model fit statistics of each construct in line with the recommendations made by Wheaton et al. (1977). It is clear that, all the values meet the cut off criteria. Thus, it is concluded that data fits the model well.

Table No. 3: Model Fit Statistics for Each Construct

Particulars	**CMIN/ DF**	**GFI** (Goodness of Fit Index)	**AGFI** (Adjusted Goodness of Fit Index)	**CFI** (Comparative Fit Index)	**NFI** (Normed Fit Index)	**SRMR** Standardized Root Mean Residual)	**RMSEA** (Root Mean Square Error of Approximation)
Acceptable Levels	1-5	≥ 0.90	≥ 0.90	≥ 0.90	≥ 0.90	≤ 0.08	≤ 0.10
Training & Development	4.589	0.981	0.941	0.975	0.968	0.028	0.077
Competency Analysis	4.337	0.986	0.952	0.976	0.969	0.027	0.075
Mentoring	4.729	0.988	0.954	0.979	0.974	0.025	0.079
Competency Based Assets	3.962	0.967	0.932	0.962	0.950	0.033	0.070
Capability Development	4.807	0.976	0.938	0.970	0.962	0.040	0.080
Continuous Capability Development	4.599	0.956	0.914	0.930	0.913	0.036	0.077

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Reliability

According to Fornell & Larcker (1981), reliability of a construct is its test retest ability. This means that, the outcome of a scale should be same when it is used again and again. There are two ways to measure reliability, first is through construct reliability wherein, cronbach alpha value is calculated and it should be above 0.7and secondly, through composite reliability of the construct, the value of which should also be above 0.7. Table no. 4 shows the reliability of these construct.

Convergent Validity

According to Carmines & Zeller (1979), convergent validity is the degree of agreement between two or more items measuring the same construct. According to Hair, Black, Babin, Anderson, & Tatham (2006), there are three ways to measure convergent validity. Firstly, standardized factor loadings should be above 0.5; secondly, average variance extracted should be above 0.5; and thirdly, composite reliability score should be above 0.7 (Kesharwani, Sreeram, & Desai, 2017). Table no. 4 shows that, all these values for each construct are acceptable. Therefore, these practices show adequate convergent validity (as shown in table no. 4).

Discriminant Validity

Discriminant validity is the degree to which each construct differs from another in a model (Carmines & Zeller, 1979). The purpose of testing discriminant validity is to ensure that different latent variables in the model does not have high correlation among them. According to Fornell & Larcker (1981), to achieve discriminant validity three conditions should be met. Firstly, average variance extracted should be greater that maximum shared variance AVE > MSV, secondly, average variance extracted should be greater than average shared variance, and thirdly, square root of average variance extracted should be greater than the correlations between the constructs. Table no. 5 shows pair wise correlation matrix of constructs, wherein, non-diagonal items are correlation among constructs and diagonal items are square root of average variance explained by that construct. Also, table no. 5 shows that, MSV and ASV values of the construct are below the AVE values respectively.

Finally, table no. 6 presents the items retained along with their individual contribution to the respective constructs.

Table No. 4: Reliability and Validity Scores of Each Construct

Particulars	Reliability		Convergent Validity		Discriminant Validity	
Acceptable Levels	Cronbach's Alpha ≥ 0.70	Composite Reliability ≥ 0.70	Standardized Factor Loadings ≥ 0.50	Average Variance Extracted ≥ 0.50	Maximum Shared Variance ≤ AVE	Average Shared Variance ≤ AVE
Training & Development	0.788	0.886	0.764	0.528	0.464	0.393
Competency Analysis	0.757	0.859	0.707	0.507	0.429	0.334
Mentoring	0.746	0.832	0.700	0.502	0.392	0.328
Competency Based Assets	0.849	0.920	0.884	0.536	0.464	0.430
Capability Development	0.802	0.893	0.871	0.547	0.458	0.411
Continuous Capability Development	0.748	0.921	0.870	0.516	0.458	0.413

Table No. 5: Pairwise Construct Comparison for Discriminant Validity

Particulars	TD	CA	ME	CBA	CD	CCD	AVE
TD	0.727						0.528
CA	0.580	0.712					0.507
ME	0.571	0.423	0.709				0.502
CBA	0.681	0.655	0.615	0.732			0.536
CD	0.644	0.610	0.606	0.666	0.740		0.547
CCD	0.652	0.595	0.626	0.659	0.677	0.718	0.516

Note: The Diagonal elements are square root of Average Variance Extracted (AVE); Non diagonal elements are correlations between constructs.

Establishing Criterion Referenced Norms

The data collected was then used to establish external standard or criterion and comparison of scores are made with it. This process is known as criterion referencing. Criterion referenced scale has a fixed performance criterion. If a respondent is able to achieve a predetermined score, it is said that the respondent is capable of the total performance demanded by the scale. Glaser (1963) explained criterion reference scale as one in which the performance of the test is linked or related to some behavioural measures or referents. Table no. 7 show the criterion reference norms developed for Competency Development Practices scale.

Re-validation of Competency Development Practices Scale

Once the questionnaire was finalized it was administered on 1068 mangers working on the top, middle, and lower level management in different organization. Out of these managers, 701 were males and 367 were females. Confirmatory Factor Analysis was applied again to this data to

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Table No. 6: Showing retained items with their individual contribution to the construct

Q. No.	Statement	R^2
	Training & Development	
1.	Critical skills required for performing each employee's assigned tasks are identified.	0.677
2.	Training needed in critical skills of each employee are identified.	0.831
3.	Employees receive timely training needed to perform their assigned tasks.	0.730
4.	Development discussion is held periodically with each employee.	0.698
5.	Director HR is assigned the responsibility for assisting and advising units on T&D activities and procedure.	0.703
6.	Within each unit, a manager or executive is assigned responsibility and authority for ensuring that T&D activities are performed.	0.591
7.	Appropriate measurement tools are used to determine the status and performance of T&D activities.	0.826
	Competency Analysis	
8.	Each of the organization's workforce competencies is analysed to identify the knowledge, skills, and process abilities that compose it.	0.698
9.	Workforce competency descriptions are documented and maintained according to a documented procedure.	0.694
10.	Employees best in each workforce competency perform competency based processes, which act as benchmark for other employees.	0.856
11.	Information on capabilities of employees in their workforce competencies is collected and maintained according to documented procedures.	0.730
12.	Competency information is updated on a periodic and event driven basis.	0.692
13.	Appropriate measurement tools are used to determine the quality of workforce competency descriptions and competency information.	0.574
	Mentoring	
14.	Each mentoring program is communicated to mentor and mentee.	0.609
15.	Each mentoring program is communicated to mentor and workgroups.	0.818
16.	Mentors and mentees receive appropriate orientation in mentoring practices.	0.766
17.	Practices and procedures for performing mentoring are defined and documented.	0.614
18.	Appropriate measures are used to determine the effectiveness of mentoring activities.	0.710
	Competency Based Assets	
19.	Selected components of competency based information and artifacts are organised into Competency based assets and made available for use.	0.736
20.	Competency based assets are updated to reflect periodic revision in the knowledge, skills, and process abilities constituting workforce competencies.	0.762

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Q. No.	Statement	R^2
21.	Competency based assets are integrated into competency based processes and related technologies.	0.786
22.	Individual employees use competency based assets in performing their business activities.	0.672
23.	Employees responsible for developing the organization's competency based assets develop the knowledge, skills, and process abilities needed to perform their responsibilities.	0.662
24.	Employees responsible for deploying the organization's competency based assets develop the knowledge, skills and process abilities needed to perform their responsibilities.	0.731
25.	Practices and procedures for capturing and using the competency based assets are defined and documented.	0.787
26.	Employees involved in capturing or using competency based assets have the knowledge, skills, and process abilities needed to perform their responsibilities.	0.724
27.	Appropriate measures are used to determine the status and performance of activities contributing to and using competency based assets.	0.675
28.	Executive management periodically reviews the competency based assets activities, status, results, and resolves issues.	0.775
	Capability Development	
29.	Activities related to development of competencies among the workforce are based on plans for each workforce competency	0.843
30.	Organization makes available the description of workforce competencies and information about development opportunities related to them.	0.708
31.	Experience and information related to competencies are captured and made available to all.	0.702
32.	Director HR is assigned the responsibility for coordinating Competency Development activities across the organization.	0.795
33.	Within each unit, a manager or executive is assigned the responsibility and authority for ensuring that activities pertaining to development of competencies are performed.	0.749
34.	Appropriate measures are used to determine the quality of Competency Development activities.	0.715
35.	The definition and use of Competency Development are periodically audited for compliance with organizational policies.	0.647
	Continuous Capability Development	
36.	Individual employees are empowered to continuously improve their capability for performing competency based processes.	0.686
37.	Within each critical workforce competency, objectives are defined for critical competency based processes.	0.678

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Q. No.	Statement	R^2
38.	Within each critical workforce competency, capability objectives for competency based processes are compared to process performance baselines to identify improvement objectives.	0.694
39.	Individual employees evaluate the capability of their personal work processes to identify opportunities for improvement.	0.816
40.	Individual employees continuously improve the capability and performance of their personal work processes.	0.719
41.	Recommendations resulting from improvements in workgroup operating processes are reviewed to determine if they should be incorporated into competency based processes.	0.749
42.	Within selected workforce competencies, a manager identifies the opportunities for improving the capability and performance of competency based processes.	0.611
43.	Within selected workforce competencies, a manager, identifies, evaluates, and select improvements to competency based processes.	0.749
44.	Selected improvement recommendations are incorporated into competency based processes and made available for use.	0.725
45.	Adequate resources are provided for continuously improving overall workforce capabilities.	0.702
46.	Mentoring support is offered to improve the capability and performance of individual employees.	0.753

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Table No. 7: Criterion Reference Norms

Level of Maturity	Practices	Low	Medium	High
Managed	Training and Development	7-15	16-26	27-35
Defined	Competency Analysis	6-13	14-22	23-30
	Capability Development	7-15	16-26	27-35
	Total Defined	13-28	29-48	49-65
Predictable	Mentoring	5-10	11-18	19-25
	Competency based Assets	10-22	23-37	38-50
	Total Predictable	15-33	34-55	56-75
Optimized	Continuous Capability Development	11-24	25-40	41-55

revalidate the scale on a larger sample. Vandenberg (2006) and Schermelleh, Moosbrugger, and Müller, (2003) argued that, chi-square is not used as a good measure to accept or reject a model as it is a non parametric test which is very sensitive to larger sample. Thus, it is recommended to use the other goodness and badness of fit values like GFI, AGFI, CFI, RMSEA, and SRMR to test the measurement model. Table no. 8 shows the model fit indices for revalidating competency development practices scale on large sample of 1068 respondents.

Table No. 8: Model Fit Statistics for Revalidation of Each Constructt

Particulars	**GFI** (Goodness of Fit Index)	**AGFI** (Adjusted Goodness of Fit Index)	**CFI** (Comparative Fit Index)	**NFI** (Normed Fit Index)	**SRMR** Standar-(dized Root Mean Residual)	**RMSEA** (Root Mean Square Error of Approximation)
Acceptable Levels	≥ 0.90	≥ 0.90	≥ 0.90	≥ 0.90	≤ 0.08	≤ 0.10
Training & Development	0.970	0.905	0.941	0.937	0.0357	0.10
Competency Analysis	0.983	0.939	0.964	0.960	0.0325	0.90
Mentoring	0.980	0.924	0.955	0.952	0.0343	0.11
Competency Based Assets	0.963	0.924	0.948	0.941	0.0366	0.082
Capability Development	0.979	0.946	0.972	0.968	0.0397	0.077
Continuous Capability Development	0.956	0.914	0.918	0.908	0.0407	0.084

Conclusion & Managerial Implications

The present study developed a standardized scale to measure Competency Development of managers working at different levels in the organization with the established criterion reference norms. This scale containing 46 items is an accurate and quick measure of Competency Development and norms established out of 1068 respondents in Indian context. The categorization of managers has been done on the basis of different maturity levels i.e., managed, defined, predictable, and optimized and their scores on high, medium, and low. Managers scoring high of each level perceive that their organization is practicing the Competency Development pertaining to the level of maturity. Organizations at **Managed level** can be categorized on the basis of respondent scoring high on Training and Development scores and low on all other Competency Development practices. At this level, organizations have a major focus on managing the performance of employees and coordinating the contribution of employees into overall performance of a unit or department. To assess the capability of an organization to perform, the performance of individual units put together is analysed. This can only be achieved by ensuring that employees possess the requisite knowledge, skills, and process abilities to perform their assigned tasks. Proper measurement tools are used to assess the performance and relevant developments are made as per the gap areas identified. Organizations are categorized at **Defined level** when the managers of these organizations score high on both managed and defined level while, medium or low score for predictable and optimised level. It means that, organizations are not only providing training and development but also focusing on competency analysis and development of capabilities of its employee. At this level, organization develops a comprehensive framework of competencies which builds the structure of the workforce of the organization. Every single workforce competency identified is fundamental to structure of the workforce and their dependencies on competency based processes. Thus, this becomes a basic element of element of the strategic business plan. Organization which are perceived to have reached the **Predictable level** are those whose managers score high on managed, defined, and predictable level but low or medium at optimized level. At this level, organization conducts mentoring programs to manage and exploit the capabilities of superior performing employees and create a workforce competency framework. This framework aids in predicting the capability of the organization to perform assigned tasks as it can quantify the capability of its workforce and that of the competency-based processes. Organizations which are categorised in **Optimised level** are those whose employees score high on the practices of competency development. At this level, the whole organization

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targets on continuous development and improvement. These developments are conducted to enhance capabilities of employees as well as workgroups to perform competency-based processes. Organization empowers its employees to identify their knowledge skills and process ability gaps in comparison with the benchmarks & process performance baselines and work towards the improvement. A culture of performance excellence is created and maintained wherein, employees set their own improvement objectives and work in the direction to attain them.

Limitations of the Research

Since the study has been conducted in India, its applicability is limited to other countries. The finding of this study, therefore, may not have universal applicability.

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Effect of lubrication on the wear behaviour of CrN coating deposited by PVD process

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Abstract: This paper investigates the effect of SAE grade 20W50 engine oil as a lubricant on the wear behaviour of chromium nitride (CrN) coating deposited by PVD process at higher loads and speeds by pin on disc tribometer. The specific wear rate ranges from 9.82×10^{-5} to 2.87×10^{-5} mm^3/Nm in dry condition whereas in lubricated condition 0.97×10^{-5} to 0.19×10^{-5} mm^3/Nm. Successive increase of speed and load rises the temperature of wear track from 65°C to 178°C in dry condition while 34°C to 40°C in lubricated conditions results to decrease in friction coefficient, which has immense influence on the wear resistance of coating. The wear mechanism of the coatings was analysed by SEM and EDS and found deformation, cracks and, nitride particle pull-out, built up edge formation, erosion and adhesive wear coupled with oxidation wear. The highlights of the paper are: 1) tribology of CrN coating against cylinder liner material as counter face summarised; 2) research has practical

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applications for piston ring with the influence of engine oil; 3) temperature ranges from 65°C to 178°C in dry and 34°C to 39°C in lubrication during wear test; 4) the wear mechanism is combination of three body abrasion, metal transfer and oxidation.

Keywords: physical vapour deposition; PVD; CrN; wear; friction; lubrication; temperature.

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1 Introduction

Automotive industries are always in need of eco-friendly superior components to meet the ever increasing demand of high efficiency engines by taking consideration of available resources. These challenges can be overcome by utilising high strength and low weight materials as well as employing surfaces that generate low friction. Surface modification by means of different coatings has become an essential step to enrich the surface properties of the bulk materials like wear, corrosion, anti-adhesive nature, oxidation, etc. (Podgornik et al., 2016, 2015; Jha et al., 2013; Groche and Christiany, 2013; Eriksson and Olsson, 2011). To increase the efficiency of many engine components such as piston rings and liner combination, require surfaces that generate ultra-low wear and friction of mating surfaces. There are number of techniques that are available to deposit such coatings on bulk materials such as physical vapour deposition (PVD), plasma-assisted chemical vapour deposition (PACVD), thermal spray processes [X1], diffusion coating processes, etc. Out of above mentioned processes, PVD is widely used to deposit coatings on parts having in intrinsic geometry. PVD is an atomistic deposition technique that includes the vaporisation and subsequent deposition of target material in the form of coating. A wide range of materials such as metals, alloys and ceramics can be deposited in that way on most of the materials with wide range of shapes. Common examples of PVD deposited coatings are CrN, TiN, diamond-like carbon (DLC), etc. Though for cutting and forming applications, TiN coating on cutting/forming tools are commonly used due to their galling tendency; DLC coatings provide very low friction and superior running-in properties. CrN is another popular example of such PVD deposited coating that shows high hardness, low friction, excellent corrosion and high thermal stability properties. For lubricated condition applications, CrN is more foreseen in automotive industries, as large grain size and highly textured surface of CrN provide micro-reservoirs for lubricants and as a result reduces coefficient of friction (COF) (Lorenzo-Martin et al., 2013; Chen and Nie, 2011; Donnet and Erdemir, 2007; Petrogalli et al., 2014; Quinones-Salinas et al., 2015).

Some tribological components, like piston rings, forming tools and gears, bearings, etc. are generally lubricated. Sufficient lubrication is important for their best operation, due to severe contact conditions and to prevent failure, even when using thin film of hard coatings. Usually lubricants are prepared methodically for optimal performance with different additives and account for 4%–10% of fully formulated lubricants (Ortmann et al., 2003; Lubas, 2012). Additives interact with the mating parts of the material to form a tribo-chemical film as a protective layer. Haque et al. (2010) reported that, friction modifier (FM) additives mixed with engine oils in case of CrN/cast-iron systems, provide low friction as well as wear and attributed to tribo-chemical film formation. In that respect, little work has been reported to understand the performance for CrN coating on engine parts and effect of lubrication together with the effect of additive types and concentration. In contrast, it has been widely accepted in literature that CrN coating deposited by PVD can reduce friction and wear in substantial level. In most of such reposts, experiments have done on relatively low load (10–50 N) and speeds (0.3–1 m/s) (Singh et al., 2017). However in reality, during the component test of piston ring-cylinder liner applications where coatings are expected to withstand higher loads and speeds

(300–1,500 rpm) has been recommended (Söderfjäll et al., 2016). Capability of the coatings to withstand under higher load and speed reduces cost and increase equipment efficiency. So far there is no information available in open literature regarding tribological behaviour of PVD deposited CrN under high loads and speeds in lubricated conditions. The information on wear behaviour of this coating with cylinder lining material counter face is also unavailable. This information is imperatively needed for better understanding and wider application of such coatings. In view of that, aim of this research is to determine the influence of engine oil as a lubricant on tribological behaviour of PVD deposited CrN coating under high loads and speeds.

2 Experimental

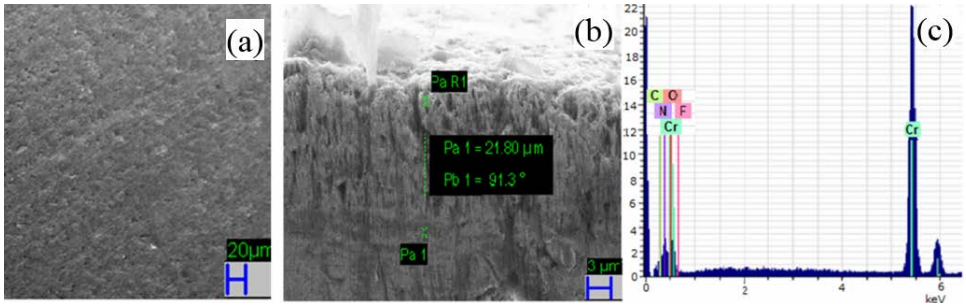
2.1 Coating characterisation

CrN coating was deposited on piston rings made of cast-iron whose elemental composition is given in Table 1. Prior to deposition of CrN, substrate material was well cleaned and roughened by a dry mechanical finishing process (micro-blasting) by using alumina particles of the particle size 15–45 μm to remove surface irregularities such as oxides, dirt, oils, etc. to ensure proper bonding of the coating with the substrate. In fact, hardness of deposited coating depends upon the state of the substrate surface. Substrate surface also needs to be in the state of fine ground finish, particularly for thin film coatings, to ensure coating thickness is higher than that of surface roughness for uniform and durable coverage. During the process, samples were heated up to 400°C for 80 minutes in vacuum chamber. The chamber was filled with carrier gas (nitrogen) and acetylene with argon as fuel under 550 MPa pressure. Cathode power was set at 2,500–2,700 W and pulse frequency was adjusted to form nitride phase of chromium. Detail x-ray diffractometry (XRD) analysis of the coatings were carried out as reported in our previous corresponds (Singh et al., 2017) and confirmed that the coatings structure is mainly face centred cubic (FCC) CrN with a trace of hexagonal CrN along (200) and (111) preferential orientation. Morphology of the coating as well as elemental analysis is shown in Figure 1. The coating consists of small grains and form dense structure [Figure 1(a)] throughout the film with short and disordered columnar texture [Figure 1(b)] and good adhesion with the substrate. Thickness of the coating is about 21.80 μm [Figure 1(b)] and composed of about 64% chromium and 22% nitrogen [Figure 1(c)]. Neither pinholes nor voids were seen throughout the structures. The mean surface roughness (Ra) was evaluated by a Taylor Hobson 3D surface profilometer and results of about 0.60 μm surface roughness.

Table 1 Composition of cast iron piston ring

Elemental content weight (%)	*Fe*	*C*	*Si*	*Mn*	*Cr*
	Balance	3.4–4	2.4–3.0	0.6–1	0.2–0.4
	W	*V*	*Ti*	*P*	*S*
	0.15–0.16	0.15–0.25	0.05	0.25–0.45	0.1

Figure 1 Morphology of as-deposited CrN coating, (a) top-view SEM micrograph, (b) cross-section view of coating with substrate and (c) EDS spectra of the coating (see online version for colours)



2.2 Lubricant

SAE grade 20W50 engine oil, characteristics details as given in Table 2, was used as a lubricant during pin-on-disk sliding test. During pin-on-disk tests, attention was given to mimic the exact contact configuration that took place in practical application between piston ring and cylinder liner configuration.

Table 2 Characteristics of engine oil used as lubricant

Engine oil	*SAE Grade (20W50)*	*Units*
Volumetric mass at 15°C	892	kg/m^3
Viscosity at 40°C	152	mm^2/s
Viscosity at 100°C	17	mm^2/s
Viscosity index	120	-
Flash point	> 200	°C
Pour point	–24	°C

Source: Söderfjäll et al. (2016)

2.3 Wear test

Sliding wear tests were performed on chromium nitride coated sample against uncoated cylinder liner material in both dry and lubricated conditions according to ASTM G99 Standard. The cylinder liners are made of uncoated grey cast iron to increase their tribological and mechanical properties, the addition of chromium, nickel, copper and molybdenum are required. Optical images of coated surface, coated pin and pin-on-disk configuration and wear test set-up is shown in Figure 2.

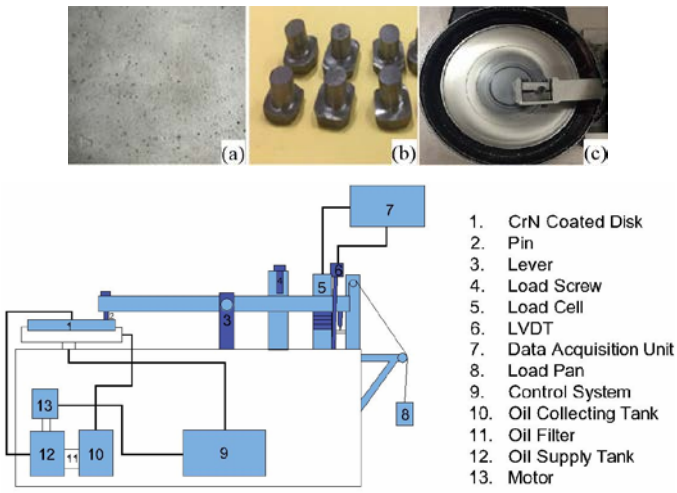
Wear volume was measured in three intervals: after 833 s, 1,250 s and 2,500 s. Total sliding distance of 2.5 km was constant in all cases and performed in ambient of 25°C and 50% relative humidity. Details of experimental parameters are given in Table 3. After wear tests, specimens were cleaned in ethanol to remove loosely adhering wear particles ultrasonically prior to weight loss measurement. Specific wear rate was calculated by a wear coefficient (K) which is often used to categories resistance to contact wear according to equation (1) (Ramalho and Celis, 2002; Steinschütz et al., 2010):

$$K = \frac{\text{Wear volume of pin}}{\text{Load} * \text{Sliding distance}} \tag{1}$$

$$\text{Wear volume} = \text{Wear volume} \times \text{Pin area} \tag{2}$$

Wear volume solved according to equation (2). The wear depth obtained by data acquisition system of the pin on disc tribometer and the area of the pin (counter-body) is 6 mm. The unit of wear volume is in mm^3, load is in Newton (N) and sliding distance is in metre. Wear track temperature during test was measured by a thermal imaging camera manufactured by Fluke thermography (model Ti400) with infrared sensor size of 320 × 240 and; emissivity and transmission of 0.95 and 1.0 has been used, respectively.

Figure 2 (a) Coated sample (disc), (b) Counter body (pin), (c) Pin on disc during wear test, (d) Pin on disc wear test set-up (see online version for colours)



(d)

Table 3 Experiment details of process parameters

Expt.	*Samples*	*Load (N)*	*Slide speed (m/s)*
1	Coated sample in dry condition	50	1
2	Coated sample in dry condition	80	1
3	Coated sample in lubricated condition	50	1
4	Coated sample in lubricated condition	80	1
5	Coated sample in dry condition	60	2
6	Coated sample in dry condition	90	2
7	Coated sample in lubricated condition	60	2
8	Coated sample in lubricated condition	90	2
9	Coated sample in dry condition	70	3
10	Coated sample in dry condition	100	3
11	Coated sample in lubricated condition	70	3
12	Coated sample in lubricated condition	100	3

3 Results and discussion

Friction and wear are most important factors in tribological study of piston rings and liner combination. Characterisation of chromium nitride coatings by tribometer (pin-on-disc) tests in terms of specific wear rate, COF, temperature rise in wear track during the process and overall wear has been analysed in dry and lubricated conditions as reported in subsequent sections.

3.1 Specific wear rate

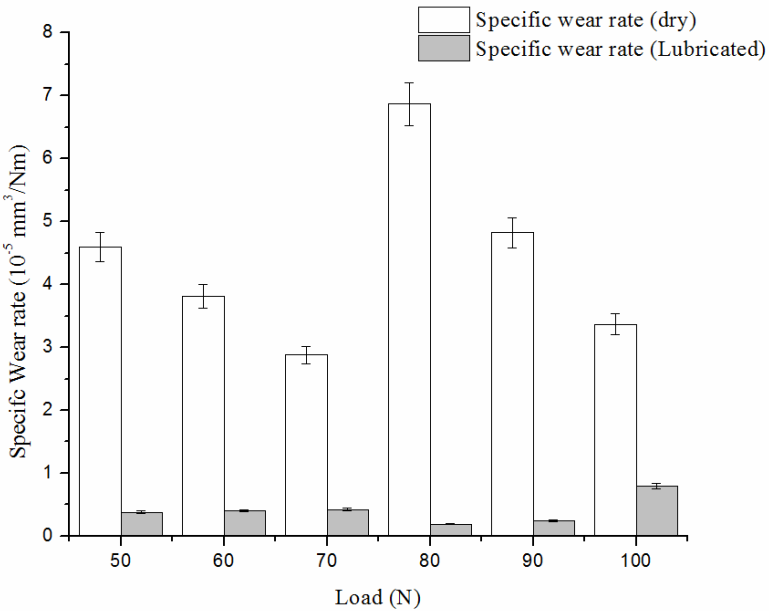
Figure 3 shows a comparison of specific wear rate of current investigated materials under different experimental conditions. Increase of normal loads causes an increase in wear rate as a result of standard weighted increase of frictional heat produces at the interface and hence, decrease of materials' strength. Combined effect of loads and sliding speeds affect the amount of friction force. Wear rate was found to decrease with increase in hardness (de Wit et al., 1998; Holmberg and Mathews, 1994; Al-Samarai et al., 2012; Paul and Sellamuthu, 2016). The effect of engine oil as a lubricant on the wear coefficient has been reported in this section. Wear factor in dry conditions is much higher than lubricated conditions. It is seen in the experiment that the wear coefficient is 4.59×10^{-5} mm^3/Nm in dry and 0.38×10^{-5} mm^3/Nm in lubricated conditions at 50 N load and speed 1 m/s. At the same sliding speed when the amount of load is increasing from 50 to 80 N the wear rate is 6.86×10^{-5} mm^3/Nm in dry and 0.19×10^{-5} mm^3/Nm in lubricated conditions. It can be observed from above results that specific wear rate is increased when the load is increasing at a constant velocity in dry conditions and decreasing in lubricated conditions at the same operating parameters. A similar pattern is observed at different test conditions; wear rate is 3.81×10^{-5} mm^3/Nm and 0.40×10^{-5} mm^3/Nm in dry and lubricated conditions at 60 N load and 2 m/s sliding speed. While the load is increasing from 60 to 90 N at the same speed (2 m/s), the wear coefficients are 4.82×10^{-5} mm^3/Nm in dry and 0.24×10^{-5} mm^3/Nm in lubricated conditions. At the load of 70 N and sliding velocity, 3 m/s the wear coefficient is 2.87×10^{-5} mm^3/Nm of coating in dry conditions and 0.42×10^{-5} mm^3/Nm in lubricated conditions. With the increase of load from 70 to 100 N the wear rate is 3.36×10^{-5} mm^3/Nm in dry and 0.97×10^{-5} mm^3/Nm in lubricated conditions.

The wear coefficient is a function of sliding velocity and time of contact, wear rate magnitude and the mechanism at the wear track and counter body both are dependent upon the sliding speed. The dependence of specific wear rate on velocity can be clarified in the following way. Momentum transfer in the normal direction increases when the speed increases, which yields an upward force on the top layer of the coating. This results to increase the gap between the mating parts which will results to decrease in the real contact area. Contributing to the fact of increased the separation at higher sliding velocity, the time in which opposing asperities wrapped each other is reduced and increasing the level on which the upper surfaces move.

The specific wear (wear coefficient) rate is also higher in dry conditions as compare to lubricated conditions, due to the fact, formation of a lubricious transfer layer on the counter face (pin). The chemical reaction of engine oil and coating can lower the frictional properties, to match the different counter faces and minimise a progressive loss of disc and pin both. While pin on disc tribometer is a unidirectional wear test, the applied normal load causes to increase the re-orientation of the top layers (even those are

re-crystallised) of the coating such that base planes and sample surface are parallel. Increase in applied loads causes more re-orientation and cause to increase in wear coefficient at a constant speed and lower friction coefficients.

Figure 3 Specific wear rate of coating under dry and flooded condition



3.2 Coefficient of friction

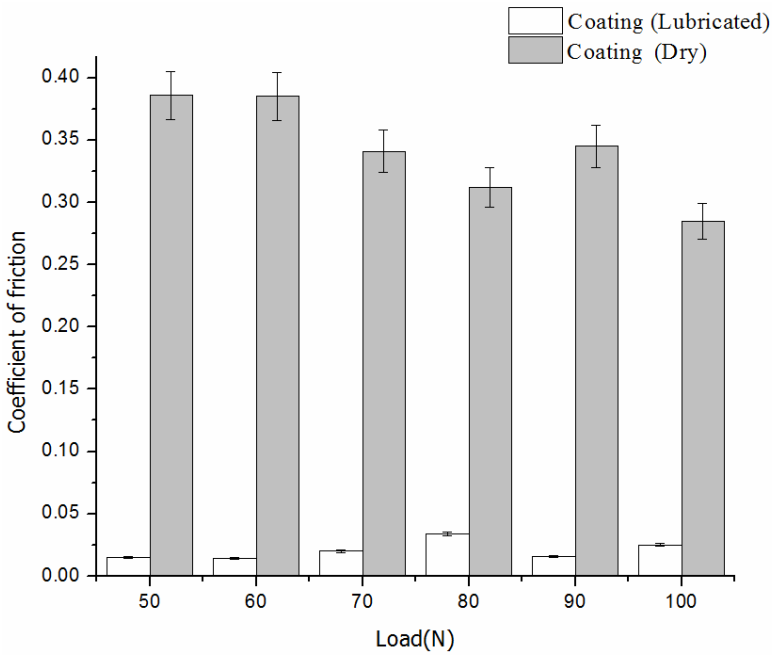
Steady-state friction coefficient was decreasing from 0.07 to 0.05 due to increase in load from 50 to 80 N. This is due to the amount of debris accumulated and formation of transfer layer on the mating parts that increases with time and found to be constant while the friction coefficient reaches a steady-state value.

To study and simulate the behaviour of engine cold-starting on tribological properties, the CrN-coating with the ethanol-oil blend was studied in running. It was reported that the engine oil results the lowest friction of the coated sample (Pramanik, 2016; Basak et al., 2014; Stallard and Teer, 2004). It is also reported that uncoated Ti-6Al-4V titanium alloys, which exhibited a lower COF due to the change of wear mechanism to slight abrasion wear from severe delamination. The friction coefficient of the plasma nitrided samples fall in order of 0.47–0.53 due to the presence of a compound layer with very good frictional characteristics caused even lower values of the COF. As the loads increase, the friction coefficients of the laser surface cladding Ni-base alloy coatings change among 0.29–0.39, and the average value is 21.2% less than that in dry friction (Gangatharan et al., 2016; Taktak et al., 2014; Tan et al., 2016).

Figure 4 illustrates about the COF in dry and lubricated conditions. Initial stage of the wear test, COF of coating is 0.38 in dry condition at 50 N load and 1 m/s sliding speed and decreases up to 0.015 in lubricated condition at the same load and speed. While load increases from 50 N to 80 N at the same speed of 1 m/s, the COF is 0.33 in dry condition

and 0.034 in lubricated condition. It can be clearly seen in lubricated conditions, the engine oil as a lubricant showing large reduction in COF. While considering separately in the dry and lubricated condition at 1 m/s sliding speed, when load is increasing friction coefficient is decreasing. The higher applied load reduces the friction coefficient. The reduction in COF due to localised surface melting result to decrease in shear strength and COF drops to a low value determined by the viscous force in liquid layer.

Figure 4 Combined effect of load and sliding velocity at COF in dry and wet conditions



Friction coefficient of the coating is 0.38 in dry condition at 60 N load and speed 2 m/s while at the same load and sliding speed it is 0.014 in lubricated conditions. At the load of 90 N and 2 m/s sliding speed, the COF is 0.34 in dry condition and 0.016 in lubricated conditions. It can be clearly stated that at a constant velocity, when load is increasing COF is decreasing in both the condition of dry and wet. At a fix load and velocity, friction coefficient of coating in dry condition is significantly higher than that of lubricated condition. A quite similar result also can be seen in Figure 4 at the variable load of 70 to 100 N and speed 3 m/s, under dry and lubricated conditions. COF at 70 N load and speed 3 m/s is 0.34 of CrN coating in dry condition while in lubricated condition; it is 0.020 at the same operating condition of tribometer. At the 100 N load the COF is 0.28 of coating in dry condition while 0.025 in lubricated conditions.

From all the above discussion, it can be clearly seen that COF reached a nearly constant value due to the transfer layer and debris collected on the mating parts increases with the running in period. COF during the wear test is an intricate phenomenon, as it typically involves a third body presence between the CrN coating and the counter-body. The applied normal load during the wear test creates a lubricious film of graphite between the mating parts (coating and the counter-body) at the surface due to structure transformations. As the normal load increases during wear test it results in larger level of

re-crystallisation at the top layer of the CrN coating and lower the steady-state value of COF.

3.3 Wear track temperature generation

Influence of generated temperature at the wear track in relation to friction, wear and failure of coating has been reported by authors due to change in mechanical properties. It is also reported that flexible material becomes brittle under some operated conditions if the operating temperature is reduced, while some brittle materials showed ductile fracture at higher temperatures and brittle fracture at low temperature. Study also reports about the decrease in friction from0.64 to 0.41 while operating temperature is increasing from 200°C to 500°C (Field et al., 2004; Bandeira et al., 2013; Arun and Venkatesha, 2008).

Thermal stability of the film is a most important factor at a higher temperature. Figure 5 shows the temperature generation of coated sample in dry and lubricated conditions with increasing load and sliding speed. It is clear that the recorded test temperature of the coating in dry condition is higher than the coated sample in lubricated conditions under the same test conditions.

a In the first set at load 50 N and sliding speed 1 m/s the recorded temperature was 65°C and 34°C of dry and lubricated condition respectively. When load increases from 50 N to 80 N at the same sliding speed 1 m/s, recorded temperatures are 96°C and 36°C respectively of coating in dry and lubricated condition. This increased temperature of coating in dry condition from 65°C to 96°C causes to decrease in friction coefficient from 0.38 to 0.31.

b When the load is 60 N and speed 2 m/s in the second case the recorded temperatures are 87°C and 37°C for coated samples in dry and lubricated conditions respectively. At the same velocity 2 m/s when the load is increasing from 60 N to 90 N temperatures are118°C and 380°C respectively for coated samples in dry and lubricated conditions. The friction coefficient of the coating in dry condition is also decreasing from 0.38 to 0.34 by growth in temperature from 87°C to 118°C of the coating.

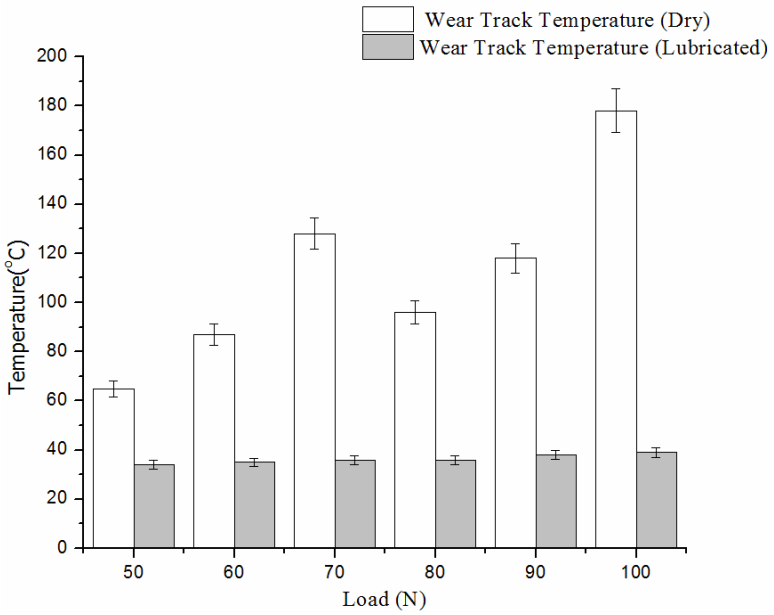
c In the third set with load 70 N and sliding speed 3 m/s generated temperatures are 128°C and 36°C for coating in dry and lubricated conditions respectively. When the load is increasing from 70 N to 100 N at the same velocity the temperatures of coating in both dry and lubricated conditions are 178°C and 39°C.

The temperature rises from 65°C to 178°C of coating in dry condition in all the operating conditions the maximum and minimum friction coefficients are 0.47 and 0.28. While the maximum and minimum recorded temperature in lubricated conditions are 34°C to 40 °C. This is because the temperature of wear track significantly influences the sliding wear behaviour of CrN coating after the long-term run (large sliding distance) at this temperature. Oxidation at the mating parts and formation oxide layers which can avoid the adhesion between the CrN coating and the counter body (pin) possesses self-lubricating properties.

COF is a significant factor to estimate the adhesive wear resistance. ‘In general, a lower friction coefficient means a higher wear resistance’. Above decrease of COF and increase of wear could be clarified that the increase in temperature causes to the

formation of oxides layer on the coated sample and inter splats, which will result to decrease in hardness, affect the propagation and formation of parallel micro-cracks followed by coating delamination.

Figure 5 Wear track temperature generation during wear test



3.4 Wear mechanism

The progressive loss of materials from the mating parts during the relative motion in known as wear. The loss of material from the contacting surface affects the dimensions of the component of IC engines like piston and rings arrangement. That leads to high noise, high vibrations and system malfunctions. To control such type of failure we prefer to use engine oil as a lubricant. Wear volume measurement of CrN coating against the pin of cylinder liner material was calculated by Holmberg and Matthews equation as described above. Figure 9 and Figure 11 show the SEM micrograph of wear track in dry and wet conditions.

3.4.1 Surface conditions of counter face

The pictures of counter face before and after wear test in dry and wet conditions are given in Figure 6. The figure does not show a major difference in micrographs before and after wear test in dry conditions. While the wear face of counter body in lubricated condition shows less metal transfer due to shear but more plastic deformation of the lobes at surface. Both of the surfaces before wear test and after wear test in dry condition contain wave like lobes due to plastic deformation and ductile shearing at moderate temperature. However, the compositions of these surfaces are not similar as shown in Figure 7. It is found that only the proportion of the carbon decreased after the test in dry condition while increasing in wet conditions. On the other hand, the proportion of Fe increased

significantly and remains nearly constant in wet conditions, also in addition to the minor increase of oxygen (O_2), chromium (Cr) and silicon (Si). This indicates that carbon was diffused to the coating from the counter-body material and the counter-body experienced oxidation in addition to the diffusion of Cr from the coating. The rest of the elements are then balanced out.

Figure 6 Surface of counter face, (a) before wear test and (b) after wear test at load 80 N and speed 1 m/sec on coated samples in dry condition (c) after wear test at load 80 N and speed 1 m/sec on coated samples in lubricated condition

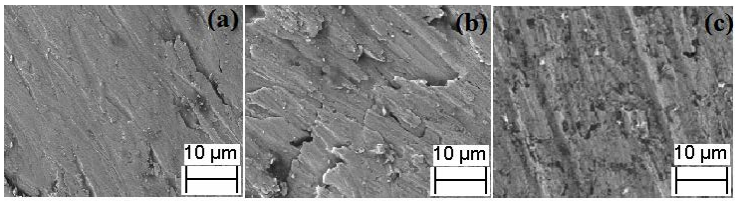
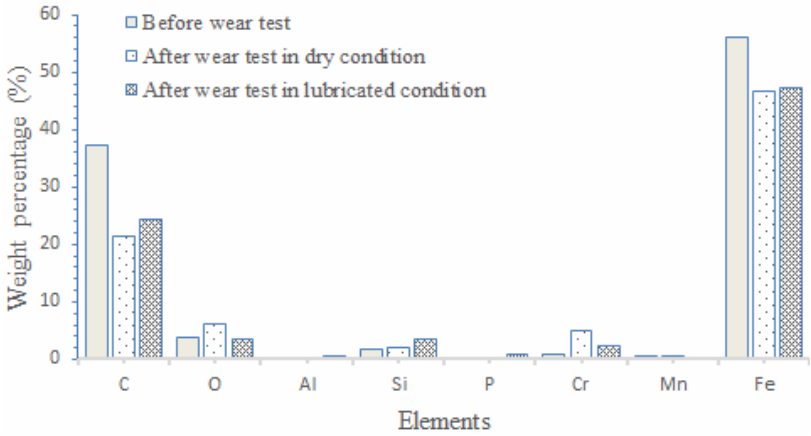


Figure 7 EDS analysis of counter body before and after wear test at load 80 N and speed 1 m/s (see online version for colours)



3.4.2 Wear mechanism in dry conditions

To provide a clear understanding of wear mechanism of CrN coating in dry condition for a run of 2,500 m at higher load and sliding velocity. Wear track of the coated sample has been shown in Figure 8. The worn surface has been analysed by the SEM that is not confirming the dominant nature of abrasion and erosion but the combined effect of these

a delamination

b sliding marks

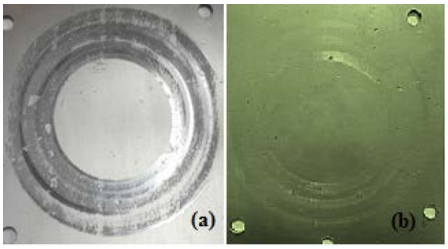
c plastic deformation

d abrasion and material pull out

e cracks

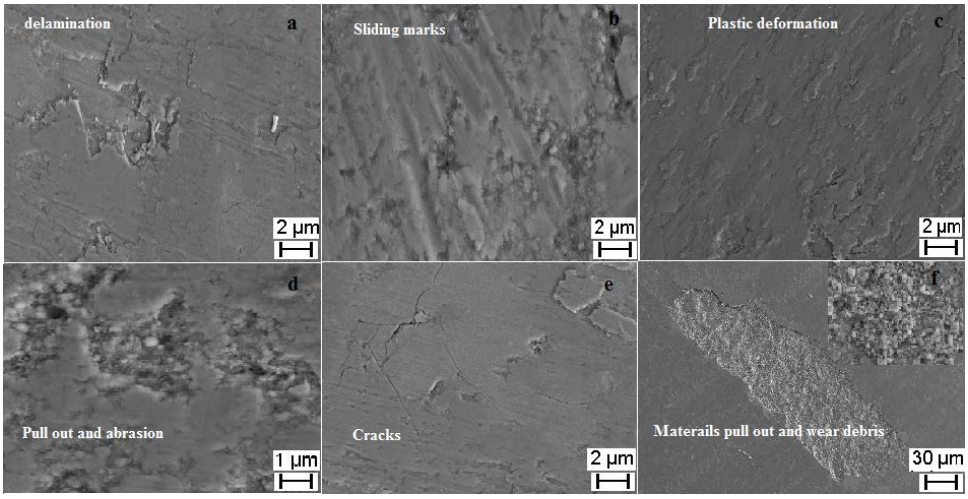
f materials pull out and accumulation of wear debris.

Figure 8 Wear tracks after test (a) dry condition (b) lubricated condition (see online version for colours)



For the duration of wear test, when the dispersed hardened phases and inserted strengthened layer are totally worn away, the progressive loss of material, i.e., wear behaviour proceeds to a next stage, that is affected by the tribology of the CrN thin film coating until ultimate failure due to some voids and cracks remarked in the deposited coating. The primary fragment points that cause the coating to be poorly wear-resistant (Hong et al., 2017). SEM micrographs of CrN film deposited by PVD on cast iron cylinder surfaces by normal operation condition were observed almost no wear, while deep wear grooves, surface cracks and severe deformation on the uncoated cast iron cylinder tubes (Wesmann and Espallargas, 2016). The wear track is covered with a lot of nano-scale needle-like rolls and some accumulation of wear debris around the worn surface is visible even under optical microscopy (Weng et al., 2008).

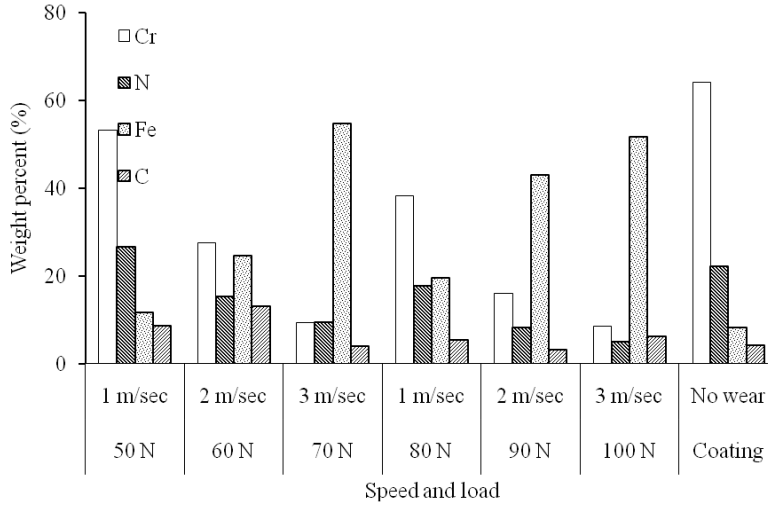
Figure 9 Wear tracks on the coated samples in dry conditions at different loads and speeds respectively (a) 50 N and 1 m/s (b) 60 N and 2 m/s (c) 70 N and 3 m/s (d) 80 N and 1 m/s (e) 90 N and 2 m/s (f) 100 N and 3 m/s



It can be clearly seen some micro-cracks and the delamination of coating at a particular area in Figure 9(a). There is also a type of material damage consisting of small cracks lead to failure. It may occur on coating during the load strain of coating. Some micro-pullout and sliding marks can also be seen in Figure 9(b) in the direction of sliding. Material layer is also being transferred in the in the direction of sliding and some plastic deformation can be observed in Figure 9(c). Figure 9(d) shows the built-up edge

formation and accumulation of wear debris on the wear track due to involves of some hard and foreign particles, either confined between two mating surfaces and abrading to one or both surfaces, or fixed in a softer surface and abrading the opposing one. At the onset of abrasive wear in Figure 9(d) and Figure 9(f), the particles strike and penetrate into the softer surface under the pressure of mating parts. The tangential force forced during the wear test, the metal removal mechanism in the softer surface showed the combined effects of 'micro-ploughing', 'micro-cutting' and 'micro-cracking'. Accordingly, the worn surface is characterised by scratches and grooves. The wear debris shown in the form of small or micro-cutting chips which are shown in Figure 9(f). Whereas some cracks can be seen in the coating in Figure 9(e) at 90 N load and speed 2 m/s.

Figure 10 Weight percentage of Cr, N and Fe of coating after test



The compositions of the coating, substrate and counter face before wear test were presented in Figure 12 where highest percent of material was Fe in substrate (piston ring) and counter face (cylinder liner) in weight% of 91–90 and 56.02, respectively. On the other hand, the coating contained 64.15% Cr and 22.19% N_2 by weight. However, after the sliding in the tribometer at different loads and speeds the materials compositions of the coating surface in dry conditions changes significantly as shown in Figure 10. The figure shows Fe has been migrated to coating and the coating content has been reduced significantly in all the cases. The migration of the Fe might be due to adhesion, attrition and diffusion. The N_2 content of the coating does not change significantly with the variation of load and speed but the proportion and content of Fe and Cr changed significantly. At less sever conditions, such as at speed 1 m/sec with loads 50 and 80 N and speed 2 m/sec with load 60 N the coating surface contained higher amount of Fe compare to that of Cr. In the other conditions which can be considered as very sever conditions; the content of Cr was higher than that of Fe. It seems that at less sever conditions; the migration of Fe to the coating takes place due to adhesion and attrition which occur by Fe build-up from the counter face material. But with the increase of load

and speed the Fe build-ups are removed and tribo-chemical reaction starts. This diffuses Fe to the coating tracks.

3.4.3 Wear mechanism in lubricated conditions

Figure 11 depicts the SEM Micrograph of wear track in with a constant flow rate of SAE grade 20W50 for a run of 2,500 m at different load and sliding velocity are:

a erosion and accumulation of wear debris

b sliding marks and micro-pullout

c tribo-chemical action and metal transfer

d deep grooves and sliding marks

e abrasion

f material transfer.

Severe wear of the piston ring (disc) against the cylinder liner material (pin)mostly take place in the running condition of the engine, so the surface is worn off by the counter-body, and the mating surfaces finally get the improved conformity. Under lubrication conditions, damaged surface studied by Lorenzo-Martin et al. with the help of SEM micrograph, the wear was mostly abrasive, against coating, which produced partial formation of tribo-film. Abrasive wear followed by two and three-body abrasion and the overall effect of wear rate can be tribo-chemically progressed by lubricant that have been trapped in the ring zone. The wear of the piston rings decreases when surface irregularities of the liner reduced, consequently the progressive loss of material, i.e., counter-body decreases when the rings become smoother after some running period (Öner et al., 2009; Ouyang and Sasaki, 2004; Priest et al., 2000; Lorenzo-Martin et al., 2013).

It can be clearly seen the combination of wear at the surface under lubrication, plastic deformation due to strong adhesion force between the CrN coating (disc) and the cylinder liner (pin) leads to scuffing that involves higher frictional force and the formation of wear scars on the mating parts. Some micro-pullout and sliding marks can also be observed in Figure 11(b) in the direction of sliding. Metal transfer and some tribo-chemical reaction can be seen in Figure 11(c). The wear mechanism is followed by abrasive on the coating surface, when wear debris progressed to the mating interface. Erosion on the top layers can be on the top layer of coating, whereas the accumulation of wear debris can also be seen in top corner of Figure 11(a). These wear debris are not similar as the wear debris in dry conditions. Some metal transfer can also be seen in Figure 11(c) due to adhesion in the wet conditions. On the coating and counter-body surfaces as evidence of scuffing some wear scars are present those are indicating, e.g., abrasive ploughing, adhesive transfer and the plastic deformation of work hardened cast iron to a CrN coated piston ring, and a ‘white layer’. Figure 11(d) and Figure 11(f) shows the micro-chipping and small erosion and deep groves at the coating surface, temperature, running speed and surface roughness, are the most important parameters that affect the wear at the lubrication regime most.

Figure 11 Wear tracks on the coated samples in lubricated conditions at different loads and speeds respectively (a) 50 N and 1 m/s (b) 60 N and 2 m/s (c) 70 N and 3 m/s (d) 80 N and 1 m/s (e) 90 N and 2 m/s (f) 100 N and 3 m/s

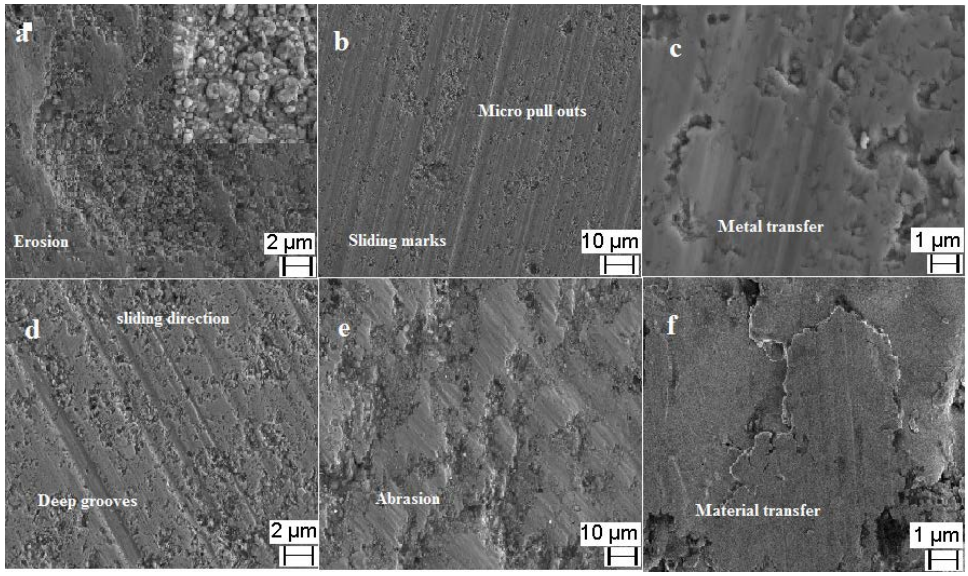
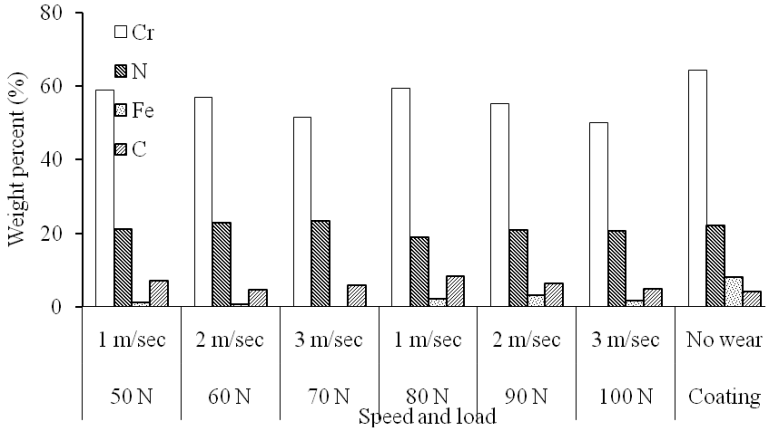


Figure 12 Weight percentage of Cr, N and Fe of coating after test



Wear track materials composition in lubricated conditions has been reported after the test at diverse loads and speeds of the coating surface changes significantly as shown in Figure 12. The figure shows that the Cr content in not showing a major difference in all the wear track while in the dry conditions Cr is changing significantly. Fe has been migrated to coating and the coating content has been reduced significantly in all the cases. The migration of the Fe might be due to adhesion, attrition and diffusion. The N_2 content of the coating does not change significantly with the variation of load and speed, but at a speed 1 m/s when load is increasing from 50 N to 80 N the N_2 content is

decreasing slightly. Similar trend can also be observed at a speed when load is decreasing the N_2 content showing slight decrease. Whereas at all the load and speed conditions, such as at speed 1 m/sec with loads 50 and 80 N, and speed 2 m/sec with load 60 N the coating surface contained less amount of Fe compare to that of N_2 and Cr. Whereas the compositions of the coating, substrate and counter face before wear test were presented in Figure 12 where highest percent of material was Fe in substrate (piston ring) and counter face (cylinder liner) in weight% of 91–90 and 56.02, respectively. On the other hand, the coating contained 64.15% Cr and 22.19% N_2 by weight.

4 Conclusions

A practical comparison has been presented in this paper between dry and lubricated condition of CrN coating during pin on disc wear test. The following conclusions derived from the above results and discussions:

1 Flatness of the sample is crucial while establish the contact during the wear test along with the alignment (perpendicularity) between pin holder and disc axis to ensure the cross-section contacts the disc properly.

2 The coating consists of small grains and form dense structure throughout the film with short and disordered columnar texture and good adhesion with the substrate. Coating thickness is about 21.80 μm composed of about 64% chromium and 22% nitrogen and surface roughness about 0.60 μm.

3 Specific wear rate is increasing with the load at constant velocity in dry conditions and decreasing in lubricated conditions at the same operating parameters. This is due to the chemical reaction of engine oil and coating, causes to its low friction characteristics, to suit different counter faces and minimise wear of disc and pin both.

4 COF during the wear test is an intricate phenomenon, as it typically involves a third body presence between the CrN coating and the counter-body. As the normal load increases during wear test it results in larger level of re-crystallisation and the partial melting wear debris at the top layer of the CrN coating and lower the steady-state value of COF. Above statement is also supported by the temperature at point of contact ranges from 65°C to 178°C in dry conditions while 34°C to 39°C in wet conditions.

5 The wear mechanism of the coatings was found deformation, cracks, fracture or pullout, built up edge formation nitride particle pull-out, erosion of top layers and adhesive wear dominated by metal transfer, and a combination of oxidation wear.

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OPTICAL PHYSICS

Fiber optic Fabry–Perot interferometer sensor: an efficient and fast approach for ammonia gas sensing

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In this work, we propose and demonstrate a Fabry–Perot-interferometer-based polydimethylsiloxane (PDMS) and poly(methyl methacrylate) (PMMA)-composite-coated optical sensor for ammonia and volatile organic compounds (VOCs) detection at room temperature. The principle of sensing is based on change in the cavity length of the FP cavity in the presence of varied concentrations of gases, which results in changes in the total reflectance due to the shift in wavelength of an interference pattern. The sensing composite material was coated on a single-mode optical fiber by using a simple dip-coating technique and explored it for sensing. The ammonia and VOCs measurements were performed for concentrations ranging from 5 to 500 ppm. The corresponding sensitivity and limit of detection of the developed sensor for ammonia gas detection was observed of the order of around 4.16 pm/ppm and 4.8 ppm, respectively. The response and recovery times of the sensor were found to be of the order of 50 s and 10 s, respectively, for the ammonia gas. This sensor provides a simple, cost-effective, highly sensitive, and repeatable approach to measure ammonia gas and other VOCs at room temperature and could fulfill the demands of industrial applications. © 2019 Optical Society of America

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1. INTRODUCTION

Detection of toxic or harmful gases has become more and more essential for the environment, our own safety, and industrial product monitoring, as well as in manufacturing [1–4]. Ammonia gas concentrations above 100 ppm can produce eye burning, tearing, swollen eyelids, corneal abrasions, blurred vision, and even permanent blindness [5,6]. Due to its potential hazard to human beings, real-time monitoring of ammonia in closed environments at room temperature is critically important [2,6–8].

Currently, electrochemical- and optical-based sensors are used for ammonia gas detection. Traditional gas sensors are based on semiconducting oxide materials and show excellent performance in terms of sensitivity [9] but usually operate at high temperature (200°C–600°C) [10,11], need long measuring periods, are bulky, have low reproducibility, have weak stability, and are high cost, which restrict these methods from on-site gas monitoring and real-time analysis [11]. Similarly, optical sensors based on absorption and fluorescence are used for the ammonia detection. In these sensors, the side of the optical fiber (cladding or tip) is coated with a chemically sensitive material, which acts as a sensor. In cladding-based sensors, a certain portion of the optical fiber cladding is replaced with a chemically sensitive material composite, which interacts with the ammonia gas and gives fluorescence [3,12]. In the case of fiber-tip-based sensors, the distal end was coated with certain materials that form a Fabry–Perot interferometer cavity. This cavity interacts with the gas, and by the oxidation/reduction reaction, the length of the cavity and the refractive index of the composite changes [13]. A change in the cavity length results in a change in the wavelength shift and amplitude of the modulation [14].

Optical-fiber-based sensors have major advantages over other types of sensors, such as their electrical neutrality, fast response, light weight, high sensitivity, and miniaturized setup [15–17]. However, the reagent used for the fluorescence-based gas detection technique is a toxic and carcinogenic substance. Although the fiber optic gas sensors exhibit high sensitivity and fast response times, they often need calibration. The Fabry–Perot interferometric (FPI) cavity is sensitive and with time the coated components may change its properties. Currently, PDMS and PMMA are very attractive for gas-sensing applications due to their swelling properties in the presence of gas moieties and ability to work at room temperature. Some reports are available based on FPI cavity formation for the gas detection purpose [14,18].

The aim of this study was to explore a new sensitive composite (PDMS and PMMA) for the FPI cavity development for the ammonia gas detection at room temperature. The goal was to improve present ammonia gas detection techniques. The developed ammonia sensor can be used for remote detection or in hazardous environment trough optical fibers [19]. This sensor is also immune to electromagnetic fields and can therefore be used in industrial gas sensing applications.

2. MATERIALS AND METHODS

A. Fabry–Perot Interferometer Cavity Preparation and Its Characterization

The free end of a circulator (SMF-28, 60:40, Optolink Corp. Ltd., Hong Kong) was stripped, cleaved, and cleaned properly. This end was then dipped in a freshly prepared mixture of equal proportions of PDMS (Sylgard 184, Elastomer, USA) and PMMA (–160 mesh/ + 100 mesh, Poly (methyl methacrylate), Alfa Aesar, USA). During the dip-coating process, an interference signal was observed on the optical spectrum analyzer (OSA). The experiment procedure was repeated until a fine modulation pattern due to interference was observed on the OSA. After curing (∼5 h) the cavity, stability of the observed fine modulation was checked, and after confirming the stability, the developed sensor was used for gas sensing. The thickness (L) of the PDMS/PMMA-composite-coated FP cavity is observed to be around 60 μm, calculated from FP formula

$$L = \frac{\lambda_1 * \lambda_2}{2 * n_m * (\lambda_2 - \lambda_1)}, \tag{1}$$

where $\lambda_1 < \lambda_2$, λ_1 is the first trough wavelength, λ_2 is the second trough wavelength, and n_m is the refractive index of the coated material.

B. Fabry–Perot Interferometer Gas-Sensing Setup

The experimental setup shown in Fig. 1(A) consisted of a broadband source (C band, ASE light source, 1525–1565 nm, and maximum output power 28 mW; Optolink Corp. Ltd., Hong Kong), an OSA (model number AQ6370C, spectral range of 600–1700 nm, ans spectral resolution of $\sim \pm 0.02$ nm; Yokogawa, Japan), and an optical circulator. The light source was connected to one end of the circulator. We found that 40% of the coupled light traveled to the OSA through the other end of the circulator, and 60% of the light traveled to the free end of the circulator coated tip as shown in Fig. 1(B). The reflected signal also coupled with the OSA through the same circulator to form an interference pattern. The free end of the coated fiber tip was placed in the middle of the three-neck funnel (100 ml capacity, Borosil, India). One side neck of the funnel was used for gas insertion with the help of a calibrated syringe. Measurements were performed for different random concentrations of the gas between 0 and 500 ppm under different intervals of time. For each measurement, the sensor response and recovery were checked and recorded. For each concentration of gas, the measurement was repeated three times for better repeatability. The experiment was performed at room temperature (25°C) and in a constant humidity environment (65%).

In order to check the cross sensitivity of the PDMS/PMMA-coated FPI, the measurement was performed with acetone, methanol, and ethanol. For each concentration of gas, a signal was recorded for 30 s and 60 s, respectively. This time was enough for ammonia, acetone, methanol, and ethanol to evaporate and distribute homogeneously within the flask. To visualize the data from the experiments, Origin software (8.1 G) was used.

3. PRINCIPLE OF OPERATION OF THE FABRY–PEROT INTERFEROMETER

To understand the mathematical base for the shifts seen in both wavelength and power, upon exposure of the developed PDMS/PMMA composite on the mirror end of the fiber with various vapors, the shift in wavelength and power can be explained by two-beam optical interference. The total intensity ($I(\lambda)$) from the Fabry–Perot cavity is given by the equation [18,20]

$$I(\lambda) = I_1(\lambda) + I_2(\lambda) + 2\sqrt{I_1(\lambda) I_2(\lambda)} \cos\left(\frac{4\pi L n_m}{\lambda} + \varnothing_0\right), \tag{2}$$

where $I(\lambda)$ is the intensity of the total interference; $I_1(\lambda)$ and $I_2(\lambda)$ are the intensity reflections at the cavity end faces, respectively; $\varnothing_0$ is the initial phase of the interference; L is the cavity length; n_m is the refractive index of the coated material; and λ is the optical wavelength. The total power level reflected by the fiber–material–air (R_{123}) interface is given by Eqs. (3) and (4),

$$R_{123} = \left|\frac{r_{12} + r_{23} \cdot e^{-i\beta}}{1 + r_{12} \cdot r_{23} \cdot e^{-i\beta}}\right|^2 \quad r_{12} = \frac{n_{\text{eff}} - n_m}{n_{\text{eff}} + n_m}; \quad r_{23} = \frac{n_m - n_{\text{ext}}}{n_m + n_{\text{ext}}}; \tag{3}$$

$$\beta = \left(\frac{4.\pi}{\lambda}\right) \cdot n_m \cdot L, \tag{4}$$

where n_{eff} is the effective refractive index of the fundamental mode of the optical fiber, n_{ext} is the external refractive index of the medium (i.e., air), and β is the propagation constant in the film. The change in length of the coated film occurs in presence of the external gaseous environment, which further changes the reflectance of the material–air interface (r_{23}) and hence total reflectance R_{123} (fiber–material–air). Simultaneously, β will also be modified due the change in the refractive index of the coated material. Thus, there will be changes in the wavelength shift and the modulation shift in the interference spectra. The shift in the intensity modulation is given by extinction ratio (ER) [18,21]:

$$\text{ER} = 10lg\frac{I_{\max}}{I_{\min}} = 10lg\frac{I_1(\lambda) + I_2(\lambda) + 2\sqrt{I_1(\lambda) + I_2(\lambda)}}{I_1(\lambda) + I_2(\lambda) - 2\sqrt{I_1(\lambda) + I_2(\lambda)}}. \tag{5}$$

The sensing principle mainly depends on the change in the length of the cavity due to the adsorption of gas molecules. Thus, the relationship between the wavelength shift and the change in cavity length is given by [20,22]

$$\Delta\lambda = \frac{\Delta L}{L} \cdot \lambda. \tag{6}$$

The sensitivity (S) of the developed sensor can be calculated from the ratio of the corresponding shift in wavelength to the

corresponding per unit change in gas concentration. Similarly, the limit of detection (LOD) of the developed sensor can be calculated as the ratio of resolution of the OSA ($\delta\lambda$) to the sensitivity (S) of the sensor at the lowest concentration [3]:

$$\mathrm{LOD} = \frac{\delta\lambda}{S}. \tag{7}$$

4. RESULTS AND DISCUSSION

Figures 2(A) and 2(B) show the sensing output of the PDMS/PMMA-composite-coated FPI sensor in terms of the power (dBm) versus wavelength (nm). The value 0 ppm (recorded spectrum in the absence of gas) shows the spectrum with coated material only. It is depicted that the reflected interference spectrum of the sensor shifts towards longer wavelengths with corresponding wavelength shifts of around 0.02 nm, 0.04 nm, 0.07 nm, 0.15 nm, 0.34 nm, 0.54 nm, 0.69 nm, 1.25 nm, and 1.62 nm for the ammonia gas concentrations ranging from 5, 15, 25, 50, 150, 200, 250, 400, and 500 ppm, respectively, for 30 s [Fig. 2(A)]. Similarly, the reflectance spectrum of the sensor shifts with the longer wavelengths of 0.05 nm, 0.09 nm, 0.15 nm, 0.23 nm, 0.5nm, 0.73 nm, 0.9 nm, 1.59 nm, and 2.29 nm are measured for the ammonia gas concentrations of 5, 15, 25, 50, 150, 200, 250, 400, and 500 ppm, respectively, for 60 s [Fig. 2(B)].

The observed shifts in the reflectance spectra are due to the change in the FP cavity length. During these shifts, the physical interaction takes place between the ammonia gas and the PDMS/PMMA polymer composite [14,22]. Similarly, the measured changes in the intensity modulation ER also show a longer increase in the extension ratio of 0.50 dBm, 0.53 dBm, 0.56 dBm, 0.6 dBm, 0.62 dBm, 0.64 dBm, 0.68 dBm, 1.00 dBm and 1.15 dBm are measured for the ammonia gas concentrations of 5, 15, 25, 50, 150, 200, 250, 400, and 500 ppm, respectively, at 60 s due to the change in the refractive index of the FP cavity resulting from the swelling effect [Fig. 3(B)]. In the concentration range of 0–500 ppm, a linear dependence has been observed with the linear coefficient of determination $R^2 = 0.99\%$ and $R^2 = 0.98\%$ for 30 and 60 s, respectively, between the wavelength shift and the molar gas concentration [Fig. 3(A)]. Similarly, in ER change, linear dependence has been observed with the linear coefficient of determination $R^2 = 0.91\%$.

The sensing mechanism of this sensor is based on the swelling of the polymer composite due to the interaction of gas molecules with the PDMS/PMMA polymer composite. The PDMS contains cross-linked structure of the repeating units of $-OSi(CH_3)_2$ groups. The PMMA has ester pendant group (=O). The composite of PDMS/PMMA could be very effective for sensing various reducing gases like ammonia and other VOCs. Depending on the surface chemistry of the PDMS/PMMA

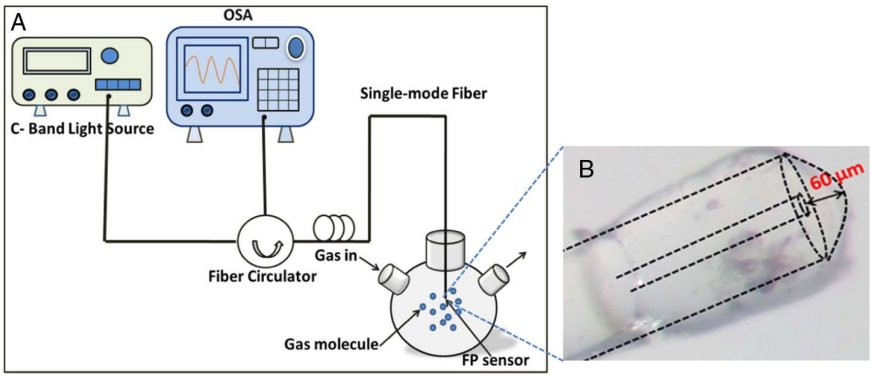


Fig. 1. (A) Fabry–Perot interferometer gas-sensing setup; (B) Coated fiber tip.

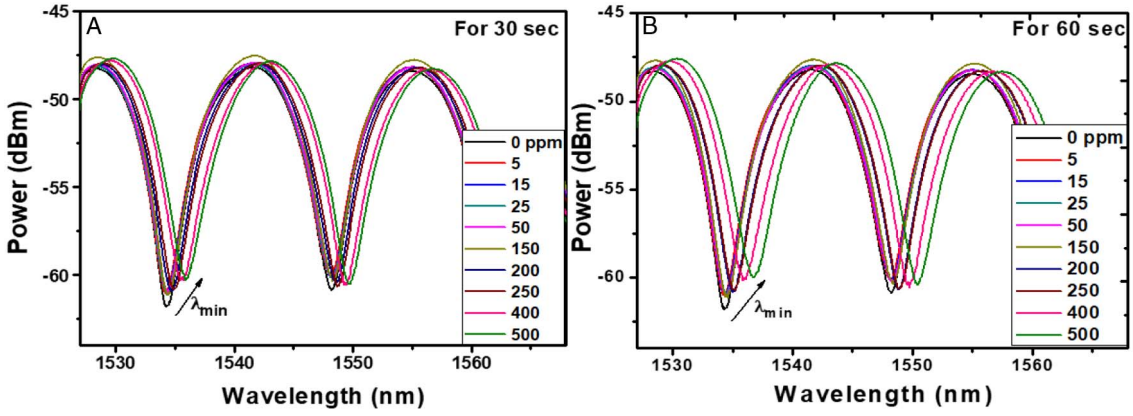


Fig. 2. FPI sensor response for ammonia gas with concentration ranging from 5 ppm to 500 ppm in time: (A) 30 s and (B) 60 s, respectively.

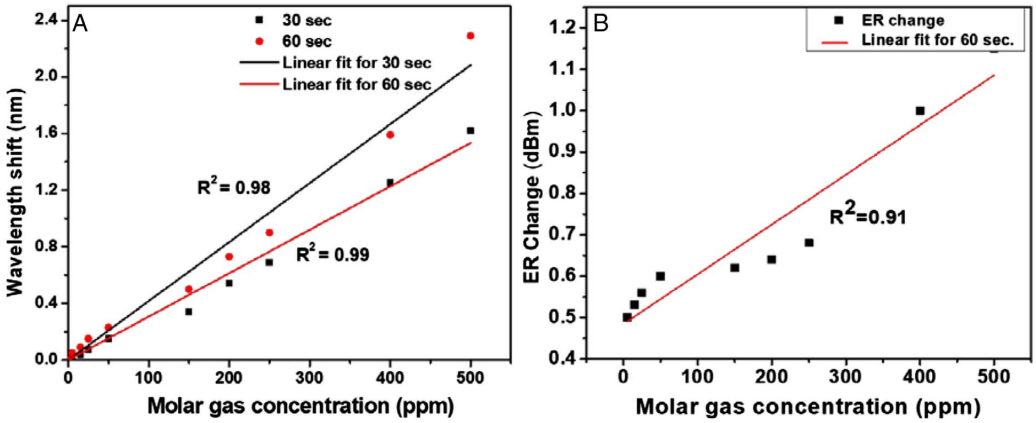


Fig. 3. (A) Wavelength shift versus ammonia concentration for 30 s and 60 s time periods, respectively. (B) Relative change in ER (refractive index) of the FPI cavity with corresponding concentrations at 60 s.

polymer composite first, the gas may interact with the ester pendent group of =O of PMMA, which will induce swelling in the polymer and later interacts with PDMS, which further induces the swelling of the polymer composite [11,18,23]. When the ammonia molecules diffuse into a relatively large molecular gap of PMMA, the polar molecule ammonia readily gives lone pair electrons to PMMA, which induces the swelling of the PMMA [11,18]. Then further ammonia molecules also interact with PDMS without destroying the covalent bonding and enhance the swelling effect [14]. The relative change in length of the of FPI cavity due to the swelling effect of the material composite with corresponding concentrations of ammonia shows linear dependence with the linear coefficient of determination $R^2 =$ 0.97% at 60 s (Fig. 4).

The time response graph is very important for the gas sensor. It gives the response and recovery time of the sensor. Figure 5 depicts the time response of the PDMS/PMMA-composite-coated FPI sensor. It shows that as the ammonia concentration increases, the wavelength shift also increases. From Fig. 5, the response time and recovery time were found to be of the order of 50 s and 10 s, respectively.

The responses of various gases like acetone methanol and ethanol were measured at 100 ppm and 500 ppm and cross checked with ammonia at fixed ppm as shown in Figs. 6(A) and 6(B). It was observed that the PDMS/PMMA sensor shows better cross sensitivity with ammonia, followed by acetone, methanol, and ethanol. The sensitivity was measured for 30 s and 60 s, respectively. For 60 s, the sensitivity values for ammonia, acetone, methanol, and ethanol were observed as 4.16 pm/ppm, 2pm/ppm, 1.76 pm/ppm, and 0.96 pm/ppm, respectively. The sensing mechanism depends on the interaction of gas molecules with the PDMS/PMMA composite.

The Reid vapor pressure (RVP) is also a very important parameter in such an interaction. The RVP for ammonia, acetone, methanol, and ethanol are approximately 483 kPa, 30 kPa, 16 kPa, and 7 kPa, respectively, at 25°C as reported elsewhere [24–26]. Hence, for 60 s the interaction of ammonia with the PDMS/PMMA composite is faster than compared with other gases. Due to the lower vapor pressure of ethanol, the sensitivity is low. The sensor shows better response with ammonia as compared with other gases and can detect lower concentrations of the ammonia gas, i.e., 5 ppm. The measured experimental error in wavelength shift for 5 ppm, 15 ppm, 25 ppm, 50 ppm, 150 ppm, 200 ppm, 250 ppm, 400 ppm, and 500 ppm for 30 s and 60 s are 0.02 ± 0.007,

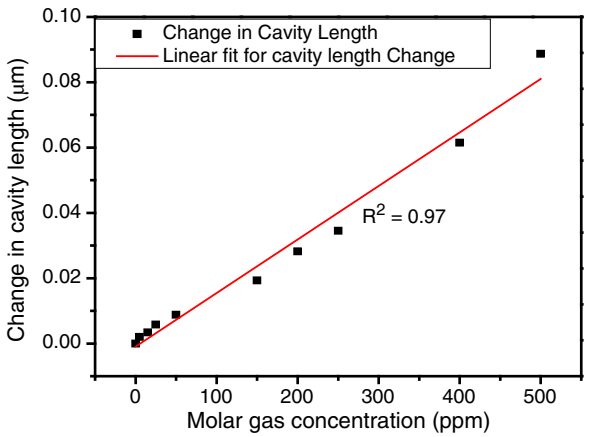


Fig. 4. Relative change in length of the of FPI cavity due to swelling with corresponding concentrations of ammonia for 60 s.

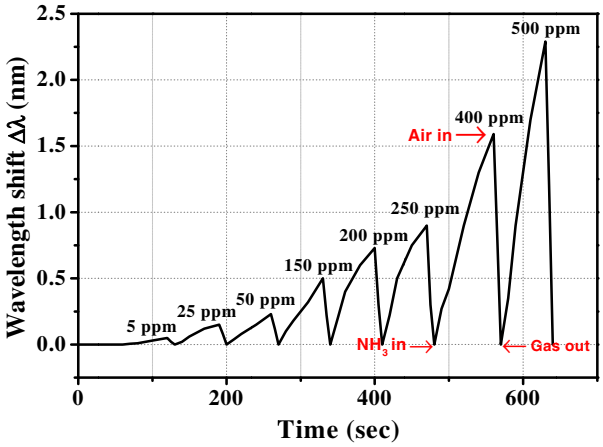


Fig. 5. Time response curve of the PDMS/PMMA-composite-coated FPI sensor probe with varied concentrations of ammonia gas.

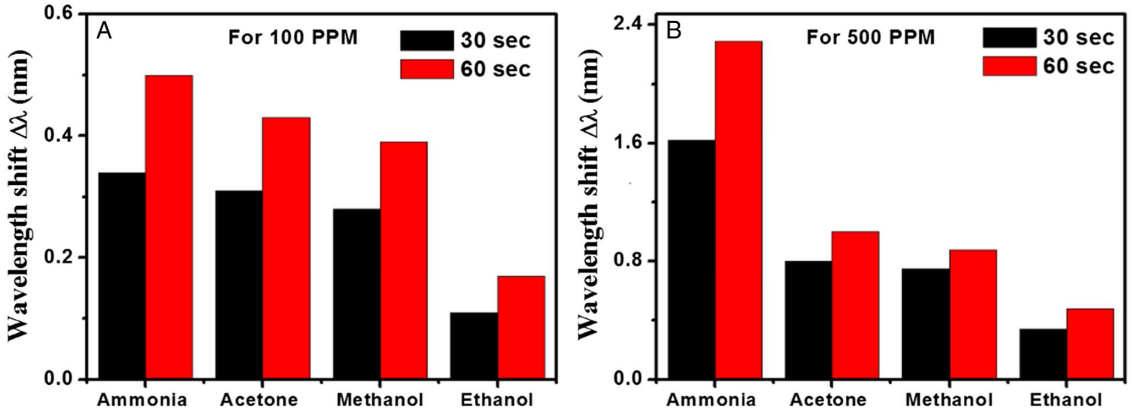


Fig. 6. Time cross-sensitivity response of different gases with the PDMS/PMMA-composite-coated FPI sensor for 30 s and 60 s with (A) for 100 ppm and (B) for 500 ppm.

0.04 ± 0.008, 0.07 ± 0.03, 0.15 ± 0.05, 0.34 ± 0.05, 0.54 ± 0.06, 0.69 ± 0.07, 1.25 ± 0.08, and 1.62 ± 0.1, and 0.05 ± 0.005, 0.09 ± 0.008, 0.15 ± 0.01, 0.23 ± 0.03, 0.5 ± 0.04, 0.73 ± 0.05, 0.9 ± 0.06, 1.59 ± 0.06, and 2.29 ± 0.08, respectively. Similarly, the error measured from the ER change experiment for 5 ppm, 15 ppm, 25 ppm, 50 ppm, 150 ppm, 200 ppm, 250 ppm, 400 ppm, and 500 ppm are 0.50 ± 0.014, 0.53 ± 0.051, 0.56 ± 0.042, 0.6 ± 0.014, 0.62 ± 0.028, 0.64 ± 0.007, 0.68 ± 0.051, 1.00 ± 0.032, and 1.15 ± 0.025, respectively.

The fabricated gas sensor system was tested with four types of VOC gases. The different polarities of the VOC gases cause changes in the effective refractive index of the sensing coating material and results in wavelength shifts. According to the results, the proposed gas sensor showed high sensitivity. Based on this principle, the sensor realized a gas sensitivity of 4.16 pm/ppm and limit of detection of 4.8 ppm in 60 s for 500 ppm ammonia gas from the wavelength shift due to the change in the cavity length. Similarly, the calculated sensitivity of the sensor due to the intensity modulation change was observed of the order of 0.001 dBm/ppm.

In this research, the change in length of the cavity observed was due to the swelling of the polymer composite in the presence of varied ammonia gas concentrations. The swelling results in a change in cavity length of the FP cavity (ΔL), and thus changes the wavelength shift in the interference pattern. The swelling also changes the refractive index of the composite material and thus changes the optical intensity modulation of the transmitted optical signal. However, as compare to the wavelength shift, the changes in intensity modulation are very weak. Thus, in the presented work, an ammonia gas-sensing mechanism based on wavelength shift is elaborated upon.

Although the developed sensor from the PDMS/PMMA composite has provided interesting preliminary results of ammonia detection, some limitations need to be noted. The measured gas sensitivity of 4.16 pm/ppm and the limit of detection 4.8 ppm in 60 s for 500 ppm of ammonia gas is limited by the thickness of the coating material and the resolution of the OSA, i.e., $\sim \pm 0.02$ nm, respectively. The sensitivity of the sensor can be increased by decreasing the film thickness or by doping nanomaterial (sensitive to ammonia) in the polymer as well as by functionalization on the surface of the sensing material. The detection limit of the sensor can be increased by using a high-resolution OSA or spectrometer. Measurements were performed on the ammonia gas in a closed environment at the room temperature; however, thermo-optic coefficients of PDMS and PMMA are large [27,28] and show a linear relationship with temperature change. Therefore, for gas-sensing applications at different temperatures, the sensor needs to be calibrated. The cross-sensitivity study was also performed in a closed environment individually. Therefore, sensitivity and selectivity of the developed sensor need to the evaluated for the VOC mixtures.

5. SUMMARY

In this paper, we have shown the potential of a PDMS–PMMA-composite-based fiber optic FPI sensor as an alternative, robust, fast, accurate, and efficient approach for ammonia sensing at room temperature. Ammonia gas concentrations, ranging from 5 ppm to 500 ppm, were effectively measured with a novel FP approach. The sensitivity in terms of wavelength shift was observed at 4.16 pm/ppm, and the limit of detection was 4.8 ppm in 60 s for 500 ppm ammonia gas from the wavelength shift due to the change in cavity length. The response and recovery times of the sensor were found to be of the order of 50 s and 10 s, respectively, for ammonia gas. The cross sensitivity of the sensor studied on acetone, methanol, and ethanol for 100 ppm and 500 ppm concentrations shows good agreement and sensitivity. Measured results confirm that the proposed gas sensor has high sensitivity and good selectivity for ammonia gas. By using this proposed method, we can monitor and quantify ammonia in real time. The proposed ammonia gas sensor has many advantages like high sensitivity, low cost, high recovery time, linear response over a dynamic range, immunity to electromagnetic interference, easy fabrication, capacity for online monitoring, and remote sensing.

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Identification of New Parameters for Ontology Based Semantic Similarity Measures

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Abstract

A major challenge among various applications of computational linguistics, natural language processing and information retrieval is to measure semantic similarity accurately. In this research paper, various ontology-based approaches i.e. compute semantic similarity between words have been studied and listed their benefits and shortcomings on the various identified parameters. Earlier, correlation with human judgment was the single criteria for the judgment of good similarity measures. In this paper, more parameters for semantic similarity measures have been identified and a relative analysis of similarity measures is performed on the identified parameters. These identified parameters can be further utilized for formulating the new semantic similarity-measures in the latest research area of text mining, web mining and information retrieval. We have identified various parameters like features-set, applicability on various ontologies such as single ontology, cross ontology or fuzzy ontology, Ontology type, dataset applied and relationship mapping for the various measures. Through detailed analysis we have found that feature based and hybrid approaches has higher accuracy as compare to edge and content based methods and works in different type of ontologies. Recent research drawing interest to find new feature set in this area like fuzzy distance, graph generation and text snippets etc. Max Accuracy was achieved in single ontology 0.87 and 0.83 over cross ontologies. WordNet and MeSH are maximally utilized Global Ontologies.

Keywords: Ontology, Natural-Language-Processing, Text-Mining, Knowledge-Based, Semantic-Similarity, WordNet.

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1. Introduction

Huge success of WWW and knowledge society quantity of textual electronic information has been expanded significantly[1] that has acquired the interest of many researcher groups in this area. Most of the information on the WWW is represented by structural form like HTML, DHTML and XML formats. This information interpreted by the humans not by the machines. Now a day's web generates approximately 25 billon textual data on each day. Such a huge data, big data[2,3,4] cannot be organized by humans, so latest research is drawing interest how this textual information can be understood and interpreted by machines. Understanding and Interpretation of textual information revolves around two basic terms i.e. Text Mining [5] and Natural Language Processing(NLP) [6,7]. Textual information is broken into smaller chunks and the smallest chunk is known as terms/words. A major concern in NLP and computational linguistics is to interpret the meaning of each single word. For understanding the meaning of a word/concept first step is to calculate the semantic similarity among the words or terms [8]. Semantic similarity measures evaluate a numerical value which quantifies the closeness among terms/concepts. Semantic closeness stated that how analytically near, two ideas (words or terms) are, on the ground they share some common part of their meaning [9,10]. Aim of semantic similarity is to measure the accurate closeness among the different words. Author Resnik et al. [11] defined the similarity between the words ("*Car*" & "*Automobile*") as 1. For measuring the similarity several researchers proposed their similarity measures.

Although massive research have been done in this area, however in this research paper we have conducted a research study on ontology based similarity measures presented in the area of Knowledge Based(KB)[12,13]. KB system stores huge information in un-structural formats. Un-structural information can be processed and presented through an object model known as ontology [14,15].

Ontologies are created for different aspects and domains; they regularly contains overlapping data and information that can be further used for calculating the similarity among the different words [16]. In this paper, a relative study is presented on various parameters in the area of ontology based measures. Similarity is not a new term; semantic similarity was coined in 1995 by the Resnik et al. After that every year new similarity measures were proposed.

First motivation for this study is none of the research papers presented such an extension research on the ontology based measures; they merely illustrated a small amount of measures in this area, however in this paper authors have studied more than 45 research papers in this area. A detailed comparative study is shown.

Second motivation is to identify different parameters; by these approaches can be compared. In the prior studies accuracy was the only criteria for the formulation and judgment of a good similarity measures however, every year; new similarity measures are proposed to deal with the latest research in this area[17,18]. To cope up with these new emerging fields of knowledge base authors have identified more parameters for the formulation of a good similarity measure. By the extension study in this field the authors have identified different parameter such as: features set, type of ontology framework, benchmark dataset used, relationship consideration and Ontology type. Detailed explanation is presented in the forthcoming sections.

This paper is divided into different sections; First section describes the methodology for conducting the research study, in the same section briefly explains similarity taxonomy. Third section shows the various similarity measures in the area of KB. Fourth section characterized the various parameters identified and their respective meaning. Next section presented the detailed relative study of various approaches on identified parameters. Next section illustrates the analysis and finding of the research paper. Last section describes conclusion and future work in this area.

2. Research methodology and brief of semantic similarity taxonomy

2.1. Research Methodology

For conducting this research study, we have searched various research papers from the online repository like IEEE, Elsevier, Springer, IGI Global, InderScience journal and conference papers from year 1996-2018. Identified keywords for extraction of research papers are; "*Word-Similarity Concept", "Semantic Similarity Meaning", "Corpus-based Similarity", "Text-based Similarity", "Knowledge based similarity", "Ontology based similarity", "Edge-based similarity" and "feature based similarity*". If above defined keywords found in the title and in abstract of the research paper we manually considered them for our research paper. After studying these papers we have identified more related terms that illustrated more depth information in this area. The related keywords are "*WordNet–based similarity measures", "Bio-medical based similarity measures", "Cross–Ontology based Similarity measures", "Fuzzy–ontology based similarity measures" and "Formal concept analysis based similarity measures"*. In this research paper we work on the word similarity measures in the area of knowledge base thus we have not included the "string based similarity", "corpus based similarity", "Sentence based similarity" ,"Paragraph based similarity" and "Document level similarity" for the research paper.

2.2. Semantic Similarity Taxonomy

Similarity can be word similarity, sentence similarity or paragraph similarity. In this paper, word similarity is discussed. Two words can be similar lexically or semantically. Lexical similarity represents words having similar string sequence like in {"*Man", "Lan"* and *"Van*"} and also in DNA sequence matching {"*ADCGTDCGTC*" and "*ADCCGTCGCA*"}.Lexical similarity has a wide application in the areas of medical sequence matching [19, 20] and pattern recognition. Various measures are proposed in this area [20].

Whereas semantic similarity deals with the meaning of the two words, how the linguistic meanings of two words are similar, such as how much similar the words {"*mango" and "orange*"} as both words belong to class "*Fruit*". Another term, associated with semantic similarity is "semantic relatedness" [22] not necessarily relay's only on the taxonomic relationship "*is-a*", however more relationships were explored in semantic relatedness. For example {"tier", "pencil"} was less associated to each other as compared to {"pencil", "paper"} in terms of semantic relatedness and "*pencil*" and "*paper*" don't has "*is-a*" relationship. In this other relationships like "*part-of*", "antonym" is explored.

For calculating the semantic similarity among the words diverse similarity measures have been proposed by different researcher's groups. In literature two approaches "Corpus-Based Approaches" and "Knowledge-Based Approaches" are presented by the researchers [12,23]. In corpus based approaches large amount of textual information is used for calculating the similarity among the words. Latent Semantic Approach (LSA) [24] and Pointwise mutual information(PMI) [25] are the widely used methods for computing the similarity. Fig 1 shows the taxonomy of similarity measures.

Knowledge-Based Methods are an effort to figure out the semantic similarity without human intervention, it uses a vast amount of environment knowledge about the concepts. The major related work on semantic similarity measures utilizing the taxonomy knowledge by the Global ontologies like WordNet[26], MeSH[22] a medical ontologies. Ontologies have been extensively used in the area of knowledge-Base systems.

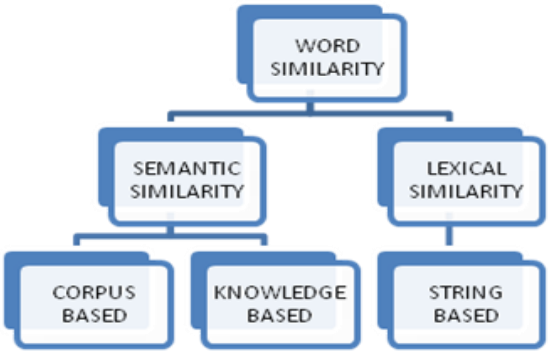


Figure 1. Taxonomy of similarity approaches

Ontologies are represented using classes, attributes and relationships among the attributes. Ontologies characterized as "*a formal specification of a shared conceptualization*" [27]. WordNet is a domain free and all-purpose thesaurus for English words. It organizes more than ten thousand English words that are semantically structured, and forms ontology. It formulates approximately 10000 English words in a semantic structure that looks like ontology. A graph prototype is generated in form of network and it is used for forming the meaning of concepts. In most of the knowledge based approaches; researchers used WordNet as the base ontology for the computing similarity among the word /concepts. In the next section we have explained the various measures present in WordNet ontology.

3. Knowledge based/ Ontology- based approaches

There are mainly three approaches present in literature for KB method [8, 28, 29] and last one is hybrid that is combination of any two approaches. The approaches are,
1. Edge/ path based Approaches
2. Information Content Approaches
3. Features Based Approaches
4. Hybrid Approach

In this section we briefly explain these approaches

Terms associated in semantic similarity measures are:-

Len (c_i) - shortest path length starting from synsets to another synset in WordNet.
LCS(c_i)- Lowest Common Subsumer in WordNet (LCS/lso) of c_i, and
depth(c_j)- path length to a synset from overall root unit and depth of root =1
Max_deep - taxonomy maximum depth.
Max_node - maximum number of words present in the ontology.
Sim(c_i) - semantic similarity among the two concept c_i and

3.1. Edge/ Path based Approach

Edge-Counting approaches were introduced by Author Lin et al [30]. It was a very basic technique to measure the similarity, it calculates the minimum path-distance from the end to end connections in their related ontological model by a "*is-a*" links. As path length increased the similarity between the terms tends to decreased. If two terms are closed their distance must be low and similarity was high.

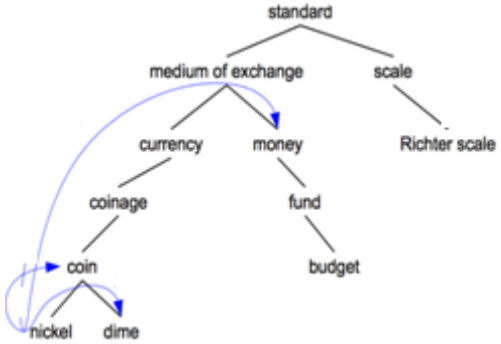


Figure 2. Edge Based Approach presented by Lin [26]

Here the similarity between words (*nickel*, *dime*) & (*nickel*, *money*) was computed according to edge based approach proposed by Lin as:

)= —— = 0.5

———

Mostly used measures in edge based approaches:

3.1.1 Shortest Path based measures introduced by Researcher Rada et al. [31].This measure taken len(C_1, into consideration C_1 and C_2 are the two concepts and similarity was computed as:

(C)= 2*max_deep((1)

3.1.2 Sussna's Measures [32] : This measure was proposed by Sussna et al. in 1993. It is based on the relative depth in the WordNet Ontology. WordNet Ontology has maximum 16 node depth strength. It was based on the assumptions that sibling of the concepts in the lower nodes have more similarity than the higher pairs of nodes. In this noun network of WordNet was used, on this; they defined the two relationships among the edges one was direct relationship and another was inverse relationship. Both the relationships lies between the two ranges {min and max} min=1and max=2^4.
The weight for edge for a node A is calculated as:

——— (2)

The distance between the two adjuncts Node (A, B) was calculated using the weight and depth of node as:

——————— (3)

3.1.3 Wu & palmer's Measure [33]: In this measure they work on the position for the concept $C_1$and C_2 in the taxonomy. For finding the position the relative location was considered for common concept lso (C_1, C_2) which is based on LCS . They concluded similarity among the concepts was based on path length and depth of the ontology. Path length and depth was defined through the links in the ontology.

(C) = (4)

3.1.4 Leacock & Chodorow Measure [34]: Maximum depth of the taxonomy was considered and defined the subsequent measure. They considered that if C_1 have the same sense or the meaning, then their similarity was defined to be 1.

(C) = (5)

3.1.5 Li's Measures [35]:It works on a hypothesis that sources of information are infinite, and humans tend to evaluate sources of word similarity by means of a limited space between completely similar and non-similar words.

(C 2) = (6)

This equation symbolize similarity is monotonically increasing with respect to the depth. The value for a can be manually adjusted for better results. Here the length, depth and lso parameters were considered.

3.2. Information Content Approach

It was based on the theory that every concept is a combination of a large extent of information in WordNet. It relay on a fact that a node is a distinctive representation of a concept in a particular domain and hold some about of information. Direct link between the two concepts is represented by an edge. Similarity among these two concepts was computed on the shared information in that particular domain. The concepts are more similar if they share related amount of information in a domain.

$$\mathbf{IC\ (w)} = -\log \mathbf{p}(\mathbf{w}) \quad (7)$$

Here w presents a class/concept.

Here, w represent the concept and $p(w)$ probability of that instance.

As the number of nodes increases, the information it contains was found decreases. If there exist a single root node in the ontology, then it is having the highest probability of occurrence, value can defined to 1 and information it contain is lowest and measured to 0.

Most used measures in Information content approaches:

3.2.1 Resnik Approach[11]: It relied upon shared information between two concepts. Two terms are dissimilar the most, if LCS doesn't not exist. If LCS exists, using information content of the LCS, similarity was calculated as,

(C) = IC (LCS (C)) (8)

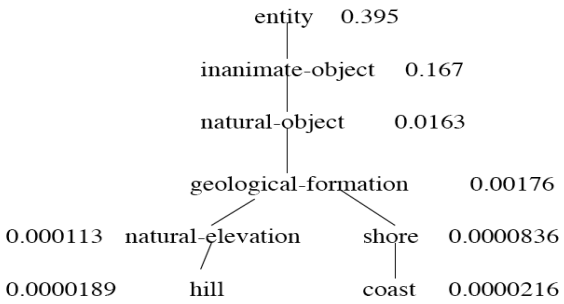


Figure 3. An Information Content Approach presented by Resnik [9]

3.2.2 Lin Approach [36]: It was proposed that the similarity among the concepts is measured as the ratio between the extents of information desirable to specify their association.

(C) (9)

3.2.3 Jiang and Conrath [37]: It depends on measuring taxonomical length of connections among the IC of a specific word and it's LCS. This formula defines the dissimilarity concept between the two terms.

(C) = IC (C_1) + IC (C_2) - 2* (C) (10)

According to author Resnik et al for each incidence of a particular noun among the corpus is measure as an incident of every taxonomical class and can be formulated as,

P (a) = (11)

Here W (a) represent as nouns set in a corpus and multiple senses of the word w are denoted by "a". N shows overall number of nouns present in a defined corpus.

3.3. Feature Based Approach

Feature based methodology describes similarity among the concepts as a factor of their properties. They relied upon the amount of common and un-common features of evaluated concepts. Common features enhanced the similarity and exceptional features tend to weaken it.

3.3.1 Tversky's Model [38]: It was established on the fact that each concept was depicted through a set of keywords presenting their properties and features. It was represented in the WordNet using definitions and glosses values. Glossary of the word "automobile" describe through the WordNet as "*a motor vehicle with four wheels; usually propelled by an internal combustion engine*".

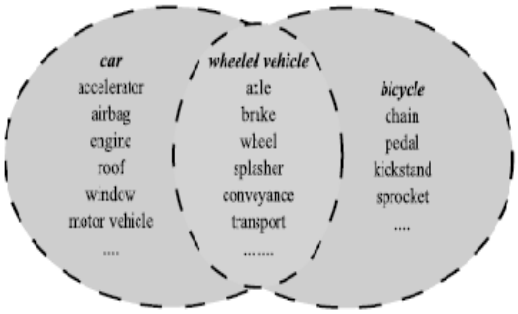


Figure 4 Tversky Model for two words 'car' and 'bicycle'[34]

Two words/concepts are more similar if they contain more common characteristics of words. Exceptional characteristics tend to decrease the similarity.

$$_{ky}(\mathbf{C}\quad_{2}) = \frac{\qquad\qquad\qquad\qquad\qquad\qquad}{\qquad\qquad\qquad\qquad\qquad\qquad} \quad (12)$$

K is adjustable factor and k

3.3.2 Rodriguez and Egenhofer [39]: It proposed a similarity measure, where computation is done on the basis of the individual sum of likeness between the "synsets", their "features" and "neighborhood concept" of the estimated terms as:

$$_{s}(\mathbf{C_1}, \mathbf{C_2}) = \text{w.}\boldsymbol{S_{synsets}}(\mathbf{C}\quad_{2}) + \text{u.}\ \boldsymbol{S_{feature}}(\mathbf{C_1}, \mathbf{C_2}) + \text{v.}\ \boldsymbol{S_{neighborhood}}(\mathbf{C_1}, \mathbf{C_2}) \quad (13)$$

are the similarity among the "synonym set", their "features" and corresponding "semantic neighborhood" of the computed terms. According to this (w, u, v>=0) value of w, u and v depends on the particular similarity weights of every specific component. The value relies upon the individuality of the taxonomy. Here S symbolizes the coinciding between the dissimilar features, which are computed using equation (12).

3.4. Hybrid Approaches

Hybrid approaches can be any approach where these two or more approaches can be combined. Recent research is drawing interest in these approaches. In the recent time author Cai et al.[40] used a hybrid technique of Edge based and the Information content approach. Detail analysis is shown in Table 6.

4. Parameter Identification

4.1. Identified Parameters

So far, we have discussed similarity measures in knowledge based system. To cope with the new emerging field of knowledge base system new measures are proposed every year[16].In this section we have defined some new parameters for similarity measures. After conducting a thorough literature review, the following parameters have been identified for the evaluation of measures. For analysis, we have considered type of measure. Measure belongs to any of three mentioned category or it is based on the hybridization method.

Next, we have chosen feature set of measures that provides insight view of measures. By detailed study we get thirty different features for different measures.

Next parameter is accuracy; it is computed by the correlation value of the computed measure with the human judgment. If the correlation is high, accuracy is high for that measure.

Next parameter is ontology development framework; mainly three type of work present in the literature: single ontology [20], cross ontology [41] and fuzzy ontology [42].

Another parameter is relationships considered among words as *mango* "*is-a*" *fruit* so *mango* and *fruit* having *"is-a"* relationship between two words. However, "*mango*" is also related to the word "*seed*". Semantic similarity is also present in above defined words. A good similarity measure also computes the similarity among these two words. So, considering all the relationships among the words is also an important factor for any measure. Some of the measures computes good similarity with a "is-a" relationship but can't computes the similarity with other type of relationships; Some Edge based methods has high accuracy for "is-a" relationship, but not given same results on other type of relationship. A complete understanding of semantic relationship is an important factor for similarity measures.

Next parameter is dataset; three types of standard datasets are available for the WordNet ontology.

Last parameter is the ontology type; in that we have shown measures are applicable on which type of Ontology. As some of measures are applied Global ontology such as WordNet, MeSH and Gene ontology and some are applied for domain ontology like solar ontology or product ontology. The parameters and their meaning are given in table1.

Table 1. Parameters and Meaning

Sl. No	Parameter	Meaning
1.	Type of Measure	It represents the approach that has followed as Edge based, Content based, Feature based or hybrid approach.
2.	Feature Set	Feature used for computing the similarity.
3.	Accuracy	It computes the correlation with human judgment and the value varies from [0- 1].

		Near to 1 signifies high correlation value.
4.	Types of Ontology Framework	The types of ontology framework on which the measure works as single ontology, cross ontology or fuzzy ontology.
5	Benchmark Datasets	It specifies on which dataset the approach has been applied. There are various standard datasets are 1. Miller & Charles dataset[43] 2. Rubenstein & GoodEnough's[44] 3. Word Similarity353-Test Collection data-sets.[45]
6	Taxonomical relations	It specifies the relationship from the WordNet & Mesh such as "is-a", "part-of", "anatomy" etc. examined in the measures.
7	Ontology Type	Global Ontology like WordNet/Mesh/Gene ontology or any domain ontology.

4.2. Evaluation of different parameters

Here we have discussed the evaluation of identified parameters.

Type of measure*:* Research shows that first measure was proposed based on edge based and but current research focused on hybrid approaches. A hybrid approach gives more accuracy, flexibility and adaptability to the systems as compared to edge based, content and feature based approach.

Feature-Set: This parameter shows feature set used for various measures. Study demonstrates that in starting years of research, the main features were used such as "node", "lcs" and "depth". But in the resent research many different type of features are used such as:"case-based-reasoning","lexical-pattern","normalized-dis-siimilairty","cluster", "neighborhood concepts", "gloss-information", "fuzzy-distance", "vector-models", "swarm-optimization", "text-snippets", "support vector regression", "named entity overlap", "heuristic approach" and "Wikipedia" and many more. The detailed lists are shown in the table (2-6).

Accuracy**:** The accuracy for the different measures is shown in tables; for this we have considered previous research work presented in this area. The Author Alexendra et al. in 2006 [46] compares result of many previous research work and quoted that Jiang and Conrath [37] performs better than the other approaches at that time. For recent work different researcher[40,47,48] given their measures and compared their results with previous works. We have taken their results for accuracy parameter.

Types of Ontology Framework:

1. Single Ontology- WordNet, Mesh and SUMO ontology are general purpose ontology. Mostly researchers used WordNet as main ontology for their measures. All the proposed measures work on the single ontology.

2. Cross Ontology - Measuring the similarity among the cross ontology has a wide application area of new ontology development. New ontology can be developed using merging of two ontologies. In merging; two words from different ontologies are combined. Like the word "fever" having same synonyms "Pyrogens" in MeSH ontology. For developing a new ontology for medical science we can utilized both the word "fever" and "Pyrogens".

3. Fuzzy Ontology- Fuzzy ontology is an emerging field of ontology development. Conventional ontologies are not suitable to manage imprecision or vagueness in information, to deal with probabilistic, uncertainty and vagueness in information, it was introduced Yen et al.[49,50,51]. Fuzzy ontology is the extension of crisp ontology and fuzzy membership is assigned between two concepts for a particular relationship. In recent years fuzzy ontology drawing interest of many research groups and detailed literature review in given by Author Devadoss [52].

Data-Set: We have found that mostly three standard dataset are used for different measures, mentioned in the table 1. Mostly researcher considered one or two dataset for their measures. Miller and Charles is the most popular dataset in this area. This dataset has 30 word pairs and three columns; the first column specify first word, second column specify other word and the last column gives the similarity among these two words according to the human judgment. It varies from [0-1] in data set, 1 means highest similarity. In the 353-TC dataset, it has 353 word pairs are present and the similarity varies from [0-4] among the words. Latest researcher considered the 353-TC dataset. In this dataset more emphasis on semantic relatedness as compare to similarity.

Relationships–Considered: Most common taxonomical relationship "*is-a*". However some of the measures also computed the similarity among different words and considered more semantic relationship such as "part-of" and "anatomy".

Ontology Type- Mostly presented work based on the WordNet ontology. Some of the measures considered the MeSH and Gene Ontology (medical science ontology). In some of the paper's domain ontologies was also considered.

5. A Relative Study on identified parameters for various Measures

Table 2. Edge Based Measures on Various Parameter

Sl. No	Author Name and Year	Feature set	Accuracy (correlation with human judgment)	Type of ontology(Single, cross ,fuzzy)	Benchmark – dataset	Taxonomical-Relationship	Type of ontology
1	Simple-path[31] [Rada,1989]	Only length is considered	0.51	Single	No data set	" is-a"	WordNet
2	Sussna's Measure[32] [Sussna,1993]	Length, direct and reverse link	0.53	Single	Miller & Charles	"is-a"	WordNet Ontology
3	Wu&palmer[33] [Wu&Palmer, 1996]	Depth and least common subsequence (lcs)	0.57	Single	Miller & Charles	" is-a"	WordNet Ontology
4	L&C Measure[34] [Leacock & Chodorow, 1998]	Depth is considered similar word have similarity =1	0.61	Single	Miller & Charles	"is –a"	WordNet Ontology
5	Li's Measure [35] [Li, Bander,2003]	Depth and length is considered	0.6	Single	Miller & Charles	"is –a"	WordNet ontology and MeSH ontology
6	Al and Ngugen [53] [Nguyen, 2006]	Cluster approach ,length and depth	0.67	Single	Miller & Charles	"is- a", "part-of"	WordNet and MeSH ontology
7	James and Zhidian [54][Wang,2007]	Ancestor are considered	0.62	Single	No data set	"is-a" and "functional relationship"	Gene Ontology

Table 3. Information content based Measures on various parameters

Sl. No	Author Name and Year	Feature set	Accuracy	Type of ontology)	Benchmark – dataset	Taxonomical-Relation	Type of Ontology
1	Resnik [11] [Resnik, 1995]	Node based approach, lcs is used	0.59	single ,cross	Miller & Charles	"is- a", "part-of" relation is considered	WordNet
2	Lin [36] [Lin, 1999]	Based on Resnik approach ,and its ratio information	0.68	single ,cross	Miller & Charles	"is- a", "part-of" relation is considered	WordNet & MeSH
3	Ji&Corth[37] [Conrath,1997]	Resnik approach and lcs parameter	0.72	single, cross	Miller & Charles	"is- a", "part-of", antonym	WordNet & MeSH
4	Ontology based concept similarity in FCA[55]	Similarity graph	0.78	single, cross	FCA ,domain ontology	"is- a " relation is considered	domain ontology
5	A semantic similarity method based on Information content in multiple ontology[56] [Batet, 2011]	Intrinsic IC computing model, least common equivalent subsume	0.76	single, cross	miller & Charles	Only "is-a "relation is shown	MeSh, SNOWED CT ontology
6	Concept similarity in FCA an information content approach[57] [Formica, 2006]	Nouns, Synets of WordNet	Not mentioned	single, cross	Formal concept analysis	All relation can be considered	domain ontology

Table 4. Feature based Measures

Sl .No	Author Name and Year	Feature set	Accuracy	Type of ontology	Benchmark – dataset	Taxonomical-Relation	Type of Ontology
1	Tversky's [38] [Tversky, 1997]	Common feature and uncommon feature is computed	0.74	single, cross	Miller & Charles	All relation can be used in WordNet	WordNet &MeSH ontology
2	Roand& Eg [39] [Roand,2001]	Neighborhood ,glosses, features synonyms	0.77	single, cross	miller & Charles	All relation can be used in WordNet	WordNet &MeSH ontology
3	X-Similarity: Computing Semantic Similarity between Concepts [45] [Petrakis,2006]	Feature based approach Synset and term description among cross ontology	0.72	Cross Ontology	Miller and Charles	All Relationship	MeSh and WordNet Ontology
4	Ontology –based semantic similarity feature based approach[58] [Sanchez,2012]	Taxonomical features, normalized dissimilarity , sub-sumbers, features generated	0.83	Single	Miller & Charles, Rubenstein& GoodEnogh data set	"is-a" , "part – of" relationship	WordNet ontology
5	Towards the estimation of feature – based semantic similarity[59] [Albert,2014]	Common taxonomic subsumbers , static cost between two subsumbers	0.76	Single ,cross	Miller & Charles, Rubenstein& GoodEnogh data set	All relation can be considered	WordNet ,MeSH ontology
6	Ontology based similarity for product information [60] [Akmal,,2014]	Case based reasoning , classes, feature replaced by words ,concept lattice	0.79	single, cross	Product dataset	All relation can be considered	Domain ontology
7	Feature based approaches using Wikipedia[61] [Yuncheng,2015]	Feature extraction using Wikipedia, formal representation of Wikipedia	0.83	single, cross	Miller and Charles, 353 data set	All relation can be consider	WordNet

Table 5. Hybrid Measures on various parameters

Sl. No	Author Name and year	Feature set	Accuracy	Type of ontology	Benchmark –dataset	Taxonomical-Relationship	Type of Ontology
1	Similarity using fuzzy distance[62][Valerie, 2004]	Fuzzy min and max distance	0.74	Cross and fuzzy	No dataset	All kind of relationship	WordNet
2	Fuzzy Semantic Distance Measures [63] [Allahverdi, 2007]	Fuzzy distance, vector models, Bhattacharya distance	0.79	single, cross, fuzzy	No dataset	All Relationship	WordNet ontology ,merging multiple ontology
3	Fuzzy Measures on the Gene Ontology for Gene Product Similarity[64] [Mihail, 2006]	Annotation terms, fuzzy measure similarity, Choquet integral	0.83	single, cross ,fuzzy	No dataset	All relation is considered	Gene ontology
4	Evaluating Similarity Measures for Emergent Semantics of Social Tagging[65] [Benjamin,2009]	User-created tag, per user projection ,open dictionary	0.81	single, cross	social mining data	All relation can be considered	WordNet ontology

5	Similarity Measure using Fuzzy Formal concept [66][Selvi, Suresh; 2012]	Page count ,lexical pattern, pattern extraction cluster	0.76	single, cross, fuzzy	Miller and Charles dataset	All relation can be considered	WordNet
6	Semantic similarity estimation from multiple ontologies[56] [Batet,2011]	Ratio of taxonomic feature ,heuristic approach	0.81	single, cross	Miller and Charles dataset	is-a , part -of relationship	MeSh, SNOWED CT, WordNet ontology
7	Semantic similarity assessment of words using weighted WordNet[67] [Mostafa,Ehsan,2014]	Weighted edge distance, depth of the word ,swarm optimization	0.82	single, cross	Miller & Charles	All relation can be used in WordNet	WordNet ontology
8	Combining edge-counting and information content theory[68] [Jian-Bo, Xiao-Hua,2015]	Information content ,edge based weighted shortest path	0.8	single, cross	No dataset	Semantic Relatedness	WordNet ontology
9	A Novel Approach to Find Semantic Similarity Measure between Words[69][Lakshay,2014]	Page count, text snippets , edge counting approach, svm	0.76	Single, cross	Miller and Charles	All relation can be used in WordNet	WordNet ontology
10	LIPN-CORE[70] [Davide,2013]	Support vector regression model, Levenshtein distance, Named Entities overlap, Wu-Palmer	0.83	single, cross	WordNet &MeSH ontology	Length ,distance, Depth, synonym, antonym	WordNet &MeSH ontology
11	FMLNCSIM: fuzzy measure-based similarity calculation[71] [Chen ,2016]	Fuzzy Measure lncRNA functional similarity	0.78	Single	Lnc RNADisease	All	MeSH ontology
12	A hybrid approach for measuring semantic similarity[40] [Cai,2017]	Hybrid Approach Intrinsic- IC and Edge based	0.87	Single Ontology	Miller and Charles TC-353	“is –a”	WordNet
13	Semantic similarity and relatedness between biomedical concepts [48] [Sam,2018]	Frequency count and UMLS hierarchy	0.84	Cross Ontology	Med-Line Text Data	All Relationship	UMLS Hierarchy
14	Distance learning techniques for ontology similarity[72] [Wei,2017]	Graph structure of Ontology Distance structure	0.82	Single Ontology	Textual Data	All Relationship	Go Ontology Plant Ontology

6. Discussion

We have given the detailed comparative study in the above section. These finding can be further used for defining the New similarity measures in this area. Different analysis and results are given below:

In the Edge based measures, feature sets like length, depth, LCS, direct and indirect links were considered. These approaches are quite simple and execution time is less as they have to consider only length or the depth of the ontology**.** In these measures accuracy lies between the ranges of 0.51 to 0.67. It works only for the single ontologies. These measures considered only the “is-a” relationship among the ontology. They work well for the Global ontologies like WordNet and MeSH ontologies as these ontologies describes the complete structure of the general purpose ontology.

In the information content approach LCS, formal concept analysis, noun, synsets and graph similarity features sets were used. Here the accuracy lies between the 0.59-0.78. The accuracy depends on the coverage and the structure of the ontology. As the depth of ontology increases the similarity increases. They work well in single ontology and also works for the cross ontology using the LCS, if the LCS exists among the ontology, the similarity can be computed accordance with the LCS. In this type of measures “is-a”,

"part-of" relationships can be considered if the relationships were present among ontologies. It works for the single, cross ontology framework where complete structure/relationships are defined among the ontologies.

Feature based approaches can be applied for the single, cross and fuzzy ontology framework. There accuracy lies between the 0.67-0.83. In WordNet we have the gloss information that can be used to calculate the similarity however MeSH ontology doesn't provide such information. In this all the relation can be considered as these approaches not consider length and the structure of the ontology. These measures computed high correlation value among the words. However, none of work was presented, where fuzzy integration with feature based approaches was given. So, this can be future work in this area. These approaches furnish the same result on small or big ontology or on any type of ontology. These measures only depended upon the features of the concepts. For the small size and for the domain ontology they compute good accuracy with less complexity.

In Hybrid method, any two of the above method can be combined. It takes the advantages of any of two techniques. Accuracy lies between 0.76-0.87 in Hybrid approaches. In the hybrid work some researcher introduced the fuzzy concepts in their measures. The accuracy is high as compared to edge based and content base and comparable to the feature based approach. The features set in these techniques were used annotated terms, open dictionary, swarm optimization, heuristic approach and text snippets. These types of approaches are good and give high accuracy and can be used for the all relationship but it adds complexity to the system due to its features set. These approaches can be applied for fuzzy ontology.Very few measures were proposed in the area of fuzzy ontology framework.

Accuracy graph of different Similarity Measures is shown in Fig 5. Maximum accuracy is 0.86 by feature based approach[61] and Hybrid approaches[40,70].

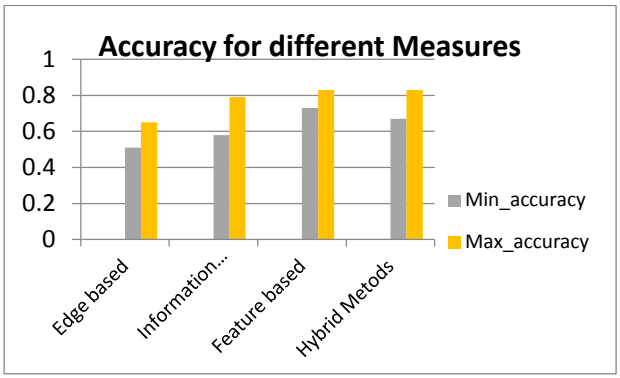


Figure 5 Accuracy Graph for the different measures.

Mostly research drawing interest in Hybrid approaches due to its high accuracy and adaptability to new research areas. Edge based approaches are good for global ontologies and but consider only taxonomical relations and works for single ontology. Information Content approaches works for cross ontologies and where complete structure and relationships are described among the ontologies. Feature based approaches work well in single and cross ontology. Only limitation with this method is to find the complete features of the concepts in the defined domain ontologies. Various measures work on the different ontologies framework is shown in Fig 6.

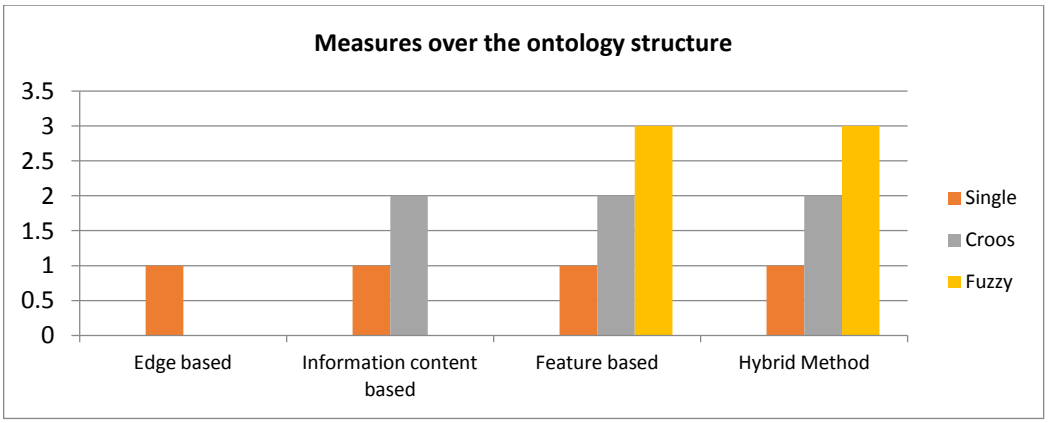


Figure 6 Measures over the Ontology's framework

Charles's dataset[43] is most popular dataset for WordNet. TC-353 dataset is used in recent research, as it has more emphasis on semantic relatedness as compared to similarity.

Data-set used by various measures shown in Fig.7.

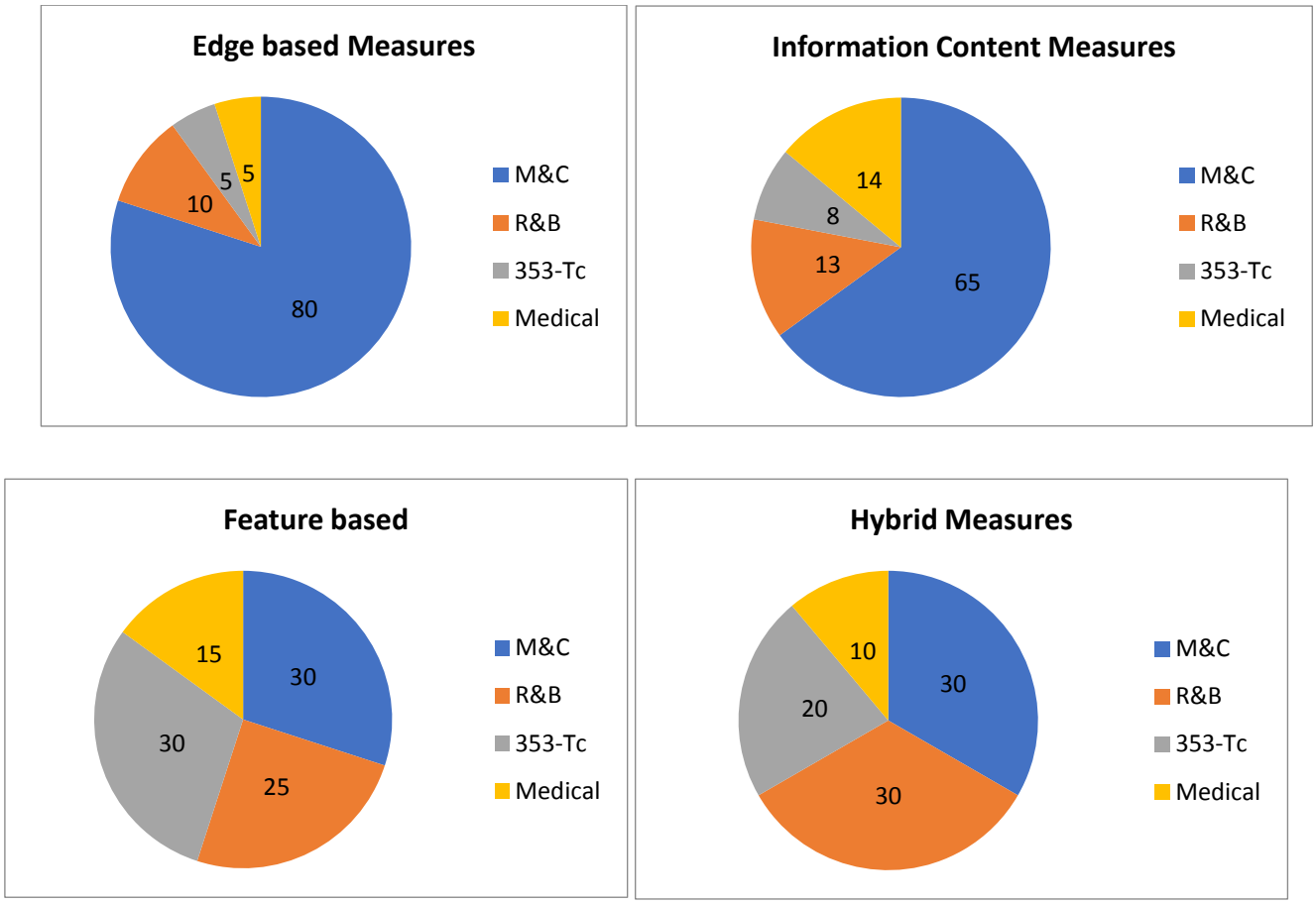


Figure 7 (a), (b), (c), (d) Data Set used in Various Measures.

Taxnomoical relationships considered by the different knowledge- based approches are shown in fig 8.

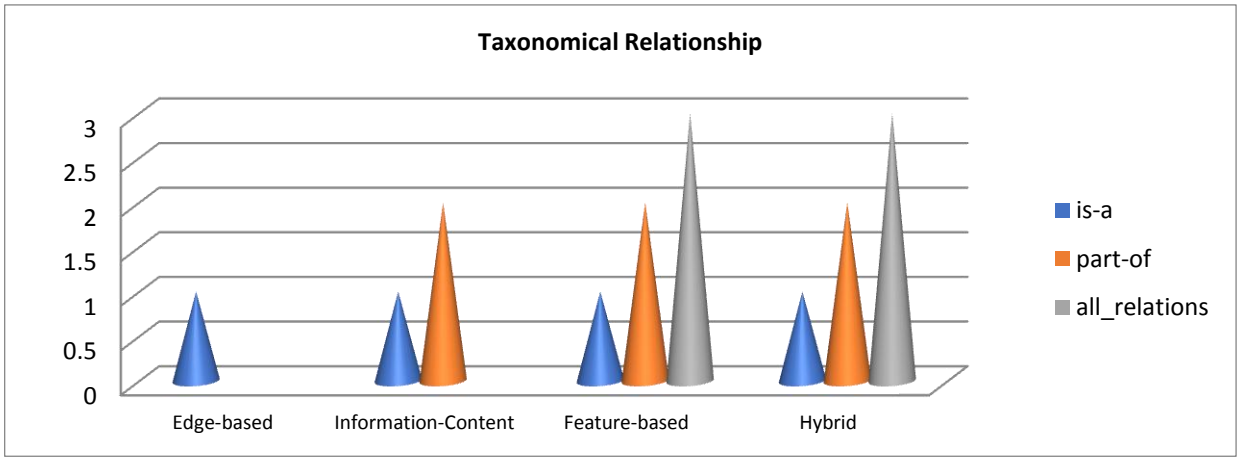


Figure 8 Represention of taxinomical relationships among the measures

7. Conclusion and future work

In this research paper, a detailed study of previous two decade work in field of semantic similarity is presented. In this study the state of the art similarity measures are compared based on the seven parameters like Type of Measure, Feature set, Accuracy, Ontology framework, Benchmark Datasets, Taxonomical relationships and Ontology Type. To cope up with new emerging fields new similarity measures are proposed every year. However, there are certain issues in their approaches. If similarity is high, then complexity is high due to their feature set. Similarity measure compute good result among the single ontology but not give the same result over the cross ontologies. Edge based measure works only in single ontology and only taxonomical relationships are considered. Information content methods are works in the area of cross ontology with the existence of LCS. Feature based approaches are found to give high correlation values and give good result on both single and cross ontologies. But some time it is difficult to determine the features of a concept in certain ontologies. Corpus based method like LSA and PMI can be further used for finding the features in the domain ontologies. These measures are used for the domain ontologies and features can be formulated using text processing methods.

To cope up with new emerging field of knowledge based new methods for similarity measured was proposed every year. Further we can identify more parameters in this area like complexity of the measures, tool/ language support for measures, ease of adaptability and ontological coverage.

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Integration of Solar PV with Low-Voltage Weak Grid System: Using Normalized Laplacian Kernel Adaptive Kalman Filter and Learning Based InC Algorithm

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***Abstract*—This work proposes a novel Normalized Laplacian Kernel Adaptive Kalman Filter (NLKAKF) based control technique and Learning based Incremental Conductance (LIC) MPPT (Maximum Power Point Tracking) algorithm, for low voltage weak grid-integrated solar photovoltaic (PV) system. Here, a two-stage topology of three-phase grid integrated solar PV system is implemented, where the loads are connected at the PCC (Point of Common Coupling). Proposed LIC is the improved form of Incremental Conductance (InC) algorithm, where inherent problems of traditional InC technique, like steady state oscillation, slow dynamic responses and fixed step size issues, are successfully mitigated. The prime objective of proposed NLKAKF control is to meet the active power requirement of the loads from generated solar PV power, and after feeding load, excess power is fed to the grid. However, when generated PV power is less than the required load power, then NLKAKF control meets the load by taking extra required power from the grid. During this process, power quality is improved at the grid. The controller action provides reactive power compensation, power factor correction, harmonics filtering and mitigation of other power quality issues. Moreover, when the solar irradiation is zero, than VSC (Voltage Source Converter) acts as DSTATCOM (Distribution Static Compensator), which enhances the utilization factor of the system. The proposed techniques are modeled and their performances are verified experimentally on a developed prototype, in solar insolation variation conditions, unbalanced loading, as well as in different grid disturbances such as over-voltage, under-voltage, phase imbalance, harmonics distortion in the grid voltage etc.**

***Index Terms* — Solar PV Array, Grid Integrated System, NLKAKF Control, LIC MPPT, Power Quality, DSTATCOM.**

I. INTRODUCTION

CURRENTLY, a large amount of renewable distributed generation is fed to low-voltage weak distribution networks, which is posing significant impacts on the operation and power management of the system [1].

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The major advantage is power generation support with zero fuel cost, zero pollution and minimum operating cost. Out of several renewable resources, due to the static structure, and small size, solar PV (Photovoltaic) based energy generating system is highly popular. Therefore, three-phase two-stage grid integrated solar PV topology is popular on the residential level, as a rooftop PV array, and on a commercial level, as a PV park [2]. The advantage of a two-stage system is, that it can work with any rating of the PV array because the DC-DC converter maintains the constant DC link voltage. The overall control complexity is much less, because two separate controllers are used, one for the DC-DC converter such as boost converter, and another one for the DC-AC converter, such as Voltage Source Converter (VSC). Moreover, in partial shading condition [3][4], the fluctuation of PV voltage is very rapid in huge amount [5], so the two-stage system is the only option for operating in constant DC link voltage condition.

However, a robust and efficient control strategy for DC-AC converter (VSC), is essentially required for optimal operation. The prime objective is that first fullfils the load demand and, after satisfying the load demand the rest power is supplied to the main grid. However, when generated power is not sufficient for the load, then the load requirement is met by taking extra required power from the grid. In this process, the responsibilities of the control technique, are power conversion from DC to AC, to follow the grid code for synchronization to the grid, improvement of power quality of the supply power, to act as a DSTATCOM (Distribution Static Compensator) when solar irradiation is zero, and power management. Moreover, during this process, power quality is improved at the grid, it provides power factor improvement, reactive power suport, harmonics filtering and mitigation of other power quality issues.

In-depth literature review on 'control techniques for the grid integrated solar PV system' depicts that several novel fundamental extraction, harmonics elimination and synchronization techniques have been proposed for efficient control of grid integrated solar PV system. The *dq0*-transformation based SRF (Synchronous Rotating Frame) [6][7] control technique is a most popular technique. Because, in normal condition, it performs very good UPF (Unified Power Factor) operation or reactive power support to the grid. However, due to load unbalances, a second harmonic component dominants in *dq0*-components. Therefore, for mitigation of second harmonic component, a low-pass filter is used, which slows down the performances of the SRF based control technique. Moreover, recently, researchers have proposed several adaptive control algorithms, such as fuzzy

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adaptive control, learning based control, power delta control etc. However, for abnormal grid conditions, the performances of these control techniques, are not reported, which is the essential phenomenon of the distribution grid. The other control techniques like, discrete-Fourier transform (DFT) [8], PM (Prony's method), frequency locked loop (FLL), second-order generalized integrator (SOGI) [9] and Kalman filter (KF) [10] have been proposed to handle the abnormal grid conditions. However, none of these techniques is suitable for all types of grid adverse conditions, such as FLL and SOGI based control techniques are unable to handle lower order harmonics and DC offset. The fixed length window with stationary waveform is required for searching in DFT based control technique, which is not suitable for online searching. The performance of PM is appreciable in different grid adverse conditions. However, in the PM technique, the higher order polynomial equation and its solution process, create a huge computational burden on the processor, which is not suitable for the low-cost microcontroller. Similarly, KF based control technique is good for estimation using correction and prediction process. Moreover, the modified version of KF, like extended KF [11] and linear KF based control techniques are also good for the integrated grid system. However, during state variable estimation, linearization, prediction and correction, the derivative properties are used, which is the source of burden and algorithm complexity on the processor. Therefore, a heavy computational burden arises on the processor, which is not suitable for a low-cost microcontroller. Model predictive control technique [12] is also popular for good steady-state response, but during dynamic condition, its responses are poor, due to its predictive nature, which is based on the previous dataset. Similarly, resonant controllers, for tracking the sinusoidal inverter current, in the grid-connected system [13], show a good steady state response with low harmonics content in injected grid current. However, during the transient condition, performance rapidly deteriorates, due to the changes in the grid frequency.

Recently, several adaptive control algorithms have been developed, like repetitive current control [14], adaptive ripple correlation control [15] discrete Fourier transform [8], SOGI (Second Order Generalized Integrator) [9], FLL (Frequency Locked Loop), KF (Kalman Filter), least mean square [16], least mean fourth (LMF) [17], Leaky LMF etc. However, the major issues with these techniques are that the performances of the algorithms are not examined under abnormal grid conditions, those are most frequent, unusual and critical phenomenon in distributed power generation system.

Therefore, in this paper, a novel Normalized Laplacian Kernel Adaptive Kalman Filter (NLKAKF) based control algorithm is developed for robust and efficient control of grid-tied solar PV system. NLKAKF technique belongs to the estimator family, where Laplacian kernel function is integrated into the estimation process for quick pattern recognition of fundamental component. Due to the hybridization of Laplacian kernel function with Kalman filter, this technique is free from the derivative term, so the computational burden is low, as well as the performance of NLKAKF control is instantaneous and suitable for the high-frequency system.

Moreover, in this paper, a Learning based Incremental Conductance (LIC) based MPPT (Maximum Power Point Tracking) algorithm is proposed. This LIC is the improved form of Incremental Conductance (InC) algorithm [18], which mitigates the inherent problems of traditional InC algorithm like steady state oscillation, slow dynamic responses and fixed step size issues. A literature review on MPPT, shows that many authors have tried to solve these problems through some modifications in classical algorithm namely, adaptive P&O [19], improved InC [20], modified InC [21][22] direct MPPT [23], fuzzy logic based MPPT, dynamic MPPT [24], fast MPPT [25], artificial intelligence based MPPT approach, *etc*. However, still, an optimum solution has not come. Because, if few improved techniques are performing well in the steady state then lagging during dynamics, vice versa. Moreover, few techniques are performing relatively well, but the huge computational complexity and large design constraints, restrict to perform on low-cost processor. Therefore, LIC algorithm is proposed, which simple structure is easy in implementation and its learning nature decides size of step change according to the situation, such as step size decreases during steady state condition, and step size increases during dynamic change.

In this manuscript, the merits of the NLKAKF control technique and LIC MPPT technique, are verified experimentally on a developed prototype, in solar irradiation variation conditions, imbalanced loading condition for linear/nonlinear loads, as well as in different grid disturbances such as grid over/under voltage, phase imbalance, harmonics distortion in grid voltage etc. Obtained test results have satisfied the objectives of the developed technique and the IEEE-519 standard [26].

II. System Layout

A two-stage topology of three-phase grid-tied solar PV system is given in Fig.1, where solar PV power is supplied to the grid, through a DC-DC converter and a three-phase voltage source converter (VSC) in such a way that the operating point of PV array is at MPP (Maximum Power Point) and, the converter is synchronized to the grid.

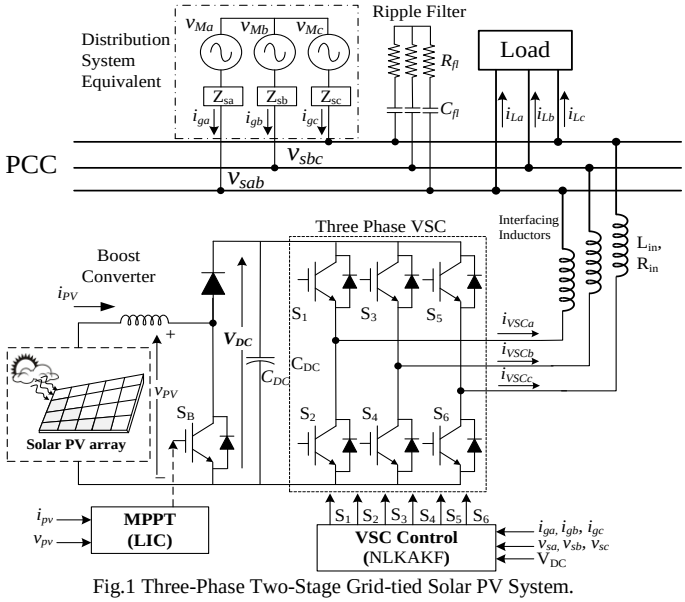


Fig.1 Three-Phase Two-Stage Grid-tied Solar PV System.

Here for control, LIC MPPT algorithm is used for the DC-DC converter, and NLKAKF based control algorithm is used for the VSC. In this configuration, at the point of common coupling (PCC), ripple filter (C_{fl}, R_{fl}), grid through interfacing

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inductors (L_{in}, R_{in}), load and output terminals of VSC are connected. Here, the ripple filter is used for absorbing switching ripples, which are produced by VSC. The main objectives of control scheme, are during PV power generation, the power is fed to the grid in UPF (Unity Power Factor) mode of operation, and when PV power is unavailable then it operates in DSTATCOM mode [27].

III. CONTROL APPROACH

In the proposed control scheme, two separate control strategies are used for the boost converter and for VSC, which is shown in Fig.2. For boost converter, a novel LIC MPPT technique is used for maximum power harvesting from the solar PV array. Moreover, for VSC, a novel NLKAKF based control strategy is used in UPF operation. Here, NLKAKF algorithm is used for extraction of fundamental component from load current and estimation of reference grid currents.

First, LIC MPPT technique is used for the boost converter, which produces a reference voltage (V_{ref}), for operating on maximum power.

For keeping constant DC link voltage (V_{DCref}) and forced to operate at V_{ref}, an optimal duty cycle (β) is calculated, which is described as,

$$\beta = 1 - \frac{V_{ref}}{V_{DCref}} \tag{1}$$

For generating switching signal for the boost converter (S_B), the sawtooth signal and calculated β are compared, which generates switching pulse. V_{DCref} is calculated [28] as,

$$V_{DCref} = \sqrt{3} \times \theta \times V_x \tag{2}$$

Where, V_x is amplitude of grid voltage and θ is loss compensation component.

After this, line voltages (v_{sab}, v_{sbc}) are sensed at PCC and 3-phase voltages (v_{sa}, v_{sb}, v_{sc}) are calculated as,

$$\begin{bmatrix} v_{sa} \\ v_{sb} \\ v_{sc} \end{bmatrix} = \frac{1}{3}\begin{bmatrix} 2 & 1 \\ -1 & 1 \\ -1 & -2 \end{bmatrix}\begin{bmatrix} v_{sab} \\ v_{sbc} \end{bmatrix} \tag{3}$$

These grid phase voltages (v_{sa}, v_{sb}, v_{sc}) are filtered by using NLKAKF. During filtering process, v_{sa}, v_{sb}, and v_{sc} are converted into $v_{s\alpha}$, and $v_{s\beta}$ by using abc-to-αβ conversion. $v_{s\alpha}$, and $v_{s\beta}$ are separately filtered by using two separate NLKAKF blocks, which outputs are v_α, and v_β. v_α, and v_β are converted into v_a, v_b, and v_c, by using αβ-to- abc conversion, where v_a, v_b, and v_c are in-phase quantity of the grid voltage. This chain process is described as,

$$\begin{bmatrix} v_{s\alpha} \\ v_{s\beta} \end{bmatrix} = \begin{bmatrix} 2/3 & -1/3 & -1/3 \\ 0 & 1/\sqrt{3} & -1/\sqrt{3} \end{bmatrix}\begin{bmatrix} v_{sa} \\ v_{sb} \\ v_{sc} \end{bmatrix} \tag{4}$$

$$\xrightarrow[\begin{bmatrix} v_{s\alpha} \\ v_{s\beta} \end{bmatrix} \Rightarrow \begin{bmatrix} v_\alpha \\ v_\beta \end{bmatrix}]{NLKAKF} \begin{bmatrix} v_a \\ v_b \\ v_c \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ -1/2 & \sqrt{3}/2 \\ -1/2 & -\sqrt{3}/2 \end{bmatrix}\begin{bmatrix} v_\alpha \\ v_\beta \end{bmatrix}$$

Where, $r=\sqrt{2}\times\omega_o\times T_s$, T_s and ω_o are sampling period and natural frequency ($2\pi f$), respectively.

The amplitude of grid voltage (V_x) is calculated as,

$$V_x = \sqrt{\frac{2}{3}\left(v_a^{\,2} + v_b^{\,2} + v_c^{\,2}\right)} \tag{5}$$

The in-phase unit-templates (u_a, u_b, u_c) are calculated as,

$$u_a = \frac{v_a}{V_x},\ u_b = \frac{v_b}{V_x},\ u_c = \frac{v_c}{V_x}, \tag{6}$$

For improving the dynamic performances, by using the solar PV dynamic reflection component (I_{Dpv}), the impact of the instantaneous reflection in PV power (P_{PV}) on the grid current is taken under consideration, which is derived as,

$$I_{Dpv} = \frac{2P_{pv}}{3V_x} \tag{7}$$

For maintaining the DC link voltage, V_{DCref} is compared with sensed DC link voltage (V_{DC}), which generates DC link voltage error (e_{DC}= V_{DCref} - V_{DC}). This e_{DC} is fed to the PI (Proportional Integral) controller, which gives the value of the DC loss component (β_{DC}), as,

$$\beta_{DC}(n+1) = G_{P1}\times e_{DC}(n) + G_{I1}\times\int_0^t e_{DC}(n)\,dn \tag{8}$$

Where, G_{I1} and G_{P1} are integral and proportional gains of PI controller, respectively, which regulates *DC* link voltage.

Since, nonlinear load currents consist of harmonic components and shape of the waveform is very similar to quasi square. Therefore, to obtained the active load power components (i_{loa}, i_{lob}, i_{loc}), the load currents (i_{La}, i_{Lb}, i_{Lc}) are fed to NLKAKF, which generates in-phase fundamental components (k_a', k_b', k_c'), quadrature components (k_a'', k_b'', k_c'') and estimated fundamental frequency (C_f).

$$\left.\begin{aligned} \begin{bmatrix} k_a' & k_a'' & C_f \end{bmatrix} &= f_{\text{NLKAKF}}(i_{La}) \\ \begin{bmatrix} k_b' & k_b'' & C_f \end{bmatrix} &= f_{\text{NLKAKF}}(i_{Lb}) \\ \begin{bmatrix} k_c' & k_c'' & C_f \end{bmatrix} &= f_{\text{NLKAKF}}(i_{Lc}) \end{aligned}\right\} \tag{9}$$

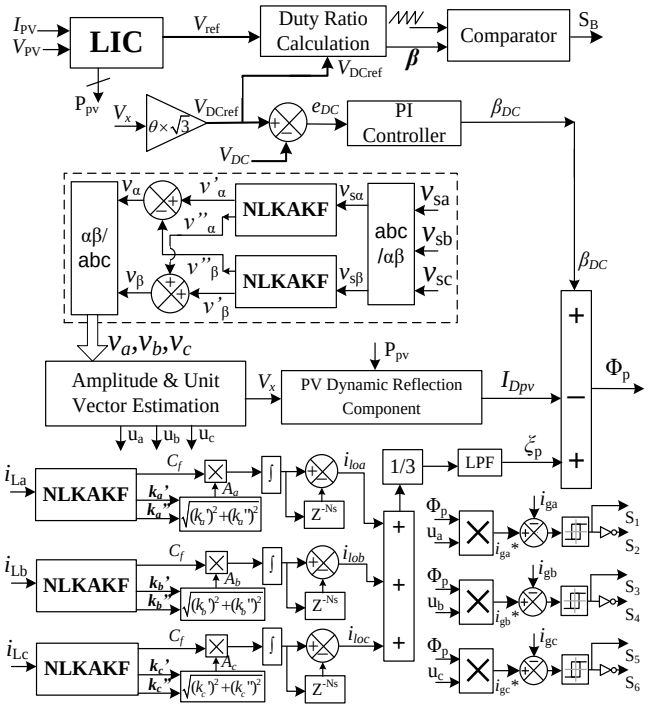


Fig.2 Control scheme for two-stage three-phase grid-tied solar PV system.

By using k_a', k_b', k_c' and k_a'', k_b'', k_c'', the amplitudes (A_a, A_b, A_c) of fundamental components (FC) of all phases are generated as,

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$$\left.\begin{aligned} A_a &= \sqrt{k_a'^2 + k_a''^2} \\ A_b &= \sqrt{k_b'^2 + k_b''^2} \\ A_c &= \sqrt{k_c'^2 + k_c''^2} \end{aligned}\right\} \quad (10)$$

A_a, A_b, and A_c are amplified by using C_f. After it, active load power components (i_{loa}, i_{lob}, i_{loc}) of all phases are found, which is the difference of 'integrated signal' and 'one step delayed signal of integrated signal'. The samples interval of 'one step delayed signal of integrated signal' is N_s ($N_s=f_s/C_f$), where f_s is sampling frequency.

The resultant active load power (ξ_p) is calculated as,

$$\xi_p = \frac{1}{3}\left(i_{loa} + i_{lob} + i_{loc}\right) \quad (11)$$

The net loss component (Φ_p) is calculated as,

$$\Phi_p = \beta_{DC} + \xi_p - I_{Dpv} \quad (12)$$

The reference grid currents (i_{ga}*, i_{gb}*, i_{gc}*) are generated as,

$$\left.\begin{aligned} i_{ga}^* &= u_a \times \Phi_p \\ i_{gb}^* &= u_b \times \Phi_p \\ i_{gc}^* &= u_c \times \Phi_p \end{aligned}\right\} \quad (13)$$

The switching pulses (S_1, S_2, S_3, S_4, S_5, and S_6) for voltage source converter are generated by using hysteresis controller (HC), where the input signals are grid currents (i_{ga}, i_{gb}, i_{gc}) and i_{ga}*, i_{gb}*, i_{gc}*. Here, fixed band modulation scheme is used for HC. The advantages of HC are, its ability to control the peak to peak value of current ripple in desired hysteresis band limit and, it provides good dynamic performance.

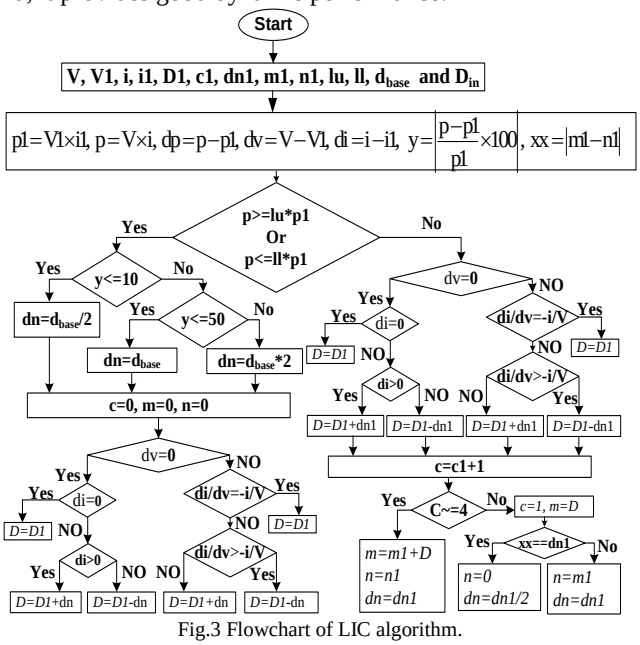


Fig.3 Flowchart of LIC algorithm.

A. *Learning based Incremental Conductance (LIC) Algorithm*

The efficiency of the solar PV array is improved by using a MPPT algorithm, which forces to operate at the maximum power point. The most popular MPPT techniques are P&O, Inc and HC (Hill Climbing). However, the problems with these techniques are steady state oscillation, slow dynamic responses and fixed step size issues. Therefore, for mitigating the all above problems a novel LIC algorithm is proposed here.

Figs.3-4 show the working strategy of LIC technique, which is divided in 2 parts.

1st section deals with the steady state situation after that mitigates oscillation, by reducing the size of step change. Moreover, 2nd section deals with the dynamic change condition after that it quickly jumps on required duty cycle, by increasing the size of step change. For sensing the condition, an envelope is created in each iteration, which upper and lower bands are *lu* and *ll*, respectively. *lu* and *ll* are calculated according to the base step size (d_{base}), which is taken as a fixed size of step change in conventional InC. *lu* and *ll* are described as,

$$lu = \left(100 + \left(\left(\frac{V_{oc}}{1-d_{base}}\right) - V_{oc}\right) \times \frac{100}{V_{mpp}}\right) \times \frac{1}{100} \quad (14)$$

$$ll = \left(100 - \left(\left(\frac{V_{oc}}{1-d_{base}}\right) - V_{oc}\right) \times \frac{100}{V_{mpp}}\right) \times \frac{1}{100} \quad (15)$$

$$\left.\begin{aligned} (lu \times p1) >= p >= (ll \times p1) \quad &\Rightarrow Steady\ State\ Condition \\ else \quad &\Rightarrow Dynamic\ Change\ Condition \end{aligned}\right\} \quad (16)$$

In dynamic change condition, the change in step size is described as,

$$\left|\frac{p-p1}{p1} \times 100\right| \Rightarrow \left\{\begin{aligned} if\ <=10, \quad &\rightarrow dn = d_{base}/2 \\ if else <=50 \quad &\rightarrow dn = d_{base} \\ else \quad &\rightarrow dn = 2 \times d_{base} \end{aligned}\right\} \quad (17)$$

In steady state condition, store addition of first 3 conjugative duty cycles in variable '*nl*' and, after this store addition of second 3 conjugative duty cycles in variable '*ml*'. Here *dn* is calculated as,

$$\left.\begin{aligned} if \quad |ml - nl| == dn1, \quad &\Rightarrow n = 0,\ dn = dn1/2 \\ \text{else} \quad , \quad &\Rightarrow n = ml,\ dn = dn1 \end{aligned}\right\} \quad (18)$$

After *dn* calculation, follow the logics for optimal duty cycle (*D*) calculation, which is described as,

$$\left.\begin{aligned} if\ dv = 0, \quad &\left\{\begin{aligned} if \quad di = 0 \quad &\Rightarrow D = D1 \\ elseif \quad di > 0 \quad &\Rightarrow D = D1 + dn \\ else \quad &\Rightarrow D = D1 - dn \end{aligned}\right. \\ else, \quad &\left\{\begin{aligned} if \quad di/dV = -i/V \quad &\Rightarrow D = D1 \\ elseif \quad di/dV > -i/V \quad &\Rightarrow D = D1 - dn \\ else \quad &\Rightarrow D = D1 + dn \end{aligned}\right. \end{aligned}\right. \quad (19)$$

Where, *dp=p-p1*, *dV=V-V1*, *di=i-i1*, and *D1* is the previous duty cycle.

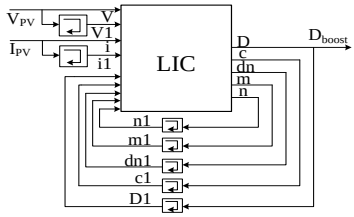


Fig.4 Block model of LIC algorithm.

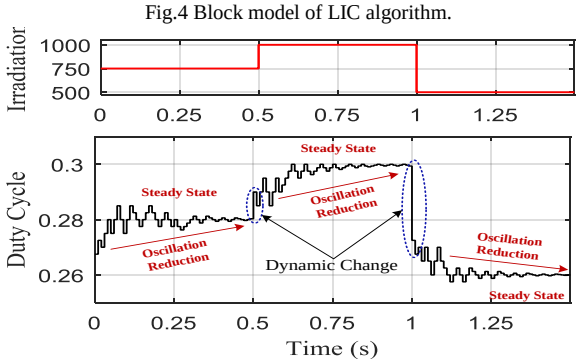


Fig.5 Steady-state and dynamic behavior of LIC algorithm.

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The steady-state and dynamic behaviors of LIC algorithm, are shown in Fig.5. Fig.5 shows an optimal behavior of LIC algorithm during steady-state and dynamic conditions, which show oscillation reduction in steady state condition and sudden jump, according to the amount of irradiation change in dynamic conditions.

B. Normalized Laplacian Kernel Adaptive Kalman Filter (NLKAKF)

The NLKAKF is the hybrid of Kalman filter and Laplacian Kernel function, as well as it performances, are accelerated by adaptive concept with normalizing vector. In this paper, NLKAKF through filtering, smoothing and learning process, estimates fundamental component (FC) from the load currents and grid voltages, which consists of huge amount of harmonics.

1) Kalman Filter (KF)

KF is a well-established recursive technique of estimation in the discrete time domain, from derived state space model of any system [29]. For derivation of KF, the considered state space model is described as,

$$\left.\begin{aligned} k(\mathrm{i}+1) &= \mathrm{g}_i\, k(\mathrm{i}) + \mathrm{Q}_i \\ y(i) &= h_i^T k(i) + O_i \end{aligned}\right\} \tag{20}$$

Where, k is state vector, i is sampling instant, y is the input signal, g_i is state transition matrix, Q_i is process noise, O_i is measured noise, h_i is measurement matrix.
The different stages of KF is described as,
Stage-1: Prediction of state vector ($\bar{k}(\mathrm{i}+1)$)

$$\bar{k}(\mathrm{i}+1) = \mathrm{g}_i\, k(\mathrm{i}) \tag{21}$$

Stage-2: Prediction of covariance matrix ($\bar{C}_{i+1}$)

$$\bar{C}_{i+1} = \mathrm{g}_i\, C_i\, \mathrm{g}_i^{\mathrm{T}} + q_i \tag{22}$$

Stage-3: Calculation of Kalman gain matrix (E_i)

$$E_i = \frac{\bar{C}_i h_i^T}{h_i \bar{C}_i h_i^T + q'} \tag{23}$$

Stage-4: Update estimation (k_i)

$$k(\mathrm{i}) = \bar{\mathrm{k}}(\mathrm{i}) + E_i y(\mathrm{i}) - E_i h_i \bar{\mathrm{k}}(\mathrm{i}) \tag{24}$$

Stage-5: Update covariance matrix (C_i)

$$C_i = \left(I - E_i h_i\right)\bar{C}_i \tag{25}$$

Where, T indicates transpose matrix, q_i is process noise covariance matrix, I is the identity matrix, q' is measurement noise covariance parameter.
In this paper, KF is used for FC (Fundamental Component) extraction from the signal. A sinusoidal signal is expressed as,

$$y_i = A_i(\mathrm{i})\sin\left(i\omega(\mathrm{i})\mathrm{T}_s + \Theta\right) \tag{26}$$

Where, i is an integer number, T_s is sampling time. Θ_0 and Θ are initial and instantaneous phase angles. This expression (26) is broken into two parts, in-phase (k') and in quadrature (k'') w.r.t. FC, which is shown as,

$$\left.\begin{aligned} k'(\mathrm{i}) &= A_i(\mathrm{i})\sin\left(\omega(i)\,\mathrm{T}_s + \Theta_0\right) \\ k''(\mathrm{i}) &= A_i(\mathrm{i})\cos\left(\omega(i)\,\mathrm{T}_s + \Theta_0\right) \end{aligned}\right\} \tag{27}$$

Here, state vector is k(i)=[k'(i) k''(i)]$^{\mathrm{T}}$, so predicted state vector is derived as,

$$\left.\begin{aligned} \bar{k}'(\mathrm{i}+1) &= k'(i)\cos\left(\omega(\mathrm{i})\,\mathrm{T}_s\right) + k''(i)\sin\left(\omega(\mathrm{i})\,\mathrm{T}_s\right) \\ \bar{k}''(\mathrm{i}+1) &= -k'(i)\sin\left(\omega(\mathrm{i})\,\mathrm{T}_s\right) + k''(i)\cos\left(\omega(\mathrm{i})\,\mathrm{T}_s\right) \end{aligned}\right\} \tag{28}$$

From (28), g_i is expressed as,

$$g_i = \begin{bmatrix} \cos\left(\omega(\mathrm{i})\,\mathrm{T}_s\right) & \sin\left(\omega(\mathrm{i})\,\mathrm{T}_s\right) \\ -\sin\left(\omega(\mathrm{i})\,\mathrm{T}_s\right) & \cos\left(\omega(\mathrm{i})\,\mathrm{T}_s\right) \end{bmatrix} \tag{29}$$

Since, estimated frequency is equal to the input voltage frequency, so $h_i = [1 \quad 0]$.

2) Normalized Laplacian Kernel Kalman Filter

Laplacian kernel function has well-known strong estimation ability, as well as a good learning capability. The Laplacian kernel function (K_L) [30] is defined in such a way that all samples (s_i and s_j) belong to the input space (S_s). By using feature map, K_L is described as,

$$K_L(\mathrm{s}_i, \mathrm{s}_j) = <\xi(\mathrm{s}_i),\ \xi(\mathrm{s}_j)> \tag{30}$$

Where, ξ indicates feature map. Here, by using ξ all sample points are mapped at high dimensional feature space (S_H), which is described as, $\xi \rightarrow S_S \in S_H$
For mapping of K_L, normalized Laplacian kernel function is used, which is described as,

$$K_L(\mathrm{s}_i, \mathrm{s}_j) = e^{\left(-\frac{\|s_i - s_j\|}{\sigma}\right)} \tag{31}$$

Where, σ is width parameter and mathematical operator $\| f \|$ means the nearest integer to f. The operating region of K_L, for σ, 0 to +∞ is shown in Fig.6, and described as,

$$\left.\begin{aligned} \sigma &\rightarrow 0, & K_L(\mathrm{s}_i, \mathrm{s}_j) &\rightarrow 0 \\ \sigma &\rightarrow +\infty, & K_L(\mathrm{s}_i, \mathrm{s}_j) &\rightarrow 1 \\ K_L(\mathrm{s}_i, \mathrm{s}_j) & & &\in [0,\ 1] \end{aligned}\right\} \tag{32}$$

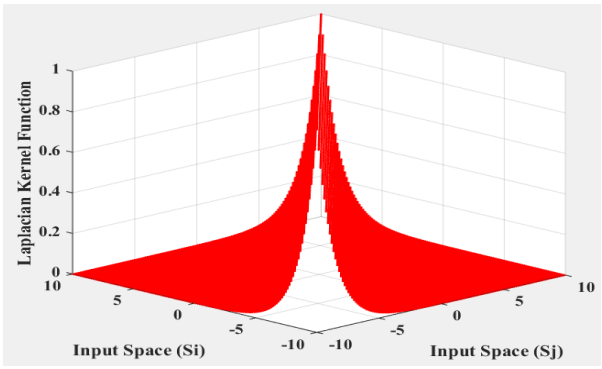


Fig.6 Surface of Laplacian kernel function.

Fig.6 and (32) show that in between [0, 1] all training patterns are separated correctly. However, in optimal performance, the dependency on σ is very high, which is reduced by the iterative process. The adaptive σ is calculated as,

$$\sigma_{i+1} = ((\sigma_i - \sigma_{i-1})/2) + \sigma_0 \tag{33}$$

Where, σ_0 is initial σ. i+1, i and i-1 indicate, future, present and past instant.
Since, state space model of KF is non-linear in nature, therefore, for quick response during online process, it needs modification according to the level of nonlinearity of the problem, which is achieved through the integration of normalized Laplacian kernel trick with KF. NLKAKF is modelled as,

$$\left.\begin{aligned} k(\mathrm{i}+1) &= \delta(k(\mathrm{i})) + \mathrm{Q}_i \\ y(i) &= \gamma(k(\mathrm{i})) + O_i \end{aligned}\right\} \tag{34}$$

Where, $\delta(k(i))=g_i k(i)$ and $\gamma(k(i))=h_i^T k(i)$. Using Hilbert Space (HS) (34) is reformulated as,

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$$\left.\begin{aligned} k(\mathrm{i}+1) &= \delta(k(\mathrm{i})) + \mathrm{Q}_i \\ y(i) &= \langle \gamma,\ \varphi(k(i)) \rangle_{HS} + O_i \end{aligned}\right\} \quad (35)$$

The Kalman gain is defined as,

$$E_i = \frac{\rho\left[k(\mathrm{i}+1) \times \sigma_i^T\right]}{\theta_{\sigma,i}} \quad (36)$$

$$\sigma_i^T = y(i) - \bar{y}(i) = y(i) - \gamma(\bar{k}(\mathrm{i})) \quad (37)$$

Where ρ[.] is expectation operator.

By using the principle of orthogonality, $\theta_{\sigma,i}$ is defined as,

$$\theta_{\sigma,i} = \rho\left[\sigma_i \times \sigma_i^T\right] = \rho\left[\left(\gamma(k(i)) - \gamma(\bar{k}(i)) + O_i\right)\left(\gamma(k(i)) - \gamma(\bar{k}(i)) + O_i\right)^T\right] \quad (38)$$

$$= \rho\left[\left(\gamma(k(i)) - \gamma(\bar{k}(i))\right)\left(\gamma(k(i)) - \gamma(\bar{k}(i))\right)^T\right] + \rho\left[O_i O_i^T\right]$$

$$\rho\left[k(\mathrm{i}+1)\sigma_i^T\right] = \varepsilon_i \rho\left[k(\mathrm{i})\sigma_i^T\right] + \rho\left[\mathrm{Q}_i\, \sigma_i^T\right] \quad (39)$$

$$\varepsilon_i = \frac{\partial \delta(x)}{\partial x} \quad (40)$$

$$\rho\left[k(\mathrm{i})\sigma_i^T\right] = \rho\left[\left(k(\mathrm{i}) - \bar{k}(\mathrm{i})\right)\left(\gamma(k(\mathrm{i})) - \gamma(\bar{k}(\mathrm{i}))\right)\right] \quad (41)$$

$$\rho\left[\mathrm{Q}_i\, \sigma_i^T\right] = \rho\left[\mathrm{Q}_i\, O_i^T\right] = 0 \quad (42)$$

Prediction of covariance matrix ($\bar{C}_{i+1}$)

$$\bar{C}_{i+1} = \rho\left[\left(k(i) - \bar{k}(\mathrm{i})\right)\left(k(i) - \bar{k}(\mathrm{i})\right)^T\right] \quad (43)$$

$$\gamma(\mathrm{k(i)}) \approx \gamma(\bar{\mathrm{k}}(\mathrm{i})) + \frac{\partial \gamma}{\partial \bar{\mathrm{k}}(\mathrm{i})}\left(k(i) - \bar{\mathrm{k}}(\mathrm{i})\right) \quad (44)$$

$$h_i = \frac{\partial \gamma}{\partial \bar{\mathrm{k}}(\mathrm{i})} = \phi_{i-1}^T \varphi\left(\bar{k}(i)\right) \quad (45)$$

$$\phi_i^T(.) = \left[\phi_{i-1},\ K_G\left(\bar{k}(\mathrm{i}), .\right)\right] \quad (46)$$

From (35)-(46), Kalman gain matrix (E_i) is calculated as,

$$E_i = \frac{\bar{C}_i h_i^T}{h_i \bar{C}_i h_i^T + \theta} \quad (47)$$

The unique feature of proposed technique is, all measurement functions are approximated by using input and hidden state functions where, hidden state functions are estimated using previous information. Like this, in chain process, this is continued during the entire operation, which significantly enhances the estimating and tracking efficiency. The simplified block diagram of NLKAKF is shown in Fig.7, and chain process of NLKAKF is shown in Fig.8, where ϵ is integral controller gain, to track the actual frequency, and ω_o is the ideal frequency of the system.

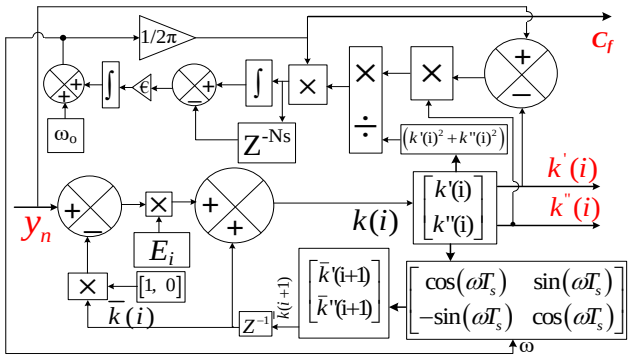


Fig.7 Block Diagram of NLKAKF.

3) Tuning of NLKAKF

The close estimation and tracking capability of NLKAKF, are based on Q_i and q_i parameters. Therefore, the online and adaptive tuning process is used here, which is based on estimated parameters of the previous iteration. The estimated value of Q_i is derived as,

$$\mathrm{Q}_i = k(\mathrm{i}) - k(\mathrm{i}-1) = E_i\left[y(\mathrm{i}) - h_i\, \mathrm{k(i)}\right] \quad (48)$$

By using (48), the measured noise is calculated for each element, and square of Q_i is used to calculating the process noise covariance (q_i). q_i is derived as,

$$q_i = \begin{bmatrix} [Q_1]^2 & 0 \\ 0 & [Q_2]^2 \end{bmatrix} \quad (49)$$

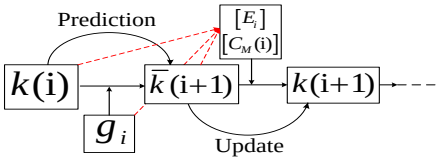


Fig.8 Chain process of NLKAKF.

4) Comparative Analysis of Proposed NLKAKF Algorithm

The comparative analysis of proposed NLKAKF control algorithm with most popular algorithms, such as SOGI, ANF (Adaptive Notch Filter), and KF is shown in Fig.9.

For comparative analysis, the load unbalance situation is considered, where the outage of one phase load for the period of 0.2s to 0.4s, is considered. Fig.9 shows a comparison in the response of fundamental load component extraction from the load current, which is resultant active load component (ξ_p). In term of oscillations, Fig.9 shows that during load unbalance the highest oscillations are in ANF and lowest in NLKAKF. Similarly, in terms of settling time and accuracy, Fig.9 depicts that higher settling time and lower accuracy are in SOGI, while lower settling time and higher accuracy, are in NLKAKF, which shows a very good fundamental load component extraction ability of NLKAKF control Algorithm.

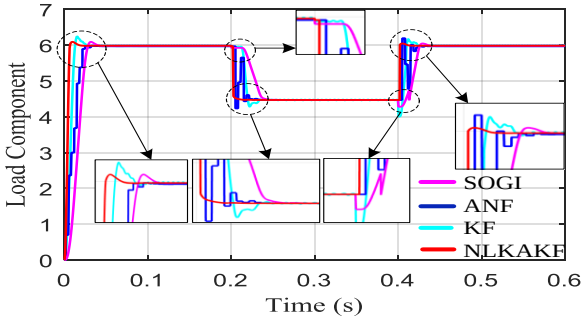


Fig.9 Responses of different algorithms.

IV. Results and Discussion

A prototype of the system is developed for performance evaluation of NLKAKF based control technique, as shown in Fig.10. To realize the PV characteristic, a solar PV simulator (AMETEK, ETS600x17DPVF) is used [31]-[35], and it is integrated to the actual grid. During integration, for PV array power to conversion in AC form, load feeding, and for synchronization, a three-phase voltage source converter (VSC) is used. Moreover, for MPPT operation, a novel LIC MPPT algorithm is used, which operates the boost converter. The RC filter and interfacing inductors are used for harmonics and switching ripples mitigation. A DSpace (Digital Signal Processor for Applied and Control Engineering) controller (1202-DSPACE) [32][33] is used for execution of control techniques. Hall-Effect current (LA-55p) and voltage (LV-25)

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sensors are used for sensing all signals. For voltage and current measurement, a multimeter (Fluke-115) is used. Power quality analyzers (Fluke-43B and Hioki-3100)[34] are used for analysis of different harmonic spectra. Differential voltage probe (HAMEG-115Hz) and current probe (Tektronix-A622) are used for voltage and current measurement. Digital Storage Oscilloscope (DSO7014A) is used for dynamic performance analysis.

The used system parameters are V_{oc}=400V, I_{sc}=14A, P_{load}=1.9kW, v_{sa}=180v, f=50Hz, L_{in}=5mH, C_{fl}=10μF, R_{fl}=10Ω, Ns=20000, €=40×ω_0, d_{base}=0.01, and θ=1.1. The upper and lower limits of hysteresis band controller, are +0.064 and -0.064. Sampling frequency is 40kHz and commutation frequency of the boost converter is 20kHz.

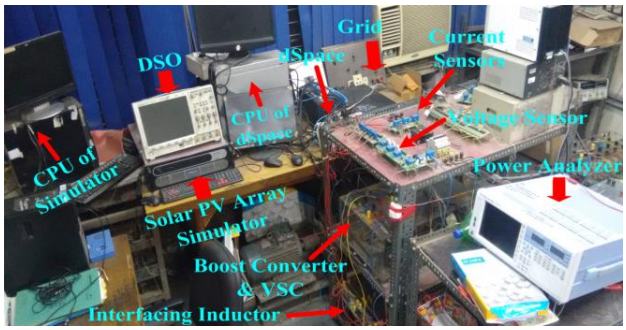


Fig.10 Photograph of developed prototype.

A. *Operation under Normal Condition*

For phase 'a', the steady-state responses of the system at solar irradiation 1000W/m^2, for nonlinear loads, are shown in Fig.11.

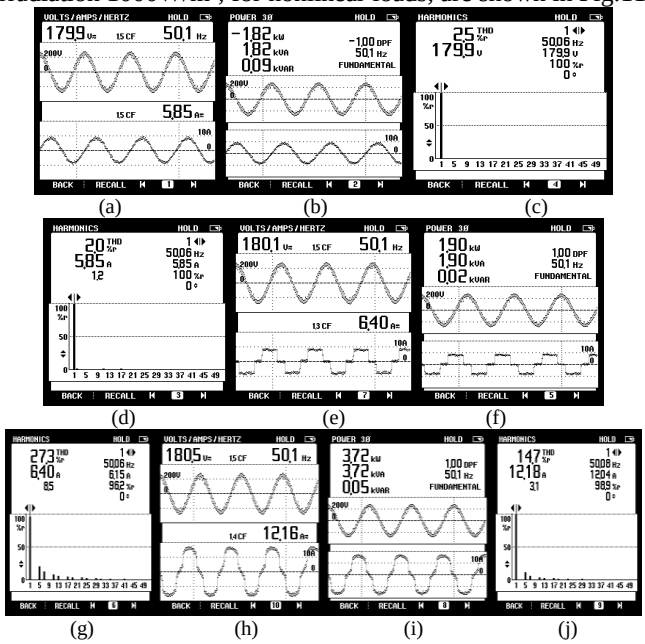


Fig.11 Waveforms of steady-state response for phase 'a' at solar irradiation 1000W/m^2, (a)-(d) grid voltage, grid current, grid power and harmonic spectra of v_{sa} and i_{ga}, (e)-(g) v_{La}, i_{La}, P_{La} and harmonic spectrum of i_{La}, and (h)-(j) v_{VSC}, i_{VSC}, P_{VSC}, and harmonic spectrum of i_{VSC}.

Figs.11(e)-(g) show that successfully power is supplied to nonlinear load, which THD is 27.3%. Moreover, Figs.11(a)-(d) show that after satisfying the load demand, rest 1.82kW power is supplied to the main grid, where THD of the grid current is 2.0%, which is found good within permissible limit of 5% according to the IEEE-519 standard. Figs.11(h)-(j) show the waveforms of VSC power flow, which is supplied by solar PV array and consumed by the load as well as the grid. The THD of VSC current is 14.7%. It shows that VSC supplies required harmonics at PCC to the nonlinear load. Therefore, the grid currents are found sinusoidal having THD within the limit.

Similarlly, for phase 'a', the steady-state responses of the system at solar insolation 800W/m^2, for nonlinear loads, are shown in Fig.12, where Figs.12(e)-(g) show that successfully, same amount of power is fed to nonlinear load, at 800W/m^2.

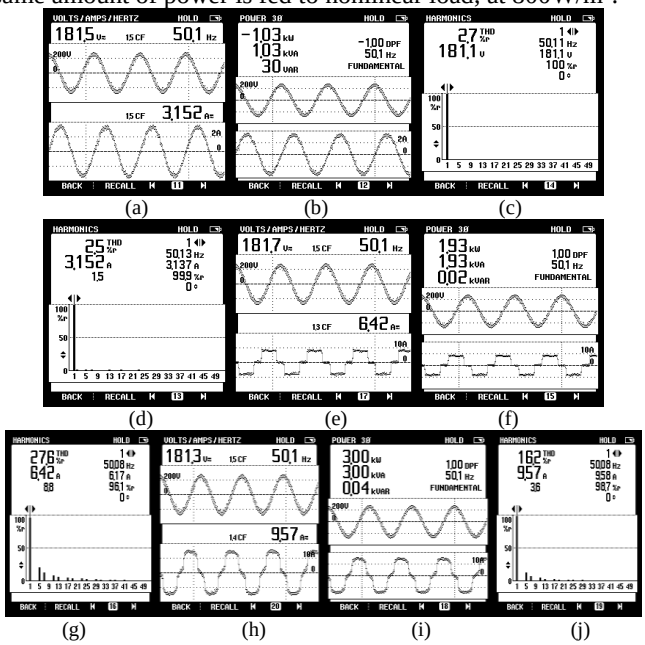


Fig.12 Waveforms of steady-state response for phase 'a' at solar irradiation 800W/m^2, (a)-(d) v_{sa}, i_{ga}, grid power and harmonic spectra of v_{sa} and i_{ga}, (e)-(g) v_{La}, i_{La}, P_{La} and harmonic spectrum of i_{La}, and (h)-(j) v_{VSC}, i_{VSC}, P_{VSC}, and harmonic spectrum of i_{VSC}.

Figs.12(a)-(d) show that after satisfying the load demand, rest 1.03kW power is supplied to the main grid, where THD of the grid current is 2.5%, which is found good within permissible limit of 5% according to the IEEE-519 standard. Moreover the VSC power 3.00kW shows that 20% reduction in solar PV power, which is due to the 20% solar irradiation reduction from 1000W/m^2 to 800W/m^2. Figs.12(h)-(j) show the waveforms of VSC power flow, which is supplied by solar PV array with the THD of VSC current of 16.2% for harmonics support for the nonlinear load.

B. *Operation under Nonlinear Load Unbalanced Condition*

During unbalanced nonlinear load condition, load of phase 'a' is removed, and its dynamic effects on phase 'a' and phase 'b' are shown in Fig.13(a), and Fig.13(b), respectively, as well as internal signals, are shown in Fig.13(c). Fig.13(a) shows that load of phase 'a' removed, so the load current becomes zero. However, due to proper control action, grid currents are balanced and sinusoidal, as well as DC link voltage is constant. Since, due to outage of phase 'a' load, the requirement of reactive power is reduced, so the shape of VSC current is improved and becomes sinusoidal, as well as nonlinearity of the phase 'b' load current is also reduced, which is shown in Fig.13(b). The performance of internal signals during dynamic condition is shown in Fig.13(c), which shows that the value of DC loss component (β_{DC}) is much less, due to balanced DC link voltage. Moreover, PV dynamic reflection component

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(I_{Dpv}) is constant, because solar irradiation is constant, and estimated active weight component (ξ_p) is reduced as the requirement of active power is reduced. Therefore, the resultant of all components (Φ_p), is also reduced.

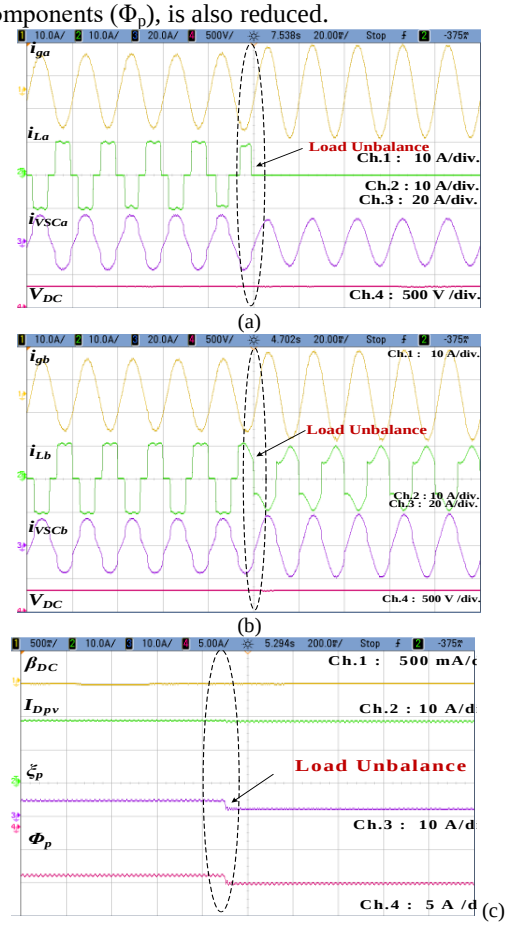


Fig.13 Waveforms during load unbalance, (a)-(b) i_{ga}, i_{La}, VSC current and DC link voltage of phase 'a' and 'b', (c) internal signals.

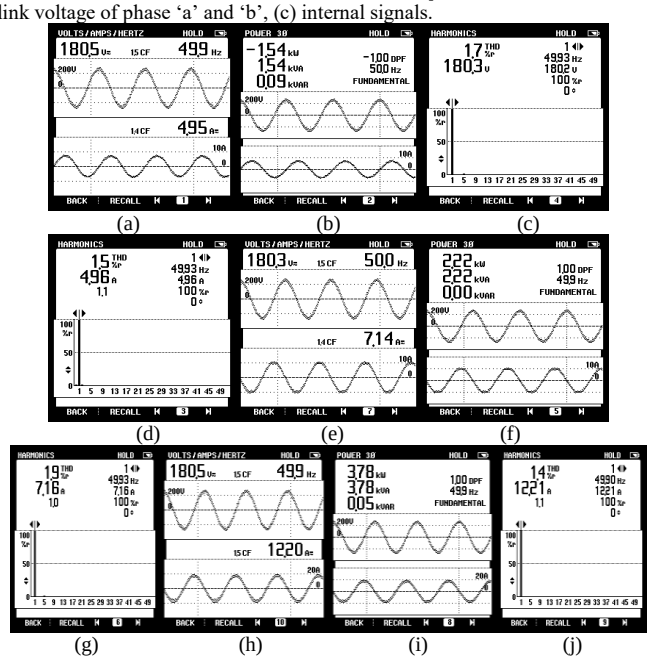


Fig.14 Waveforms of steady-state response for phase 'a', (a)-(d) v_{sa}, i_{ga}, grid power and harmonic spectra of v_{sa} and i_{ga}, (e)-(g) v_{La}, i_{La}, P_{La} and harmonic spectrum of i_{La}, and (h)-(j) v_{VSC}, i_{VSC}, P_{VSC}, and harmonic spectrum of i_{VSC}.

C. Operation under Linear Load Unbalanced Condition

For phase 'a', the steady-state responses of the system, for linear loads are shown in Fig.14, where Figs.14(e)-(g) show that 2.22kW power is supplied to linear load. Figs.14(a)-(d) show that after satisfying the load demand, the rest 1.54kW power is supplied to the grid, where THD of the grid current is 1.5%. Moreover, Figs.14(h)-(j) show the waveforms of VSC power flow, which is supplied by solar PV array and consumed by the load as well as grid. The THD of VSC current is 1.4%. It shows that due to linear load the requirement of harmonics at PCC is much less.

During unbalanced linear load condition, load of phase 'a' is removed, and its dynamic effects on phase 'a' are shown in Fig.15, which shows that when load of phase 'a' is removed, then load current becomes zero. However, due to proper control action, grid currents are balanced and sinusoidal, as well as DC link voltage is constant. Moreover, Fig.15 shows that after load removal, the grid current is increased. Because due to outage of phase 'a' load, the load demand is reduced, so the amount of excess power is increased, this is fed to the grid. However, in Fig.15, the VSC current is constant, because the generation from PV array is considered constant.

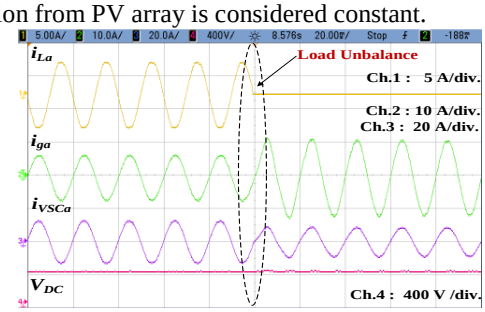


Fig.15 Waveforms during load unbalance.

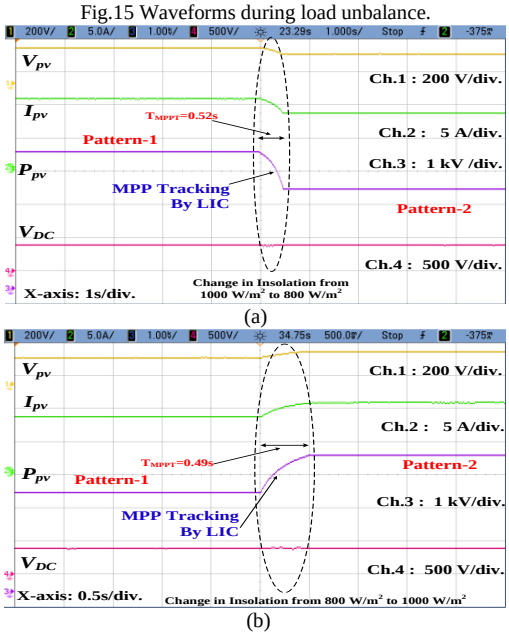


Fig.16 Waveforms during (a) insolation fall and (b) insolation rise.

D. Operation under Solar Insolation Change Condition

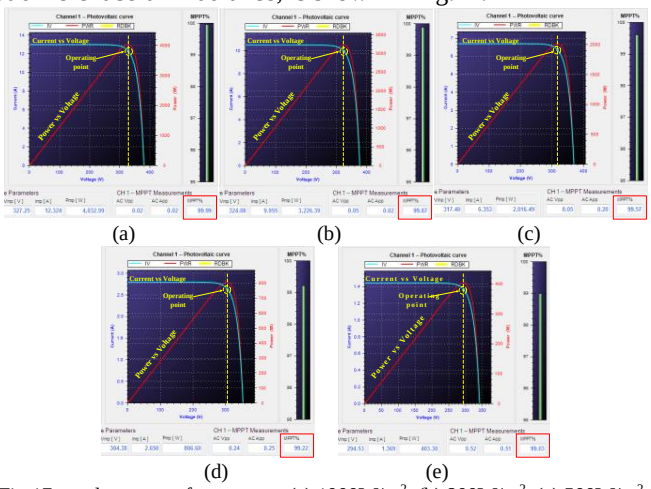
In insolation change situation, it is tested for insolation fall (from 1000W/m^2 to 800W/m^2), as well as tested for insolation rise (from 800W/m^2 to 1000W/m^2) condition. The steady-state as well as dynamic performances of both conditions, are shown in Fig.16, which shows a very smooth and quick MPPT

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performance. Those oscillations free and rapid tracking performances, are possible only due to the LIC algorithm.

The oscillation free performance in steady-state, is due to the learning based duty cycle reduction process of LIC algorithm. Moreover, after irradiation change, it has taken approximately 0.5s to track the MPP, which is due to the optimum rise in duty cycle in dynamic condition that shows the excellent dynamic performance of proposed MPPT technique. In both conditions, the tracking efficiency is approximately close to 100%, which shows the accuracy of the LIC algorithm. For detail analysis of tracking efficiency, the steady state response of LIC algorithm at different solar irradiance, is shown in Fig.17.

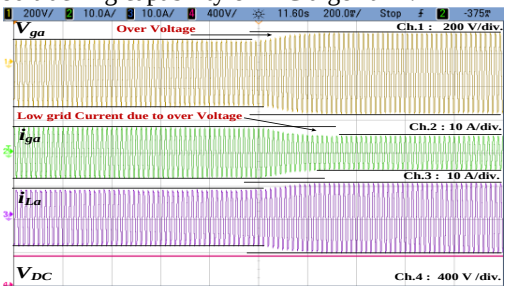


(a) (b) (c)

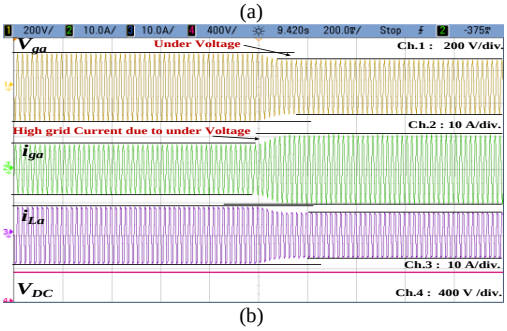
(d) (e)

Fig.17 steady state performance at (a) 1000W/m^2, (b) 800W/m^2, (c) 500W/m^2 , (d) 200W/m^2 and (e) 100W/m^2 .

Fig.17 shows that the achieved % MPPT, at 1000w/m^2, 800W/m^2, 500W/m^2, 200W/m^2 and 100W/m^2 are 99.99%, 99.87%, 99.57%, 99.22% and 99.03%. The efficiency variation shows that the achieved efficiencies are continuously decreasing with decrement of solar irradiation. However, the lowest MPPT efficiency is also more than 99%, which shows a very good tracking capability of LIC algorithm.



(a)

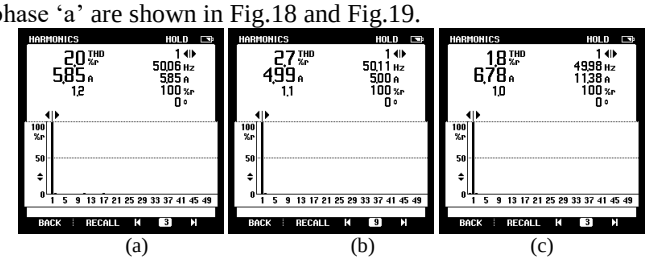


(b)

Fig.18 Waveforms (a) of over-voltage, and (b) of under-voltage condition.

E. Operation during Grid Voltage Fluctuations Condition

During testing for grid voltages fluctuation, over voltage and under voltage conditions are considered. In both conditions, fluctuation in grid voltage of approximately 12% is taken, which test responses and harmonics spectra of grid current of phase 'a' are shown in Fig.18 and Fig.19.



(a) (b) (c)

Fig.19 Waveform of harmonic spectrum of i_{ga}, during (a) normal condition, (b) over voltage and (c) under voltage condition.

The waveforms of overvoltage depict that, the v_{PCC} is increased, so due to constant supply power, the i_{ga} is decreased. Moreover, since P_L (load power) is directly propositional to the square of v_{PCC}, so P_L, as well as i_L, is increased. However, due to strong control ability, the V_{DC} is regulated to the desired value, and a balanced power is fed to the load, which is shown in Fig.18(a). Moreover, after fulfill the load demand, the extra power is supplied to the grid. During this process, the THD of i_{ga} is still low and within the permissible limit of 5% according to the IEEE-519 standard, which is shown in Fig.19(b). Similarly, during under-voltage condition, the power management and the THD of grid currents are good and within the permissible limit, which waveforms are shown in Fig.18(b) and Fig.19(c).

F. Operation during Grid Voltage Imbalance Condition

The dynamic behavior of the system under imbalance grid voltage condition is shown in Fig.20 and vector diagram of all components are shown in Fig.21.

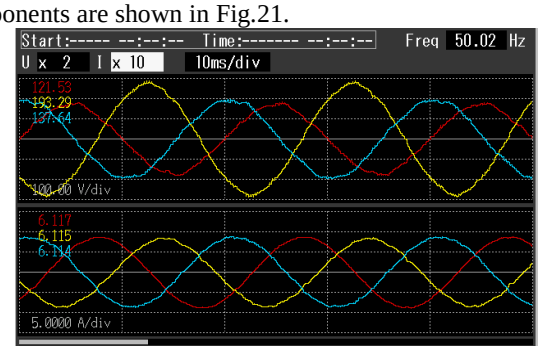


Fig.20 Waveforms of three-phase voltage and current during phase imbalance.

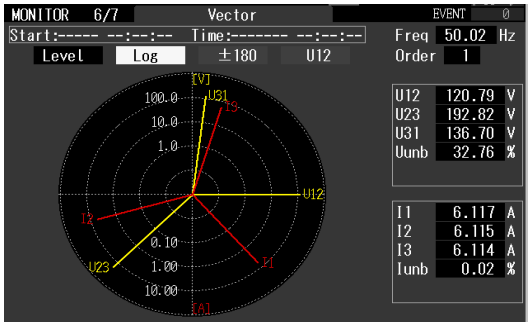


Fig.21 Vectors of three-phase voltage and current during phase imbalance.

From Fig.21, it is clearly visible that the three phase voltages are 120.79V, 192.82V and 136.70V, which is a highly

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imbalance condition. However, in this situation, the three phase currents are 6.117A, 6.115A, and 6.114A, which show balanced supply currents. Moreover, the THDs of all three phase grid currents are below 5%, which shows a satisfactory performance.

G. Operation during Distorted Grid Voltage Condition

The performances in distorted grid voltage condition for phase 'a', are shown in Fig.22, and analyzed by using power analyzer, which obtained waveforms, are shown in Fig.23.

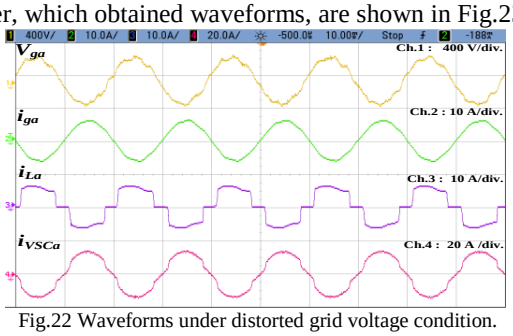
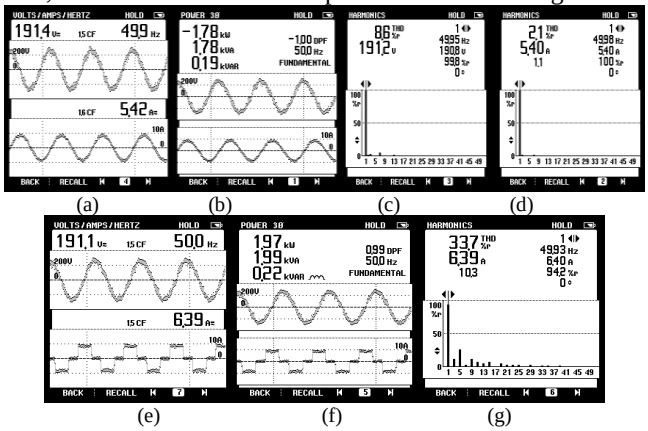


Fig.22 Waveforms under distorted grid voltage condition.

Here the THDs of distorted grid voltage and nonlinear load current for phase 'a', 8.6%, and 33.7% are considered, which are shown in Fig.23(c) and Fig.23(g), respectively. Moreover, for testing of proposed control technique in a highly complex situation, the overvoltage condition is applied with distorted grid voltage condition. Therefore, the considered amount of grid voltage during distorted grid voltage condition is 191V. In this highly nonlinear situation, the proposed control technique has performed very well and properly fed the load. After satisfying the load demand, the extra power is successfully transferred to the grid, where THD of grid current is only 2.1%, with unity power factor, which is shown in Fig.23(d). The waveform of v_{sa}, i_{ga}, i_{La} and i_{VSC} are shown in Fig.22. In Fig.22, the waveforms of v_{sa}, and i_{ga} are out of the phase from each other, which shows reveals that power is fed in to the grid.



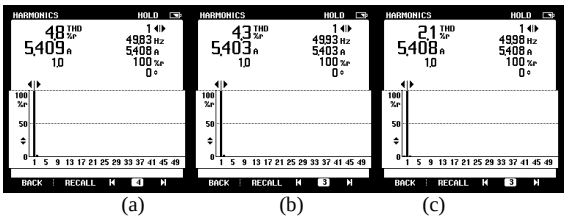
(a) (b) (c) (d)

(e) (f) (g)

Fig.23 Waveforms of, (a)-(d) v_{sa}, i_{ga}, grid power and harmonic spectra of v_{sa}, and i_{ga}, and (e)-(g) v_{La}, i_{La}, P_{La} and harmonic spectrum of i_{La}, under distorted grid voltage condition.

1) Comparative Analysis under Distorted Grid Voltage and Nonlinear Load Condition with State of Art Techniques

For comparative analysis, on the same circuitry condition, the most popular techniques, those are SOGI, KF and proposed NLKAKF techniques are tested. During testing, the nonlinear load is connected, at PCC and distorted grid voltage situation is taken. Here the objective of the controller is, first the load is fed, and after the load feeding, the rest power is supplied to the grid. In this situation, the obtained harmonic spectra of i_{ga}, by all techniques are shown in Fig.24.



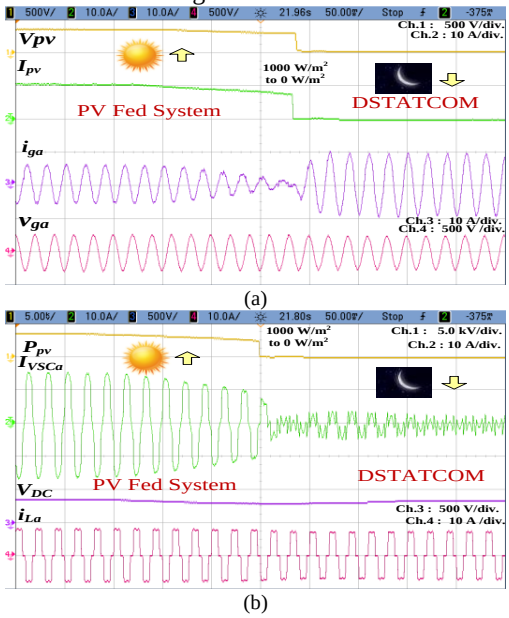
(a) (b) (c)

Fig.24 Harmonic spectrum of i_{ga}, using (a) SOGI, (b) KF, and (c) NLKAKF technique.

Fig.24 shows that the achieved THD of i_{ga} by using SOGI based control technique is very poor, that is 4.8%, which is shown in Fig.24(a). In the case of KF based control technique, the THD of i_{ga} is improved, that is 4.3%, which is shown in Fig.24(b). However, Fig.24(c) shows that the obtained THD of i_{ga} by using NLKAKF technique is only 2.1%, which depicts a significant difference, in comparison to state of art techniques.

H. Operation during Day-to-Night Mode

In day-to-night condition, during the daytime, solar PV power is used to fulfill the load demand, and if some power is left, then it is fed into the grid. Moreover, during the night time, when solar power is zero, then the load demand is fulfilled by taking power from the grid, and VSC acts as a DSTATCOM, which provides reactive power support. These all performances for day-to-night mode, are shown in Fig.25 and for night-to-day mode are shown in Figs.26.



(a)

(b)

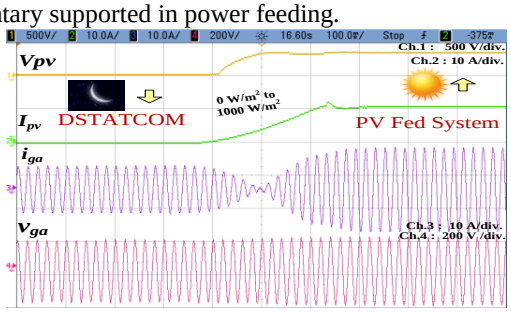
Fig.25 Waveforms of day-to-night mode, (a)-(c) PV voltage-current and grid voltage-current of phase 'a', (b)-(d) PV power, VSC current, V_{DC}, and load current of phase 'a' for day-to-night and night-to-day condition, respective.

In Fig.25(a) and Fig.26(a), during the daytime, i_{ga} and v_{sa} are out of phase, which shows that the power is fed into the grid. Moreover, during night time, i_{ga} and v_{sa} are in the same phase, which shows that power is supplied from the grid. The reactive power compensation behavior of VSC at the night time, is shown in Fig.25(b) and Fig.26(b), where it behaves like DSTATCOM. It increases the utility of the system. Moreover,

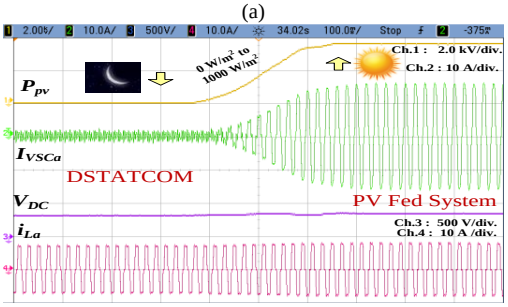
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in both conditions, the DC link voltage is maintained, which has only possible due to the strong controlling ability of the NLKAKF based VSC control and LIC MPPT algorithm. Moreover, Fig.25(b) and Fig.26(b) illustrate that the i_{La} is constant in every condition. Even in transient condition, i_{La} is constant, where DC link capacitor is discharged and momentary supported in power feeding.



(a)



(b)

Fig.26 Waveforms of day-to-night mode, (a)-(c) PV voltage-current and grid voltage-current of phase 'a', (b)-(d) PV power, VSC current, V_{DC}, and load current of phase 'a' for day-to-night and night-to-day condition, respective.

V. Conclusion

A novel Normalized Laplacian Kernel Adaptive Kalman Filter (NLKAKF) based control technique and Learning based Incremental Conductance (LIC) MPPT (Maximum Power Point Tracking) algorithm for grid-integrated solar photovoltaic (PV) system have been proposed. Here, a two-stage topology of three-phase grid integrated solar photovoltaic system has been implemented with the loads at PCC (Point of Common Coupling). The MPPT by LIC has been shown very good steady state as well as dynamic performance on different types of irradiation conditions. Moreover, NLKAKF control technique has successfully fulfilled the active power requirement of the loads from generated solar PV power, and excess power has been fed to the grid. However, when generated PV power is less than the required load power, then NLKAKF fulfills the load by taking extra required power from the grid. During this process, the power management and improvement in power quality have been successfully achieved. The controller action has provided reactive power compensation, power factor correction, harmonics filtering and mitigation of other power quality issues. Moreover, when the solar irradiation is zero, then DC link capacitor and VSC act as DSTATCOM (Distribution Static Compensator), which has enhanced the utilization factor of the system. The proposed techniques have been verified experimentally on a developed prototype, in solar insolation variation conditions, imbalance loading conditions for linear/nonlinear loads, as well as in different grid disturbances such as over-voltage, under-voltage, phase imbalance, harmonics distortion in grid voltage etc. Test results and overall performances have been successfully satisfied the objectives of the developed techniques and the IEEE-519 standard.

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Multimedia Tools and Applications
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Iris localization for direction and deformation independence based on polynomial curve fitting and singleton expansion

Rajiv Kapoor[1] · Rashmi Gupta[2] · Le Hoang Son[3] · Raghvendra Kumar[4]

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Abstract

In an authentic biometric system, iris recognition aims to detect the iris pattern of a person. The single unique pattern of the human iris may be extracted from the image and encoded, such that a given code may be compared to several others, and then validating if the patterns belong to a particular eye or not. Iris localization is an important aspect of iris recognition since accuracy in iris localization affects iris recognition. The previous iris localization methods were less efficient owing to slow processing time and inefficiency in handling non-straight faces in imperfect conditions. In this paper, we propose a new iris localization method with direction and deformation independence. It is based on the idea that the iris is localized from the side face and from distance. A novel approach of curve fitting using polynomial along with singleton expansion is adopted to efficiently and accurately localize the iris in any distance and direction from the camera. We validate the method by experimental analysis on the basis of accuracy, segmentation error and execution time. The method is suggested to be significant for diagnosing several eye-related disorders as well as for biometric authentication processes.

Keywords Canny edge detection · Gaussian smoothing · Iris localization · Polynomial curve fitting · Singleton expansion

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1 Introduction

The process of authentication is based on what an entity has (e.g. a credit card), what an entity knows (e.g. PIN - Personal Identification Number or password) and what an entity is (e.g. biological data). Biometric identification is a scientific authentication method that takes into account biological data like fingerprints, human gaits, DNA, facial characteristics [3] and retinal scan in order to authenticate an entity. Iris recognition is a biometric identification method that uses pattern recognition techniques to validate an individual based on pattern recognition techniques that have high resolution. Since the structure of iris remains stable throughout life, it is one of the strongest means of biometric identification. They are unique for every individual and are different for even twins. They have more than 250 degrees of freedom, hence the uniqueness. Iris recognition finds its use in several domains. It is durable, quantifiable, recordable and definitive.

In today's era, identity verification becomes very useful. However, the verification also requires a high-security level for personal data against unauthorized access. Though PIN is a widely used method for information security, it is also vunerable especially when using with any technology. In such cases, the biometric technique is a more reliable identification method based on advanced features. A trend is to introduce new authentication processes based on iris patterns. Iris recognition has been majorly accepted as the most reliable biometric technique to protect information. Some iris recognition systems have achieved good accuracy. Most of them used infrared cameras which increase the cost of system. There are many applications available using the human iris for system authentication such as the world first phone equipped with iris authentication ARROWSNXF-04G [2] and ForYourIrisOnly (FYIO) [13, 14].

The process of iris recognition involves several steps. Initially, detailed images of the eye are gathered using devices like a digital camera at visible wavelengths. This is the identification step (Nicole et al. 2018). A matching engine is then used to compare iris images with those stored in the database (Nicole et al. 2018). Iris recognition is also flexible and non-invasive in the sense that it is capable of being integrated into existing security systems that are non-contact and accurate. It is perfect for handling large databases without any degradation in authentication accuracy. Due to its unmatched speed and convenience, iris recognition is the newly adopted biometric identification technique in many industries, for example, finance and banking sectors. Authentication and authorization in the health and welfare industries are performed using iris recognition. Security concerns across the world have led to the use of this biometric even in cross border and immigration [4, 5, 12, 37, 38, 63].

In real systems, the conditions vary and iris is affected by various factors such as eyelashes, lighting condition, and iris deformations [48]. In [41], the authors stated that the iris localization can be achieved by combining the curve fitting and edge detector. The iris is an annular part between sclera and pupil. Researches in [6, 52] affirmed that iris boundaries are modeled as non-concentric circles. The traditional approaches used integral differential operators or Hough transforms to identify iris boundaries after edge detection in the localization [45]. However, since these approaches fail to handle non-straight faces in a highly controlled environment, an enormous search must be performed in the three-dimensional parameter space [20]. Thus, the existing methods are somewhat infeasible to be deployed in real-time iris recognition systems [33].

In this study, we introduce a novel approach to iris localization combined with direction and deformation independence. It is primarily based on the idea that iris is localized from the side face and from a distance [31]. The proposed method allows biometric identification for iris

recognition systems. It gives a new direction to the existing iris systems and is beneficial for surveillance, security, and financial applications.

Specifically, the proposed method works in several stages namely *binary edge generation, pupil detection*, and *iris detection stages.*

Binary edge generation is edge point's estimation, iris region segmentation and, polynomial curve fitting.

Pupil detection is based on image pre-processing which incorporates several techniques like gamma correction, image segmentation, Gaussian filtering, and morphological operations [44]. The achieved results are expected to show the exact pupil contours even in high severe deformations cases. The process of polynomial curve fitting [11] and extracting iris region from eye images are novelty of this technique. This means that after finding the most probable iris boundary points, the polynomial curve fitting will give a near-perfect iris boundary [59, 60]. This non-linear approach may be effective in excluding pixels, which are a part of obstruction causing elements like the eyelashes and camera lights [70].

Iris detection can be achieved using two arrays for storing the curve fitted iris boundary and the pupil boundary points Tan *et al*. [64] and [51]. Then, Singleton expansion is applied to these arrays for correctly capturing the area that lies between them. Thereafter, we apply a general iris recognition technique, the Daugman's Rubber Sheet model [69] to find the iris pattern which is then converted into the desired feature vector for iris detection. The iris detection stages are based on edge point estimation, polynomial curve fitting and iris region segmentation.

The advantage of the proposed algorithm lies in its speed and efficiency. Moreover, it is direction and deformation independent. The existing state-of-the-art scanned an iris image for a possible pupil center and detected the pupil using a pre-processing algorithm [50], thereby taking much processing time, and in some cases are incapable of detecting non-straight faces in imperfect conditions [76]. Hence, to efficiently and accurately localize the iris in any distance and direction from the camera, a novel approach of curve fitting using polynomial along with singleton expansion should be proposed.

Besides, the technique is unique and universal due to geometrically accurate results it produces. It has significant meaning in practical applications. Specifically, the pupil contour localization in the new method can assist the diagnosis of several disorders related to eyes like as Coloboma, which is a depression at the pupil edge. It can also detect other disease such as Leukocoria and Aniridia [1, 63]. The proposed algorithm can also be used in classifying pathological and normal iris.

Besides, efficiency in iris localization would also contribute to efficient iris recognition, hence strengthening biometrics authentication. Finally, the proposed algorithm is simple with new concepts and feasible, since it may be used and implemented easily. For the quantitative improvement, we consider three criteria namely segmentation error, execution time and accuracy where segmentation error causes programs to be crashed; thereby degrading the overall performance. Execution time is the time spent for executing a task, and accuracy deals with measuring the accurate values.

The rest part of this paper has been organized as follows. Section 2 reviews the related methods for iris localization along with a critical evaluation, which would strengthen our novel approach. Section 3 presents the new algorithm. Section 4 validates it on the benchmark databases. This section also highlights the experimental analysis and discussions using graphical representations. Section 5 highlights the conclusions and future work.

2 Related works

In this section, we briefly introduce the most typical works for Iris localization. Initially, we have analyzed the related works pertaining to the various methods proposed for iris localization. Since the scope of the problem is quite extensive, we have taken into account the works cited over the last decade. Subsequently, we have performed a critical evaluation of the methods proposed, so as to suggest a novel approach for Iris Localization.

Dey and Samanta [10] incorporated characteristics like thresholding, identifying pupil boundary points in order to study boundary detection and dilation, vertical edge detection and eliminating trivial edges in the images for boundary detection. The reason for adapting scaling as the method for iris localization is because it reduces the search space remarkably and image thresholding is simpler. The experimental analysis conducted reveal that 95%–99% accuracy may be obtained using the proposed method. The approach is found to be 75% faster than the existing approaches. They used several databases like UBIRIS, Bath, MMU, etc. Although the research has been carried successfully using experimental analysis, due to the involvement of preprocessing along with iris boundary detection and pupil boundary detection, the overhead may be slightly more.

Govindaraju *et al.* [19] suggested a robust method for iris localization that involved the Active Contour Model and Hough Transform. The segmentation proposed algorithm is based on iris segmentation, noise removal, and eye localization. Hundred images from the CASIA iris image database were taken to perform experimental analysis. The research analysis was compared to Daugman's [9] algorithm in which the proposed algorithm achieves an accuracy of 99% in comparison to Daugman's 96%. The limitation of the proposed research work lies in the small range of images used for the experimentation. A significantly larger number of images would strengthen their approach. Also, the researchers focus on a single database. The use of multiple databases would have justified the robustness of their research work. Lastly, the comparison was performed against a single algorithm. The researchers did not take into account several factors like the number of iterations for the evolving contour, the threshold for binarization and blurring parameters which may ultimately affect iris segmentation.

Poornima *et al.* [47] compared some existing iris localization methods in order to introduce the concept of neural networks for iris localization. The localization algorithms considered in that research are Integral-differential operator, Canny edge transform and Hough transform. The network model chosen for the proposed neural network approach for iris localization is Feedforward Back-propagation. For experimental analysis, images from the CASIA iris database were scanned. Although the researchers have been successful in practically implementing the proposed technique, the research has a few limitations. The network has been trained using only eighty-seven images. Neural Networks must be trained on large datasets. Training time would be significantly higher. Moreover, it is difficult to interpret parameters and sometimes the missing parameters cause the considerable error. Moreover, the study shows that the iris localization algorithm based on the integral-differential operator is prone to bright spots, which needs attention.

Sundaram *et al.* [61] presented a simple and fast method for iris localization using two steps: edge point's detection and circular the Hough transform. Based on the proposed approach, the researchers carried out experimental analysis considering over a thousand iris images which are a part of the UBIRIS database. The proposed method was compared to Wildes et al. [75] method based on Hough transform. As per the experimental analysis, the

suggested method is incapable of iris localization in several situations when the image quality is poor, closed or almost closed eyes and in situations with boundaries cannot be localized.

Wei et al. [74] proposed a novel technique of iris localization based on an improved least squares fitting algorithm. The canny edge detector was used to detect iris image boundary to find a perfect threshold to binaries an image. The least squares fitting algorithm has been used to locate the inner boundary and make up circular arc segment of the outer boundary. Experimental analysis using 150 images of the CASIA iris image database was conducted. The proposed method has been proved to be fast, accurate and computationally efficient. Although experimental results vouch for the proposed research work, the narrow range of images makes the research quite weak. Also, the use of multiple public database images could have strengthened the research. Moreover, the concept of least squares fitting has its own limitations. It is rigid and complicated and may not be appropriate for too much or too fewer data.

Liu et al. [41] proposed a new approach for recognition of complex activities by having two components: temporal pattern mining and the adaptive Multi-Task Learning. Soliman *et al.* [53] presented a coarse-to-fine algorithm for efficient iris location owing to the time consumption of the previously proposed techniques. The idea is to transform the iris grey image to a binary image using an adaptive threshold which is obtained from examining the image intensity histogram. An initial center point for both pupil and iris boundaries are extracted using morphological processing. The research relies on the integral differential operator to find the center and radius of the pupil and iris. The algorithm has two stages: the course stage and the fine stage. Around 1800 images from the CASIA3 iris image database have been used to perform the experimental analysis. As per the experimental analysis, several images have pupil boundary errors due to specular reflections and obstructions. There are also cases of false acceptances and false rejections for the suggested technique.

Galdia et al. [18] discussed the sensor interoperability problem and presented an advanced approach that combines users' devices and iris. They have also tested the present research on MICHE. Frucci et al. [15] proposed an advanced iris recognition system called as Watershed transform, which is helpful for noisy images captured in the visible wavelengths. Two known databases (subset of UBIRIS version 2 and UBIRIS version 1 session 2) were used for comparative analysis. Liu et al. [42] proposed an algorithm for temporal patterns identification and used the identified pattern for activities representation.

Kaur and Sohal [36] proposed a hybrid algorithm incorporating Circular Hough Transform, Fuzzy Clustering Method and Canny Edge Detector for iris localization. The image was firstly clustered using the Fuzzy Clustering to choose the cluster having maximum intensity. Circular Hough Transform is then applied to obtain the rough iris circle, cropping a window around the circle. Canny Edge Detector is then applied to this window and the Circular Hough Transform is implemented to obtain the accurate iris region. The researchers have calculated accuracy, sensitivity and specificity to deduce the strength of the proposed algorithm, although several other factors could have contributed to the same. The dataset is too small incorporating the data of only eight persons. Further, the overall accuracy achieved is 98.4%. Experiments manifest that few results have been wrongly matched thereby making the proposed technique slightly inaccurate.

Gaikwad et al. [16] introduced a biometric driven Personal Identification Framework. This model is based on Palm-print and Fingerprint biometrics for authentication and verification. The proposed method eliminates textures, lines and appearance highlights from palm prints. A wavelet-based combination system incorporating wavelet augmentations and mean-max combination method has been taken into account to address highlight combination issue. Experimental results showed the accuracy of 98.82% for the proposed biometric system. Although

the palm-print contains more information than the fingerprint, the only drawback this method is the processing time. Nalla and Kumar [45] suggested an accurate iris recognition technique based on cross spectral matching. Using Markov random field models, they introduced an algorithm in order to enhance the cross-domain iris recognition. The framework is based on Naive Bayes nearest neighbor classification and has taken into account real-valued feature representations. Experiments have shown that the proposed bi-spectral iris recognition system is capable of acquiring visible and near-infrared images. The experimental analysis has been performed on available databases like the PolyU cross-spectral iris image database, UND database and IIITD CLI. The drawback of the proposed technique lies in the fact that it may be difficult to interpret due to the involvement of the Markov random field model. Further, additional approximation techniques may be required. The Naive Bayes nearest neighbor classification is less accurate compared to several other classifiers.

Wang et al. [73] proposed an optimization model for efficient iris localization. The research uses SIFT (Scale-invariant feature transform) to represent the characteristic information about the outer boundary of the iris and the eyelid for localization. A Supervised Descent Method algorithm has been suggested to identify the eyelid and boundary points. The iterative Reweighted Least-Square method has been relied upon to find parameters of the outer boundary as well as upper and lower eyelids. For experimental analysis, an image database has been constituted with 700 images. Experimental results showed that the run time of the proposed method is much more efficient than compared algorithms. However, the research has its own limitations. SIFT is not only mathematically complicated but also computationally heavy. Since it is based on a histogram of gradients, pixels must be computed which takes time. Thus, it is inefficient for low powered devices.

Dagnes et al. [8] orchestrated a literature survey on recent Occlusion detection and restoration techniques. The research was carried out for 3D face recognition keeping in mind the fact that criminals take advantage of occluding their faces with glasses, facial hair, scarves etc. so as to bypass security systems. The research lists out experiments and databases considered in past to address the issue of occlusion. The techniques have been eventually compared. The limitation of the research lies in the fact that the study only compares the existing works and the outcomes do not introduce anything novel. Vezzetti *et al.* [72] proposed an automatic technique to localize facial landmarks based on geometrical features of the 3D facial surface. The study analyzed faces in presence of emotions as well as occlusions. Geometrical studies pertaining to the coefficients of Gaussian, mean, shape index, curvature, etc. were considered to localize landmarks near ears and nose areas. The behavior of each geometric descriptor has been taken into account. A detection algorithm has been executed in order to manage occlusions, succeeded by landmark localization. Several images have been considered for experimental analysis. The proposed technique is somewhat feasible, although there still exists certain mean localization errors. Zhang et al. [77] improved the performance of mobile identification by a new fusion network that exploits the data presented in periocular regions and iris. In this method, the maxout unit was applied to the convolutional neural networks.

We have already analyzed some of the previous works on iris localization along with the proposed techniques as well as the limitations these techniques have. As observed, there are several ways to ensure iris localization. Gaining motivation from the related work, we have proposed a novel method for iris localization in this paper. Others can be retrieved in [8, 16, 21, 22, 34, 35, 39, 40, 71]. The following Table 1 represents the summarized critical evaluation of the related works.

3 Proposed method

In the previous section, we have taken a look at the previous methods for iris localization. We are also aware of the issues of the previous methods. One of the important issues to consider for proposing the new method is the slow processing time taken by the other algorithms. Another issue is the various angles considered for face direction which leads to poor results. Our proposed work will address the issues of slow processing time and different angles for face direction by using the Polynomial Curve Fitting and Singleton Expansion.

Daugman's Integral Differential Operator [69] is a principal method for automated iris recognition wherein a point is taken to radically move outwards, maximizing the radius and circularly integrating the edge pixels to detect two concentric circles in the image [27]. The

Table 1 Summarized Critical Evaluation of Related works

No.	Authors	Descriptions	Limitations
1.	Poornima *et al.* [47]	introduced the concept of neural networks for iris localization	Very few images, training time significantly high, difficult to interpret parameters, an algorithm based on the integral-differential operator is prone to bright spots
2.	Sundaram *et al.* [61]	method for iris localization using two steps: edge points detection and circular Hough transform	Method suggested is incapable of iris localization in several situations like when the image quality is poor, closed or almost closed eyes and in situations where boundaries cannot be localized
3.	Wei *et al.* [74]	improved least squares fitting algorithm for iris localization	Narrow range of images, least squares fitting method is rigid and complicated and may not be appropriate for too much or too less data.
4.	Soliman *et al.* [53]	Coarse-to-fine algorithm for efficient iris location	Several images have pupil boundary errors due to specular reflections and obstructions, false acceptances and false rejections.
5.	Kaur and Sohal [36]	Hybrid algorithm incorporating Circular Hough Transform, Fuzzy Clustering Method and Canny Edge Detector for iris localization	Dataset is too small, wrongly matched results leading to inaccuracy
6.	Gaikwad *et al.* [16]	Biometric driven Personal Identification Framework	More processing time
7.	Nalla *et al.* (2017)	Accurate iris recognition technique based on cross spectral matching	Difficult to interpret due to the involvement of Markov random field's model. Additional approximation techniques may be required. The Naive Bayes nearest neighbor classification is less accurate.
8.	Wang *et al.* [73]	optimization model for efficient iris localization using SIFT	SIFT is mathematically complicated and computationally heavy, inefficient for the low powered device
9.	Dagnes *et al.* [8]	Survey on occlusion detection and restoration techniques.	The study only compares the existing work, and based on the outcomes does not introduce anything novel
10.	Vezzetti *et al.* [72]	Automatic technique to localize facial landmarks based on geometrical features of 3D facial surface	Experiments show that certain mean localization error exists.



Fig. 1 Closed boundary pupil binarized images (Deformed and Normal)

objective is to calculate the circular contour which is at the margin of higher change in intensity of pixels. It can be observed by changing the center of the circle and radius. The integral differential operator is given as:

$$max_{(r,x_0,y_0)}\left|\frac{\partial}{\partial r}G_\sigma(r)*\int_{r,x_0,y_0}\frac{I(x,y)}{2\pi r}ds\right|, \tag{1}$$

where the intensity of (x, y) pixel is $I(x, y)$ for image I, $G_\sigma(r)$, and it is a two-dimensional gaussian filter having specified radius and variance. A lot of computational time is consumed by the Daugman's operator in the observation of iris center.

In [75], a binary edge map develops the image of eye by derivative of pixel intensities. By using the voting system, the detection of circular edge point is done. For the circular boundary having the points set (x_j, y_j) lying on it, the Hough Transform is given as,

$$H(x_c, y_c, r) = \sum_{j=1}^{n} h\left(x_j, y_j, x_c, y_c, r\right) \tag{2}$$

The drawback posed by this technique lies in intensity holding to detect circles due to which many edge points are left out and misdetections may take place. Since eyes are a unique feature for authentication of a person, we can use multi-biometric system for better security [28–30]. To improve the overall security, proper implementation and design of the biometric system is required [17]. In the previous works, it is evident that

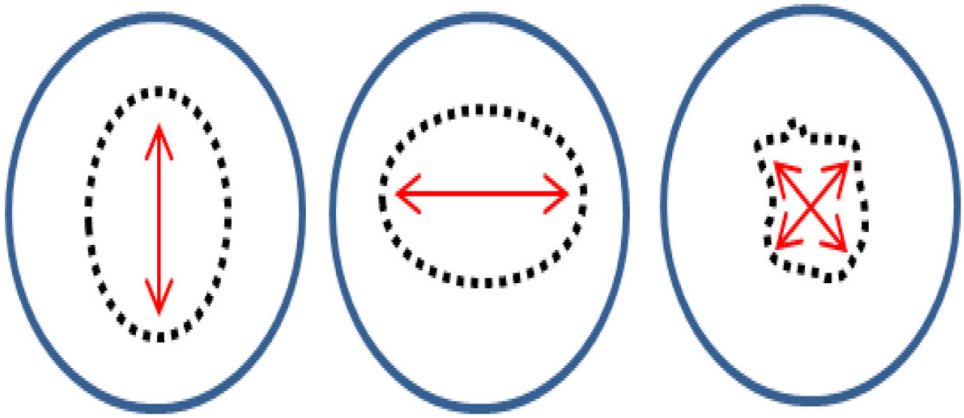


Fig. 2 Pupil Deformations (expansions and contractions)

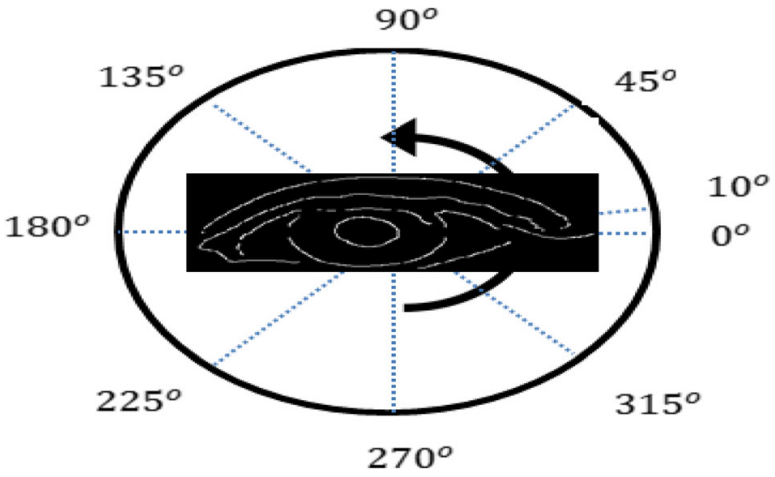


Fig. 3 The rotation of image by every 10 degrees for finding a point

a good quality input image with the eye ball in the center was needed. Our method does not require such kinds of requirement so that it can also applied to a real time basis by scanning the iris from a long distance. The proposed scheme is also suitable for the iris recognition systems using hidden-cameras.

Specifically, the new algorithm uses the Near Infrared (NTR) camera for acquiring the images as well as online data likes CASIA [7]. The pre-processing involves the pupil darkening to make it occlusion-free. This is achieved by complementing the image so that abnormally bright spots may be exposed, which are then classified as the high valued pixels surrounded by less valued pixels. A flood fill operation may be used to fill these spots with the surrounding intensities.

In the second step, to remove any pre-dominant occlusion spots, we apply the Gaussian filter. This operation is performed by using the singleton expansion method during iris extraction stage. The aim is to blur the image along with its edges. The Gaussian function is defined as,

$$g(x,y) = \frac{1}{2\pi\sigma^2} exp\left(-\frac{x^2+y^2}{2\sigma^2}\right) \tag{3}$$

We define the details of the proposed method in the subsequent subsections.

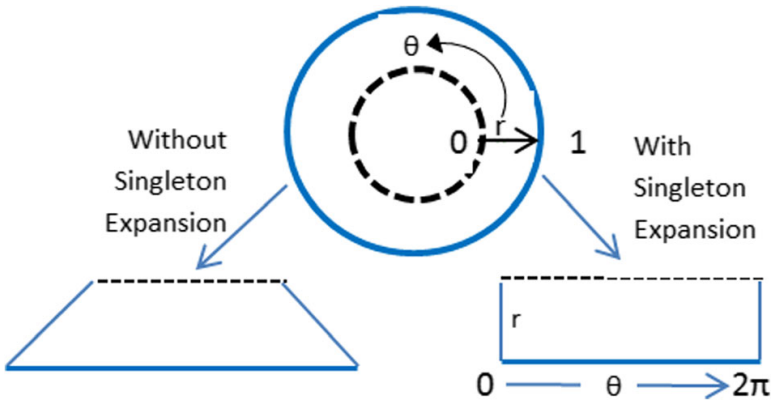


Fig. 4 Accurate Daugman's Rubber Sheet Model using Singleton Expansion to reduce iris information sampling loss

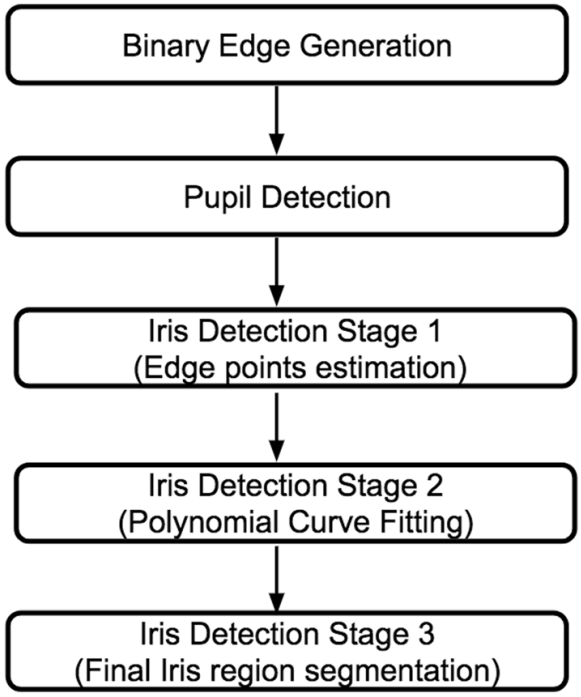


Fig. 5 The proposed approach incorporates the represented stages

3.1 Generation of binary edge

The Canny Edge Detection can provide an accurate boundary for the darkened pupil with negligible noisy spots. In few cases, the component of boundary may be still detached. Thus, the morphological close operation can be used to observe a structuring element, which makes a comparison between noisy pixels and neighboring ones to calculate the accurate value.

Essentially, to fill gaps in the boundaries, it performs dilation followed by erosion [24]. The resulting binarized image contains boundaries which are valued as one (rest all values are zeros) as indicated in Fig. 1.

3.2 Detection of pupil

This progression includes discovering components that have much-closed boundary [49]. This progression is incredibly significant since it guarantees that pupil has shut closed boundary. To



Fig. 6 Iris detection sample test cases in any direction

Table 2 Standard datasets and their statistics

Dataset	UB-IRIS	CASIA
Total Subjects	240	824
Total Images	1871	16,313
Sensor	Nikon E5700 Camera	IRISPASS-h Iris Lamp
Image Mask	Yes	No
Subject origin	Caucasian	Asian
Resolution	400 × 300	640 × 480
Image format	Jpg & tiff	Jpg

do as such, a basic logic was utilized as in the event that a figure is closed, there must be something like two components in the case of a binary image in a single column. At the beginning stages (extreme left and right), a component can be exhibited as far as a perfectly circular pupil. This special case is taken care by approving a similar condition of no less than two components for each column on the column perfectly to the extreme left point and simply left to the extreme right point. Then, a threshold is connected to evacuate the specular noise with boundaries lying outside of the pupil. The outputs are these points of boundaries whose centers are considered as the contour center- $C = (x_c, y_c)$.

$$C = \frac{1}{n}\sum_{i=1}^{n} B_i, \tag{4}$$

where B_i represents the detected edge points of the papillary boundary indicated in Fig. 2. Such steps in pupil localization may be used in the detection of paralytic stages of the optical nerve as well as for the temporal lobe of the brain which controls vision [31].

3.3 Detection of iris: stage 1

Since limbic boundary is always outside the pupillary boundary, radically outward motion is performed from the pupil center until it reaches the second binary iris point. Initially, the method finds the first iris point, and then rotates the image by 10 degree, the same process is repeated for finding probable iris points until the full 360-degree rotation completes by taking the rotation center fixed at the center of pupil. At the end of this step, for representing the most probable iris boundary points, a 36-point vector are formed, which include eyelashes as well as eyelid points. Since most of these points belong to the iris edge, the curve fitting function covers the entire iris boundary region when it is performed on these points. The novelty of this step lies in the fact, which as a result, not only most of the identified points fall as iris boundary

Table 3 Confusion Matrix along with accuracy for UBIRIS

Classes	A	B	C	Producer Accuracy (Precision)
A	97	1	2	97%
B	0	98	2	98%
C	0	2	98	98%
User Accuracy (Recall)	100%	97.03%	96.078%	

*A-setosa, B- versicolor, C- virginica

Table 4 Confusion Matrix for CASIA

Classes	A	B	C	D	E	F	Producer Accuracy (Precision)
A	78	11	4	7	0	0	78%
B	14	77	3	4	1	2	76.238%
C	1	9	76	3	7	4	76%
D	2	1	3	75	9	6	78.125%
E	5	2	4	6	78	1	81.25%
F	3	2	1	8	7	79	79%
User Accuracy (Recall)	75.728%	75.49%	83.516%	72.816%	76.471%	85.87%	

*A-Angry, B-Disgust, C-Fear, D-Happy, E-Sad, F-Surprise

points, but also the eyelash points acting as occlusions get eliminated during the polynomial curve fitting. Figure 3 illustrates this stage.

3.4 Detection of iris: stage 2

Curve fitting finds the best-fit polynomial for covering most of the given data points [32]. The Least Squares technique has been considered to fit the curve representing to the iris boundary as it limits the square of the error between the given information and qualities gotten by the derived equation. Outliers produced are taken care of by singleton expansion. The arrangement of boundary points (x,y) fulfills the second-degree polynomial condition:

$$ax^2 + bxy + cy^2 + dx + ey + f = 0. \tag{5}$$

This equation forms an elliptical conic if

$$D_A(v1) = \sum_{i=1}^{n} F(v2_i)^2 \rightarrow min, \tag{6}$$

where $v_1 = [a\ b\ c\ d\ e\ f]$ is the coefficient vector, representing to the polynomial, and $v_2 = [x^2\ xy\ y^2\ x\ y\ 1]$ is the vector putting away iris data points. Numerically, k^{th} order polynomial coefficients of regression model are calculated by using set of linear equations given below, it is also known as

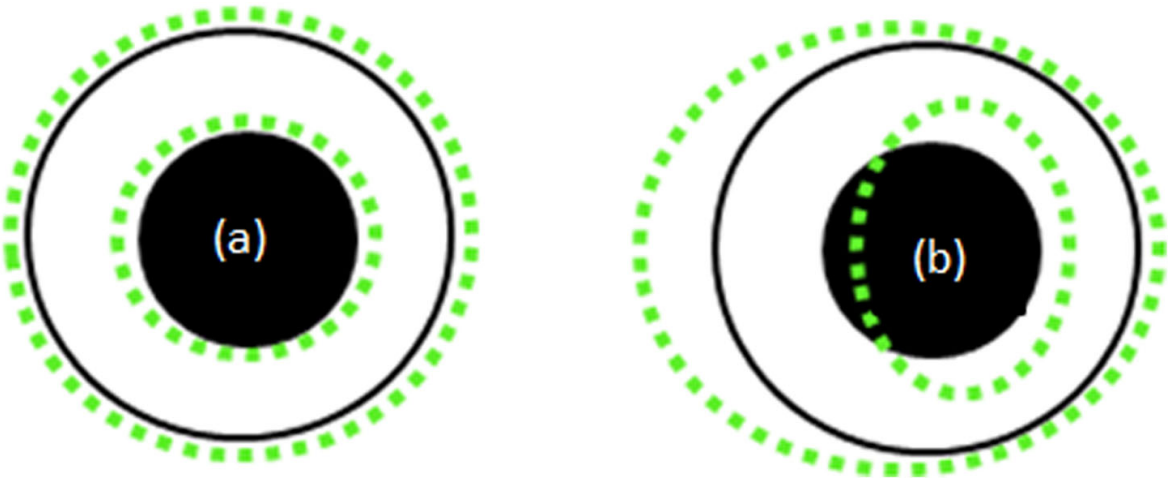


Fig. 7 Visually analyzing segmentation categories **a** Good, **b** Bad

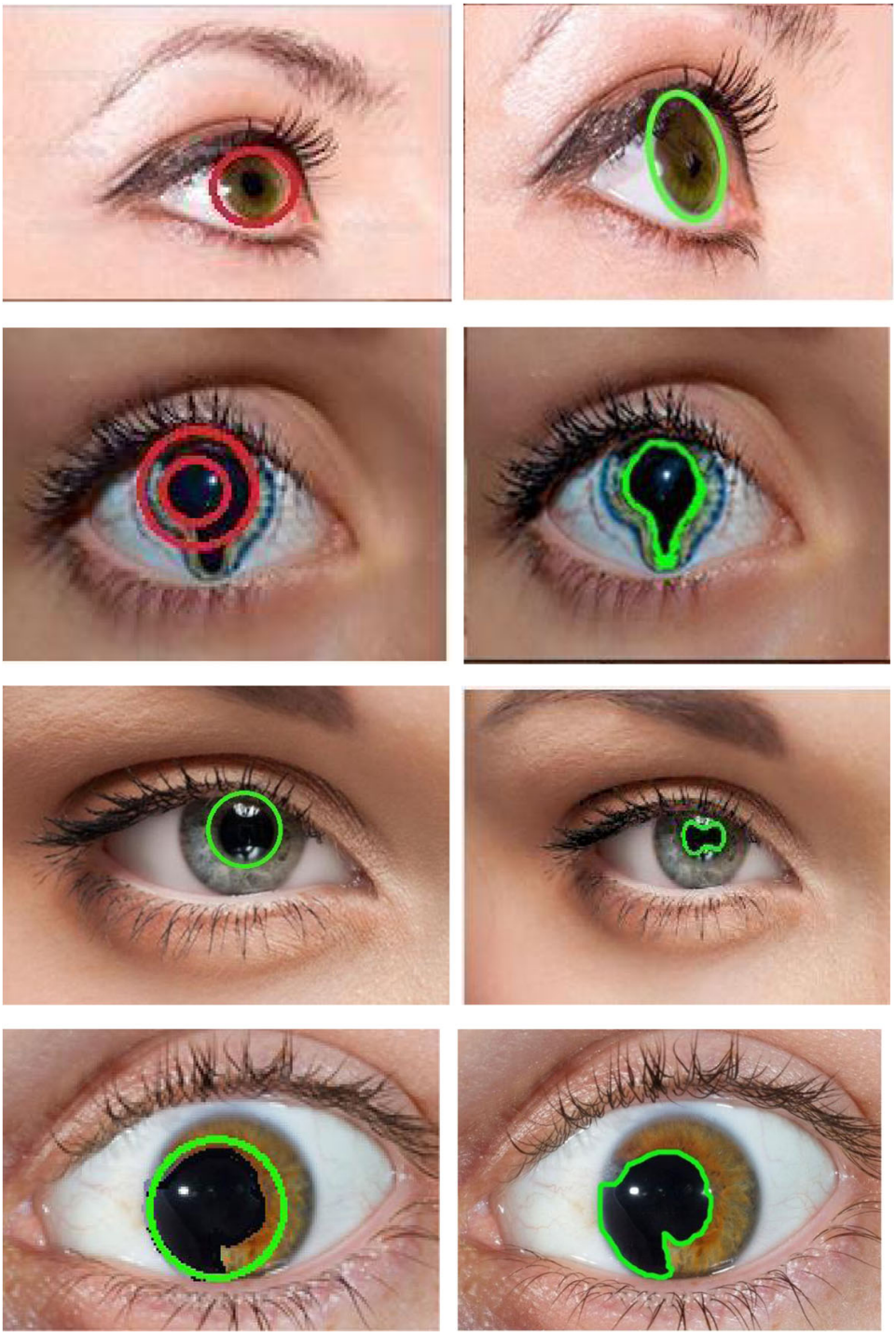


Fig. 8 The output results comparison for the proposed algorithm (right) and the Daugman algorithm [69] (left)

Vander monde matrix, and in geometric progression in $_{(}V_N)$ it has all the non-zero terms.

$$\begin{bmatrix} N & \sum_{i=1}^{N} x_i & \cdots & \sum_{i=1}^{N} x_i^k \\ \sum_{i=1}^{N} x_i & \sum_{i=1}^{N} x_i^2 & \cdots & \sum_{i=1}^{N} x_i^{k+1} \\ \vdots & \vdots & \vdots & \vdots \\ \sum_{i=1}^{N} x_i^k & \sum_{i=1}^{N} x_i^{k+1} & \cdots & \sum_{i=1}^{N} x_i^{2k} \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_k \end{bmatrix} = \begin{bmatrix} \sum_{i=1}^{N} y_i \\ \sum_{i=1}^{N} x_i y_i \\ \vdots \\ \sum_{i=1}^{N} x_i^k y_i \end{bmatrix} \quad (7).$$

It can be shown that $V_N \neq 0$ i.e., the matrix is nonsingular if the non-diagonal elements are not equal. Hence, a unique solution exists that satisfies the interpolation requirements of the desired polynomial curve. We can also use the higher order polynomial for irregularities representation in iris edges, but only pupil deformations

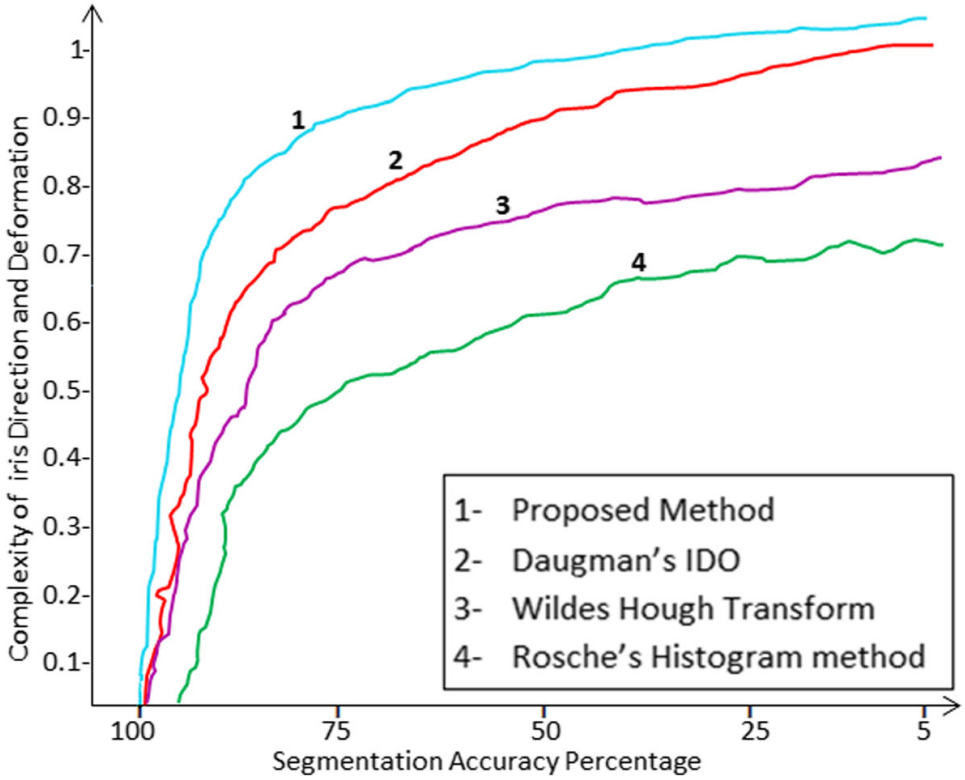


Fig. 9 Illustration of ROC Curve for different methods

are known in general cases. Iris boundary deformation case is not available there so that the second-order polynomial is preferred in order to reduce the complexity and computation time of the algorithm. The parts of eyelashes and eyelids are enclosed in the output curve but in array which kept these edge points, the output curve is a close figure. Since only the second most bit from pupil center is treated as iris boundary points, these factors are not stored.

3.5 Detection of iris: stage 3

After deriving both the pupillary and limbic boundaries, the iris region cannot be extracted by simply subtracting two regions but by applying the singleton expansion



Fig. 10 Segmentation Errors

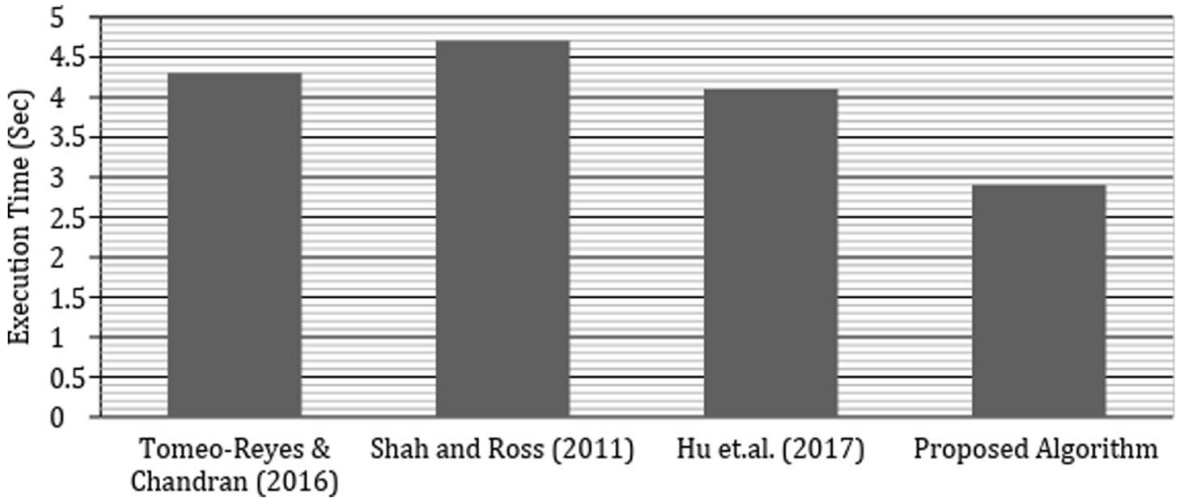


Fig. 11 Execution Time (Sec)

on the two boundaries in order to capture the intermediate area between two arrays [25]. We propose the use of singleton expansion to adjust the length and shape of a pupillary boundary to match with limbic boundary. This is done so that texture information of the iris does not get tampered during the rubber sheet modeling of the iris for feature extraction wherein the circular shape of the iris is stretched and re-molded in a form of a rectangle. The circumference of the pupillary boundary is certainly less than the limbic boundary. Therefore, performing the singleton expansion at specific intervals creates equal length pupillary and limbic boundaries. Element-wise binary operation is performed on vectors A and B where A stores the limbic boundary points and B stores the pupillary boundary points. The predefined expansion function used is $f(a, b) = a - e^b$ as indicated in Fig. 4.

Thus, we have introduced an approach for iris localization, which incorporates several steps. Figure 5 is a representation of the steps involved.

4 Experimental analysis

Environments Performance evaluation has been conducted by implementing the proposed algorithm and those of Shah and Ross [51], Tomeo-Reyes and Chandran [69], Hu *et al.*

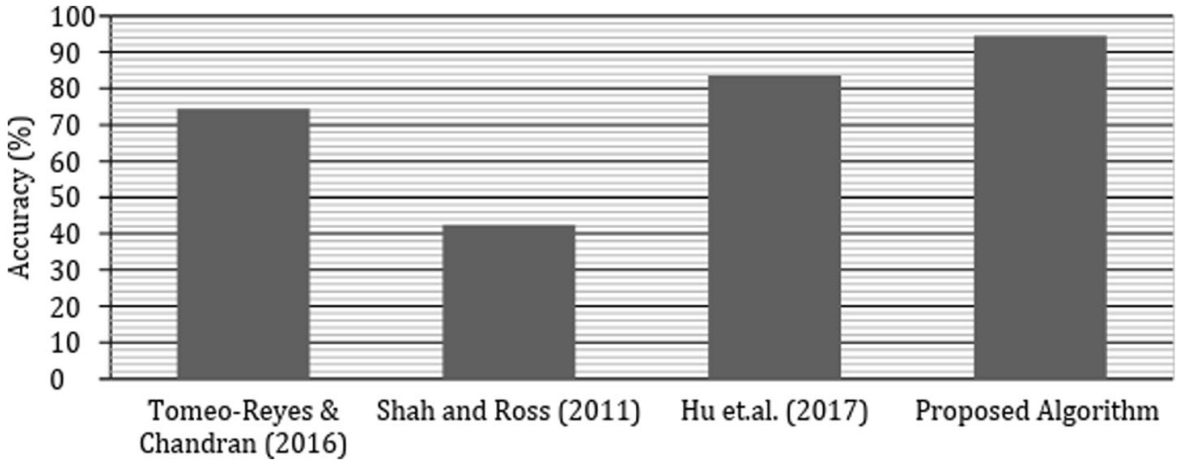


Fig. 12 Accuracy (%)

[30] in MATLAB 2015a on a computer having configurations: 64-bit Windows operating system, Intel-based 2.00 GHz Core i3 Processor with 4 GB RAM. Parameters of the algorithms are set as in the original papers. The compared algorithms were chosen because of working in the same ideas and baselines with the proposed one from edge detection and iris detection stages.

Datasets We apply the proposed method to two different types of datasets taken from the UB-IRIS database [40], and CASIA [7]. Comprises eye view is the first type of dataset taken from a different camera positions, different eyeball positions and different angle (Fig. 6). Comprises of deformed pupils and iris is the second type of dataset. The datasets properties and statistics used for the testing are discussed in Table 2. For each iris image, iris segmentation database contains a mask in form of a method to extract the mask and parameters. The iris databases are divided into two main segments by considering shapes CC[1] and EP.[2]

The CC dataset can be partitioned into different iris image datasets: BioSec Baseline database,[3] MobBIO Database,[4] and CASIA Iris Image Database.[5] In order to facilitate the conformity level estimation of the ground truth generated by different operators, the CASIA was segmented by two independent operators. The database of iris segmentation is provided without the databases of the original eye image. In the databases description, a link is included to the actual iris database [26]. Tables 3 and 4 indicate the confusion matrix for both the database. Included in the tables are Producer Accuracy (Precision) and User Accuracy (Recall). The overall accuracy has also been mentioned for both the databases. Precision defines the positive identification proportion that was actually correct whereas recall, also known as sensitivity defines the actual positives proportion that was identified correctly.

The overall accuracy for IRIS is estimated to be 97.667%.

The overall accuracy for CASIA is estimated to be 78.078%.

Evaluation criteria The following criteria have been considered for evaluating the results: Segmentation error, Receiver Operating Characteristic (ROC) curve, Execution time, Accuracy, and Visual observation. Visual Observation may be categorized as ‘Good’ or ‘Bad’ such that ‘Good’ refers to the final demarcated iris having contour exactly as the original image and ‘Bad’ refers to the ground truth that iris has pixels lying outside or inside of the final demarcated iris. The categories are represented in Fig. 7.

The measurement of segmentation error is done using the formula:

$$E_i = \frac{1}{s \times g} \sum_s \sum_g S(s,g) \otimes G(s,g) \tag{8}$$

where I_i is the input of the original image, G_i is the ground truth mask and S_i is the segmented iris output, s and g are the iris marked segmented image pixels and the ground truth image respectively. XOR operation between round truth and default pixels is represented by the symbol

[1] http://islab.hh.se/mediawiki/index.php/Iris_Segmentation_Groundtruth
[2] http://www.wavelab.at/sources
[3] http://atvs.ii.uam.es/databases.jsp
[4] http://paginas.fe.up.pt/~mobbio2013
[5] http://biometrics.idealtest.org

⊗. The net segmentation error can be calculated by the mean of segmentation errors of the "*n*" sample image. The convergence speed of an algorithm can be shown by the execution time.

Results The first experimental results have been derived by comparing the Daugman algorithm to the proposed algorithm. It is evident that the proposed algorithm is much more accurate in detecting the iris. The visual comparison of the proposed algorithm may be inferred from Fig. 8.

We have justified the accuracy of the algorithms based on the ROC curve as indicated in Fig. 9. Various algorithms taken into consideration are the proposed algorithm, Daugman's Integro Differential Operator (IDO), Wildes Hough Algorithm and the Rosch's Histogram method. As evident from the illustration, decrease in sensitive results an increase in specificity. Similarly, decrease in the segmentation accuracy percentage results in increasing complexity of iris detection and deformation. The pupil straight view is indicated by a lower complexity without any deformation. An extreme and highly occluded view is indicated by high complexity with severe pupil deformation. A highly robust algorithm will give a near unity area with a square looking shape, whereas a poor algorithm will give area near to 0.5 with a circular shape. The performance of the proposed algorithm is reasonably better than the other algorithms taken into consideration (Fig. 9).

The overall performance (segmentation error, execution time and accuracy) have been distinctly indicated in Figs. 10, 11 and 12. The segmentation error and execution time for the proposed technique are significantly lower, while the accuracy percentage is much higher, as is evident from the corresponding graphs. It is observed that the proposed algorithm can be further extended to construct a fully-fledged iris recognition system with even more improved efficiency. Moreover, the advantage of the proposed model is that a speedup ranging from 4 to 10 s is provided on a similar workstation as defined before. The proposed system can also be utilized in a multimodal biometric system to

Table 5 Threshold values and corresponding FAR and FRR

Threshold	TP	FN	TN	FP	FAR	FRR
t = 0.00	0	100	100	0	0.00	1.00
t = 0.10	19	81	100	0	0.00	0.81
t = 0.15	21	79	78	22	0.22	0.79
t = 0.20	25	75	71	29	0.29	0.75
t = 0.25	33	67	65	35	0.35	0.67
t = 0.30	34	66	59	41	0.41	0.66
t = 0.35	35	65	56	44	0.44	0.65
t = 0.40	27	63	55	45	0.45	0.63
t = 0.45	28	62	55	45	0.45	0.62
t = 0.50	38	62	42	58	0.58	0.62
t = 0.55	41	59	41	59	0.59	0.59
t = 0.60	42	58	33	67	0.67	0.58
t = 0.62	43	57	26	74	0.74	0.57
t = 0.65	53	47	25	75	0.75	0.47
t = 0.70	61	39	16	84	0.84	0.39
t = 0.75	67	33	11	89	0.89	0.33
t = 0.80	73	27	03	97	0.97	0.27
t = 0.85	79	21	0	100	1.00	0.27
t = 0.90	87	13	0	100	1.00	0.13
t = 1.00	100	0	0	100	1.00	0.00

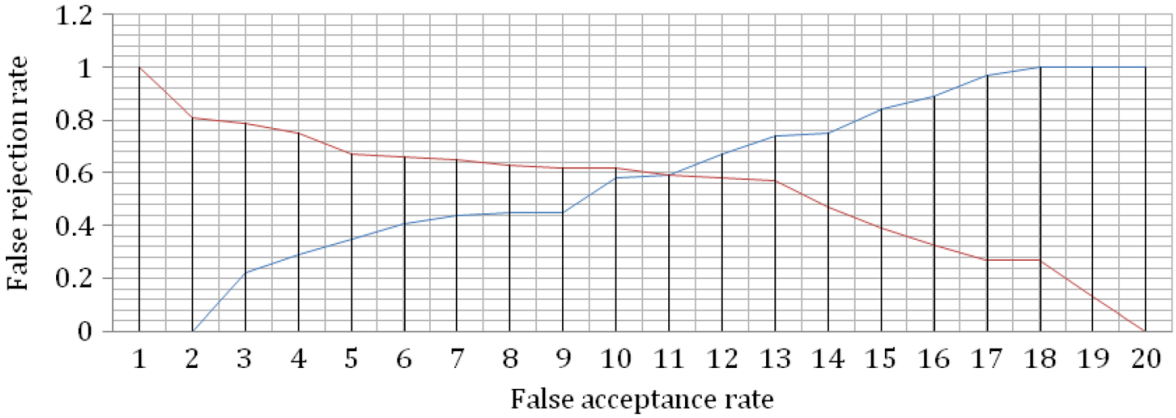


Fig. 13 FAR vs FRR

solidify the system robustness in terms of False Acceptance Rate (FAR), Equal Error Rate (EER), and False Rejection Rate (FRR).

$$FAR = \frac{FP}{FP + TN}$$
$$FRR = \frac{FN}{FN + TP}$$

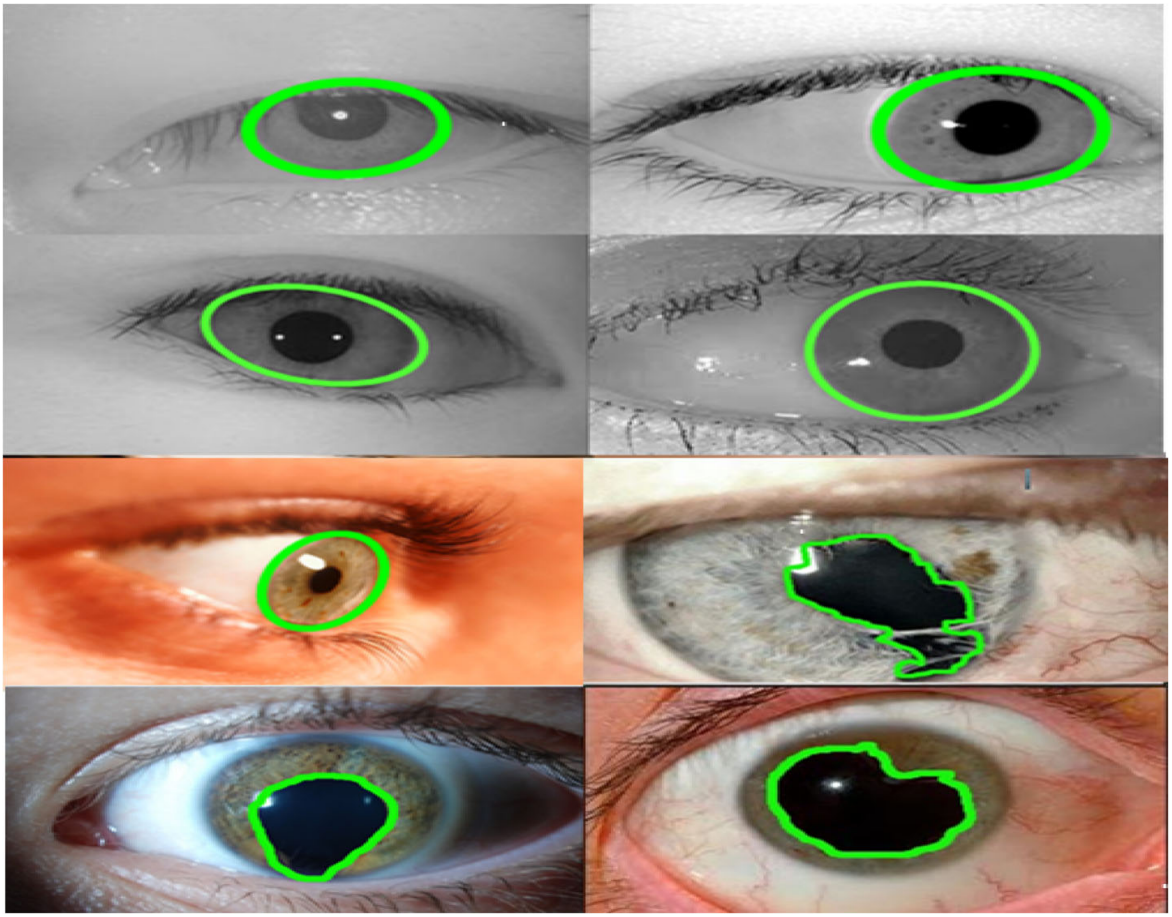


Fig. 14 Green marker is used to show the results of final segmentation for Iris on CASIA and Pupil and UBIRIS have extreme direction views

Table 6 Computational complexity

No.	Method	Complexity
1.	Tomeo-Reyes and Chandran [69]	O(n log(n))
2.	Shah and Ross [51]	$O(n^2)$
3.	Hu *et al.* [30]	O(n log(n)) + O(n)
4.	Proposed Work	O(n) + O(log(n))

*n-number of transactions per database

Table 5 indicated the threshold values and corresponding false positive, false negative true positive, false positive and false negative true negative, corresponding FAR and FRR values.

Figure 13 represented the ROC curve between FAR and FRR. When FAR = FRR that means EER is the point where FAR and FRR are minimal and optimal, we get the threshold value: t = 0.55.

Lastly, segmentation results of the proposed algorithm on the UBIRIS and CASIA database are indicate by green markers for both iris and pupil in Fig. 14. Thus, it can be concluded that the proposal is effective for iris recognition.

The proposed method is an integration of several techniques like binary edge generation, pupil detection and several iris detection stages. The complexity of the proposed work is calculated in term of the processing time, when the numbers of transaction are increases the execution time is decreases as compare to other existing methods. Table 6 indicated the computational complexity.

5 Conclusions

In this paper, we proposed a new approach to Deformation and Direction Independent Iris Localization based on Curve Fitting using Polynomial along with singleton expansion. The proposed method is an integration of several techniques like binary edge generation, pupil detection, and several iris detection stages. Experiments have been conducted taking into account several images that are part of the CASIA and UBIRIS databases. The iris localization and pupil challenging tasks have been handled for unusual and extreme cases with significant results where the relevant algorithms is surpassing with minimum computational time. The accuracy visual proofs achieved in the output have been demonstrated with iris and pupil being localized in high accuracy for any deformation and direction.

The proposed method is relevant to surveillance and security, also can be beneficial for other financial applications (mobile banking and home). The proposed algorithm may further be extended to construct a fully-fledged iris recognition system with even more improved efficiency. An efficient method of iris localization also serves greatly to iris recognition, thus strengthening the biometric process. Further, to identify the disorders of several eyes and central nervous system by using or analyzing the localized information of pupil, we plan to design a supervised learning-based system. The pupula duplex is a very rare disorder, in which there are two pupils in a single eyeball. This could be taken into account in the future system. Several extreme machine learning techniques may also be adapted in the future for iris localization such as the clustering algorithms in [23, 43, 46, 54–60, 62, 65–68, 70] .

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Label-free detection of *Escherichia coli* bacteria by cascaded chirped long period gratings immunosensor

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ABSTRACT

An optical fiber based immunosensing platform formed by two identical chirped long period gratings (CLPGs) for sensitive and label-free detection of *Escherichia coli* (*E. coli*) is presented. The proposed immunosensor having two CLPGs with an inter-grating space (IGS) works like a Mach-Zehnder interferometer. The important feature of this sensor is that by changing the refractive index (RI) induced phase at the IGS region, a corresponding shift in resonance wavelength can be realized without affecting the actual grating region. Additionally, the confining bandwidth of the interference fringes promotes greater resolution in the resonance wavelength analysis of the transmission spectrum. The main aim of this study was the specific and rapid detection of the *E. coli* bacteria in phosphate buffer saline (detection range: 10 cfu/ml to 60 cfu/ml) by using the bio-functionalized IGS region as a sensing probe of the dual CLPG structure. The observed detection limit was 7 cfu/ml. For specificity analysis, *Salmonella typhimurium* and *Staphylococcus aureus* were tested and no significant shift in resonance wavelength was observed. In addition, the proposed immunosensor has the ability to selectively detect *E. coli* in real samples including lake water. The high specificity, good sensitivity to ambient RI, and robustness of the developed sensing platform will open a new avenue in optical immunosensing technology, and cascaded long CLPG sensors can contribute significantly to the detection of pathogenic bacteria in water and food samples.

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I. INTRODUCTION

The design and development of immunosensors capable to perform sensitive, fast, and reliable detection of pathogenic bacteria have been an area of great interest for applications in biochemical analysis, dairy industry, environmental monitoring, and industrial quality control.[1] Bacteria are ubiquitous in nature and are present throughout in food, in our bodies, and in our surrounding environment. Many bacterial strains are useful, but several strains are hazardous to our health and can cause serious illness.[2] *E. coli* is a gram negative, rod shaped facultative anaerobic bacterium belonging to *Enterobacteriaceae* family. Many *E. coli* strains are non-pathogenic including those present in the gut and intestine of living organisms. However, strains having virulence factors are pathogenic in nature causing different health complications

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including diarrhea,[3,4] Crohn's disease,[5] neonatal meningitis,[6] urinary tract infections,[7] and colorectal cancer.[8] Detection of pathogenic bacterial strains and their related toxins to prevent disease is prerequisite to the food industry, clinical diagnosis, and therapeutics.[9,10] Conventional microbiological methods for determining the cell counts of bacteria employ selective culture, serological, and biochemical characterization.[11,12] Although these sensors have high sensitivity and selective bacterial detection capability, they are typically time consuming and involve complex pre-enrichment processes. The potential of instantaneous detection of pathogenic bacteria has increased largely based on the advent of sensor technologies capable of detection in real-time with high selectivity, specificity, and portability, using low-cost assays and ultra-small volumes. Various sensing platforms like electrochemical sensors,[13] amperometric sensors,[14] potentiometric sensors,[15] surface plasmon resonance (SPR) based sensors,[16] and Surface Enhanced Raman Spectroscopy (SERS)[17] have been explored for the detection of bacteria in different matrices. However, *in situ* and label free monitoring of analytes remains a major challenge in these techniques. To address the need of sensitive, rapid, and portable biosensors for the detection of specific biomolecules, concerted research is in progress across the world. With advances in immunosensing devices, optical fiber based sensors are emerging as a promising platform for detection purposes due to their high signal efficiency, non-invasive, no electrical interference, and high sensitivity features.[18–20] In recent years, surface plasmon resonance based sensors,[21–23] fiber Bragg gratings,[24] tapered fiber optic sensors,[25,26] dual-core fiber sensors,[27] and a large number of sensing schemes with Long period grating (LPG) structure have been reported[28–32] for sensing applications. In all of these reported articles based on LPG sensors, it was observed that the LPG region was itself used as the sensing portion. This has the disadvantage of distorting the LPG transmission spectrum during the course of experimental analysis. It was also reported that lower refractive index (RI) sensitivity was observed in bio-molecular detection as compared to LPGs functionalized with high refractive index material coating,[33] resulting in the complex fabrication process. Furthermore, it was observed that the attenuation bandwidth in the transmission spectrum of a single LPG structure is very wide, ~10-15 nm. Such a wide bandwidth leads to lesser resolution, thus limiting its widespread applications. Therefore, in order to increase the resolution and sensitivity of sensing using LPG, it was required to design new LPG structures with lesser attenuation bandwidth.

The present study reports a fiber optic immunosensor for *E. coli* detection. The proposed immunosensor consists of two identical chirped long period gratings (CLPGs) in series separated by an inter-grating space (IGS) of 1 cm. The IGS was immobilized with anti-*E. coli* antibodies for the sensitive detection of a model bacterium, i.e., *E. coli*. To the best of our knowledge, the immunosensing applications of CLPGs have not been explored, particularly for bacteria detection. A specific advantage of the proposed structure is that the sensing of analytes can be performed without disturbing the CLPGs. The experimental demonstration of the cascaded CLPG sensor for *E. coli* quantification will assist the optimal utilization of this structure in practical applications. In addition, the performance of the proposed immunosensor was examined by comparing the results obtained with the reported sensing platforms for the detection of *E. coli*.

A. Working principle

The proposed sensor works as a Mach–Zehnder interferometer (MZI), generating interference fringes within the attenuation bands.[34–36] The first CLPG acts to couple light from the core mode to cladding modes. Both core mode light and cladding mode light then propagate through the IGS region of length d. By virtue of their different refractive indices, the modes effectively traverse different optical distances ($n_{eff\,d}$). At the second CLPG, the cladding mode light was coupled back into the core. The light coupled into the core by the second CLPG was phase shifted with respect to the light that propagated through the core, giving rise to an interference pattern. The chirping of the gratings causes monotonous variation in period resulting in broader bandwidth as compared to uniform LPG. However, the attenuated peaks generated by the interference pattern have much lower bandwidth as compared to the broader bandwidth of single CLPG. Researchers have explored CLPG and concatenated CLPG for wavelength division multiplexing (WDM) channel tuning,[37] dispersion compensation,[38] simultaneous measurement of temperature and strain,[39] and monitoring the flow of epoxy resin.[40] However, the remarkable application of this structure as an immunosensing platform has been successfully dispensed in the present study.

Similar to LPG, light coupling in CLPG occurs between the guided core mode and the co-propagating cladding modes. The mode coupling occurs at wavelengths which satisfy the phase matching condition, as shown in Eq. (1),

$$\lambda_r = \left(n_{eff,01} - n_{eff,lp}\right)\Lambda_o, \tag{1}$$

where λ_r is the resonance wavelength coupled to the pth cladding mode, $n_{eff,01}$ is an effective index of the core mode, l is the azimuthal number, p is the mode order (=1, 2, 3, . . .), $n_{eff,lp}$ is an effective index of the pth cladding mode, and Λ_o is the grating period. The refractive index (RI) sensitivity of LPG is given by[41]

$$\left(\frac{d\lambda}{dn_s}\right) = \left(\frac{d\lambda}{dn_{eff,lp}}\right)\left(\frac{dn_{eff,lp}}{dn_s}\right). \tag{2}$$

Equation (2) clarifies that the RI sensitivity depends upon the effective refractive index (ERI) of the cladding mode ($n_{eff,lp}$) which is further dependent on the refractive index of the surrounding material (n_s). As cladding modes suffer from high attenuation, a series of attenuation bands in the fiber transmission spectrum can be seen, each centered at a particular wavelength, known as resonance wavelength that depends on the grating period and the effective index of the core and cladding of the optical fiber.

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We have considered the amplitudes of co-propagating core and cladding modes as A_{01}^{core} and A_{lp}^{clad} coupled along the grating length ($0 \le x \le L_g$), respectively. Therefore, the electric field of the coupled light from the core mode to the co-propagating cladding mode is written as

$$E(x) = A_{01}^{core}(x)e^{j(\beta_{co,01}-\delta_{01,lp})x} + A_{lp}^{clad}(x)e^{j(\beta_{cl,lp}-\delta_{01,lp})x}. \quad (3)$$

Here, $\beta_{co,01}$ (propagation constant of core mode) = $k_o n_{eff,01}$, $\beta_{cl,lp}$ (propagation constant of cladding mode) = $k_o n_{eff,lp}$, and $\delta_{01,lp}$ (detuning parameter)= $(1/2)(\beta_{co,01} - \beta_{cl,lp}) - (\pi/\Lambda_o)$, where $k_o = 2\pi/\lambda$. According to coupled mode theory, the field equations of LPG are then written as

$$\frac{dA\frac{core}{01}}{dx} = j\left[A\frac{core}{01}\delta_{01,lp} + A\frac{clad}{lp}K_{cl,lp}\right], \quad (4)$$

$$\frac{dA\frac{clad}{lp}}{dx} = j\left[-A\frac{clad}{lp}\delta_{01,lp} + A\frac{core}{01}K_{cl,lp}\right], \quad (5)$$

where $K_{cl,lp}$ is the coupling coefficient.

It can be noted that the working principle of chirped long period gratings (CLPGs) is similar to that of LPG, and the difference is that the grating period varies over the grating length in CLPGs. In addition, the coupling coefficient varies linearly with increase in grating length. The grating period (Λ) is a function of z. The periodicity of the generated interference pattern can be precisely tuned by varying the chirp, the grating period, or the total length of the sensor. Depending on the amount of phase shift, we can obtain a well separated pair of dips. In linearly chirped grating, the period can be expressed as

$$\Lambda(z) = \Lambda_0 + C\left[\left(L_g/2\right) - z\right], \quad (6)$$

where C represents the chirp constant (change in grating period per unit length of the grating), L_g is the length of the grating, Λ_0 is the grating period at the center of the grating, and z varies from 0 to L_g.

The MZI design with two CLPGs is shown in Fig. 1(a). Both CLPGs are separated by a distance "d" (inter-grating space of 1 cm) which is responsible for a phase shift between the two arms of MZI. After coupling with the second grating, the phase shift is observed in the interference fringe pattern of each resonance. The spectral profile is dependent on the detuning parameter (δ), the light coupling order of the cladding mode, and a wavelength range which gets coupled across the grating length.[42] The detuning parameter in CLPG varies along the grating length represented by $\delta_{01,lp}$,[43]

$$2\delta(z) = \beta_{co} - \beta_{cl} - \gamma(z), \quad (7)$$

where $\gamma(z) = 2\lambda/\Lambda(z)$.

It has been reported that the cascaded CLPG sensors have higher RI sensitivity than a single CLPG or single LPG due to the extra phase difference introduced by the IGS. Moreover, the cascaded CLPGs show finer-scale features in the transmission spectrum and offer higher resolution for monitoring changes in several environmental parameters.

II. MATERIALS AND METHODS

A. Materials

A single mode photosensitive optical fiber (FIBERCORE, UK) with a core diameter of ~8 μm and a cladding diameter of 125 μm was used for all the experiments. Anti-*E. coli* monoclonal antibodies were procured from MyBioSource, U.S.A. N-(3-dimethylaminopropyl)-N′-ethyl carbodiimide hydrochloride (EDC), N-hydroxysuccinimide (NHS), (3-aminopropyl) triethoxysilane (APTES), and 1 M Phosphate Buffer Saline (PBS) (pH 7.4) were purchased from Sigma-Aldrich, India, and hydrofluoric acid (48%) was purchased from Merck, India. Nutrient broth and nutrient agar were procured from Hi

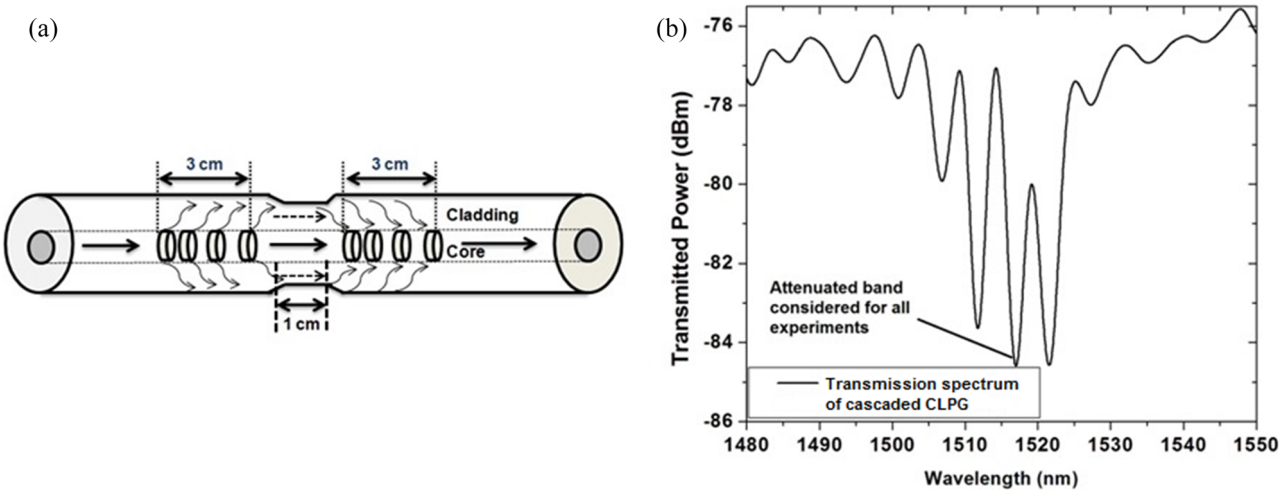


FIG. 1. (a) Schematic representation of cascaded chirped long period gratings inscribed in the core of the photosensitive single mode optical fiber with an inter-grating space of 1 cm. (b) Transmission spectrum of the fabricated sensing probe with attenuated peaks generated by the interference pattern.

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Media, India. *Escherichia coli* (*E. coli*) (MTCC No.: 1687), *Salmonella typhimurium* (*S. typhimurium*) (MTCC No.: 1251), and *Staphylococcus aureus* (*S. aureus*) (MTCC No.: 87) were procured from Microbial Type Culture Collection and Gene Bank (MTCC), Institute of Microbial Technology, India. Lake water samples were collected from Sukhna Lake, Chandigarh, and de-ionized (DI) water >18 mΩ cm (specific resistivity) at 25 °C was procured from Millipore.

B. Instruments

White light source (AQ4305, Ando Electric Co., Ltd) with a bandwidth of 1550–1630 nm was used for light propagation through the cascaded CLPG, and the corresponding transmission resonance wavelength measurements were recorded on an Optical Spectrum Analyzer (OSA) (Yokogawa, AQ6319, Ando Electric Co., Ltd.). A Fujikura CT-20 cleaver was used for cleaving, and the I/O connections were made by using an AQC fusion splicer (Fujikura, FSM-50S). The morphological characteristics of the developed sensor were studied by using a scanning electron microscope (SEM) with accelerating voltage 1–4 kV (JSM-1T300; Jeol, Japan).

C. Fabrication of chirped LPGs

Cascaded CLPG with an inter-grating space (IGS) of 1 cm was fabricated by exposing a boron co-doped germanosilicate fiber core to a KrF laser by the point-by-point method at a pulse repetition rate of 200 Hz and a pulse duration of ~15 ns with the pulse energy of the UV laser beam being ~3 mJ using the TeraXion grating writing station. The length of both CLPGs was 3 cm. Prior to UV inscription, the fiber was photosensitized by a standard hydrogen loading process performed at a pressure of 150 bar for one week. The photosensitive fiber was placed on a computerized translation stage. Light from a broadband source was passed from one end of the fiber, and at the other end, an optical spectrum analyzer (OSA) was connected to monitor the transmission spectrum. The observed transmission spectrum of fabricated cascaded CLPG is shown in Fig. 1(b). Fabrication of negative chirped long period gratings (increase in the grating period with distance) was achieved, and the grating period was from 575 μm to 600 μm in both chirped LPGs. The forward propagating fundamental core mode excites the lp_{04} and lp_{05} cladding modes. After the UV-inscription, the gratings were stabilized by thermal annealing at 90 °C for 20 h. For enhancing the RI sensitivity, the sensing probe (IGS region) was chemically etched with HF (48% v/v) for 13 min. The bandwidth of the transmission loss of cascaded CLPG is 2.3 nm. The attenuated band at 1517 nm, as shown in Fig. 1(b), was considered for all the sensing purposes.

D. Bacteria culture method

E. coli was grown in a culture medium of sterilized nutrient broth (pH: 7.4) under optimal conditions at 37 °C. Briefly, 1 ml of *E. coli* culture (MTCC No.: 1687) was transferred to a conical flask having 1000 ml solution of nutrient broth (13 g) in DI water. The solution was incubated for 24 h at 37 °C under the continuous shaking process. When the culture was examined after 24 h of incubation, bacterial growth was manifested by the appearance of pale yellow turbidity in the broth. The concentration of the cell suspension was 1.5×10^8 cfu/ml as calculated by measuring optical density (OD 600). 5 ml of *E. coli* culture was centrifuged at 3000 g, and the pellet was resuspended and serially diluted (1:20 dilution) in sterile phosphate buffer (1 M; pH 7.4). Determination of *E. coli* concentration in terms of colony forming units (cfu)/ml was performed by plating the serial dilutions on the surface of the nutrient agar plates. A detection range of 10 cfu/ml–60 cfu/ml was selected from the dilutions. The anti-*E. coli* monoclonal antibodies were diluted in PBS (pH 7.4) at a dilution factor of 1:1000 and stored at 4 °C.

E. Antibody immobilization

After cleaning the tapered sensing probe with DI water, it was immersed in piranha solution (H_2SO_4:H_2O_2 = 3:1) for 1 h to generate hydroxyl groups on the sensing area followed by washing with de-ionized water. The fiber was then coated with 1 ml of 10% (v/v) APTES solution in isopropanol for 30 min to generate $-NH_2$ groups on the surface of the sensing probe and was washed for three times with de-ionized water to remove unbounded APTES molecules. 10 mM EDC and 20 mM NHS were prepared in 10 ml of PBS (pH 7.4) and 1 ml of this prepared cross-linking solution was mixed with 100 μg/ml of anti-*E. coli* monoclonal antibodies and stored for 30 min at 4 °C.

This results in activation of carboxyl groups of anti-*E. coli* antibodies to form covalent bonding with the amine groups on the sensing probe via carbodiimide cross linker chemistry. The above-activated antibody solution was immobilized on an amine functionalized sensing probe and incubated for 30 min in an inert environment at 37 °C. The process involved in immobilization of anti-*E. coli* antibodies on the sensing probe is shown in Fig. 2. The non-specific binding sites on the surface of antibodies immobilized on the sensing probe were blocked by incubation with 2% BSA in PBS for 30 min at room temperature, followed by washing with PBS (pH 7.4) and drying with pure nitrogen (99.999%) gas.

F. Experimental setup

The experiments were executed in a glass flow cell, and the experimental setup is clearly depicted in Fig. 3. The flow cell has inlet and outlet openings with Teflon lining inside the cell. Cascaded CLPGs with IGS were fixed between two micropositioners for straight positioning of the sensing probe, thereby eliminating bending losses. The broadband source was connected at one end of the sensing probe, whereas the other end was connected with OSA. The monoclonal antibodies were immobilized on the cladding region of the sensing probe. The developed immunosensor was then exposed to different concentrations of *E. coli* (10 cfu/ml–60 cfu/ml). The transmission spectrum was continuously monitored by using the OSA, and the reading was noted after 12 min of settling time. After recording the spectral data, the sensing probe was

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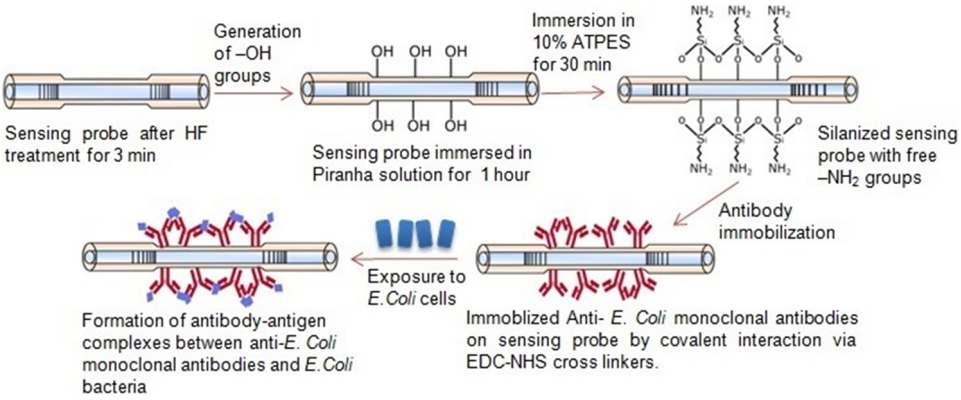


FIG. 2. Schematic representation of immobilization of anti-*E. coli* monoclonal antibodies as bioreceptors on the fiber optic probe.

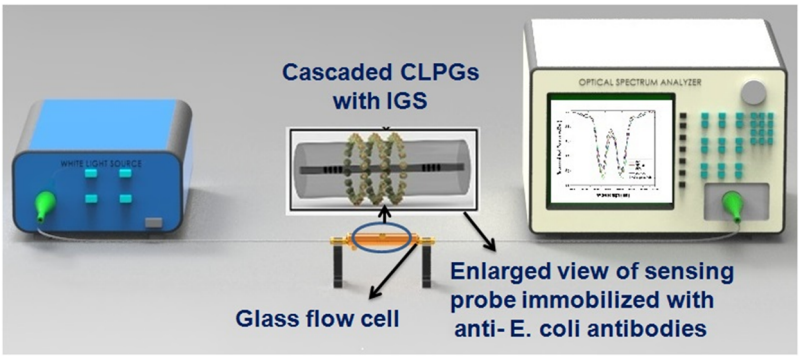


FIG. 3. Schematic representation of cascaded CLPGs with biofunctionalized inter-grating space employed for detection of *E. coli*.

washed thrice with DI water to regain the sensor to its original position. The temperature is maintained constant throughout the experiment at 25 °C and monitored through a digital thermometer.

III. RESULTS AND DISCUSSION

A. Morphological studies

The scanning electron microscopic (SEM) images of the bare optical fiber and sensing probe with *E. coli* bacteria colony forming units are shown in Figs. 4(a) and 4(b), respectively. Uniform and nicely adhered biorecognition layers can be depicted by the roughness over the cladding surface of the sensing probe. Surface modifications are evident and affirm the protocols used for the silanization and the subsequent anti-*E. coli* antibody immobilization.

B. Control experiments

The bare sensing probes were directly exposed to different concentrations of *E. coli* to perform the control experiments. Pathogenic *E. coli* having a concentration less than 100 cfu/ml can cause severe health complications; therefore, the selected detection range was from 10 cfu/ml to 60 cfu/ml. Samples with different concentrations of *E. coli* were passed

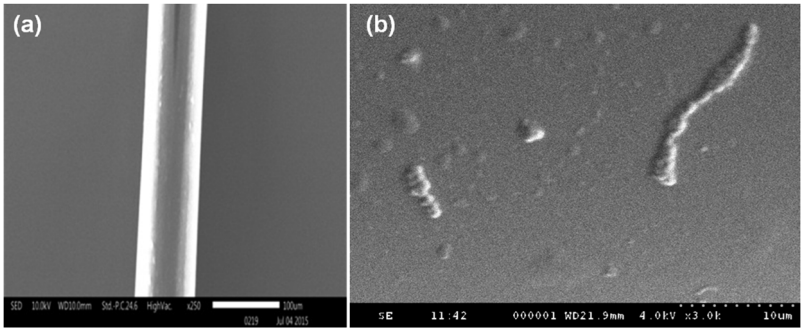


FIG. 4. Scanning electron microscope image of (a) a bare optical fiber and (b) an enlarged view of a bio-receptor functionalized sensing probe with adhered *E. coli* bacteria colonies. The roughness on the surface of the sensing probe has been generated by chemical etching and ATPES treatment on which antibodies are immobilized by covalent bonding via EDC-NHS cross linkers.

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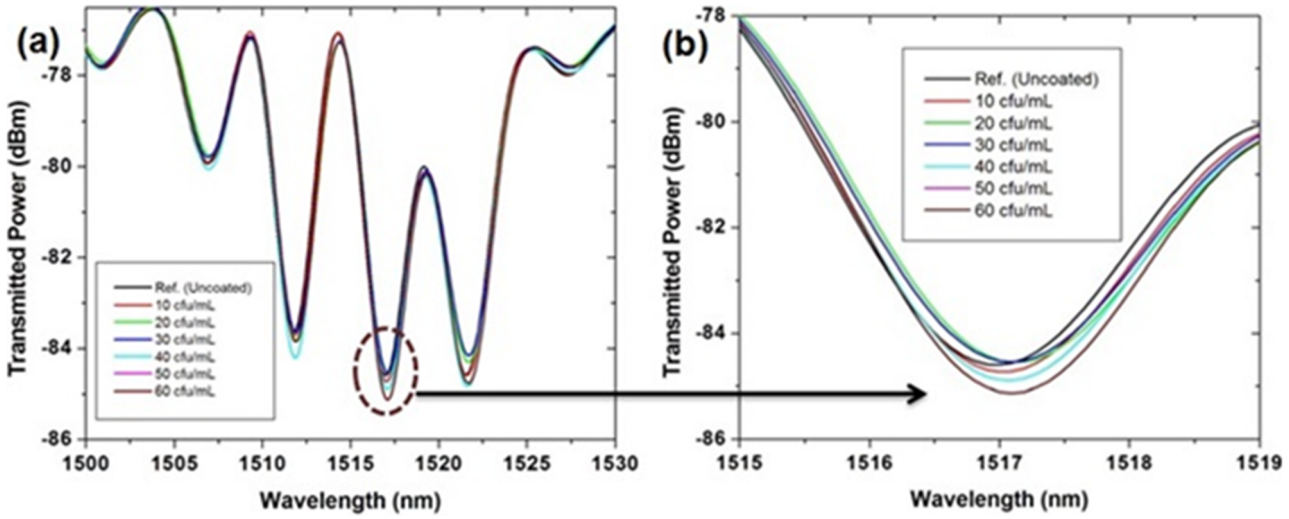


FIG. 5. (a) Measured transmission spectrum of the bare sensing probe and (b) the enlarged view of transmission spectra showing resonance wavelengths corresponding to the different concentrations of *E. coli*.

through the flow cell. The transmission spectrum was measured after each experiment. The experiments were repeated thrice for each concentration. The shift in wavelength for each concentration was not significant as compared to the detection of *E. coli* by using the antibody immobilized sensing probe. The marginal shift in wavelength, as shown in Fig. 5, was due to a change in ambient refractive index caused by the different concentrations of *E. coli* bacteria. The transmission spectrum (1480 nm-1550 nm) of the bare sensing probe and the anti-*E. coli* immobilized sensing probe for different *E. coli* concentrations is presented in Fig. S1 (supplementary material).

C. Sensing of *E. coli* with anti-*E. coli* immobilized sensing probe

The resonance wavelength obtained after the antibody immobilization was considered a reference peak. The bandwidth of the resonance wavelength was increased initially after the silanization process; however, no significant effect on sensitivity was observed during quantification of *E. coli* with varied concentration. The considerable shift in resonance wavelength was observed for each concentration. As presented in Fig. 6, a sharp red shift of 1.59 nm was observed when an *E. coli* sample with 60 cfu/ml concentration was passed over the anti-*E. coli* antibody immobilized sensing probe. The bacterial concentration of *E. coli* shows a linear correlation in the range of 10–60 cfu/ml with a correlation coefficient (R^2) of 0.9834, as shown in Fig. S2 (supplementary material). A considerable difference in a shift of resonance wavelength was observed between the bare sensing probe and the anti-*E. coli* antibody immobilized sensing probe, as shown in Fig. 7. The developed sensor has high sensitivity as exhibited by the red shift of 0.2 nm for 10 cfu/ml. The detection limit of the developed immunosensor was 7 cfu/ml.

D. Specificity studies, reproducibility, and real samples analysis

Monoclonal antibodies have a specific affinity toward the target analyte against which they are produced. To investigate the specificity of the immunosensor, the anti-*E. coli* antibody immobilized sensing probe was sequentially exposed to two similar bacteria: 0.063 nm shift was observed for 20 cfu/ml of *Salmonella typhimurium* and 0.062 nm shift in resonance wavelength was noted for 20 cfu/ml of *Staphylococcus aureus*, as shown in Fig. 8. To examine the reproducibility of the immunosensor, the experiments were performed 4 times

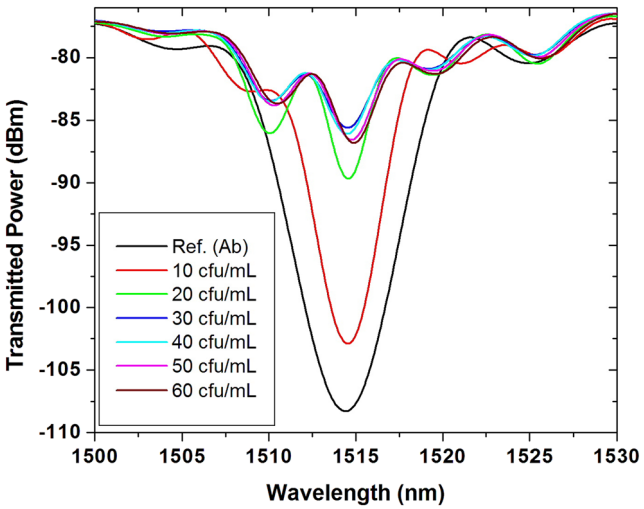


FIG. 6. Transmission spectrum of the immunosensor for 10 cfu/ml–60 cfu/ml concentration range of the *E. coli* bacteria in PBS (pH 7.4).

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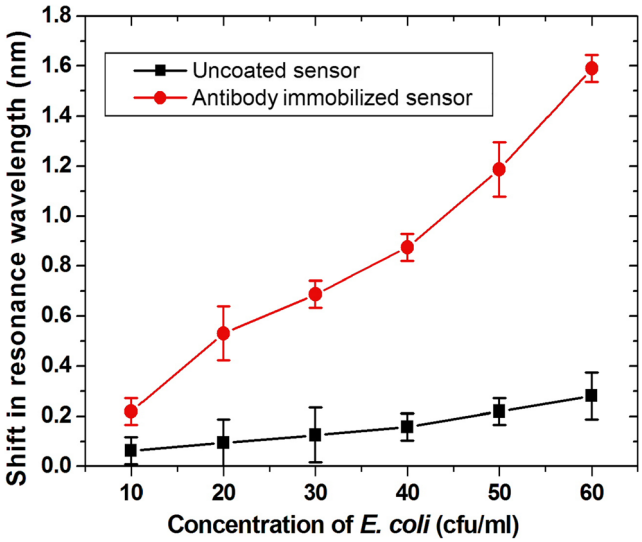


FIG. 7. The relative wavelength shifts of the bare sensing probe and antibody immobilized sensing probe for *E. coli* detection. Error bars represent standard deviation (n = 3).

for *E. coli* detection (2 lower and 2 upper concentrations were considered) with a gap of 2 h between each cycle, and there is no significant change in its performance up to three cycles, as shown in Fig. S3 (supplementary material). However, the change in performance can be noted after 3 cycles. It may be due to little variation in the immobilized surface of the biosensor. The antibody layer is intact for multiple cycles and its affinity toward target analytes may decrease with storage period. The capability of the developed immunosensor for

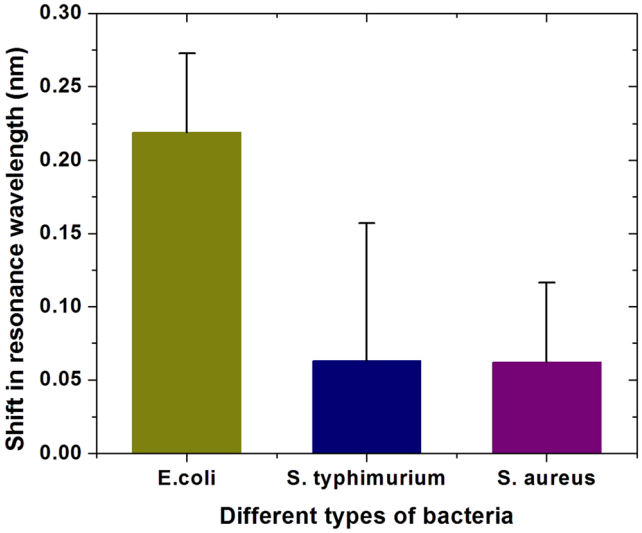


FIG. 8. Comparative specificity of the developed fiber optic immunosensor with anti-*E. coli* functionalization for different bacteria in PBS.

detection of *E. coli* in real samples was investigated by testing spiked lake water samples. Initially, the lake water samples were diluted 20 times and spiked with specific concentrations of *E. coli*. These spiked samples were then examined, and the corresponding calibration plot is shown in Fig. S4 (supplementary material) along with the graph [Fig. S4(c)] depicting the relative shift in wavelength for different concentrations of *E. coli* in buffer samples and spiked lake water samples. The shift in wavelength for spiked samples was slightly higher than the shift in wavelength for buffer samples as the higher RI of the spiked samples has little effect on the shift in resonance wavelength. The specific detection of *E. coli* in spiked samples can be observed by the standard calibration plot [Fig. S4(b) (supplementary material)].

E. Statistical analysis

One way ANOVA was used to investigate if there is a statistically significant difference in the mean wavelengths. The ANOVA test results indicate a statistically significant difference in wavelength across at least one of the samples ($F_{3,8}$ = 4.61, p =0.037). Tukey's Honest Significant Difference (HSD) post-hoc test was used to conduct pair-wise comparisons while controlling the family-wise alpha to 0.05. Mean wavelength in the detection of *E. coli* do not differ significantly from that of other interferent bacteria, viz., *S. typhimurium* (p = 0.175) and *S. aureus* (p = 0.078). Mean wavelength in the detection of *E. coli* is observed to be significantly different from that of the blank sample (p = 0.035). We observed no significant difference in mean wavelength in the detection of *S. typhimurium* (p = 0.668) and *S. aureus* (p = 0.936) when compared to blank samples. A $p < 0.05$ was considered to be significant. Table S1 (supplementary material) gives the descriptive statistics, and Table S2 (supplementary material) shows the result of pair wise comparisons. The statistical analysis of data was performed by SPSS version 15.0 (SPSS South Asia, Bangalore). The statistical analysis results confirm the high specificity of the developed sensing probe for *E. coli* detection.

F. Comparative studies

Several studies on *E. coli* detection in different media using different sensing platforms have been reported with certain limitations. An inclusive comparison of reported immunosensors with the developed CLPG immunosensor is presented in this segment. SERS based bio-functionalized gold-coated magnetic spherical nanoparticles were studied to detect *E. coli* with a limit of detection of 8 cfu/ml. The reported method was highly sensitive and has good specificity toward *E. coli*; however, it possesses certain limitations including long assay period and low capture efficiency.[44] Researchers have reported an impedimetric immunosensor for the detection of *E. coli* O157:H7 and *S. typhimurium* in food samples. The reported sensor specifically detected *E. coli* O157:H7 in the range of 10^2 to 10^6 cfu/ml with LOD (Limit of detection) of 2.05 × 10^3 cfu/g in beef samples.[45] [LOD is defined by 3*SD Blank/slope of calibration curve]. However,

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the higher LOD and use of large electrodes are certain impediments of the reported study. Recently, researchers have explored an aptasensor for detection of *E. coli* O157:H7 with a detection limit of 1.46×10^3 cfu/ml and detection time of 50 min.[46] This highly selective and sensitive detection technique was observed to be tedious and time-consuming requiring multiple steps for the fabrication of the aptasensor. Researchers have a developed capacitive biosensor based on microcontact imprinting for detection of *E. coli*.[47] The biosensor has a detection limit of 70 cfu/ml and was investigated for *E. coli* detection in river water samples. An antimicrobial peptide (AMP)-based colorimetric bioassay was studied for sensitive detection of *E. coli* O157:H7.[48] The reported bioassay has LOD of 13 cfu/ml, and food samples were tested for detection of target bacteria. However, the experiments were not repeated for multiple cycles to analyze the reproducibility of the developed method. Some other fiber-optic label free techniques for quantification of *E. coli* have been presented in Table S3 (supplementary material). Limit of detection for the developed immunosensor (07 cfu/ml) and its specificity toward the target bacteria (*E. coli*) are comparable to or better than those of the above-mentioned studies.

IV. CONCLUSION

In the present study, an anti-*E. coli* antibody immobilized cascaded chirped long period grating (CLPG) immunosensor for highly sensitive and specific *E. coli* detection was successfully demonstrated. This alternative sensing approach of fiber optic sensors for quantitative monitoring of bacteria is novel and can be employed multiple times for *E. coli* detection. It can be further pursued for onsite monitoring of bacterial cells in different matrices like food, water, and other biological samples. This sensing probe provides an edge over the available grating based refractometric sensors as the inter-grating space (IGS) between the CLPG pair is used for sensing purposes without disturbing the grating region of the developed sensor. Although the present study has provided intriguing preliminary results, some limitations need to be noted. The optical fiber is delicate; therefore, proper packaging of the sensor is required. Nanomaterials can be functionalized over the sensing probe for sensitivity enhancement. In this study, control experiment analysis and specificity results are presented. The detection limit of *E. coli* by the developed sensor is comparable with the results obtained from other bacteria sensing platforms. The sensing probe can be reused for multi-parameter sensing, and this property supplements a new feature to the existing characteristics of grating based sensors for chemical and biological sensing. The obtained results from real water samples suggest the possible applications of the developed optical fiber sensor as a sensing platform in agriculture, medicine, food processing industry, etc. With immobilization of specific receptors, the IGS sensing probe of cascaded CLPG has remarkable applications for *in vitro* detection of pathogens for industrial quality control and environmental process monitoring at distant locations.

SUPPLEMENTARY MATERIAL

The transmission spectrum of the developed sensing platform, Tukey's HSD test for pair-wise comparisons, results of biosensor's performance for multiple cycles of detection, graph related to *E. coli* detection in spiked lake water samples, and overview of different fiber-optic biosensing platforms for *E. coli* detection is presented in supplementary material.

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ORIGINAL PAPER

Loss of target information in full pixel and subpixel target detection in hyperspectral data with and without dimensionality reduction

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Abstract
In most hyperspectral target detection applications, targets are usually small and require both spatial as well as spectral detection. Hyperspectral imaging facilitates target detection (TD) applications greatly, however, due to large spectral content, hyperspectral data requires dimensionality reduction (DR) which also leads to loss of target information both at full pixel and subpixel level. Literature reports many DR and TD algorithms in practice. Several studies have focussed on assessing the loss of target information in DR, however, not much work seems to have been done to assess loss of target information in full pixel and subpixel TD in hyperspectral data with and without DR. This paper seeks to study various combinations of DR techniques combined with full pixel and subpixel TD algorithms. The results indicate that in the case of full pixel targets, both DR and TD contribute to the loss of target information, however, there is more loss of target information in the case when DR precedes TD in comparison to a case where TD is applied without DR. In the case of subpixel TD, however, there appears to be loss of subpixel target information in the case where TD alone is performed in comparison to a case where DR precedes TD.

Keywords Dimensionality reduction · Full pixel target detection · Subpixel target detection · Spectral unmixing · Mixed pixel · Target information

1 Introduction

Hyperspectral sensors produce an image cube having numerous, narrow spectral band information centring on equally distributed wavelengths ranging throughout the visible, near infrared, mid infrared and thermal infrared portions of EM spectrum (Shippert 2004). These narrow wavelength bands provide a good platform for its use in a variety of applications such as target detection and identification, terrain classification, environmental mapping, pollution monitoring etc.

Availability of high spectral and spatial resolution hyperspectral data has greatly facilitated target detection (TD). TD here refers to the process of searching the pixels of hyperspectral data cube for finding pixels of interest, appearing with low probabilities in any given scene (Eismann 2012), using known spectral signatures (Shaw and Burke 2003). In most TD applications, targets are usually small thus occupying less than 1% of total pixels in the captured image (Davood and Safari 2012). Detection of targets, therefore, requires them to be resolved both spatially and spectrally (Manolakis et al. 2003). However, many parameters linked with target of interest such as its location, orientation, state, shape, material composition, size, etc., influence the TD process, thereby increasing the complexity of TD. Spectral variability may also arise from noise, spectrometer error, and self- shadowing (Shaw and Burke 2003).

Dimensionality reduction (DR) in the case of hyperspectral image processing improves the signal to noise ratio (Muhammad and Haq 2011). However, DR process needs to be carefully performed to ensure that crucial information pertaining to target data (as in case of TD) is not lost. After DR, if target pixels are lost, the whole purpose of TD fails. In hyperspectral data analysis, principal component analysis (PCA) (Rodarmel and Jieshan 2002; Agarwal et al. 2007), independent component analysis (ICA) (Hyvarinen and Oja 2000; Song and Jiang 2007) and minimum noise fraction (MNF) (Green et al. 1988; Rhonda et al. 2008) are some of the most widely used techniques for DR and have been considered in this research for assessment.

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Another issue affecting TD is that the spectra of any given pixel recorded in an image by hyperspectral sensors [which have a high spectral resolution but low spatial resolution (Keshava 2003)] might be a composite of many different materials appearing in the pixel. Target under consideration might occupy multiple pixels (resolved pixel or subpixel). In case of mixed pixels, soft classification is generally explored. Classification here refers to the process of allocating the subregions of fine resolution images to distinct classes (Gu and Angelov 2018a, b; Angelov and Gu 2018). Many approaches have been studied and proposed in the past including the recent work by (Gu and Angelov 2018a, b) on DRB classifiers. However, to estimate the proportion of a certain class within each pixel and neighbouring pixels, classification alone has some limitations. Therefore, while performing TD, the problem of such mixed pixels needs to be addressed. This can be achieved by spectral unmixing, which decomposes the spectrum of mixed pixel into a collection of endmembers and their corresponding abundance fractions indicating the proportion of each endmember in the pixel (Plaza et al. 2004). In linear mixing models, the acquired spectrum is a linear combination of the endmember weighted by their respective fractional abundances (Settle and Drake 1993a, b; Petrou and Foschi 1999; Settle 2006). Nonlinear mixing holds when light suffers multiple scattering involving different materials (Borel and Gerstl 1994; Fan et al. 2009; Guilfoyle et al. 2001; Altmann et al. 2012). Spectral unmixing techniques for resolving subpixel targets used in this research are linear spectral unmixing (LMM) (Manolakis et al. 2001), K-means (Keshava et al. 2000), sequential maximum angle convex cone (SMACC) (Chen and Reed 1987).

Many TD algorithms have been studied in the past but a few amongst them that have been chosen from the literature are Spectral Angle Mapper(SAM) (Kruse et al. 1993), adaptive coherence estimator (ACE) (Manolakis et al. 2003), matched filter (MF) (Manolakis et al. 2000), constrained energy maximization (CEM) (Harsanyi 1993; Chang et al. 2000), mixture tuned matched filter (MTMF) (Boardman 1998; Kruse et al. 2003), spectral similarity mapper (SSM) (Chen and Reed 1987), normalised Euclidean distance (NED), TCIMF (Ren and Chang 2000; Du and Chang 2004), SID and orthogonal subspace projection (OSP) (Harsanyi and Chang 1994; Chang 2005).

A lot of work has been done in the past to study DR independently and TD independently but very few studies (such as those done by Boardman 1998; Binol et al. 2016) are there which connect DR and TD ensuring that there is no loss/minimal loss of target data. Therefore, in this paper we propose to study loss of target information in full pixel and subpixel target detection (TD), with and without dimensionality reduction (DR). The objectives of this paper, therefore, are to assess full pixel TD without performing DR, to assess DR linked full pixel TD (along with the study of the impact of background characterization); and to assess DR linked subpixel TD for finding minimal/no loss of target data.

This research paper is organized under six sections including the Introduction. The experimental datasets used have been documented in Sect. 2, under Dataset. Section 3 on background and methodology; explains all the algorithms and background concepts. Section 4, titled implementation, explains the complete process adopted for implementing the algorithms to achieve the objectives of this paper. The work performed and the results of applying the approaches onto the data sets have been illustrated under Sect. 5, results and discussions. Conclusions, in Sect. 6, provide a summary of the findings from results obtained. Therefore, in order to follow a particular thread, corresponding parts of the thread may be referred under different sections.

2 Dataset

Two hyperspectral Datasets, referred to as Datasets 1 and 2, have been considered. In Dataset 1; target deployments, data collection was conducted in Cooke City of USA on July 4, 2006, by RIT (Cocks et al. 1998). Dataset 2 was collected under a campaign titled: SpecTIR Hyperspectral Airborne Rochester Experiment: SHARE 2012, conducted in Avon NY on September 20, 2012 by RIT in conjunction with SpecTIR, LLC, Air Force Research Lab, NR Lab, UTAS and MITRE.

2.1 Dataset 1

Figure 1 shows RGB of a hyperspectral image that was collected using HyMap sensor. Sensor captured some vehicles and fabric panels of various sizes placed around RIT campus.

General acquisition parameters for data collection process are shown in Table 1.

For this study, three vehicles: V1 (Green Chevy Blazer), V2 (White Toyota T100) and V3 (Red Subaru GL); which occupy a few pixels (but are visually difficult to detect) and placed in different locations are chosen as targets (Fig. 2). Each vehicle has 8 full pixels around 1 mixed pixel (subpixel) in data, making a total of 9 target pixels of every vehicle. Spectral signatures of vehicles are shown in Fig. 3.

A spatial subset (S1) of 190×84 pixels from an entire image of 280×800 pixels is chosen for implementation (to reduce complexity and computational time) as shown in Fig. 4.

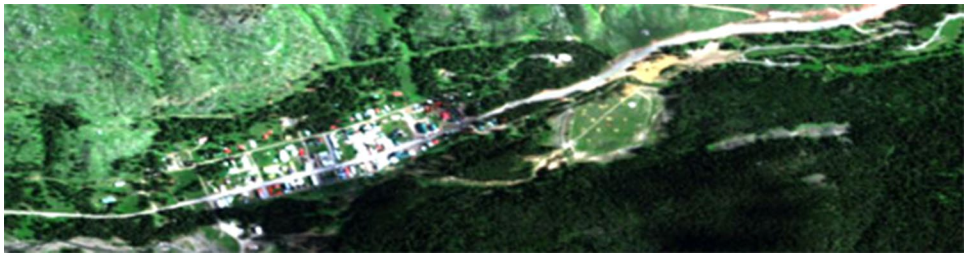


Fig. 1 RGB image showing Cooke city and surrounding terrain (RIT)

Table 1 General acquisition parameters for Dataset 1

Sensor	Data type	Data size	Spectral resolution	Spectral region	Spatial resolution
HyMap sensor	Hyperspectral	280×800 pixels	126 contiguous bands, at 0.45–2.5 nm interval	390–2450 nm	3 m

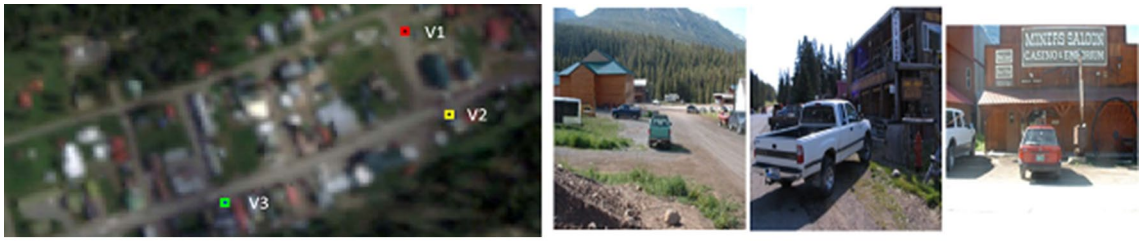


Fig. 2 **a** A zoomed in part of Cooke city, Montana showing the location of vehicles V!, V2 and V3. The truth mask for each vehicle shows 8 guard pixels around 1 mixed vehicle pixel (sub pixel). **b** RGB images of the vehicles V1, V2 and V3 respectively in the available hyperspectral data

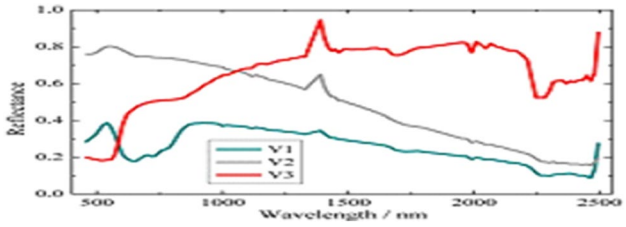


Fig. 3 Spectral signatures of vehicles V1, V2 and V3 present in the hyperspectral data



Fig. 4 Spatial subset S1 of 190 × 84 pixels selected from the available image of Cooke city

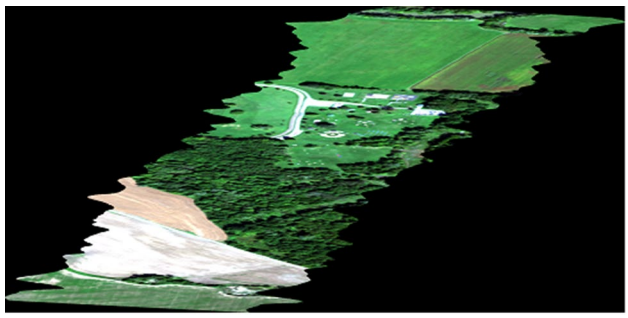


Fig. 5 Data for AVON city (SHARE 2012)

2.2 Dataset 2

Airborne imagery was collected over four different sites (Avon, Conesus Lake, Hemlock Lake, and a nearby quarry) with hyperspectral, multispectral, and LIDAR sensors.

From the entire data, Dataset for Avon city (Figs. 5, 6), with acquisition parameters as shown in Table 2 has been selected to conduct experiments for evaluation of subpixel detection and unmixing algorithms. Data contains an image and related GLT files.

TD experiment deployment contains many fabric and wooden panels placed at different locations around the city. One such panel is a blue target (24 rows × 24 columns) visible in upper right area of asphalt court while yellow target (16 rows × 16 columns) is placed in upper left as shown in Fig. 7. Yellow target is a mixed pixel target containing yellow felt and yellow cotton in the ratio of 75% and 25% respectively. Six whole panels of fabrics (10 rows × 10 columns each) are placed below mixed pixel targets. Two small panels placed just below and to the left of the blue target are pink felt (on the left) and yellow cotton (on the right). For this paper, A spatial subset (S2) of 150 × 150 pixels from entire Dataset is chosen for implementation and targets chosen are mixed pixel target Y1 (8 × 8 pixels) and full pixel target Y2 (5 × 5 pixels).

3 Background and methodology

Algorithms that have been selected from literature for TD are discussed briefly in this section. SAM (Kruse et al.1993) is background independent algorithm where only a-priori information related to target spectra needs to be known. Literature review suggests that despite the wide use of SAM, it is not much efficient in modelling of target spectrum under different illumination conditions. Algorithm that focuses on modelling the background is ACE (Manolakis et al. 2003), which follows a generalized likelihood ratio approach (Kelly 1986). After replacing normalization value in ACE by variance MF (Robey et al. 1992) is obtained. It was shown by Manolakis et al. 2001, that for a limited dataset, although each of the algorithms exhibited some degree of success in TD, ACE performs best. CEM (Ferrand and Harsanyi 2004) minimizes the response of unknown background signatures while maintaining that of target at a desired constant level and is useful when interest is only in one target and there is a-priori availability of its spectral signature. However, it does not perform well in the presence of low probability background signatures and is very sensitive to noise (Schott 2002). MTMF (Boardman 1998) operates on MNF transformed data and uses MF along with an added output infeasibility (INF) score. Targets have large MF values and small infeasibility scores (SMF). ENVI software displays a plot of SMF vs. INF where end user manually selects appropriate target pixels based on the criteria previously described. OSP works on a priori availability of data. In this technique, spectral signature of target of interest is taken as desired signature and background spectral signatures are considered as undesired signatures (Muhammad and Haq 2011). OSP seeks to reduce data dimensionality, suppresses undesired background signatures, and maximizes SNR of target spectrum. OSP is suitable for detection of manmade objects. NED normalizes the vectors first by dividing each vector by its mean and then computing the Euclidean distance between two vectors. SSM (Chen



Fig. 6 Satellite image for AVON city including the flight lines

Table 2 General acquisition parameters for Dataset 2

Sensor	Data type	Data size	Spectral resolution	Spectral region	Spatial resolution
Prospectir-VS	Hyperspectral	280 × 800 pixels	360 bands, 5 nm interval	~400 to ~2450 nm	1 m, 0.5 m

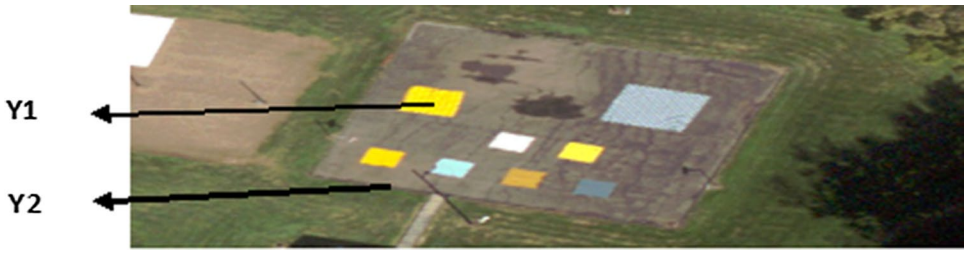


Fig. 7 Targets Y1 and Y2 selected for unmixing target detection experiment in a subset S2 (150 × 150 pixels) of Dataset 2

and Reed 1987) is also based on computation of Euclidean distance between spectra of a pixel and reference spectrum to measure the similarity amongst them.

Literature review suggests many algorithms for DR. A few of these DR algorithms such as PCA, ICA, and MNF are studied as a part of this work. Review of these is done in Table 3.

Most of the TD algorithms available thus far, can at best detect full pixel targets, leaving out several partially occupied (mixed) pixels. To deal with mixed pixels for subpixel TD, it is widely accepted that the spectral unmixing proves a useful method (Plaza et al. 2004). LMM for spectral unmixing is a flexible technique and is easy in implementation (Boardman et al. 1995; Zhang et al. 2013).

4 Implementation

A systematic procedure for present study has been implemented as shown in Fig. 8 and explained as follows:

(a) *Full pixel TD without DR in Dataset 1* Atmospheric and geometric correction has been performed on Dataset 1, followed by geo-referencing using available GLT files.

Following this, TD has been implemented using selected TD algorithms on subset S1 for each target (V1, V2, and V3) without performing DR. An Assessment of all the results obtained for every combination of algorithm and target is done to select an optimum value of threshold. Different thresholds have been explored to maximize the detections and minimise false positives. Outcomes for all the sets of experiments for a window of 20×30 pixels and results of computations of the values for true positives (TP), false positives (FP), true negatives (TN), and false negatives (FN) are noted. Post analysis, the best performing TD algorithm is selected for further processing.

(b) *DR linked full pixel TD in Dataset 1* To study the impact of DR linked full pixel TD, DR algorithms ICA, PCA and MNF are implemented. ICA based dimensionality reduced dataset contains more information in the initial bands/components and the noise or information with little spatial structure appear last (Hyvarinen and Oje 2000; Song and Jiang 2007). Noise is removed using a forward transform and bands containing coherent images are determined. Threshold selected for this is 0.0001 with iterations of 100. Thereafter, sets of different good ICA bands i.e., 10 bands, 15 bands, 20 bands, 25 bands, 30 bands have been analysed and 20 bands containing maximum information and minimum noise are selected.

Next PCA is applied. Since, maximum information is contained in first few PCA bands while the last bands appear noisy (Agarwal et al. 2007; Chang and Du 2004; Harsanyi and Chang 1994; Koonsanit et al. 2012; Zabalza et al. 2014), again sets of different good PCA bands i.e., first 10 bands, 15 bands, 20 bands, 25 bands, 30 bands have been analysed for PCA and 20 bands containing maximum information and minimum noise are selected.

MNF is then implemented which computes mean of each band, finds covariance statistics for noise and eigenvalues (Green et al. 1988; Rhonda et al. 2008). Output obtained contains eigenvalues plot. Bands with large eigenvalues (> 1) contain data and the bands with eigenvalues near 1 contain noise. Thus 20 best bands out of 126 bands have been selected.

Further DR linked full pixel TD is performed on reduced spectral subset of 20 bands (window size of 20×30 pixels) selected respectively after ICA, PCA and MNF reduction. Accuracy assessment has been done using confusion matrix (Davood and Safari 2012; Binol et al. 2016) and corresponding accuracy percentage is calculated.

(c) *DR linked full pixel TD in Dataset 2 with and without background characterization* In subset S2, first full pixel TD without background characterization is performed. Results are analyzed to find out the best performing TD algorithm. Further analysis is done for DR linked full pixel TD without background characterization using MNF, ICA, PCA as DR algorithms.

Next TD is done using K-means and SMACC as background characterization algorithms. After this, DR linked TD with background characterization is implemented to find out the best DR linked TD algorithm that gives minimal/no loss of target data.

(d) *DR linked subpixel TD in Dataset 2* One part of target under consideration (Y1) in on subset S2 is a mixture of yellow felt and yellow cotton. Thus, for subpixel TD and to find their respective compositions in Y1, spectral unmixing is done using LMM. Once their respective abundance fractions are retrieved, a new table is reconstructed for Y1 in the format of actual placement of blocks at the time of data collect. Then, based on chosen threshold values, subpixel TD results are evaluated.

Next, Spectral unmixing using LMM is performed without DR without background characterization on S2. Again, after computation of abundance fractions, values for detection for yellow felt and yellow cotton are obtained. Results of subpixel TD with DR is then compared to results obtained without DR.

Table 3 Summary of Dimensionality reduction algorithms

Algorithm	Introduction	Process	Merits	Demerits
PCA	PCA states that neighbouring bands of all hyperspectral images are highly correlated and give almost same information about a target. It aims to identify and collect PC's (principal components), and to find their significance by using eigenvalues	High dimensional data is converted to PC's, using Eigen vectors which are orthogonal to each other. PC's are ordered in order of decreasing variance (Harsanyi and Chang 1994). Only first few components which are in direction of maximum variation contain required information and are selected (Koonsanit et al. 2012)	Number of PC's are less than the total number of bands. Bands retained are identified by accumulated sum of variance and eigenvalues	High computational cost, memory requirement is high (Zabalza et al. 2014) *Not effective in the case of small targets* (Ramakrishna et al. 2005; Chang 2003; Chang and Du 2004)
ICA	*ICA assumes that* spectra of components in any pixel is not related and presence of one substance in a mixed pixel should not interfere with scattering of another, regardless of quantity in which they appear. *It finds statistically independent components and a-priori information about targets is not needed*	ICA transforms the set of randomly mixed signals into corresponding mutually independent components The selection of an Independent Component (IC) is based on its score produced by two measures: skewness and kurtosis (Wang and Chang 2006)	*Proves effective in case of small targets*	Selection of desired components is challenging for any application. Very less work is reported in the literature on how to prioritize and select IC's based on exploitation criteria (Wang and Chang 2006)
MNF	MNF works on the principle of computing the eigen vectors and maximizing signal-to-noise ratio. Once the Eigenvectors are computed, individual covariance matrices are created. Noise levels are obtained from PCA of the covariance matrices	Decomposition of a signal into components is done on basis of ratio of noise to signal power (Kruse et al. 2003). Larger values of eigenvectors identify signal components which exhibit highest noise fractions, while smaller eigenvalues identify the opposite	Set of obtained random variables can be truncated to retain only those bands that have useful SNR	*Not effective in case of small targets* ***B***and truncation needs to be done carefully. If result has many bands, too much noise is left in the image. If few bands are left, useful signal may be lost from the image

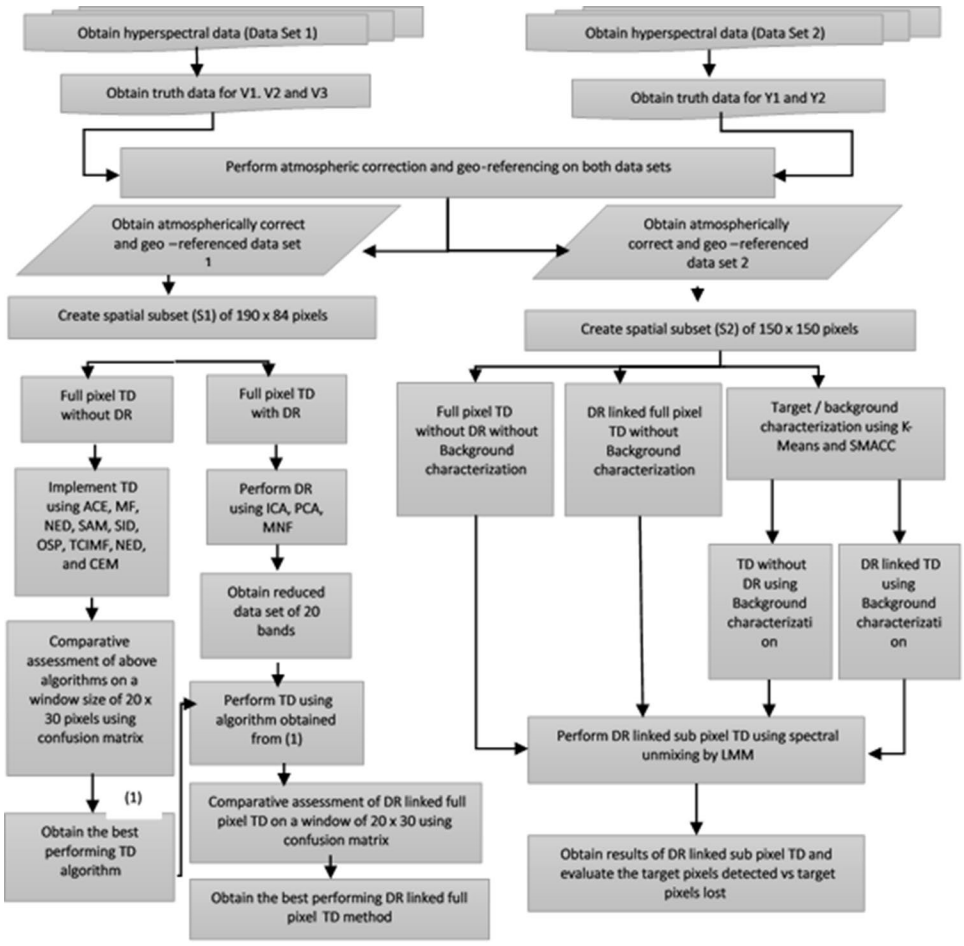


Fig. 8 A flowchart representing the step by step procedure followed for the present study

5 Results and discussions

(a) *Full pixel TD without DR in Dataset 1* TD algorithms: ACE, MF, NED, SAM, SID, OSP, TCIMF, NED, and CEM are implemented on subset S1 using ENVI. Results of computations of the values for TP, FP, TN, and FN for a window of 20×30 pixels have been tabulated in Table 4.

It may be observed from Table 4 that ACE detects all nine target pixels of V1, V2, V3 with very less FP. However, MF detects 9 pixels for V1 and 8 pixels for V2 and V3 (both) with a slight increase in FP. NED and SAM further reduce the detected target pixels to 6 and 7 out of 9 but FPs are much higher. CEM gives the lowest FPs.

Since ACE detects all target pixels with very low FP and outperforms all other algorithms, hence has been chosen further to check results for DR linked TD. Second-best TD algorithm that detects higher number of target pixels, but less FP is MF and is also retained for next step.

(b) *DR linked full pixel TD in Dataset 1* To perform full pixel TD with DR on Dataset 1; ICA, PCA and MNF are implemented on subset S1 and further DR linked TD is carried on dimensionally reduced spectral subset of 20 bands. Accuracy assessment has been done using confusion matrix. Results obtained for a window of 20×30 pixels are shown in Table 5.

Following may be observed from Table 5:

- ICA with ACE detects 7,7,8 target pixels for V1, V2, V3 respectively and gives comparatively much lower false alarms with highest accuracy of detection $\approx 98.33\%$. PCA with ACE detects 7, 8, 7 pixels for V1, V2, V3 respectively but with higher false alarms decreasing the accuracy to 97% (V1, V2) and 94.83% (V3). MNF with ACE detect 7, 8, 8 target pixels for V1, V2, V3 respectively, however, false alarms have increased thus decreasing accuracy to 96.50% (V1), 96.83% (V2) and 95.83% (V3).
- On the other hand, these DR algorithms when linked with MF, exhibit a very sharp decrease in detection of target

Table 4 Full pixel TD results for 126 bands and window of size 20×30 pixels in Subset S1 of Dataset 1

Sr. No	TD algorithm	Target ID's	TP (targets)	FN (loss)	FP (alarms)	TN
1	ACE	V1	9	0	1	590
		V2	9	0	2	589
		V3	9	0	2	589
2	MF	V1	9	0	2	589
		V2	8	1	3	588
		V3	8	1	2	589
3	NED	V1	7	2	21	570
		V2	6	3	45	546
		V3	6	3	131	460
4	SAM	V1	6	3	30	561
		V2	7	2	49	542
		V3	6	3	89	502
5	SID	V1	7	2	35	556
		V2	6	3	46	545
		V3	4	5	47	544
6	OSP	V1	4	5	29	562
		V2	4	5	16	575
		V3	4	5	38	553
7	TCIMF	V1	4	5	84	507
		V2	4	5	143	448
		V3	3	6	75	516
8	CEM	V1	4	5	321	270
		V2	3	6	291	300
		V3	6	3	423	168

Table 5 DR linked TD results and their assessment using a window of size 20×30

Sr. no	DR algorithm	TD algorithm	Target ID's	Number of bands selected out of 126	TP (targets)	FP (alarms)	FN (loss)	TN	Accuracy (%)
1	ICA	**ACE**	**V1**	**20**	**7**	**4**	**2**	**587**	**97.83**
			V2		**7**	**7**	**2**	**584**	**98.33**
			V3		**8**	**1**	**1**	**590**	**98.33**
		MF	V1	20	3	13	6	578	96.83
			V2		4	21	5	570	95.00
			V3		7	20	2	571	95.33
2	PCA	ACE	V1	20	7	5	2	586	97.00
			V2		8	9	1	582	97.00
			V3		7	22	2	569	94.83
		MF	V1	20	4	19	5	572	95.50
			V2		8	18	1	573	95.67
			V3		4	27	5	564	94.17
3	MNF	ACE	V1	20	7	11	2	579	96.50
			V2		8	12	1	579	96.83
			V3		8	16	1	575	95.83
		MF	V1		1	23	8	568	94.67
			V2	20	8	19	1	572	95.50
			V3		3	34	6	557	93.00

pixels. Accuracy of ≈95% is achieved for PCA with MF, around 94% in case of MNF with MF, however, ICA with MF still performs better (than MNF or PCA) with accuracy ≈96%.

- Thus, it appears that ICA performs better for DR assuring minimal loss of target data and higher accuracy after applying ACE for TD.

A comparison of Table 4 (TD without DR) with Table 5 (TD with DR), shows that there is reduction in detected target pixels in case of TD with DR. In the case of TD using ACE without DR, number of target pixels detected successfully are 9 for V1, V2, V3 respectively. When same TD algorithm is applied after ICA, there is a loss of 2 target pixels for V1, V2 and 1 pixel for V3. Results give us a platform for usage of ICA linked ACE as a better DR linked TD algorithm ensuring minimal loss of target data.

(c) *DR linked full pixel TD in Dataset 2 with and without background characterization* TD is achieved on subset S2 of Dataset 2, in which, first part of selected target is subpixel target (a mixture of yellow felt and yellow cotton) and total number of pixels of is 64 pixels. Second part of the target which is a full pixel target (a yellow felt), occupies 25 pixels in the image. Therefore, total target pixels under considerations are 89 pixels. First, TD is performed on atmospherically corrected and georeferenced data using MF, TCIMF, SAM, ACE, SID, CEM, NED and OSP. Results are shown in Table 6.

Table 6 Full pixel TD results for 360 bands, targets, and a window of size 20×30 pixels in Dataset 2, without DR and without background characterization

Sr. no	TD algorithm	TP (targets)	FN (loss)	FP (alarms)	TN
1	MF	71	18	3	508
2	TCIMF	67	22	4	507
3	SAM	60	29	1	510
4	ACE	55	34	3	508
5	SID	42	47	2	509
6	CEM	60	29	76	435
7	NED	44	45	13	498
8	OSP	44	45	121	390

MF detects 71 out of total 89 pixels with very less false alarms (3 pixels) and a loss of 18 target pixels. TCIMF gives loss of 22 pixels with false alarms of 4. With SAM, the detection further reduces to 60 target pixels with false alarm of 1. However, with ACE and SID, the detection reduces to 55 and 42 pixels respectively, thereby incurring an increased loss of target pixels. Based on these observations, MF, TCIMF and SAM are chosen further for DR linked TD. TD is carried out in two steps, using background characterization (SMACC and K-means) and without using background characterization. Results for DR linked TD without background characterization are shown in Table 7.

Following may be observed from the results of Table 7:

- MNF with MF detects 67 target pixels and 8 false alarms attaining an accuracy of 95%, which is reduced to 94.83% in MNF with TCIMF and false alarms increase to 11. With SAM, number of target pixels retained observe an increase with 73 pixels, however, false alarms increase further to 21 pixels reducing the accuracy to 93.83%. Thus, MNF with MF provides better results of detection and minimal loss of target data.
- ICA with MF delivers highest accuracy of 94% with successful detection of 66 target pixels. ICA with TCIMF attains accuracy of 93.17% while ICA with SAM detects 69 target pixels; higher than MF and TCIMF, but with 17 false alarms.

Table 7 DR linked TD results for targets and their assessment using a window of size 20×30—Dataset 2 and without background characterization

Sr. no	DR algorithm	TD algorithm	Number of bands selected out of 360	TP (targets)	FP (alarms)	FN (loss)	TN	Accuracy (%)
1	MNF	MF	20	67	8	22	503	95.00
		TCIMF	20	69	11	20	500	94.83
		SAM	20	73	21	16	490	93.83
2	ICA	MF	20	66	13	23	498	94.00
		TCIMF	20	59	11	30	500	93.17
		SAM	20	69	17	20	494	93.83
3	PCA	MF	20	66	7	23	504	95.00
		TCIMF	20	40	11	49	500	90.00
		SAM	20	35	10	54	501	89.33

- PCA with MF gives 95% accuracy, TCIMF delivers accuracy of 90% and SAM performs poorly in this case with 89.33% accuracy.
- Thus, with DR linked TD, MNF outperforms as DR; and MF outperforms as TD algorithm by providing better results of detection.

TD is next carried on by defining and submitting background spectra using SMACC and K-means. Background spectra for six end members are retrieved in both the cases and have been considered for a window size of 20 × 30 pixels. Spectra that have been obtained for background endmembers for both SMACC and K-means are shown in Fig. 9a, b.

Background characterization is done followed by TD using MF, TCIMF and SAM without DR. Results obtained for this study are shown in Table 8.

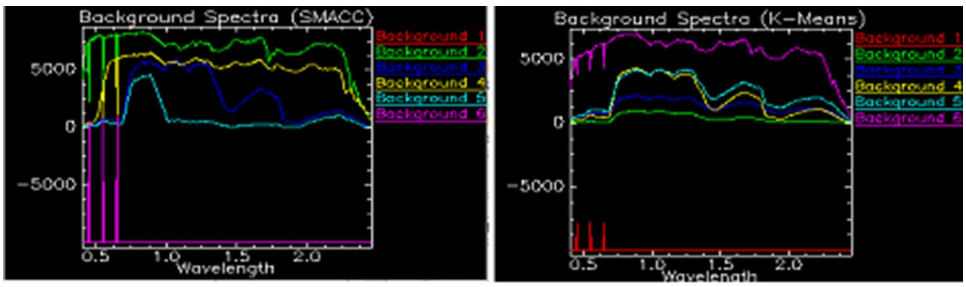
Following may be observed from Table 8:

- MF using SMACC gives lower accuracy (94%) as compared to K-means which gives an accuracy of 94.67%.
- TCIMF retains fewer target pixels with both SMACC and K-means i.e. 40 pixels and 52 pixels, i.e. with a loss of 49 pixels and 37 pixels respectively.
- SAM performs better with detection of 66 and 68 target pixels for SMACC and K-means respectively with false alarms of 16 pixels in each case. The false alarms are higher than that for MF, thereby reducing the accuracy to 93.5% (SMACC) and 94.17% (K-means).
- K-means here retains more target pixels in all cases as compared to SMACC.

DR linked TD is then implemented using ICA, MNF, and PCA as DR algorithms and MF, TCIMF, and SAM as TD algorithms. Detection process was aided using the background characterization and results using both SMACC and K-means and further, TD results have been shown in Tables 9 and 10 respectively.

Following may be observed from the above Table 9:

- While using background characterization with SMACC, with DR as MNF and with TD as MF, 67 target pixels are retained (in comparison to TD without DR which is 71 pixels) at an accuracy of 95%. With TCIMF, accuracy is 93.33% while SAM on the other hand gives accuracy of 94.83%. Thus, SAM performs better with DR as compared to SAM without DR.
- With ICA and MF, accuracy reduces to 94.67%, which reduces further to 91.83% in case of TCIMF. With SAM, however, target pixels retained are 68 but alarms increase to 13 which reduces accuracy to 94.33%.
- With PCA, accuracy with SAM is reduced to 90.83% but with MF it is 95.13%. TCIMF performs poorly in this case. Thus, SAM with DR as MNF, detects more target



(a) (b)

Fig. 9 Background spectra obtained after **a** SMACC and **b** K-means

Table 8 TD results and their assessment using a window of size 20 × 30 pixels—Dataset 2 with background characterization using SMACC and K-means

Sr. no	TD algorithm	Background characterization using SMACC and K-means	Number of bands selected out of 360	TP (targets)	FP (alarms)	FN (loss)	TN	Accuracy (%)
1	MF	SMACC	**20**	**66**	**13**	**23**	**498**	**94.00**
		K-means		**68**	**11**	**21**	**500**	**94.67**
2	TCIMF	SMACC	**20**	40	15	49	496	89.33
		K-means		52	14	37	497	91.50
3	SAM	SMACC	**20**	66	16	23	495	93.50
		K-means		68	16	21	495	94.17

Table 9 DR linked TD results for target—yellow felt and their assessment using a window of size 20×30 pixels—Dataset 2 and background characterization using SMACC

Sr. no	DR algorithm	TD algorithm	Number of bands selected out of 360	TP (targets)	FP (alarms)	FN (loss)	TN	Accuracy (%)
1	MNF	MF	20	67	8	22	503	95.00
		TCIMF	20	53	4	36	507	93.33
		SAM	20	68	10	21	501	94.83
2	ICA	MF	20	68	11	21	500	94.67
		TCIMF	20	47	7	42	504	91.83
		SAM	20	68	13	21	498	94.33
3	PCA	MF	20	67	6	22	507	95.13
		TCIMF	20	18	6	71	505	87.17
		SAM	20	34	0	55	511	90.83

Table 10 DR linked TD results for target—yellow felt and their assessment using a window of size 20×30 pixels—Dataset 2 and background characterization using K-means

Sr. no	DR algorithm	TD algorithm	Number of bands selected out of 360	TP (targets)	FP (alarms)	FN (loss)	TN	Accuracy (%)
1	ICA	MF	20	67	0	22	511	96.33
		TCIMF	20	59	3	30	508	94.50
		SAM	20	68	13	21	498	94.33
2	MNF	MF	20	70	15	19	496	94.33
		TCIMF	20	55	0	34	511	94.33
		SAM	20	68	10	21	501	94.83
3	PCA	MF	20	68	11	21	500	94.67
		TCIMF	20	60	0	29	511	95.17
		SAM	20	34	0	55	511	90.83

pixels thereby incurring minimal loss of target data, followed by MF.

- Also, MF, in all the cases (i.e. with DR as MNF, ICA, and PCA) gives nearly consistent results of detection and may also be considered for further TD.

DR linked TD is then performed using background characterization as K-means. The results have been compiled in Table 10.

Following may be observed from Table 10:

- MF with ICA gives accuracy of 96.33%, MF with MNF detects 70 target pixels which is the highest but false alarms are 15 which is reduced in case of SAM to 10 thus increasing accuracy to 94.83%. MF with PCA retains 68 target pixels out of 89 which is highest when PCA is used as a DR algorithm.
- With SAM and ICA, the loss is 21 pixels, but false alarms are 13. TCIMF with ICA performs worst with accuracy of 94.5%. SAM, however, performs the worst with PCA and K-means with a loss of 55 pixels. TCIMF comparatively works better with DR as PCA detecting 60 target pixels.
- So, it may be seen that MF, in all the cases (MNF, ICA, and PCA) gives nearly consistent results with K-means. ICA linked MF gives highest accuracy of the three, but maximum target pixels are retained with MNF + MF (70 pixels out of 89).
- Overall, results of detection are improved with K-Means in comparison to SMACC.

(d) *DR linked subpixel TD in Dataset 2* TD algorithms discussed above detect only yellow felt and assign whole pixel to it. DR chosen for this process is ICA and TD chosen is MF, based on results obtained for DR linked TD background characterization using K-Means in Table 10. Target under consideration is Y1 as shown in Fig. 10.

A result of performing LMM on a 150×150 spatial subset S2 is shown in Fig. 11:



Fig. 10 Target Y1 under consideration for performing spectral unmixing (Dataset 2)

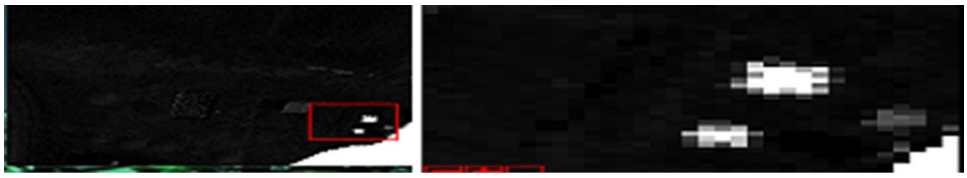


Fig. 11 Unmixing results using LMM on **a** S2 (Dataset 2) and **b** zoom view of Y1 and Y2

Table 11 Fractional composition obtained after LMM of (a) yellow felt in Y1 and (b) yellow cotton in Y1

(a)							
0.71	0.85	0.63	0.83	0.86	0.86	1.04	0.76
0.33	0.76	0.66	0.66	0.77	0.76	0.93	0.76
0.76	0.71	0.28	0.71	0.72	0.88	0.89	0.75
0.71	0.72	0.51	0.5	0.7	0.89	0.9	0.59
0.71	0.76	0.54	0.81	0.81	0.71	0.92	0.78
0.76	0.45	0.45	0.88	0.87	0.91	0.86	0.43
0.71	0.28	0.89	0.86	0.9	0.9	0.91	0.55
0.71	0.71	0.62	0.74	0.71	0.71	0.76	0.76
(b)							
0.34	0.22	0.22	0.23	0.21	0.21	0	0.24
0.79	0.33	0.23	0.23	0.23	0.24	0.07	0.24
0.35	0.21	0.71	0.23	0.23	0.21	0.21	0.25
0.25	0.21	0.23	0.23	0.25	0.21	0.08	0.25
0.26	0.22	0.22	0.23	0.55	0.18	0	0.22
0.2	0.21	0.24	0.21	0.2	0.25	0.21	0.38
0.15	0.15	0.23	0.31	0.3	0.15	0.15	0.23
0.22	0.22	0.25	0.25	0.25	0.21	0.22	0.24

After spectral unmixing, two tables Table 11a, b, have been generated containing abundance fractions of Yellow felt and Yellow cotton respectively in Y1 (8 × 8 pixels).

Based on results, we have tried to reconstruct a table for Y1 (8 × 8 pixels) in the format of the actual placement of yellow felt (75%) and yellow cotton (25%) blocks at the time of data collect. Table 12 shows the fractional compositions of both yellow felt and yellow cotton in the 8 × 8 pixels in subset S2.

Now, we randomly set the value of target detected to be 1 if fractional abundances are greater than 0.40% for Yellow felt and greater than 0.10% for yellow cotton in every pixel; otherwise the value is set to 0. Formulated values are shown in Table 13. The results, however, may vary for different values of threshold.

Based on these values the subpixel TD results are:

Yellow felt	Target pixels detected = 61/64, target pixels not detected = 03/64,
Yellow cotton	Target pixels detected = 60/64, target pixels not detected = 04/64.

Next, spectral unmixing using LMM is performed without DR and without background characterization on same subset. Results obtained for Yellow felt and Yellow cotton have been shown in Table 14a, b respectively.

Based on the results, again a table for Y1 (8 × 8 pixels) has been reconstructed in format of the actual placement of yellow felt (75%) and yellow cotton (25%) blocks at the time of data collect. Table 15 shows fractional

Table 12 Fractional compositions of both yellow felt and yellow cotton in the 8×8 pixels in subset S2

.71 .34	.85 .22	.63 .22	.83 .23	.86 .21	.86 .21	1.04 0	.76 .24
.33 .79	.76 .33	.66 .23	.66 .23	.77 .23	.76 .24	.93 .07	.76 .24
.76 .35	.71 .21	.28 .71	.71 .23	.72 .23	.88 .21	.89 .21	.75 .25
.71 .25	.72 .21	.51 .23	.50 .23	.70 .25	.89 .21	.90 .08	.59 .25
.71 .26	.76 .22	.54 .22	.81 .23	.81 .55	.71 .18	.92 0	.78 .22
.76 .20	.45 .21	.45 .24	.88 .21	.87 .20	.91 .25	.86 .21	.43 .38
.71 .15	.28 .15	.89 .23	.86 .31	.90 .30	.90 .15	.91 .15	.55 .23
.71 .22	.71 .22	.62 .25	.74 .25	.71 .25	.71 .21	.76 .22	.76 .24

Table 13 Values corresponding to target detected / not detected in the 8×8 pixels panel

1 1	1 1	1 1	1 1	1 1	1 1	1 0	1 1
0 1	1 1	1 1	1 1	1 1	1 1	1 0	1 1
1 1	1 1	0 1	1 1	1 1	1 1	1 1	1 1
1 1	1 1	1 1	1 1	1 1	1 1	1 0	1 1
1 1	1 1	1 1	1 1	1 1	1 1	1 0	1 1
1 1	1 1	1 1	1 1	1 1	1 1	1 1	1 1
1 1	0 1	1 1	1 1	1 1	1 1	1 1	1 1
1 1	1 1	1 1	1 1	1 1	1 1	1 1	1 1

Table 14 Fractional composition obtained after LMM of (a) yellow felt in Y1 and (b) yellow cotton in Y1

(a)							
0.01	0	0.02	0.01	0.18	0.05	0.05	0.03
0.01	0.05	0.1	0.5	0.18	0.36	0.03	0.08
0.01	0.01	0.1	0.64	0.86	0.78	0.43	0.81
0	0.04	0.03	0.36	1	0.96	1	0.49
0	0.01	0.25	1	0.98	1	0.89	0.91
0.02	0.05	0.42	0.94	0.87	1	0.87	0.25
0.02	0.05	0.05	0.26	0.65	0.55	0.87	0.5
0.02	0.02	0.01	0.01	0.08	0.07	0.15	0.01
(b)							
0.02	0	0.03	0.03	0.14	0.01	0.02	0.04
0	0	0	0.03	0.11	0.06	0.14	0.05
0.02	0.02	0.16	0.01	0.08	0.21	0.07	0.19
0	0.05	0.16	0.07	0.07	0.12	0.11	0.28
0.01	0.02	0.01	0.01	0.08	0.06	0.1	0.1
0.01	0.01	0.22	0.03	0.16	0.04	0	0.1
0.02	0.01	0.05	0.22	0.22	0	0.04	0
0	0.01	0.03	0.04	0.03	0.02	0	0.04

compositions of both yellow felt and yellow cotton in 8×8 pixels in subset S2.

Again, by randomly setting value of target detected to be 1 for values of fractional abundances greater than 0.40 for Yellow felt and setting it to 0 for values greater than 0.10 for yellow cotton in every pixel, certain values for detection are obtained as shown in Table 16.

Based on values, subpixel TD results are:

Table 15 Fractional compositions of both yellow felt and yellow cotton in the 8×8 pixels in subset S2

0.01	0.02	0	0	0.02	0.03	0.01	0.03	0.18	0.14	0.05	0.01	0.05	0.02	0.03	0.04
0.01	0	0.05	0	0.1	0	0.5	0.03	0.18	0.11	0.36	0.06	0.03	0.14	0.08	0.05
0.01	0.02	0.01	0.02	0.1	0.16	0.64	0.01	0.86	0.08	0.78	0.21	0.43	0.07	0.81	0.19
0	0	0.04	0.05	0.03	0.16	0.36	0.07	1	0.07	0.96	0.12	1	0.11	0.49	0.28
0	0.01	0.01	0.02	0.25	0.01	1	0.01	0.98	0.08	1	0.06	0.89	0.1	0.91	0.1
0.02	0.01	0.05	0.01	0.42	0.22	0.94	0.03	0.87	0.16	1	0.04	0.87	0	0.25	0.1
0.02	0.02	0.05	0.01	0.05	0.05	0.26	0.22	0.65	0.22	0.55	0	0.87	0.04	0.5	0
0.02	0	0.02	0.01	0.01	0.03	0.01	0.04	0.08	0.03	0.07	0.02	0.15	0	0.01	0.04

Table 16 Values corresponding to target detected / not detected in the 8×8 pixels panel

0	0	0	0	0	0	0	0	0	1	0	0	0	0	0	0
0	0	0	0	0	0	1	0	0	1	0	0	0	1	0	0
0	0	0	0	0	1	1	0	1	0	1	0	1	0	1	0
0	0	0	0	0	1	0	0	1	0	1	1	1	1	1	1
0	0	0	0	0	0	1	0	1	0	1	0	1	1	1	1
0	0	0	0	0	0	1	0	1	0	1	0	1	1	1	1
0	0	0	0	1	1	1	0	1	1	1	0	1	0	0	1
0	0	0	0	0	0	1	0	1	1	1	0	1	0	1	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Yellow felt Target pixels detected = 24/64, target pixels not detected = 40,

Yellow cotton Target pixels detected = 17/64, target pixels not detected = 47.

Following may thus be observed for subpixel TD of Yellow felt (75%) in target Y1:

- *Subpixel TD without DR, without background characterization* 24 out of 64 pixels.
- *Subpixel TD with DR, with background characterization* With ICA, linked TD (MF), using background characterization (K-means), detection improves to 61 pixels out of total 64 target pixels.

Similarly, observations for subpixel TD of Yellow cotton (25%) in target Y1 are:

- *Subpixel TD without DR, without background characterization* 17 out of 64 pixels.
- *Subpixel TD with DR, with background characterization* With ICA, linked TD(MF), using K-Means, detection improves to 60 pixels out of total 64 target pixels.

Thus, it may be seen that subpixel TD with DR provides better results of detection in comparison to results obtained without DR, thereby incurring minimal loss of target data.

6 Conclusion

This research work focusses on studying loss of target information in full pixel and subpixel TD in hyperspectral data with and without DR. A study has been performed on spatial subsets (S1 and S2) from hyperspectral Datasets: Datasets 1 and 2 respectively, involving different targets of interest. All results have been assessed on a window of size 20×30 pixels using confusion matrix for accuracy assessment. It is observed that in case of full pixel TD without DR, ACE appears to outperform all the TD algorithms considered and MF also performs well with the loss of 1 target pixel. On the other hand, in the case of DR linked full pixel TD, there is a greater loss of target information in comparison to the case when only TD is performed. However, in this case, ICA linked ACE performs better than other combinations with an accuracy of ≈98%. When DR linked full pixel TD is studied with and without background characterization on one more dataset, MF is seen to outperform all the TD algorithms for full pixel TD without DR. However, for DR linked full pixel TD, though there is further loss of target pixels, the highest accuracy of 95% is obtained. With SAM and MNF, target pixels retained are even more than that with MF, but the number of false alarms also increase. For full pixel TD without DR using K-means, loss of target data is less

when MF with K-means is implemented while in case of SMACC, the loss of target pixels is either more or remains same in certain combinations. Accuracy is 94.67% for MF and ICA. In case of DR linked full pixel TD with K-means, highest accuracy is 96.33% with MF and ICA. K-means gives improved results of detection as loss of target pixels is lesser. For DR linked subpixel TD, LMM is studied to obtain the fractional composition with and without DR. Loss of target pixels for both subpixel targets: yellow felt and yellow cotton is lesser in comparison to the case where no DR is performed.

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ORIGINAL CONTRIBUTION

Multiobjective Economic Load Dispatch Studies in 2-D and 3-D Space by Particle Swarm Optimization Technique

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Abstract In this paper, three important objectives of power systems—cost of generation (FC), system transmission losses (FL) and environmental emissions (FE)—have been considered. The multiobjective economic load dispatch problem has been formulated using weighting method. The noninferior set for IEEE 5 bus, IEEE 14 bus and IEEE 30 bus systems has been generated using particle swarm optimization technique. The noninferior set obtained has been displayed in 3-D space considering all the three objectives and in 2-D space all the combinations of two objectives, viz. for FC & FL, FC & FE and FL & FE for IEEE 5 bus, IEEE 14 bus and IEEE 30 bus systems. The target point or best compromise solution has been obtained by maximizing the minimum relative attainments of all the objectives.

Keywords Optimization · Maximization of minimum relative attainment · Noninferior set · Ideal point · Target point

Abbreviations

F	Objective function to be optimized
FC	Cost of generation, measured in $/h
FL	Transmission losses, measured in MW
FE	Cost of environmental emission, measured in kg/h
a_i, b_i, c_i	Cost coefficients of ith generator
d_i, e_i, f_i	Emission coefficients of ith generator
P_i	Active power generation of the ith generator
$P_{i\max}$	Maximum power generation limit of ith generator
$P_{i\min}$	Minimum power generation limit of ith generator
P_{D}	Total power demand
Q	Penalty factor
NG	Total number of generators in the system
B_{ij}, B_{oi}, B_{oo}	Loss coefficients
P	Number of particles in the swarm
v_{ij}^{k}	Velocity of jth particle of ith generator at kth iteration
W	Inertia weight factor
C_{p}, C_{g}	Acceleration coefficients
r_{p}, r_{g}	Random numbers between 0 and 1
x_{ij}^{k}	Current position of jth particle of ith generator at kth iteration
$x_{\mathrm{pbest}ij}^{k}$	Personal best position of jth particle of ith generator at kth iteration
$x_{\mathrm{gbest}i}^{k}$	Global best position of swarm for ith generator till kth iteration
IT	Maximum number of iterations
k	Current iteration
$W1$	Weight attached to cost of generation
$W2$	Weight attached to transmission losses
$W3$	Weight attached to environmental emissions
$\mathrm{FC}_{\max}$	Maximum value of cost of generation
$\mathrm{FC}_{\min}$	Minimum value of cost of generation
$\mathrm{FL}_{\max}$	Maximum value of transmission losses
$\mathrm{FL}_{\min}$	Minimum value of transmission losses
$\mathrm{FE}_{\max}$	Maximum value of environmental emission

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FE_{min}	Minimum value of environmental emission
Kount	Function evaluation
τ_C	Minimum relative attainment for cost of generation
τ_L	Minimum relative attainment for transmission losses
τ_E	Minimum relative attainment for environmental emission

Introduction

In this paper, three important objectives of power systems, viz. cost of generation (FC), system transmission losses (FL) and environmental emissions (FE), have been considered for multiobjective economic load dispatch (MELD) problem. Single-objective optimization techniques cannot handle such problems because of conflicting nature of these objective functions. Therefore, multiobjective approach [1–8] should be used for solving such problems. Recently intelligent techniques, viz. GA, PSO, BFO and ant colony, have been used to solve ELD and MELD problems.

Jain et al. [9–11] solved MELD problem by genetic algorithm. Jain et al. [12] suggested an improved version of PSO [ISBPSO] and implemented the same to solve ELD problem.

Jain et al. [13] considered generation cost and transmission losses as the objectives for MELD problem. They generated noninferior set for IEEE 5 bus, IEEE 14 bus and IEEE 30 bus systems by PSO technique and obtained the best compromise solution as the one which gives equal percentage saving for both the objectives. Singh et al. [14] proposed moderate random search algorithm (MRPSO) to solve multiobjective economic load dispatch problem considering fuel cost and emission as the objective functions. They compared MRPSO algorithm with other PSO algorithms and found MRPSO to be the most efficient and fastest of all PSO algorithms.

Abido [15] proposed a novel approach based on strength pareto evolutionary algorithm (SPEA) to solve environmental–economic power dispatch problem, consisting of fuel cost and emission as the objectives. The author implemented the proposed approach on a standard test system and obtained the pareto-optimal test in a single run. Also he found the approach to be superior than classical techniques and could deal with premature convergence. Abido [16] developed pareto-based multiobjective evolutionary algorithms (MOEA) and applied to IEEE 30 bus 6 generator system. They applied fitness sharing niching technique and restricted mating nonniching techniques to deal with premature convergence problem. The author compared three multiobjective evolutionary algorithms NSGA, NPGA, SPEA and found SPEA as the most promising multiobjective evolutionary algorithm. Abido [17] proposed a multiobjective particle swarm optimization (MOPSO) technique to solve environmental/economic dispatch (EED) problem, with cost and emission as objectives. The author generated high-quality pareto-optimal set in single run for cost and emission for IEEE 30 bus 6 generator system and found MOPSO to be superior to linear programming (LP), multiobjective stochastic search technique (MOSST) and strength pareto evolutionary algorithm (SPEA).

Rey et al. [18] proposed a revised version of micro-MOPSO, i.e. micro-time variant multiobjective particle swarm optimization (micro-TVMOPSO) and applied to 24 benchmark functions and for study of a residential solar thermal system consisting of two conflicting objective functions—the life cycle cost and energy use. Shankar et al. [19] suggested application of PSO and CPSO to study the power system economic load dispatch with ramp rate limit constraints. Hadji et al. [20] proposed time varying acceleration-based particle swarm optimization [TV-PSO] for solving environmental economic dispatch problem. They implemented the proposed algorithm to IEEE 30 bus system and compared the proposed algorithm with PSO, NSGA-II and SPEA and found the proposed algorithm to be the most efficient and robust. Taheri et al. [21] suggested multiobjective economic load dispatch problem by considering environmental pollution for 6 generating units using particle swarm optimization algorithm. The best solution was obtained by fuzzy decision function. Kumar et al. [22] suggested review on heuristic technique for solution of combined economic and emission dispatch (CEED) problem using 22 papers from 1997 to 2015. Yu et al. [23] proposed ensemble multiobjective differential evolution algorithm (EMODE) to solve economic and emission dispatch problem for 6 generators. Results were compared with PSO, DE, recursive and improved recursive. This algorithm accelerates optimization with population diversity. Poornima et al. [24] suggested A-loss coefficient method to calculate the transmission losses. A-loss coefficients are derived from the load flow analysis using perturbation method. Weighted sum method and strength pareto genetic algorithm are used to solve MOELD problem for 6 generating units. Mohammadian et al. [25] suggested the new evolutionary PSO by incorporating the three operators mutation, crossover and selection to enable the search process to skip local optimal points and enhance computational efficiency. To improve the exploration and exploitation for smooth convergence, dynamic inertia weight, cognitive and social weight coefficients have been included.

Ideal point (I.P.) is one where all the objectives achieve their minimum values simultaneously, i.e. I.P. is defined as (FC_{min}, FL_{min}, FE_{min}). However, it is an infeasible point and cannot be achieved in practice. In multiobjective optimization problems, noninferior set is generated which includes many alternatives all of which are candidate for the target point (T.P.). These must be traded off against each other in moving from one alternative to another, and a strategy has to be adopted to achieve the optimum values. The preferred alternative is called target point or the best compromise solution. In this paper, it has been obtained by maximizing minimum relative attainments of all the objectives.

Particle swarm optimization

PSO [26, 27] is one of the intelligent optimization techniques and is recently being used for various optimization applications. PSO has four main variants—cognitive component, social component, inertia weight and velocity of particles. In an n-dimensional search space, velocity of particles is represented by

$$v_{ij}^{k+1} = W * v_{ij}^{k} + C_{\mathrm{p}} r_{\mathrm{p}} \left(x_{\mathrm{pbest}ij}^{k} - x_{ij}^{k} \right) + C_{\mathrm{g}} r_{\mathrm{g}} \left(x_{\mathrm{gbest}ij}^{k} - x_{ij}^{k} \right) \tag{1}$$

where $i = 1, 2,\ldots, \mathrm{NG}$; $j = 1,2,\ldots, P$.

Position of particles is updated by the following equation

$$x_{ij}^{k+1} = x_{ij}^{k} + v_{ij}^{k+1} \quad i = 1, 2\ldots\mathrm{NG};\ j = 1, 2, \ldots, P \tag{2}$$

Formulation of MELD Problem

The three aspects of the multiobjective economic load dispatch in 3-D space are:

(1) To minimize the cost of generation
(2) To minimize the system transmission losses
(3) To minimize the environmental emission

The MELD problem in 3-D space is to

$$\text{Minimize}\quad F = [\mathrm{FC}, \mathrm{FL}, \mathrm{FE}] \tag{3}$$

Subject to the constraints

Equality constraint

$$\sum_{i=1}^{\mathrm{NG}} P_i = P_{\mathrm{D}} + \mathrm{FL} \tag{4}$$

Inequality constraint

$$P_{i\min} \le P_i \le P_{i\max} \quad i = 1, 2, \ldots, \mathrm{NG} \tag{5}$$

The objective function (F) to be minimized is formulated as the weighted sum of objectives.

$$F = W1 * \mathrm{FC} + W2 * \mathrm{FL} + W3 * \mathrm{FE} + Q * (\mathrm{FL} + P_{\mathrm{D}} - \sum P_i) \tag{6}$$

$$\mathrm{FC} = \sum_{i=1}^{\mathrm{NG}} a_i P_i^2 + b_i P_i + c_i \tag{7}$$

$$\mathrm{FE} = \sum_{i=1}^{\mathrm{NG}} d_i P_i^2 + e_i P_i + f_i \tag{8}$$

$$\mathrm{FL} = \sum_{i=1}^{\mathrm{NG}} \sum_{j=1}^{\mathrm{NG}} P_i B_{ij} P_j \tag{9}$$

Design of Particle Swarm Optimization for MELD

In this paper, PSO has been applied to solve multiobjective economic load dispatch (MELD) problem consisting of three objectives: cost of generation, system transmission losses and environmental emission. Multiobjective economic load dispatch (MELD) problem has been formulated as weighted sum of objectives. The noninferior set has been obtained by systematically varying weights attached to the objectives in the multiobjective function shown in (6). $W1$, $W2$ and $W3$ are the weights attached to the cost of generation function, system transmission losses function and environmental emission function.

There are various ways of measuring time consumed in running a computer program. First, the easiest and obvious method is to consider the time given by the computer. This method includes the time taken for input and output statements along with the time taken for computation. For this reason, it is not a correct measure of computational effort. Further, the time given by the computer for execution of the program depends on technology. We know technology is changing fast. Computers are becoming faster and faster day by day. So, the computational time given by a computer for running a particular program at a particular instant of time cannot be compared with time taken by another computer after some times.

Second, in this case of iterative techniques, the number of iterations have been taken as measure of computational effort by many researchers. This also cannot reflect true computational time because the time taken for each iteration is not same. These facts motivate the authors to devise some other methods of measuring the computational effort. This measure should not depend on the technology or the number of iterations. Any optimization technique involves

calculation of the value of objective function to be optimized. It is done several times before the optimal solution is obtained. This has been considered as the measure of computational effort. It is represented by Kount. This represents the number of time a function has been evaluated during the optimization process.

The design of PSO for multiobjective economic load dispatch (MELD) problem is as under:

(1) Fix the number of particles and generate the particles (generation) and their velocities.
(2) Set values of cost coefficient, loss coefficient and environmental emission coefficient, respectively.
(3) Set the parameters of PSO as under: $P = 40$, $r_p = 0.4$, $r_g = 0.5$, C_p, $C_g = 2$, $W = 0.6$ $Q = 1000$, IT = 1000, $\varepsilon = 10\text{^}(-6)$
(4) Input weights $W1$, $W2$ and $W3$ are assigned to cost of generation, system transmission losses and environmental emission functions, respectively. Program has been run for various values of these parameters.
(5) Calculate the losses for each particles.
(6) Calculate value of MELD function F for each particle at zeroth iteration, and this is equal to personal best value of PSO, i.e. $x^k_{\text{pbest}ij}$. Search the minimum value of function $x^k_{\text{gbest}i}$ at zeroth iteration.
(7) Increase iteration count $k = k + 1$ and function evaluation Kount = Kount + 1.
(8) Update the velocity using (1). Check the limits if the generation is violated, fix the generation to the limit violated. The upper and lower velocity limits have been fixed to $P_{i\max}/2$, $-P_{i\min}/2$, respectively.
(9) Calculate the new position of each particles for each iterations. Check the limits if the generation is violated, fix the generation to the limit violated. The upper and lower generation limits have been fixed to $P_{i\max}$, $P_{i\min}$, respectively.
(10) Calculate MELD function value for new (position) generations generated. Update $x^k_{\text{pbest}ij}$ and $x^k_{\text{gbest}i}$.
(11) Check difference of two consecutive iteration so that difference should not be less than (10^(−6)).If it is less than ($\varepsilon = 10\text{^}(-6)$) go to step 13, else go to 7.
(12) Check equality constraint, if its sum is less than ε, go to step 13, else go to step 7.
(13) Output the value of FC, FL, FE, number of iterations, Kount, $W1$, $W2$ and $W3$.
(14) Select the target point or best compromise solution by maximizing the minimum relative attainments of all the objectives.

This design of PSO for MELD problem has been depicted in the form of flow chart in Fig. 1.

Computational Results

Tables 1, 2 and 3 show the results of multiobjective economic load dispatch (MELD) and corresponding minimum relative attainments for IEEE 5 bus, IEEE 14 bus and IEEE 30 bus system, respectively, in 3-D space.

Columns (2), (3) and (4) of Tables 1, 2 and 3 show the weights $W1$, $W2$ and $W3$, respectively. Columns 5, 6 and 7 show the noninferior set. Columns (8), (9) and (10) show the minimum relative attainments of cost of generation (τ_C), transmission losses (τ_L) and environmental emissions (τ_E), respectively. The column (11) shows the sum of minimum relative attainments of all the objectives. Columns (12) and (13) show the Kount (function evaluation) required to minimize the function, and column (13) shows the number of iteration required to complete the optimization. In this paper, target point has been achieved by maximization of minimum relative attainments method. This method assumes that all the objectives are being minimized and seeks the solution which maximizes the minimum relative attainment, $\tau_i(x)$ by any objective $Z_i(x)$ of its ideal reference value $Z_{i\min}$ relative to its worst feasible value Z_i^{worst}.

$$\tau_i(x) = (Z_i(x) - Z_i^{\text{worst}})/(Z_{i\min} - Z_i^{\text{worst}}) \quad i = 1, 2, 3 \ldots h \tag{10}$$

where h = no. of objectives.

Following observations are made from Table 1.

FC_{max} = 762.753 \$/h, FL_{max} = 5.18346 MW, FE_{max} = 129.646 kg/h.
FC_{min} = 760.960 \$/h. FL_{min} = 5.059 MW, FE_{min} = 120.700 kg/h.

Ideal point is one where all the objectives attain their minimum value. From this table, ideal point for IEEE 5 bus system is: FC_{min} = 760.960 \$/h, FL_{min} = 5.05934 MW and FE_{min} = 120.700 kg/h.

The target point is one for which sum of minimum relative attainments is maximum. It is seen at S. no. 6 of Table 1 and is highlighted. Target point for IEEE 5 bus system in 3-D space is:

FC = 761.643 \$/h, FL = 5.08229 MW, FE = 123.230 kg/h.

Following observations are made from Table 2.

FC_{max} = 1198.268 \$/h, FL_{max} = 8.82141 MW, FE_{max} = 613.6401 kg/h.
FC_{min} = 1135.67 \$/h, FL_{min} = 7.3429 MW, FE_{min} = 492.8321 kg/h.

It is seen that S. no. 12 of Table 2 is the target point for IEEE 14 bus system in 3-D space for which

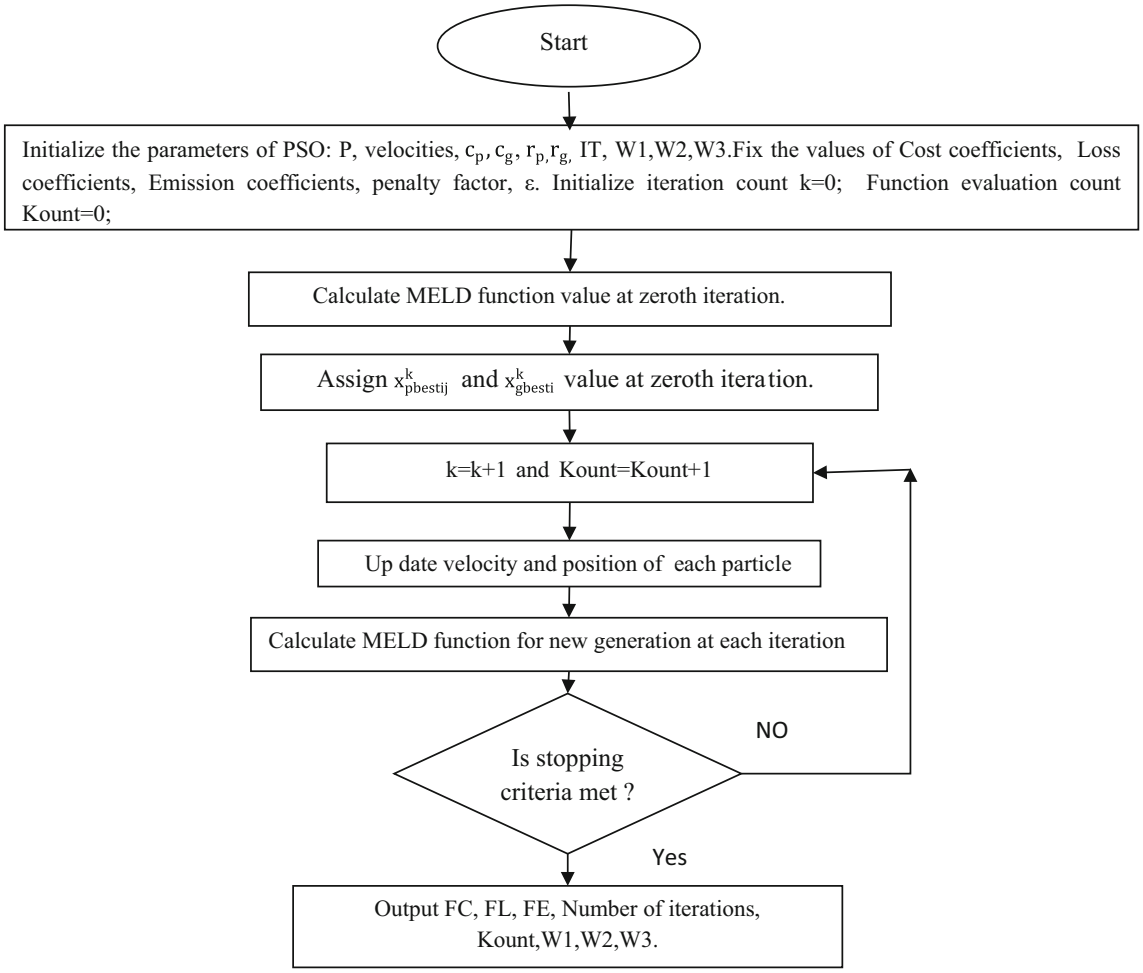


Fig. 1 Flow chart of PSO for MELD

FC = 1162.251 $/h, FL = 7. 349 MW, FE = 503.716 kg/h.

Following observations are made from Table 3. It is seen that S. no. 16 of Table 3 is the target point for IEEE 30 bus system in 3-D space for which FC = 1267.511 $/h, FL = 8.8756 MW and FE = 540.3717 kg/h.

Noninferior set can also be displayed in 3-D space in terms of percentage distance from origin, where origin represents I.P. Columns (8), (9) and (10) of Tables 4, 5 and 6 show the percentage distance of FC, FL and FE from the I.P. for IEEE 5,14 and 30 bus systems, respectively.

Percentage distance from origin along x-axis, y-axis and z-axis has been calculated using following equations:

$$\% \text{ Distance for FC from origin along } x \text{ axis} = ((FC - FC_{min})/(FC_{max} - FC_{min})) * 100$$

$$\% \text{ Distance for FL from origin along } y \text{ axis} = ((FL - FL_{min})/(FL_{max} - FL_{min})) * 100$$

$$\% \text{ Distance for FE from origin along } z \text{ axis} = ((FE - FE_{min})/(FE_{max} - FE_{min})) * 100$$

For IEEE 5 bus system, the noninferior set for all the three objectives has been displayed in 3-D space in Fig. 2 and for various combinations of two objectives—FC–FL, FC–FE and FL–FE have been displayed in Figs. 3, 4 and 5, respectively, in 2-D space.

For IEEE 5 bus system, Fig. 2 shows the variation of cost of generation (FC) on x-axis, transmission losses (FL) on y-axis and environmental emission (FE) on z-axis. The 3-D curve shows the behaviour of FC, FL and FE in 3-D space. It is observed from Table 1 and Fig. 2 that when cost of generation increases, transmission losses as well as environmental emissions decrease. Thus, it is concluded that cost of generation is conflicting with both the objectives—transmission losses and environmental emissions, whereas environmental emissions and transmission losses are supportive in behaviour.

The behaviour of all the three objectives can be explicitly observed in 2-D space from Figs. 3, 4 and 5.

Table 1 Results of MELD and minimum relative attainments in 3-D space (IEEE 5 bus system)

S. no. (1)	*W*1 (2)	*W*2 (3)	*W*3 (4)	FC ($/h) (5)	FL (MW) (6)	FE (kg/h) (7)	τ_C (8)	τ_L (9)	τ_E (10)	$\sum\tau$ (11)	Kount (12)	Iterations (13)
1	100	0	0	760.960	5.18346	129.646	1.00	0.00	0.0000	1.0000	9760	243
2	100	100	0	760.978	5.15993	128.310	1.00	0.19	0.1493	1.3389	9480	236
3	100	200	0	760.999	5.15070	127.770	0.99	0.26	0.2097	1.4636	9440	235
4	100	420	0	761.064	5.13338	126.730	0.98	0.4	0.3259	1.7079	14120	352
5	100	0	10	761.255	5.10753	125.070	0.94	0.61	0.5115	2.0652	21280	531
6	100	0	20	761.643	5.08229	123.230	0.84	0.82	0.7172	2.3678	9320	232
7	100	3500	0	761.913	5.07250	122.380	0.62	0.89	0.8122	2.3251	9400	234
8	100	4600	0	762.039	5.06924	122.064	0.47	0.92	0.8475	2.2362	9320	232
9	118	2800	39	762.060	5.06850	121.992	0.4	0.93	0.8556	2.1802	9400	234
10	100	5000	0	762.085	5.06818	121.954	0.39	0.93	0.8598	2.1751	9640	240
11	100	0	30	762.230	5.06500	121.613	0.37	0.95	0.8979	2.2251	9200	230
12	100	5800	0	762.252	5.06400	121.583	0.29	0.96	0.9013	2.1554	9320	232
13	100	6000	0	762.262	5.06473	121.562	0.28	0.96	0.9037	2.1397	9320	232
14	160	200	77	762.270	5.06400	121.527	0.27	0.96	0.9076	2.1437	9360	233
15	160	40	80	762.310	5.06000	121.452	0.27	0.99	0.9160	2.1801	9440	235
16	160	75	83	762.320	5.06373	121.430	0.25	0.96	0.9184	2.1301	9480	236
17	180	180	95	762.369	5.06308	121.350	0.24	0.97	0.9273	2.1387	9520	237
18	160	70	85	762.440	5.06209	121.200	0.21	0.98	0.9441	2.1360	9440	235
19	0	100	0	762.742	5.05940	120.720	0.17	1	0.9978	2.1719	9200	229
20	0	100	20	762.753	5.05934	120.700	0.01	1	1.0000	2.0061	9520	237

Figure 3 represents the variation of cost of generation (FC) and transmission losses (FL) in 2-D space. The curve shows that when cost of generation increases the transmission losses decrease. That is, FC and FL are conflicting in behaviour. Figure 4 represents the variation of cost of generation (FC) and emission (FE) in 2-D space. The curve shows that when cost of generation increases the emission decreases, i.e. FC and FE are conflicting. Figure 5 represents the variation of transmission losses (FL) and emission (FE) in 2-D space. The curve shows that when the transmission losses decrease, emission also decreases, i.e. FL and FE are supportive in behaviour.

For IEEE 14 bus system, the noninferior set for all the three objectives has been displayed in 3-D space in Fig. 6 and for various combinations of two objectives—FC–FL, FC–FE and FL–FE have been displayed in Figs. 7, 8 and 9, respectively, in 2-D space.

It is observed from Table 2 and Fig. 6 that when cost of generation increases, transmission losses and emissions decrease. Thus, it is concluded that cost of generation is conflicting with both the objectives—transmission losses and environmental emissions, whereas environmental emissions and transmission losses are supportive in behaviour. The behaviour of all the three objectives can be explicitly observed in 2-D space from Figs. 7, 8 and 9. Figure 7 represents the variation of cost of generation (FC) and transmission losses (FL) in 2-D space. The curve shows that when cost of generation increases the transmission losses decrease. That is, FC and FL are conflicting in behaviour. Figure 8 represents the variation of cost of generation (FC) and emission (FE) in 2-D space. The curve shows that when cost of generation increases the emission decreases, i.e. FC and FE are conflicting. When the transmission losses decrease, emission also decreases, i.e FL and FE are supportive in behaviour. Figure 9 represents the variation of transmission losses (FL) and emission (FE) in 2-D space.

For IEEE 30 bus system, the noninferior set for all the three objectives has been displayed in 3-D space in Fig. 10, and for various combinations of two objectives, i.e. FC–FL, FC–FE and FL–FE have been displayed in Figs. 11, 12 and 13, respectively, in 2-D space.

Figure 10 shows the variation of cost of generation (FC) on *x*-axis, transmission losses (FL) on *y*-axis and environmental emission (FE) on *z*-axis. The 3-D curve shows the behaviour of FC, FL and FE in 3-D space. It is observed that cost of generation is conflicting with both the objectives—transmission losses and environmental emission, whereas environmental emission and transmission losses are supportive in behaviour. The behaviour of all the three objectives can be explicitly observed in 2-D space from Figs. 11, 12 and 13. Figure 11 represents the variation of

Table 2 Results of MELD and minimum relative attainments in 3-D space (IEEE 14 bus system)

S. no. (1)	*W*1 (2)	*W*2 (3)	*W*3 (4)	FC ($/h) (5)	FL (MW) (6)	FE (kg/h) (7)	τ_C (8)	τ_L (9)	τ_E (10)	$\sum\tau$ (11)	Kount (12)	Iteration (13)
1	1	1	0	1135.67	8.8214	613.2896	1.0000	0.0000	0.0029	1.0029	7080	88
2	1	0	0	1135.736	8.8143	613.6401	0.9989	0.0048	0.0000	1.0037	8040	100
3	1	5	0	1136.704	8.4788	592.5560	0.9835	0.2317	0.1745	1.3897	7000	87
4	1	10	0	1139.498	8.1192	569.3447	0.9388	0.4750	0.3667	1.7805	6760	84
5	1	20	0	1142.426	7.9063	554.1978	0.8921	0.6190	0.4920	2.0031	7480	93
6	1	30	0	1144.029	7.8340	549.1883	0.8665	0.6679	0.5335	2.0679	8040	100
7	1	10	1	1145.619	7.7277	538.7998	0.8411	0.7398	0.6195	2.2003	7960	99
8	1	20	1	1146.091	7.7225	539.9504	0.8335	0.7433	0.6100	2.1868	7640	95
9	1	5	1	1147.347	7.6986	538.4211	0.8135	0.7595	0.6226	2.1956	8520	106
10	1	30	1	1149.108	7.6105	530.8281	0.7853	0.8190	0.6855	2.2899	7800	97
11	1	1	1	1149.436	7.6256	532.2451	0.7801	0.8088	0.6738	2.2627	8360	104
12	1	20	1	1162.251	7.3495	503.0716	0.5754	0.9956	0.9152	2.4862	7640	95
13	1	40	1	1169.323	7.3503	503.0457	0.4624	0.9950	0.9155	2.3729	7880	98
14	1	50	1	1169.884	7.3430	502.4701	0.4534	1.0000	0.9202	2.3737	7240	90
15	1	30	5	1187.431	7.3584	494.2004	0.1731	0.9896	0.9887	2.1514	7160	89
16	1	50	5	1187.72	7.3494	494.1329	0.1685	0.9956	0.9892	2.1534	6440	80
17	1	40	5	1187.932	7.3491	494.0940	0.1651	0.9959	0.9896	2.1505	7560	94
18	1	20	5	1188.146	7.3653	494.0481	0.1617	0.9849	0.9899	2.1366	6440	80
19	1	5	5	1188.269	7.3660	494.0222	0.1597	0.9844	0.9901	2.1343	7640	95
20	1	10	5	1188.543	7.3659	493.9609	0.1554	0.9845	0.9907	2.1305	7560	94
21	1	1	5	1188.676	7.3705	493.9427	0.1532	0.9814	0.9908	2.1254	7000	87
22	1	30	10	1192.469	7.3692	493.3742	0.0926	0.9823	0.9955	2.0704	7080	88
23	1	5	10	1193.375	7.3827	493.2310	0.0782	0.9732	0.9967	2.0480	6680	83
24	1	0	10	1193.416	7.3837	493.2232	0.0775	0.9725	0.9968	2.0467	6760	84
25	1	1	10	1193.416	7.3837	493.2232	0.0775	0.9725	0.9968	2.0467	6600	82
26	1	10	10	1193.851	7.3797	493.2192	0.0706	0.9751	0.9968	2.0425	7640	95
27	1	5	12	1194.751	7.3949	493.0908	0.0562	0.9649	0.9979	2.0189	7400	92
28	1	5	15	1195.998	7.4210	492.9527	0.0363	0.9472	0.9990	1.9825	6680	83
29	1	1	1	1196.013	7.4214	492.9515	0.0360	0.9469	0.9990	1.9820	8360	104
30	1	30	20	1196.061	7.4042	493.0000	0.0353	0.9586	0.9986	1.9925	7720	96
31	0	0	1	1196.543	7.4033	493.0023	0.0276	0.9592	0.9986	1.9853	6760	84
32	1	10	20	1196.55	7.4126	492.9514	0.0274	0.9529	0.9990	1.9793	5960	74
33	1	5	20	1197.19	7.4288	492.8858	0.0172	0.9419	0.9996	1.9587	7480	93
34	1	0	20	1197.45	7.4241	492.8929	0.0131	0.9451	0.9995	1.9577	7080	88
35	1	0	30	1198.268	7.4487	492.8321	0.0000	0.9285	1.0000	1.9285	6280	78

cost of generation (FC) and transmission losses (FL) in 2-D space. The curve shows that when cost of generation increases the transmission losses decrease. That is, FC and FL are conflicting in behaviour. Figure 12 represents the variation of cost of generation (FC) and emission (FE) in 2-D space. The curve shows that when cost of generation increases the emission decreases, i.e. FC and FE are conflicting. Figure 13 represents the variation of transmission losses (FL) and emission (FE) in 2-D space. The curve shows that when the transmission losses decrease, emissions also decrease, i.e. FL and FE are supportive in behaviour.

Target point using the minimum relative attainments for noninferior set of IEEE 5 bus, IEEE 14 bus and IEEE 30 bus systems has been shown in Figs. 14, 15 and 16, respectively.

Figure 14 represents the variation of minimum relative attainments for cost of generation (τ_C), transmission losses (τ_L) and environmental emissions (τ_E) in 3-D space. The minimum relative attainment of an objective increases with the decrease in the value of that objective. I.P. represents

Table 3 Results of MELD and minimum relative attainments in 3-D space (IEEE 30 bus system)

S. no.	*W*1 (2)	*W*2 (3)	*W*3 (4)	FC ($/h) (5)	FL (MW) (6)	FE (kg/h) (7)	τ_C (8)	τ_L (9)	τ_E (10)	$\sum\tau$ (11)	Kount (12)	Iterations (13)
1	20	1	1	1244.729	10.2626	639.3834	1.0000	0.0000	0.0000	1.0000	5160	64
2	10	1	1	1245.158	10.0756	627.4210	0.9920	0.1300	0.0995	1.2215	6840	85
3	10	0.50	1	1246.079	9.8644	614.3042	0.9749	0.2768	0.2085	1.4603	6680	83
4	1	0	0	1247.792	9.6774	604.7701	0.9430	0.4068	0.2878	1.6377	6680	83
5	1	1	0	1247.792	9.6774	604.7701	0.9430	0.4068	0.2878	1.6377	6840	85
6	1	0	0	1247.794	9.8082	616.8960	0.9430	0.3159	0.1870	1.4459	6680	83
7	1	0.50	0	1247.994	9.7817	614.9666	0.9393	0.3343	0.2030	1.4766	6920	86
8	1	10	0	1248.823	9.6880	608.0366	0.9238	0.3995	0.2607	1.5840	6840	85
9	3	0	1	1248.830	9.5769	597.5952	0.9237	0.4767	0.3475	1.7479	6680	82
10	2	0	1	1249.925	9.4915	591.3659	0.9033	0.5361	0.3993	1.8387	6920	86
11	1	20	0	1252.344	9.4086	585.9975	0.8583	0.5938	0.4439	1.8960	6760	84
12	10	0	3	1253.146	9.3337	579.5993	0.8434	0.6458	0.4971	1.9864	6680	83
13	12	0	4	1255.852	9.1662	565.4351	0.7930	0.7623	0.6149	2.1703	6680	83
14	18	0	9	1261.155	8.9907	550.9842	0.6944	0.8843	0.7351	2.3138	5960	74
15	16	0	9	1262.390	8.9823	549.4007	0.6714	0.8901	0.7483	2.3098	6840	85
16	0	0	1	1267.511	8.8756	540.3717	0.5761	0.9643	0.8233	2.3638	7160	89
17	1	0.5	1	1269.219	8.8970	539.1601	0.5443	0.9495	0.8334	2.3272	6920	86
18	1	200	0	1283.008	8.8865	527.0773	0.2878	0.9568	0.9339	2.1784	7160	89
19	1	200	1	1283.425	8.9171	527.7670	0.2800	0.9355	0.9282	2.1437	7160	89
20	1	0.5	20	1287.813	8.8725	523.4930	0.1984	0.9665	0.9637	2.1286	6920	86
21	1	200	10	1293.343	8.8387	520.3835	0.0955	0.9900	0.9896	2.0751	7160	89
22	1	0.5	30	1295.116	8.8274	519.8162	0.0625	0.9978	0.9943	2.0546	7160	89
23	1	0	40	1298.476	8.8243	519.1279	0.0000	1.0000	1.0000	2.0000	6920	86

Table 4 Noninferior set of IEEE-5 bus system in 3-D space

S. no. (1)	*W*1 (2)	*W*2 (3)	*W*3 (4)	FC ($/h) (5)	FL (MW) (6)	FE (kg/h) (7)	% Distance of FC from origin along *x*-axis (8)	% Distance of FL from origin along *y*-axis (9)	% Distance of FE from origin along *z*-axis (10)
1	100	0	0	760.9600	5.1835	129.6400	0.0000	100.0000	100.0000
2	100	100	0	760.9780	5.1599	128.3100	1.0039	81.0425	85.0688
3	100	200	0	760.9985	5.1507	127.7700	2.1472	73.6062	79.0324
4	100	420	0	761.0640	5.1334	126.7300	5.8003	59.6544	67.4067
5	100	0	10	761.2550	5.1075	125.0700	16.4529	38.8253	48.8503
6	100	0	20	761.6432	5.0823	123.2300	38.1037	18.4902	28.2817
7	100	3500	0	761.9130	5.0725	122.3800	53.1511	10.6026	18.7800
8	100	4600	0	762.0386	5.0692	122.0644	60.1562	7.9762	15.2520
9	118	2800	39	762.0600	5.0685	121.9920	61.3497	7.3800	14.4427
10	100	5000	0	762.0845	5.0682	121.9538	62.7161	7.1221	14.0157
11	100	0	30	762.2300	5.0650	121.6134	70.8310	4.5601	10.2105
12	100	5800	0	762.2519	5.0640	121.5830	72.0524	3.7560	9.8707
13	100	6000	0	762.2622	5.0647	121.5619	72.6269	4.3418	9.6348
14	160	200	77	762.2700	5.0640	121.5270	73.0619	3.7544	9.2447
15	160	40	80	762.3100	5.0600	121.4515	75.2928	0.5317	8.4007
16	160	75	83	762.3200	5.0637	121.4300	75.8505	3.5361	8.1603
17	180	180	95	762.3692	5.0631	121.3503	78.5945	3.0132	7.2694
18	160	70	85	762.4400	5.0621	121.2000	82.5432	2.2188	5.5893
19	0	100	0	762.7420	5.0594	120.7200	99.3865	0.0483	0.2236
20	0	100	20	762.7530	5.0593	120.7000	100.0000	0.0000	0.0000

Table 5 Noninferior set of IEEE-14 bus system in 3-D space

S. no. (1)	*W*1 (2)	*W*2 (3)	*W*3 (4)	FC ($/h) (5)	FL MW (6)	FE (kg/h) (7)	% Distance for FC from origin along *x*-axis (8)	% Distance for FL from origin along *y*-axis (9)	% Distance for FE from origin along *z*-axis (10)
1	1	1	0	1135.6700	8.8214	613.2896	0.0000	100.0000	99.7099
2	1	0	0	1135.7360	8.8143	613.6401	0.1054	99.5205	100.0000
3	1	5	0	1136.7040	8.4788	592.5560	1.6518	76.8269	82.5474
4	1	10	0	1139.4980	8.1192	569.3447	6.1152	52.5016	63.3341
5	1	20	0	1142.4260	7.9063	554.1978	10.7927	38.1022	50.7961
6	1	30	0	1144.0290	7.8340	549.1883	13.3535	33.2112	46.6494
7	1	10	1	1145.6190	7.7277	538.7998	15.8935	26.0236	38.0502
8	1	20	1	1146.0910	7.7225	539.9504	16.6475	25.6696	39.0026
9	1	5	1	1147.3470	7.6986	538.4211	18.6540	24.0531	37.7367
10	1	30	1	1149.1080	7.6105	530.8281	21.4671	18.0959	31.4516
11	1	1	1	1149.1900	7.6295	532.5697	21.5981	19.3797	32.8932
12	1	20	1	1162.2510	7.3495	503.0716	42.4630	0.4390	8.4758
13	1	40	1	1169.3230	7.3503	503.0457	53.7605	0.4990	8.4544
14	1	50	1	1169.8840	7.3430	502.4701	54.6567	0.0000	7.9779
15	1	30	5	1187.4310	7.3584	494.2004	82.6880	1.0445	1.1326
16	1	50	5	1187.7200	7.3494	494.1329	83.1496	0.4378	1.0768
17	1	40	5	1187.9320	7.3491	494.0940	83.4883	0.4127	1.0446
18	1	20	5	1188.1460	7.3653	494.0481	83.8302	1.5079	1.0066
19	1	5	5	1188.2690	7.3660	494.0222	84.0267	1.5593	0.9851
20	1	10	5	1188.5430	7.3659	493.9609	84.4644	1.5532	0.9344
21	1	1	5	1188.6760	7.3705	493.9427	84.6768	1.8614	0.9193
22	1	30	10	1192.4690	7.3692	493.3742	90.7361	1.7732	0.4487
23	1	5	10	1193.3750	7.3827	493.2310	92.1835	2.6844	0.3302
24	1	0	10	1193.4160	7.3837	493.2232	92.2490	2.7546	0.3237
25	1	1	10	1193.4160	7.3837	493.2232	92.2490	2.7546	0.3237
26	1	10	10	1193.8510	7.3797	493.2192	92.9439	2.4873	0.3204
27	1	5	12	1194.7510	7.3949	493.0908	94.3816	3.5096	0.2141
28	1	5	15	1195.9980	7.4210	492.9527	96.3737	5.2813	0.0998
29	1	1	1	1196.0130	7.4214	492.9515	96.3977	5.3062	0.0988
30	1	30	20	1196.0610	7.4042	493.0000	96.4743	4.1410	0.1390
31	0	0	1	1196.5430	7.4033	493.0023	97.2443	4.0823	0.1409
32	1	10	20	1196.5500	7.4126	492.9514	97.2555	4.7110	0.0988
33	1	5	20	1197.1900	7.4288	492.8858	98.2779	5.8089	0.0445
34	1	0	20	1197.4500	7.4241	492.8929	98.6933	5.4870	0.0503
35	1	0	30	1198.2680	7.4487	492.8321	100.0000	7.1490	0.0000

the ideal point (FC_{min}, FL_{min}, FE_{min}) where the relative attainment of each objective is maximum and is equal to 1. In this figure, T.P. represents the target point. At T.P., the relative attainments τ_C, τ_L and τ_E are 0.84, 0.82 and 0.717183, respectively, and FC, FL and FE are 761.643 $/h, 5.082 MW and 123.230 kg/h, respectively. Figure 15 shows the minimum relative attainments of noninferior set of IEEE 14 bus system.

Figure 15 represents the variation of minimum relative attainment for cost of generation (τ_C), transmission losses (τ_L) and environmental emission (τ_E) in 3-D space for IEEE 14 bus system. The minimum relative attainment of an objective increases with the decrease in the value of that objective. I.P. represents the ideal point (FC_{min}, FL_{min}, FE_{min}) where the relative attainment of each objective is maximum and is equal to 1. At T.P. (target point), the relative attainments τ_C, τ_L and τ_E are 0.57, 0.99 and 0.91, respectively. And FC, FL and FE are 1162.25 $/h, 7.349 MW and 503.0716 kg/h, respectively.

Figure 16 shows the minimum relative attainments of noninferior set of IEEE 30 bus system.

Table 6 Noninferior set of IEEE-30 bus system in 3-D space

S. no. (1)	*W*1 (2)	*W*2 (3)	*W*3 (4)	FC ($/h) (5)	FL (MW) (6)	FE (kg/h) (7)	% Distance for FC From origin along *x*-axis (8)	% Distance for FL from origin along *y*-axis (9)	% Distance for FE from origin along *z*-axis (10)
1	20	1	1	1244.729	10.2626	639.3834	0.0000	100.0000	100.0000
2	10	1	1	1245.158	10.0756	627.4210	0.7981	87.0015	90.0525
3	10	0.50	1	1246.079	9.8644	614.3042	2.5117	72.3173	79.1452
4	1	0	0	1247.792	9.6774	604.7701	5.6989	59.3166	71.2170
5	1	1	0	1247.792	9.6774	604.7701	5.6989	59.3166	71.2170
6	1	0	0	1247.794	9.8082	616.8960	5.7026	68.4079	81.3004
7	1	0.50	0	1247.994	9.7817	614.9666	6.0747	66.5691	79.6960
8	1	10	0	1248.823	9.6880	608.0366	7.6171	60.0500	73.9333
9	3	0	1	1248.830	9.5769	597.5952	7.6301	52.3277	65.2507
10	2	0	1	1249.925	9.4915	591.3659	9.6675	46.3874	60.0707
11	1	20	0	1252.344	9.4086	585.9975	14.1682	40.6222	55.6066
12	10	0	3	1253.146	9.3337	579.5993	15.6604	35.4172	50.2861
13	12	0	4	1255.852	9.1662	565.4351	20.6951	23.7699	38.5078
14	18	0	9	1261.155	8.9907	550.9842	30.5617	11.5659	26.4910
15	16	0	9	1262.390	8.9823	549.4000	32.8595	10.9879	25.1742
16	0	0	1	1267.511	8.8756	540.3710	42.3874	3.5658	17.6661
17	1	0.5	1	1269.219	8.8970	539.1601	45.565334	5.054424	16.6586
18	1	200	0	1283.008	8.8865	527.0773	71.220719	4.323464	6.6111
19	1	200	1	1283.425	8.9171	527.7670	71.996577	6.449179	7.1846
20	1	0.5	20	1287.813	8.8725	523.4930	80.160753	3.347274	3.6305
21	1	200	10	1293.343	8.8387	520.3835	90.449700	0.997396	1.0448
22	1	0.5	30	1295.116	8.8274	519.8162	93.748488	0.216862	0.5731
23	1	0	40	1298.476	8.8243	519.1279	100.0000	0.0000	0.00075

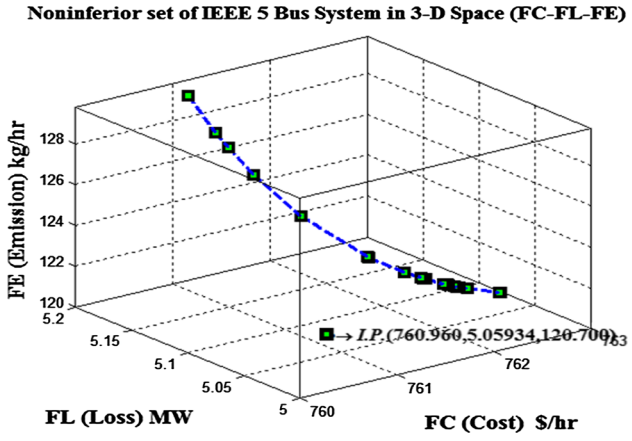


Fig. 2 Noninferior set of IEEE 5 bus system in 3-D

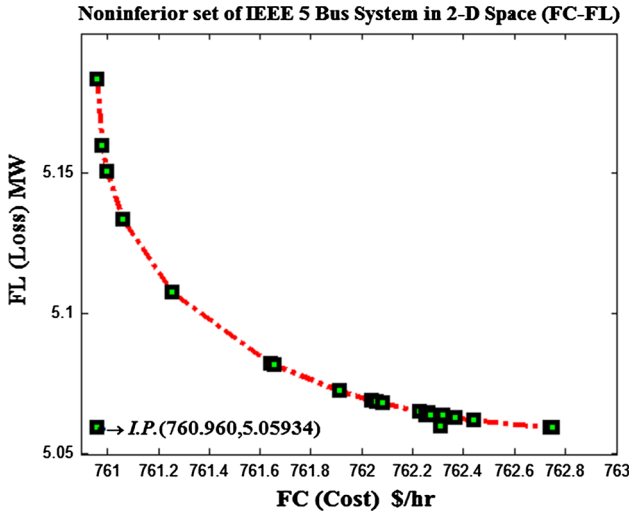


Fig. 3 Noninferior set of IEEE 5 bus system

Figure 16 represents the variation of minimum relative attainment for cost of generation (τ_C), transmission losses (τ_L) and environmental emission (τ_E) in 3-D space. The minimum relative attainment of an objective increases with the decrease in the value of that objective. I.P. represents the ideal point (FC_{min}, FL_{min}, FE_{min}) where the relative attainment of each objective is maximum and is equal to 1. At T.P., the relative attainments τ_C, τ_L and τ_E are 0.576, 0.9643 and 0.8233, respectively, and FC, FL and FE are 1267.511 $/h, 8.8756 MW and 540.376 kg/h, respectively.

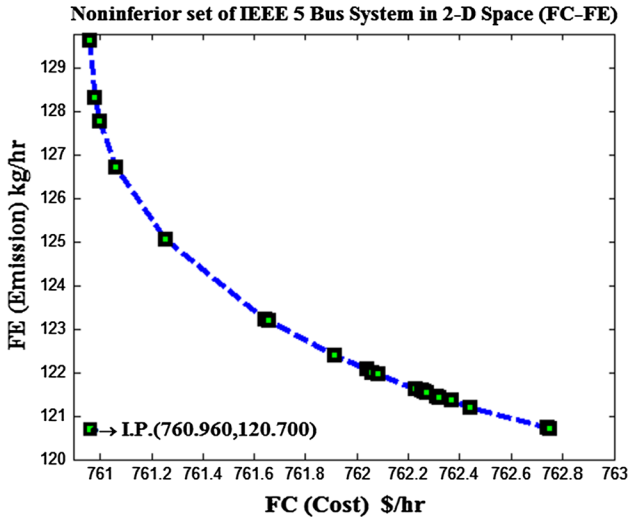


Fig. 4 Noninferior set of IEEE 5 bus system

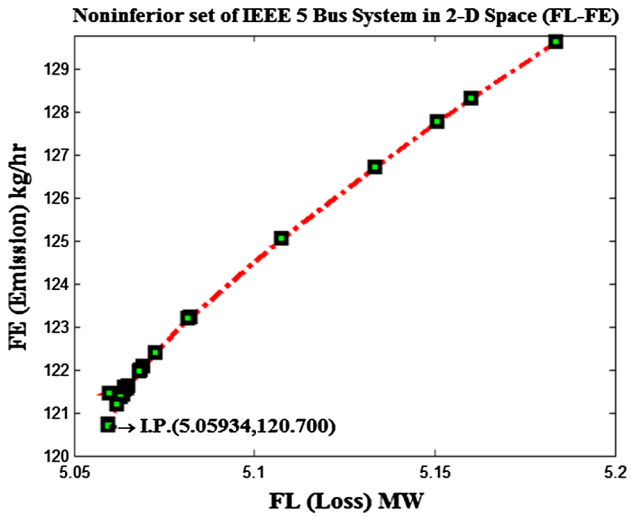


Fig. 5 Noninferior set of IEEE 5 bus system

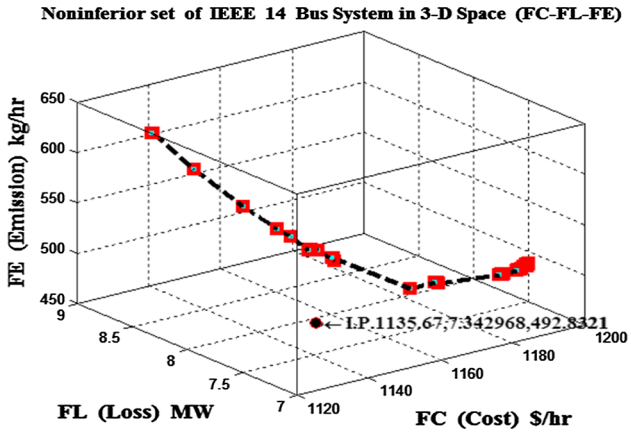


Fig. 6 Noninferior set of IEEE 14 bus system in 3-D

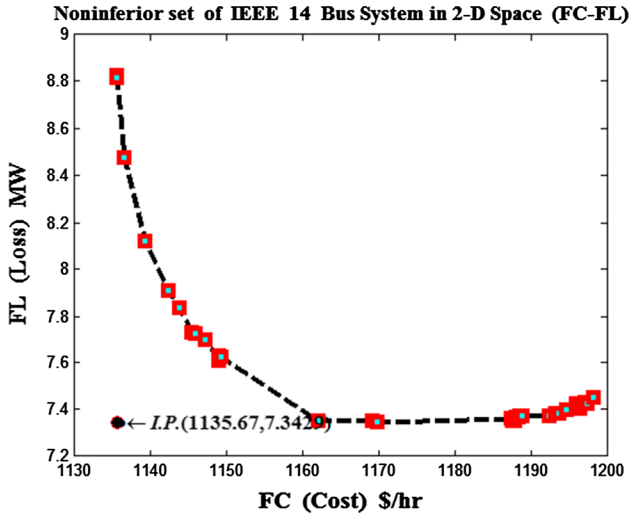


Fig. 7 Noninferior set of IEEE 14 bus system

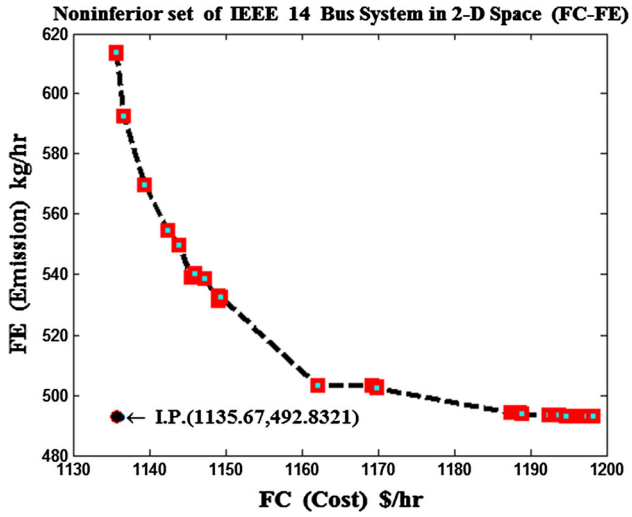


Fig. 8 Noninferior set of IEEE 14 bus system

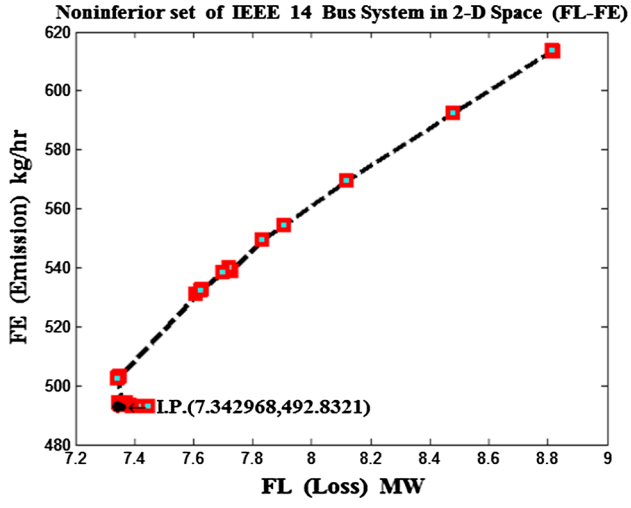


Fig. 9 Noninferior set of IEEE 14 bus system

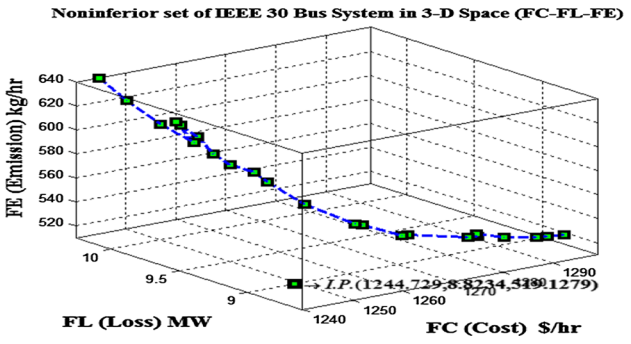


Fig. 10 Noninferior set of IEEE 30 bus system

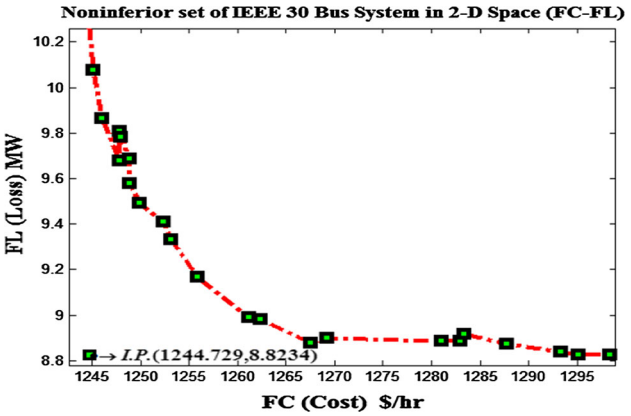


Fig. 11 Noninferior set of IEEE 30 bus system

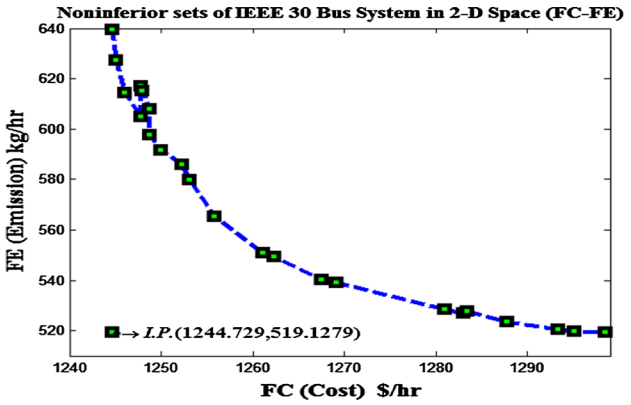


Fig. 12 Noninferior set of IEEE 30 bus system

Noninferior set can also be displayed in 3-D space in terms of percentage distance from origin, where origin represents I.P. Columns (8), (9) and (10) of Tables 4, 5 and 6 show the percentage distance of FC, FL and FE from the I.P. for IEEE 5, 14 and 30 bus systems, respectively. The same has also been displayed in Figs. 17, 18 and 19. Figure 17 shows the noninferior set in terms of percentage distance of each objective from the origin (I.P.) for IEEE 5 bus system.

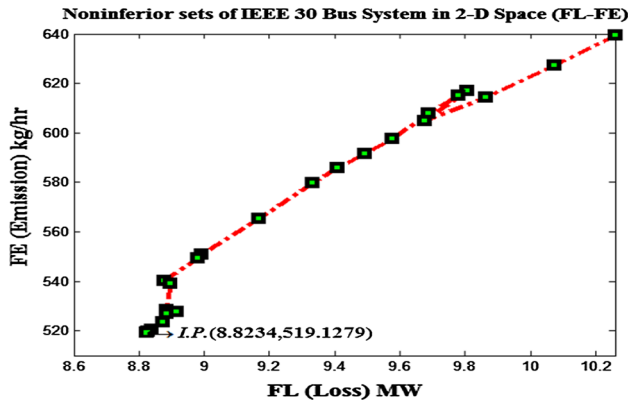


Fig. 13 Noninferior set of IEEE 30 bus system

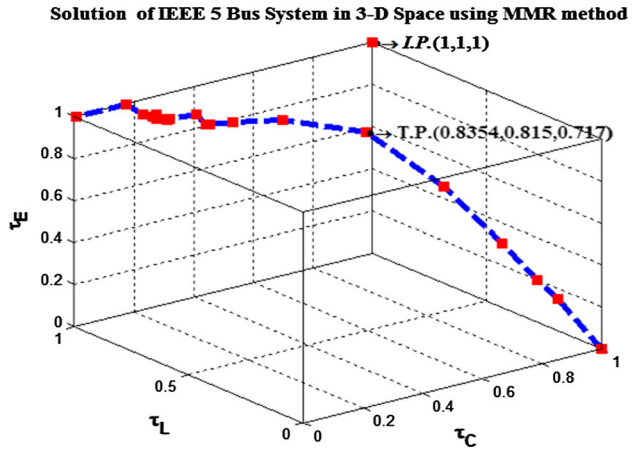


Fig. 14 Minimum relative attainments of noninferior set of IEEE 5 bus system

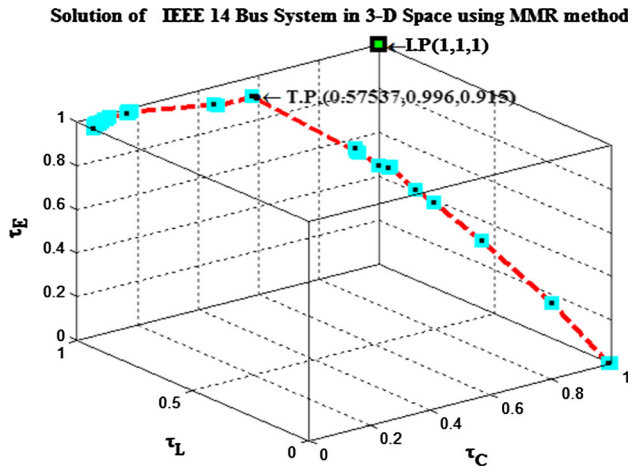


Fig. 15 Minimum relative attainments of noninferior set of IEEE 14 bus system

Figure 18 shows the noninferior set in terms of percentage distance of each objective from the origin (I.P.) for IEEE 14 bus system.

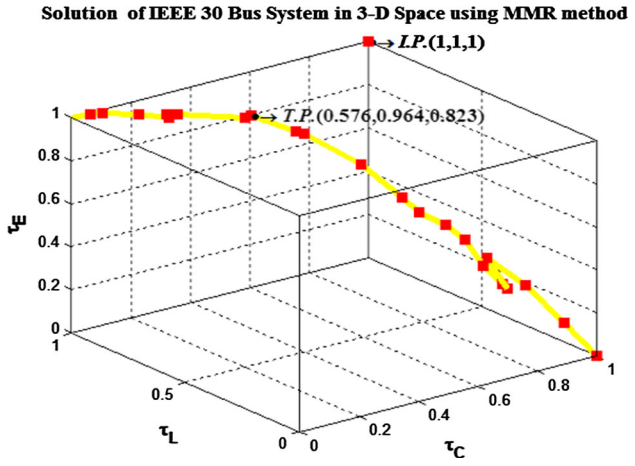


Fig. 16 Minimum relative attainments of noninferior set of IEEE 30 bus system

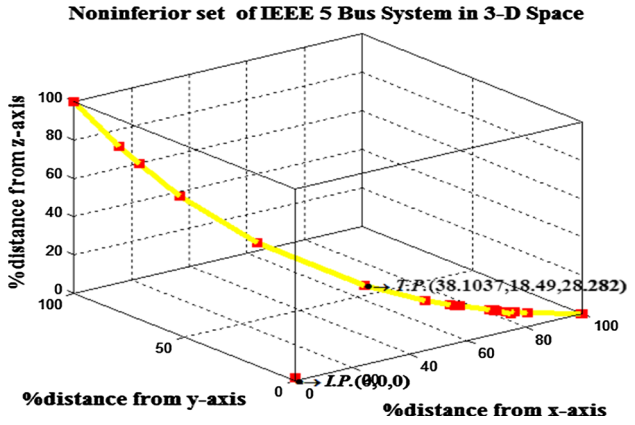


Fig. 17 Noninferior set of IEEE 5 bus system in 3-D space

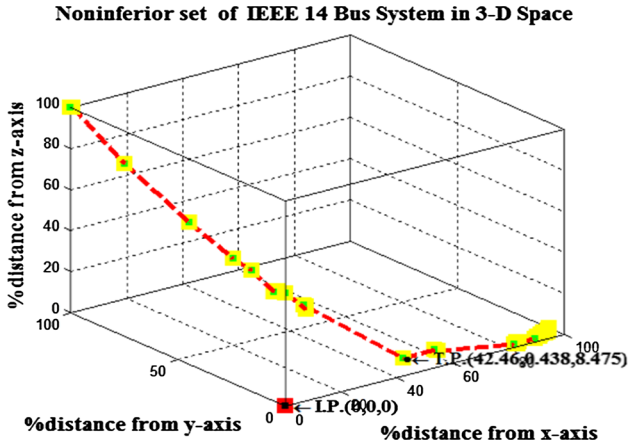


Fig. 18 Noninferior set of IEEE 14 bus system in 3-D space

For IEEE 30 bus system, Fig. 19 shows the noninferior set in terms of percentage distance of each objective from the origin (I.P.).

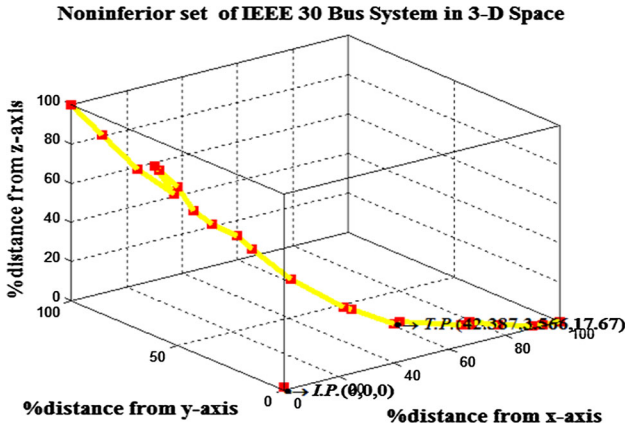


Fig. 19 Noninferior set of IEEE 30 bus system in 3D space

Table 7 shows comparison of target points achieved by GA and PSO algorithms for IEEE 5 bus, IEEE 14 bus and IEEE 30 bus systems.

It is observed from Table 7 that PSO algorithm and GA give comparable results in terms of cost of generation for IEEE 5 bus, 14 bus and 30 bus systems.

Discussion

The ideal points for IEEE 5 bus, 14 bus and 30 bus systems in 3-D space are (760.96 $/h, 5.059 MW, 120.70 kg/h), (1135.67 $/h, 7.34297 MW, 492.8321 kg/h) and (1244.729 $/h, 8.8243 MW, 519.1279 kg/h), respectively. But ideal point is an infeasible point and cannot be achieved in practice. Therefore, the target point has been obtained by maximizing the minimum relative attainments of cost of generation, system transmission losses and environmental emissions. Target points have been displayed in 3-D space by Figs. 14, 15 and 16 for IEEE 5 bus, 14 bus and 30 bus systems, respectively. The noninferior set has also been displayed in 3-D space by Figs. 17, 18 and 19 for IEEE 5 bus, 14 bus and 30 bus system, respectively. 3-D curve drawn in these figures shows the behaviour of the objective functions. From 3-D data, 2-D graphs have also been plotted for FC–FL, FC–FE and FE–FL which explicitly describe the behaviour of objective functions. These graphs confirm that cost of generation is conflicting with transmission losses and environmental emissions, whereas transmission losses and environmental emissions are supportive in behaviour.

Conclusions

Following are the definite contributions of this paper.

Table 7 Target points achieved by GA and PSO algorithms

	IEEE 5 bus		IEEE 14 bus		IEEE 30 bus	
	PSO	GA	PSO	GA	PSO	GA
FC ($/h)	761.643	761.688	1162.251	1163.28	1267.511	1273.65
FL (MW)	5.08229	5.080	7.349458	7.28	8.8756	9.44
FE (kg/h)	123.230	123	503.0716	508	540.3717	538

1. MELD problem has been formulated using weighting method for IEEE 5 bus, 14 bus and 30 bus systems. Noninferior set has been generated by varying the weights attached to cost of generation, system transmission losses and environmental emission. PSO technique has been used to solve the MELD problem.
2. Target point has been achieved by maximizing the minimum relative attainments of all the objectives.
3. Noninferior set has been displayed in 3-D space and 2-D space to study the behaviour of objectives.
4. It is observed that cost of generation and transmission losses, cost of generation and environmental emission are conflicting in behaviour. System transmission losses and environmental emission are supportive in behaviour.

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MVDC Microgrid Protection using a Centralized Communication with a Localized Backup Scheme of Adaptive Parameters

Vaibhav Nougain, Sukumar Mishra, *Senior Member, IEEE*, and Ashok Kumar Pradhan, *Senior Member, IEEE*

***Abstract*—The work proposes a centralized protection scheme with a localized backup for a MVDC microgrid. The centralized scheme is implemented using the percentage differential current approach backed up with a localized scheme employing running autoregressive smoothing average (*RASA*). An adaptive mathematical analysis of the parameters employed is performed for a justified assent. The proposed scheme is ratified to be accurate and immune to the system configuration, voltage fluctuations and high resistance faults with its security, dependability and selectivity validated for different transients and fault contingencies employing minimum solid state circuit breakers (SSCBs) in the microgrid.**

***Index Terms*—MVDC microgrid, centralized protection, localized backup.**

I. Introduction

THE performance, feasibility and acceptability of Renewable Energy Sources (RES) have made the penetration of RES indispensable to the existing power systems [1]. The simplistic integration of RES to form microgrids and the ease of operation of microgrids in both grid-connected and islanded mode have been of great research and industrial interest. The research on DC microgrid has picked up in the recent time over its AC counterpart due to its lesser cost, complexity and higher efficiency employing lesser power electronic devices [2]-[5]. However, considering protection aspect, AC system is backed up with a century of handling experience and standardization and protection of DC microgrids has been a domain of less exploration with inadequate standardization [6]. Protection of DC microgrid is however, a challenging task as the rate of rise of current is high; the power electronic devices are sensitive with their withstanding capability only twice the full load rating [7]; delaying fault interruption by a few milliseconds in the microgrid can lead to system collapse and load detriment(elaborated in section V(A)), explaining the inability of employing ACCBs and isolators for protection. Employing isolators and ACCBs for fault segment isolation entails zero crossing of current in the network to devoid current arcing and DC microgrid does not hold that attribute.

The related literature attempts to overcome the challenges of DC microgrid protection with [8] considering molded case circuit breakers employing over current relays; [9] utilizing voltage and current magnitudes, [10] considering first and second current derivative for fault detection; [11] employing differential current for fault identification depending on relay coordination; [12]-[15] using traveling waves for fault analysis; [16] incorporating a centralized protection based differential current approach backed up with over current relays (OCRs). However, operation of molded case CBs as used in [8] delays fault interruption and can lead to microgrid collapse; coordination of over current relays is a problem and can lead to mal-operation of the relays. However, the delay in the fault interruption can be avoided using SSCBs (high cost; operation time of less than 1ms). The authors of [9]-[10] employ SSCBs for fault segment isolation at all segments of LVDC microgrid making the schemes inviable to implement. Communication failure in [11] takes down the protection scheme leading the microgrid to collapse due to no backup protection. The work in [12]-[15] use traveling waves for protection which depend on surge arrival time for accurate observations and installation of traveling-wave-based relays make the scheme economically inviable. The authors of [16] revamp the limitations of the literature with the idea of using fewer SSCBs employing centralized protection based on differential current approach with restrictive signal generator (RSG) unit (to avoid the mal-operation of the differential current approach due to current transducer (CT) saturation) along with OCR units serving as the backup. However, the scheme piles up multiple units for an effective centralized protection. Also, the backup protection (OCRs) are prone to relay incoordination and eventually mal-operation.

On the similar line of thought, the proposed body of work employs a centralized protection based on percentage differential current approach backed up with a local Running Autoregressive Smoothing Average (RASA) algorithm. The percentage differential current approach eliminates the need of any RSG unit, working fine to avoid any mal-operation in the case of CT saturation. The backup protection employed is effective, selective, dependent and secure and hence devoid the scheme to mal-operate. Two different types of IEDs (intelligent electronic devices) are employed in the piece of work for the execution of the proposed schemes, one incorporating a current transducer (CT), a voltage sensor and a microcontroller with an isolator and the second one, a CT, a voltage sensor and a microcontroller with a SSCB. The proposed work addresses

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the viable protection of a MVDC radial microgrid using a combination of the two types of IEDs in a topology of sub-microgrid (SMGs) in the radial microgrid. Centralized protection works with the operation of CTs whereas RASA serves as the local backup protection for the case of point-of-failure for the centralized communication where nodal voltage and segment current magnitudes are utilized for the algorithm operation.

The paper is organized into VI sections. Section II describes the radial DC microgrid that has been considered for the validation for the proposed scheme. Section III explains implementation of the centralized protection with the local backup complimenting the work proposed. Section IV explains the mathematical analysis for the calculation of the adaptive threshold for the RASA algorithm for voltage and current. Section V validates the work employing MATLAB/SIMULINK whereas section VI gives a hardware validation for the same. Section VII concludes the work.

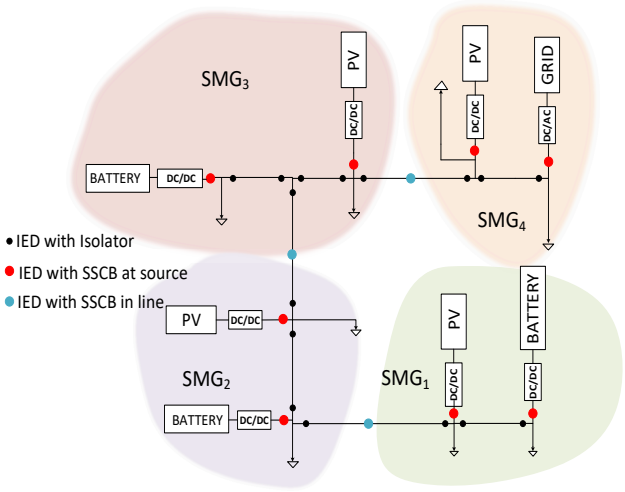


Fig. 1: Test system of radial DC microgrid

II. Test System Description

The test system is a multi-terminal MVDC radial microgrid as shown in Fig. 1 with operating voltage of 1.4 kV. The network is divided into sub-microgrids (SMGs) with a combination of IEDs$_{isolator}$ and IEDs$_{sscb}$. The scheme is designed considering that the scheme is blind to the aspect of whether internal protection is present in the power electronic interfaces or not. This makes it effective in all scenarios and not just when the power electronic interface is having internal protection. This explains employing IEDs with SSCB at the output of all the power electronic interfaces (IEDs$_{sscb_s}$ or source IED$_{sscb}$). In order to keep the healthy SMGs away from any power disruption during a fault contingency, IEDs with SSCB in line (IEDs$_{sscb_l}$ or line IED$_{sscb}$) are employed for isolation of the healthy SMGs from the faulty one. IEDs$_{isolator}$ are employed for all the other segments. SMG$_1$, SMG$_2$ and SMG$_3$ each have a PV, battery system interfaced to the feeder with individual DC/DC converters. SMG$_4$ has a PV with a DC/DC converter; and a utility grid connected with a VSC (voltage source converter) interfaced to the feeder. Constant power loads (CPLs) at feeder are operating at output voltage of 240V.

The need for formation of SMGs is explained as to devoid the overall microgrid outage in case of a fault contingency. Each SMG is connected to the other one with line IED$_{sscb}$. In case of a fault contingency in the microgrid, de-energization of only the faulty SMG happens extricating the complete system outage. However, there is a trade-off between the viability of the scheme and the microgrid area de-energized. More number of IEDs$_{sscb}$ ensure no de-energization in the system but the cost of the system goes high. The proposed work outlines the protection of a possible topology of a radial microgrid with IEDs; the optimal SMG formation and IEDs placement are not the ideas of consideration and are out of scope of the proposed work. However, SMG formation, here can be explained on the basis of self-adequacy as described in [17].

III. Formulation of the Proposed scheme

A. Centralized Protection

The centralized protection is based on the percentage differential current relaying operation where the segments have two terminal IEDs$_{isolator}$ (as shown in Fig. 1) with CTs evaluating the differential current in the segment. In the case of normal operation,

$$diff_i(n) \leq \zeta * avg_i(n) \tag{1}$$

where $diff_i(n)$ and $avg_i(n)$ are the differential and average current of the terminal CTs of a segment; i representing a specific segment and ζ is the slope setting of the percentage differential current approach. The employed parameters are mathematically analysed in section IV(B). The idea of percentage differential approach is to eliminate the need of any RSG unit as employed with differential approach in [16]. Since there is no CT mal-operation in the proposed centralized approach, false tripping of SMG relay is averted. As shown in the flowchart in Fig. 2, when the communication status is 1 and a fault contingency occurs in the microgrid, centralized protection works to isolate the faulty segment in the faulty SMG. The SMG relay sends a trip signal to the IED$_{sscb_l}$ isolating the faulty SMG from the other healthy segments as shown in Fig. 4; devoiding the healthy SMGs to participate in a fault. Once the healthy SMGs are not related to the fault, they continue their normal operation without any power disruption. The SMG relay, then sends a trip signal to IED$_{sscb_s}$ of the faulty SMR de-energizing the faulty SMG. Once the SMG is completely de-energized, the SMG relay trips IED$_{isolator}$ related to the faulty segment isolating the faulty segment. Once the segment is isolated, reclosing of the source IED$_{sscb}$ takes place to energize the SMG followed by reclosing of the line IED$_{sscb}$ to restore the normal operation of the radial microgrid.

B. Backup Protection

Running autoregressive smoothing average (RASA) serves as the local measurement based backup for the proposed

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protection scheme. RASA is a mathematical approach to reduce the random variation in time series analysis of parameters and is mathematically realized as;

$$Y(a) = 0.5(\frac{\sum_{k=1}^{k=a-1} y(k)}{a-1} + y(a)) \quad (2)$$

where $y(a)$ is the instantaneous value of a parameter and $Y(a)$ is its respective RASA at ath sample. The same idea has been employed to consider the segment currents and terminal voltages to model a localized backup scheme as explained in Fig. 5 with the sequence explained in Fig. 2.

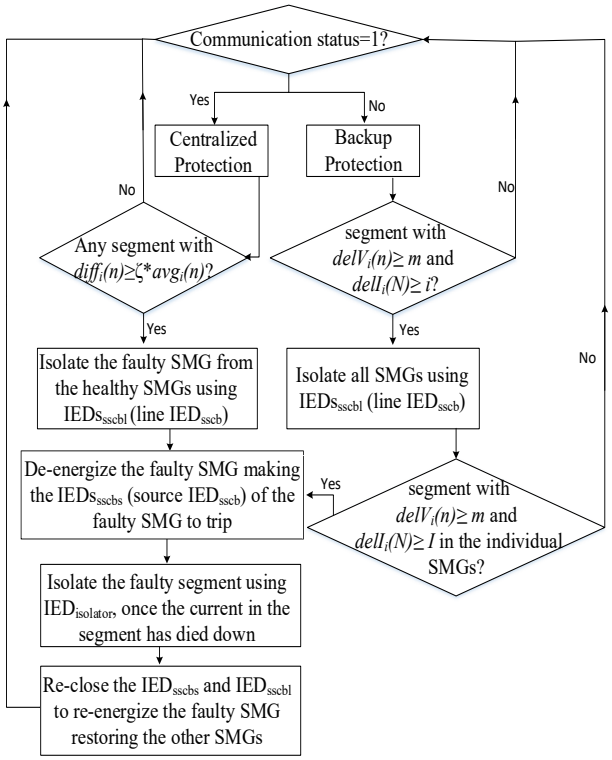


Fig. 2: Proposed Protection scheme flowchart

The same IEDs (the IEDs employed for centralized protection) are used (voltage sensor unit, CTs and the microcontroller unit) to implement RASA. The local measurement based *RASA* is a communication-free approach for faulty segment identification. The need for *RASA* over taking the normal parameter for any decision making arises due to different types of market available power electronic interfaces (with/ without DC capacitor; with/ without sufficient inductance) in a microgrid. The protection scheme has been designed to be blind to the types of power electronic interfaces in a microgrid. Fig. 3(a) shows the DC link voltage profile when there is no capacitor at the DC link in a microgrid. The variation can lead to mal-operation of the protection scheme if just the DC link voltage (as a parameter) is considered for the decision making for fault detection. However, Fig. 3(b) shows the *RASA* for the same voltage profile to justify the use of $RASA_{voltage}$ over just the parameter itself. The same idea is employed for the consideration of $RASA_{current}$ over just the segment current itself.

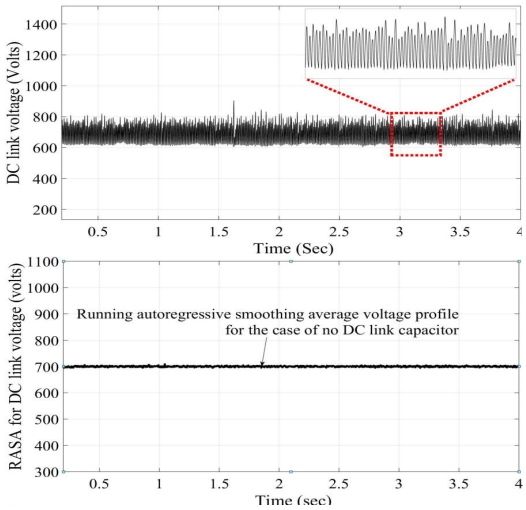


Fig. 3: (a) DC link voltage profile for no capacitor at DC link; (b) RASA DC link voltage profile for no capacitor at DC link

The proposed algorithm takes into consideration running average of voltage at each terminal for n^{th} sample at the sampling time of 5μs. RASA for voltage at i^{th} terminal is given as $V_i(n)$ which is mathematically expressed as,

$$V_i(n) = 0.5(\frac{\sum_{k=1}^{k=n-1} v_i(k)}{n-1} + v_i(n)) \quad (3)$$

where $v_i(k)$ is the i^{th} bus voltage at k^{th} sample. Once the RASA voltage is known at n^{th} sample of the i^{th} terminal, the proposed algorithm outlines the calculation of a parameter $delV_i$, which is defined as the difference between running average voltage at n^{th} and $(n+3)^{rd}$ sample. RASA, reducing the random variation of parameters, is a more reliable approach than considering just the parameter itself for decisive operations. Therefore, employing parameter $delV_i$ finds its justification for fault detection where it is mathematically realized as,

$$delV_i(n,:) = V_i(n) - V_i(n+3) \quad (4)$$

The calculation of $delV_i$ at every third sample is executed and compared to the fault threshold m of the system which is computed with mathematical analysis presented in section IV. The three sample window for the calculation of $delV_i$ is explained so as to ensure the tripping signal only when there is a fault contingency. If $delV_i$ is greater than the threshold for a window of three samples, the system is considered to be subjected to a fault. Since, the voltages at the terminal which are directly connected to the faulted segment have suddenly dropped, thus, the associated $delV_i$ of the adjoining terminal will breach the adopted threshold at the earliest sample. The calculated value of $delV_i$ is much smaller in case of a transient or CPL operation in the system than it is for a fault condition. As the threshold violation is not taking place for the normal operation, RASA takes the

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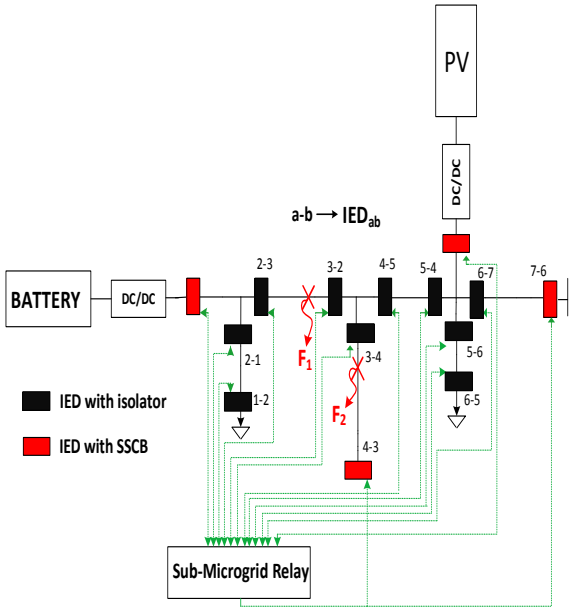


Fig. 4: Faulty SMG with fault at different segments

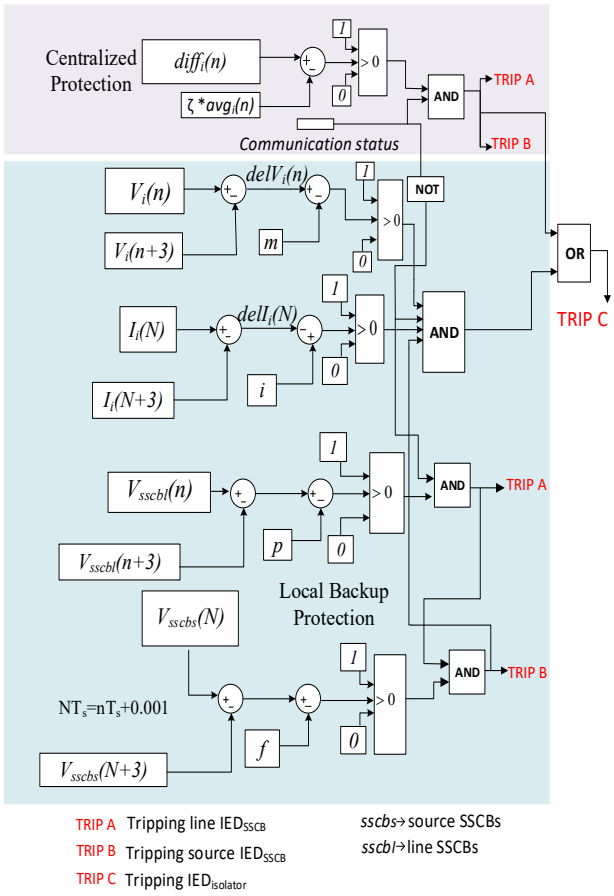


Fig. 5: Proposed Protection schematic

variability of the operations of the system into account and do not mal-operate in case of transients and CPL operation in the system. Under normal operating conditions,

$$delV_i(n) \leq m \tag{5}$$

When the communication status is *0* and a fault contingency occurs in the system, the centralized protection is not operational and hence, the localized backup scheme comes into picture serving as the operational protection for the MTDC microgrid. The sequence of actions on the occurrence of a fault, as explained in Fig. 2 are, RASA algorithm making all the line IED$_{sscb}$ to trip. The operational time of the SSCB has been assumed to be 1ms. After a delay of 1ms, RASA executes to trip the source IED$_{sscb}$ of the faulty SMG as once the line IEDs$_{sscb}$ have tripped, the healthy SMGs start restoring the voltage discrepancy of the respective system and would not violate the threshold for RASA algorithm. However, the faulty SMG sees continuous collapse of voltage profile and hence, RASA, after a delay of 1ms executes for source IED$_{sscb}$ and IED$_{isolator}$ to identify the faulty segment in the SMG followed up with tripping of source IED$_{sscb}$ of the faulty SMG. Once the source IED$_{sscb}$ trip, the faulty SMG gets de-energized making the current in the faulty segment *0*, thereby isolating the faulty segment. Once the faulty segment is isolated, the reclosing of SSCBs take place to restore the normal operation of the SMGs and the microgird. RASA execution needs a threshold as shown in Fig. 5, where *m*, *i*, *p* and *f* are the threshold for different parameters and are mathematically analysed in section IV(A).

However the trade-off with employing backup protection over centralized protection is not related to the time of fault isolation (where the fault isolation time is more or less the same as shown in Table IV) but is related to the possibility of load shedding in the healthy SMG under a fault contingency. This is because the backup protection isolates all SMGs under a fault contingency and there is possibility of load shedding if the healthy SMG has lesser power backup (case when the PV is not producing any real power in the night and the battery is discharged).

IV. Mathematical Modelling of Adaptive Threshold of Parameters

A. Computing m, p and f:

The operation of RASA requires the online evaluation of certain parameters to make the backup protection scheme selective, secure and dependable. In the case of a fault inception in a segment of the microgrid, the voltage profile sees a collapse and the current begins to rise. The IEDs are employed to analyse the voltage and the current profiles. Fig. 6 shows the SMG area with faulty segment when the fault has occurred at d= d_{max} (threshold evaluation is done considering highest impedance of a segment; the online evaluation changes the threshold for high resistance faults

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accordingly based on the instantaneous values of fault currents) to explain the adaptive threshold evaluation of different parameters for the execution of RASA algorithm. The parameters m, p and f as mentioned in Fig. 5 are evaluated implementing the same explained analysis.

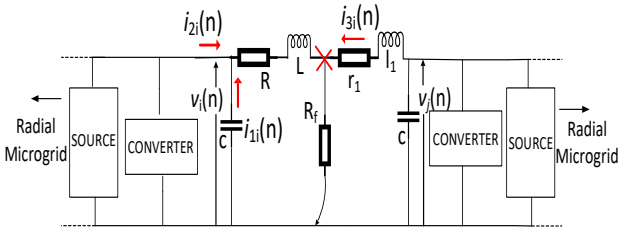


Fig. 6: SMG area with the faulty segment under a fault contingency at d=d_{max}

$$v_i(n) = v_i(0) - \frac{\sum_{k=1}^{k=n} i_i(k) n T_s}{C} \tag{6}$$

$$i_i(n) = \frac{v_i(0)}{L(\beta-\alpha)}[e^{-\alpha n T_s} - e^{-\beta n T_s}] + \frac{i_L(0)}{\beta-\alpha}[-\alpha e^{-\alpha n T_s} + \beta e^{-\beta n T_s}] \tag{7}$$

where $v_i(n)$, $v_j(n)$ are the terminal voltages at ith and jth terminal, $v_c(0)$ is the voltage across the capacitor and $i_L(0)$, the current across the inductor at the fault instant. α and β are the solutions for the current response in the RLC circuit as shown in the Fig. 6.

$$i_i(n) = \frac{v_i(0)}{L(\beta-\alpha)}[1-\alpha n T_s - 1 + \beta n T_s] + \frac{i_L(0)}{\beta-\alpha}[-\alpha(1-\alpha n T_s) + \beta(1-\beta n T_s)] \tag{8}$$

$$i_i(n) = \frac{n T_s v_i(0)}{L} + i_L(0)[1 - n T_s(\beta+\alpha)] \tag{9}$$

The parameter threshold m is defined as,

$$m = V_i(n) - V_i(n+3) \tag{10}$$

where RASA is employed to eliminate the randomness of parameter and hence while analysis can be written as,

$$m = v_i(n) - v_i(n+3) \tag{11}$$

$$m = \frac{n T_s}{C}\left(\sum_{k=1}^{k=n+3} i(k) - v_i(0) - \sum_{k=1}^{k=n} i(k) + v_i(0)\right) \tag{12}$$

$$m = \frac{n T_s}{C}[i(n+1) + i(n+2) + i(n+3)| \tag{13}$$

Parameters p and f are calculated with the similar line of analysis.

B. Computing $\zeta * avg_i(n)$:

Computing $\zeta * avg_i(n)$ is executed with a high fault resistance (HRF) to calculate the threshold that violates each time a fault incurs in the system. Calculating $\zeta * avg_i(n)$ is mathematically explained as;

$$\zeta * avg_i(n) = 0.133 * (i_{1i}(n) + i_{2i}(n) + i_{3i}(n)) + \gamma \tag{14}$$

where the parameters in equation (14) are explained in Fig. 6. The percentage differential slope setting constant is taken to be 0.4 and γ is taken to be of value 5 based on the simulation studies.

V. Simulation Validation

MATLAB/SIMULINK platform has been employed to validate the proposed scheme of centralized protection with the localized backup for both bolted pole-pole and unbolted pole-pole fault contingencies. In case of any fault contingency, the healthy SMGs see no power disruption, the faulty SMG sees a de-energization (as shown in Table IV) in either case when the centralized protection or backup protection are operational. The scheme has been validated to check the security, dependability and the selectivity for variability of scenarios like transients and CPL operations in the microgrid.

A. Fault Interruption

The fault interruption time is critical in the protection of DC microgrids, a delay of few milliseconds can cause system collapse and load detriment (if the power electronic interface is not having internal protection) as shown in Fig. 7 and Fig. 8. In the presence of internal protection, load shedding happens due to blocking of the interfacing units which defeats the objective of an effective protection scheme. Hence, the need of SSCBs with operational time of less than 1ms is justified rather than employing normal ACCBs (for MVDC microgrid) with operational time of around 40ms.

B. Security of the Scheme

Security of a protection scheme is defined as the property of fault detection only in case of a fault contingency. Maloperation of the relays in case of transients and the CPL operation make the scheme insecure. The proposed scheme is hence, tested for CPL operation, off-grid transients and PV insolation transients to validate the security for centralized as well as backup protection. SMG_3, as shown in Fig. 4 is subjected to a CPL operation of 6KW, a PV insolation change from 1000W/m^2 to 450W/m^2 and an off-grid operation (for SMG_3 battery acts as the voltage control unit) all at t=0.4s as shown in Fig. 9 to see the variation of parameters employed in the fault detection analysis.

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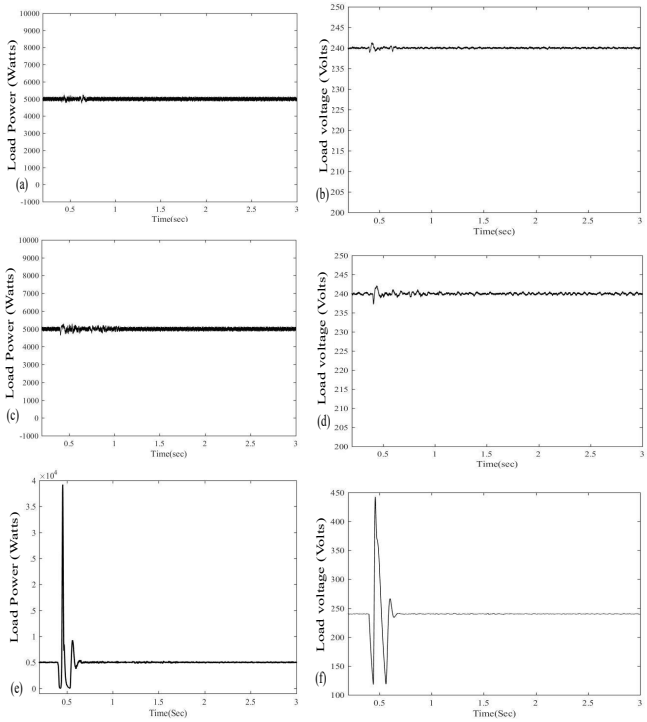


Fig. 7: Load Power vs Time at the faulty SMG when the fault is interrupted after (a) t=2ms; (c) t=5ms; (e) t=20ms; Load Voltage vs Time at the faulty SMG when the fault is interrupted after (b) t=2ms; (d) t=5ms; (f) t=20ms

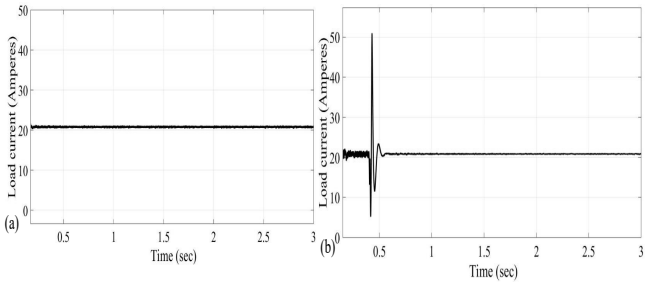


Fig. 8: Load current vs Time at the faulty SMG when the fault is interrupted after (a) t=2ms; (b) t=20ms

1) Communication Status 1: When the communication status is 1, centralized protection is operational. For the transient contingencies in the system, $\text{diff}_i(n)$ would ideally be zero as shown in Fig. 10 and therefore falls in the blocking zone (below the blue line with slope) employing the proposed percentage differential relay.

2) Communication Status 0: When the communication status is 0, backup local protection is operational, $delV_i < m$ and $delI_i < i$ as shown in Table I and the tripping of the IEDs do not happen ensuring the security of the protection scheme.

C. Dependability of the Scheme

Dependability of a scheme is defined as the property of fault detection if there is actually a fault contingency in the system. Mal-operation of the relays, not detecting the fault in case of an actual fault in the system makes the scheme undependable.

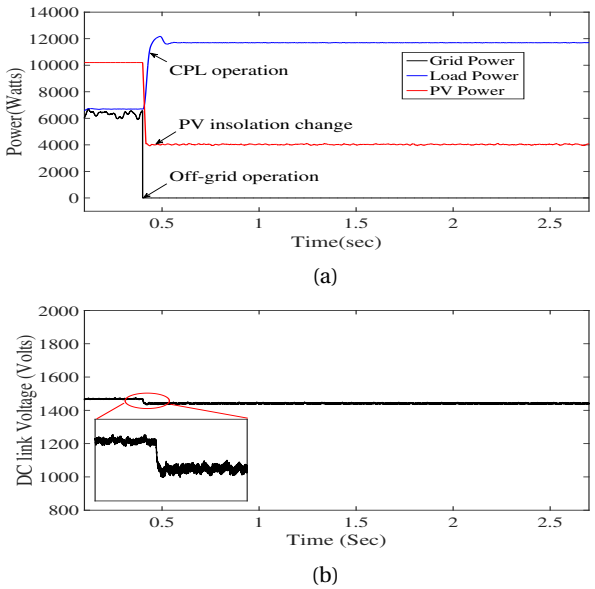


Fig. 9: (a) Power vs Time at SMG_3 for a transient operation at t=0.4s (b) DC link Voltage vs Time at terminal of IEDs 1 and 2 of SMG_3 for a transient operation at t=0.4s

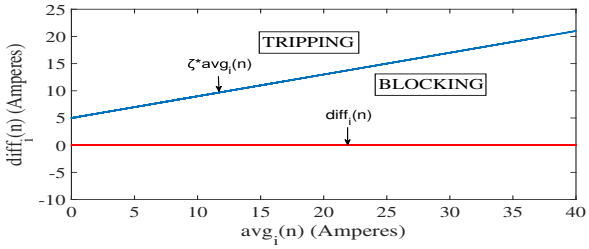


Fig. 10: $\text{diff}_i(n)$ vs $\text{avg}_i(n)$ at SMG_3 for a transient operation at t=0.4s

TABLE I: Parameter $delI_i$ (A) and $delV_i$ (V) variation in different IEDs for a transient operation at t=0.4s

IED_{ab}	$delI_i$	IED_{ba}	$delI_i$	IED_{ab}	$delV_i$	IED_{ba}	$delV_i$
1-2	0.119	2-1	0.119	1-2	2.114	2-1	1.392
2-3	0.042	3-2	0.042	2-3	1.392	3-2	0.974
3-4	0.017	4-3	0.017	3-4	0.974	4-3	0.554
4-5	0.025	5-4	0.025	4-5	0.974	5-4	0.647
5-6	0.011	6-5	0.011	5-6	0.647	6-5	0.436
6-7	0.008	7-6	0.008	6-7	0.647	7-6	0.313

1) Unbolted pole-pole contingency: An unbolted pole-pole contingency (F_1) has its inception at SMG_3 as shown in Fig. 4 at t=0.4s.

a) Communication Status 1: In case of an unbolted pole-pole fault contingency, the $\text{diff}_i(n)$ picks above the ζ*$\text{avg}_i(n)$ line detecting the fault contingency in 6μs as shown in Fig. 11 and initiating the fault isolation process.

b) Communication Status 0: The parameter variation when backup protection is operational is shown in Table II for the mentioned contingency. The fault detection time

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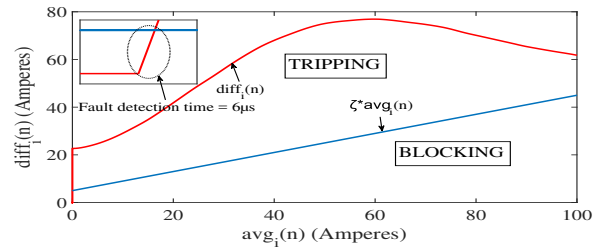
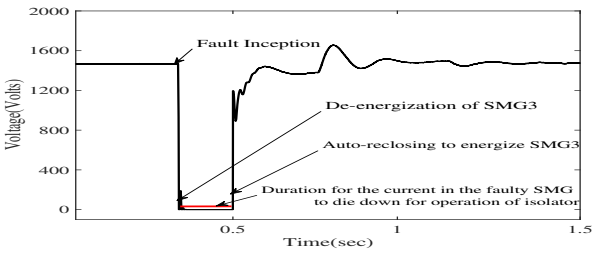
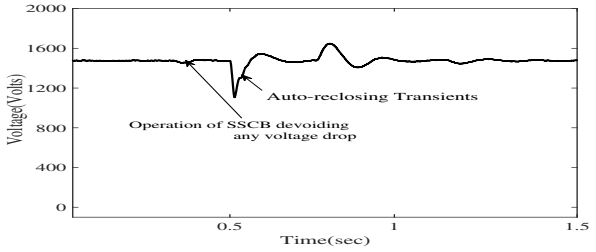


Fig. 11: diff$_i$(n) vs avg$_i$(n) at SMG$_3$ for an unbolted pole-pole contingency at t=0.4s



(a)



(b)

Fig. 12: Terminal DC link voltage vs Time for an unbolted pole-pole contingency for (a) SMG$_3$ (b) SMG$_4$

for the backup protection is 1.015ms. This happens as the line IEDs$_{sscb}$ operational time is 1ms and 15μs is the computational time of the scheme to detect the fault locally.

TABLE II: Parameter $delI_i$ (A) and $delV_i$ (V) variation in different IEDs for an unbolted contingency (F$_1$) in SMG$_3$ at segment with IEDs 2 and 3

IED$_{ab}$	$delI_i$	IED$_{ba}$	$delI_i$	IED$_{ab}$	$delV_i$	IED$_{ba}$	$delV_i$
1-2	0.024	2-1	0.024	1-2	1.249	2-1	9.064
2-3	0.732	3-2	1.119	2-3	9.064	3-2	29.072
3-4	0.062	4-3	0.062	3-4	29.072	4-3	2.054
4-5	0.075	5-4	0.075	4-5	29.072	5-4	1.347
5-6	0.028	6-5	0.028	5-6	1.347	6-5	0.434
6-7	0.013	7-6	0.013	6-7	1.347	7-6	0.313

Employing either scheme, the terminal DC link voltage plots of the faulty SMG (SMG$_3$) and the healthy SMG (SMG$_4$ is taken here) are shown in Fig. 12. The faulty SMG i.e., SMG$_3$ is de-energized till the fault is isolated and the system is restored. However, the healthy SMG sees no power disruption. The transient voltage stresses during recovery are mitigated using a backstepping based non-linear robust controller for the microgrid as proposed in [19].

2) Bolted pole-pole contingency: A pole-pole short circuit fault (F$_2$) contingency has its inception in SMG$_3$ as shown in Fig. 4 at t=0.4s.

a) Communication Status 1: In case of a bolted pole-pole fault contingency, the diff$_i$(n) picks above the ζ*avg$_i$(n) line detecting the fault contingency almost instantaneously as shown in Fig. 13, initiating the fault isolation process.

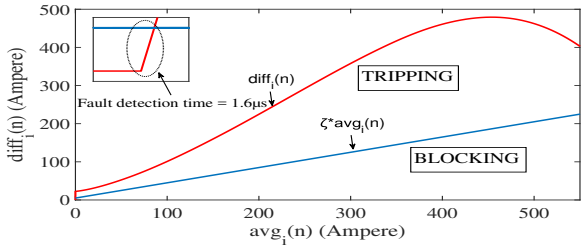


Fig. 13: diff$_i$(n) vs avg$_i$(n) at SMG$_3$ for a bolted pole-pole contingency at t=0.4s

b) Communication Status 0: The parameter variation when backup protection is operational is shown in Table III for the pole-pole contingency. IEDs 3 and 4 violate both the current and voltage threshold as shown in the table and hence are detected as the faulty segment.

TABLE III: Parameter $delI_i$ (A) and $delV_i$ (V) variation in different IEDs for a pole-pole short circuit (F$_2$) contingency in SMG$_3$ at segment with IEDs 3 and 4

IED$_{ab}$	$delI_i$	IED$_{ba}$	$delI_i$	IED$_{ab}$	$delV_i$	IED$_{ba}$	$delV_i$
1-2	0.014	2-1	0.014	1-2	0.642	2-1	2.863
2-3	0.037	3-2	0.037	2-3	2.863	3-2	187.022
3-4	4.762	4-3	2.862	3-4	187.022	4-3	56.094
4-5	0.079	5-4	0.079	4-5	187.022	5-4	1.347
5-6	0.034	6-5	0.034	5-6	1.347	6-5	0.338
6-7	0.018	7-6	0.018	6-7	1.347	7-6	0.243

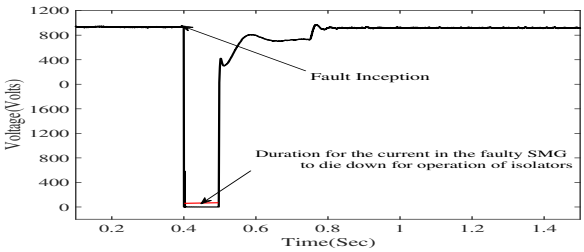


Fig. 14: DC link Voltage vs Time at terminal of IEDs 3 and 4 of SMG$_3$ for a pole-pole fault at t=0.4s

The terminal DC link voltage plot of the faulty SMG (SMG$_3$) is shown in Fig. 14 where the power disruption in the SMG takes place until the current in the SMG dies to let the isolators operate and isolate the fault. Once the fault is isolated, the system is restored to normal operation (refer to Table IV).

D. Selectivity of the Scheme

Selectivity of a protection scheme is defined as the property of fault detection only in case of a fault contingency only by the relays responsible for the fault detection in the allotted area and not by the neighbouring relays. The

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centralized approach does not violate the selectivity as $diff_i(n)$ is zero for the healthy segments and the parameter falls in the blocking zone.
The proposed backup scheme also takes care of the selectivity as can be shown in Table II. IEDs 2-1, 3-4 and 4-5 violate the threshold for voltage RASA, however, considering current RASA along with voltage RASA, the selectivity of scheme remains intact.

E. Communication delay for centralized protection

The proposed centralized scheme is subjected to a communication delay of up to 5ms in the relaying operation as suggested in [18]. The effect of the delay on the scheme is studied on the load side to see if there is any load detriment or shedding due to this delay. Fig. 15 shows the fault interruption at t=6.006ms for the same (0.006ms for the fault detection, 5ms for the delay and 1ms for the IED_{sscb} operation). The figure shows that even an appreciable communication delay holds the scheme intact.

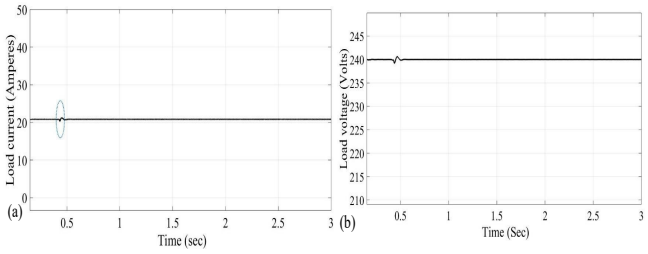


Fig. 15: (a) Load current vs time (b) Load voltage vs time when the fault is interrupted after a communication delay of 5ms

TABLE IV: Time taken by the different proposed schemes; (Fault Isolation Time considers the time for the current in the faulty segment to die down to 0 to let the isolators in the segment work)

	Fault Detection Time (msec)	Fault Isolation Time (msec)
Centralized Protection (without delay)	0.006	94
Centralized Protection (with delay)	0.006	99
Backup Protection	1.015	94

VI. Hardware Results

A. Setup and configuration

A 48V radial DC microgrid (further divided into two sub-microgrids) is implemented with a 5 bus system as shown in Fig. 17. Bus 2 and bus 4 have 3×12V, 12Ah lead-acid batteries with a market purchased boost converter [20]. Bus 3 and bus 5 have a 12V, 12 Ah lead-acid battery each with a buck converter. Bus 1 has a single-phase grid tied inverter (operating range 24V-48V DC). Rheostats (12Ω, 12A) and inductors (0-5mH, 10A) are employed to replicate the distribution line with reistance per km= 0.5Ω and inductance per km= 0.5mH. LV25-P voltage sensors, LA55-P current sensors with Arduino Uno and relay modules are employed to detect the fault and consequently isolate segment 2 from the microgrid. In order to observe the plot of bus voltages and segment currents for RASA and percentage differential protection, differential probes (B&K Precision PR60) and current probes (Tektronix A622) along with a mixed domain oscilloscope (Tektronix MDO4054B-3) are employed.

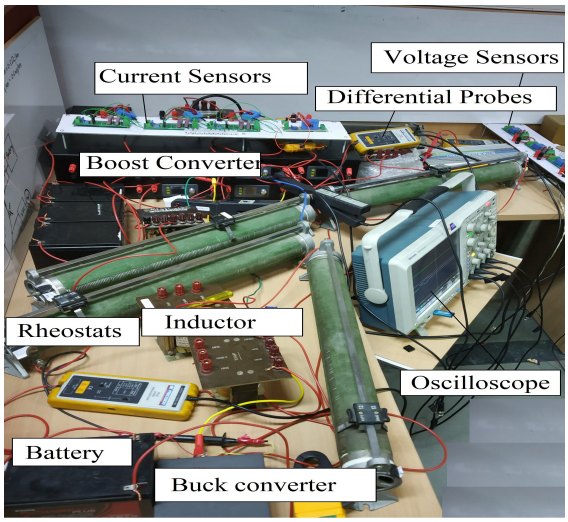


Fig. 16: Hardware setup for the proposed scheme

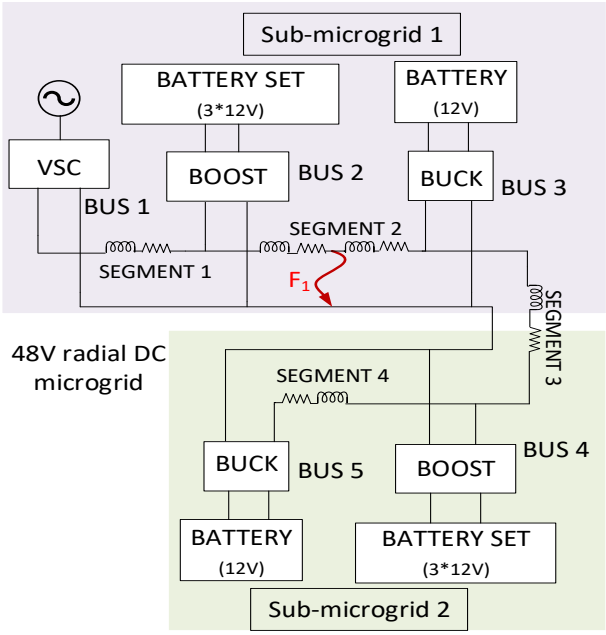


Fig. 17: Test system for hardware validation

B. Results

A fault is made to occur at segment 2 of the radial microgrid as shown in Fig. 17. When the communication is operational, percentage differential protection is employed as shown in Fig. 18(a). Segment 2, on fault inception violates the normal operation condition to make $diff_i(n)$ greater

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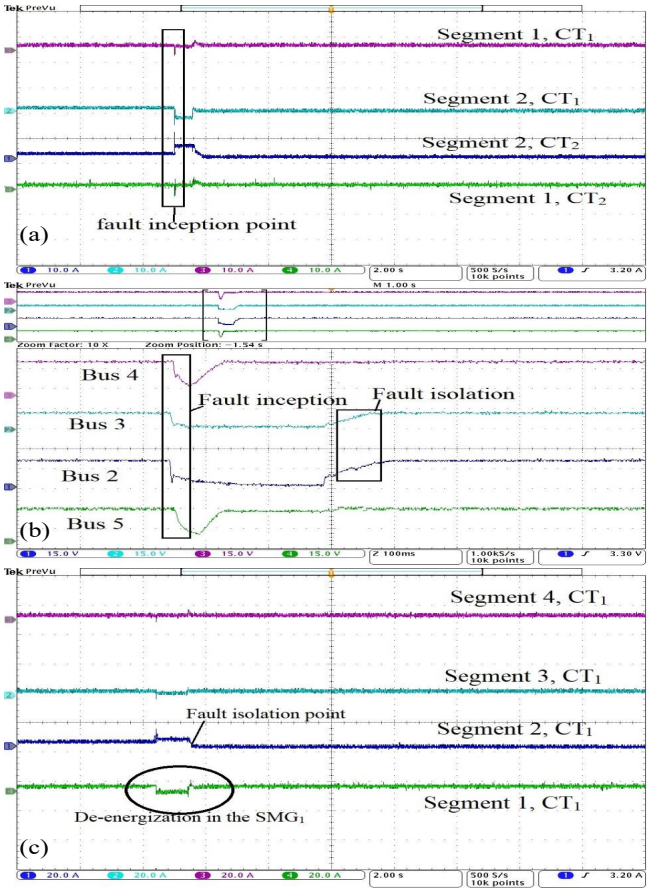


Fig. 18: (a) Percentage differential approach validated for healthy and faulty segment; (b) Bus voltages for different buses; (c) Segment current as measured by the current transducer of a particular segment

than the threshold. However, the healthy segments (1, 3 and 4) operate normally. When the communication is not operational, the backup protection is employed as shown in Fig. 18(b) and Fig. 18(c). In Fig. 18(b), bus 2 and bus 3 see a rather instantaneous collapse of voltage, however, faulty segment is decided by the current algorithm as shown in Fig. 18(c) where segment 2 sees a sudden rise in current compared to other segments.

The healthy sub-microgrid and the sources of the faulty sub-microgrid are isolated using 5V relay modules (operating time of 10ms) to further isolate the faulty segment subsequently restoring the system. If however, the fault is not interrupted in time, the bus voltage collapsed would make the boost converters to operate in constant current mode (under normal operation, the boost output current is 1.8A which goes upto 5A during fault as shown in Fig. 18(c)) feeding the fault and shedding the load (VSC not operating due to the bus voltage getting lower than its normal operational voltage, batteries with buck converter not getting charged due to insufficient potential difference).

VII. Conclusion

This paper proposes a centralized protection for a MVDC radial microgrid using percentage differential current approach. When the communication status is 0, the localized backup protection is employed which makes use of RASA, to locally detect and isolate the faulty segment. The scheme is a secure, dependable and selective approach to effectively restore the microgrid ensuring its normal operation within 100ms. The scheme works to employ minimum number of IEDs$_{sscb}$ which are expensive and employing them at every segment would lead to economically inviability, suggesting a topology justifying a trade off between the area de-energized and the viability. The same proposed scheme can however be altered according to the DC microgrid design and employed accordingly.

Appendix

The conductor employed as the DC line, has cable resistance of 0.5Ω per km. The idea of SSCBs employment considers silicon carbide junction gate field-effect transistor (SiC JFETs) based DC circuit breakers [21]. The rating of the employed breaker is 0.1kA/1.4kV and the operation time is as low as 0.5ms. The idea of transient overvoltage suppression with the suggested SSCB operation is based on the breaker snubber design as suggested in [22].

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Validation of growth enhancing, immunostimulatory and disease resistance properties of *Achyranthes aspera* in *Labeo rohita* fry in pond conditions

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Abstract

The immunostimulatory and disease resistance properties of herb *Achyranthes aspera* L. (Amaranthaceae) were evaluated in rohu *Labeo rohita* in pond. Rohu fry (1.9 ± 0.08 g) were cultured in hapas (25 hapa^{-1}) set inside a pond and were fed with two experimental diets containing 0.5% seeds (D1) and leaves (D2) of *A. aspera* and control diet (D3). Fish were challenged with *Aeromonas hydrophila* after 80 days. The cumulative mortality rate of fish was significantly ($P < 0.05$) higher in D3 (28−48%) compared to others. Average weight was significantly ($P < 0.05$) higher in D1 (6.5−12.5%) compared to other treatments. Myeloperoxidase and nitric oxide synthase levels were significantly ($P < 0.05$) higher in D1 and D2 compared to D3. Thiobarbituric acid reactive substances and carbonyl protein levels were significantly ($P < 0.05$) lower in hepatopancreas and kidney of D1 compared to others. In hepatopancreas, the expressions of lysozyme C, loysozyme G, TNF-α, IL-10 and IL-1β were

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significantly ($P < 0.05$) higher in D1 compared to others. This treatment was followed by D2. In kidney, lysozyme G and TNF-α levels were significantly ($P < 0.05$) higher in D1 and D2 compared to D3. Whereas, IL-10 and IL-1β were significantly ($P < 0.05$) down-regulated and up-regulated, respectively in kidney of D2. There was up-regulation ($P < 0.05$) of TLR-4 in hepatopancreas and kidney of D1 and D2 diets fed rohu, respectively compared to others.

Keywords: Immunology, Zoology

1. Introduction

The application of herbal immunostimulants has been increasing rapidly to control the disease in aquaculture [1]. Several plant ingredients show promising results viz. miers, *Tinospora cordifolia* leaf extract [2], mango, *Magnifera indica* kernel [3], *Solanum trilobatum* leaf [4], green tea [5], guava *Psidium guajava* leaves [6, 7], ginger *Zingiber officinale* [8]. All these studies are performed in the control laboratory conditions. Validation of these studies is required in the ponds, the most important source for aquaculture production in Asian countries. *Achyranthes aspera* L., a member of the Family Amaranthaceae is commonly found as weed in various parts of India. The bushy herb can be grown in the field regularly. Roots and seeds of *A. aspera* showed immunostimulatory and disease resistance properties in fishes in the laboratory conditions. The supplementation of *A. aspera* in diets stimulates specific and non-specific immune systems of *Catla catla* (catla), *Cyprinus carpio* (common carp) and *Labeo rohita* (rohu) [9, 10, 11, 12, 13]. The supplementation of seeds of *A. aspera* in diet also enhances the growth of fish. Even it protects the early larvae of carps from harmful UV-B irradiation [14, 15, 16, 17, 18].

The study of biochemical composition of seeds unveils the reason for beneficial effect of *A. aspera* on carps. Two glycosides of oleanolic acid, saponin A and B are present in the alcohol extract of seeds [19]. Chakrabarti et al. [20] reported the occurrence of ecdysterone and two essential fatty acids linolenic acid and oleic acid in the seeds. Ecdysterone is associated with the increased protein synthesis in skeletal muscle [21]. The amino acid profile study shows that leucine, isoleucine, phenylalanine and valine contents of seeds are equivalent to Bengal gram, whereas, sulphur amino acids methionine and cystine contents are higher compared to most pulses [22]. The long-chain polyunsaturated fatty acid (PUFA) plays important role in many physiological functions. So far, all experiments with *A. aspera* are conducted in laboratory conditions. The validation of laboratory study is most essential in the field conditions. Among various parts of the plant, only immunostimulatory properties of roots and seeds have been evaluated; the efficiency of leaves yet to be evaluated.

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The innate immune system is the baseline defence system of fish [23]. Myeloperoxidase and nitric oxide synthase reflect the status of the immune system of the species. The elevated levels of these parameters are indicators of healthy immune system of fish. The pattern recognition molecule, the toll-like receptor (TLR) is associated with certain activities of the innate immune system viz. production of cytokines, differentiation of cells, production of reactive nitrogen and oxidative radicals [24, 25]. Cytokines play an important role in the immune system by binding to specific receptors and setting off a cascade of events leading to induction, enhancement or inhibition of a number of cytokines-regulated genes [26]. Interleukin-1β is one of the pivotal early response pro-inflammatory cytokines that enables organisms to respond to any infection, inducing an inflammatory cascade, along with other defensive responses [23, 27]. TNF-α is associated with recruitment and activation of phagocytes [28]. The expression patterns of immune related genes were studied in rohu infected with *Edwardsiella tarda* [29] and *Aeromonas hydrophila* [10, 30, 31]. The information on the expression of immune related genes in fish fed with enriched diets and challenged with bacteria in pond conditions is lacking. The aim of the present study is to evaluate the immunostimulatory and disease resistance properties of seeds and leaves of *Achyranthes aspera* in *Labeo rohita* challenged with *Aeromonas hydrophila* in the pond conditions.

2. Materials and methods

2.1. Culture of fish and challenge with pathogen

Indian major carp *L. rohita* fry were procured from a fish farm, acclimated for 7 days and then fry (1.9 ± 0.08 g) were introduced in hapas (25 hapa^{-1}) set inside the pond (54.5 m × 30.5 m × 2.25 m) of Rohtak Centre, Central Institute of Fisheries Education (Indian Council of Agricultural Research), Haryana. Each hapa (2.0 m × 1.5 m × 1.5 m) was made of nylon net; the top of the hapa was covered with a net to avoid the escape of fish. Hapas were set inside the pond with bamboo stick. Rohu fry were fed with two experimental diets containing plant ingredients and control diet (Table 1). The experimental diets were prepared with 0.5% seeds (diet 1, D1) and leaves (diet 2, D2) of *A. aspera* with other ingredients; diet without plant ingredient served as control (diet 3, D3). *A. aspera* was grown in the outdoor facility; leaves and ripe seeds were collected regularly, cleaned, dried, ground and kept in the refrigerator for further use. Three replicates were used for each feeding regime. Food was given once daily (9.00 a. m.) at the rate of 5% of body weight. Major water quality parameters like temperature, pH, dissolved oxygen and conductivity were recorded regularly using HQ40d Multiparameter (Hach, USA) from four sides of the pond closer to the hapas. Water temperature and pH ranged from 28.5 to 31 °C and

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Table 1. Composition of experimental and control diets.

Ingredients	Diets		
	0.5% Seeds (D1)	0.5% Leaves (D2)	Control (D3)
Composition (g kg^{-1})			
Fish powder	482.76	482.76	482.76
Wheat flour	488.24	488.24	493.24
Cod liver oil	20.00	20.00	20.00
Vitamin & mineral pre-mix	4.00	4.00	4.00
Leaves	-	5.00	-
Seeds	5.00	-	-
Proximate composition (g 100 g^{-1})			
Crude protein	36.71	35.67	33.58
Crude fat	8.31	7.82	8.64
Carbohydrates	37.52	38.36	43.45
Ash	8.03	8.12	7.20
Moisture	9.43	10.03	7.14
Crude fibre	0.44	0.65	0.41
Energy (kcal 100 g^{-1})	371.7	366.5	385.8

8.4 to 9.16, respectively throughout the culture period. Dissolved oxygen level ranged from 7.11 to 9.62 mg L^{-1} in the pond. After 80 days of initial feeding, fish were anesthetized with MS 222 (Sigma, USA) and injected intraperitoneally (100 μL) with live *Aeromonas hydrophila* (5×10^6 CFU mL^{-1}). A group of fish injected with buffer served as sham control. All fish were introduced in the respective hapa and mortality of fish was recorded for 10 days at 12 h interval. The whole study was conducted following the guidelines of Institutional Animal Ethics Committee, IAEC (approved by Committee for the Purpose of Control and Supervision of Experiments on Animals, CPCSEA) (Reference: DU/ZOOL/IAEC-R/2015/08). The study was conducted following all regulations.

2.2. Collection of samples

After 10 days of challenge test, fish were anesthetized with MS 222 (Sigma), blood sample was drawn from the caudal vein of each fish using Dispo van 2 mL single use syringe (0.55 × 25 mm/24 × 1) and transferred in serological tube. Blood samples were allowed to clot at 4 °C overnight. The serum was then spun down at 400 × g for 10 min. Then the serum was stored in sterile tube at −20 °C until used for assays. Three replicates were used for each feeding regime. Hepatopancreas and head kidney were collected aseptically and were preserved at −80 °C for biochemical assays and gene expression study.

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2.3. Myeloperoxidase and nitric oxide synthase assays

Myeloperoxidase activity was measured following the standard method [32]. First 10 μL serum was taken in each well of microplate, then 90 μL of Hank's balanced salt solution (without Ca^{2+} or Mg^{2+}), 35 μL of 20 mM 3,3′,5,5′-tetramethylbenzidine hydrochloride (Genei, India) and 5 mM H_2O_2 were added to each well of microplate. The mixture was incubated for 2 min and 35 μL of 4 M sulphuric acid was added to stop the reaction. The activity was recorded at 450 nm.

Nitric oxide synthase levels of tissues (hepatopancreas and head kidney) were recorded [33]. In 1 mL phosphate buffer (pH 7.4), 100 mg tissue was homogenized; centrifuged at 10000× g for 20 min at 4 °C. The supernatant, 100 μL was mixed with 100 μL Griess reagent and incubated 10 min at room temperature. The activity was recorded at 540 nm. The nitrite concentration was measured with the nitrite standard curve and expressed as mmol mg tissue^{-1}.

2.4. Oxidation of tissue lipids and proteins

Thiobarbituric acid reactive substances (TBARS) indicate the oxidation of tissue lipids (hepatopancreas/head kidney). In 9 mL of KCl (1.15%), 1 g tissue was homogenized. Then the sample was incubated at 100 °C for 1 h in acid medium containing 0.45% sodium dodecyl sulphate (SDS) and 0.6% thiobarbituric acid [34]. The sample was centrifuged at 800 x g at 4 °C for 15 min. The standard was prepared with 1, 1, 3, 3-tetramethoxy propane. The activity was measured at 532 nm and expressed as mmol MDA mg protein^{-1}.

Carbonyl protein is an indicator of tissue protein oxidation. A 100 mg tissue (hepatopancreas/head kidney) was homogenized in 1 mL of potassium phosphate buffer (50 mM, pH 7.0) containing 0.5 mM ethylenediaminetetraacetic acid and 100 μM of phenylmethlysulfonyl fluoride [35]. The homogenate (250 μL) was mixed with 0.5 ml of 10% TCA, centrifuged at 13000× g for 5 min and the pellet was used for the assay. The pellet was mixed with 10 mM dinitrophenyl hydrazine (1 mL, DNPH) dissolved in 2 M HCl. It was incubated 1 h at room temperature, centrifuged at 13000 x g for 5 min; the pellet was collected and washed thrice with 1 mL of ethanol-butylacetate (1:1, v/v). Then it was dissolved in 1.5 mL of 6 M guanidine hydrochloride, centrifuged at 13000× g for 5 min and the supernatant was collected. The optical density of the supernatant was measured at 370 nm. The result was expressed as nmol mg protein^{-1}. The molar extinction coefficient was 22 × 10^3 M^{-1} cm^{-1}. Total tissue protein was measured at 750 nm [36].

2.5. Cumulative mortality rate of fish

The mortality of rohu in each hapa was recorded at 12 h interval after the challenge with *A. hydrophila*. The number of fish was recorded and expressed in per cent with

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respect to the initial one. Finally, it was expressed as cumulative mortality rate of rohu.

2.6. Gene expression study

2.6.1. Total RNA isolation and cDNA synthesis

The hepatopancreas and head kidney (100 mg) of rohu were processed separately in TRIzol reagent (Ambion, Life Technologies, USA) for the extraction of total RNA following the protocol of manufacturer. In Synergy H1 Hybrid microplate reader (Biotek, USA), the concentration and purity of RNA was checked at 260 and 280 nm, using Take 3 plate. Then integrity of extracted RNA was checked in 1% agarose gel. Total RNA (1 μg), was treated with 1U of DNase I (Sigma-Aldrich, USA) to avoid any contamination of DNA. High capacity cDNA reverse transcription kit (Applied Biosystems, USA) with RNase inhibitor was used for the reverse transcription of DNase-treated RNA following the manufacturer's protocol. The product was stored at −20 °C for further gene expression study.

2.6.2. Quantitative real-time PCR analysis

The quantitative real-time PCR (qRT-PCR) was performed to amplify immune relevant target genes like, lysozyme G, lysozyme C, TNF-α, IL-10, IL-1β, TLR-4 and housekeeping gene, β-actin using QuantStudio 6 Flex Real-Time PCR system (Applied Biosystems). MicroAmp optical 96-well reaction plate (0.1 mL) was used for amplifications. Primers for different genes were either self-designed or collected from earlier published data (Table 2). The cDNA of all the treatments were diluted (1:1) in nuclease-free water. Amplifications were carried out with 10 μL reaction volume and that composed of 1.0 μL of diluted cDNA, 0.25 μL of Forward and Reverse primers (2.5 μM each), 5 μL of Universal 2X PowerUp SYBR Green Master Mix (Applied Biosystems), 3.5 μL of nuclease-free water. Amplifications were performed in duplicate wells under following conditions: initial denaturation at 95 °C for 10 min followed by 40 cycles of 95 °C for 15 sec, annealing at 55 °C (for lysozyme G, lysozyme C, TNF-α) and 60 °C (for IL-10, IL-1β, TLR-4, β-actin), and extension at 72 °C for 1 min. The reaction carried out without cDNA template was a negative control. The qPCR specificity was verified with melt curve analysed at a 95 °C for 15 sec (1.6 °C sec^{-1}), 60 °C for 1 min (1.6 °C sec^{-1}) and 95 °C for 15 sec (0.15 °C sec^{-1}). The PCR efficiencies were determined by analysis of serial dilutions of cDNA. The efficiencies close to 100% allowed the application of $2^{-\Delta\Delta CT}$ method for calculation of relative gene expression of the target gene with that of reference gene β-actin [37]. The specificity of the amplification product was verified in 1% agarose gel.

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Table 2. Target genes and sequences of primers used for qPCR analysis.

Target gene	Primer	Primer sequence (5′-3′)	Accession number/reference
Lysozyme C	Lyso C Fw Lyso C Rv	CGATGATGGCACTCCAGGT CATGCTTTCAGTCCTTCGGC	EF203085.1
Lysozyme G	Lyso G Fw Lyso G Rv	CAATGGCTTTGGCCTCATGC CACGTGGGAAACTTTGCTCTG	KC934746.1
TNF-α	TNF-α Fw TNF-α Rv	GGCGGCTTGAAAGTAGTGGA TATGCAGAACGTCGTGGTCC	FN543477.1
IL-10	IL-10 Fw IL-10 Rv	GCTCAGTGCAGAAGAGTCGAC CCCGCTTGAGATCCTGAAATATA	[49]
IL-1β	IL-1β Fw IL-1β Rv	GTACCCCACAAAACATCGGC CAAGAGCAGTTTGGGCAAGG	AM932525.1
TLR-4	TLR-4 Fw TLR-4 Rv	CTAAGAAAGTGCTTGGGCTTCAT GGTTTGTGGCAATAATGGCTTTC	KX218428.1
β-actin	β-actin Fw β-actin Rv	GACTTCGAGCAGGAGATGG CAAGAAGGATGGCTGGAACA	[29]

2.7. Statistical analysis

All data are given as Mean ± SE. One-way analysis of variance and Duncan's multiple range test [38] were used to find out the difference among various treatments. Statistical significance was accepted at $P < 0.05$ level.

3. Results

3.1. Cumulative mortality of rohu

Rohu fry were fed with test diets containing 0.5% seeds (D1) and leaves (D2) of *A. aspera* and control diet (D3) for initial 80 days and then challenged with *A. hydrophila*. After bacterial challenge, the mortality of fish was recorded for 10 days at 12 h interval. First mortality was recorded in D2 diet fed rohu within 12 h of challenge with bacterial pathogen. The mortality rates were 2, 4 and 10% in D1, D2 and D3 diets fed groups, respectively after 24 h of challenge. In control diet fed group, 50% fish died within five days of challenge. The cumulative mortality rate was significantly ($P < 0.05$) higher in control diet fed rohu compared to the seeds and leaves supplemented diets fed fish (Fig. 1). The cumulative mortality rates were 28, 48 and 76% in D1, D2 and D3 diets fed rohu, respectively.

3.2. Average weight

Plant supplemented diet showed a positive impact on the growth of rohu fry. The average weight was significantly ($P < 0.05$) higher in rohu fed with 0.5% seeds supplemented diet (D1) compared to other two feeding regimes. The average weight of

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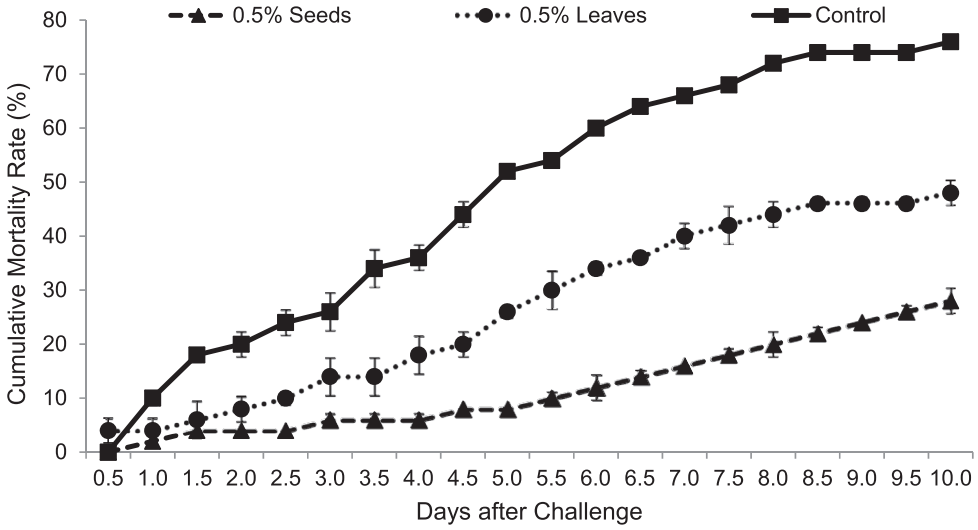


Fig. 1. Cumulative mortality of *L. rohita* fed with three different diets and challenged with *A. Hydrophila*.

D1 diet fed rohu was 6.5 and 12.5% higher compared to the D2 and D3 diets fed fish, respectively (Table 3).

3.3. Myeloperoxidase and nitric oxide synthase assays

Myeloperoxidase activity was significantly ($P < 0.05$) higher in D1 and D2 diets fed rohu compared to the control diet fed fish. There was no significant ($P > 0.05$) difference in myeloperoxidase activity between the former two groups. Nitric oxide synthase levels in hepatopancreas and kidney were significantly ($P < 0.05$) higher in D1 diet fed rohu compared to others. The level was 5−7 folds higher in hepatopancreas compared to the kidney of rohu fed with same diet (Table 4).

3.4. Oxidation of tissue lipids and proteins

TBARS levels were significantly ($P < 0.05$) lower in hepatopancreas and kidney of D1 diet fed rohu compared to others. Similarly, carbonyl protein level was significantly ($P < 0.05$) lower in D1 diet fed rohu compared to others. Highest TBARS and carbonyl protein levels were found in D3 diet fed rohu. The levels

Table 3. Initial and final average weights of *L. rohita* fed with three different diets and challenged with *A. hydrophila*. Mean ± SE (25 fish hapa^{-1}, 3 hapas treatment^{-1}; 25 × 3 = 75 in each treatment) sharing different letters in the same column are significantly ($P < 0.05$) different.

Parameters	(D1) 0.5% Seeds	(D2) 0.5% Leaves	(D3) Control
Initial weight (g)	1.9 ± 0.08a	1.9 ± 0.08a	1.9 ± 0.08a
Average weight (g)	25 ± 0.40a	23.50 ± 0.22b	22.22 ± 0.11c

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Table 4. Myeloperoxidase, nitric oxide synthase, thiobarbituric acid reactive substances (TBARS) and carbonyl protein levels found in *L. rohita* fed with three different diets and challenged with *A. hydrophila*. Mean ± SE (6 fish hapa^{-1}, 3 hapas treatment^{-1}; 6 × 3 = 18 in each treatment) sharing different letters in the same column are significantly ($P < 0.05$) different.

Parameters	0.5% Seeds (D1)	0.5% Leaves (D2)	Control (D3)
Serum			
Myeloperoxidase (O.D. at 450 nm)	0.92 ± 0.04a	0.91 ± 0.02a	0.62 ± 0.03b
Hepatopancreas			
Nitric oxide synthase (μmol mg tissue^{-1})	20.82 ± 0.14a	15.25 ± 0.26b	15.36 ± 0.20b
TBARS (mmol MDA mg protein^{-1})	0.98 ± 0.02c	1.32 ± 0.04b	2.94 ± 0.03a
Carbonyl protein (nmol mg protein^{-1})	7.80 ± 0.04c	8.56 ± 3.16b	16.71 ± 5.05a
Head kidney			
Nitric oxide synthase (μmol mg tissue^{-1})	4.30 ± 0.02a	2.74 ± 0.02b	1.78 ± 0.02c
TBARS (mmol MDA mg protein^{-1})	0.75 ± 0.01c	1.97 ± 0.05b	3.25 ± 0.05a
Carbonyl protein (nmol mg protein^{-1})	5.48 ± 0.19c	7.78 ± 0.27b	17.99 ± 0.28a

were higher in hepatopancreas compared to the kidney of rohu cultured in the same feeding regime (Table 4).

3.5. Gene expression

Expression of various immune-related genes supported the physiological study. In hepatopancreas of seeds (D1) supplemented diet fed rohu, the expressions of lysozyme C and G were significantly ($P < 0.05$) higher compared to others. This treatment was followed by D2 diet fed rohu and minimum level was found in control diet (D3) fed fish (Fig. 2). The expression of lysozyme C was higher compared to lysozyme G in the hepatopancreas of rohu cultured in the same feeding regime. Lysozyme G levels were significantly ($P < 0.05$) higher in kidney of rohu fed with D1 and D2 diets compared to the D3 diet fed fish (Fig. 3). There was no change in lysozyme C level in plant supplemented diets fed rohu compared to the control diet fed fish. In hepatopancreas of D1 diet fed rohu, the expression of TNF-α was significantly ($P < 0.05$) higher compared to others. This treatment was followed by D2 and D3 diets fed rohu (Fig. 4). In kidney, the expression of TNF-α was significantly ($P < 0.05$) higher in D1 and D2 diets fed rohu compared to D3. The expression of TNF-α was 2−6 folds higher in hepatopancreas compared to kidney of rohu cultured in same feeding regime. There was up-regulation ($P < 0.05$) of IL-10 in hepatopancreas of rohu fed with D1 diet compared to others (Fig. 5). This treatment was followed by D2 diet fed rohu. In kidney, IL-10 was up-regulated ($P < 0.05$) only in D1 diet fed rohu and it was down-regulated in D2 diet fed fish compared to the control diet fed fish. In hepatopancreas of D1 diet fed rohu, IL-1β was up-regulated ($P < 0.05$) compared to others (Fig. 6). Whereas, in kidney significantly ($P < 0.05$) higher

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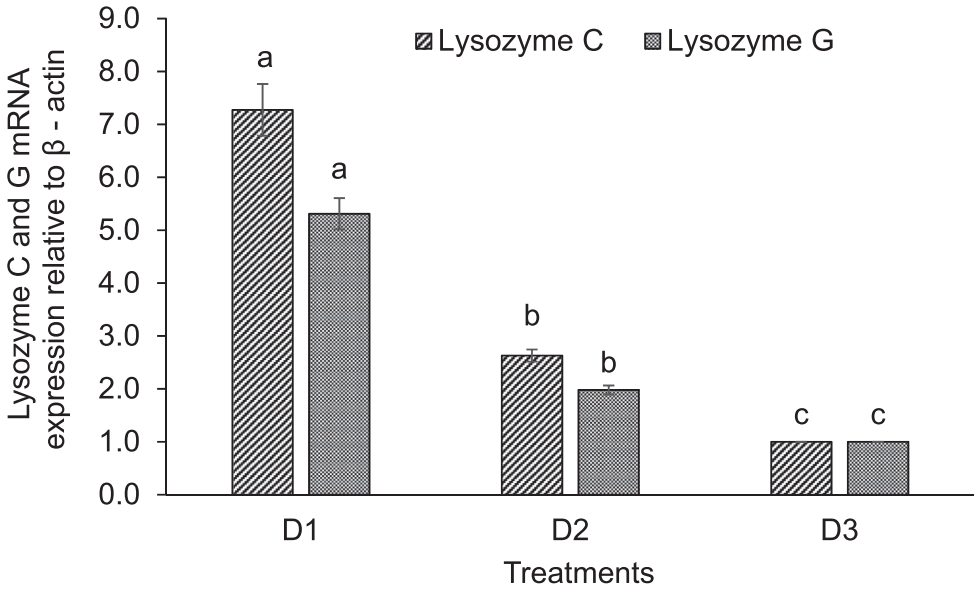


Fig. 2. Expression of lysozyme C and lysozyme G in hepatopancreas of *L. rohita* fed with three different diets and challenged with *A. hydrophila*. The relative expression of the target gene lysozyme C/G was normalized to the expression of β-actin (internal control) and expressed as fold changes relative to the control diet fed group. Vertical bars with different superscripts are significantly ($P < 0.05$) different (2 fish hapa^{-1}, 3 hapas treatment^{-1}; $2 \times 3 = 6$).

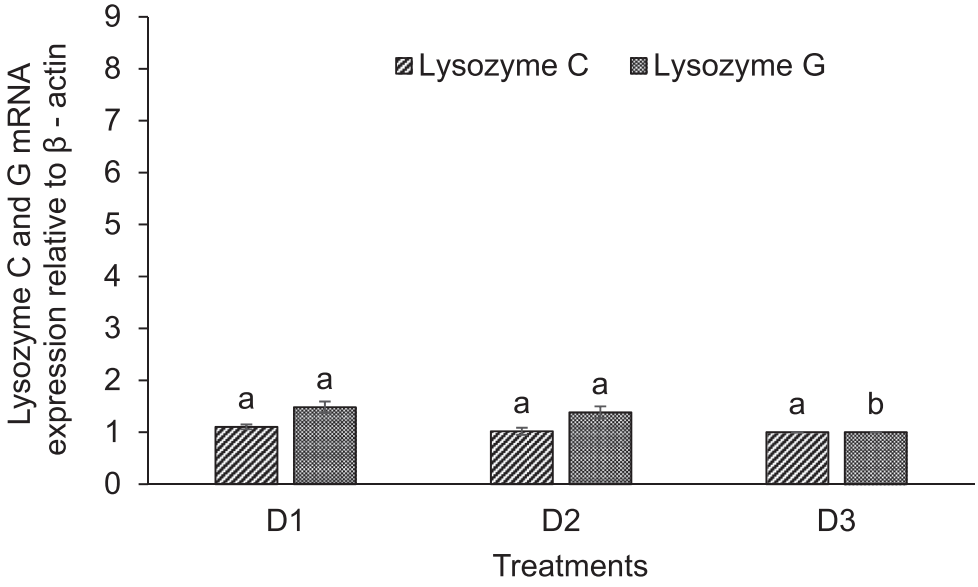


Fig. 3. Expression of lysozyme C and lysozyme G in kidney of *L. rohita* fed with three different diets and challenged with *A. hydrophila*. The relative expression of the target gene lysozyme C/G was normalized to the expression of β-actin (internal control) and expressed as fold changes relative to the control diet fed group. Vertical bars with different superscripts are significantly ($P < 0.05$) different (2 fish hapa^{-1}, 3 hapas treatment^{-1}; $2 \times 3 = 6$).

expression was found in D2 diet fed fish compared to others. Similar trend was also found with TLR-4. There was up-regulation ($P < 0.05$) of TLR-4 in hepatopancreas and kidney of rohu fed with D1 and D2 diets, respectively compared to D3 diet fed fish (Fig. 7).

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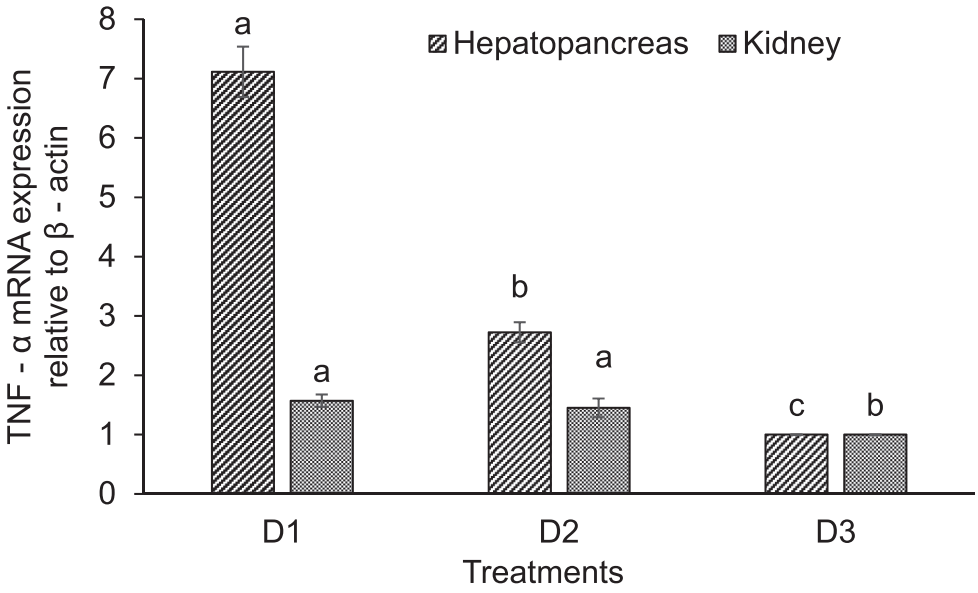


Fig. 4. Expression of TNF-α in hepatopancreas and kidney of *L. rohita* fed with three different diets and challenged with *A. hydrophila*. The relative expression of the target gene TNF-α was normalized to the expression of β-actin (internal control) and expressed as fold changes relative to the control diet fed group. Vertical bars with different superscripts are significantly ($P < 0.05$) different (2 fish hapa^{-1}, 3 hapas treatment^{-1}; $2 \times 3 = 6$).

4. Discussion

The feeding of rohu fry with *A. aspera* seeds and leaves enriched diets showed very positive effect even in the pond conditions. The mortality rate was highest in the control diet fed fish. The cumulative mortality rate of fish was 28–48% reduced in

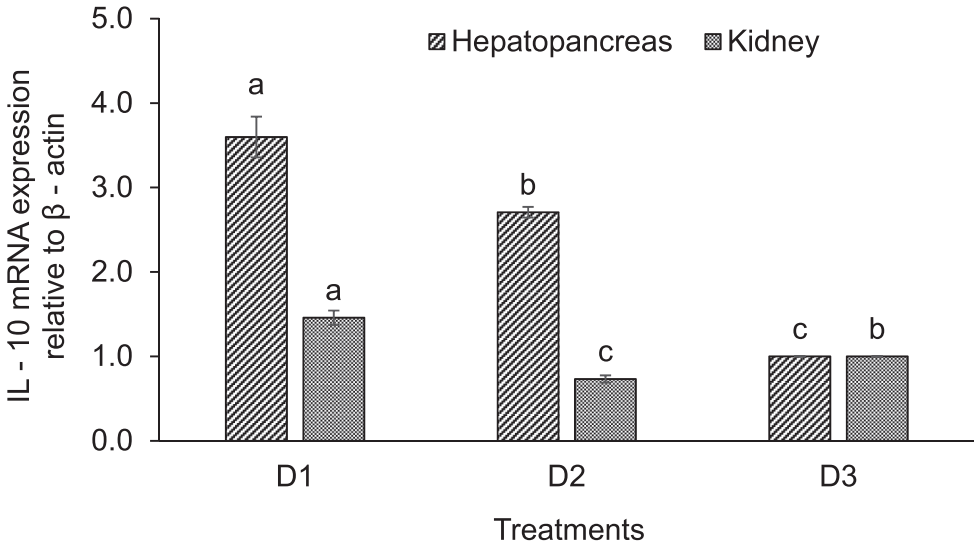


Fig. 5. Expression of IL-10 in hepatopancreas and kidney of *L. rohita* fed with three different diets and challenged with *A. hydrophila*. The relative expression of the target gene IL-10 was normalized to the expression of β-actin (internal control) and expressed as fold changes relative to the control diet fed group. Vertical bars with different superscripts are significantly ($P < 0.05$) different (2 fish hapa^{-1}, 3 hapas treatment^{-1}; $2 \times 3 = 6$).

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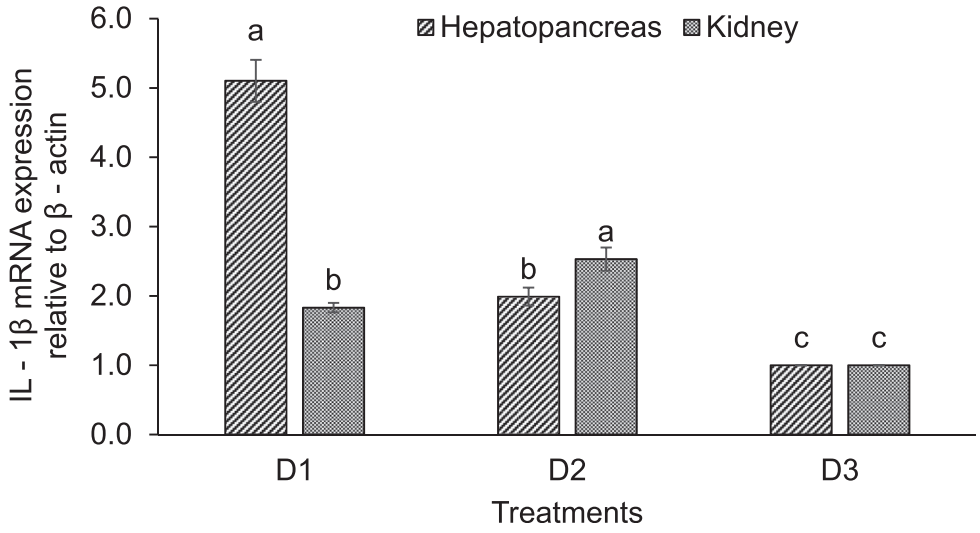


Fig. 6. Expression of IL-1β in hepatopancreas and kidney of *L. rohita* fed with three different diets and challenged with *A. hydrophila*. The relative expression of the target gene IL-1β was normalized to the expression of β-actin (internal control) and expressed as fold changes relative to the control diet fed group. Vertical bars with different superscripts are significantly ($P < 0.05$) different (2 fish hapa^{-1}, 3 hapas treatment^{-1}; $2 \times 3 = 6$).

enriched diet fed rohu. Like earlier laboratory based study, best result was obtained in the seeds supplemented diets fed rohu compared to the other feeding regimes. This is the first report showing immunostimulatory and disease resistance properties of leaves of *A. aspera*. In laboratory experiments, early larvae and fingerlings of rohu were fed with seeds supplemented diets and then challenged with *A.*

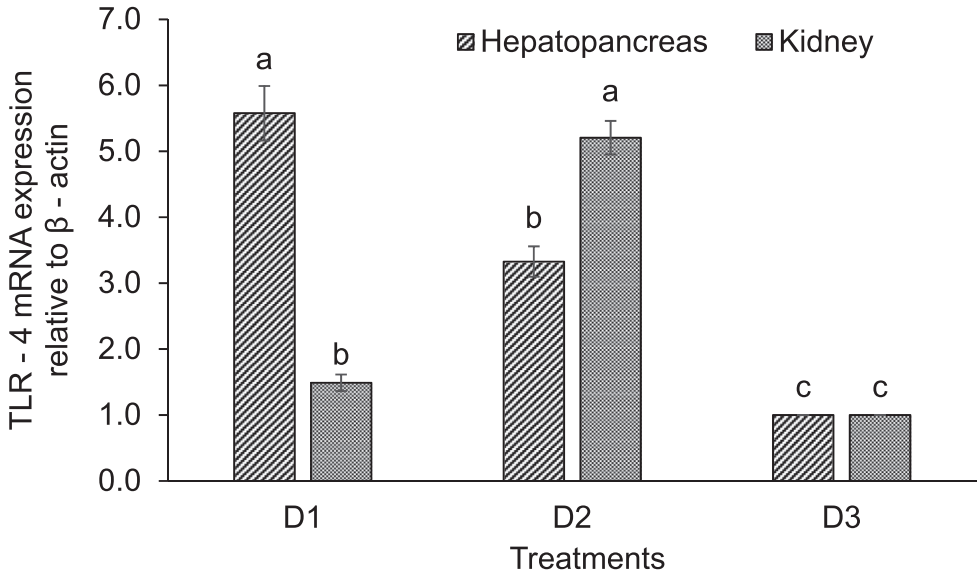


Fig. 7. Expression of TLR-4 in hepatopancreas and kidney of *L. rohita* fed with three different diets and challenged with *A. hydrophila*. The relative expression of the target gene TLR-4 was normalized to the expression of β-actin (internal control) and expressed as fold changes relative to the control diet fed group. Vertical bars with different superscripts are significantly ($P < 0.05$) different (2 fish hapa^{-1}, 3 hapas treatment^{-1}; $2 \times 3 = 6$).

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hydrophila. Significantly lower mortality was found in seeds supplemented diets fed rohu compared to the control one [10, 30]. This is clear from the study that *A. aspera* provides protection against bacterial pathogen to all age groups of rohu in control laboratory conditions as well as in natural pond.

Like earlier study conducted in the laboratory conditions, growth stimulatory property of plant supplemented diet was observed in rohu fry cultured in pond. The average weight was 6.5−12.5% higher in rohu fed with 0.5% seeds supplemented diet compared to other two feeding regimes in the present study. Enhanced growth of fish was also found in leaves supplemented diet fed fish compared to the control one in the pond study. Giri et al. [6] found that supplementation of leaves of other plant, the guava leaves at 0.5% level enhanced the growth of rohu compared to the control diet fed fish. The growth of fish is an indicator of health status that influences the other physiological conditions. In a laboratory study, common carp larvae fed with 0.5% seed supplemented diet showed higher average weight compared to the fish fed with control diet [20]. Enhanced growth and survival are the basic requirements of successful aquaculture. In the present study, these two primary requisites are achieved in the pond conditions. The study of immunological and oxidative stress parameters and gene expression supported these two basic observations.

Higher levels of myeloperoxidase and nitric oxide synthase showed the efficient immune system of rohu in the present study. This pond study confirmed the earlier laboratory experiments. Enrichment of diets with plant ingredients improved the efficiency of the immune system. Seeds are superior to leaves. A tissue-specific physiological activity was recorded in the present study as nitric oxide synthase level was always higher in hepatopancreas compared to the kidney of rohu cultured in the same feeding regime. Myeloperoxidase and nitric oxide synthase are indicators of the immunological status of the fish. Myeloperoxidase shows antimicrobial activity. It occurs abundantly in neutrophil granulocytes; elevated level of myeloperoxidase helps in the destruction and elimination of invading pathogens from the host body [39, 40]. Nitric oxide synthase catalyzes the production of cellular signalling molecule nitric oxide that plays vital role in defence mechanism of fish [41]. In the present study, the elevated levels of myeloperoxidase and nitric oxide synthase indicated the improved defence system of rohu fed with plant supplemented diets. Supplementation of seeds of *A. aspera* enhanced the nitric oxide synthase level in catla [42]. The presence of long-chain polyunsaturated fatty acids such as linolenic and oleic acids in the seeds [20] may be associated with the immunostimulatory properties of rohu challenged with bacterial pathogen in the present study.

Feeding of fish with enriched diets stimulated the immune system and as well as reduced the stress in fish [14, 24, 26]. This was evident from the lower levels of TBARS and carbonyl protein in hepatopancreas and kidney of enriched diets fed fish compared to the control fish in the present study. The study also showed that

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hepatopancreas was more sensitive to stress compared to kidney as TBARS and carbonyl protein levels were highest in the former regardless of feeding regime. Seeds showed better performance in stress reduction compared to the leaves; still the latter was better compared to the control treatment. Elevated levels of TBARS and carbonyl protein are indicators of oxidation of tissue lipid and protein, respectively. Lipid peroxidation is a well-established mechanism of oxidative damage caused by reactive oxygen species [43]. Lipid peroxidation is the process of oxidative degradation of PUFA and its occurrence in biological membranes causes impaired membrane function, structural integrity and inactivation of several membrane-bound enzymes [44]. Lipid peroxidation may bring about protein damage by its end products, MDA and 4-hydroxynonenal [45]. Fish challenged with bacterial pathogen were prone to oxidation of lipid and protein. Dietary supplementation of plant ingredients reduced oxidative stress in rohu in the present study.

In the present study, lysozyme C, lysozyme G, TNF-α, IL-10, IL-1β and TLR-4 were up-regulated in hepatopancreas of enriched diets fed rohu compared to the control one after challenged with *A. hydrophila*. The expressions were higher in seeds supplemented diet fed rohu compared to the fish fed with leaves supplemented diet. In kidney of same rohu, most of these genes were up-regulated compared to the control diet fed fish, except lysozyme C and IL-10. IL-10 was down-regulated in leaves supplemented diet fed rohu compared to the control diet fed fish. In kidney, lysozyme G, TNF-α, IL-10 expressions were higher in the seeds supplemented diet fed rohu compared to the leaves supplemented diet fed fish, whereas, expressions of IL-1β and TLR-4 showed the opposite trend. The feeding of rohu fingerlings with other plant ingredient, ginger (root of the plant) showed up-regulation of IL-10, transforming growth factor-beta (TGF-β) in head kidney, intestine and hepatopancreas [8]. A significant difference was found in the expression pattern of IL-1β, TNF-α, lysozyme C and lysozyme G in *E. tarda* infected and un-infected rohu [29]. In rohu challenged with *A. hydrophila*, a significant up-regulation of IL-10 and down-regulation of IL-1β and TNF-α was reported in treated group compared to control [30]. This showed the response of these genes in presence of pathogen. In rohu fed with other plant leaves, the guava leaves supplemented diets, there were up-regulations of IL-1β, TNF-α in head-kidney, intestine and hepatopancreas, whereas, IL-10 was down-regulated [6]. Significantly higher expressions of lysozyme, TNF-α and IL-1β were observed in common carp fed with jujube *Ziziphus jujube* [1], ferula *Ferula assafoetida* [46] and loquat *Eriobotrya japonica* [47]. In another study, common carp fed with guava leaf powder enriched diets showed significant up-regulation of IL-1β while there was no change in the expression of TNF-α [7]. The expressions of NOD 1 and TLR-22 were higher in liver compared to kidney [48]. Tissue-specific expressions of various genes were reported in catla [42]. Similar results were also found in the pond experiment with rohu as the

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expressions of various genes were higher in hepatopancreas compared to kidney of fish cultured in the same feeding regime.

5. Conclusions

In conclusions, dietary supplementation of *A. aspera* seeds and leaves enhanced the growth of rohu, induced the immune system, reduced oxidative damage of tissue and protected fish from bacterial pathogen. There were up-regulations of most of the genes in enriched diets fed rohu compared to the control group. Seeds showed better performance compared to the leaves. The bioactive compounds present in seeds are beneficial for the fish health. This plant ingredient has immense prospect in the production of healthy fish in ponds.

Declarations

Author contribution statement

Rina Chakrabarti: Conceived and designed the experiments; Performed the experiments; Analyzed and interpreted the data; Contributed reagents, materials, analysis tools or data; Wrote the paper.

Neelesh Kumar: Performed the experiments; Analyzed and interpreted the data; Wrote the paper.

Jaigopal Sharma: Conceived and designed the experiments; Performed the experiments; Contributed reagents, materials, analysis tools or data; Wrote the paper.

Samar Pal Singh: Performed the experiments; Analyzed and interpreted the data.

Amarjeet Singh, V Harikrishna: Performed the experiments.

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Competing interest statement

The authors declare no conflict of interest.

Additional information

No additional information is available for this paper.

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Nutritional analysis of cereal bars formulated using *Morinda citrofolia* and *Bacopa monnieri*

Rupanjali Pathak, Vandana Thakur and Rajinder Kumar Gupta

Abstract
The present formulation of both herbs with amalgamated food ingredients has been found to be beneficial for health. Cereal bars are products which are manufactured with cereal grains and the other ingredients such as fruits, legumes, dehydrated or crystallized fruits, nuts, chestnuts, almonds, candies, chocolates, sugar, etc. So, the fortified herbal cereal bars are the new way to provide a synergistic effect. It contains high protein, low carbohydrates, high fiber, vitamins, minerals, low sodium, and antioxidants. The bars were prepared using Noni and Brahmi herbal extracts and other ingredients like puffed rice and chocolate. Brahmi has a marked ability to enhance memory power and also it has many beneficial health effects and noni has high rich source of antioxidants and it also has beneficial neural effects and other disease prevention properties. These herbs are sources of bioactive phytochemicals. The bars were formulated in three different formulations. One is standard with no herbs and other two containing herbal mixture with 2% and 4% formulation. Estimation of antioxidants, total flavonoid, total phenolics and saponin content were also done. Formulated bars were also tested for various sensory and nutritional components and were found to be a good source of energy. The fiber content for cereal bar containing 2% herbal mixture and 4% was 2.03±0.65 and2. 43±0.26 percent. It was also found that these bars contain high amount of carbohydrate (Standard: 50.50±0.34, F-I50. 63±0.43, F-II 50.45±0.80) and fats (Standard: 29.25±0.06 F-I 27.34±0.81, F-II 25.26±0.04). The overall acceptability of three selected formulations was evaluated and it was found to be acceptable.

Keywords: formulated bars, nutritional analysis, sensory analysis, phytochemical analysis

1. Introduction
In today's world, people are more health conscious and keep safety limits in eating habits. These modern lifestyle are big contributors for causing illness and poor health (Shridhar G, *et al*., 2015) [1]. In fact, for teenagers and school going children too it is seen to be affected. Basically, these foods contain artificial coloring and preservatives which cause ill health affects (Iriti M *et al*., 2010) [2].

Organic agricultural products and herbs have been used in foods and edible items since ancient times (Gottardi, N *et al*., 2016) [3]. Food items mixed with herbal extracts or formulations have gained popularity for its taste, health benefits, detoxifying properties and formulations. As a result of the lifestyle changes foods are being changed to ready-to-eat form so that in one bite one can get a healthy diet.

In lieu of the above discussed things a formulation of herbs with chocolate bar is prepared and checked for various nutritional analysis and chemical tests to determine the presence of useful components in bars.

The two herbs are as follows:
1. *Bacopa monnieri*
2. *Morinda citrofolia*

1.1 *Bacopa monnieri*: *Bacopa* is a plant of the kingdom Plantae with small oval shaped leaves (Veena S Kasture *et al*., 2016) [4]. It has been used for various types of diseases and as traditional medicine from ancient times (Yuan, M *et al*., 2016) [5]. Basically the plant herb has no aroma and is bitter in flavor and taste if consumed at high dose. It supports to provide *in vitro* antioxidant and cell protective effects (Mukherjee A *et al*., 2017) [6]. *Bacopa* is mainly known for its activity to increase and improve memory enhancing power. It is also beneficial for respiratory diseases. *Bacopa* is mixed in combination with ghrita and in ayurvedic medicine it is known Brahmi ghrita. (Yadav KD and Reddy KRC, 2015) [7]. Brahmi marmalade is also available as food products in the market.

1.2 *Morinda citrofolia*: (Noni)
Morinda citrofolia is an herb of the native of southeast Asia and Australia commonly known as

Noni, Great *Morinda*, cheese, fruit, etc. and it bears small fruit in the shape of mulberry and is usually green in color with a fishy odor (Wang MY *et al*., 2002) [8]. Noni is mainly used for therapeutic and pharmacological functions. Mainly it consists of active compounds shown to inhibit antibacterial and immunological functions (Krishnakumar NM *et al*., 2015) [9]. Roots of Noni contain anthraquinone compounds which are proven to have shown antibacterial agents along with it consists of 1-methoxy -2 –formyl-3-hydroxy anthraquinone which can suppress the cytopathic, effect of HIV infected MT-4cells, without inhibiting cell growth (Umezawa K, 1992) [10].
The proposed formulated cereal bar consists of dark chocolate and puffed rice as a base material.

Dark Chocolate: Chocolate is good for the heart. It contains 70% cocoa. Chocolate is a favorite compound for all ages, especially children and also it has enough beneficial factors in terms of health concerns. It is highly rich in antioxidant and has cardiovascular benefits and is proved to reduce heart diseases, stroke, etc. Cocoa derived products and chocolate has suggested to play an important role in various kinds of severe diseases due to its high flavanol containing compounds (Engler *et al*., 2004) [11]. It contains high calories approximately in a range of 225-325 kcal (1000-1500kJ).

Puffed Rice: Puffed Rice is known as murmure is derived by heating rice kernels under high pressure in the presence of steam. It imparts a crispy, white in color, appearance and is used in many Indian Dishes. There are many useful benefits of using puffed rice as it increases and keep the shelf life extended. It increases the volume of projects and also there are less chance of growing microbes in puff rice. Yukwa a dish prepared in Korea has found out that the oil, puffed rice kernels has much extended shelf life than those puffed with air (Shin. *et al*., 1990) [12].

2. Materials & Methods

2.1 Reagents
The analytical grade reagents and solvents used in the sample preparation were purchased from local suppliers of Indchemie Pharma, Mumbai.

2.2 Main Ingredients
All the ingredients- Dark Compound Chocolate, Puffed Rice, butter were procured from the local market of North Delhi (India). Upon arrival all these ingredients were stored in refrigerator until usage.

2.3 Herbal extract
Bacopa monnieri and *Morinda citrofolia* herbal extracts were obtained from Kisalaya herbals limited, Indore.

2.4 Formulation of Cereal Bars
2.4.1 Cereal bars were prepared in three different formulations

Table 1: The formulations of cereal bars

Formulation	Puffed Rice (g)	Chocolate (g)	Herbs (g)
Standard	100	200	_
F-I	50	200	2
F-II	50	200	4

2.4.2 Procedure for formulation
All the ingredients were weighed in right proportions. The compound chocolate was melted at 50 ◦ C in a water bath and mixed with the herbs. The melted chocolate was poured into a plain vessel and puffed rice was spread over it one more layer of the melted chocolate was poured over the puffed rice grains to make a double layer. The prepared bar was refrigerated till further usage

2.5 Determination of nutritional constituents
For nutritional analysis the formulated bars were crushed in mortar and pestle.
Moisture and total ash content were determined by AOAC methods (AOAC, 2000) [13]. The determination of Fat content and total protein content was done by following the methods described by S. Ranganna, S. (Ranganna, 1999) [14]. Crude fibre content was assessed using the AOAC method (AOAC, 2000). Total Carbohydrate was estimated by Phenol-Sulphuric acid method described by Brand-Miller J and Holt S (Brand-Miller J, Holt, 2010) [15].

2.6 Antioxidant activity evaluation
2.6.1 DPPH free radical scavenging activity
DPPH free radical scavenging activity was analyzed by the method of Blois, (2000) [16] with slight modification as described in the paper.

2.7 Sensory Evaluation of formulating Biscuits
The sensory qualities, particularly the flavor attributes, are essential to be measured subjectively (S Ranganna, 1999) [14]. The main objective behind the sensory analysis is to check the overall acceptability of the formulated biscuits. The samples were evaluated for color, flavor, crisp and general acceptability using a 9 point hedonic scale where 9 was equivalent to like extremely 1 meant dislike extremely as described by Ihekoronye and Ngoddy (1985) [17].

Table 2: Sensory analysis chart

Score	Hardness scale
9	Like extremely
8	Like very much
7	Like moderately
6	Like slightly
5	Neither like nor dislike
4	Dislike slightly
3	Dislike moderately
2	Dislike very much
1	Dislike extremely

2.8 Stability evaluation
Cereal bars are kept under refrigerated cold conditions for days and their stability evaluation was checked under both normal and low temperature conditions.

2.9 Statistical analysis
All the experiments were carried out in triplicate and replicated at least twice. Results are expressed as average ± standard deviation (SD).

2.10 Microbial analysis
Total plate count agar Media was prepared and autoclaved at 121 ◦ C for 15 mins at 5 psi. Meanwhile 10gm sample was crushed and dissolved in 90ml saline water. Further dilutions were made 10^{-9} concentration. Further 1ml of sample from the concentration of 10^{-3} and 10^{-6} of was plated and incubated in bacteriological incubator for 24 hours at 37 ◦ C. There after the results were recorded according to the number of microbial colonies appeared on the plate. (FSSAI Manual. 2015) [18].

3. Results

3.1 Nutritional Analysis OF Cereal Bars

Table 3: The nutritional composition of formulated bars

Composition	Standard	F1 – 2%	FII -4%
Protein (%)	2.2±0.15	3.1±0.28	3.2±0.34
Fat (%)	29.25±0.06	27.34±0.81	25.26±0.04
Carbohydrate (%)	50.50±0.34	50.63±0.43	50.45±0.80
Crude fibre (%)	1.39±0.36	2.03±0.65	2.43±0.26
Moisture (%)	15.62± 0.58	17.03±0.43	19.01±0.54
Ash (%)	1.03 ±0.36	1.02±0.45	1.33±0.36

3.2 Energy Value

Table 4: Energy value of formulating cereal bar

Composition	Energy value (k Cal/ 100gm)
Standard	474.05
F-I	460.98
F-II	438.86

3.3 Determination of antioxidant activity

Table 5: DPPH assay of various herbal extracts and bar

Herbal extracts	% Inhibition
Herbal mixture	74.40±0.08
Standard	85.00±0.09
F-I	85.23±1.22
F-II	88.56±0.06

3.4 Sensory analysis

Table 6: Sensory analysis chart

Formulation	Appearance	Taste	Flavor	Texture	Overall acceptability
Standard	6±0.57	8±0.81	8±0.57	7±1.29	7±0.5
F-I	6±0.57	8±0.5	8±0.57	7±0.67	7±0.5
F –II	6±0.67	7±0.56	7±0.67	7±0.34	7±0.5

4. Discussions

4.1 Sensory analysis

The cereal bars were formulated using mixtures of Brahmi and Noni extract in different concentration (2gm and 4gm). These bars were evaluated on the basis of various sensory parameters. The analysis showed that the cereal bars of 2% herbs had different taste as compared to those containing 4%. It was also observed that all cereal bar formulations did not differ as far as sensory parameters. In most of the cases, the scores for the sensory attributes were in the range of 6 to 8 hedonic scale, which shows their moderate acceptability. Thus, both the formulations were found suitable for consumption. These formulations were then analyzed for different physico-chemical characteristics.

4.2 Discussions on nutritional analysis

The different physicochemical characteristics of the various formulations are reported in the table.

4.2.1 Total protein

From the results it is observed that the protein content was in the range of 2-3%, which is very less. Most of the cereal bars that are available in the market have a relatively very high amount of proteins. The less amount of protein in our formulations may be due to less use of puffed rice (25% only). Brito *et al*. (2004) [19] formulated cereal bars with oat flakes, corn glucose and sucrose and obtained higher protein values in between (7- 8).

4.2.2 Crude fiber

It is found that the total crude fiber of cereal bars formulated with an herbal mixture (2%) and (4%) was 2.03 and 2.43 times respectively higher than the cereal bar standard. According to Mattos and Martins (2000) [20], the value found for fibers in their formulated bars were in between 4.10 and 4.60 g/100gm and they considered these bars as a product of moderate fiber content Therefore, the cereal bars formulated in this work contain less fiber.

4.2.3 Carbohydrate

The formulated cereal bars presented a higher carbohydrate content (50-51), if compared to other bars (Santos *et al*., 2011) [21]. This may be due to the addition of dark compound. The incorporation of herbs along with cocoa allows an increase in the amounts of carbohydrates.

4.2.4 Fat

The fat content in the formulated bars is found to be higher due to the incorporation of dark chocolate. As compared with other cereal bars formulated with a jackfruit (Santos. *et al*) the fat content is found to be much higher in the formulated herbal cereal bars.

4.2.5 Moisture

The moisture content in the formulated bars is found to be in the range of 15-20. Torres *et al* 2011 [22] used exotic fruits to produce cereal bars, that resulted in 23.46% of moisture in the formulated bars and Freitas and Moretti *et al*. 2006 [23], produced cereal bars on the basis of textured soy protein and wheat germ, toasted, with values of 10.71% moisture and ash 2.20%. In comparison to these the formulated herbs show less amount of moisture and ash content which indicates that the product can absorb less moisture and is stable. Lima *et al* [24]., using cashew to produce cereal bars, reported 7.40% of moisture, 9.73% of protein, 1.63% of ash, 9.70% of lipids and 5.84% of the fiber. Freitas and Moretti *et al*. 2006 [23], produced cereal bars with textured soy protein and wheat germ verified10. 71% moisture. Compared these levels are close to those obtained with the bars formulated in this work, except for protein content.

4.2.6 Energy Value

The energy value found in the bars is between (400-475) kcal/100gm.

5. Antioxidant activity

Antioxidants have free radical scavenging properties. Free radicals are highly reactive oxygen species are capable of oxidizing bio-molecules viz. Nucleic acids, proteins, lipids and DNA and can initiate the process of different degenerative diseases like neurological disorders, cancer, emphysema, cirrhosis, atherosclerosis, arthritis etc.

The result indicated that water alcoholic extract and formulated bars exhibited potent antioxidant activity by inhibiting DPPH free radicals, which indicates that they are rich in antioxidant phytochemicals specially saponins, phenols flavonoids etc.

6. Antimicrobial Activity

The Results of antimicrobial activity were found to be too less to count. Antimicrobial activity was done both for 15 days and

a 22 day period. The results of both showed negligible microbes.

7. Conclusion

The Cereal bars are easy to manufacture and keeping in view the cost of ingredients, the nutri bars can be sold at a low price. These products can be conveniently added to a packed lunch or eaten as a snack. The growth of functional foods may expand the options for curing health disorders and for providing health benefits (Lobato, LP *et al*.,2011) [25]. The herbal nutri bars formulated in this study were well accepted in the sensory analysis. Although during storage, however, the bars became dry in appearance and there was an increase in hardness when kept in refrigerator. While at normal temperature they retained the normal texture. Slight modifications in formulation may prevent these kind of problems. The antioxidant activity of the bars is found to be high. It signifies that they are good in free radical scavenging activity. Incorporation of herbs provides the bars a different taste along with the herbal benefits. Brahmi and Noni both help protect our bodies against many diseases and especially Brahmi is good for mental health. The formulated cereal bars are found to be rich in phenolic content, flavonoids, and also they have a better shelf life.

Finally the fortification process helps food to enrich their quality along with a great value of micro and macronutrients.

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Performance Analysis of Evolutionary Optimization Techniques for Economic Dispatch Problem

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Abstract: *This paper deals with comparisons of different evolutionary optimization techniques for the solution Economic Dispatch Problem (EDP) in power system. The main principle behind the evolutionary techniques is inspired by the biological evolution of the living organisms. Economic Dispatch problem deals with optimizing the operational cost of the online generators with fulfilling the consumer end power demand. Scheduling the practical generation units involves the complex limitations. Among these limitations valve point loading effect is included in this work for increased convolution. In this paper, the evolutionary optimization techniques such as the Real Coded Genetic Algorithm (RCGA), Binary Coded Genetic Algorithm (BCGA), Particle Swarm Optimization (PSO), Simulated Annealing (SA) and Artificial Immune System (AIS) are simulated for EDP for its performance analysis. These optimization algorithms are validated for three, thirteen and forty generating systems and their results are compared. From these results, the elite and the most suitable algorithm are found for solving the EDP.*

Keyword: *Artificial Immune System (AIS); Binary Coded Genetic Algorithm (BCGA); Economic Dispatch Problem (EDP); Evolutionary optimization Techniques; Particle Swarm Optimization (PSO); Real Coded Genetic Algorithm (RCGA); Simulated Annealing (SA).*

1. INTRODUCTION

In the power system operation and control, the generation sector cost optimization plays a vital role. If the cost of power generation increases, then the consumer tariff gets drastically hiked. Also the available fossil fuel gets depleted quickly. Among the fossil fuels, the coal is abundantly available and the amount of power produced is high. In this article, the coal power generating units are taken into account for the optimal operation. So for decreasing the tariff, the efficient utilization of coal generating units is the only solution. The efficient operation of these generating units is possible by the Economic dispatch problem. This EDP deals with determining the optimal power output of a certain set of generators to fulfill the system demand and other operational limitations with minimal operational cost.

Generally large turbo generators in coal fired thermal generating units have a set of valves at the inlet to the steam turbine. With the increase in power demand these valves are opened sequentially. The throttling loss in a valve is large, when it is just opened and is small when it is fully opened. This loss is termed as a valve point loading effect, which makes the cost curve highly nonlinear.

Over the recent years, the EDP is solved with the traditional mathematical methods include [linear programming (LP) [1], Dynamic Programming (DP) [2], Quadratic Programming (QP) [3].These methods are

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very good at solving the EDP, but if the nonlinearity of the problem increases, then the problem solving is complex and time consuming.

To overcome these hardships, the evolutionary meta-heuristics techniques [4] are widely used to solve ED Problems. The recent methods include Genetic Algorithm (GA) [5], Particle Swarm Optimization (PSO) [6], Simulated Annealing (SA) [7], Ant Colony Optimization (ACO) [8], Harmony Search (HS) [9], Cultural Algorithm (CA) [10], Artificial Immune System (AIS) [11], Biogeography Based Optimization (BBO) [12], Bat Motivated Optimization (BMO) [13], Bacterial Swarm Optimization [14,15] are proposed to solve the EDP

Genetic Algorithm (GA) mimics the Darwin's principle of natural selection and survival of the fittest which essentially attempt to emulate evolution in biological systems to compute solutions for optimization problems have been proved to be effective in solving the optimization problem, but it suffers from premature convergence and time consuming also fail to locate global solution.

The PSO is an evolutionary optimization tool of swarm intelligence field based on a swarm (population), where each member is seen as a particle, and each particle is a potential solution to the problem under analysis, has been found to robust in solving continuous nonlinear and linear optimization problem with less computation time and stable convergence characteristic than other heuristic optimization methods.

Simulated Annealing (SA) is having the ability to search for global solutions. It is a random search technique which exploits an analogy by the way in which a metal cools and freezes into a minimum energy crystalline structure. The annealing process and search for a minimum in more general system forms the basis of an optimization technique for combinatorial and other problems. It is probabilistic based method of accepting candidate's solutions in the search process. It suffers from setting the control parameters to achieve global optimum.

In order to get the qualitative solutions for problem related to EDP, algorithms like ACO, Harmony Search (HS) & Cultural Algorithm (CA) is proposed to solve the EDP with valve point loading. But these techniques have some shortcomings in convergence and stuck in local optima.

In this article, Artificial Immune System is simulated and compared with the above mentioned techniques for optimal operation and effectiveness. Artificial Immune System (AIS) [16] are adaptive systems inspired by theoretical immunology and observed immune functions, principles and models, which apply to complex problem domain. The immune system is highly complicated and appears to be precisely tuned to the problem of detecting and eliminating infections. It mimics the human immune system and follows the clonal selection or the clonal expansion principle. This process is used to explore new search regions and also escape from local optima. The recognition and learning capabilities of natural immune system provides the property of robustness, dynamism and adaptability to AIS based algorithm.

This paper considers three standard EDP problems, namely 3, 13 and 40 generating units with incremental fuel function, including a variable percentage of the maximum power being demanded with the valve-point loading effects.

2. PROBLEM FORMULATION

The objective of the ELD problem is to minimize the total fuel cost by adjusting the power output of each of the generators connected to the grid while satisfying the demand and other operational constraints which can be described mathematically as a minimization of the problem. The modeling is determined for the total fuel cost as the sum of the cost function of each generator.

The total fuel cost, which is the basic economic dispatch problem, can be described mathematically as a minimization of the problem.

$$F_t = \sum_{i=1}^{n} F_i(P_i) + m \times \{\max(0, (P_d - \sum P_i)\} \quad (1)$$

Where $F_i(P_i)$ is the variation of fuel cost in $ with generated Power (MW) which is the fuel cost equation of the i^{th} plant. It is given by

$$F_i(P_i) = a_i + b_i P_i + c_i {P_i}^2 \quad (2)$$

To attain an exact and practical economic dispatch solution, the sensible operation of the ED problem must be examined with the valve point effects. Generally, to model the valve point effects, a rectified sinusoidal function is added to the input and output correlation. The power generating units with multi-valve steam turbines show a higher discrepancy in the fuel-cost functions. Figure 1 shows the ripple due to the valve-point, i.e., a cost function has higher order nonlinearity. Typically, the cost function taking into account the valve-point loadings of a generating unit is given in equation below

$$F_i(P_i) = a_i + b_i P_i + c_i {P_i}^2 + |e_i \sin f_i \ (P_{imin} - P_i)| \quad (3)$$

The total fuel cost is to be reduced subject to the following constraints.

$$\sum_{i=1}^{n} P_i - P_d = 0 \quad (4)$$

$$P_{imin} \le P_i \le P_{imax}; i = 1,2,..n \quad (5)$$

Where a_i, b_i, c_i are the fuel cost coefficients of i^{th} generator, e_i and f_i are the fuel cost coefficients of the

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i[th] unit with valve-points effects, $F_i(P_i)$ is the fuel cost of i[th] generator, \$/hr, F_t is the total fuel cost, \$/hr, n is the number of generators, P_{imax} is the maximum generation limit of i[th] generator, MW, P_{imin} is the minimum generation limit of i[th] generator, MW, P_d is the system power demand, MW P_i is the real power output (MW) of i[th] generator corresponding to time period t.

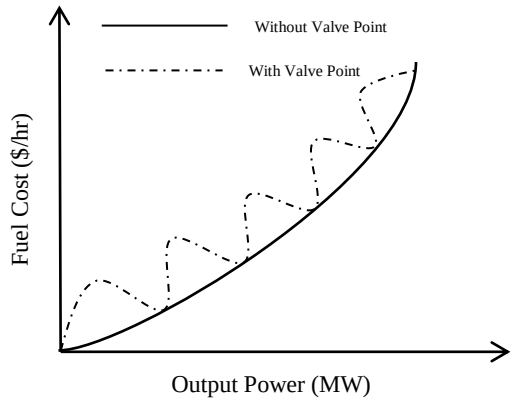


Figure 1 Incremental fuel cost versus power output steam turbine unit with valve point effect

3. ECONOMIC DISPATCH PROBLEM USING VARIOUS OPTIMIZATION ALGORITHMS

3.1 Economic Dispatch Problem Using RCGA and BCGA

For each problem of optimization in GA there are a large number of possible encodings. Although Binary coded Genetic Algorithm (BCGA) [17] is usually applied to power optimization problems. Real coded Genetic Algorithm (RCGA) [18] is a modified GA employing real valued vectors for representing chromosomes and its use of real valued representation in the GA has a several merits with optimization of function numerically over binary encoding. The efficiency of the RCGA is increased as there is no need to convert chromosomes to the binary, hence less memory is required and also there is no loss in precision by converting to binary or other values, and there is a great advantage to use different genetic operators. The procedure for BCGA is same as RCGA except for binary coding of chromosomes.

Step1: Initialize a population to generate the initial parent vectors of power outputs by choosing randomly RCGA by the implementation of probabilistic search, distributed uniformly in intervals within the limits and obtains a global optimum solution over a number of iterations.

Step2: The implementation of the RCGA is given below:
The initial population is obtained if equation (6) is satisfied. The fitness function is used to transform the cost function value into a measure of relative fitness. For representing the real valued function, the k[th] chromosome C_k can be defined as follows:

$$C_k = [P_{k1}, P_{k2}, \ldots . P_{kn}] \quad (6)$$

where $k = 1,2, \ldots$ population size
Where P_{ki} represent output power of n[th] generator of a k[th] chromosome.

Step3: Reproduction, it involves formation of a mating pool by roulette wheel selection method.

Step4: Cross over, offspring's are created from the mating of two selected parents or mating pairs. It is thought that the crossover operator is mainly responsible for the global search property of the GA. A non-uniform arithmetic crossover operator was introduced into the RGA, which produces a complimentary pair of linear combinations produced from random proportions of the parents. The heuristic crossover operator generates a child that is a linear extrapolation away from the better parent along the direction of the vector joining the two parents. Two chromosomes, selected randomly for crossover, C_{igen} and C_{jgen}, may produce two offspring, $C_{igen} + 1$ and $C_{igen} + 1$, which is a linear combination of C_{igen} and C_{jgen} i.e.,

$$C_{igen} + 1 = a \times C_{igen} + (1 - a)C_{jgen} \quad (7)$$

$$C_{jgen} + 1 = (1 - a) \times C_{igen} + a)C_{jgen} \quad (8)$$

Where a is a randomly generated number in the range of [0, 1].

Step5: In the mutation process, the non-uniform mutation operator is used to inject new genetic material into the population and individually it is applied to each new structure. A given mutation involves random alteration of each gene with a small probability. Suppose that $C = (c_1, c_i, c_n)$ and $C_i \in [up_i, low_i]$ a gene to be mutated. Next, the gene, C_i', which results from non-uniform mutation can be defined as follows:

$$C_i' = C_i + d_i \times rand \quad (9)$$

Where $d_i = (P_{imax} - P_{imin}) \times mut_scale$.
The value of mut_scale is normally set to 0.1 and $randn$ is normally distributed random numbers. The chromosomes which vi-

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olate constraints are given a penalty which will be added to the total fuel cost of those chromosomes. Hence the objective function value of chromosomes which have violated the constraints will be high. The penalty handling is shown in the procedure of PSO.

Step6: The parents and children created so in this iteration will compete with each other to form the next generation of chromosomes.

Step7: An elitist GA search is used and guarantees that the best solution obtained so far in the search is retained and used in the next generation, and thereby ensures no good solution in the previous generation can be lost in the search process.

Step8: Repeat steps 2-6 stop the process which maximum number of iterations has reached.

The important parameters in GA are tabulated in Table 1.

TABLE I GA PARAMETERS

Parameters	Size
Population size	50
Maximum no of iterations	500
Probability of cross over	0.8
Probability of mutation	0.1
Demand Penalty (m)	200

3.2 Particle Swarm Optimization (PSO)

Particle swarm optimization is a population based hypothetical optimization technique which can be applied for almost all non-linear complex optimizations in power system. It was aspired by the social behavior of organisms such as bird flocking and fish schooling and it utilizes a population based search procedure. According to the research results, birds find food by flocking hence all information is shared inside the flocking. This assumption is a basic concept of PSO. In PSO, each response is a particle and each particle in the search space regulates its flying velocity in agreement with its own flying velocity and its neighbors' flying velocity. The fitness values of all the particles are evaluated by the fitness function. The evaluated function is then optimized and has velocity, which directs the flying of particles. This operation is initialized by updating generations with a troop of random particles which search for optima.

Each particle is treated as a point in D dimensional space, and the ith particle is represented as

$$X_i = (x_{i1}, x_{i2}, \ldots . x_{id}) \quad (10)$$

The best former position of the ith particle is recorded and denoted as

$$P_{besti} = (P_{best1}, P_{best2}, \ldots . P_{bestd}) \quad (11)$$

The index of the best among the entire particle in the population is represented by the symbol G_{best}. The velocity (the rate of the position change) for particle is

$$V_i = (V_{i1}, V_{i2}, \ldots \ldots V_{id}) \quad (12)$$

The reformed velocity and position of each particle can be calculated using the current velocity and the distance from $P_{bestid}$to G_{bestid} as shown in the following equations

$$V_{id}^{j+1} = W \times V_{id}^{j} + C_1 \times rand\ (\ ) \times (P_{best\ id} - X_{id}^{j}) + C_2 \times rand(\ ) \times (G_{best\ id} - X_{id}^{j}) \quad (13)$$

Inertia weight factor

$$W = W_{max} - \frac{(W_{max} - W_{min}) \times iter}{iter_{max}} \quad (14)$$

$$X_{id}^{j+1} = X_{id}^{j} + V_{id}^{t+1} \quad (15)$$

The power outputs from each generator are taken as the particles of the PSO. Then the steps in the PSO algorithm for the economic dispatch problem are as follows:

Step1: In the Initial generations of particles and future updates of particles are generated in such a manner that the sum of the outputs of the particles equals power demand. Hence the demand is always satisfied, thus only feasible solutions are considered.

Step2: The particle velocities are generated randomly between maximum and minimum values of each particle.

Step3: Objective function values are calculated for each particle and penalties are assigned for those particles which do not satisfy the demand constraint. These values are assigned as P_{best} and minimum among these particles is assigned as G_{best}.

Step4: New velocities of the particles are evaluated using (13).

Step5: The position of each particles are modified using (15).

Step6: New objective function values are calculated for new positions of the particles. If the new values are better than previous P_{best} and G_{best} the new values are assigned to P_{best} and G_{best}.

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Step7: Repeat steps 2-6 and terminate if the maximum number of iterations are achieved.

The important parameters in PSO are tabulated in Table 2.

TABLE II PSO PARAMETERS

Parameters	Size
Population size	50
Maximum iterations	500
Wmin	0.4
Wmax	0.9
C1, C2	4
Vdmax	0.005*Pmax
Vdmin	-0.005*Pmax

3.3 Simulated Annealing

Simulated annealing (SA) is a random-search technique which exploits an analogy between the way in which a metal cools and freezes into a minimum energy crystalline structure (the annealing process) and the run in for a minimum in a general system; it forms the basis of an optimization technique for combinatorial and other problems. SA approaches the global maximization problem similar to the use of a bouncing ball that can bounce from valley to valley over mountains. The ball makes very high bounces at high "temperature", which enables it to bounce over any mountain to access any valley, given adequate bounces. The ball cannot bounce so high as the temperature declines and it can get trapped in relatively small ranges. A generating distribution generates valleys (states) to be explored and all the generating and acceptance distributions depend on the temperature and it has been proved that by carefully controlling the rate of cooling of the temperature, SA can reach the global optimum.

However, this requires infinite time and this problem is overcome by fast annealing and very fast simulated annealing (VFSR) or adaptive simulated annealing (ASA) since they are each in turn exponentially faster than SA. The major advantage of SA over other methods is an ability to avoid becoming trapped in local minima. Thus Simulated annealing (SA) is a random search approach which not only accepts changes that reduce the objective function, but also any changes that rises it. The latter is accepted with a probability

$$P = \exp\left(-\frac{\Delta f}{T}\right) \quad (16)$$

Where Δf is the increase in f and T is the system "temperature" irrespective of the objective function involved.

The steps in Economic Load Dispatch Problem Using SA is given as

Step1: Create Initial solution (power outputs of the generators) and evaluate the fitness function.

Step2: Initialize the Temperature.

Step3: Generate new solution and access new solution.

Step4: Check whether new solution can be accepted with a probability.

Step5: Update Solution if probability is satisfied.

Step 6: Adjust temperature.

Step7: Repeat steps 2-5 until maximum iteration is reached.

The important parameters in SA are tabulated in Table 3.

TABLE III SA PARAMETERS

Parameters	Size
Initial temperature	100
Final temperature	0
Incremental decrease in Temperature	0.5
Maximum iterations	100

3.4 Artificial Immune System

Artificial Immune Systems (AIS) is a diverse area of research that attempts to bridge the division between immunology and engineering and is developed through the application of techniques such as mathematical and computational modeling of immunology. AIS are adaptive systems inspired by theoretical immunology applied to complex problem domain. The AIS system is more complex and appears to be precisely tuned to the problem of detecting and eliminating infections. AI has become known as an area of computer science and engineering that uses immune system metaphors for the novel creation of solutions. AIS is presently moving into an area of true interdisciplinary and one of genuine interaction between immunology, mathematics and engineering. Researchers have proved that it also provides a compelling example of a distributed information-processing system, which can be applied for designing better artificial adaptive systems. It has two selection principles the clonal selection or clonal expansion principle and negative selection. This process is used to explore new search regions and also escape from local optima. The recognition and learning capabilities of natural

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immune system provides the property of robustness, dynamism and adaptability to AIS based algorithm. The Proposed AIS Algorithm to solve EDP is given by the following steps:

In the Proposed Artificial immune system the new population is created by mutation operator. In this proposed algorithm a step wise linear decreasing mutation scale is introduced after some fixed number of iterations. The mutation for this algorithm is taken from real coded genetic algorithm i.e., specified in equation (9).

Step1: Generate randomly initial population (Power output of generators).

Step2: Find and sort objective values in ascending order by using equation (17)

Step3: Calculate affinity value (Affinity)

$$\text{Affinity} = \frac{1}{\text{objective function}} \quad (17)$$

Step4: Calculate the cloning rate of each of the anti-body using the following equation

$$\text{Rate of cloning} = \frac{\text{Affinity value} \times \text{Pop Size}}{\sum \text{Affinity value}} \quad (18)$$

Step5: Generate clones proportional to their cloning rate. (At this stage size of the population is increased)

Step6: Apply mutation process to each clone. In this algorithm a real mutation operator is used with step wise decreasing mutation scale is used i.e. after some fixed no of iterations mutation scale is decreased.

Step7: Compare the objective values of the mutated clone with the objective values of the original antibody and retain the best clone

Step8: Sort the mutated population in ascending order.

Step9: The population size is trimmed to original size by deleting the worst solutions.

Step10: Replace a percentage of R individuals with high objective values with randomly generated ones to introduce diversity.

Step11: Go back to step 2 until convergences occurs or after reaching a certain (predetermined) number of iterations.

The important parameters in AIS are tabulated in Table 4.

Table IV AIS PARAMETERS

Parameters	Size
Population size	50
Maximum no of iterations	500
Probability of mutation	0.75

4. RESULTS AND DISCUSSION

In this paper, the five optimization algorithms such as RCGA, BCGA, PSO, SA and AIS are used to solve EDP of thermal power plants with value point loading effects. The results for 3, 13 and 40 [19] generating unit test system with non-convex fuel cost functions are presented. For the implementation of EDP of these techniques a software program is written in MATLAB and they are executed using Intel core i5 processor @1.70 GHz with 4GB RAM.

The generating unit test system for a 3 unit system with the load demand of 850MW, a 13 unit system with the demand of 1800 MW, 2520MW & 2500MW and 40 unit systems with the load demand of 10500 MW is taken into consideration.

The power dispatch results of the considered generating system are simulated with above mentioned algorithms are shown in Table 5, 7, 9, 11 and 13 respectively. From these tables it is clear that the proposed AIS outperform the other techniques.

The best, worst and average results are trailed for 50 runs and the preeminent solution is given in the Table 6, 8, 10, 12 and 14. It is clear from the table 6 that the average values of the fuel cost of the proposed AIS technique are better than the others which shows the efficacy of the considered technique.

The optimum results of 3 unit system of AIS is 8218.8204$, a 13 unit system with 1800MW is 17972.8105$, 2520MW is 24137.8296$ and for 2500MW is 23948.8531$. The results for 40 unit system that of AIS is 121429.6627$.The average value for 3 unit system for that of AIS is 8219.7732$, a 13 unit system with 1800MW is 17986.1861$, for 2520MW is 24153.3883$ and of 2500MW is 23980.6673$. The average value of 40 unit system is 121791.3054$.To validate the optimum results 50 trail runs were made and the results were recorded.

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TABLE V RESULTS OF 3-UNIT SYSTEM WITH 850MW

Method/ Unit output	RGA	BGA	PSO	SA	AIS
P1	349.4736	349.627	349.4662	349.9628	349.7662
P2	400.0000	399.9998	400.0000	399.9996	400.0000
P3	100.5264	100.3726	100.5338	100.0378	100.2340
Total fuel cost ($)	8220.6892	8220.7025	8220.6884	8220.73	8218.8204
Total power generation(MW)	850.000	850.000	850.000	850.000	850.000

TABLE VI COST COMPARISON OF 3-UNIT SYSTEM WITH 850 MW

Total fuel cost ($)			
Method	**Best**	**Worst**	**Avg**
RGA	8220.6892	8225.6759	8223.3323
BGA	8220.7025	8221.1096	8221.3978
PSO	8220.6884	8228.3639	8224.5286
SA	8220.7300	8378.3282	8299.5084
AIS	8218.8204	8220.7260	8219.7732

TABLE VII RESULTS OF 13- UNIT SYSTEM WITH 1800MW

Method/ Unit output	RGA	BGA	PSO	SA	AIS
P1	628.0000	629.0000	448.7990	628.0000	628.3185
P2	299.0000	229.0000	302.5355	225.0000	297.5489
P3	224.0000	300.0000	299.1993	296.0000	224.3995
P4	60.0000	60.0000	109.8666	60.0000	60.0000
P5	60.0000	60.0000	60.0000	60.0000	109.8665
P6	60.0000	61.0000	109.8666	60.0000	60.0000
P7	60.0000	110.0000	60.0000	60.0000	109.8665
P8	60.0000	60.0000	109.8666	160.0000	60.0000
P9	159.0000	60.0000	109.8666	60.0000	60.0000
P10	40.0000	80.0000	40.0000	40.0000	40.0000
P11	40.0000	41.0000	40.0000	40.0000	40.0000
P12	55.0000	55.0000	55.0000	55.0000	55.0000
P13	55.0000	55.0000	55.0000	56.0000	55.0000
Total fuel cost($)	17987.9	18076.1	17975.3434	18019.6	17972.8105
Total power generation (MW)	1800	1800	1800	1800	1800

TABLE VIII COST COMPARISON OF 13-UNIT SYSTEM WITH 1800MW

Total fuel cost ($)					
Method	**RGA**	**BGA**	**PSO**	**SA**	**AIS**
Best	17987.9547	18076.1725	17975.3434	18019.6772	17972.8105
Worst	18265.5741	18008.0157	18140.2845	17978.5618	17999.5618
Avg	18167.7644	18042.0941	18057.8139	17999.1195	17986.1861

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TABLE IX RESULTS OF 13- UNIT SYSTEM WITH 2520MW

Method/ Unit output	RGA	BGA	PSO	SA	AIS
P1	664.3178	628.3185	664.3183	628.3185	664.3181
P2	335.1984	299.1993	335.1941	299.1993	335.1828
P3	359.192	299.1993	359.1828	299.1993	359.1975
P4	179.7331	159.7331	129.8665	159.7331	129.8665
P5	146.7331	159.7331	146.7331	159.7331	146.7331
P6	117.8665	159.7331	167.7331	159.7331	167.7329
P7	159.8665	159.7331	159.8665	159.7331	159.8665
P8	135.0000	159.7331	135.0000	159.7331	135.0000
P9	135.0000	159.7331	134.9998	159.7331	135.0000
P10	55.1898	110.0844	86.34206	77.3999	86.3189
P11	87.7187	114.7998	56.59825	110.0844	56.6000
P12	56.5867	55.0000	56.58563	92.3999	56.5943
P13	87.5971	55.0000	87.58541	55.0000	87.5893
Total fuel cost ($)	24141.9514	24178.8346	24137.8623	24174.0762	24137.8296
Total power generation (MW)	2520.0000	2520.0000	2520.0000	2520.0000	2520.0000

TABLE X COST COMPARISON OF 13-UNIT SYSTEM WITH 2520MW

Total Fuel Cost in $					
Method	**RGA**	**BGA**	**PSO**	**SA**	**AIS [Prop.]**
Best	24141.9514	24178.8346	24137.8623	24174.0762	24137.8296
Worst	24487.7324	24421.7324	24358.9581	24300.7467	24168.9471
Avg.	24314.8419	24300.2835	24248.4102	24162.9581	24153.3883

TABLE XI RESULTS OF 13- UNIT SYSTEM WITH 2500MW

Method/ Unit output	RGA	BGA	PSO	SA	AIS
P1	664.3184	664.3183	664.3183	664.3183	664.3183
P2	260.3992	335.1785	260.3992	335.1977	260.3994
P3	359.1824	359.1876	359.1951	359.1922	359.1964
P4	179.7331	179.7331	179.7331	129.8665	179.7331
P5	146.7330	96.86642	146.7331	96.86646	146.7331
P6	167.7331	117.8665	167.7331	167.7331	167.7331
P7	159.8665	110.0000	159.8665	110.0000	159.8664
P8	134.9999	135.0000	135.0000	135.0000	135.0000
P9	135.0000	135.0000	135.0000	134.9999	135.0000
P10	55.18601	91.34222	91.35855	92.59365	91.31050
P11	56.58422	93.98903	56.5834	92.65454	56.59253
P12	92.72311	93.95845	56.57892	93.99277	56.57883
P13	87.54106	87.55988	87.50073	87.58488	87.53825
Total fuel cost($)	23949.1498	23967.9597	23948.8588	23964.0537	23948.8531
Total power generation (MW)	2500.0000	2500.0000	2500.0000	2500.0000	2500.0000

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TABLE XII COST COMPARISON OF 13-UNIT SYSTEM WITH 2500MW

Total Fuel Cost in $					
Method	**RGA**	**BGA**	**PSO**	**SA**	**AIS**
Best	23949.1498	23967.9597	23948.8588	23964.0537	23948.8531
Worst	24292.1476	24279.8475	24217.7463	24162.9581	24012.4816
Avg.	24120.6487	24123.9036	24083.3025	24063.5059	23980.6673

TABLE: XIII RESULTS OF 40- UNIT SYSTEM WITH 10500MW

Unit	**AIS**	**Unit**	**AIS**
1	113.9944	21	523.2794
2	110.9617	22	523.2794
3	97.39991	23	523.2794
4	179.7331	24	523.2794
5	90.1231	25	523.2794
6	140.0000	26	523.2794
7	259.5997	27	10.0000
8	284.5997	28	10.0000
9	284.5997	29	10.0000
10	130.0000	30	91.44074
11	94.0000	31	190.0000
12	168.7998	32	190.0000
13	214.7598	33	190.0000
14	394.2794	34	164.8370
15	394.2794	35	200.0000
16	304.5196	36	200.0000
17	489.2794	37	110.0000
18	489.2794	38	110.0000
19	511.2794	39	110.0000
20	511.2794	40	511.2794
Total fuel cost ($)			121429.6627
Total power generation (MW)			10500.0000

TABLE XIV COST COMPARISON OF 40-UNIT SYSTEM

Total Fuel cost in $					
Method	**RGA**	**BGA**	**PSO**	**SA**	**AIS**
Best	121519.3287	121568.6587	121493.1624	121524.0357	121429.6627
Worst	123852.7251	122382.9581	123252.5651	122632.6291	122152.9451
Avg	122686.0269	121975.5605	121922.8327	122078.3324	121791.3054

5. CONCLUSION

This paper proposes the Real Coded Genetic Algorithm, Binary Coded Genetic Algorithm, Particle swarm optimization, Simulated Annealing and Artificial Immune System technique to solve economic dispatch problem of 3, 13 and 40 generating unit test system with non-convex fuel cost function for different load demand. The above presented algorithm is simulated and validated for its performance. The best and average results clearly propose that the Proposed AIS gives better fuel cost than the other techniques. Further, it is applicable for distribution scheduling problem.

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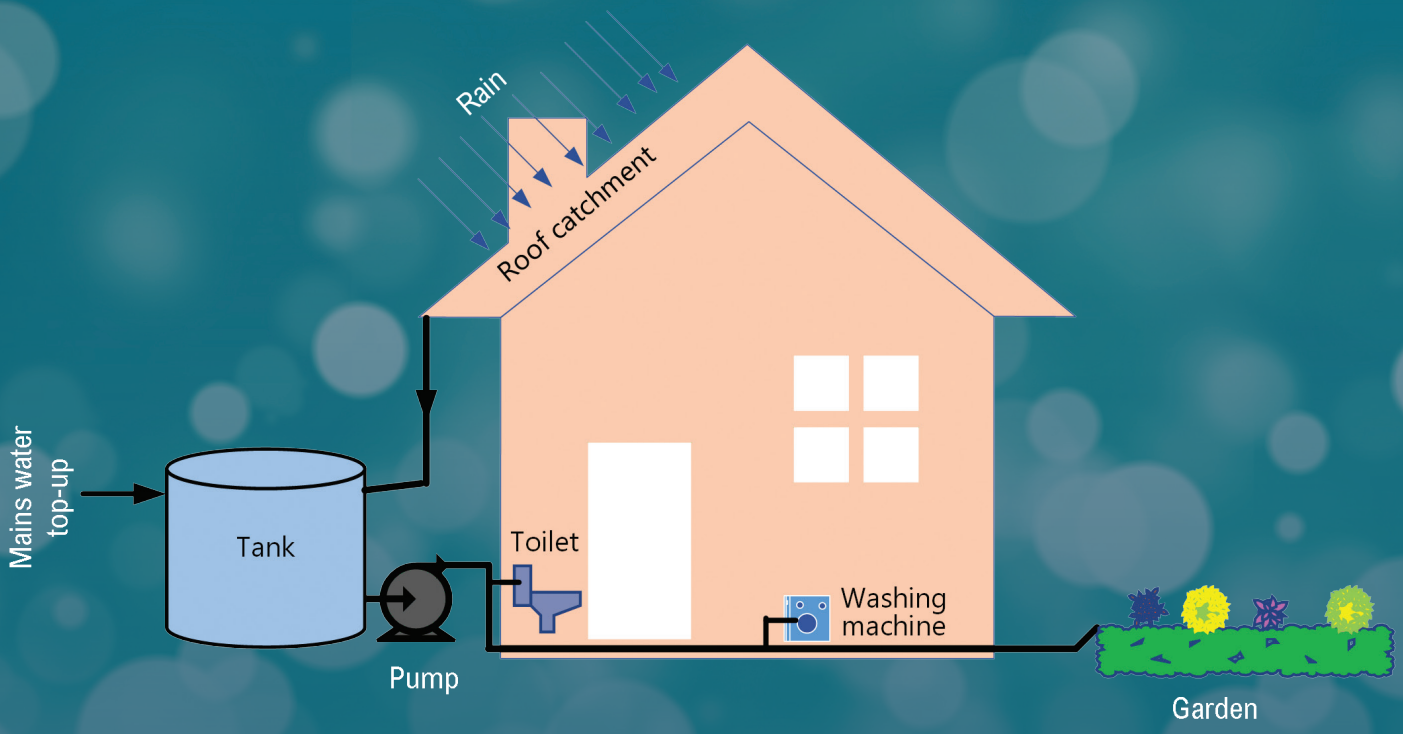
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Design, Yield, Energy, Health Risks, Economics and Social Perceptions

Ashok K. Sharma, Donald Begbie and Ted Gardner



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Adjunct Professor Ted Gardner (University Sunshine Coast) is a retired scientist with a number of adjunct appointments with regional universities in Queensland, where he enjoys interacting with students. Prior to his retirement in 2010, Ted was Principal Research Scientist in the Integrated Urban Water Systems group of CSIRO Land and Water. He led the Urban Water Security Research Alliance funded projects into decentralised technologies, and storm water harvesting and reuse in South East Queensland. He was also the Principal Scientist with the Queensland Department of Environment and Resource Management, leading the Urban Water Cycle group which focused on soil physics, irrigation and catchment hydrology/salinity, effluent reuse, and urban water sustainability. Ted has won several achievement awards, including the 2005 Australia Day Award Public Service Medal for his work on water recycling and urban water supply. In 2014, he was award the biennial McLean-Idema award from Irrigation Australia for his career work on irrigation using recycled water. He has an extensive publication record including over 200 peer reviewed journal and conference papers, 3 book chapters, editor of a scientific monograph on purified recycled water, and has made numerous presentations to technical and community groups. Ted completed his Bachelor of Agricultural Science and Masters of Agricultural Science at the University of Queensland.

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Foreword

A book on rainwater tanks! Really? What is there to write about concerning those concrete, plastic or corrugated iron structures that many will associate as the source of water on rural or remote properties where the water distribution system has not reached? Haven't they been around for ages? Do you not just install them and allow them to fill from rainwater runoff from a roof or from pumped groundwater? Then doesn't gravity cause the water to flow to taps, hot water systems, toilets and gardens? So simple, so established, so what?

What, however, if we wish to include rainwater tanks as part of a regional water supply system, whether rural, urban or in-between? Are rainwater tanks an efficient means of reducing demand from other water supplies? Is the water in urban rainwater tanks suitable for drinking? Does plumbing the tanks into a household for non-drinking purposes make sense? How energy efficient are rainwater tanks? What are the maintenance requirements? What is the public acceptability of such tanks in an urban setting where there are other options for supplying water? Are there alternatives to small-scale rainwater harvesting? What is the trade-off between keeping spare capacity in a rainwater tank to capture the first flush of stormwater, thereby reducing the environmental load, as opposed to keeping the tank as full as possible to maximize available supply?

While individual articles address these and many other questions, this book is unique in bringing together the many aspects of this deceptively simple device – the rainwater tank. The chapters are informed both by the past findings of others and the latest research results. The motivation for the book was the extended extremely low rainfall period endured by south-east Queensland in the early part of this century and the impact that this was having on the communities that lived there. As one response, the Queensland Government, CSIRO, Griffith University and The University of Queensland created and resourced the Urban Water Security Research Alliance (UWSRA), to address a range of water supply options – one of which was the systematic and comprehensive introduction of rainwater harvesting.

As chair of the Research Advisory Committee (RAC) of UWSRA, I am delighted that Ashok Sharma, Don Begbie and Ted Gardner, and ultimately, IWA Publishing took up the suggestion that there was a need for a 'rainwater tank book', so that others throughout the world might gain from our experiences in Australia.

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So simple? – perhaps;
So established? – undoubtedly;
So what? – read the book.

Paul Greenfield
Chair International Water Centre,
Brisbane, Australia & Chair,
Local Organising Committee,
IWA Congress,
Brisbane, 2016.

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Preface

Historically, household rainwater tank systems have been implemented in rural and peri-urban areas for potable water supply where municipal reticulated water supply systems were not feasible due to economic and/or technical considerations. They have also been implemented in urban areas in a number of countries to provide a local, decentralised water source. However, their widespread implementation in urban areas with a centralised water supply is comparatively novel. The importance of these systems in cities has grown as water managers seek to address capacity constraints of current water supply systems as well as increasing resilience to drought and the adverse impacts of climate change. Rainwater tank systems are now implemented under integrated urban water management (IUWM) and water sensitive urban design (WSUD) approaches, which take a holistic view of the urban water system for water supply and stormwater management. These approaches include stormwater quality management and flood mitigation.

Dwellings with rainwater tanks increased from 15% to 28% of Australian capital city households (about 5.5 million dwellings) over the last six years; however, the increase in rainwater tanks outside capital city areas was much smaller, increasing from 38% of households to 44% over the same time period. Taken overall, 34% of all Australian households (8.9 million) had installed a rainwater tank by 2013. This rapid uptake of rainwater tanks in Australian cities was encouraged through financial incentives, including rebates for homeowners, but more importantly, from changes to residential building codes that effectively mandated the installation of rainwater tanks in response to the 'millennium drought' (2003 to 2008), as well as environmental sustainability objectives. These actions were taken by water policy makers to diversify the urban water supply source mix in order to address drought, which was particularly acute in many of the urban water supply catchments. Similar trends for increased uptake of rainwater tanks in urban areas can also be expected in other parts of the world impacted by potable water shortage to meet present and future demand, reduced availability of good quality water, or where there is an environmental driver to reduce the adverse impacts of urban runoff on receiving waters.

Much of the research to date has been focussed on tanks in developing countries for potable supply applications, or for flood mitigation in highly-urbanised, developed countries. This book is based on a comprehensive research program on rainwater tanks in South East Queensland, Australia, undertaken with funding from the Urban Water Security Research Alliance (UWSRA). The UWSRA, a partnership between the State government and selected research institutions, was motivated by the millennium drought, whilst the rainwater program's brief was to provide an evidence base for expanding scientific knowledge

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about rainwater tank systems, and their role as an auxiliary water supply source in modern urban water systems.

This book addresses many of the significant knowledge gaps for the successful implementation of rainwater tanks systems as part of an integrated urban water management approach, including: actual harvested yield and the corresponding mains water savings, optimal sizing for rainwater storages and roof collection systems, modelling tools for sizing tanks and estimating long-term yields, expected chemical and microbiological water quality and implications for managing public health risks, energy consumption of rainwater systems, successful approaches for operation and management of rainwater tanks, the sociology of community acceptance of tanks and their maintenance, impact of rainwater tanks on stormwater quality and quantity, economics of distributed and communal rainwater systems, and regulatory and policy implications in adopting rainwater tanks.

We believe this book will provide students and researchers around the world with a valuable resource on the biophysical aspects and social implications of rainwater tanks. The book will also be a valuable resource for developers, civil designers, architects and plumbers seeking to implement sustainable water servicing approaches using rainwater tanks for residential, industrial and commercial developments. And last but not least, the book should also be useful for water professionals who are involved in the strategic water planning for a town or at a larger scale. Although this book is based on research projects conducted in South East Queensland, Australia, we believe the generalised approaches and methodologies described in the book can be applied to rainwater tank implementation programs in most geographic and social contexts of the international community. Furthermore, the book provides insights on the expected performance and potential pitfalls of the adoption of rainwater tanks systems as part of an integrated approach in managing urban water systems. The book also identifies a number of remaining knowledge gaps that need to be addressed to better inform the policy development and management decisions needed for encouraging rainwater tank systems as one of the mainstream solutions for augmenting centralised water supply systems. We believe their widespread adoption will move society closer to the goal of ecologically sustainable development.

We posit that the future of tanks seem bright in both developed and developing countries. In the former, communal systems in dense urban areas give the opportunity to provide water at a quality assured potable standard, as well as reducing peak stormwater discharge into combined sewers, drains and creeks. In developing countries, the suite of available construction materials and treatment devices make distributed rainwater systems a very attractive source of safe household water. But in all cases, the engagement of the community is essential to ensure that the system operates to design specifications over the long term.

Good information allows good policy development and good decision making. The information presented in this book should empower designers, planners and regulators to better incorporate rainwater systems into the urban fabric of the world, after allowing for some local context specific modifications.

We hope you enjoy reading it.

Ashok K. Sharma
Don Begbie
Ted Gardner

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Editorial

There is growing pressure on urban fresh water resources due to an ever increasing population and climate change. Implementing rainwater tanks is one option to supplement freshwater resources based on the *fit for purpose* concept. A rainwater tank system looks apparently simple, but various complexities occur in their design and implementation to achieve long-term economic, social and environmental benefits. We have championed this book to provide knowledge to water professionals, managers and regulators to help them better realise the complexities in rainwater tank systems implementation so as to achieve the desired benefits. We are proud to have been able to facilitate contributions from Australian authors who have worked on various aspects of rainwater tank systems covering modelling, auditing, monitoring, management, social perception, optimal system configuration design, economics, and chemical and biological water quality.

In Chapter 1, Stephen Cook, Ashok Sharma and Ted Gardner describe the history of rainwater tanks implementation and reviewed rainwater harvesting practices around the world. They have indicated that rainwater harvesting systems have been used for local water supply as far back as the ancient civilisations of Greece, Jordan and Persia. Rainwater harvesting can provide a source of better quality drinking water in developing countries where surface water becomes contaminated, and good quality ground water is not available. In peri-urban and rural areas of developed countries, rainwater is often the only potable source, as reticulated water supply is not available due to economic considerations. However, this chapter mainly focusses on the provision of rainwater systems in urban areas as a supplementary source to mains water supply, to address resource constraints due to population growth and climate change, with a highlight on Australian experiences.

Numerical models are now readily available on personal computers and can simulate performance of rainwater tank systems over long time periods. Model outputs are used across the globe for supporting decisions on the suitability of rainwater tank systems to meet household water demand. In Chapter 2, Alison Vieritz, Luis Neumann and Stephen Cook present a generalised model of a rainwater tank/roof catchment system, discuss the various hydraulic and computational processes, and explore the impact of key model parameters, the choice of time-step, order of calculation and simulation length on predicted rainwater yield. The authors also discuss the modelling issues in representing the collective behaviour of a large number of identical tank systems in an urban area (also known as spatial lumping) for estimating the average reliability and yield of a large rainwater tank population.

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Chapter 3 covers the various methods to quantity mains water savings from installing residential rainwater tanks to (partially) substitute for potable water in urban settings. It is important for water planners to quantify mains water savings to ensure rainwater tanks contribute their component to the strategic water plan for a city or a region. The rainwater usage estimated with modelling tools or theoretical approaches can be significantly different from the actual rainwater usage due to the variation in various modelling parameters as described in Chapter 2. In this Chapter 3, Cara Beal and colleagues describe three different statistical methods for assessing mains water savings, using examples from Australia where rainwater tanks were installed on a suburb wide basis. It is anticipated that these methods can be applied in any part of the globe for quantifying mains water savings where rainwater tanks are mandated or encouraged in urban households. The factors that mainly influence the mains water savings are also described in this chapter.

Mathematical models and statistical analysis are described in Chapters 2 and 3 respectively to estimate mains water savings. However direct measurement of rainwater use is the *gold standard* of quantifying potable water savings. In Chapter 4, Shivanita Umapathi and colleagues describe a method for real-time monitoring of rainwater usage from household raintanks and the associated instrumentation required. Two Australian case studies are described in this chapter, where real-time monitoring of water flows and energy usage was conducted and monitoring outcomes were compared with mathematical and other mains water saving approaches. Limitations of small sample size are also discussed.

Local guidelines or development codes are prescribed for the installation of rainwater tank systems to achieve certain rainwater yield from the raintanks. These guidelines usually specify minimum raintank size (kL), connected roof area (m^2), and water quality improvement devices. However, compliance with these guidelines or development codes is not know until a post installation physical audit of these systems is undertaken. Non-compliance of local development codes could seriously impact the mains water saving assumed to occur from installing rainwater tanks. Sharon Biermann and Reid Butler, in Chapter 5, describe a generic rainwater tank installation compliance audit protocol, and demonstrate its application in South East Queensland (SEQ), Australia, where Queensland Development Code MP 4.2 specified minimum tank size, connected roof area, water quality improvement devices, and connected water end uses for non-potable application in new detached dwellings.

Pumps are an integral part of most rainwater systems, so understanding energy consumption and exploring ways to minimise energy use are important from economic and environmental sustainability considerations. A large number of these systems have been installed in urban developments, and thus, any attempt to improve energy efficiency should have significant overall economic and environmental impact. In Chapter 6, Grace Tjandraatmadja and colleagues examine the factors that influence energy use in commonly used rainwater pump systems. These factors are pump size, flow rate, system and infrastructure design, and indirectly, water policy. The authors also describe how the system configuration could be improved to reduce energy use. A description of laboratory setup for validating various system configurations is provided for wider professional interest, as well as providing guidance to allow similar studies to be undertaken in other parts of the globe.

Supply from rainwater tank systems at desired quantity and quality can only be achieved if the systems are regularly maintained, usually by the tank owners. There are also substantial public health risks from mosquito borne arboviruses if mesh screens fitted to raintanks are poorly maintained. Magnus Moglia and colleagues, in Chapter 7, describe strategies to ensure that privately owned rainwater tanks remain both functional and safe. These strategies are not straight forward as, in many cases, the private owners are either not motivated or not technically competent to undertake maintenance. Whilst it is relatively simple to maintain a single rainwater tank, the task becomes much more complex to ensure that the entire stock of rainwater tanks is maintained. Problem definition and communication strategies described in this chapter will help water professionals to achieve the desired maintenance objectives for rainwater tanks.

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The adoption of rainwater tanks, including their regular maintenance, is very much influenced by community perception and attitude, which in turn are impacted by psychological factors. In Chapter 8, Aditi Mankad, Kelly Fielding and Sorada Tapsuwan describe methodologies to investigate these factors, and demonstrate their application using case studies from various regions of Australian. The authors explore attitudes of users and non-users of rainwater tanks, psychological and behavioural data comparing mandated installation of rainwater tanks with voluntary adoption through rebate programs, and the main psychological variables likely to influence rainwater use and tank maintenance beyond public acceptance.

In urban areas where mains water is available, health agencies usually do not recommend rainwater for potable applications for microbiological reasons. However, it is also important to understand the health implications of the chemical water quality of rainwater if it is used for potable purposes. In Chapter 9, Mirela Magyar and Anthony Ladson review the chemical water quality aspects of rainwater tanks and compared them with drinking water guidelines. The authors indicate that high lead concentrations, elevated metal concentration and low pH are common issues in rainwater. High concentration of lead was reported in 31 of the 32 studies. The authors suggest that the risk of lead contamination in urban areas should be taken seriously. Most aspects of water quality can be improved by suitable treatment, on-going maintenance and improvement in tank design, especially the pump intake hose.

As mentioned above, rainwater is not recommended for potable applications in urban areas with reticulated water supply. However, such use can't be completely stopped, whilst potable use of rainwater in peri-urban and rural communities is common. Thus, the understanding of microbiological quality of rainwater is essential. Warish Ahmed and Simon Toze, in Chapter 10, describe the microbiological quality of rainwater and associated health risks from zoonotic pathogens in roof captured rainwater. The conclusions provided in this chapter are based on water samples from residential rainwater tanks in South East Queensland, Australia. However, the information provided, especially on the kinetics of natural die off, will be of general use for all professionals involved with rainwater supply in any residential urban or rural development.

Cluster-scale (communal) rainwater tanks are an alternative to individual householder tanks and are discussed in Chapter 11. In communal systems, roof water is collected through a common gravity conveyance (collection) system from a group of houses and stored in a communal tank. After appropriate treatment, the water is supplied back to the homes through a dedicated, pressurised water reticulated system. Depending on the level of treatment, the water supply from cluster-scale systems can be used for potable applications rather than just non-potable uses such as toilet flushing, laundry and garden irrigation, as occurs for example for individual tanks. Moreover, these communal systems can be well managed through a formalised, quality assured management and maintenance arrangement, thereby overcoming the serious maintenance limitations of household-scale rainwater harvesting systems. In this chapter, Stephen Cook and colleagues have described the multiple benefits that cluster-scale rainwater tank systems can offer, including economies of scale based on life cycle costs, reduced land footprint per allotment, centralised treatment and disinfection, and matching overall demand for different households.

Understanding the economics of rainwater tank systems is essential to compare them with centralised and other alternative water supply systems. The comparison is generally based on the cost of water ($/kL) supplied by an asset over its useful life. In Chapter 12, Murray Hall, Thulo Ram Gurung and Kym Whiteoak describe the economics of both individual household and cluster-scale rainwater tank systems. They examine the levelised cost and cost benefit approaches for economic assessment using data from case studies in South East Queensland, Australia. The chapter also covers a method for evaluating the economies of scale of cluster-scale rainwater tanks system. The authors also describe other benefits from rainwater tank systems (externalities), such as delaying infrastructure upgrades and reduced stormwater flows to receiving waters, using cost benefit analysis.

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Rainwater tanks in urban areas also impact on urban hydrology and stormwater quality. Urbanisation increases runoff, reduces water quality and adversely impacts the receiving water environment; all responses which can be counter balanced to some extent by installing rainwater tanks. In Chapter 13, Matthew Burns, Anthony Ladson and Tim Fletcher describe the role of rainwater tanks in stormwater flow management and water quality improvement, with a focus on restoring natural stream flows and water quality regimes. They also describe other benefits such as urban cooling and flood mitigation due to the implementation of rainwater tanks in the urban environment.

Chapter 14 summarises the findings of the preceding 13 chapters and highlights the policy implications of these findings for Australian states, and lessons for the international community. In this chapter, Ted Gardner and colleagues also provide a social/technical context of the development of rainwater tanks in Australia. The authors highlight that the major Australian water authorities have invested huge amounts of money in seawater desalination plants as a key strategy in developing climate resilient potable water supplies. Thus, the future of rainwater tanks and dual reticulation recycled water systems as alternative supplies have become uncertain in urban areas. However, the authors also highlight that Australian water professionals consider rainwater tanks and recycled water will continue to play a major role in mitigating the adverse impacts of climate change on the urban environment. The authors also conclude that rainwater tanks can supply superior water quality in developing countries, and the body of work included in this book can be used across the globe either directly, or with some modifications based on the local social/technical/political contexts.

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Chapter 1

Rainwater harvesting systems for urban developments

Stephen Cook, Ashok K. Sharma and Ted Gardner

ABSTRACT

Rainwater harvesting systems have been used as a local water supply source since the first human settlements. In recent times, rainwater harvesting systems have become an important water supply source in rural and remote areas where reticulated water supply systems are not available. Harvested rainwater can also provide an 'improved' drinking water source in rural and peri-urban areas of developing countries where surface water can be contaminated by faecal pathogens, and/or good quality groundwater is not readily available. However, this chapter is focussed on the potential of rainwater harvesting as a secondary water source in modern cities that have a centralised reticulated water supply system. Rainwater tanks are now being implemented under integrated urban water management concepts, to reduce the use of mains water for non-potable household uses. This substitution concept is based on a 'fit for purpose' water quality to help address the increase in demand for freshwater resources due to rapid population growth and urbanisation.

This chapter reviews rainwater harvesting practices around the world with a particular emphasis on the drivers behind the adoption of rainwater harvesting. There is a particular focus on the Australian experience due in part to the rapid uptake of rainwater systems over the last decade or so. This uptake was in response to pressures on mains water supply due to an extended drought and growing population.

The chapter also outlines some of the issues that are confronted when planning rainwater harvesting systems as a source of non-potable water in modern cities. These issues include likely yield from rainwater systems (kL/household/year), managing public health risks, cost-effectiveness, energy demand and environmental benefits. This chapter provides foundation knowledge on the issues, which are then explored in more detail in subsequent chapters of this book.

Keywords: rainwater tanks; modelling; strategic water planning; water quality.

1.1 INTRODUCTION

Rainwater harvesting systems have been an important water source for human settlements since the earliest examples of civilised society. There are examples of rainwater harvesting in the ancient civilisations of the

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Middle East (AbdelKhaleq & Alhaj Ahmed, 2007; Evenari *et al.* 1971). Mays *et al.* (2007) noted that in ancient Greece cities used rainwater collection to augment supply from aqueduct systems fed by natural springs when population growth resulted in demand exceeding supply from existing sources. In modern cities of developed countries, there has been a renewed interest in the potential benefits of rainwater to complement drinking water supply systems. Whilst in rural areas, as well as in developing countries, rainwater harvesting can provide an important source of drinking water.

Whilst rainwater harvesting was an important water source in early forms of human settlement as cities populations grew, the main approach to water supply was sourcing water from catchments outside of cities, which is then supplied via large-scale reticulated networks. These centrally managed and operated systems have usually provided safe and reliable safe services in developed countries since the mid-1850s. However, over the last decade or so, there has been increased adoption of rainwater tanks for augmenting urban water supply in developed countries. For example in Australian cities, the number of household rainwater tanks more than doubled over the period 1994 to 2010, with more than one million households in Australian cities now having a rainwater tank (ABS, 2010). In developed countries, rainwater tanks were historically used in areas on the urban fringe as an interim measure before reticulated potable water became available. An exception of course is rural areas where mains water supply is usually limited to towns. While the focus of this chapter is on the experiences of rainwater tanks in cities of the developed world, there is some attention paid to the use of rainwater harvesting in developing countries. In these countries, rainwater can supply an 'improved' drinking water source. Rainwater systems can be particularly useful in conditions where surface water is contaminated by faecal pathogens, and groundwater is either not readily available or contaminated by chemicals, such as naturally occurring arsenic in Bangladesh (Chakraborti *et al.* 2010).

The basic design of household rainwater systems has not changed significantly over the centuries in that runoff from an imperious area, such as a roof, is directed by gravity into to storage vessels where it can then be drawn upon to meet household water demands. In modern settlements, building roofs provide the impervious runoff area with collection via roof gutters and down pipes to storage tanks. By adding an electric pump, water can be supplied to any elevation in the dwelling at a flow rate and pressure acceptable for most domestic uses. There is also the potential to expand the use of harvested rainwater through treatments such as filtration and disinfection for potable application. Whilst the basic elements of rainwater tanks are well understood, the re-emergence of rainwater tanks as an important water source in modern cities has exposed a number of knowledge gaps. Current knowledge gaps on rainwater harvesting systems include:

- The likely yield and reliability of rainwater harvesting systems in different development contexts and system configurations;
- The public health risks associated with the use of rainwater tanks;
- The treatment options available to supply rainwater that is fit for the intended purpose;
- The life cycle costs associated with constructing and operating a rainwater system;
- The impact on flows in the centralised water supply and stormwater networks;
- The environmental benefits of rainwater harvesting systems due to avoided stormwater discharge;
- The energy demand associated with rainwater system pumps;
- The community acceptance of rainwater systems and their associated maintenance tasks; and
- The appropriate management models to best mitigate risks of decentralised rainwater systems.

Addressing these knowledge gaps is important for encouraging greater adoption of rainwater harvesting systems, which we believe should contribute to a more sustainable urban water system.

This chapter provides an overview of rainwater harvesting practices across the world, with a particular focus on the drivers for their adoption. The Australian experience with rainwater harvesting is explored

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in more detail. The chapter then introduces the knowledge gaps that we believe are impeding greater adoption of rainwater harvesting in modern cities. This chapter sets the context, and introduces the issues, that are then explored in more detail in subsequent chapters of this book.

1.2 INTERNATIONAL EXPERIENCES WITH RAINWATER HARVESTING SYSTEMS

In this section we review the literature on experiences with rainwater harvesting systems across the world. In particular, we examine the drivers for their adoption in different urban contexts and the level of uptake across countries.

Rainwater harvesting has undergone a surge in popularity in the United States. The uptake of rainwater tanks has mostly been in areas where there is a lack of high-quality freshwater supplies or where households are motivated by environmental concerns (Mendez *et al.* 2011). Thomas *et al.* (2014) undertook a survey to better understand rainwater harvesting practices and the motivation for harvesting rainwater in the United States. This survey found the main use of harvested rainwater was irrigation. However, 25% of the 222 respondents indicated that they used rainwater for potable purposes. Of the households using rainwater for potable uses, 70% employed ultraviolet light as their main method of disinfecting the water. Moreover, 21% of respondents who used rainwater tanks for potable uses undertook no water quality testing (Thomas *et al.* 2014). The significant number of households not monitoring the quality of the harvested water has implications for the risk management and design of an appropriate treatment train. Mendez *et al.* (2011) investigated the effect of roofing material on the quality of harvested rainwater in the United States. This study recommended that first-flush diversion, filtration and disinfection be used to meet United States Environmental Protection Agency (USEPA) water reuse guidelines (Mendez *et al.* 2011).

In Canada, harvesting roof runoff for domestic purposes has mostly been practiced in rural communities, but there has been renewed interest in urban areas (Farahbakhsh *et al.* 2009). The increased interest has been motivated by the potential of harvested rainwater to contribute to sustainability objectives, including water conservation and stormwater quality (Farahbakhsh *et al.* 2009). Farahbakhsh *et al.* (2009) noted that while the benefits of rainwater harvesting are well understood, there are a number of impediments for greater uptake in Canada, including the lack of a clear policy for rainwater harvesting, and uncertainty on costs and risks. Despins *et al.* (2009) undertook an assessment of rainwater quality from systems in Ontario, Canada. Their results indicated that microbiological quality improved during colder weather, whilst the physiochemical quality of harvested rainwater was most influenced by roofing and storage materials, as well as local environmental conditions (Despins *et al.* 2009). They found that the quality of harvested rainwater could be managed to acceptable standards via the selection of appropriate materials, and the implementation of post-tank treatment (Despins *et al.* 2009). Although Canada has abundant freshwater resources, there are many rural communities that rely upon water from local tanks for potable water supply (Baird *et al.* 2013). These tanks are filled by a range of water sources including trucked-in water and rainwater harvesting. It has been identified that there is the need for improved risk management policies and practices to reduce the potential for adverse human health impacts from water tanks. First Nations communities (i.e., the indigenous communities) are particularly vulnerable to water quality issues from storage tanks given they often lack access to alternative safe water supply (Baird *et al.* 2013).

In Southern Brazil, the projected increased demand for drinking water due to population growth has generated interest in the benefits of rainwater harvesting (Ghisi *et al.* 2007). An analysis of 62 cities in Southern Brazil indicated that rainwater harvesting could potentially reduce potable water demand by 34% to 92% (Ghisi *et al.* 2007). However, this analysis did not consider seasonality of demand, or the dynamics of roof runoff volume, available storage volume and demand.

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In developed countries of Europe and Asia, the interest in rainwater harvesting systems is often driven by concerns for stormwater discharge into combined sewers (i.e., sewers that collect both sewage and stormwater flows), local flooding control, and lastly, water supply. In Germany for example, water scarcity is not a major issue yet the uptake of rainwater tanks has been widespread since the 1980s (Nolde, 2007). The rainwater industry is well established with over 1.6 million installations (4% of households) and approximately 50,000 rainwater systems being installed every year in new homes (Nolde, 2007). The major driver for government and water companies to encourage greater adoption of rainwater harvesting systems is to reduce the capital costs associated with providing additional flow capacity in the sewerage system to cope with increases in wastewater and stormwater discharges. Hence, rainwater tanks are part of a system to retain stormwater runoff on site for subsequent local infiltration (Hermann & Schmida, 1999). The 'disconnection of impervious areas' can lead to direct government subsidy and/or a reduction in household sewage charges from water companies (Hermann & Schmida, 1999). Despite the subsidies, the cost-benefit ratio for households to install a rainwater harvesting systems remains unfavourable. However, there is still a high incidence of voluntary installation of rainwater harvesting systems in new private dwellings in Germany (over 65%). This uptake is thought to be due to peoples' desire to contribute to sustainability (by reducing stormwater discharge into waterways) as well as the concept of self-reliance (Schuetze, 2013). Rainwater tanks in new dwellings can be used to meet water demand for toilet flushing, clothes washing, garden irrigation and other external uses. The harvested rainwater can also be used to recharge. In some cases, there is reluctance from local authorities and water companies to promote greater adoption of rainwater tanks to help substitute for mains water demand. This is due to the potential for the increased use of harvested rainwater to reduce mains water billing revenue that is needed to invest in, and maintain, the centralised infrastructure (Schuetze, 2013).

In France, adoption of rainwater harvesting systems has been limited, which is due in part to a French law that restricts the domestic use of rainwater for clothes laundry, showering and drinking (Vialle *et al.* 2011). This law, which constrains the domestic use of rainwater to external uses such as garden irrigation and cleaning, is based on concerns with water quality and potential public health impacts. This contrasts markedly with a European Union Directive that puts a priority on urban water savings including rainwater harvesting and reuse in buildings (Palla *et al.* 2011). In other parts of Europe, such as Sweden, the concept of ecologically sustainable development is motivating installation of rainwater harvesting systems in large (1100 units) community housing complexes (Villarreal & Dixon, 2005).

In southern Europe, the Mediterranean rainfall pattern of dry, hot summers means there is considerable interest in rainwater harvesting systems for public and private dwellings because of drought induced water supply restrictions (Domènech & Saurí, 2011). Domènech and Saurí (2011) reported on rainwater harvesting systems in a municipality of Barcelona, Spain, where rainwater tanks were mandated for individual and communal houses with gardens greater than 300 m^2. Their study, which largely focussed on socio-economic factors, reported a high user satisfaction level with rainwater tanks despite the long payback time, and a community pride in the water savings that benefits the whole society.

In the United Kingdom, there are government policies that encourage rainwater harvesting in private and public dwellings (DEFRA, 2008; Ward, 2010) as well as publications providing technical detail for its implementation (e.g., UK Environmental Agency, 2008). As with Germany, a driver for the adoption of rainwater harvesting is to reduce stormwater discharge into waterways, and mitigate local flooding issues (Farnsworth, 2012). Hence, rainwater tanks in individual and communal dwellings are seen as part of implementing a Sustainable Urban Drainage System (SUDS) (Farnsworth, 2012). However, as there is no rebate available for rainwater tank installation, adoption by households has been limited (Farnsworth, 2012; Ward, 2010).

Rainwater tanks can also be one measure to adapt to uncertainty in supply from traditional water sources due to inherent climate variability and the impacts of climate change. Pandey *et al.* (2003) articulated a

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theory that in a changing climate, people have resorted to local rainwater harvesting in order to adapt and ensure survival. This theory was explored by undertaking a detailed analysis of the relationship between periods of climate change (in particular droughts) and the adoption of local water harvesting over recent millennia. The study found a correlation between periods of drought and archaeological evidence of increased human construction of rainwater harvesting systems (Pandey *et al.* 2003). The analysis extended to modern times where in 1999, the hottest summer experienced in central India during the 20th century, resulted in a government program of investment in rainwater tanks for augmenting domestic water supply. Said (2014) reported on a study that assessed the potential for rainwater harvesting in New Delhi, India. This study found that the benefits of rainwater harvesting, as a measure to encourage more sustainable use of water resources, could be maximised when combined with a program encouraging water efficiency (Said, 2014). Islam *et al.* (2011) undertook an analysis of the potential for rainwater harvesting to provide an improved supply of safe water to slum dwellers in Dhaka City, Bangladesh. This analysis found that rainwater harvesting was a feasible option for improved water supply, which was accepted by the local community provided there was some Government assistance to offset the costs of installation (Islam *et al.* 2011).

In Japan, rainwater harvesting systems are promoted largely to reduce urban flooding, noting that roofs comprise about 50% of the total impervious area of cities (Ward, 2012). In China, rainwater harvesting has been explored as a measure to mitigate urban flooding in areas with monsoonal rainfall (Zhang & Hu, 2014). In the semiarid areas of China, rainwater harvesting is promoted to address water scarcity for domestic and agricultural uses (Li *et al.* 2004).

Korea is another developed Asian country with a strong interest in rainwater harvesting and reuse systems, which is motivated by the objectives of reducing urban flash floods and combined sewer overflows during the wet season. However, Kim and Yoo (2009) found that having 10% of the impervious urban area connected to rainwater harvesting systems only reduced the level of urban flooding by 1% during the wet season. This was due to the limitations of storage volume that could be provided relative to the runoff volume.

Experiences with rainwater tank systems for urban water supply can largely be partitioned into developed and developing countries. While this chapter has largely focussed on developed countries experiences, the following considers the importance of rainwater harvesting systems in developing countries. For many countries in Africa, and many parts of South East Asia, access to a safe drinking water supply is poor, especially in rural areas, which leads to increased rates of illness (Baguma *et al.* 2010; Kahinda *et al.* 2007). In addition, the source of water supply is often remote from village settlements and travel time and effort for its collection is onerous (Baguma *et al.* 2010). Although household rainwater systems generally does not have the same microbiological standards as potable water (Ahmed *et al.* 2011), it is usually of far superior quality to untreated water accessed from surface water bodies and some shallow wells. Consequently, there is a range of programs in Africa where non-government organisations encourage the installation of local rainwater harvesting systems to improve health outcomes and quality of life (e.g., RAIN, 2011).

1.3 THE AUSTRALIAN EXPERIENCE WITH RAINWATER TANK SYSTEMS

Australia has significant uptake of rainwater tank systems in cities relative to other developed countries (Ward, 2010). In 2013, 34% of households had a rainwater tank; an increase from 24% of households in 2007 (ABS, 2013). In this section, we explore the drivers for such high adoption of rainwater tanks.

The uptake of rainwater tanks as a non-potable water source in Australian cities accelerated during the Millennium drought, which occurred from 2000 to about 2008. The extended drought saw capital cities' water catchments fall to unprecedented low levels, with the real possibility of cities running out of water unless radical steps were taken (Apostolidis *et al.* 2011). It was this factor that 'focused the minds' of the water planners in all Australian states and lead to an explosion of investment in alternative water supply

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sources (seawater desalination by reverse osmosis, recycling of wastewater, stormwater harvesting and reuse) and rainwater tanks, as well as demand reduction programs.

In Australian cities, rainwater tank uptake was encouraged both by financial rebates for installation, and changes to building codes that encouraged households to install a secondary alternative water source for non-potable demands such as toilet flushing and garden irrigation (NSW Planning and Infrastructure, 2004; Queensland Department of Infrastructure and Planning, 2008). The installation of rainwater tanks was also a response to increased water restrictions during the drought (ABS, 2013). Also, rainwater tanks were promoted under Water Sensitive Urban Design (WSUD) and Integrated Urban Water Management (IUWM) approaches as a tool for reducing the impact of urban stormwater on the natural environment (Sharma *et al*. 2012; Sharma *et al*. 2013). Rainwater tank systems continue to be encouraged in Australia as a supplementary water source through financial incentives and regulations such as requirements in building codes for alternative water sources and/or water conservation measures. Rainwater tanks have featured as part of an overall strategy to secure long-term water supply demand balance in Australian cities (e.g., Queensland Water Commission, 2010). However, in Queensland, the mandatory requirement for rainwater tanks to be installed in new homes was removed due to concerns that it was increasing the construction costs of residential development (Mander, 2013).

Rainwater harvesting is a mainstream practice in rural areas of Australia, with 44% of households outside of capital cities having a rainwater tank (ABS, 2013). Also, rainwater tanks have also been used as an interim water supply source in peri-urban areas where the low population density does not yet support reticulated water supply systems. In urban areas that are serviced by reticulated water supply, rainwater has provided a non-potable water source for garden irrigation. The supply of an alternative water supply source for irrigation is particularly important during periods of drought where mains water use for this purpose is often restricted by regulations. However, there has been a shift to extend the use of harvested rainwater to uses inside the home, particularly for toilet flushing. More than half (51%) of Australian households with a rainwater tank have them plumbed for internal uses (ABS, 2013). The use of rainwater systems for toilet flushing requires management of the risks associated with the potential for backflow of rainwater to contaminate potable water supply, as well as ensuring continuity of supply to the appliance via a back-up water supply source. The primary reason householders installed a rainwater tank was to save water (Figure 1.1), and as mentioned previously, there has been a substantial rise in installed numbers since 2007 (Figure 1.2) (ABS, 2013). The significant proportion of households in Australia that use rainwater for domestic purposes demonstrates their importance in contributing to water supply security, especially in rural Australia.

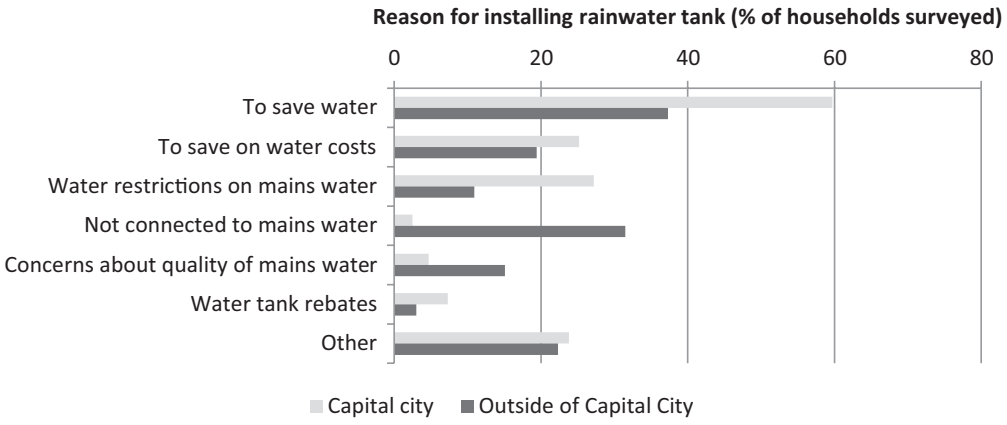


Figure 1.1 Reason for installing a rainwater tank in Australia (ABS, 2013).

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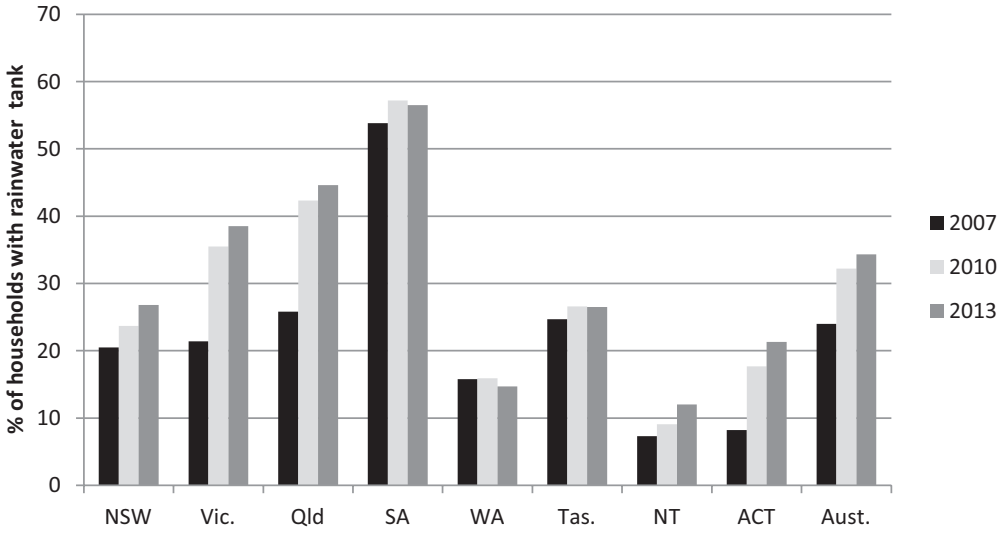


Figure 1.2 Percentage of households with rainwater tanks in Australia (ABS, 2013).

1.4 KEY ISSUES FOR GREATER UPTAKE OF RAINWATER TANK SYSTEMS

This section summarises a range of issues faced in the greater uptake of rainwater tank systems. Rainwater tanks have become very common in urban areas, which raises a number of issues that include: the integration of rainwater tanks with existing centralised water supply systems; impact on reducing demand for mains water; long-term reliability and yield; energy implications; supply cost relative to other supply and demand options; water quality considerations and public health risk; and the need for improved planning and design guidelines. Some of these issues are considered in more detail in the remainder of this book, whilst the following sections summarise some of the main challenges that need to be addressed in securing greater mainstream acceptance of rainwater tanks in modern cities.

1.4.1 Estimating rainwater system yield and mains water savings

A significant driver for the uptake of rainwater tanks was the need to reduce demand for potable water supply due to drought conditions. Rainwater tanks were included in strategic water supply-demand balance planning (Queensland Water Commission, 2010), so there was a need for rigour when estimating the likely yield and mains water savings due to the uptake of rainwater tanks.

Understanding the likely yield from a rainwater system is also important for aiding the system design, as it can inform the sizing of roof catchments and storages. Also, estimating the likely mains water savings provides an understanding of the reliability of the rainwater system for the designated end-uses.

The amount of mains water saved due to the installation of the rainwater tank is primarily a function of the following factors: catchment area; storage volume; end-uses; household demand profile; and rainfall pattern. Modelling tools have been developed to simulate the dynamic interactions amongst these factors, which can be used to assess likely mains water savings due to the installation of rainwater harvesting system (see Chapter 3). However, there is also the need for monitoring studies to validate results from simulation tools. The comparison of modelling results with the measured household potable water savings

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is essential to gauge the accuracy of these modelling predictions. The validation of the potable water savings is also essential to avoid systemic errors in the long-term water planning for a city or a region. Hence, modelling predictions *alone* should not be used for strategic water planning purposes.

Chong *et al.* (2011) assessed the potable water savings from rainwater tanks by comparing mains water consumption data from households with rainwater tanks against the regional average residential water consumption for the same period. Their study found the average mains water savings for households with a 5 kL rainwater tank was 58.8 kL per household per year (kL/hh/yr), but with significant variation between local government areas. Beal *et al.* (2012) estimated the mains water savings associated with rainwater tanks plumbed for indoor non-potable use. This estimate was based on comparing water billing data for households with internally plumbed rainwater tanks with those households with no rainwater tank plumbed for indoor use. This pairwise comparison found there was significant spatial variation in mains water savings due to internally plumbed rainwater tanks, with average annual mains water savings of 50 kL/hh/yr for the South East Queensland region, Australia, ranging from 20 to 95 kilolitres per household (Beal *et al.* 2012).

1.4.2 Understanding the risks associated with rainwater quality

There is a need to consider the likely quality of rainwater harvested and the associated risks that are posed to households. The inclusion of rainwater tanks in government policies has renewed interest in measuring the microbiological and chemical quality of captured rainwater (Magyar *et al.* 2007). Rainwater quality can be affected by the roof and storage tank materials, overhanging trees, and the rigor of maintenance of rainwater system (Rodrigo *et al.* 2010). Lee *et al.* (2012) investigated the quality of harvested rainwater in Korea as affected by roofing materials. Wooden, concrete, clay tiles and galvanised steel roofing materials were investigated, and galvanised steel was found to provide the best rainwater quality, which was attributed by the authors to disinfection provided by the high daily surface temperature of this material (Lee *et al.* 2012).

Huston *et al.* (2012) conducted a study to identify the contributors of heavy metals and ionic contaminants in rainwater tanks in Brisbane, Australia. They identified four source factors influencing the bulk deposition at various locations in Brisbane, which included crustal matter/sea salt, car exhaust/road dust, industrial dust and aged sea salt/secondary aerosols. These factors, on average, contributed 65% of the total contaminants. They also identified six collection system factors which included plumbing, building material, galvanizing, roofing, steel and lead flashing/paint. These factors contribute nearly 35% of the contaminants.

Magyar *et al.* (2007) reported that the concentration of lead exceeded the Australian Drinking Water Guidelines (ADWG) values in 5 of the 9 tanks investigated in metropolitan Melbourne. O'Connor *et al.* (2009) expanded this study to 52 tanks and identified relationships between lead concentration in the tank water and tank sediments, and various environmental variables. In 14 of the 52 tanks, lead concentrations exceeded ADWG health guidelines. Lead flashing, prevailing winds, proximity to roads and commercial zones had statistically significant relationships with lead concentration in rainwater. However, no single factor was identified as the major cause. Lead has the most potential to impact seriously on human health, particularly on infants and children (Goyer, 1993). These issues are discussed in more detail in Chapter 9.

The microbial quality of rainwater depends on number of factors. For example, climate can have a significant impact on the microbial composition of harvested rainwater. For example, Evans *et al.* (2006) found airborne microorganism contributed a significant non-pathogenic bacterial load to roof water, with the magnitude influenced by wind velocities and wind direction. Yaziz *et al.* (1989) found that the bacterial contamination of rainwater, as measured by total coliform concentration, increased the longer

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the period between rainfall events. This study also found that roof materials and the intensity of the rainfall event influenced total coliform concentration. In a study of 24 household rainwater tanks in South East Queensland, 63% of rainwater tanks contained *E.coli* exceeding the limit of ADWG (Ahmed *et al.* 2012), which was related to faecal matter from small animals such as possums and birds.

The studies reported above show that the chemical and microbiological quality of roof harvested rainwater systems varies significantly, with a number of studies finding that rainwater quality exceeded drinking water guidelines for both chemical and microbiological parameters (Magyar *et al.* 2007; O'Connor *et al.* 2009; Yaziz *et al.* 1989). However, epidemiological studies of children in South Australia could identify no adverse health link between ingestion of rainwater and gastroenteritis (Heyworth *et al.* 2006). Care should be taken in using rainwater based on a 'fit for purpose' concept, and proper treatment of rainwater will be required if used for drinking purposes. Limiting rainwater for irrigation and selected indoor non-potable uses may be the most appropriate uses as they can significantly reduce mains water demand, whilst requiring minimal or very little treatment. When rainwater systems are plumbed for indoor non-potable applications, the primary concerns of guidelines are to avoid the risks of cross contamination with drinking water supply (via backflow events) and to reduce human contact with pathogens that may be present in harvested rainwater.

1.4.3 Guidelines for managing risks of rainwater use

The widespread adoption of rainwater tanks as an alternative water source has been encouraged to reduce mains water use, and to provide environmental benefits such as reduced stormwater flows. However, the increased use of rainwater tanks in urban areas does raise the need for guidelines that manage the risks associated with their use. The quality of rainwater for human use (potable or non-potable) is not regulated by any standard that is internationally recognised (Birks *et al.* 2004). Therefore, many countries and regions have developed local guidelines for local needs (Schuetze, 2013). Guidelines for rainwater use need to consider the water quality requirements of the intended use of the rainwater tank, and the likely microbiological and chemical risks posed. The preceding section has (briefly) detailed the quality of rainwater, whilst this section assesses the guidelines that are available to manage risks associated with rainwater quality.

In Australia, there is a national guidance document, *Guidance on the Use of Rainwater,* which takes a systematic analysis of the potential hazards and risks associated with rainwater use (EnHealth Council, 2010). This document argues that the health risks associated with drinking rainwater from a properly maintained tank are low in most parts of Australia, however, the microbial and chemical quality of rainwater is likely to be lower than mains water supply (EnHealth Council, 2010). Therefore, state guidelines recommend drinking of mains water supply where it is available (NSW Health, 2007). While the potable use of rainwater is possible with disinfection treatment, this section focuses on the guidelines for non-potable use of rainwater. Where the rainwater collected in a tank is intended for ingestion, drinking water guidelines, such as the World Health Organisation (2011), should be applied. Chapman *et al.* (2008) recommend a comprehensive health risk assessment is undertaken if the harvested rainwater is intended for drinking and other potable uses. The health risk assessment should consider if there are potential sources of pollution, suitability of materials used for rainwater system, the likelihood of vulnerable people (such as the very young and the very old) drinking the water, and how ongoing maintenance is assured (Chapman *et al.* 2008).

The EnHealth Council (2010) identified practical preventative measures that can be used to minimise most of the health and aesthetic hazards associated with rainwater collected in tanks. These preventative measures include regular, simple maintenance practices. The maintenance practices include keeping intact

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insect screen on the tanks, cleaning the area around tank to prevent breeding ground for mosquitoes, regular cleaning of gutters, and trimming of overhanging trees to discourage possums. In Australia, there is a range of other guidelines and standards that provide comprehensive technical advice on all aspects of rainwater tank design, installation and maintenance. These include a handbook for rainwater tank design and installation (Standards Australia, 2008), which includes guidance on maintenance tasks for rainwater tanks, and the frequency these tasks should be carried out.

In the United States, there is a lack of uniform guidance for the use of rainwater. This has resulted in a range of guidelines for use and treatment amongst state and local governments (Kloss, 2008). This lack of specific guidance on the use of rainwater has meant that some jurisdictions have based requirements on guidelines used for recycled water sources, which resulted in overly stringent regulations (Kloss, 2008). Kloss (2008) recommended that development of national guidelines on rainwater use, needs to consider the likely harvested rainwater quality and yield with the demand requirements of targeted end uses.

Fewtrell and Kay (2007) found that there are no regulations on the microbial quality required for the non-potable use of rainwater in the United Kingdom. Furthermore, where water supplied from rainwater tanks is used solely for non-potable purposes, there is often no requirement for quality monitoring. Fewtrell and Kay (2007) considered that adaption of other microbial water guidelines to non-potable use of rainwater was unlikely to be successful. Rather, they argue that the development of a standard for the microbial quality of rainwater tank water should take a health impact assessment approach, and that microbial concentrations are at set a level to protect human health, based on the intended uses.

1.4.4 Evaluating the cost-effectiveness of rainwater tanks

Prior to adopting rainwater tanks as official government policy, there is a need to consider their cost-effectiveness relative to centralised mains water supply, or alternative non-potable local water sources. The cost-effectiveness of a rainwater tank will be a product of whole of life cost and the water yield delivered over time (Marsden Jacobs Associates, 2007). Cost-effectiveness can be considered from either the perspective of an individual householder (levelised cost) or that of the whole of community (Benefit Cost analysis, Marsden Jacobs Associates, 2007). The whole of community cost considers not only the costs and benefits borne by the households, but also accounts for avoided costs for the capital and operating expenses associated with reduced capacity of public water supply and stormwater systems (Marsden Jacobs Associates, 2007).

The direct capital costs for rainwater tanks include the storage tank, tank installation and fittings, concrete slab or tank stand, household plumbing and a pump. The ongoing operating costs for a household are: energy costs for pumping; and maintenance of the tank and pump (Marsden Jacobs Associates, 2007). Vivian *et al.* (2010) undertook an analysis of the installation costs for a rainwater tank in Australian cities. Their study found that for a 5 kL tank plumbed for indoor and outdoor uses, installation cost was approximately AU$3,900 for the Gold Coast. In most Australian cities, there are rebates available to offset the costs of a household installing of a rainwater tank. The amount of rebate varies among jurisdictions, along with the size of the tank and the connected end uses. Hall (2013) examined the cost-effectiveness of rainwater tanks in South East Queensland, Australia. This study found that the average levelised cost of rainwater tanks for the scenario was $9.22 per kilolitre (kL) with 95% confidence limits of $6.73 and $12.77/kL. The variation in yield, pump and tank life and maintenance had the largest effect on the variation in the cost-effectiveness. The results were also sensitive to discount rate assumptions (Hall, 2013). As with all models, the outcomes of economic studies are strongly dependent on the input assumptions. But the results indicate that the supply costs of household rainwater systems in South East Queensland cannot compete economically with other alternative water supply sources.

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As the cost-effectiveness of rainwater tank is a function of both yield and whole of life costs, there is the need to consider factors that influence yield. The efficiency of a rainwater tank system is influenced by: tank size, roof catchment area, and the amount and regularity of the water demand (Vivian *et al.* 2010). Of course, the local rainfall amount and its temporal pattern strongly influences the yield from rainwater tank. The analysis by Marsden Jacobs Associates (2007) found that roof catchment area had the greatest impact on yield, followed by annual rainfall and tank size. This highlights the need to consider both the optimal configuration of rainwater systems, as well as the local climate in maximising cost-effective investment in rainwater systems.

The lifecycle costs and benefits for a household can be calculated using a discounted cash flow analysis, which accounts for the time value of money with future costs being discounted to their present value. This analysis uses estimated costs (initial and ongoing) of rainwater system, rainwater yield, and the avoided costs (e.g., avoided water tariffs) (Marsden Jacob Associates, 2007). If a householder is considering investing in a rainwater tank system and the present value life cycle costs exceeds the present value life cycle benefits, then it may be necessary to offer a rebate to cover the shortfall (Marsden Jacobs Associates, 2007).

In considering diversification of water supply sources, there is the need to consider cost-effectiveness as one of the criteria in developing a preferred portfolio of sources in an urban water supply system. PMSEIC (2007) undertook a comparison of the direct costs associated with different water supply/demand options. That study found that rainwater tanks can often be expensive in terms of cost per unit of water supplied. The results indicated that household scale rainwater systems have a higher unit cost for water supplied when compared to centralised water supply options. However, it is necessary to consider more than direct costs in developing a water supply source mix for cities. Other factors to be considered include reliability, environmental impact, community acceptance, freedom to water gardens and the suitability of current governance models (PMSEIC, 2007; Sharma *et al.* 2012).

In South East Queensland the mandatory requirements for rainwater tanks in new dwellings was removed in 2013 (Mander, 2013). The decision to remove the mandatory requirements for rainwater tanks was based on a report by the Queensland Competition Authority, which found that costs of the rainwater exceeded the benefits (Queensland Competition Authority, 2012). The capital and operating costs of rainwater tanks were found to be greater than anticipated benefits, which include deferred augmentation of mains water supply system, reduced operating costs for mains water supply and reduced bioretention costs (Queensland Competition Authority, 2012).

1.4.5 Understanding the indirect costs and benefits of rainwater tanks (externalities)

Outcomes from rainwater tanks that aren't captured in the direct costs and benefits to the affected parties can be considered as externalities. The parties that generally bear the direct costs or receive the direct benefits from a rainwater tank are the householder and the water utility. The latter may be impacted by reduced demand for mains water and/or offer a rebate for rainwater tank adoption. More specifically, an externality is any cost (or benefit) that is not incurred directly by the utility or the householder. Externalities are usually not adequately captured by the market price to reflect the full cost (or benefit) of the service or product, in this case rainwater tanks. There can be positive as well as negative externalities. This section discusses some of the externalities that are associated with the adoption of rainwater tanks as an alternative local water source. One of the most challenging aspects of evaluating the costs and benefits of alternative water policy options is economic quantification of the externalities.

The economic 'cost benefit ratio' may be more favourable where the rainwater tanks can be used to avoid or defer investment in stormwater infrastructure. For example, Coombes *et al.* (2000) found that

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a water sensitive design approach that included rainwater tanks could be 25% more cost effective than a conventional approach to providing stormwater infrastructure. Coombes and Kuczera (2003) found that investment in rainwater tanks provided greater economic benefits to the community than investment in traditional water supply and traditional stormwater management options. Marsden Jacob Associates (2007) made the point that the savings from deferring, downsizing or avoiding investment in traditional infrastructure due to rainwater tanks is only likely to be realised in *greenfield areas* prior to the construction of water supply and stormwater infrastructure.

Rainwater tanks uptake can provide some significant socio-economic benefits for the general public. For example, investments in rainwater tanks can leave money in local communities and create local jobs. Rainwater tanks installations require skilled labour and significant materials, while utilities starting a program to encourage rainwater tank may add staff and hire contractors. These jobs, and the materials purchased, can add significantly to the local economy and benefit the general public (Maddaus, 1999).

1.4.6 Impact of rainwater systems on stormwater flows and nutrient loads

A study by Parkinson (2005) investigated the impacts of domestic water conservation on urban sewerage systems in cities with combined sewer overflow (CSO), and concluded that rainwater harvesting was the most beneficial water conservation method. The justification for this was that rainwater tanks could assist in reducing discharge into the combined sewer system during high rainfall events (Parkinson, 2005). This finding is supported by Vaes and Berlamont (2001) who showed, based on modelling, that rainwater storage systems can significantly reduce rainfall to combined sewer systems, including reduced peak flow if installed on a sufficiently large scale. However, there is the need to account for tank storage levels at the start of the rainfall event to accurately estimate the impact of rainwater storages on downstream flows (Vaes & Berlamont, 2001).

In Australian cities (which have separate sewer and rainwater systems), the objectives of rainwater systems are primarily the augmentation of potable water supplies, and to some extent, restoration of pre-development flow regimes in the receiving waterways (Burns *et al.* 2012). The impact of rainwater tanks on the latter is not yet well understood nor quantified. Modelling undertaken by Burns *et al.* (2012) found that rainwater tanks can assist in restoring catchment retention capacity (units of mm) closer to that of the natural conditions. However, this will depend upon the match between roof size, storage volume and demand profile. A report to the National Water Commission considered the impact of rainwater tanks on the size of stormwater drains, and demonstrated that under certain conditions rainwater tanks can reduce peak flows to stormwater drains by up to 50% (Marsden Jacob Associates, 2007). This means that stormwater drain capacity could be reduced in new developments. However, there will be a limit to size reduction since drains are typically designed to manage peak flow events for a 1 in 20 year event (Marsden Jacob Associates, 2007).

The mandatory installation of rainwater tanks in all new homes of greenfield developments has implications for both receiving water quality and management of stormwater discharge. Analysis by Mackay Regional Council, located in tropical North Queensland, found that removing rainwater tanks from the stormwater treatment train increased the required wetland from 3.5% of the development catchment area to 5.8%, a 65% increase in the size of constructed wetlands needed to meet water quality targets (Galea, 2014).

The discharge of urban stormwater to receiving waters impacts on the ecological health of streams and other waterways (Walsh *et al.* 2009). Walsh *et al.* (2009) argued that if stream ecosystems are to be restored or protected, there is the need to reduce the hydraulic connectivity between impervious surfaces in urban areas and streams for the small, frequent rainfall events. Water harvesting by rainwater tanks will

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help reduce both the number and peak flow of runoff events which in turn seems to have a beneficial effect on the macro-invertebrate health of ephemeral streams around Melbourne. Reduction in nitrogen export has also been shown to be significant when rainwater tanks are installed (Sharma *et al.* 2008). Khastagir and Jayasuriya (2010) modelled the impact of rainwater tanks on runoff quality. They found that a 3 kL rainwater tank used for toilet flushing, laundry and garden watering could reduce nitrogen loads by 81%.

1.4.7 Impact of rainwater tank systems on centralised water systems and water quality

The widespread rainwater harvesting and use practices can also affect the mains water demand and quality. Grandet *et al.* (2010) studied the effect of rainwater harvesting on centralised urban water systems in Northern France. The study highlighted rainwater use resulted in a permanent decrease in mains water demand leading to an increase in water age, and hence quality deterioration in the distribution system. Water age was generally affected when rainwater supplied more than 30% of the overall water demand. However, the rainwater supply systems might be profitable for the community if rainwater use allowed the deferment of new water mains infrastructure. Lucas *et al.* (2010) investigated the impact of diurnal water use patterns, demand management and rainwater tanks on water supply network design. The study suggested that the rainwater tanks combined with mains water 'trickle top-up' produced diurnal 'mains water' use patterns different to that of 'household' water use patterns. When simulated correctly, this significantly reduced peak hour mains water demand. This outcome impacts upon water supply network design criteria and provides opportunities to offset water infrastructure costs.

1.4.8 Energy consumption in rainwater tank systems

The energy associated with household scale rainwater pumping is a function of the pump characteristics, the system set-up, and the household water use patterns (Retamal *et al.* 2009). The energy can be expressed as the 'total energy' consumed over a period of time for pumping (e.g., kWh per year) or as 'specific energy', that is, the energy required to pump a set amount of water (e.g., kWh per kL of rainwater).

The tank location relative to where water is used and the land topography can influence the head required and the associated energy usage. Gardner *et al.* (2006) and Beal *et al.* (2008) examined the energy for rainwater pumping for 4 to 6 properties located on a steep slope in Brisbane, Australia, where household rainwater tanks received back-up supply from a communal tank at the base of the slope. This study found that the energy required for water supply from the rainwater system was between 2.1 and 3.8 kWh/kL. Retamal *et al.* (2009) found the energy footprint of household-scale rainwater harvesting systems varied from 0.9 to 2.3 kWh/kL for 8 households equipped with various rainwater pump and mains backup systems, different numbers of occupants, and diverse rainwater end uses.

The large variability observed between dwellings is a reflection of the wide range of rainwater systems configurations (mainly pump type/size) and the demand characteristics of the different households (low flow or high flow appliances/end uses). It is also an indication that the energy requirements for rainwater pumping can be optimised for dwellings through appropriate system design and configuration set-up. Analysis by Umapathi *et al.* (2013), based on a monitoring study of 20 homes in South East Queensland, found that rainwater systems with automatic switching devices for topping up tanks with mains water had significantly less energy demand than systems using trickle top-up.

Small pumps used for rainwater supply are typically much less efficient than large pumps used for bulk water supply (Retamal *et al.* 2009). In Australian capital cities, pumping for centralised water supply typically has an average energy demand of 0.9 kWh/kL, with a range between 0.09 and 1.85 kWh/kL

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depending upon pumping distance and lift required for each city (Kenway *et al.* 2008). This places the median energy for household rainwater supply of 1.5 to 1.8 kWh/kL within the upper range of centralized gravity fed water supply. However, when compared to other alternative sources such as recycled water or desalinated water, which use on average 2.8 kWh/kL (Knights *et al.* 2007) and 3.5 kWh/kL (Apostolidis *et al.* 2011) respectively, rainwater supply is the least energy intensive option for alternative water supplies.

1.5 CONCLUSIONS

Rainwater harvesting for local water supply is not a new concept as there is well documented evidence of its practice since the first urban societies evolved. This chapter has reviewed rainwater harvesting practices around the world, with a particular emphasis on the drivers behind the adoption of rainwater harvesting. There is a particular focus on the Australian experience with rainwater systems, which is due to the rapid uptake of rainwater systems over the last decade. This uptake was in response to growing pressures on mains water supply systems due to an extended drought and growing population.

Rainwater tanks can provide reliable and affordable water supply in rural and remote areas where piped water supply systems are not available. In developing countries, rainwater can supply an 'improved' drinking water source where surface water is contaminated by faecal pathogens, or good quality groundwater is not readily available. In modern cities, rainwater tanks are now being implemented under integrated urban water management concepts, to reduce the volume of mains water consumed for non-potable household uses. This substitution concept is based on fit for purpose water quality to reduce unnecessary treatment costs.

This chapter has outlined some of the issues that are faced when considering the potential for rainwater harvesting systems as a secondary source of non-potable water in modern cities. These issues include understanding the likely yield from rainwater systems, both for optimising the design of the rainwater system as well as estimating the likely impact on reducing mains peak flows. There is also the need to manage the risks associated with the use of rainwater, which requires an understanding of its likely quality as well as improved guidelines on how to manage risks. The chapter has highlighted the challenges of evaluating the cost-effectiveness of rainwater harvestings relative to other alternative water sources, as well as centralised water supply systems. Whilst rainwater harvesting often has a higher cost per unit of water supplied than other sources (e.g., recycled water), consideration of externalities, such as mitigating the environmental impact of stormwater discharge to receiving waters, can increase the cost to benefit ratio. However, economic analysis has found that under most assumptions the operating and capital costs of installing a rainwater tank as a secondary water source will be greater than the benefits. The challenge is to identify the urban contexts and rainwater tanks configurations that are best suited to maximise the benefits relative to the costs. This challenge is explored in greater detail in the subsequent chapters of this book.

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Chapter 2

Rainwater tank modelling

Alison M. Vieritz, Luis E. Neumann and Stephen Cook

ABSTRACT

Mathematical models that simulate the performance of rainwater systems are important in supporting decisions on the suitability of rainwater systems to not only meet potable and non-potable water demands, but also reduce discharge of stormwater and associated pollutants to the environment. A variety of modelling tools have been developed over the last few decades to support the design of rainwater systems and optimise the combination of connected roof area and storage size to best meet demands. However, the selection of the rainwater system modelling approach can influence the predicted outcomes, with different choices of time-step, algorithms and simulation length significantly influencing the results.

This chapter presents a generalized model of a rainwater tank, and discusses its components in relation to the different rainwater tank models that have been developed around the world. We then explore the impact of key model parameters, including connected roof area, tank storage size, rainfall loss factor, water demand and climate inputs, as well as the choice of time-step and simulation length on the output, using the rainwater tank model described by Mitchell (2007). We demonstrate how each of these parameters can affect the simulated results of the tank behaviour. Finally, we show that using an 'average tank' behaviour to represent the collective behaviour of a large number of identical tanks in an urban area (also known as spatial lumping) can significantly overestimate the reliability and yield of the rainwater system. The errors introduced by such approaches are discussed using examples of yield and overflow estimation.

Keywords: Rainwater tank model; yield estimation; overflow estimation; model time-step; spatial averaging.

2.1 INTRODUCTION

It may be a little surprising to observe that rainwater tank systems have been adopted in many modern cities even though reticulated (mains) water supplies exist in these areas. There are a number of reasons for this. Firstly, they provide a secondary, non-potable water source to complement reticulated drinking water supply. Water scarcity and the need to reduce demand on the drinking water system has been the

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primary driver for the uptake of rainwater systems in Australia (Cook *et al.* 2013), Spain (Domènech & Saurí, 2011), south-eastern United States (Jones & Hunt, 2010) and Jordan (Abdulla & Al-Shareef, 2009). Secondly, in regions where water scarcity is not an issue, rainwater harvesting has been adopted to address broader urban sustainability issues, such as the mitigation of stormwater environmental impact. In Germany, rainwater harvesting has been adopted by environmentally conscious households (Herrmann & Schmida, 2000), whilst in Sweden, rainwater harvesting has been investigated as an approach to improve environmental sustainability of multi residential developments (Villarreal & Dixon, 2005). In developing countries, the context for adopting rainwater systems is that they can provide much improved quality of water relative to alternative local sources, are more affordable for low-income households, and can provide a water supply source where no piped system is provided (Campbell, 1986).

But the challenge in many places is how can these rainwater tank systems be designed for optimal performance? Indeed, how can we predict the performance of a rainwater tank system before it is even built? To support the design of rainwater systems, a variety of modelling tools have been developed over the last few decades. These tools have been developed and used to estimate the performance of rainwater tanks in various locations throughout the world including: Australia (Coombes & Barry, 2007; Mitchell, 2007), Taiwan (Su *et al.* 2009), United States (Jones & Hunt, 2010), Poland (Słyś, 2009), United Kingdom (Fewkes, 2000), Brazil (Ghisi *et al.* 2007), West Africa (Cowden *et al.* 2008), Italy (Palla *et al.* 2012) and Spain (Farreny *et al.* 2011) amongst many others.

Some of these tools are very simple, considering only the variability in annual rainfall (mm/year) when sizing rainwater tanks (e.g., Gould & Nissen-Petersen, 1999). However, this approach can obscure reliability estimates as two cities with similar annual rainfall can have significantly different seasonal rainfall patterns, and hence would be expected to show quite different tank water capture/yield behaviour (Basinger *et al.* 2010).

Another modelling approach is to develop analytical formulas that estimate the required storage volume based on the anticipated water use rate, local climate, and the required level of reliability of the tank to supply water to meet demand at any point in time. These models are very location-specific and use probabilistic relationships developed using local rainfall records (Basinger *et al.* 2010). But once developed, these models provide engineers and planners with a robust tool for rapid interpretation of likely tank performance. Further details of this approach can be found elsewhere (e.g., Guo & Baetz, 2007; Basinger *et al.* 2010) and will not be discussed in this chapter.

The most common approach for modelling rainwater system performance is to use a continuous water balance simulation that applies historical rainfall observations to generate inflow, with an assumed water demand as outflow, to calculate the volume of water within a rainwater tank as a function of time (Basinger *et al.* 2010). In this chapter, we will focus on this approach and provide examples of models that are used around the world, including countries with severe data constraints.

Finally, when modelling the behaviour of a rainwater tank for a household, or the impact of rainwater tanks in a multi residential development, a number of important factors need to be considered including time-step, simulation length, processes to include in the model, order of calculations used within the model, and output required. These factors, and their influence on the model predictions, are explored in this chapter to guide the selection of the modelling approach for a given application.

2.2 GENERAL CONCEPTS UNDERLYING A RAIN WATER TANK MODEL

Modelling the water volume inside a rainwater tank would seem straight forward compared to, say, modelling the water balance of an open paddock of grass. A rainwater tank is usually a closed vessel so that evaporative and leakage losses can be considered negligible, and there is no direct entry of rainfall.

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The water volume inside the tank could then be determined simply by the amount of roof runoff entering the tank, the amount of water drawn off (yield) to supply demand, and the amount that is lost through tank overflow. The equations needed for a rainwater tank simulation model are built upon this simple mass balance concept.

A rainwater tank system is usually comprised of a collection system (i.e., roof, gutter and downpipe) and a storage system (i.e., tank) as shown in Figure 2.1. The collection system consists of the connected roof area A (m^2), representing the area of the roof that drains to the tank, and which may be smaller than the total roof area of the household (often not all of the roof area is connected to the tank). The collection system may also include a first flush device which retains a certain volume FF (m^3). A first flush device is installed to discard the first amount of roof runoff as a contaminant mitigation measure. The storage component includes a tank with an active storage S (m^3), which excludes the dead storage volume (DS) below the supply pipe, and the area above the overflow pipe. In this closed system, water export is via the yield to household Y_t, and tank overflow O_t.

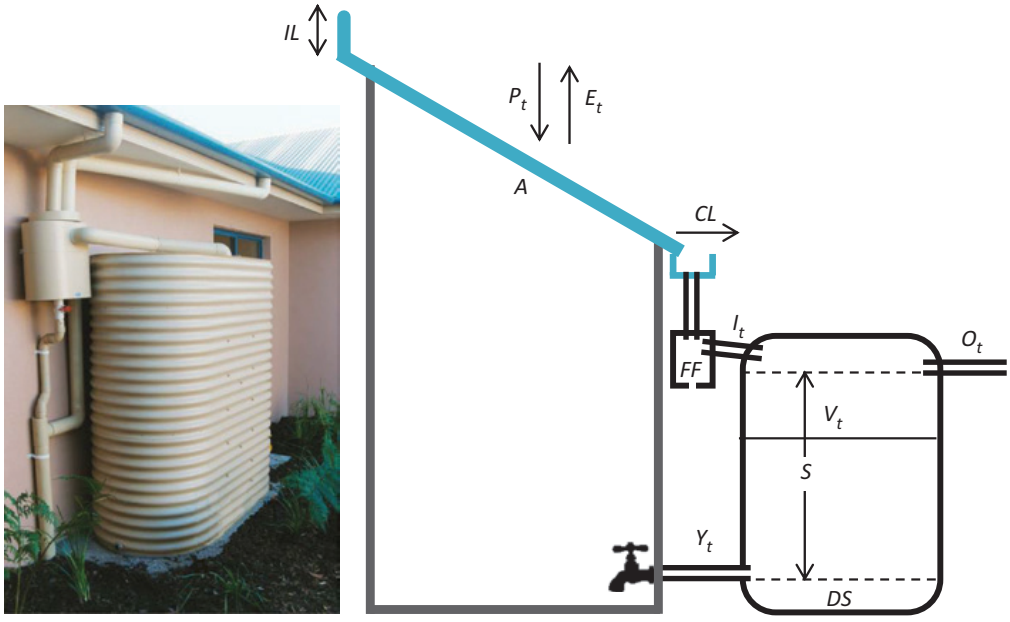


Figure 2.1 Schematic representation of a rainwater tank system.

The roof area collects rainfall P_t (mm) over a time period t. But not all rainfall that falls on the roof becomes inflow to the tank. Some of the rainfall at the beginning of a rainfall event will be lost due to wetting up of the roof surface (adhesion or detention loss), and this initial loss can be represented using a single storage of capacity IL (mm). The initial storage is also subjected to evaporation (E_t). After the initial storage is filled, the roof runoff will be further reduced by a continuing loss factor CL (%) representing a continuous percentage loss due to water being splashed or blown off the roof or gutter, and runoff capture by the first flush system. The initial and continuing losses can be represented by the following equations (Coombes & Barry, 2007; Mitchell *et al.* 2008):

$$RR_t = \max[(P_t + RST_{t-1} - IL), 0] \tag{2.1}$$

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$$RST_t = \max[(P_t + RST_{t-1}) - RR_t - E_t, 0] \tag{2.2}$$

$$HR_t = A * \frac{RR_t}{1000} * \left(1 - \frac{CL}{100}\right) \tag{2.3}$$

where HR_t is the harvestable roof runoff (m^3), RR_t is the roof runoff in mm, RST_t and RST_{t-1} are the roof storage level in mm in the current and previous time-step respectively and E_t (mm) is the evaporation over a time period t. If a first flush device is present, the inflow to the tank I_t is given by:

$$I_t = \max[(HR_t + FFI_{t-1} - FFV), 0] \tag{2.4}$$

$$FFI_t = \max[(HR_t + FFI_{t-1}) - I_t - LR, 0] \tag{2.5}$$

where FFI_t and FFI_{t-1} are the volume of roof runoff captured by the first flush device at time t and t–1, respectively; FFV is the capacity of the first flush device and LR is the leakage rate. The leakage rate represents the volume (m^3) at which the first flush device drips in one time-step. If the system does not have a first flush device, the inflow to the tank I_t is equal to the harvestable roof runoff HR_t.

The second part of the model uses a simple water balance to simulate the amount of water stored in the tank (Mitchell *et al.* 2008):

$$V_t = V_{t-1} + I_t - O_t - Y_t \tag{2.6}$$

where V_t and V_{t-1} are the volume of water (m^3) in the tank at the end of the current time-step and at the end of the previous time-step, respectively; O_t is the tank overflow (m^3); and Y_t is the yield or volume of water extracted from the tank during time-step t. The water balance in *Equation 2.6* assumes that the rainwater tank is a closed vessel (as mentioned previously) and hence direct rainfall and evaporation are excluded.

To solve the water balance given by *Equation 2.6* in a model simulation, overflow and yield must be calculated for each time-step. However, tank inflow, yield and overflow can occur in any order or can occur simultaneously during any time-step. If the time-steps are large, it is also possible that multiple events occur within one time-step, but the model will only be able to simulate the multiple events as one lumped event. The discrete nature of *Equation 2.6* means that an order for the inflow, yield and overflow processes must be assumed in the calculation process. If yield is assumed to occur before overflow (spill), the model type is called YBS (Yield Before Spill). If spill is assumed to occur before yield, the model type is called YAS (Yield After Spill). Therefore, for a YBS model, the yield Y_t for a time t is given by (Jenkins & Pearson, 1978; Fewkes & Butler, 2000; Liaw & Tsai, 2004):

$$Y_t = \min[D_t, V_{t-1} + I_t] \tag{2.7}$$

$$V_t = \min[S, V_{t-1} + I_t - Y_t] \tag{2.8}$$

where D_t is the demand for tank water (m^3) for a time-step t, S is the active storage (m^3) which excludes any dead storage below the water level from which yield is taken.

For a YAS model, the equations are (Jenkins & Pearson, 1978; Fewkes & Butler, 2000; Liaw & Tsai, 2004):

$$Y_t = \min[D_t, V_{t-1}] \tag{2.9}$$

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$$V_t = \min[S - Y_t, V_{t-1} + I_t - Y_t] \tag{2.10}$$

As the equations for V_t constrains the tank water volume remaining at the end of the time-step to its maximum volume, the excess water is routed as overflow. Hence overflow O_t is calculated as:

For YBS model:

$$O_t = \max[(V_{t-1} + I_t - Y_t) - S, 0] \tag{2.11}$$

For YAS model:

$$O_t = \max[(V_{t-1} + I_t - Y_t) - (S - Y_t), 0] = \max[(V_{t-1} + I_t) - S, 0] \tag{2.12}$$

Comparison of the yield equations for the YBS and YAS models shows that yield will often be greater in the YBS model in each time-step, since it can include the inflow water as part of the yield to meet household demand. Consequently, the overflow will be potentially smaller in the YBS model in each time-step, since tank yield is first removed from any inflow before the remaining inflow is available for overflow. The implication of this 'order of calculation' concept on predicting rainwater tank behaviour will be discussed later.

To simulate the complete rainwater tank behaviour, these calculations of yield, overflow and water volume are simply repeated for a continuous series of time-steps, with the tank water volume from the previous time-step becoming the starting tank water volume for the next time-step. In this way, the rainwater tank model outlined above will predict the partitioning of any roof-impacting rainwater into initial roof loss, continuing roof losses and roof runoff. The runoff may then be further partitioned into loss from a first flush device and tank inflow. Any inflow is then added to the water store within the tank. Meanwhile, the tank water store may undergo further partitioning with some being extracted as yield to the household. If there is insufficient water in the tank to supply all of the household demand for a particular time-step, then the yield will be less than demand. Where the tank storage capacity is exceeded at the end of the time-step, excess tank water is partitioned to overflow.

The inputs required by this model are the connected roof area, effective tank volume, the depth of the roof storage representing initial loss, the proportion of roof runoff that is continuously lost due to splash, the capacity of the first flush device, and the first flush leakage rate. For each time-step, rainfall, evaporation and household water demand is required. The length of the time-step will determine how much variability of these inputs over time can potentially be captured by the modelling. The amount of variability that needs to be captured will depend on the purpose of the modelling, and this will be discussed later.

The outputs from this model are the predicted yield and overflow over the period simulated for the specified roof area and tank storage volume. The long term yield Y can be calculated and compared with the long term demand D to provide the tank performance measure volumetric reliability VR, the proportion of household demand that is likely to be supplied from the rainwater tank where:

$$Y = \sum_{t=1}^{T} Y_t \quad \text{and} \quad D = \sum_{t=1}^{T} D_t \tag{2.13}$$

$$VR = \frac{Y}{D} \tag{2.14}$$

where T is the total number of time-steps in the period of simulation.

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Having described the general components and concepts underlying a physically rigorous rainwater tank model, we will now explore the modelling approaches that have been used to address particular objectives and issues.

2.3 ASPECTS OF SOME EXISTING RAIN WATER TANK MODELS

A selection of continuous simulation models of rainwater tank applied in various locations around the world were reviewed and were found to vary considerably in complexity, ranging from simple spreadsheet models (Roebuck & Ashley, 2007; Imteaz *et al.* 2011) to software using a spreadsheet user interface (Liu *et al.* 2006; Vieritz *et al.* 2007a,b), and to very detailed process based models (Coombes & Kuczera, 2001) that include hydraulic calculations and processes not described in our generalised model. We also mention urban water models that simulate the whole of the water cycle, including on-site detention, infiltration, wastewater, greywater and stormwater flows. Such models include rainwater tanks and are particularly common in Australia; for example, Aquacycle (Mitchell, 2005), UVQ (Mitchell & Diaper, 2006), MUSIC (CRC-CH, 2005), Urban Developer (eWater Cooperative Research Centre, 2011), and Watercress (Clark *et al.* 2002). However, these models will not be discussed in any detail in this chapter.

We will now consider the following aspects of the rainwater tank component of these models: time-step, climate data inputs, demand data inputs, roof runoff modelling, tank water balance configurations, and the use of model outputs.

2.3.1 Time-step and climate data inputs

The climate data required will depend on the time-step used in the rainwater tank model. The time-step chosen is often constrained by the availability of rainfall data, with daily data being more commonly available than sub-daily data. Hence, most of the simulation models reviewed used a daily time-step, although some used a time-step as short as 6 minutes (Coombes & Kuczera, 2001).

Climate data may be sourced from historical daily climate records provided by weather stations in the locality of interest. In Australia, interpolated climate data is available by fitting daily surfaces to climate data supplied by weather stations across the country (SILO Climate Data, http://www.longpaddock.qld.gov.au/silo/data_available.html). This climate data includes daily rainfall and evaporation values across Australia on a 0.05 degree grid, extending back to 1889.

However, Cowden (2008), when developing a model for use in a data-poor region of West Africa, found that daily rainfall records were available for only a limited number of sites, were of short-duration, and contained many missing values. This highlights a limitation in continuous simulation models. They are only useful provided reliable and continuous input data exists. One approach to addressing limited rainfall data availability is to develop rainfall models using parametric estimators of rainfall (Guo & Baetz, 2007). But a fundamental issue with parametric rainfall models is that the probabilistic relationships developed to generate a rainfall record require a certain length of historical data to exist. Secondly, the probabilistic relationships developed are generally not portable to other geographic locations, since rainfall distribution and seasonality can differ substantially from location to location. Nonetheless, improved portability has been reported when using non-parametric estimators of rainfall (Cowden *et al.* 2008; Basinger *et al.* 2010).

For models requiring sub-daily climate data, approaches include measured pluviograph data; daily rain data from which synthetic pluviograph rainfall can be generated based on nearby pluviograph rainfall records; or rainfall models such as the event rainfall model (DRIP) developed by Heneker *et al.* (2001).

All these approaches assume that the historic climate record provides an adequate prediction of the future climate, at least for the operational period of the rainwater tank system being designed. In Australia,

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climate projections data generated by 19 global climate models for a range of emission scenarios and climate sensitivities have been made available at http://www.longpaddock.qld.gov.au/climateprojections/about.html so that the predicted impacts of climate change can be incorporated into modelling, if desired.

2.3.2 Water demand data inputs

In rainwater tank simulations, obtaining accurate estimations of the water demand from the tank is almost as important as having access to climate data appropriate to the location. The sensitivity of tank performance predictions to demand and its temporal pattern will be demonstrated later (Section 2.4.4). Locally measured data is always the preferred source of demand data, but is not always available. Cowden *et al.* (2008), in assessing the reliability of small-capacity rainwater tank systems used in low-income households in West Africa, simply assumed 20 L/person/day, the World Health Organization's recommendation to meet basic consumption and hygiene needs (Howard & Bartram, 2003). However, assessment of rainwater tank performance in developed urbanised countries will usually require data on the non-constrained quantity of water required by the household. Household demand has been found to vary greatly due to occupancy rate, type of appliances used, behaviour and attitudes to water use, and household age structure. Such data can now be found for many locations as numerous studies have been done to quantify the amounts of water used for various internal and external end uses (e.g., Mayer *et al.* 1999; Dziegielewski *et al.* 2000; Roberts, 2004; Roberts, 2005; Willis *et al.* 2009; Sivakumaran & Aramaki, 2010; Beal & Stewart, 2011; Willis *et al.* 2011; Water Corporation, 2011; von Voigt & Mohajeri, 2013). Some models disaggregate household internal water demand into various end uses such as kitchen, laundry, bathroom, toilet, and hot or cold water (Combes & Kuczera, 2001; Vieritz *et al.* 2007a,b; Khastagir & Jayasuriya, 2010). End uses suitable for rainwater substitution are then selected and summed to estimate the demand for tank water by the household.

The household tank demand has been applied as a single value for all time-steps, either yearly or daily in a large number of rainwater tank studies (e.g., Fewkes, 2000; Fewkes & Butler, 2000; Liaw & Tsai, 2004; Ghisi *et al.* 2007; Jones & Hunt, 2010; Palla *et al.* 2011; Palla *et al.* 2012; Campisano *et al.* 2013). However, this will be adequate only where the chosen end uses do not show significant variation across time-steps, for example, if tank water is used exclusively for internal uses such as consumption (Cowden *et al.* 2008), or toilet flushing (Mitchell, 2007; KRANRRC, 2011; Neumann *et al.* 2011; Palla *et al.* 2012). External end uses (e.g., garden watering, car washing and pool top-up) usually exhibit a strong seasonal variation which must be parameterised for the model to provide realistic predictions on yield and overtopping. Coombes and Barry (2007) showed that simulations without accounting for seasonal demand underestimated rainwater yields by up to 25%, although the differences became smaller as the tank size increased.

To capture this seasonal variability in a rainwater tank model, internal and external household daily water demands are usually modelled separately. For internal household demand, Vieritz *et al.* (2007a,b) multiplied the *average* indoor water demand per person for the region by the average number of occupants per household. Burns *et al.* (2012) describes a method of using standardized measured household tank usage data to obtain daily usage distributions for each end use, from which 10-year daily usage records can be stochastically generated. Where relevant daily internal water use data is not readily available, a strategy for estimating household indoor water demand is to use an end use model to generate demands (e.g., Coombes, 2002; Duncan & Mitchell, 2008). In the empirical model developed by Coombes (2002), a regression equation was developed that related monthly daily average internal use by households in the Lower Hunter region, Australia, to the number of occupants, the average weekly income per person, monthly daily average rainfall, annual population growth, the number of days with rainfall in a month,

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and the mean monthly daily maximum temperature. However, these models are developed from available data for one specific region. For use in other regions, the model coefficients need to be calibrated against a set of locally measured water use data.

Where relevant external water use data is not readily available, one strategy is to use a physically based crop water use model. Jones and Hunt (2010) incorporated a plant irrigation module into their model so that outdoor demand for garden watering was determined according to the modelled soil water deficit and irrigation rules. By triggering irrigation when the soil dried to a specified moisture content, the seasonal effect of fewer irrigation events in wet periods was captured effectively in the modelling. A similar approach was adopted by Vieritz *et al.* (2007a,b) using a soil water balance based on inputs (rain and irrigation) and outputs (evapotranspiration and runoff plus deep drainage losses). Irrigation timing/volumes were then determined based on rules dependent on soil moisture and day of the week. However, outdoor water use is a behaviour moderated reaction to climate, and social factors such as garden interest and the householder's assessment of garden water needs can override soil moisture considerations (Beal *et al.* 2014). This was addressed by allowing the model user to constrain the predicted average annual external water use to an annual 'measured' value (calculated from suburban scale water meter readings and estimated internal water use). The model then automatically adjusts the irrigation amount and timing to constrain the predicted average annual external water use to the average 'measured' suburban scale value. Another strategy involves using regression equations and irrigation probability functions. Coombes (2002) developed a regression equation along similar lines to that previously described for estimating indoor water use. He then developed an improved outdoor demand generator based on the probability of irrigation taking place following various sequences of wet and dry days. Duncan and Mitchell (2008) estimated the probability of garden irrigation in a particular time-step as a function of daily maximum temperature. Combined with user-defined probability distributions (mean and standard deviation) of irrigation flow rate, garden irrigation could be estimated for each time-step. However, all these probabilistic approaches require the demand model to be calibrated against observed data. For example, Coombes and Barry (2007) used average internal and external water demands for three person households (from government survey reports) and local pluviograph rainfall records to generate daily water demands modified by climate influences for each Australian capital city using the demand generator developed by Coombes (2002).

Swimming pool top-up may be another external end use for water from a rainwater tank. In one model, the demand is based on garden watering rules, which can be adjusted to model swimming pool top-up as the water demand is related to the net evaporative demand of the local climate (Vieritz *et al.* 2007b). The pool is assumed to evaporate at a specified percentage of Class A Pan evaporation when uncovered (no pool blanket), and top-up is triggered whenever the water level in the pool falls to a specified distance below full level mark.

For other external end uses such as car washing, estimates of hosing duration for each event, hose flow rate and frequency of the event through the year can be used to estimate water use. Such data may be sourced from survey literature and field observations. For example, one U.S. study estimated that the water use for car washing was 75 L per vehicle based on field observations and simulations using a low flow nozzle (Smith & Shilley, 2009).

Once the amounts of tank water required for a range of internal and external end use options have been estimated, these are summed for each time-step to provide the demand required for the tank water balance. If the models are run at sub-daily time-steps, suitable sub-daily demand data is required. Demand generators such as the stochastic generator of Duncan and Mitchell (2008) (described further in Section 2.4) can be used to generate demand at sub-daily time-steps, or daily demand can be disaggregated into the required time-steps based on appropriate diurnal water use patterns (Coombes & Kuczera, 2001).

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2.3.3 Roof runoff modelling

Some models ignore roof runoff losses and estimate roof runoff (m^3) as rainfall (m) × roof area (m^2). Others include a single roof runoff coefficient in the calculation to account for loss such that it is always a constant proportion of potential roof runoff (Cowden *et al.* 2008; Imteaz *et al.* 2011; KRANRRC, 2011). Studies have shown that roof runoff coefficients are dependent on roof materials, roof orientation relative to rain direction, as well as rainfall event patterns (e.g., Ragab *et al.* 2003). Roof runoff coefficient values typically used in modelling range from 0.7–0.95 (Fewkes, 2000; Liaw & Tsai, 2004; Ghisi *et al.* 2007), but with experimental measurements reporting values in the range 0.62–0.95 (Farreny *et al.* 2011). For some locations with semi-arid and infrequent rainfall, the coefficient of runoff can be as low as 0.5 (KRANRRC, 2011). The rainfall logger data presented in KRANRRC (2011) suggested that the low runoff coefficient may be due to the dominance of roof absorption losses for rainfall events less than about 3 mm which dominated the rainfall record (64% of events < 3mm). However runoff coefficients increased to 0.7 to 1.0 when rainfall exceeded 3 mm.

Roof runoff loss due to first flush devices has been included in some models (Clark *et al.* 2002; Roebuck & Ashley, 2007; Vieritz *et al.* 2007a,b; Basinger *et al.* 2010; Jones & Hunt, 2010; Khastagir & Jayasuriya, 2010b), and is often represented as a slowly leaking reservoir of a specified volume that must be kept filled before rain water can flow onto the storage tank. The amount of roof runoff that is discarded by the first flush device can have a significant impact on rainwater catch, especially if the rate of leakage from the device is high (Millar *et al.* 2003). A highly detailed model of a first flush device was incorporated into the PURRS model by Coombes (2002), which, together with a very short time-step (6 minutes), was able to provide accurate hydraulic analysis of the behaviour of the first flush device.

2.3.4 Tank water balance configurations

As discussed previously, both the YAS (Yield After Spill) and YBS (Yield Before Spill) order of calculations for the tank water balance (Equation 2.6) are approximations of real systems given the fact that neither considers the (plausible) scenario of yield, inflow and overflow occurring simultaneously. A number of models use the YBS assumption (Dixon *et al.* 1999; Liaw & Tsai, 2004; Basinger *et al.* 2010; Imteaz *et al.* 2011; Burns *et al.* 2012), whilst others use the YAS assumption (Roebuck & Ashley, 2007; Słyś, 2009; Palla *et al.* 2011; Palla *et al.* 2012; Campisano *et al.* 2013), or leave it to the discretion of the user to choose (Vieritz *et al.* 2007a,b).

Fewkes (2000) investigated a generic form of the YAS/YBS equations which used a parameter, θ. If $\theta = 1$, the equation reverts to the YAS form, and if $\theta = 0$, the form reverts to the YBS equation. The model using θ and a monthly time-step was then compared to daily YAS simulations and a value of θ was found for a given set of conditions as such that there was little difference between the volumetric reliability predictions (percentage of demand met by the rainwater tank) by the two models. The value θ simulating a blend of YBS and YAS rules, was considered to incorporate the effect of daily fluctuations into the monthly time-step simulation so as to improve the model's performance. However, as the value of θ is dependent on demand, tank size and rainfall, it is therefore hard to define *a priori*. The importance of this choice between YBS and YAS on a model's predictions will be discussed further in Section 2.4.1.

Some tank models include additional inputs other than roof runoff into the tank, such as: automatic mains top-up triggered when the tank water level falls below a specified threshold value (Vieritz *et al.* 2007a,b; Słyś, 2009); and trucked-in water to re-fill a tank (Vieritz *et al.* 2007a,b). In one model of a domestic water reuse system, both rainwater and grey water were included as inflows (Dixon *et al.* 1999). The water balance described by Equation 2.6 must therefore be expanded to include the new inflows. In Vieritz *et al.* (2007a,b), the components of the tank water balance are the rainwater, any top-up water

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(mains or trucked water), water use for internal purposes, water use for external purposes (but only if water demand for internal purposes is first satisfied), overflow, and the change in tank water volume. Top-up occurs according to rules specified by the user, with the option to specify a threshold tank water height for triggering the addition of top-up water. For the mains trickle top-up option, a trickle top-up connection allows mains water to flow into the tank when the volume of water in the tank falls below a specified level. This flow restores the volume in the tank back to this trigger level. For this daily time-step model, this level corresponds to the maximum trickle top-up volume, which is the maximum volume of mains water that can flow into the rainwater tank on any one day, and which must be at least equal to the maximum internal daily draw (L/day) on the rainwater to ensure that the household will never run out of water for internal end uses. This means that the tank volume below this trigger level is maintained with mains water, and is effectively part of the tank dead storage (*DS* in Figure 2.1) with respect to both *rainwater* collection and use when considering the active tank storage volume for tank size optimisations. In a sub-daily time-step model, trickle top-up was triggered when the tank volume reached a minimum active storage volume (Coombes *et al.* 2003). This minimum active storage volume was set to the maximum daily water use that is expected from the tank minus the maximum daily mains water top-up volume (as topping up can be simulated throughout each day). Barry and Coombes (2006) provide further details of the impact of mains trickle top-up rate and trickle top-up volume on tank performance.

2.3.5 Model outputs

In general, most rainwater tank models are used primarily to determine how much water can be supplied by the tank to meet the defined set of water demands. These estimates of yield can take various forms, such as volumetric (kL per year) based on either annual or daily yield; volumetric reliability based on the percentage of the demand that was met by rainwater; or temporal reliability based on the percentage of days the demand was met. The estimates of yield can then be used to investigate the reliability of tanks as an alternative (primary) water source, or their impact on the reduction of mains water use.

Multiple runs of the model may be used with systematic variation in roof area and storage volume (within specified ranges) to create reliability of supply contours in a graph box using roof area and storage volume as the plotting axes (Liaw & Tsai, 2004; Vieritz *et al.* 2007a,b). The contours can be used to help select optimal roof area and tank storage volume for a particular supply performance criterion (e.g., kL/year, volumetric reliability, and etc.).

The combined impact on water savings by a cluster of rainwater tanks may be modelled by performing continuous simulation of each rainwater tank system. However, simple scaling up of the results from continuous simulation of single rainwater tank system representing the 'average' system is not recommended and this will be discussed further in Section 2.5.

To avoid the need for extensive simulations, several authors (Su *et al.* 2009; Khastagir & Jayasuriya, 2010b; Palla *et al.* 2011; Palla *et al.* 2012; Campisano *et al.* 2013) proposed the use of curves relating the volumetric reliability (*aka* saving efficiency or % demand supplied) to dimensionless parameters. Palla *et al.* (2011, 2012) used two dimensionless parameters, the demand fraction (annual demand divided by annual inflow) and storage fraction (storage divided by annual inflow), to describe the mains water savings for a range of roof areas and tank storage volumes in Europe. Campisano *et al.* (2013) proposed another dimensionless parameter that takes into account intra-annual rainfall patterns, and fitted a regression equation to estimate water saving efficiency for 17 sites in Italy. Hanson *et al.* (2009) developed regression relationships to calculate required domestic storage capacity that was generally applicable for the USA. All these equations provide an estimate of yield, either in volumetric terms (kL/year) or as a proportion of demand satisfied (%), as a function of roof area, rainfall depth and storage size. Therefore, these models provide a basic means

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of estimating system performance, but incorporate a variety of simplifying assumptions regarding water use rates, overflow volumes, and rainfall depths. In all these cases, care must be taken as these regression models use a non-varying value to represent demand including the seasonally variable outdoor water use. This assumption can lead to substantial errors in supply predictions (Coombes & Barry, 2007). Taken overall, empirical curves and analytical formulas should be restricted to situations where the rainfall and demand patterns are similar to those patterns used in the derivation of the analytical solutions.

Once yields are calculated based on demands, rainfall, roof area and tank sizes, it is possible to extend the calculations to optimize tanks, not only in terms of yield but also on costs (Liaw & Tsai, 2004) or life cycle cost estimations which consider payback periods, expected water savings, capital and operational cost (Imteaz *et al.* 2011). Jenkins (2007) considered the cost of supplying rainwater and found that as consumption rate decreased, the unit cost of supply increased, and that this could be used to determine an economically optimum size of the rainwater tank. For further details on economic analysis of rainwater tanks, see Chapter 12.

In addition to supplying water to meet internal and external demands, rainwater tanks can also provide benefits such as reduction in stormwater runoff and pollutant export to waterways due to the reduction in volumes, as well as treatment provided by tanks (Khastagir & Jayasuriya, 2010a; Neumann *et al.* 2011). In a stormwater study, Vaes and Berlamont (2001) considered the influence of runoff reduction due to rainwater tanks and adjusted the runoff from design storms used for sizing combined sewer systems (sewage plus stormwater). Burns *et al.* (2010) assessed the impact of rainwater tanks as allotment-scale stormwater management devices for a hypothetical catchment using MUSIC for tank storage and overflow modelling, and a flood event model. The modelling indicated that tanks provided moderate, but potentially significant reductions to flood risk, with a further benefit of protecting the ecological health of urban streams degraded by the frequent stormwater runoff. (The impact of rainwater tanks on stormwater quantity and quality is discussed in detail in Chapter 13.)

2.4 INFLUENCE OF DIFFERENT VARIABLES IN THE TANK SIMULATION

Based on the rainwater tank schematic described in Figure 2.1 and the equations used to describe the hydrologic behaviour of the rainwater tank, it is clear that the model parameters that influence the yield of a rainwater tank are roof area, tank volume, demand, roof initial loss and roof continuing loss factor. In addition to these five key parameters, model results are also dependent on the total simulation length, choice of time-step and spill rule (YAS/YBS), and climate inputs (rainfall and evaporation). A brief description of the influence of each of these variables is given in this section using the rainwater tank model described by Mitchell (2007). This model is based on Equations 2.1 to 2.6 and the YAS rule.[1]

The model was run for 5000 different combinations of the model parameters (roof area, tank volume, demand, initial loss and continuing loss factor) initially using daily time-steps. Hourly and 6-minute simulations using the same parameter sets were also run to demonstrate the influence of time-step length. The rainwater tank model parameterization adopted here is identical to that used by Mitchell *et al.* (2008), in which model parameters for detached residential dwellings in Melbourne were determined by literature review and industry consultation. In that study, tank volume, roof area, roof depression storage (initial loss), and effective roof area loss factor (continuing loss factor) are modelled as truncated normal distributions

[1]The *YAS* form used in this model replaces *Equation 2.9* with $Y_t = \min[D_t, V_{t-1} + I_t]$ and replaces *Equation 2.10* with $V_t = \max[\min[S - Y_t, V_{t-1} + I_t - Y_t], 0]$. The yield for a given time step is calculated *after* the inflow to the tank is added to the existing volume, whereas in the YAS form given in *Equation 2.9*, the yield is computed *before* the addition of the inflow. This necessitates a change in the calculation of the final volume V_t to avoid negative volumes if $V_{t-1} + I_t > S$.

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bounded by maximum and minimum values (to avoid physically implausible values) and are listed in Table 2.1. The initial roof loss distribution was adjusted to slightly higher values to account for the use of daily time-step as recommended by Mitchell *et al.* (2008).

Table 2.1 Assumed normal distributions of the variables used in the rainwater modelling in Melbourne using the Mitchell *et al.* (2008) model. The maximum and minimum values define the truncation values of the stochastic distributions.

Parameter	Minimum	Mean	Maximum	Standard deviation
Tank capacity (kL)	0.1	2.5	20	1.5
Roof area (m^2)	25	100	400	50
Initial Loss (mm)	0	0.5	1.7	0.5
Continuing loss (%)	0	15	30	5

The water demand data was created using a stochastic generator developed by Duncan and Mitchell (2008) and calibrated to measured Melbourne demand data reported by Roberts (2004, 2005). The demand generator uses flow rates of the various end uses, household occupancy and seasonality to generate water demands at one minute time-steps, which were aggregated to daily values. The demands considered here are toilet flushing and outdoor irrigation. The toilet end use is dependent on household occupancy, but is non-seasonal. In contrast, the garden end use has large variations in demand due to seasonality, but is relatively insensitive to the occupancy. The use of both demands therefore produces a water use pattern that has both seasonal and non-seasonal components. The toilet demand is generated using a diurnal pattern, flush volumes and number of flushes per person. The household occupancy was assumed to vary between 1 and 6 persons/household, with a distribution statistically generated to simulate household variability. The average toilet demand used was 32 litres per person per day (L/p/day), and the average outdoor use is 234 L/household/day. Based on average occupancy of 2.6 persons/household, the average yearly demand is 115 kL. The total simulation period was 50 years in order to avoid errors in estimation when using short time series (Liaw & Tsai, 2004; Mitchell, 2007). During the simulation period, the mean annual rainfall was 653 mm/year, with a mean annual potential evaporation of 1051 mm/year.

2.4.1 Time-step and spill rule

Several studies have examined the effect of time-steps on the results of rainwater tank simulation (Fewkes, 2000; Fewkes & Butler, 2000; Coombes & Barry, 2007; Mitchell, 2007) and all agreed that shorter time-steps are recommended when simulating small storage sizes. Fewkes and Butler (2000) and Mitchell (2007) compared results of year-long simulations using monthly, daily and hourly models with constant water demands, but a variety of storage size and inflows. The results from these two studies recommend a simulation time-step based on the (dimensionless) ratio of storage size to the mean annual inflow (*S/I*). Fewkes and Butler (2000) recommended an hourly time-step model if the *S/I* ratio is smaller than 0.01, with daily models recommended if $0.125 \geq S/I > 0.01$. Monthly models can be used if *S/I* is larger than 0.125. The study by Mitchell (2007) extended these results by considering longer simulation periods, a range of climatic zones in Australia, seasonality, and different quantum of demand. Accepting that the YAS rule with a 6 minute time-step provides the most accurate estimation of yield, Mitchell recommended using a daily time-step if the *S/I* ratio is equal to or higher than 0.007.

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Table 2.2 shows the differences in yield estimation for different time-steps, spill rules and different *S*/*I* ratios resulting from different tank volumes (*S*) and roof sizes (i.e., different inflow, *I*), based on the parameters described in the previous section, and an annual demand of 115 kL for toilet demand and outdoor irrigation. It is clear from Table 2.2 that larger time-steps are likely to be acceptable for model simulations using the YAS rule with tank size and roof area combinations that fall within the practical ranges. Errors are small even for $S/I = 0.004$, which corresponds to a very small tank (0.5 kL) and a relatively large connected roof area (200 m^2). For a larger tank and same roof size, the error becomes negligible. However, if the model uses the YBS rule, the errors associated with different time-steps become more significant, even for the same *S*/*I* ratio and demand. The difference between a 6-minute and a daily time-step for a *S*/*I* of 0.004 is –2.9% for a YAS rule, yet increases up to 17.6% for the YBS rule. These results are in agreement with Mitchell (2007) who showed that errors due to different time-steps are larger for a model using a YBS rule than the YAS rule.

Table 2.2 The effect of simulation time-step, spill rules (YAS and YBS) and tank and roof sizes on yearly yields (kL) and its percent changes. The annual water demand was 115 kL.

Tank size (kL)	Roof area (m^2)	Inflow (kL)	*S*/*I*	Spill rule	Yield 6 min time-step (kL)	% Difference compared to 6 min	
						Hourly	Daily
0.5	200	117.5	0.004	YAS	30.6	–0.3	–2.9
0.5	100	58.8	0.008	YAS	25.9	–0.1	–2.1
5	200	117.5	0.04	YAS	64.4	0	0.2
5	100	58.8	0.08	YAS	47.8	0	0.1
0.5	200	117.5	0.004	YBS	30.7	1.0	17.6
0.5	100	58.8	0.008	YBS	26.0	0.6	13.4
5	200	117.5	0.04	YBS	64.4	0	1.1
5	100	58.8	0.08	YBS	47.8	0	0.5

The influence of time-steps in the estimation of yield is shown in Figure 2.2, with results for the estimated tank overflow for the same simulations shown in Figure 2.3. For these figures, the *S*/*I* ratio varies between 0.001 and 0.32 and as such are within the ratios for which Fewkes and Butler (2000) and Mitchell (2007) recommend a transition from 6-minute to daily and hourly time-steps. As can be seen in Figure 2.2, the degree of under or overestimation also increases with the time-step, with daily time-steps producing larger differences than hourly time-steps. In a 6-minute time-step, several demand events may occur during the day, therefore removing water from the tank and increasing the available volume to capture roof runoff, and therefore reducing overflow. As the time-step increases, individual inflow, overflow and demand events are lumped, increasing their magnitude and decreasing their frequency (Mitchell, 2007). A daily model can only have one inflow, one demand and one overflow event in a day, whereas an hourly model can have 24 occurrences of each event type in a day. Where the tank storage volume *S* is small relative to inflow (low *S*/*I* ratio), individual rainfall inflow events and demand events have a large impact on tank water volume. Hence in situations with low *S*/*I* ratio, the lumping of events required by a daily time-step model leads to a less accurate simulation of the tank water volume than shorter time-step models.

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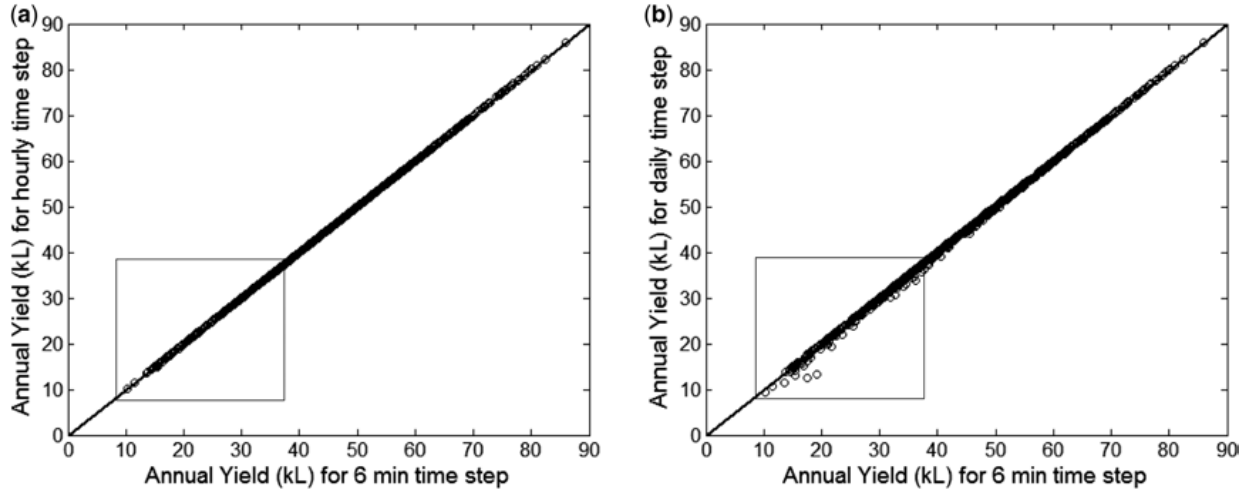


Figure 2.2 Comparison of estimated rainwater tank yield for YAS simulations using a 6-minute time-step versus simulations using hourly (a) and daily (b) time-steps. Simulations were based on the parameters described at the beginning of Section 2.4.

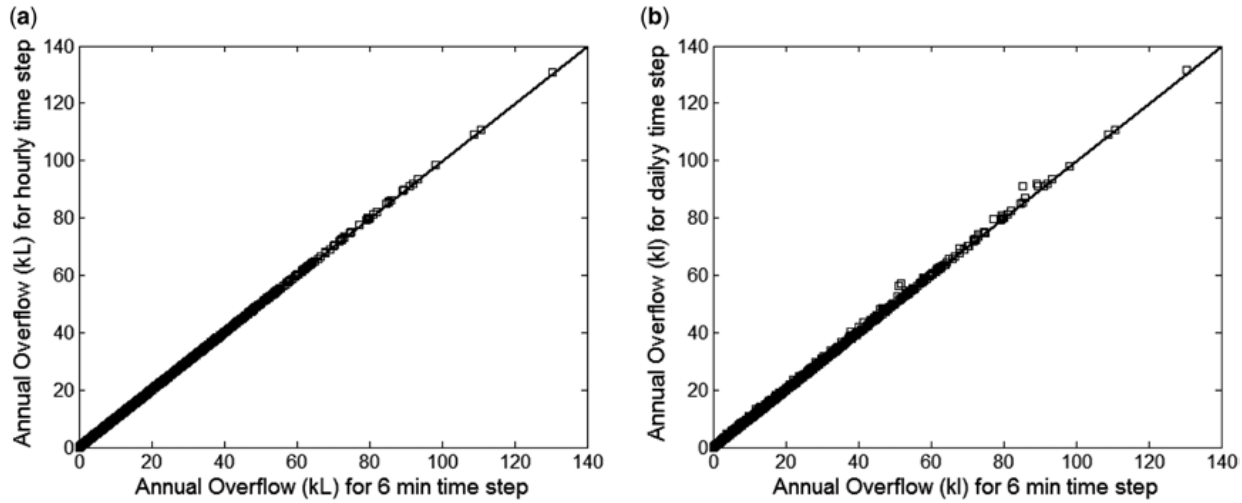


Figure 2.3 Comparison of estimated rainwater tank overflow for YAS simulations, using a 6-minute time-step versus simulations using hourly (a) and daily (b) time-steps. Simulations were based on the parameters described at the beginning of Section 2.4.

Table 2.2 shows that a YAS rule based model allows the use of hourly or daily time-steps for most practical applications as the *S*/*I* ratio is likely to be high if tank storage capacities of 1 kL or larger and reasonable roof sizes are used. A 5 kL tank with 100 m^2 connected roof area, which was considered as typical for planning purposes in Queensland (Department of Local Government and Planning, 2008), shows only a 0.1% difference in annual yield between daily and 6-minute time-steps. The use of smaller time-steps is recommended if detailed hydraulic analyses are needed, as flow routing and other hydraulic calculations often need short time-steps if they are to maintain accuracy. Therefore, as the required time scale of the hydraulic processes calculation is much smaller than a day, smaller time-steps have to be used for such analyses.

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2.4.2 Roof area

The roof area used in rainwater tank models must reflect the area of roof actually connected to the rainwater tank. Tank location and household design may only allow for a section of the roof to be connected to the rainwater tank. Ignoring for the moment rainfall losses described by the interception and depression stores, the inflow to the tank is directly proportional to the roof area for a given rainfall. As shown in Figure 2.4, as the roof size increases, the yield from the rainwater tank initially increases linearly, but after a certain roof size, the increase falls away as the yield becomes limited either by the tank size, or the water demand from the tank. Further increases in the roof area will lead to minimal improvement in yield.

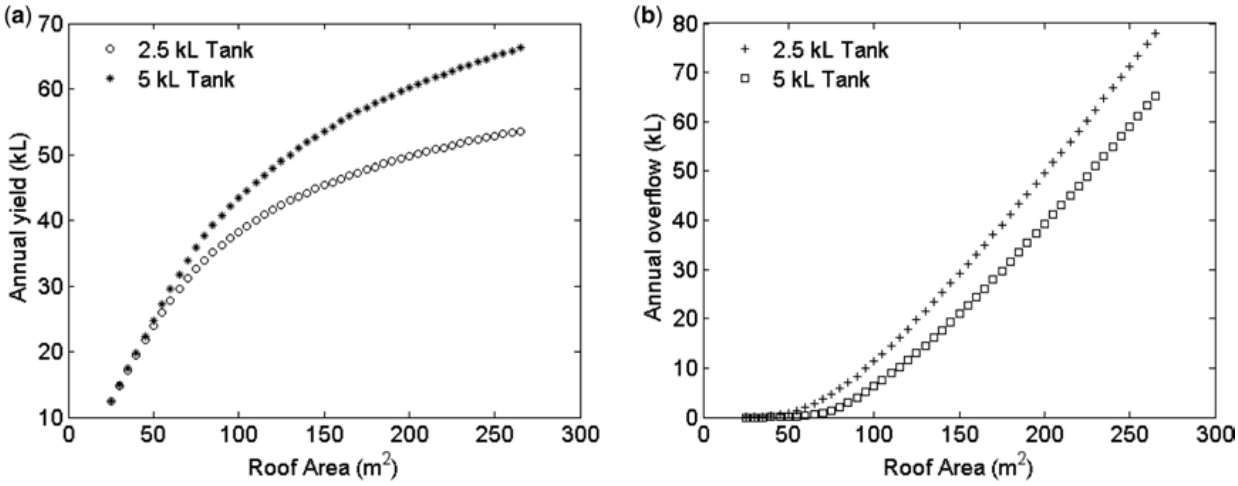


Figure 2.4 Annual yield (a) and overflow (b) for rainwater tanks of 2.5 and 5 kL for different connected roof areas (all other parameters using mean values in Table 2.1).

In contrast to the yield response, the overflow from the rainwater tank for smaller connected roof areas is nearly zero with most, if not all, inflow being used by the demands from the tank. However as the roof area, and hence roof runoff increase, the tank inflow is more than sufficient to satisfy the demand and fill the tank. At this stage, increases in the area of connected roof lead to larger increases in overflow. In such cases, larger roof area leads to increases in overflow as the system capacity is limited by storage size, not roof area.

2.4.3 Tank size

The tank capacity used in the model should be the active tank volume S (see Figure 2.1) and not the nominal tank volume. Any volume below the pipe from which yield (Y) is drawn is 'dead storage' (DS) as water stored in this part of the tank cannot be used. Where mains water is used to automatically top-up the tank to a specified water level, the tank volume below this level will also be effectively DS relative to rainwater, as discussed previously (Section 2.3.4). Furthermore, any volume above the overflow pipe will act as a temporary rain water storage buffer but that water will inevitably leave the tank as overflow (O) and hence cannot be used to meet demand (unless of course a demand event occurs before all water has drained away). The estimated yield from rainwater tanks of different sizes for a seasonal and non-seasonal demand (115 kL/year in total), as a function of roof area, is given in Figure 2.5 (a). The shape of the curve is very similar to the curve corresponding to the increase in roof area, with an increase in yield with tank

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size until a point is reached where the tank size becomes so large (about 2 to 4 kL) that it captures most of the inflow, apart from those very large events when overflow (Figure 2.5b) still occurs. At this point, increase in tank volume will lead to small increases in yield but probably large increases in cost. The overflow from the tank shows a different behaviour, with the overflow volume being inversely proportional to the tank size, as an increase in the volume leads to increased storage available, thus reducing overflow (Figure 2.5b).

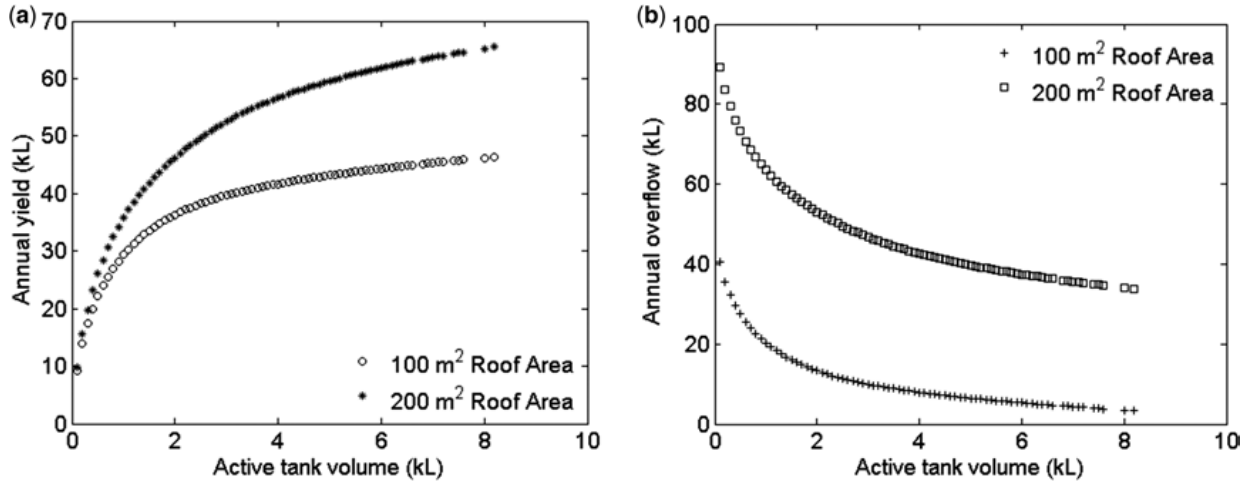


Figure 2.5 Annual yield (a) and overflow (b) for rainwater tanks of different sizes with two different connected roof areas (all other parameters using mean values in Table 2.1).

2.4.4 Demand

One of the most important variables influencing yield or overflow from rainwater tanks is the actual demand to be supplied by the rainwater tank. A large proportion of rainwater tank studies have used a constant demand, either yearly or daily (Fewkes, 2000; Fewkes & Butler, 2000; Liaw & Tsai, 2004; Ghisi *et al.* 2007; Jones & Hunt, 2010; Palla *et al.* 2011; Palla *et al.* 2012; Campisano *et al.* 2013). The impact of increasing demand for a tank with a certain volume and inflow can be seen in Figure 2.6, which shows clearly that, for a constant tank size, an increase in demand leads to an increase in the tank yield. In general, tanks with a high daily demand will result in higher yields compared to tanks with same size and inflow, but smaller daily demands.

Recent studies (Coombes & Barry, 2007; Neumann *et al.* 2011) demonstrate that if the demands have a seasonality component such as irrigation, the use of a constant demand will usually introduce errors in the estimation of yield. Coombes and Barry (2007) investigated the effect of seasonality on the supply yield of rainwater tanks supplying water to toilet (constant demand) and garden irrigation (seasonal demand) for eight Australian capital cities. For the same annual demand, the simulations ignoring the seasonal demand under estimated rainwater tank yields by up to 25%, with magnitude of under estimation becoming smaller as tank size increased.

The results of Figure 2.6 show a similar response to that of Coombes and Barry (2007) in that annual yield differences of up to 30% occur for the same value of annual demand. The same mean annual demand in Figure 2.6 has been modelled with different temporal patterns, achieved by randomly varying toilet and outdoor demand. The increase in annual yield occurs because demands for irrigation

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cause large draws on the tank for some days (irrigation days) and smaller demands on other days (toilet only). On days of increased demand, simulations with seasonality produce a larger drawdown in the rainwater tank, thereby increasing the capacity of the rainwater tank to capture water in the next rainfall event.

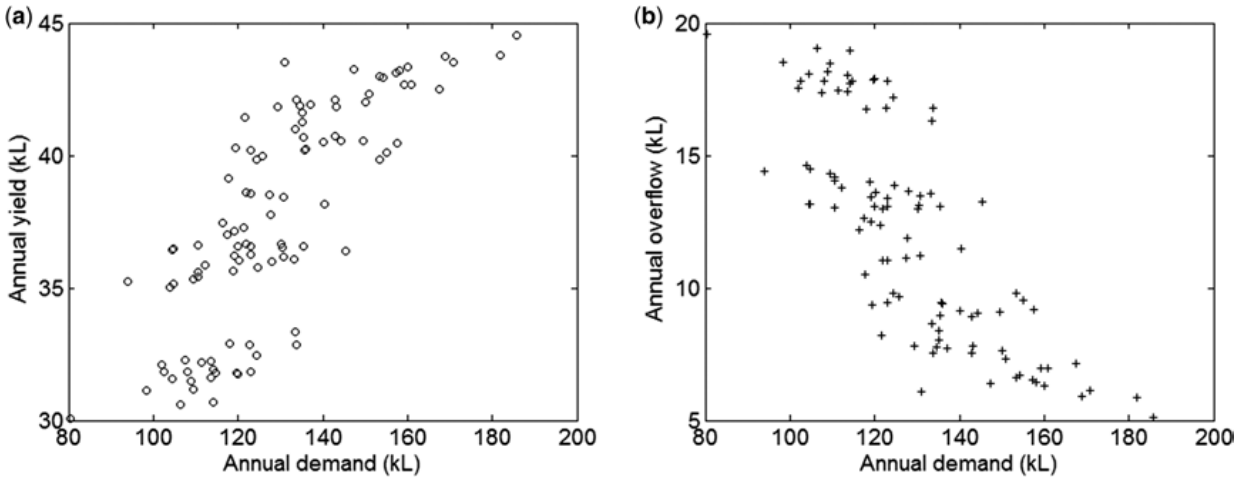


Figure 2.6 Annual yield (a) and overflow (b) for a 2.5 kL rainwater tank for different annual demands and different temporal demand patterns (all other parameters using mean values in Table 2.1).

Seasonality of demand is of particular importance for those studies which aim to determine 'optimal' tank size, or those which derive non-dimensional curves of performance based on mean annual demand and mean annual rainfall (Liaw & Tsai, 2004; Khastagir & Jayasuriya, 2010b; Palla *et al.* 2011; Palla *et al.* 2012; Campisano *et al.* 2013). Whilst the use of performance curves may be appropriate for constant or near constant demands, the variability in yield shown in Figure 2.6 for simulations with identical tank inflow and tank size suggests the approach must be used with care in cases where connected end uses show substantial seasonal variation.

2.4.5 Initial and continuing losses

Both initial loss and continuing loss will reduce the rainwater tank yield and overflow. Given the linear form described in Equations 2.1 to 2.3 for roof runoff and harvestable roof runoff, it is not surprising that for both types of losses the annual yield behaviour is closely linear, as shown in Figure 2.7 for the initial loss and in Figure 2.8 for the continuing loss. The effect of the initial loss parameter is basically to reduce the amount of rainfall for a given time-step to zero until the initial detention roof storage is full. It is important to note that the influence of the initial loss will vary depending on the distribution of rainfall. The more rainfall events there are per 100 mm of rain, the greater the effect of the initial loss.

A similar effect is observed in Figure 2.8 for the effect of continuing loss on tank yield and overflow. The continuing loss represents those losses associated with gutter overflowing, the effects of roof slope and orientation on splash losses, and evaporation during the storm event. The continuing loss coefficient is a more physically robust method to parameterise the runoff losses that are otherwise represented by a runoff coefficient in simpler models. Runoff coefficients used in daily time-step modelling typically range from 0.7–0.95 (Fewkes, 2000; Liaw & Tsai, 2004; Ghisi *et al.* 2007), with experimental measurements

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reporting values in the range 0.62 to 0.95 (Farreny *et al.* 2011). The equivalent runoff coefficients for the results modelled here (Figure 2.8) range between 0.63–0.89.

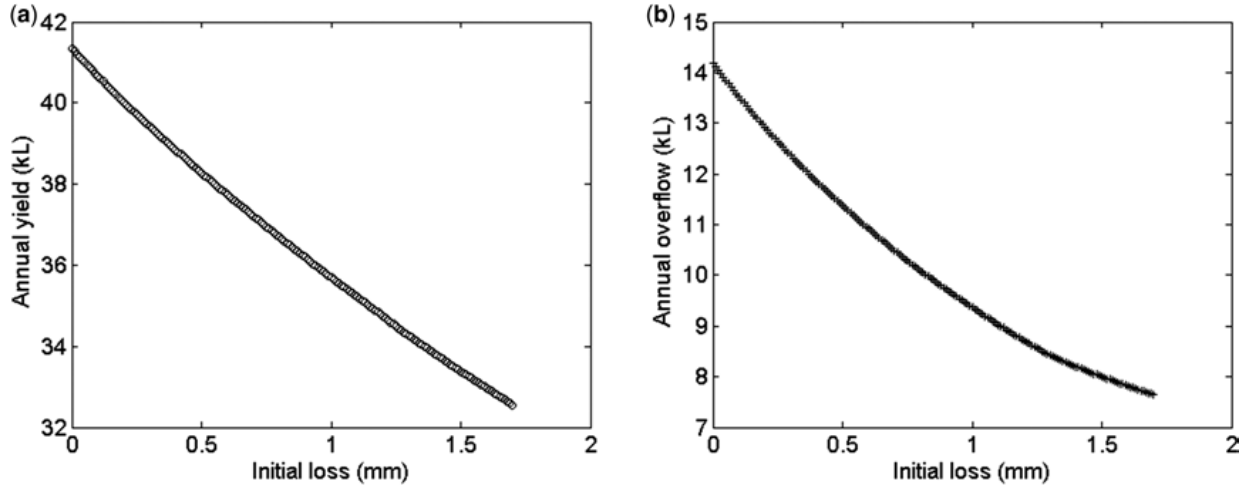


Figure 2.7 Annual yield (a) and overflow (b) for a 2.5 kL rainwater tank with different initial loss values (all other parameters using mean values in Table 2.1).

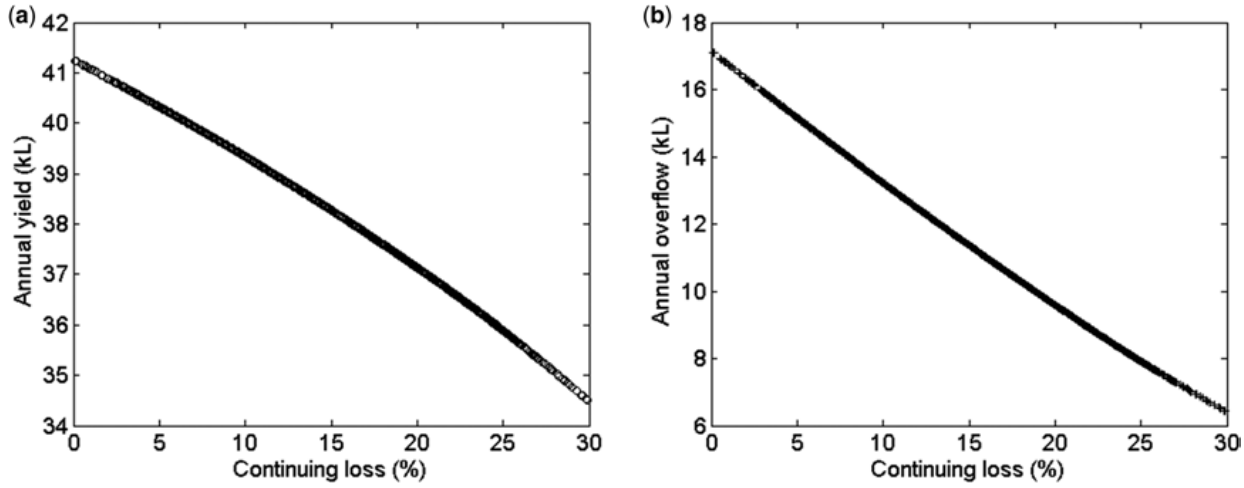


Figure 2.8 Annual yield (a) and overflow (b) for a rainwater tank for different continuing loss factors (all other parameters using mean values in Table 2.1).

2.4.6 Simulation length

To estimate volumetric reliability (percentage of demand met by the tank) of a rainwater tank system in locations with variable climates, rainfall records should be sufficiently long to capture the inter-annual and inter-decadal climate variability in the region of interest. This could mean using rainfall records of 50 years or greater. However, where computation times are an issue, use of a carefully selected portion of the rainfall record may produce acceptable results. Liaw and Tsai (2004) investigated impact of rainfall record length on the variation in the volumetric reliability for a series of rainwater tank simulations. Using one year records

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randomly taken from actual rainfall data, the volumetric reliability varied between 39 and 92%, with a mean of 66%. The variability depended on the mean rainfall for each rainfall year used for the simulation. As the rainfall record length (and hence simulation length) increased, the difference between the upper and lower bound of the variability estimates became smaller, reducing to less than 3% if the record length was 50 years. In a separate study, Mitchell (2007) investigated the differences in predicted yield using 1, 10 and 50-year rainfall periods in which all three periods had a similar mean annual rainfall. This study concluded that the use of 10-year periods which are representative of the long-term rainfall pattern produced small yield differences compared to those simulations using 50 years of rainfall. This difference was reduced even further if the rainwater storage was assumed to be empty at the beginning of the simulation.

However, in some cases, particularly in developing nations, the length of available historical rainfall records can be very short, and therefore, the length of simulations is limited by the length of available records rather than computational time. Approaches used to address this limitation have been briefly discussed in Section 2.3.1.

2.4.7 Validation

How accurate are the predictions from rainwater models? As described previously, the rainwater tank model is a water balance model with input parameters such as connected roof area and active tank volume that can be measured, household water demand that can be metered and rainfall and evaporation that can be measured at the site. Losses from the roof collection system need to be estimated based on results of studies measuring the runoff from various roof surfaces (see Section 2.3.3). To validate a rainwater tank model, observed (measured) rainwater use can be compared to predictions of rainwater use using measured input data. The measured data should also represent an independent dataset, that is, data that was not used in the development of the model. To provide a good test of model predictions, the data set should be long enough to capture the natural long-term variability of the rainfall pattern.

Millar *et al.* (2003) conducted an eight-month rain catch study in coastal South East Queensland on a house with three separate roof areas, each with a first flush device, connected to a rainwater tank with mains trickle top-up. Rain water inflow into the tank was firstly calculated from the monthly water balance of measured council mains inflow, measured tank water use by the household and the measured change in tank water level (and hence storage volume). Rainfall measured at roof level, combined with the sum of the projected roof areas, was used to calculate potential roof runoff so that rain catch efficiency could be calculated. These mass balance sums were complemented with a 10 minute time-step model of the loss of rainwater by retention from the leaky first flush devices, which in turn provided a prediction of rain water inflow into the tank, and hence allowed calculation of rain catch efficiency. An independently derived empirical relationship was used to describe the leakage rate from the first flush devices as a function of water volume (L) stored in their chambers. The predicted rain water inflow (catch efficiency 61%) agreed closely with the measured monthly rain water inflow (catch efficiency 58%), with a <3% error which could be reasonably attributed to initial and continuing loss not being taken into account in the water balance model. This provided confidence in the rain water inflow modelling, but the study did not extend to modelling tank yield behaviour.

Ward *et al.* (2012) compared the actual rainwater yield for a 300 person capacity building with the rainwater tanks plumbed to toilets against the yield predicted using a continuous simulation model developed by Roebuck and Ashley (2007). The model predicted that 46% of the water demand would be met by rainwater, whilst measured data indicated an average 35% of demand was met. The analysis demonstrated the sensitivity of the results to differences in building occupancy between that assumed in the design (300) and the actual occupancy (111).

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South East Queensland became the subject of a number of house water use studies as a consequence of a severe drought (2006–2009) which led to rainwater tanks being mandated for new homes. Early modelling using the Coombes and Kuczera (2001) model with a pre-drought average water demand of 925 L/household/day (486 internal + 439 external) suggested that 70 kL/household/year of mains water could be saved by using rainwater from a 5 kL rainwater tank connected to 100 m^2 roof area of a house in Brisbane and plumbed to supply toilet, laundry and external demand (Le Muth, 2006). This value became established as the water savings target for South East Queensland (Department of Local Government & Planning, 2008).

The reasonableness of this target was assessed by undertaking a pairwise comparison of water utility household billing data for the year 2008 for 1100 homes with internally plumbed rainwater tanks and houses without rainwater tanks. The 1100 data pairs were distributed over three local government areas (LGA) in South East Queensland (Beal *et al.* 2012). In the absence of household occupancy data, household pairing was done on the basis of lot size and suburb information. The calculated mains water savings across the three LGA ranged from 20 to 95 kL/household/yr with an average of 50 kL/household/yr. Continuous simulation of average tank performance was undertaken using the model by Vieritz *et al.* (2007a,b) with an internal demand of 406 to 448 L/household/day assuming 30% was used for toilet and laundry (Willis *et al.* 2011) and rainfall data representative of each LGA. The predicted mains water saving ranged from 46 to 54 kL/household/yr with an average predicted value of 50 kL/household/year, which was well below the target of 70 kL/household/yr; but in good agreement with the 'estimated' average value. However, the large range in mains water savings calculated by the pairwise comparison (20 to 95 kL/hh/yr) was not reflected in the modelled water savings estimates across the LGA. This was attributed to: significant external water use in those LGA with less severe water restrictions (leading to higher tank water supply); variable penetration of water efficient appliances; and the lack of household occupancy data when matching data pairs (tank/no tank). In addition, there is some doubt that modelling an average tank to represent community water savings is a valid methodology. This issue will be addressed in the section 2.5.

A more detailed benchmark analysis of household billing data from 691 households with internally plumbed rainwater tanks was conducted by Chong *et al.* (2011) for four LGA in South East Queensland (including the three described in the Beal *et al.* 2012 study). The analysis compared average mains water usage by the known mandated rainwater users group to the respective council's average mains water consumption. The mains water billing records were supplemented with demographic survey data so that mains water usage could be normalised to household occupancy. This allowed calculation of water use per person for comparison with average mains water consumption per person for each LGA. The study found that the average annual mains water savings per household in 2009 was 59 kL/household/yr (ranging 24 to 89 across the region), and 58 kL/household/yr in 2010 (ranging from 40 to 81 across the region).

Twenty homes were then selected to represent the demographics within the South East Queensland study area (Chong *et al.* 2012). An audit of these homes established that only 45% had active tank volume ≥5 kL, and 15% had a connected roof area greater than the mandated 100 m^2. Modelling 18 of these homes using actual water use data for 2009, active tank volume and connected roof area indicated potential mains water savings ranging from 26 to 71 kL/household/yr (average 49) when using the model by Vieritz *et al.* (2007a,b), and 21 to 64 kL/household/yr (average 41) when using the UVQ model (Mitchell & Diaper, 2006). These values are 15%–30% lower than the 59 kL/household/yr calculated using 2009 billing data from 691 households (Chong *et al.* 2011). Further details regarding this auditing study are presented in Chapter 5.

The same twenty homes were intensively monitored over a 12-month period commencing in April 2011 (Umapathi *et al.* 2013). Rainwater use, main water top-up and total mains water use, as well as external

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water use was monitored. After infilling of missing data periods, projected mains water saving was found to be 40 kL/household/yr. However, this measured value can only be compared with the modelled averages of 41 to 49 using the earlier (2009) data from the Chong *et al.* (2012) study. Application of this 2011 data set to validate rainwater tank models was also constrained because on-site rainfall was not measured.

The above indicates that mains water savings from rainwater tanks have been shown to average 40 to 60 kL/household/yr for South East Queensland by modelling, while measurement results provided 40 kL/household/yr of mains water savings based on monitoring of only 20 homes. However, none of these studies provide data to allow a clear comparison of model predictions with their respective observed values to allow validation of the models.

Overall, it would be fair to say that there is comparatively little validation work relative to the number of models developed. Ward *et al.* (2012) noted the lack of longitudinal empirical studies that can be used to compare actual mains water savings from rainwater systems against modelled estimates. Umapathi *et al.* (2013) made a similar observation for South East Queensland.

Rainwater tank modelling is conceptually simple compared to the modelling of the water balance of paddocks. However, the cost and effort required to instrument and monitor occupied-household rainwater tanks have contributed to the lack of validation studies. One possible source of data for validating rainwater tank models may be the urban metabolism studies where water and energy flows are quantified (e.g., Beal *et al.* 2008). However, due to the logistical constraints, it is unlikely that data sets would be longer than a couple of years. Nevertheless, the expectation is that rainwater models validated with short-term data sets should be valid for the longer term, provided that important input values such as connected roof area and active tank volume do not change over that simulation period (e.g., tank and roof collection system is well maintained) and household demand is stationary. It would appear that rainwater modelling has far outpaced the studies which attempt to validate the predictions, and this represents a serious information gap.

2.5 UPSCALING OF RAINWATER TANK BEHAVIOUR TO MULTIPLE TANKS

A common method of analysing the behaviour of *multiple* rainwater tanks is a simple scaling up of the results from the continuous simulation of a *single* rainwater tank system. Therefore, for a cluster of rainwater tanks (i.e., a cluster of domestic rainwater tanks spread across a suburb or local government area), this approach uses a linear extrapolation based on the simulation of a single tank with average roof area, tank size, losses and water demand characteristics. This approach implies that the performance of all tanks is the same, or at least that the tank yield and overflow have a linear relationship to the tank parameters. Based on the yield curves versus roof area or tank volume shown in Figure 2.4 and Figure 2.5 respectively, it is clear that the assumption of a linear relationship is only valid for very narrow intervals of tank size or roof areas. It is important to note that the behaviour of the volumetric reliability (and annual overflow) is not entirely linear in relation to either tank sizes or roof area, as shown by Figure 2.9. The point where the system becomes linear depends on both the roof area and tank volume, and hence, even for a system where only those two parameters change, the system may not be linear, and hence linear up-scaling is likely to result in errors.

Rainwater tank audits in South East Queensland have demonstrated that water use demand, associated rainwater tank sizes and associated roof areas varied across the region. The variability in tank sizes and roof areas occurred despite the existence (at the time of the study) of mandatory tank sizes and connected roof areas (Biermann *et al.* 2012). For the same region, Beal *et al.* (2011) and Willis *et al.* (2009) also demonstrated that water demand varied between households due to occupancy rate, appliances used, and behaviour and attitudes of the residents to water use.

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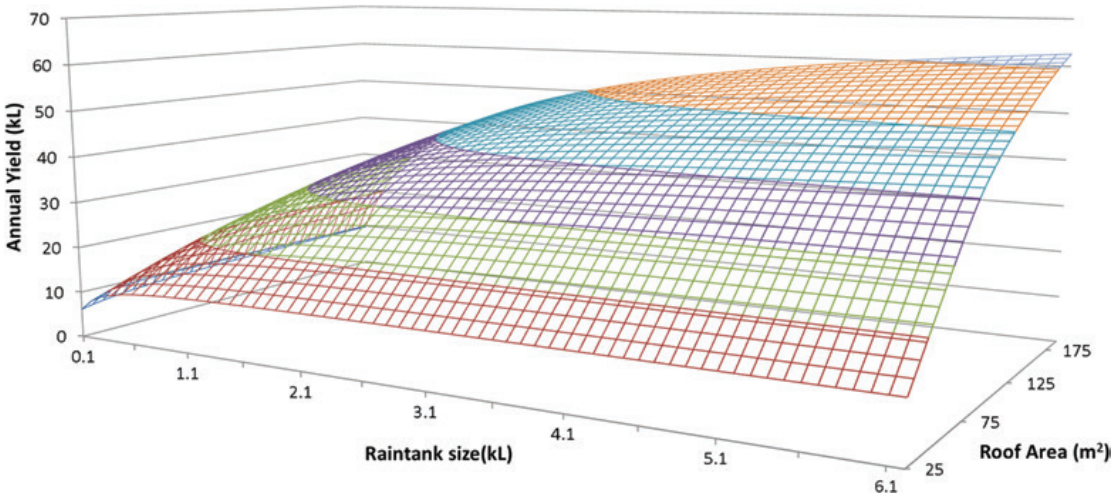


Figure 2.9 Predicted annual rainwater yield in Melbourne as a function of tank size and connected roof area for an annual demand of 115 kL/year for toilet and garden use.

The magnitude of this under and overestimation error by lumping the spatial variability under an 'average tank' was initially investigated by Mitchell *et al.* (2008). In that study, they modelled 1000 hypothetical households in Melbourne with stochastically allocated roof areas, tank sizes, roof losses (the same parameters listed in Table 2.1) to estimate the performance of a cluster of tanks. This performance was then compared to the performance of an 'average' tank system in which the roof area, tank size, demand, initial and continuing losses were the averages of the parameter values used in the 1000-house cluster. The difference in yield between the 1000 household cluster and the scaled up average tank was 14%, with the average tank method over estimating yield due to the non-linear behaviour described in Figure 2.4, Figure 2.5 and Figure 2.9. Other authors reported similar results for 5 locations in South East Queensland with different tank size, demands and climate patterns (Coultas *et al.* 2011; Maheepala *et al.* 2013). Errors varied between 10% (Gold Coast) to 22% (Ipswich), with a mean overestimation error of 15% for the five locations considered in the study. As can be seen in Figure 2.10, the simulated yields for individual household tanks show a substantial spread (from 10 to 100 kL/hh/yr), reflecting the variation in tank system characteristics and water end uses, both of which were informed by extensive inspection and survey data. For more details on input parameter values, see Chapter 5.

In addition to errors in yield estimation, Neumann *et al.* (2011) also investigated the impact of upscaling 'average tank' behaviour on overflow estimation. Given that use of average tank data *overestimates* the yield (i.e., it captures more rainfall), the authors found, as expected, that the use of average tanks *underestimated* the volume of overflow from the cluster. The difference was in the order of –37%.

Based on the non-linearity in yield with variation in roof areas and tank sizes, Neumann *et al.* (2011) suggested the use of geometric means instead of arithmetic means to represent the cluster. For the case where only roof area was varied, the use of geometric means greatly improved the estimation of yield. However when all the variables were considered, the use of geometric means resulted in even larger overestimations of yield. As such, the authors concluded that the use of 'average tank' to estimate yield and overflow is not recommended. Instead, modelling all tanks using stochastic simulation, or at least a few configurations of area/volume/demand so as to consider variability, is recommended to reduce the error in yield estimation.

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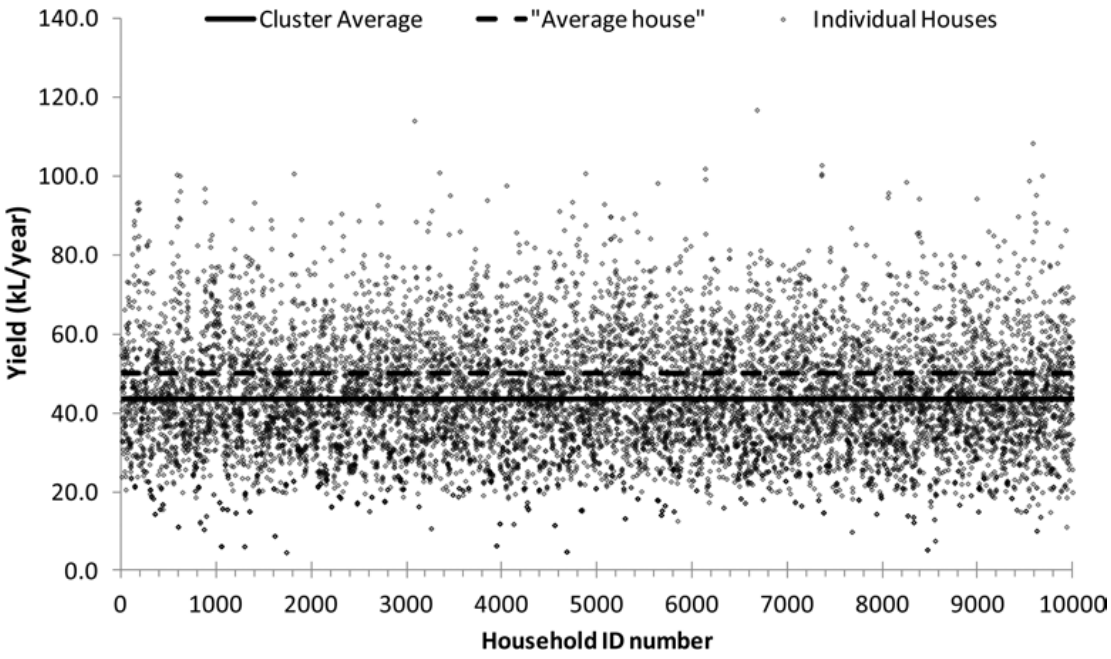


Figure 2.10 Annual tank yield for 10,000 individual South East Queensland households with various demands, connected roof areas and tank sizes. The mean yield for all tanks (cluster average) is shown as well as the average calculated from scaling up the 'average house' behavior (Maheepala *et al.* 2013).

2.6 CONCLUSIONS

The results presented in this chapter show that there are several models available for the simulation of yield and overflow from rainwater tanks. The existing models vary from simple spreadsheet models to very detailed process models which include hydraulic calculations, using time-steps from 6 minutes up to monthly. The most common modelling approach is the use of continuous simulations of the rainwater tank system over a significant period of time to minimize errors due to initial conditions, and to ensure a representation of the relevant rainfall patterns. Most, if not all, models include roof area, tank size, demand and losses as input variables that need to be considered in the model setup. In general, most models, irrespective of their level of complexity, exhibit similar patterns of yield and overflow in relation to the tank variables. Therefore, the most important consideration in modelling rainwater tanks is to ensure that the chosen model is appropriate for the scenario to be modelled so that all of the important processes of the system under study are captured, and that the assumptions behind the model are well understood. This is particularly important if the model used is a simplification based on non-dimensional parameters which are highly sensitive to demand pattern and rainfall distribution.

For the majority of practical applications in which a tank of reasonable size ($S > 1$ kL) has a connected roof area that provides a mean annual inflow (I in kL) such that the dimensionless ratio $S/I > 0.01$, daily time-step models provide sufficient accuracy, irrespective of the order of calculation spill rules, that is, YAS or YBS. If small tank sizes or very large roof areas are considered such that $S/I < 0.01$, shorter time-steps may be needed to avoid under or over estimation of yield, particularly if the model uses the YBS rule. The small time-step models, though more realistic in representing the physical processes, are more complex and more demanding of parameter values and rainfall data. However, they are the more

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appropriate models to use when the hydraulics of rainwater discharge (i.e., L/minute) are used in sizing the stormwater system.

Whilst input parameters for a rainwater model such as roof area and active tank volume can be directly *measured*, losses from the roof collection system, household water demand, and perhaps rainfall may need to be *estimated*. Adequate estimations of longer-term yield from rainwater tanks rely on rainfall records that are representative of the area of interest, and that ideally represent the long term average while preserving some of the long term variability. As discussed, local rainfall records are preferred as rainfall can vary significantly within short distances inside a catchment, while inherent rainfall measurement errors will also be a source of model error. Even if error-free rainfall data were available, different roof slopes and configurations influence the capture efficiency, and such losses have to be estimated. Careful consideration should also be given to the values used to represent the household water demand. The use of an annual or constant value can lead to underestimation of the tank yield if the demand has a seasonal component due to irrigation or other time varying demands. As water withdrawn from the tank effectively increases the available volume for water capture in the next rainfall event, increases in demand will lead to increases in yield (roof area permitting). Therefore, adequate representation of demand is important for the correct estimation of yield.

Since rainwater tank models are most useful to water planners when estimating potable water savings at a suburban scale or greater, quantifying the variability of the input parameters is also important, as variability in roof areas, demands and tank sizes can lead to significant variability in actual average yield. For large scale estimation involving several thousand households, the use of average parameters must be avoided as the non-linearity in yield response means the use of averaged parameters is likely to overestimate yields.

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Chapter 3

Quantifying mains water savings from residential rainwater tanks

Cara D. Beal, Meng Nan Chong, Julian Fyfe, Andrea Turner and Ted Gardner

ABSTRACT

The premise for mandating rainwater tanks, or implementing expensive financial incentive programs such as rebates for the installation of tanks, is that meaningful savings can be achieved from the potable water supply. Whilst there is a depth of literature on modelled and theoretical savings from rainwater tanks, there are scant studies that seek to quantify the savings from multiple household 'real life' examples. The primary objective of this chapter is to present three different methods for assessing the savings in mains water use from regions of Australia that have recently installed rainwater tanks. We believe all three methods are internationally applicable. Various 'before' and 'after' comparisons are presented of mains water demand resulting from either rebated or mandated rainwater tank installations. Case Study 1 is a desktop assessment that uses water utility water billing data, lot sizes and presence or absence of an internally plumbed rainwater tank (RWT) to make pair-wise statistical inferences on the range of savings from internally plumbed tanks at a scale of local authority areas. Building on Case Study 1, Case Study 2 applies known household socio-demographic data matched with their household billing data to determine a benchmark water savings. Case Study 3 focuses on the water savings derived from a city-wide rainwater tank rebate program by comparing water consumption of each individual rebated household with a statistically-matched non-rebated household. Conclusions from all the studies focus on the need for sufficiently large sample sizes, known household occupancy, and the penetration of water-efficient appliances in households. Comparison of savings estimates highlighted the variability of rain tank yields between regions associated with climate, tank sizes and functionality, and connected end uses and roof area. Outdoor consumption is a critical end-use that will maximise savings. Thus factors such as potable water restrictions, lot size and behavioural cues (willingness to water use) are also important in determining water savings.

Keywords: modelling; harvesting; demand management; rainwater yield; tank rebates.

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3.1 INTRODUCTION

3.1.1 Why quantify mains water savings?

As described in earlier chapters, the challenges in providing adequate and reliable sources of water for the urban community across the globe have been elevated due to potential climate change impacts and population growth. Various water strategies have been proposed to offset the demand from traditional potable water supplies, and one of the approaches for urban communities is the use of rainwater tanks. Rainwater tanks have enjoyed a recent resurgence in popularity due to widespread drought conditions and resultant water demand management schemes across many parts of Australia. In some Australian jurisdictions, rainwater tanks are mandated through building codes, requiring them to be installed in new developments or new buildings. The premise for mandating rainwater tanks, particularly those that supply internal household end-uses such as washing machines and toilets as well as external end-uses such as garden irrigation, is that significant volumetric savings of potable water can be achieved. These tanks will be referred as 'mandated rainwater tanks' in this chapter. The driving objective of installing a rainwater tank is essentially to reduce mains water demand through the on-site harvesting (collection, storage and use) of rainwater. In general, the underlying assumption that rainwater yield will adequately supplement household demand has yet to be convincingly demonstrated across a variety of rainwater tank configurations and regional settings. Additionally, yield (kL/household/year) will vary both spatially and temporally across a given region. Thus, the actual harvesting behaviour of rainwater tanks – internally and/or externally connected – is critical in terms of setting realistic and achievable water demand management goals.

As well as mandated rainwater tanks, many states in Australia have introduced rebate programs whereby residents are offered a financial incentive to voluntarily install a rainwater tank for internal (washing machine and or toilets) and/or external garden supply. The amount of rebate is linked to the overall internal and external end-uses. These 'rebated rainwater tanks' as they will be referred to in this chapter, have been very popular across Australia. However the success of these rebate schemes, and the justification for future similar programs, needs to be examined objectively.

Accurate data on the actual *mains water savings* from rainwater tanks is critical for assessing the range of urban water management strategies, along with improving the accuracy of demand (and revenue) forecasting models for future infrastructure planning and optimisation. This chapter addresses many of these questions by presenting three case studies which explore various approaches in determining mains water savings from residential water tanks used for either internal and/or external end-uses.

3.1.2 Previous studies on mains water savings

There are numerous studies that report predicted yields and optimal design criteria (e.g., tank size, roof catchment) for rainwater tank systems, based on water balance simulations and probabilistic methods (Campisano & Modica, 2012). Ideally however, a combination of field and desktop methods using smart metering, historical water billing records, long-term climate data, household demographics, household water end-use surveys and rainwater tank system audits, would capture of all the variables that determine rainwater yield and potable water savings. Such a holistic study would also include the energy demand associated with rainwater tanks (Siems *et al.* 2013). This level of detailed data is rarely available, thus a mixed method approach is often adopted whereby both empirical and modelled data are used to determine potable water savings. Some examples include Chong *et al.* (2012), Fyfe *et al.* (2011) and Sydney Water (2008). Others have used statistical methods with 'before and after' retrofit comparisons to identify mains water savings (e.g., Beal *et al.* 2011a; McBeth, 2011; Ghisi *et al.* 2007a; Turner *et al.* 2005). A summary of selected studies is presented in Table 3.1.

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Table 3.1 Summary of some previous studies on mains water savings from rainwater tanks.

Location	Approach	Reported savings (kL/ household /year)	Comments	Reference
Various capital cities across Australia	PURRS model (Probabilistic Urban Rainwater and wastewater Reuse Simulator model)	42–90 kL	Modelling assumed rainwater was used for hot water, toilet, laundry and outdoor end-uses.	Coombes and Kuczera (2003)
Various capital cities across Australia	Water balance model	42 kL (externally plumbed only) 71 kL (internal and external)	Supply scenarios modelled included all internal end-uses (excluding cold water to kitchen and bathroom) or external only.	Marsden Jacob Associates (2007)
Sydney, Australia	Comparison between BASIX (homes that have undergone a water efficiency retrofit program) and Non-BASIX homes.	Approx. 36 kL	Volumetric savings estimated. No 'before' dataset to compare with.	Sydney Water (2008); Sullivan and Wilson (2009).
Sydney, Newcastle, Wollongong, Australia	Estimated savings from end-uses connected to rain tanks. Continuous simulation water balance model.	21–57 kL depending on tank size and location.	The end-use rates (L/p/d) were based on Sydney Water's recommended demand rates, not measured datasets.	Eroksuz and Rahman (2010)
Northern NSW, Australia	Similar to BASIX approach. Statistical analysis.	27 kL	Rebated tanks were examined.	McBeth (2011)
Sydney, Australia	Simulation modelling.	45–58 kL (irrigation use) 27–34 kL (internal and outdoor)	Assumed water-efficient appliances and fixtures. Assumed a 5 kL tank size.	Hajani and Rahman (2013)
South east Brazil	Desktop assessment using demand data and population statistics.	16–175 kL	Volumetric savings estimated from % savings, water demand and average household occupancy.	Ghisi *et al.* (2007)

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3.1.3 Chapter objectives and scope

The primary objective of this chapter is to present three different, internationally-applicable methods for assessing the savings in mains water use from rainwater tanks. The case studies selected describe both theoretical modelling approaches and empirical data from in-situ measurements. They examine both mandated tanks and rebated tanks. The methodologies presented in this chapter have been chosen based on their global relevance, and thus can be applied in any part of the world where rainwater tanks are used as part of integrated urban water management to reduce reliance on mains water supply.

The different circumstances under which residential rainwater tanks are typically installed are presented in Figure 3.1. Case Studies 1 and 2 are concerned with water savings from mandated tanks, whilst Case Study 3 examines savings from tanks installed voluntarily by the householder under government rebate schemes. The methodology for each case study is discussed in detail with only a summary of results and discussion as it is the approach used, rather than the specific quantum of savings from RWTs, that is the focus of this chapter. The extended data on mains water savings and rainwater tank yields for various locations around the world can be accessed in various publications (e.g., Adeyeye, 2014; Ghisi *et al.* 2007).

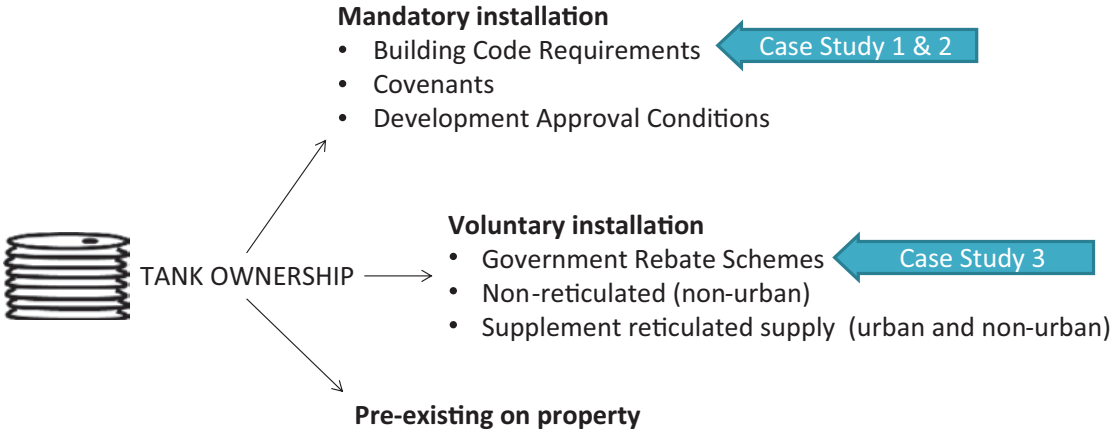


Figure 3.1 Categories of tank installation examined in the three case studies.

3.2 CASE STUDY 1 – DESKTOP ANALYSIS OF MAINS WATER SAVINGS

3.2.1 Background

In south-east Queensland (SEQ), Australia, the challenges in providing adequate and reliable sources of water for the urban community has prompted state water planning authorities to develop sustainable water planning strategies and management practices to address such important urban water issues. Different water strategies have been proposed, and one of the approaches for urban communities in SEQ is the installation of rainwater tanks. These have become an integral feature of the vast majority of detached dwellings in SEQ, either through the WaterWise Rebate Scheme commenced in 2006 (Walton & Homes, 2009) or mandated through the Queensland Development Code (QDC) MP 4.2 – *Water savings targets* (DIP, 2007). Although the requirement to achieve a mains water saving target of 70 kL per year (usually via

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a rainwater tank) has now been removed (as of 1st February 2013) from Queensland legislation following a change of government, there was considerable research effort directed at developing methods to assess the actual mains water savings from rainwater tanks. This knowledge provides methodologies that allow similar mandated programs on rainwater tank to be assessed by scientifically rigorous analysis of data in other regions of the world.

Mandated rainwater tanks (MRT) clearly played an important role in achieving the sustained reduction in demand, although quantifying this was not a simple task due to an absence in actual consumption data from newly constructed homes. In addition, there was difficulty in separating out the role that other water demand management strategies contributed to demand reduction. Case Study 1 presents the first of a staged methodological approach to investigate the mains water savings that can be achieved from mandated rainwater tanks. The second staged methodology to investigate mains water savings is discussed in Case Study 2.

3.2.1.1 Research objectives and hypothesis

The aim of the research was to conduct a desktop assessment using statistical analysis of the potential mains water reductions from internally plumbed rainwater tanks in new developments in the SEQ, Australia. A further objective of this desktop approach was to provide baseline data for further experimental work. The following hypotheses were used to frame the research methods:

- *Null hypothesis* (H_o)*:* Water consumption in houses with mandated rainwater tanks (MRT) is not significantly different from the water consumption for houses without rainwater tanks (No Tank).
- *Alternative hypothesis* (H_1)*:* Water consumption in houses with mandated rainwater tanks is significantly different from the water consumption for houses without rainwater tanks (No Tank).

3.2.2 Methods

3.2.2.1 Site locations and data collection

Three SEQ local government areas (LGAs) were included in this study: Pine Rivers City Council (now amalgamated into Moreton Bay Regional Council), Gold Coast City Council and Redland City Council (Figure 3.2). These local government areas were chosen as they represented a good cross-section of the socio-economic and climatic conditions in SEQ. At the last available Australia Bureau of Statistics (ABS) census in 2006, these regions collectively comprised almost 40% of the SEQ population (DIP, 2009). Further, they represented around a third of the areas marked for future greenfield development in the SEQ Regional Plan (DIP, 2009). From the council databases provided, approximately 8300 (Pine Rivers), 9100 (Gold Coast) and 1000 (Redland) new dwellings were selected, which had been approved (but not necessarily constructed) since January 1st 2007 when the QDC MP 4.2 requirements became active.

Potable water consumption data for 2008 was obtained from the water billing section of each council. Some councils had difficulties in providing complete datasets of water billings for post-2007 approved dwellings. Once the data was collected from the councils, the method described in 3.2.2.2 was applied to isolate post-2007 constructed properties with mandated rainwater tanks.

The rainfall data for Case Study 1 and 2 (both yearly and long-term) is presented in Table 3.2. For Case Study 1, the year 2008 is of interest for the regions of Pine Rivers, Gold Coast and Redlands.

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Figure 3.2 Location of the local government areas in SEQ used for desktop study (http://en.wikipedia.org/wiki/South_East_Queensland).

Table 3.2 Rainfall data for the studies regions examined in Case Studies 1 and 2.

Region[1]	Annual rainfall in 2008 (mm)	Annual rainfall in 2009 (mm)	Annual rainfall in 2010 (mm)	Long-term annual rainfall (mm)
Pine Rivers	1201	1367	1996	1131
Gold Coast	1766	1548	2320	1372
Redland	1348	1213	1834	1192
Caboolture	1525	1971	2118	1219

[1]data taken from Bureau of Meteorology weather stations available from Climate Data Online (http://www.bom.gov.au/climate/data/).

3.2.2.2 *Identification of sample cohorts*

In Case Study 1, properties approved and constructed post-2007 were not able to be directly identified in the raw datasets provided. Therefore a methodology was developed to extract the relevant information from typically available household databases. The main steps and assumptions in the analysis are listed below.

(1) The raw data set was filtered for duplicate and ambiguous data (e.g., incomplete, repeated records) using MS Access™ and MS Excel™ software. This data set was then filtered for the Land Use Code representing a Class 1 building as per the Queensland Development Code mandate requirements.

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Only single, detached dwellings were selected, which represent up to 60% of SEQ regional water consumption (MWH, 2007).

(2) No Tank and MRT properties were isolated by using property registration (i.e., cadastral data), meter installation and connection dates where available. In the case of Gold Coast Water, the data was supplied in predefined No Tank and MRT samples.

(3) All properties that were identified as having received a rainwater tank state government rebate were excluded. Some councils also had a field that indicated a local council rebated water tank (e.g., Gold Coast). Excluding rebated properties could only be performed where Lot and Plan data (a unique cadastral identifier for the house allotment) was supplied by council. By excluding rebated tank properties, the differences in water use between No Tank and MRT houses were likely to be maximised. Excluding rebated properties could only be performed for Pine Rivers ($n = 12{,}342$ rebated properties) and Redlands ($n = 4994$ rebated properties) where Lot and Plan data was supplied by council. MRT and No Tank data were divided into two lot size categories: ≤700 m^2 and >700 m^2 by filtering for lot size. The value of 700 m^2 represented the median (50th percentile) allotment size identified after developing a probability distribution curve for all councils. Water consumption between No Tank and MRT homes was analysed for the two lot size categories, where sample size allowed this. There was a trend for larger allotments to use more water, but as only limited statistically significant results occurred between regions, this data is neither presented nor discussed further in this chapter.

(4) No Tank and MRT properties were further grouped into suburbs within each lot size category. However, sample size was generally insufficient for a suburb grouping.

Only consumption data recorded in the 2008 calendar year was used for comparative analysis. This method reduced the likelihood of selecting new developments that were constructed after January 1st 2007 and were yet to be fully occupied, or developments that were approved *before* January 1 2007 but *constructed after* 2007. Billing data provided for all regions included information on the date of water meter installation and/or the date of house construction. This information was useful when differentiating between properties which were constructed pre- and post-2007. Unlike previous studies such as Turner *et al.* (2005) and the Sydney Water BASIX study (Sydney Water, 2008), a comparison of identified properties using known household occupancy data was not possible for this analysis. The final number of samples for the MRT and No Tank groups are shown in Table 3.3.

Table 3.3 Number of MRT and No Tank properties for each region of interest for pairing.

Region	MRT homes	No Tank homes
	(number of samples)	
Pine Rivers	648	32,718
Gold Coast	422	2993
Redland	112	33,117
Total	**1182**	**68,828**

3.2.2.3 Statistical analysis

Mean values were used to statistically compare water consumption for this desktop study using a two-tailed, independent Student's *t* Tests in MS Excel™ and SPSS© software packages. Although the distribution curves were skewed slightly to the right, the *t*-Test is more robust than other tests (e.g., *z* Test) to deviations from normality (Johnson, 1978). With the exception of comparing combined totals for water use, the

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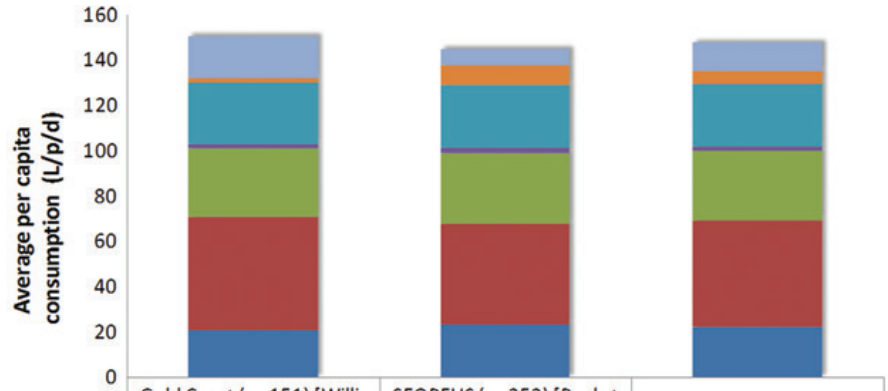
t-Test was based on equal variance and equal samples between the No Tank and MRT properties. Further statistical descriptions can be found in Beal *et al.* (2011a).

3.2.2.4 Overcoming limitations with data availability

3.2.2.4.1 Bottom-up end use calculations

The examination of savings from mandated rainwater tanks is not an easy task, particularly given the paucity (or inaccessibility) of specific council data required for a pairwise analysis. Therefore, two other approaches have also been used to assist in evaluating and providing a 'ball park' reality check on the results of the desktop analysis. These 'cross-checks' help to set the bounds of likely potable water savings for the different end use assumptions (e.g., with and without garden irrigation).

An estimation of expected mains reductions from internally plumbed rainwater tanks was made based on internal water use data from the Gold Coast end use study in the Pimpama-Coomera region (Willis *et al.* 2010) and from a recent SEQ end use study (Beal & Stewart, 2011). These studies reported a range of consumption data for various internal fixtures including the washing machine (cold water tap) and toilet. The combined water demand from these internally connected end uses provide a baseline estimation of indoor mains water savings from a MRT (Figure 3.3). Note that whilst the statistical analysis assumes a contribution from outdoor water use, the two cross-checking approaches only consider indoor end uses. Predicting outdoor end uses with any degree of accuracy is extremely difficult due to the number of factors influencing its use (e.g., climate, lot size, garden area, turf area, soil type, personal behaviour and council water restrictions). Indoor water consumption is considered a far more homogenous dataset that has less variability and is therefore easier to predict (Makki *et al.* 2011; Fox *et al.* 2009). End use studies by Willis *et al.* (2011) and Beal and Stewart (2011) suggest external water use was atypically low during the period of our tank studies (2008–9).



	Gold Coast (n=151) [Willis et al. 2009]	SEQREUS (n=252) [Beal et al. 2011]	Average
External	18.6	7.0	12.8
Leaks	2.1	9.0	5.6
Taps	27	27.5	27.3
Dish washer	2.2	2.5	2.4
Clothes washer	30	31.0	30.5
Shower / bath	50	44.5	47.3
Toilet	21	23.7	22.4

Figure 3.3 Summary of measured internal water end uses from a number of recent SEQ end use studies.

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3.2.2.4.2 Rainwater tank modelling

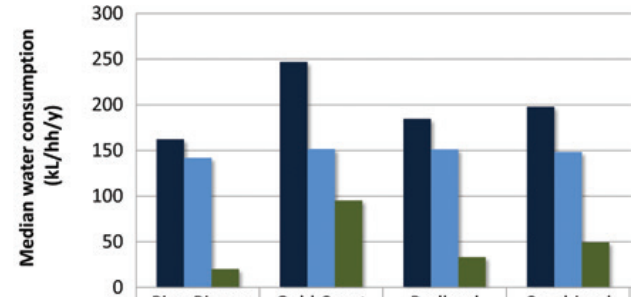
The Rainwater TANK model is an Excel-based spreadsheet model linked to a FORTRAN executable file (Vieritz *et al.* 2007). Rainwater TANK simulates the capture of rain by an urban roof. The primary aim of the model is to assess the ability of the rainwater tank to meet the water demand of connected end uses. For the purposes of this study, TANK provided a first approximation of the supply performance of rainwater tanks for comparison with the statistical desktop results. Rainfall years that were used in the modelling are provided in Table 3.4.

Table 3.4 Rainfall input data used for rainwater TANK modelling.

Region	Rainfall scenario	Yearly Rain (mm)
Pine Rivers	Dry (2006–7)	850
	Av (28 yrs)	1131
	Wet (2008)	1201
Gold Coast	Dry (2006–7)	1193
	Av (28 yrs)	1372
	Wet (2008)	1766
Redland	Dry (2006–7)	956
	Av (28 yrs)	1192
	Wet (2008)	1348

3.2.3 Results

There was a significant reduction ($p < 0.05$) in mains water consumption for MRT properties in all regions (Figure 3.4). Mains water consumption for No Tank homes averaged 197.8 kL/household/year compared with an average of 148.3 kL/household/year for MRT homes. Within regions, this trend continued with Gold Coast and Redland No Tank homes consuming the most mains water at an average of 246.9 and 184.5 kL/household/year, respectively. These two council areas were operating under relaxed outdoor watering restrictions in 2008. Mains water savings varied markedly across regions, with values ranging from 20 to 95 kL/household/year, with an average of 50 kL/household/year (Figure 3.4).



	Pine Rivers	Gold Coast	Redland	Combined
No Tank	162.0	246.9	184.5	197.8
MRT	142.0	151.7	151.4	148.3
Mains water reductions	20.0	95.2	33.2	49.5

Figure 3.4 Results from pairwise statistical analysis of water consumption from MRT and No Tank properties.

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The result of the two approaches used to cross-check the statistical analyses are presented in Table 3.5. Both of these approaches only consider indoor water consumption. Assuming an average household occupancy of three people (Australian Bureau of Statistics, 2006) in new developments, tanks supplying water efficient toilets and washing machines should reduce mains water use in the range of 43 to 46 kL/household/year, regardless of outdoor uses of rainwater. Notwithstanding the high estimated savings from the Gold Coast, where there were no restrictions on external water use in 2008, the other two council areas had lower than expected mains reductions when cross-checking them with results from predicted indoor reductions, as shown in Table 3.5.

Table 3.5 Summary of mains water use reductions for 2008 compared with two independent estimates of the water savings.

Region	Desktop Analysis of water meter records: Mean values	Desktop analysis of water meter records: median values	Water consumption based on regional end use studies (internal only)	TANK model predictions (internal only)
	(kL/household/year)			
Pine Rivers	20	28		49
Gold Coast	95	52	43 to 46	54
Redland	33	41		46
Average reduction	**50**	**40**	**44.5**	**50**

A non parametric rank test was used to statistically analyse the mains water reductions between properties that were under high water restrictions compared to those under low or no water restrictions. The results show that water consumption in No Tank homes located in low or no restrictions (Gold Coast and Redland) was statistically higher ($p < 0.05$) than for No Tank homes in high water restriction areas (Pine Rivers) (Figure 3.5). This will be discussed in more detail in the section below.

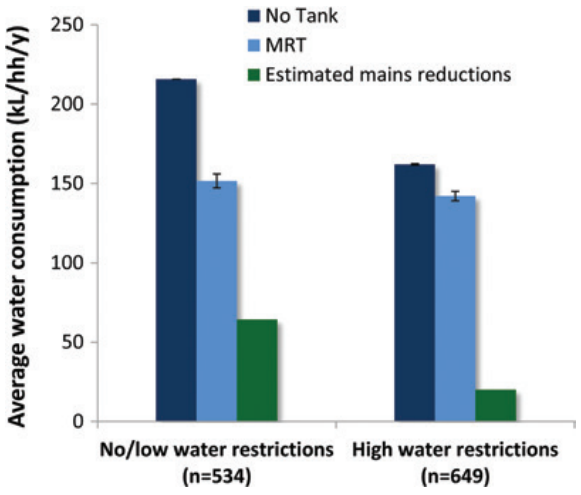


Figure 3.5 Comparison between water consumption and estimated mains reductions for regions with high and low/no water restrictions.

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3.2.4 Discussion and implications

Comparative analysis of mains water consumption between No Tank and MRT properties overall clearly showed that consumption was greater for homes without MRT. There are two main factors that are likely to be influencing the lower estimated reductions calculated from the statistical analyses: the influence of water restrictions during the period of analysis (discussed below) and the limitations of the council billing data used to determine MRT from No Tank homes (Section 3.2.5).

3.2.4.1 Influence of water restrictions

The influence of water restrictions is illustrated in Figure 3.5, which showed smaller differences in water consumption between MRT and No Tank properties in those regions with high-level water restrictions (i.e., no or low outdoor watering). Conversely, the differences in mains water use (i.e., the savings) is greater for those homes located in low or no water restriction areas where rainwater had the opportunity to substitute for garden water use otherwise supplied by mains water (Figure 3.5). The strictest water restrictions in 2008 occurred in the Moreton Bay Regional Council area, which encompasses Pine Rivers. Outdoor watering using mains water was limited to hand held bucket or watering cans. This included newly established gardens or lawns. In contrast, Gold Coast City Council had no restrictions between February and November 2008 due to high rainfall events overtopping their main water supply dam (Hinze Dam). Consequently, there was no limitation to outdoor watering with mains water. Properties in Redland Shire Council were on Level 2 restrictions which allowed outdoor watering using mains water to occur with a hand held hose both for established and new gardens. Daily per capita water use for No Tank properties all exceeded the 2008 average value for areas in SEQ under water restrictions (data not shown). Conversely, average per capita water use from households with MRT was ~20% less, and was similar to the average water use for restricted SEQ regions at that time which was 128 L/p/day (equivalent to about 131 kL/household/year). When compared to homes with a MRT, high water usage from No Tank homes would maximise the main water savings able to be achieved from rainwater tanks. However, if people are frugal in their water use due to water restrictions and demand management strategies (as was the case during our 2008 study) this will compress the differences in mains water use between tank/no tank homes, and hence minimise the potential for mains water savings from rainwater substitution.

3.2.5 Limitations of Case Study 1

Although all local government regions could be confidently divided into the two groups of No Tank and MRT, and then subsequently paired for statistical testing, there still remained some important information that could not be extracted from the data provided. This absence of information for some or all of the regions created the following limitations:

- Separating the billing data into MRT and No Tank subsamples could only be done using assumptions and proxy data, as detailed in the methods section;
- Separating out the influence of MRT from other water restriction influences was not possible;
- Details on critical factors that influence residential water consumption (garden size, water efficient fixtures etc.) could not be fully taken into account; and
- Details on socio-demographic factors such as household occupancy, family makeup and income could not be controlled for in the analysis.

These limitations are likely to have had some influence on the outcomes from the analysis. Without specific knowledge of household occupancy, household water demand cannot be properly controlled for.

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For example, a single person No Tank household with low total water use volumes may be matched with a six person MRT family using very high volumes of water, thereby reducing the estimated contribution from rainwater tanks. The same argument follows for controlling for outdoor water demand if garden sizes (as opposed to allotment sizes) were known. Although MRT and No Tank homes were paired based on two lot size categories, there were no strong trends in the differences in water consumption and savings between lot size categories. However, a large allotment does not necessarily translate into a large, irrigated garden area. With this knowledge, external water demand can be controlled for to some extent, although external water uses are notoriously difficult to quantify (Beal & Stewart, 2011; Wang, 2011).

Finally, the role of water-efficient household stock such as low water use (5 star rated) washing machines, low-flow shower roses and tap flow controllers have not been able to be quantified in this Case Study. Research shows that these efficient features and fixtures can be very effective in reducing domestic water consumption (Willis *et al.* 2010; Beal *et al.* 2011b). It is likely that had such data been available for the MRT properties, one would have seen a greater difference in water consumption from MRT (more savings) and No Tank properties.

3.2.6 Concluding remarks

Whilst it is clear that internally plumbed rainwater tanks will offset mains water demand, the annual volume of that offset is highly variable, and influenced by a range of factors including demand for rainwater (e.g., from external and internal water uses), rainfall, demographic factors (e.g., household size and waterwise awareness) and water efficient household appliances/fixtures. Additionally, the timing of the analysis with a drought-focussed community, where external water use was conservative due to water restrictions, made the differences due to tank supply options harder to detect. Any water saving features in new homes that are not present in pre-2007 homes will reduce mains water use and hence increase apparent rainwater contributions. Similarly, any systemic population difference between post- and pre-2007 homes will affect mains water use and hence bias the calculated tank water contributions.

Despite these acknowledged limitations, the desktop methodology presented in this Case Study has the advantages of providing a base range of savings for relatively low cost experimental inputs (e.g., no field trial costs or modelling work required). It exploits available datasets and uses a basic statistic pairwise approach to estimate the likely range of savings. At the least, it provides a 'first pass test' to estimate the range of achievable savings expected from mandating rainwater tanks in any given area. This may moderate the expectations of potable water saving from mandating rainwater tanks in other regions.

3.3 CASE STUDY 2 – BENCHMARK ANALYSIS OF MAINS WATER SAVINGS

3.3.1 Background

To improve the validity of the Case Study 1 approach, there were a number of recommended additional steps to take for a second stage assessment of mains water savings. These were focussed around improving the lack of specific knowledge on MRT and No Tank homes, socio-demographic data, knowledge of rebated tank installations and household water stock (e.g., presence or absence of water-efficient stock). This work is now presented in the following section.

3.3.2 Research aims

The aim of Case Study 2 is to provide a sound and methodical approach to validating the MRT savings target of 70 kL/hh/yr under the QDC MP 4.2 for SEQ. It will provide some contextual understanding

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for results discussed in Case Study 1 in achieving the mains water savings through MRT. A further aim of Case Study 2 is to document a methodological approach that can be applied globally to estimate, and subsequently justify, water supply from rainwater tanks as an alternative water supply source.

3.3.3 Methods

3.3.3.1 Data collection and participant details

The study area comprised four LGAs in the SEQ region, three of which were examined in Case Study 1: Caboolture, Pine Rivers, Redland and Gold Coast (Figure 3.2). The 2006 Australian Census described these four LGAs as containing over 40% of SEQ urban population (DIP, 2009). These regions were selected due to the availability of necessary data for this benchmark analysis. Only properties built after 2007 were included in the study to ensure only households with MRT were analysed.

A phone survey was conducted between July and August 2010 to understand the potential contribution of biophysical and social factors in achieving water saving targets as identified in Case Study 1. The results of the phone survey research are described in Chong *et al.* (2011). The participants groups, who were recruited during the phone survey study, provided their consent to access their mains water billing records from their water supply provider. Of the 15,615 targeted households, 1134 householders from the four LGAs responded to the survey satisfying the screening criterion that the household had an MRT. The water consumption data for the consenting households were obtained from the Queensland Water Commission (QWC) database. Some households were subsequently excluded from the analysis due to inconsistent or incomplete water billing data. A total of 691 households across the four council areas were ultimately found to be suitable for inclusion in the Case Study 2 analysis. Rainfall data for each of the regions is presented in Table 3.2.

3.3.3.2 Assessment procedure

A benchmark analysis approach similar to Sydney Water's BASIX approach (Sydney Water, 2008) was applied for assessing mains water savings. Figure 3.6 shows schematically the benchmark analysis approach to estimate the potential mains water savings from dwellings with mandated rainwater tanks (MRT).

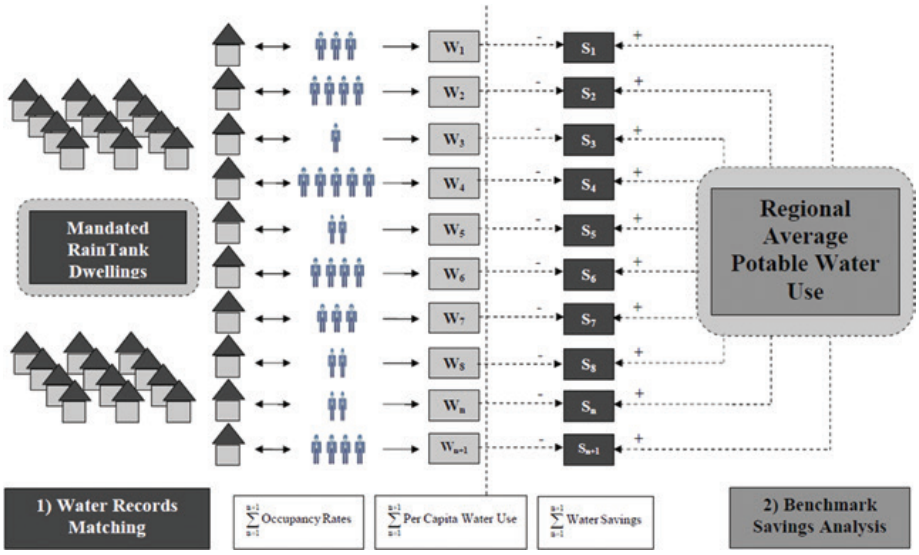


Figure 3.6 Schematic diagram for the benchmark analysis in estimating the potential mains water savings.

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Mains water consumption records for each MRT dwelling were matched to their individual household occupancy number obtained from the phone survey. This was followed by the normalisation of mains water consumption to provide the per capita mains water usage (W_X) of each matched dwelling. The water usage data set (W_X) was then individually subtracted from the *average* mains water use for the respective LGA to generate the individual mains water savings (S_X). A positive sign notation (+) indicates a mains water savings from MRT dwellings. Negative values (–) indicate the mains water consumption at the particular MRT dwelling was actually higher than the regional average value. Subsequently, the average annual mains water savings from the MRT dwellings was estimated from the summation of each of the individual mains water savings (S_X) values.

3.3.4 Results and discussion

3.3.4.1 Water consumption data for MRT dwellings

The resultant mains water savings was expressed in litres/person/day (L/p/d). In order to convert the savings into kL/hh/yr, the mean occupancy rate was estimated via telephone interviews and used to provide more accurate results in determining the water consumption in these LGAs (Table 3.6). Interestingly, the known average occupancy was found to be higher than that assumed in the Case Study 1 (3 people per dwelling).

Table 3.6 Mean water consumption (L/p/d) in MRT households and average persons per household.

Region with mandated rainwater tanks	Sample size	Mean water usage 2009 (L/p/d)	Mean water usage 2010 (L/p/d)	Average person number per household assumed by Beal *et al.* (2011)	Average person number per household in this study
Pine Rivers (Moreton Bay Regional Council)	197	119.4	109.4	3.00	3.21
Caboolture (Moreton Bay Regional Council)	158	108.5	108.2	–	3.20
Gold Coast City Council	172	138.8	125.7	3.20	3.34
Redland City Council	164	129.1	121.9	2.90	3.18

3.3.4.2 Benchmark analysis of mains water savings for MRT households

The average mains water usage for the MRT cohort was compared with the SEQ average mains water consumption data for each LGA. The differences between the two data sets provide an estimate of the mains water saving for MRT households in 2009 (Table 3.7) and 2010 (Table 3.8).

The estimated per capita mean values for mains water saving from MRT dwellings were considered to be more accurate than the earlier analysis of Beal *et al.* (2011) in Case Study 1, as they are now normalised to the specific occupancy rate for every matched household. Although both the mean and median values were

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estimated, mean values are reported to maintain consistency with the units used in the State Government published data for the SEQ region. Since the ultimate aim of this study is to validate the 70 kL per year mains water savings target under QDC MP 4.2, the calculated annual mains water savings in L/p/d in Tables 3.7 and 3.8 were converted to kL/hh/y based on the average occupancy rates per household obtained from the phone survey (Table 3.6). Further, there is some doubt as to the relevance of savings predicted from prior Probabilistic Urban Rainwater and Wastewater Reuse Simulator (PURRS) modelling because of high water use assumed at that time, that is, 300 L/person/day (WBM Oceanics, 2006). This PURRS modelling was used to set the 70 kL/hh/year MP4.2 savings target, and was based on high external water use (around 50 L/p/d) estimated at the time (2005) in SEQ. However, this amount of outdoor use simply did not occur during and after the drought in SEQ (2007 onwards) as evidenced in Figure 3.3.

Table 3.7 Average annual water savings in MRT households in 2009 for four local government areas in SEQ (sample size in brackets).

Description	Pine rivers (197)	Caboolture (158)	Gold coast (172)	Redland (164)
Average persons per household	3.21	3.20	3.34	3.18
Average mains water consumption for all households in the LGA (L/p/d)[1]	140.4	140.4	211.4	201.5
Average water consumption in MRT households (L/p/d)	119.4	108.5	138.8	129.1
Average water savings in MRT households (L/p/d)	20.9	31.9	72.6	72.4
Average annual savings in MRT households (kL/hh/yr)	24.5	37.3	88.5	84.0
Average mains water use savings (%)	15	23	35	36
Average savings over all samples (691)		**58.8 kL/hh/yr**		

[1]*Source*: QWC data.

Table 3.8 Average annual water savings in MRT household in 2010 in four local government areas in SEQ (sample size in brackets).

Description	Pine rivers (197)	Caboolture (158)	Gold coast (172)	Redland (164)
Average persons per household	3.21	3.20	3.34	3.18
Average mains water consumption for all households in the LCA[1] (L/p/d)	143.3	143.3	192.0	183.1
Average water consumption in MRT households (L/p/d)	109.4	108.2	125.7	121.9
Average water savings in MRT households (L/p/d)	33.6	34.8	66.3	61.2
Average annual savings in MRT households (kL/hh/yr)	39.7	40.9	81.0	71.0
Average water use savings (%)	24	25	35	33
Average savings over all samples (691)		**58.2 kL/hh/yr**		

[1]*Source*: QWC data.

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Results from 2009 modelling (Table 3.7) demonstrate that households with MRT substantially reduced mains water use in all the studied LGAs. Variation between LGAs could be driven by factors such as rainwater tank yield including factors related to rainfall, socio-demographic factors (water wise awareness and household water conservation behaviour) and water efficient household appliances and fixtures. The average mains water savings for Pine Rivers and Caboolture in 2009 were 20.9 L/p/d and 31.9 L/p/d respectively, which were significantly lower than the water savings for Gold Coast and Redland (72.6 and 72.4 L/p/d respectively). These data reflect the continued low water consumption in Pine Rivers and Caboolture in 2009 in the aftermath of the severe water restrictions placed on those regions in 2008.

Table 3.8 presents the average mains water consumption for IPT dwellings in 2010. The average annual mains water savings per household per year across the four council areas were found to range from 39.7 kL/hh/yr (Pine Rivers) to 81.0 kL/hh/yr (Gold Coast). Per capita reduction in mains water consumption per day ranged from approximately 24 to 35% (Table 3.8). The overall average water savings across the four regions in 2010 (for 691 households) were 58.2 kL/hh/yr. Interestingly, it was found that the mains water use pattern for the quarters in 2010 are quite different from quarters in 2009 where the inverse of higher water consumption rate towards late 2010 was observed. As discussed for Case Study 1, higher potable water savings for Gold Coast and Redland, which approximate the PURRS predictions, are probably due to much higher external water use, as these areas had minimal water restrictions compared with the other 2 LGAs.

3.3.5 Challenges and limitations

Although some challenges faced in Case Study 1 have been addressed in this analysis, there remained difficulties in obtaining complete data sets for some households. This limitation is likely to be a globally common problem. Typical difficulties associated with data gathering include:

(1) Many local authorities often had partially complete or missing billing information for households;
(2) Some datasets had been merged or removed for various reasons;
(3) The period of time for which water consumption was billed was not consistent, for example, quarterly versus six monthly; and
(4) Privacy issues can severely delay or prevent obtaining identified data.

As for Case Study 1, some inconsistencies in datasets made matching of data pairs more challenging and resulted in a reduced sample size.

3.3.6 Concluding remarks

Case Study 2 demonstrated that MRT households could reduce their reliance on mains water supplies in all the studied LGAs, albeit with substantial variation among LGAs. Case Study 2 (benchmark with empirical data) was designed to build on the results from Case Study 1 (desktop study with billing data), and to identify the advantages of this approach in more accurately quantifying mains water savings from rainwater tanks. The key difference between the two approaches is that known household occupancy rates (from the phone survey) were matched to the individual water billing records in Case Study 2. Conversely, Case Study 1 did not have access to this data, thus relied on using the average household occupancy rate from the 2006 Australian Bureau of Statistics (ABS) Census District Data for cross-checking the pairwise statistical analyses. It is anticipated that the Case Study 2 methodology can be used for most urban areas of the world, although the exact uses of the rainwater should be known. For example, if there is only internal uses (toilet and clothes washing) and little or no outdoor use, the savings from mains supply will be reduced. End uses studies reported by Beal *et al.* (2011b, 2013) are very valuable in understanding the

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quantum of potable water savings expected from rainwater tanks. Additionally, consumption and end-use also should be matched with socio-demographics and socio-economic status as this strongly influences water use per person per day (wealthy people typically use more water!).

3.4 CASE STUDY 3 – WATER SAVINGS FROM REBATED RAINWATER TANKS

3.4.1 Background

This case study presents the estimated mains water savings from installation of rebated rainwater tanks in Canberra and the broader Australian Capital Territory (ACT) based on analysis of water billing data. As part of its *Think Water, Act Water* strategy, the ACT Government subsidised the cost of purchasing and installing tanks. Initially run by the local water utility, the rebate program commenced in 1997, offering subsidies for installing medium to large tanks (>4 kL), but with no requirement for plumbing tanks to indoor connections (Fyfe *et al.* 2011). In 2004, the ACT Government took over administration of the program, adding rebates for indoor connections to new and existing tanks, and reducing eligible tank size threshold to 2–4 kL. Rebate incentives were adjusted four times between 2004 and 2007, and from July 2006 indoor connections were made a requirement for all rebates.

Throughout the majority of the program, the ACT experienced drought conditions and residents were subject to mandatory water restrictions. From 2005 to 2007, when restrictions were at their tightest, peak summer demand in the ACT dropped from 250–300 ML/d (unrestricted) to 150–170 ML/d (Fyfe *et al.* 2011). This demand reduction was in part due to customer response to water restrictions and associated public campaigns. Additional factors were the national Water Efficiency Labelling Scheme (WELS) (Australian Government, 2014), local water sensitive urban design projects, and a number of efficiency programs such as home retrofits of water-efficient devices under the *Think Water, Act Water* strategy (ACT Government, 2004).

3.4.1.1 Research aims

The central aim of the evaluation study conducted for the ACT Government (Fyfe *et al.* 2011) was to produce robust estimates of water and energy savings, and associated reductions in greenhouse gas emissions from the various efficiency programs under the *Think Water, Act Water* strategy. A key component of the research was to validate the methodologies used to generate the estimates. The research presented in this section focuses on the water savings derived from the rainwater tank rebate program.

3.4.2 Methods

3.4.2.1 Data sources and pre-processing

Data identifying rebate participants (all voluntary), their address, rebated tank size and connection details were provided by the ACT Government. The data were filtered to remove duplicates, incomplete records and participants that had participated in *other Think Water, Act Water* efficiency programs. The data for the remaining participant households were linked to quarterly water billing (metered consumption) data provided by the ACT water (and electricity) utility using lot, block, section and suburb identifiers. Only individually metered dwellings were analysed, causing most multi-residential dwellings to be excluded. The utility also supplied dates of changes to dwelling occupants (identified by changes to electricity account holders[1]), allowing the analysis to focus on households that occupied

[1] In Australia, electricity is typically billed to actual household occupants whilst water is billed to property owners who can choose to pass on the charges to their tenants.

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a property both before and after receiving a rebate. The connected roof area was not known for the households examined, but as the ACT study examined retro-fitted tanks, it was assumed to be lower than for the MRT homes in SEQ. Water billing data for all non-participant households in the ACT was also supplied by the utility to provide a pool of 'controls' information. All billing data were screened for negatives, missing records and statistical outliers before being converted into monthly values using the 'binning' algorithm explained in Fyfe *et al.* (2010). Binning is used to overcome the problem of households having differing billing cycles where for example group X's household quarterly bills might end on 5th April, whilst group Y's household bills ends on 20th May. The process regularises the consumption data on a pro-rata basis so that it conforms to calendar months, allowing direct time-based comparisons between households.

3.4.2.2 Analysis procedure

The methodology used to estimate savings is based on a pair-matching approach similar to that used in Case Study 1 (Section 3.2), except matching was performed using historical consumption patterns rather than lot size and location. The matched pairs means comparison (MPMC) method compares the consumption of *each rebated household* with *every non-rebated household* in the entire utility based on data generated within the period between 3 and 14 months *prior to tank installation*.[2] The strongest match is determined by the lowest root square error (RSE) result calculated as:

$$\sqrt{(N_{-14} - R_{-14})^2 + (N_{-13} - R_{-13})^2 + \ldots + (N_{-3} - R_{-3})^2} \tag{3.1}$$

where R = monthly average day consumption of the (future) rebated household (kL/d), N = monthly average day consumption of corresponding non-rebated household (kL/d) and subscripts indicate the month relative to the participant's rebated tank installation. A perfect match will produce an RSE of zero.

The matched non-rebated household is assumed to have similar characteristics and responses to external demand drivers as the rebated household, and is adopted as a control. Matching is performed for each participant household in a random sequence until every rebated participant has its own control household. Matches are then subjected to several statistical tests to check the veracity of the match, which are described in detail in Fyfe *et al.* (2010).

Savings in month m of year y were then calculated as:

$$(N_i - R_i)_{m,y} - (N_i - R_i)_{m,Y} \tag{3.2}$$

where R_i is consumption of rebated household i in month m of post-installation year y or the pre-installation year Y, and N_i is consumption of the matched non-rebated control in the same month.

Repeated measures t-Tests were applied to the paired household differences for each month to test against the null hypothesis that the population of monthly savings had a mean of zero (i.e., no discernable water savings). Household savings typically showed a non-normal distribution, thus, Wilcoxon signed rank tests were also applied as a non-parametric (non-normally distributed) alternative.

[2]Since ACT water bills span three months, monthly consumption data produced by the binning process is influenced by consumption that occurred up to two months before or after any given month. Thus a distinct intervention month could not be isolated in the consumption data and the two months data before and after installation had to be excluded from the analysis.

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3.4.3 Mains water savings results

Over the life of the program, 2744 rainwater tank rebates were paid to residents. Linking and pre-processing the data reduced the sample to 1913 households, and filtering through the MPMC method further reduced the sample size to 1410 households, with consumption data that ranged from October 2001 through to March 2011. The global mean savings estimate for rebated tanks between April 2003 and March 2011 (inclusive) was 40 ± 25 L/household/day, equivalent to 15 ± 6 kL/household/year. This is equivalent to 5% of average participant household water consumption in the pre installation period. Savings estimates for particular tank configurations based on analyses of subsets of the full data set are given in Table 3.9.

Table 3.9 Sample sizes, median tank sizes and savings estimates for different configurations of rebated rainwater tanks (April 2003–March 2011).

Rebated tank configuration	Sample size		Median tank size	Mean annual savings		Saving as a % of average participant consumption before installation	
	Households	Monthly consumption data points	kL	(kL/hh/year)			
All tanks	1410	66,116	5	15	±6	5	±2
Indoor plumbed	176	4837	5.3	9	±15*	3	±5*
Outdoor plumbed	845	45,176	5	10	±7	3	±2
Indoor and outdoor plumbed	182	4516	5.6	21	±16	7	±5
Tanks <4kL capacity	242	10,998	2.25	7	±11*	2	±3*
Tanks ≥4kL and <9kL capacity	660	30,794	5	13	±8	4	±3
Tanks ≥9kL capacity	478	23,016	10	20	±11	6	±3

**Notes*: Error bounds are 95% confidence intervals; not statistically significant at the 5% level.

The plot of savings for all tanks in Figure 3.7 shows that there is no clear long-term decay or growth, or seasonal pattern. Note that Figure 3.7 does not include data for the year 2003 as savings estimates were grossly exaggerated by outliers in small samples and were not statistically significant. The same absence of seasonality is evident in savings from tanks with exclusively outdoor connections (data not shown). Savings were not consistently statistically significant ($p > 0.05$), exhibiting a large dip from October 2006 to January 2007 (summer) following an extended period of low rainfall that also led to the introduction of stricter stage 3 water restrictions (after a year of relaxed restrictions) and low overall water consumption.

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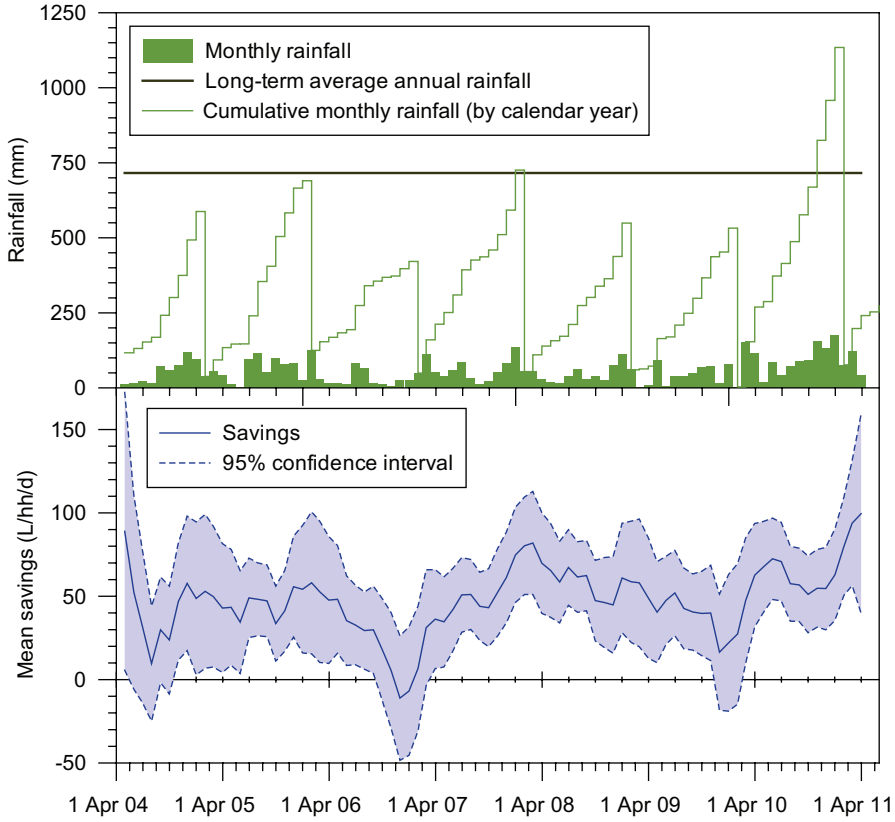


Figure 3.7 Mean monthly savings for all rebated rainwater tanks (bottom) and observed and long-term average monthly rainfall (top) over time.

3.4.4 Interpretation and implications

Savings were generally lower than anticipated and were not statistically significant for tanks with only an indoor connection, and for tanks of <4 kL capacity. Combined indoor and outdoor connections produced the greatest potable water savings (21 kL/hh/yr), and despite the small sample, the savings estimate was statistically significant ($p < 0.05$) and close to the sum of the separate indoor and outdoor connection savings. The climate of the ACT region may be characterised as Mediterranean, with relatively low rainfall throughout the year and hot, dry summers. Accordingly, rainwater tank yields cannot be expected to be as high as in the sub-tropical region of SEQ (Case Studies 1 and 2). However, savings for outdoor connected tanks (10 kL/hh/yr) were notably lower than the theoretical yield of 19 kL/year for a median-sized (5 kL) tank in the ACT region assuming a small roof catchment (50 m^2) and a relatively small 100 m^2 irrigated garden/lawn.[3] As shown in the upper plot of Figure 3.7, annual rainfall was below average (716 mm) in 5 of the 7 years s, which would have reduced yield from all tank installations. With water restrictions in force, access to mains water for irrigation was heavily constrained, thereby reducing apparent mains water savings. That is, the substitution of potable water with rainwater for outdoor end uses would not have been reflected in mains water savings for tank-owning houses.

[3]Derived using the water balance model described by McKibbin and Fane (2011).

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Savings associated with indoor connections (9 kL/hh/yr) were also considerably lower than theoretical yield for connections to toilets and/or laundry (between 15–31 kL/year for 5 kL tanks connected to a 50 m^2 roof catchment). This supports the findings of Mukheibir *et al.* (2013), who recommend applying a 'functionality factor' of between 0.5 and 0.7 to theoretical rainwater tank yields to account for reduced catch efficiency associated with compromised installation quality, operational failures and behavioural issues. The scale of the yield impairment would appear high in this case, particularly when contrasted with the good agreement between measured and predicted savings in the SEQ case studies. However, this could in part be due to the fact that the tanks were retro-fitted to existing dwellings such that many would have had sub-optimal roof catchments, guttering and plumbing. In contrast, the SEQ houses with MRT as per the 2007 building code, were likely to have greater area of connected roof to the tanks, thus further contributing to the higher mains water savings observed in Case Study 1 and 2.

3.4.5 Challenges and limitations

By using prior consumption patterns to match tank participants to controls, the MPMC method circumvents the need for collecting data on household characteristics such as number of occupants, lot size, income and plumbing fixtures and appliances. It also implicitly controls for external factors such as restrictions and price changes. However, it cannot be applied to new homes with no water use history. Also it is not immune to the vagaries of internal household dynamics such as changes in appliances, new or departing occupants and voluntary behaviour change. Thus, it relies on a sample size of several hundred or more households to obtain robust savings estimates. Four of the six tank configuration subsets reported in Table 3.9 comprised less than 500 households, which meant that monthly average savings estimates (within the time series) were at times not statistically significant (see Figure 3.7). The extensive longitudinal component of the data set helped those sub-samples produce statistically significant global savings estimates, but these have large confidence bounds, making inferences more indicative than definitive. The analysis did benefit, however, from having household occupancy details verified using electricity accounts, thereby ensuring savings estimates were not biased by changes in ownership or tenancy.

3.4.6 Concluding remarks

The analysis of household billing data confirms that the installation of rebated rainwater tanks in existing homes of the ACT has achieved measurable potable water savings, but that those savings are significantly less than theoretical yield estimates. Recent research undertaken by Mukheibir *et al.* (2013) found that rainwater tank installation, maintenance and usage is often sub-optimal, resulting in impaired yields. In the case of rebate programs such as this one, poor tank functionality would be exacerbated by the difficulties associated with retrofitting tanks to existing dwellings such as limited accessible roof catchments and deteriorating guttering. Small yields caused by low rainfall and substandard functionality would produce low apparent mains water savings, which would have also been suppressed by reduced water usage amongst the broader community stemming from water restrictions and acute awareness of water scarcity. Functionality issues and low rainfall are also likely to be behind the notable differences between savings observed in this case study and those reported in Case Studies 1 and 2.

Nonetheless, the MPMC method is a robust method, and can be considered the 'Gold Standard' of treatment comparisons in estimating actual savings achieved by implemented programs, including rainwater tank rebate programs, provided prior water use behaviour of the house cohorts is available. It has been used on a variety of efficiency programs across Australia (Turner *et al.* 2013). It is recommended that a minimum 28-month billing dataset comprising 14 months either side of implementation is available

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before a robust analysis can be conducted using a 3-month billing cycle. Longer billing cycles require proportionally larger datasets. Based on the observed magnitude (~5%) and variation of the savings signal, the analysis precision will benefit from a sample size of more than 500 households, particularly when yield is likely to be lower due to small tank sizes or singular (indoor or outdoor) plumbing connections.

3.5 KEY CONSIDERATIONS IN QUANTIFYING MAINS SAVINGS

Having presented and critiqued three approaches to quantifying mains water savings from installing both internally and externally supplied rainwater tanks, there are a number of key points to consider when designing an approach to quantifying mains water savings. Ultimately, the goal is to have a large sample size based on desktop and field data of high quality. This is not always possible due to resource and time constraints. A method evaluation chart is presented in Figure 3.8 which assess costs against sample size, method approach and data quality. The larger the circle, the greater the costs, but usually, the higher the accuracy of outcomes. Figure 3.8 suggests that if only one approach is used for determining mains water savings, then the accuracy can be improved with a dataset of large sample size and high quality. Similarly, if the quality of the data is not detailed, but two or more approaches are being used based on a large sample size, a reasonably accurate outcome can be achieved.

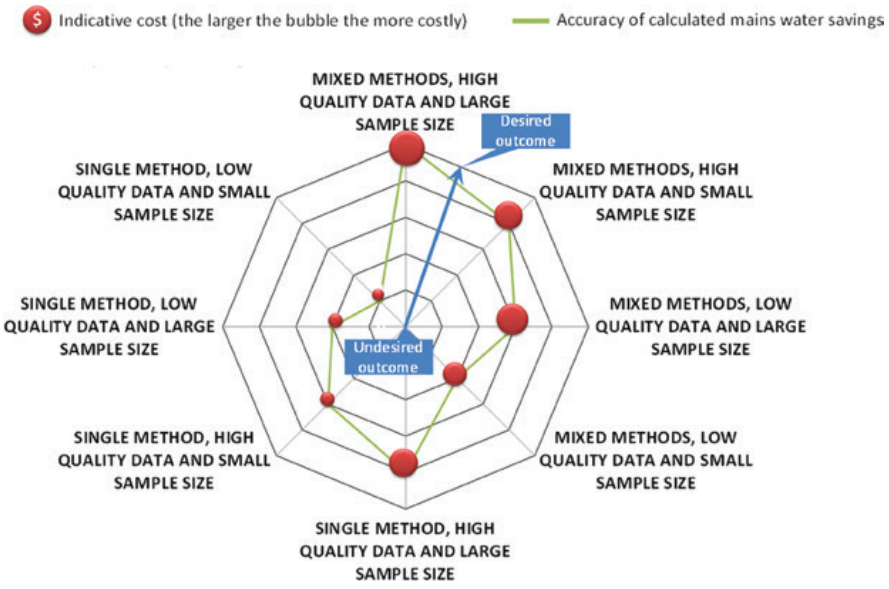


Figure 3.8 Method evaluation chart to assist in study design.

Each of the three main variables considered in Figure 3.8, data quality, methodological approach and sample size, are described below.

3.5.1 Quality of the datasets

3.5.1.1 Desktop approach only

Having access to quality data is obviously paramount in any field of research. A desktop approach using modelling and statistical analysis can certainly be valid, and even more so if it is coupled with at least

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one other method that allows for some empirical data to underpin the analysis (i.e., measured water consumption data). However, in the (often likely) absence of this possibility, a desktop approach alone may provide a reasonably accurate range of mains water savings, provided that it uses good quality data that can be applied with confidence to subsequent analysis. 'Good quality' data for estimating mains savings can be defined as having at least some or most of the following:

- *High resolution information on residential property* for example: dwelling configuration (detached, multi-unit, townhouse), people per dwelling, lot size, size of rainwater tank, rainwater end uses (internally or external only), date of tank installation, other water supply options on the property (dual reticulation/greywater system), connected roof area and degree of water-efficient appliances and fixtures.
- *Estimating external water use* is an important component as this end use has a high impact on the volume of rainwater used per year. As a first estimate, it is the difference between meter billing data and estimated internal water use for non-tank homes (as described in Case Study 1).
- *Large sample size* ($n = \geq 500$) of homes with *and* without rainwater tanks (and the configurations of the tanks).
- *A complete dataset of billing information* of water consumption (ideally at a three-month interval or less).
- *A spatially variable* dataset containing all of the above to allow some control for climate and biogeographical factors during analysis.
- *A longitudinal dataset* to also consider different seasons, water restriction regimes and water use activities (e.g., irrigation, school holidays, Christmas). Long-term data (≥3 years) for homes with and without rainwater tanks is critical to ensure representative water consumption patterns that encompasses both water restriction and non-water restriction regimes for example.

3.5.1.2 Field measurement approach

Where it is feasible to design a field measurement methodology, it is desirable that as many relevant parameters are measured for subsequent modelling and/or statistical analysis, particularly if an objective is to validate a desktop/modelling study. Chapter 4 presents a detailed section on the instrumentation for actual measurement for validation of the water savings. Below are some suggested ways to improve the quality of the data and accuracy of the method used for assessing mains potable savings from MRT (as per Figure 3.7):

- *Water consumption* – ideally both total and end-uses from the mains supply. End-use data will confirm the proportion of demand that can potentially be offset by rainwater. Smart metering equipment on both the mains meter and rainwater offtake should allow, at minimum, the total volumes of water supplied from each source. External water use, as emphasised throughout, is critical to estimate or measure as accurately as possible.
- *Socio-demographic data* – household occupancy has been emphasised as a very important parameter throughout this chapter. If there is no prior water consumption data, it is recommended to identify, as accurately as possible, the actual number of people in a household.
- *Household water-efficient stock* – if possible, the key water-related fixtures and appliances in the sample households should be identified as best as possible, and can be done simultaneously with smart meter installation if this is a feasible design option.
- *Water use behaviour* – the field methodology could also include a short survey on some water use behaviours around irrigation and outdoor use in general. For example, water behaviour information such as how often irrigation occurs and method of application (e.g., hand hose vs dripper system) will provide further opportunity to correctly match 'like with like'.

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3.5.2 Mixed method and analyses

The types of data-gathering methods such as desktop (accessing council data on water consumption and other relevant information), modelling (using known or assumed input parameters), field instrumentation (direct measurement of water consumption) and stock audit and survey (water-efficient fixtures and outdoor irrigation) will strongly influence the accuracy and representativeness of the results. Ideally, it is recommended a mixed method approach be adopted, whereby a desktop/modelling exercise (based on council billing data), is followed by a field study validation (instrumentation and survey).

In terms of statistical data analysis, a pair-matching approach can facilitate before-after control-intervention analysis design, which supports robust savings estimation. Ideally, well controlled, household pair-matching for both pre-intervention (No Tank dwellings) and post-intervention (MRT dwellings) is the ideal scenario for statistical comparisons of likely water use savings. Naturally, the higher the resolution of pair-matching the more informative the outcomes can be.

3.5.3 Sample size v quality of datasets

As shown in all three case studies, determining mains water savings often relies on a third party dataset (e.g., water utility billing data) of potentially doubtful quality for pair matching. Therefore, larger sample sizes are desirable as there can be considerable noise in both billing data and rainwater consumption rates from this third party dataset. For example in Case Study 1, a starting sample of council billing data for nearly 29,000 homes was reduced to 2800 possible matched pairs for MRT and No Tank, and down further to <790 if lot size category was being matched.

If there is a field study component, where good quality metering data is available for each home, and end-uses of rainwater and household occupancy is available, then a lower sample size is likely to be sufficient. However, this may be at a higher project cost. This is also true for modelling the savings from rainwater tanks, where high quality input parameters can improve the accuracy and reliability of the model outputs.

3.6 SUMMARY AND CONCLUSIONS

The primary objective of this chapter is to present and critique alternative statistical methods that can be widely used for assessing the savings in mains water use from rainwater tanks. Three case studies were selected which incorporated both theoretical modelling approaches and empirical field data for both mandated rainwater tanks and rebated voluntary rainwater tanks. Some key conclusions from this chapter are:

- Outdoor consumption is the critical end-use that will maximise savings. Thus, factors such as water use restrictions, lot size and behavioural cues (willingness to use water outdoors) are very important in determining savings.
- The methods employed to assess savings will depend on desired outcomes, availability of good quality data and resources. A large sample size ($n > 500$) can be partially substituted for by good quality data where household occupancy, type of RWT end uses, potable water use restrictions and lot size are known.
- A desktop approach using statistical analysis should be coupled with at least one other independent approach to underpin the confidence of the empirical data analysis.
- All three case studies focussed on the need for large sample sizes, known household occupancy and the level of water-efficient stock in households.

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- Actual rainwater yields can vary significantly between regions due not only to climatic factors, but also tank sizes, connected end uses, connected roof area, and the level of functionality (related to the quality of the installation). The functionality component is an important factor to be considered in *ex-ante* assessments of yield from rebate programs. For example, internal mains water savings in Case Study 3 were significantly lower than theoretical yields, indicating compromised tank system functionality.
- Models can provide a valid range of potential savings data provided they use realistic end use consumption figures and household population estimates. Nonetheless, validation by some level of field work (e.g., phone survey, instrumentation) is ideal.
- The pre-intervention pair-matching approach is the most statistically robust method to estimate savings as the same households are used in the post-intervention analysis.
- Statistical analysis will benefit from a sample size of more than 500 households (matched pairs), particularly when yield is likely to be lower due to small tank sizes, or singular (indoor or outdoor) plumbing connections.

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Chapter 4

Monitoring of household rainwater tank systems for rainwater usage

Shivanita Umapathi, Reid Butler, Matthew Ferguson, David Pezzaniti and Ashok K. Sharma

ABSTRACT

The purpose of this chapter is to describe monitoring methods for household rainwater tank systems to provide evidence-based data on their effectiveness. Rainwater tanks are incorporated in urban environments around the world under integrated urban water management (IUWM) and water sensitive urban design (WSUD) approaches. Individual homeowners have been increasingly embracing rainwater tanks as one of the most easily adoptable alternate water supplies for 'fit-for-purpose' uses. Various modelling tools are available to estimate the rainwater usage based on tank size, connected catchment roof area, rainwater demand based on occupancy rate and connected appliances, and local climate data. However, the actual rainwater usage depends upon a number of factors such as occupants' behaviour towards using the various appliances connected with rainwater supply, installation of rainwater tank pumping system, system reliability and losses. Savings in mains water achieved by using rainwater are plausible; however, analyses on quantifying the actual reduction in mains water demand are still at an early stage and lack confidence for their incorporation into strategic water plans. The most important challenge to monitor household rainwater tanks is to properly instrument and accurately collect data for analysis and performance assessment of household rainwater tank systems. The main focus of this chapter is to describe approaches that address these challenges. The rainwater tank system monitoring examples discussed in this chapter come from Australian case studies. However, the methodology described to measure and monitor water savings in households with internally plumbed rainwater tanks should have worldwide applicability, and hence will be of value to water professionals.

Keywords: data collection; logging; monitoring; rainwater tanks; main water saving.

4.1 INTRODUCTION

Although rainwater is a significant source of fresh water in both natural and human-managed ecosystems, the resource is greatly underutilised (UNEP, 2009). Rainwater harvesting involves standard components

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that are universally applicable, due to similar underlying concepts in rainwater capture, supply and usage (Umapathi *et al.* 2013). One of the most widely accepted and commonly used rainwater harvesting techniques in urban environments is the rainwater tank collecting rainfall from household roof area. Depending on the end uses and the configuration of the roof, tanks can be set up in a variety of ways. In urban environments, end uses for rainwater are often chosen to allow minimal treatment requirements under an integrated water management system. For example, supplying the non-potable portion of the total water demand on a 'fit-for-purpose' basis (Cook *et al.* 2013; Jones & Hunt, 2010; Sharma *et al.* 2013a; Sharma *et al.* 2013b; Umapathi *et al.* 2013; Zhang *et al.* 2009). This approach complements a centralised mains water supply, and uses the collected rainwater to meet daily demands from toilets, laundry, garden taps, and in some cases hot water supply.

Urban dwellers and service providers alike are increasingly embracing a variety of demand management strategies by including decentralised systems such as rainwater tanks. Although the water saving potential of rainwater tank systems through modelling approaches is well known, the actual supply volumes and limitations of operating a rainwater tank system are still open for debate. In order to manage ever increasing water demand, measures such as metering, water accounting and loss control, pricing and education are being implemented (Boyle *et al.* 2013). If adequate and reliable data can be garnered using these measures, there exists a great potential to interpret, analyse and understand the water saving implications of using rainwater tanks that are integrated into modern-day urban water supply strategies. Detailed consumption data analysis can be utilised to not only help water utilities improve customer services, reduce water losses and manage demand, but also to provide reliable information at the consumer level in order to help the utilities make informed decisions on water management (Aravinthan *et al.* 2012; Boyle *et al.* 2013; Davison, 2008).

Monitoring of rain water tanks provides an opportunity to acquire rich details on the collection efficiency, the effects of water end use on yield, seasonal influence on rainwater use, and associated energy use that influence rainwater collection and usage. The following sections will discuss the major components of rainwater tank systems that form the basis of monitoring studies, followed by discussions on experimental methods and monitored data assessments. The chapter draws examples from studies undertaken in some of Australia's most urbanised areas.

4.2 MONITORING OF WATER USAGE IN RAINWATER TANK SYSTEMS

One of the earliest attempts to optimise the design of rainwater collection systems using water demand patterns was by Fewkes (1999) who analysed household rainwater consumption on a 'fit-for-purpose' basis. This was followed by various research methodologies to study and estimate the performance characteristics of domestic rainwater harvesting systems (Beal *et al.* 2012; Coombes *et al.* 2000; Coombes & Kuczera, 2003; Ghisi & Mengotti de Oliveira, 2007; Villareal & Dixon, 2005; Willis *et al.* 2011a), whilst other studies have analysed the social, economic and energy implications (Mankad *et al.* 2012; Moglia *et al.* 2012). Techniques to disaggregate water flows using smart water meters within rainwater tank pumping systems have emerged over the last few years (Heinrich, 2008; Talebpour *et al.* 2011; Willis *et al.* 2011b). Disaggregation of end-uses as a means of identifying the water use characteristics within urban residences was first studied extensively in the United States (Mayer *et al.* 1996; Mayer *et al.* 1999) and used to monitor single-source centralised urban water supply systems. Smart metering or automatic meter reading (AMR) (Fane *et al.* 2011) involves key elements such as real time monitoring, high-resolution interval metering (≥10 seconds), automated data transfer (drive by, GPRS, 3G) and remote access to data from the internet (Aravinthan *et al.* 2012; Giurco *et al.* 2008). Although high resolution water flow meters are discussed in this study, the use of high resolution smart meters is beyond the scope of this study. Energy meters are used to estimate electricity consumption in supplying rainwater through rain tank pumping systems.

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Using similar monitoring methods, more detailed studies have been conducted within individual urban settings in recent years through the disaggregation of multiple water sources that are an intrinsic part of an integrated approach to manage water demands. Ferguson (2012) and Umapathi *et al.* (2013) have highlighted the use of water flow metering/automatic meter reading (AMR) methods to conduct end-use analyses of rainwater collected in domestic rainwater harvesting systems using small time-steps ($t \leq 1$ minute). In addition, the water-energy relationship of the rainwater system can also be studied as there is some concern high energy use could be a perverse outcome of such decentralised water supply systems.

Due to ongoing changes in water use patterns resulting from increasing urban densification, changing methods of water supply coupled with introduction of new technologies for water supply and end use, water efficient devices, analyses of end-use 'water behaviour' using high resolution monitoring methods is the key to demand forecasting (Turner *et al.* 2010). Water flow monitoring methodologies are clearly superior to theoretical assessments of, say, peak day water demand, and analysis of actual use patterns should provide a deeper understanding of the constantly evolving water supply milieu. Water efficiency and energy performance of fixtures and appliances can also be extensively investigated through these advanced metering methods.

4.2.1 Drivers for monitoring

Desktop studies such as estimation of urban residential water usage using modelling approaches have often been used as a basis to explore the feasibility of rainwater tank systems. However, a practical approach to understand the role of alternative water supply technologies on existing water supply infrastructure has been largely unexplored until the previous decade. Wide-scale urban water supply issues such as regulatory framework, life cycle costing and community acceptance using actual real-time water demand were not explored in-depth until early 2000s (Lloyd, 2001).

Water meter readings undertaken for billing purposes for residential customers are usually recorded on a quarterly basis. Additionally, meter read timings differ between different households to complete any given billing cycle (Fane *et al.* 2011). Disaggregated information on rainwater use for toilets or garden irrigation could have a good influence on changing consumer water consumption attitudes and behaviours by improving water literacy (Boyle *et al.* 2013; Giurco *et al.* 2010). Utilities can also benefit from smart metering technologies as it enables acquisition of data on rainwater consumption in households (Neenan & Hemphill, 2008) and also more accurate usage and billing data from mains supply.

Our knowledge of the complex interactions of key drivers such as urban form, demographics, life-style and end-use water demand, technology adoption, climate and water supply can be greatly improved and add to the argument for increasing use of alternate water supplies (Kenway *et al.* 2008). The most important driver for monitoring actual rainwater consumption from household rainwater tank supply system is the use of such data in developing more accurate strategic water plans for a region.

4.2.2 Case studies in Australia

Flow metering technologies have been used to conduct water efficiency audits since 1996 by consultants across Australia, including Sydney Water (Aravinthan *et al.* 2012). Extensive end-use studies on urban residential water consumption using flow monitoring methods were conducted in South East Queensland (SEQ), Australia (Beal *et al.* 2011; Beal *et al.* 2013; Umapathi *et al.* 2013; Willis *et al.* 2011a). A brief summary of some of these recent studies conducted in Australia for household rainwater supply monitoring are outlined in the following sections.

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4.2.2.1 Sydney Water, Sydney

Sydney Water recognized a considerable knowledge gap in existing research on the impact of using rainwater tanks on the mains water consumption in Sydney households that were designed under the State Government's Building Sustainability Index (BASIX) Scheme (Ferguson, 2011). The main driver for the study was to determine the performance of household rainwater tanks in saving mains water. Sydney Water conducted an 18-month study of 52 households around Sydney using rainwater. Rainwater usage and mains water top-up for non-potable demands and the corresponding energy consumption of rainwater pumps were monitored remotely, all at one-minute intervals.

4.2.2.2 UWSRA, South East Queensland

The SEQ study involved monitoring, over a cumulative 12-month period, 20 households with rainwater tanks (Umapathi *et al.* 2012; Umapathi *et al.* 2013) installed to meet fit-for-purpose household demands. Similar to Sydney Water's investigation, the SEQ households were monitored for mains water use (including rainwater tank top-up), rainwater use and rainwater pumping energy consumption. The main drivers for this study were to determine the effectiveness of the rainwater tanks; to validate the savings expected from the rainwater tank systems based on local building codes; and to assess the corresponding energy consumption. Earlier desktop studies, conducted in 2011 by Beal *et al.* (2012) and Chong *et al.* (2011), reported that the rainwater tanks installed in new households under the Queensland Development Code (QDC) MP 4.2 failed to meet their predicted water savings target of 70 kilolitres per household per year (kL/hh/year), prompting a detailed investigation into water and rainwater demand in selected rainwater tank households distributed across the region. Further detail on these studies can be found in Chapter 3.

4.3 RAINWATER SYSTEM COMPONENTS, ACCESSORIES AND CONFIGURATIONS

The majority of rainwater tank systems consist of an above ground tank connected to a rainwater catchment area (the roof) together with a combination of system components comprised of filtering, pumping and backup equipment to supply water to specific end-uses (Australian Government, 2013). Some household rainwater tanks may be built underground to save space. However, this is usually a more expensive option as underground tanks cost more and can hinder maintenance and ongoing monitoring efforts in case of system faults. It can also be difficult to measure tank volume if the tank specifications are unknown prior to monitoring (Australian Government, 2013).

In Australia, different configurations for household rainwater tank systems have been identified which include gravity fed systems with pumps, pumping systems, dry systems, wet systems and gutter storage systems (Australian Government, 2013), of which, uncharged conveyance systems (dry systems) and charged conveyance systems (wet systems) are more commonly found. These systems are described in detail in Chapter 5. An above-ground household rainwater tank system setup in South East Queensland is shown in Figure 4.1.

A typical household rainwater collection system (Figure 4.1) consists of roof catchment areas that have attached gutters, which are in turn connected to downpipes that transport water through gravity flow into the rainwater tank reservoir. The size and slope of roof catchment areas can be measured to determine the efficiency and catchment losses of collection areas. This data is used in conjunction with monitored flow data to determine the relationships between weather patterns and rainfall and the reliability of rainwater tank supply. Methods to estimate catchment areas in the absence of building plans were described by Chong *et al.* (2014) and Chong *et al.* (2012) as well as in Chapter 5. Aerial photographs were used during

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on-site household inspections to match the roof catchment slopes with those downpipes that were plumbed to the rainwater tank. This method can also determine the approximate roof area connected to rainwater tank when there is more than one downpipe connected along a run of gutter. Collection system components such as first flush devices and mesh guards may be present to improve water quality during rainfall event (Figure 4.1). These components are discussed in further detail in Chapter 5.

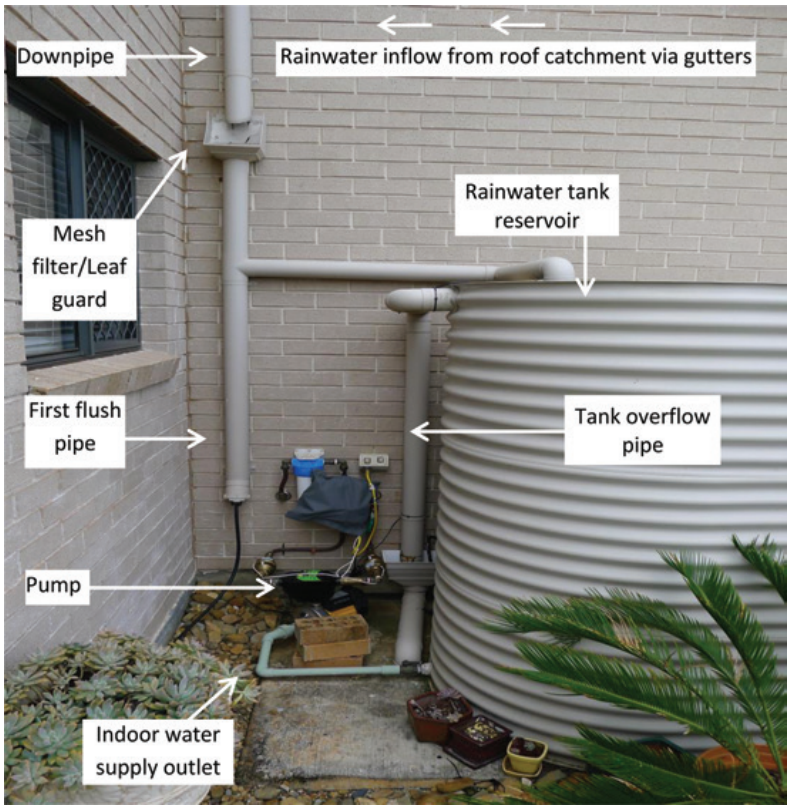


Figure 4.1 An aboveground household rainwater tank system setup in South East Queensland, Australia.

The storage system is obviously a critically part of a rainwater tank system. The volume of rainwater inflow into the storage tank (Figure 4.2) is dependent on weather conditions including rainfall, wind speed and direction and characteristics of the roof catchment area, such as the slope angle. Outflow of rainwater from the tank is dependent on supply factors such as the pumping capacity, supply pipe characteristics and most importantly, connected end-uses such as toilets or washing machines.

Pumps used in rainwater tanks systems come in different sizes (kilowatt ratings) and specifications including pressure cut off settings; hence, the water supply rate and energy used by the pumps vary. The performance of pumps also depends on characteristics external to the pumping system such as the distribution plumbing system. Monitoring of pumping systems can help in optimising pump sizing in rainwater tank systems which are generally known to be highly energy intensive. From an experimental monitoring perspective, it is preferable for the pump to be plugged into a general power outlet (GPO), rather than hard wired into the household electricity system.

In most cases, rainwater tank pumping systems also include tank level sensors (generally float based) and top-up devices including trickle top-up systems or switching device systems that provide mains water

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backup. Backup systems are an important component of rainwater tank systems; they deliver uninterrupted water supply to end uses when the water level in the rainwater tank is too low for pumping. The type of backup system employed will impact the water demand profiles from the rainwater tank and mains water back up supply. Detailed discussions on pumping systems, backup systems and the energy consumption aspects are discussed in Chapters 5 and 6. Pumping systems may also have other ancillaries such as pressure vessels, header tanks and so on (Retamal *et al*. 2009; SEWL, 2009) which are also discussed in Chapter 6.

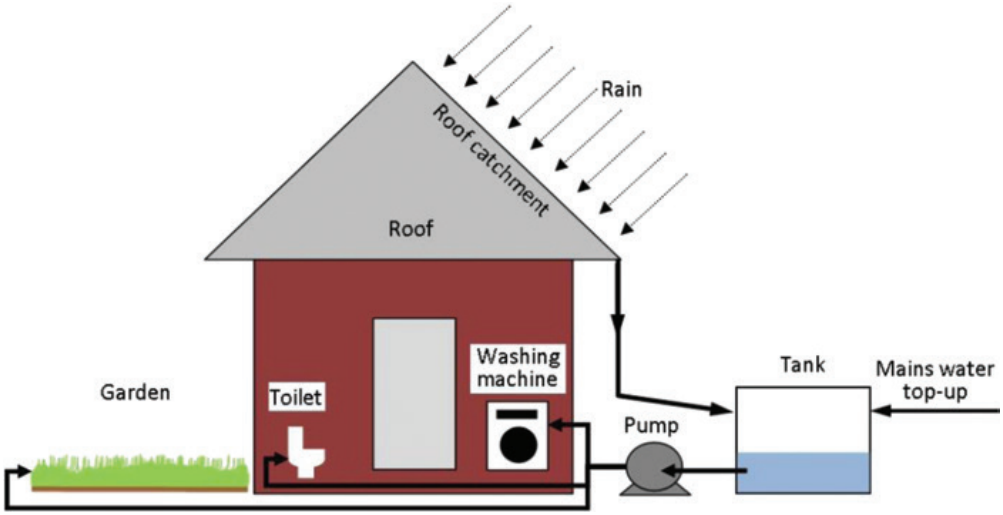


Figure 4.2 Typical end use connections for household rainwater use.

Household end use connections that receive water supply from the rainwater tank form the demand-end of the system. From a monitoring perspective, information on the water and energy demands for the various end uses can yield many useful insights for designing supply systems suited to unique end use configurations. Characteristics unique to any rainwater supply system, such as energy intensity of the pumps, reliability of the rainwater tank and sizing of collection, storage and pumping accessories, can all be estimated based on end use demand. Toilets, washing machines and garden taps are the most common end uses of rainwater (Figure 4.2). Hot water systems have also been connected in some cases. As there is often minimal or no water treatment requirement for these non-potable end uses, water quality concerns are addressed by limiting rainwater use on a fit-for-purpose basis.

4.4 EXPERIMENTAL APPROACHES

4.4.1 Monitoring methods

In developing an experimental methodology, it is necessary to identify the different water sources (e.g., rainwater and mains water) in the system and the corresponding end uses associated with the water sources. Figure 4.3 depicts a general schematic outline of a simple water and energy monitoring setup in a household setting. As rainwater is collected in the storage tank, the change in volume of water in the tank can be measured using water level sensors. Water flow meters monitor supply from the rainwater tank to indoor and outdoor end uses, total mains water supply to the household, and mains water backup to the rainwater tank. An energy meter is installed to measure the energy consumption by the rainwater pump.

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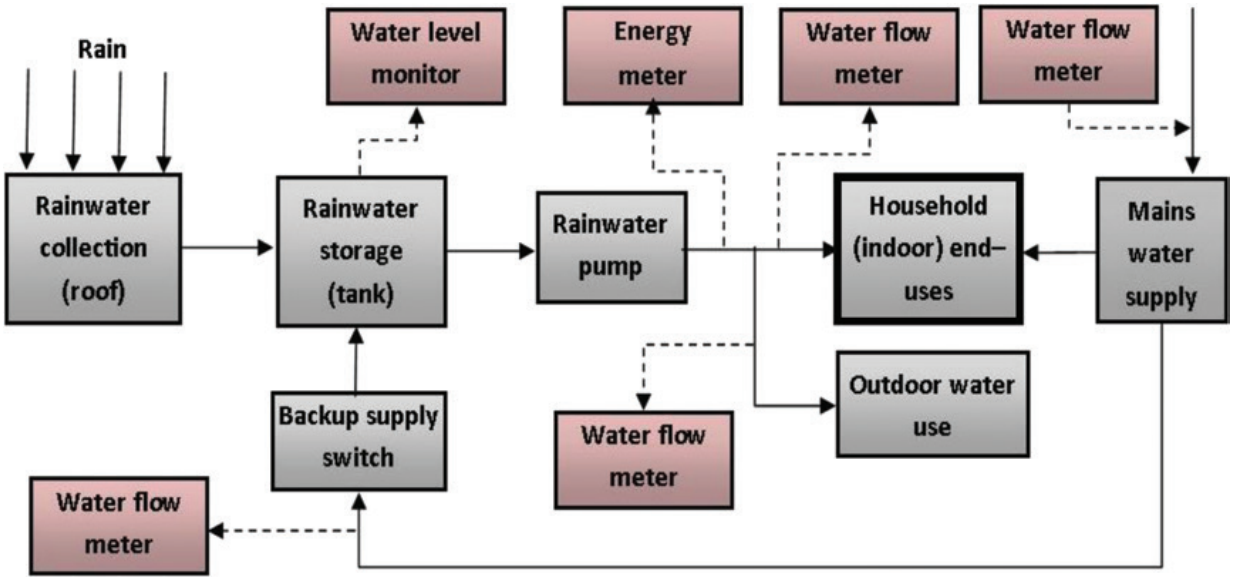


Figure 4.3 Process flow diagram of the water and energy monitoring setup in a typical household rainwater tank.

A data logger continuously records water flow through the meters and this data can be downloaded remotely using wireless connections. Water flow and energy consumption data are generated when water uses such as washing machine, showers or toilet flushing create electrical pulses in the water meter (via a reed switch) that can be logged against time stamps of a pre-determined frequency, for example, every 60 seconds The data collected using meters can vary in resolution (i.e., pulses per litre of flow) based on the specifications of the meters and data loggers. Metering of residential water supply can be tailored to meet the information requirements of researchers and other stakeholders. Case studies based on standard monitoring methodologies are further discussed in later sections.

An alternate method to installing multiple meters is to employ a high resolution meter and high frequency logger that can be used to record water supply from a primary water source (such as mains water supply and/or the rainwater tank supply) wherein the data in the form of high resolution flow traces can be disaggregated for various end uses using available commercial software. More details on this method of analysis can be found in Mayer *et al.* (1999) and Talebpour *et al.* (2011).

4.4.2 Instrumentation

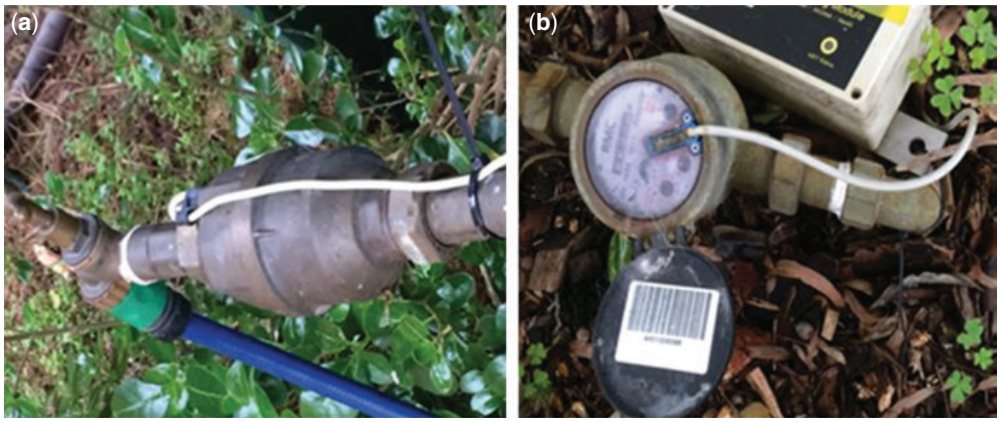
4.4.2.1 Water meter

For a basic monitoring setup, two water meters, one for the mains water inflow (into the tank) and another for total water out of the tank pumping system, are minimum requirements to enable comparisons between rainwater and mains water consumption. The simple setup would also help analyse the impact of rainwater on diurnal water consumption, including volumetric reliability of rainwater supply and percentage contribution to total water usage. For intensive monitoring, additional meters to measure individual end uses (such as different household appliances and garden water taps) can also be installed.

Residential main meters are typically sized at 15, 20 or 25 mm. Rainwater tank connections are either copper pipes or HDPE and these are generally 20 or 25 mm. The best meters to use are positive

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displacement meters (Figure 4.4), which function by water flowing into compartments of a known volume, which continuously fill and empty, turning the counter wheel as they move. As the counter rotates it causes a reed switch to open or close, which generates a low voltage pulse. The pulse ratio varies with the make and size of the meter ranging from 1 pulse per 0.5 litre to 1 pulse per 5 litres depending on the model of meter. For most rainwater tank and domestic use studies, 20 mm pipe diameter, 0.5 L/pulse meters are preferred for their greater accuracy in measuring the low flow rates of most domestic end uses.



Meter type	Positive displacement (A)	Rotary piston measurement (B)
Description	Water flows into compartments of a known volume, which continuously fills and empties	Rotary piston measurement
Size range	15 mm- 40 mm	15 mm-25 mm
Pulse	0.5 to 5 L/pulse	0.014 L/pulse
Minimum flow detection	0.048 L/min - 0.6 L/min	0.25 L/min - 0.6 L/min

Figure 4.4 Flow meters used to measure residential water flow (for demonstration purposes only).

Higher resolution meters (Figure 4.4), such as rotary piston measurement type meters, can be used to achieve greater resolution of data. This is required where a single flow meter is used to measure and estimate (by signal deconvolution) consumption of different downstream end uses. Pulse ratios in these high resolution meters can be as low as 0.014 L/pulse and are usually used in studies in conjunction with the flow trace software such as Trace Wizard (Mayer *et al.* 1996) to determine water end use characteristics (see Talebpour *et al.* (2011).

4.4.2.2 Electricity meter

In addition to water flow monitoring, rainwater pumping energy can be monitored at a small cost. Desktop studies have typically shown between 0.9 and 2.3 kWh/kL of energy intensity for rainwater use, a much lower range compared to in-situ studies in Australia which showed anywhere between 0.4 kWh/kL to 11 kWh/kL (Tjandraatmadja *et al.* 2012). Electricity meters used for domestic metering by some of the notable electricity generating companies in Australia such as Energy Australia, measure root mean square (RMS) power to accurately gauge true power consumption. They emit a pulse for each Watt-hour used and are able to capture quiescent loads. They are rated at +/–1% accuracy, which is standard industry practice for single phase meters.

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Figure 4.5 shows an electric meter, which is a direct connect, single phase, static Watt-hour meter used to measure electrical energy. It delivers a pulse for each Watt-hour that passes through, which is recorded by a data logger (refer Figure 4.6). Measuring instruments of various makes/types are available in the market. Users are advised to thoroughly investigate these instruments based on their needs. For a tank monitoring setup, standard residential electricity meters (Figure 4.5) with pulse output capability have been modified by adding an inlet and outlet power cord, and a cable for the pulse outputs. The meters are usually modified to ensure the units are waterproof, and are made electrically safe for residential use by sealing the rear terminal connectors, and checking and tagging before deployment in a residency. It is important that the rainwater pumps being monitored are 'plug-ins' into power outlets and not hard-wired into the domestic power circuit, thereby avoiding the need for an electrician to visit each site. This power connection set-up needs to be confirmed during the household recruitment process.



Figure 4.5 Electricity meter attached to data logger setup (for demonstration purposes only).



Figure 4.6 Remote terminal data logger (for demonstration purposes only).

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4.4.2.3 Data logger

Data loggers are essential to record the measured electrical pulses over a given time period or frequency. A basic monitoring setup consists of a four-channel data logger, which is set up with a subscriber identification module (SIM) card and batteries with easy connectivity to a power outlet. The reed switches generating pulse outputs from the water and electricity meters are wired to the switch closure input channel of the data logger. Additional loggers may be required if the flow meters are located too far apart (due to signal interference and /or decay) to be wired to one logger. Raw data can be retrieved directly from the loggers or converted to engineering units of litres (for flow meters) and Watt-hours (for energy meters) before or after download from the logger. The units of data will be cumulative litres, or Watt-hours, in each monitoring interval.

On-site data loggers can be accessed either on-site or remotely downloaded. Remote logging is necessary for the studies where access to the study site is challenging due to issues of privacy, remote site location, household access difficulties or guard dogs and so on.

Remote logging equipment is favoured for intensive (e.g., every 30 second interval) data collection studies to ensure logger memory capacity is not exceeded and the ability to remotely detect any failure in the data logging system. Two types of remote metering data loggers have commonly been used for these studies in Australia. One type of data logger transmits the collected water meter pulse data by radio frequency to a hub, which can then be accessed via the phone line for data downloads. These smaller units need to have a clear line of radio communication to the hub, meaning that they need to be in fairly close proximity (less than 1 km) and have a clear line of sight to the hub. Loggers can be either individual or multichannel units based on the number of input channels (i.e., sensors) they need to monitor. Data loggers have finite internal memories (quantities of bytes), hence data flow rates and data duration of the samples being measured must be taken into consideration when choosing the combination of internal storage capacity and download frequency.

Other types of data logging systems use an inbuilt mobile phone transmitter which requires a unique SIM card supplied by a mobile phone network carrier/provider (Figure 4.6). These units can be located anywhere in the surrounding area that has a strong mobile phone signal, and are able to download data to remote servers on a regular basis, either daily or more frequently depending on the battery life and study requirements. They use a low voltage circuitry, so a unit transmitting twice a day is capable of remaining in the field for five years or more without a change in batteries. There are several brands of data loggers available which are capable of monitoring 1, 2, 4, 8 or 16 meters. Some can be mains powered while others can be battery charged by a solar panel for longer deployment periods. Users should investigate available loggers in the market based on their needs. The data logger shown in Figure 4.6 connects to sensors in the field and collects pulse outputs from water meters and electricity meters and transmits the data via a GPRS/CDMA/3G mobile telecommunications network to a central server at pre-set intervals. The data is then viewed on the internet and can be manipulated and analysed. Water and energy data are collected in 1 minute intervals.

4.4.2.4 Rainfall measuring devices

Rainfall data is an essential part of the monitoring system. It can be obtained from a local weather station but more usually is measured on site using a tipping bucket rain gauge or pluviometer (Figure 4.7). This type of rain gauge consists of a collection funnel of standard diameter (e.g., 200 mm) which directs collected rainwater to a small 'tipping bucket' that tips to alternating sides with every pre-set amount of precipitation, which in turn generates a pulse output signal from a reed switch similar to that of the water meters. These pulses are countered and recorded by the data logger, which can be inbuilt as part of the rain gauge (Figure 4.7).

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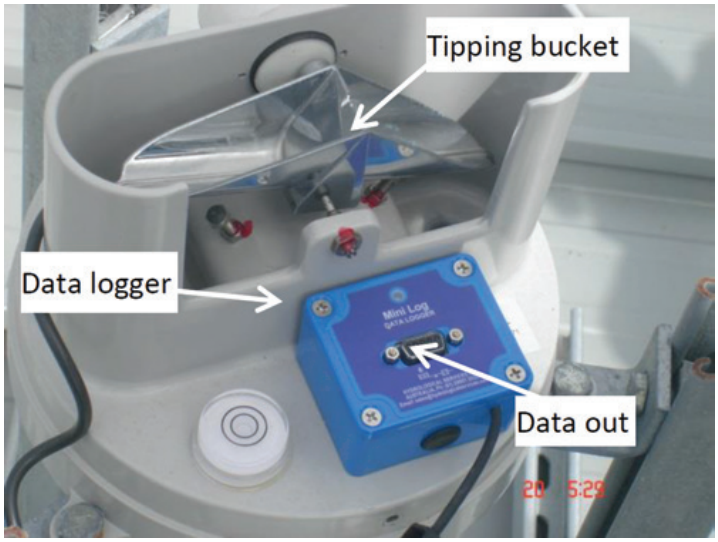


Figure 4.7 The internal tipping bucket and data logger of a typical pluviometer (for demonstration purposes only).

Monitoring studies can also comprise rain gauge stations in order to obtain localised rainfall for individual buildings; however, it is recommended that the gauges are located away from areas that are likely to collect dust and debris (such as rooftops), which may cause disturbances to the data being logged. A typical rain gauge station used in monitoring studies is programmed to record data for every 2 mm of rainfall, which is equivalent to ten pulses by the tipping bucket. A cylinder of standard diameter (200 mm) goes around this *chassis* to funnel rainfall into the tipping buckets. Sub-hourly data from rain gauges can be used to supplement daily metrological data that is usually available at a detailed spatial scale for most cities in Australia. Temperature measurements may also be useful to study evaporative effects of roof materials on the volume of rainfall collected.

4.4.2.5 Other monitoring equipment

Water level monitoring in tanks is very useful to compare rainfall (in millimetres) with tank catch (in litres). Continuous monitoring of water levels within rainwater tanks often use a hydrostatic pressure monitor that have submersible, differential pressure transducers. These are available with inbuilt data loggers and generally require manual downloads.

Differential pressure sensors measure the pressure difference between the reference location of the sensor submersed in the tank and the outside atmospheric pressure. One side of the differential pressure unit is exposed to the air through a vent tube exiting the top of the tank. The other side is in contact with the water in the tank. Differential pressure monitoring is a convenient method to monitor rainwater tank levels and requires little to no processing before data display and analysis.

Absolute pressure sensors, on the other hand, are generally housed in a submersible casing and measure the pressure (and in some cases the temperature) at the sensor suspension reference point in the tank. However, due to the absence of venting tubes, they do not measure the changes in atmospheric pressure. Hence, an atmospheric reference sensor of the same configuration needs to be suspended in the air above the water surface to allow correction for day-to-day variation in atmospheric pressure. Figure 4.8 shows a typical absolute pressure sensor setup configured to download data to a computer. The pressure sensor is

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connected to a base station through a *magnetic coupler* which enables the downloading of data through an infra-red sensor. The software used is a propriety product of the logger manufacturer.

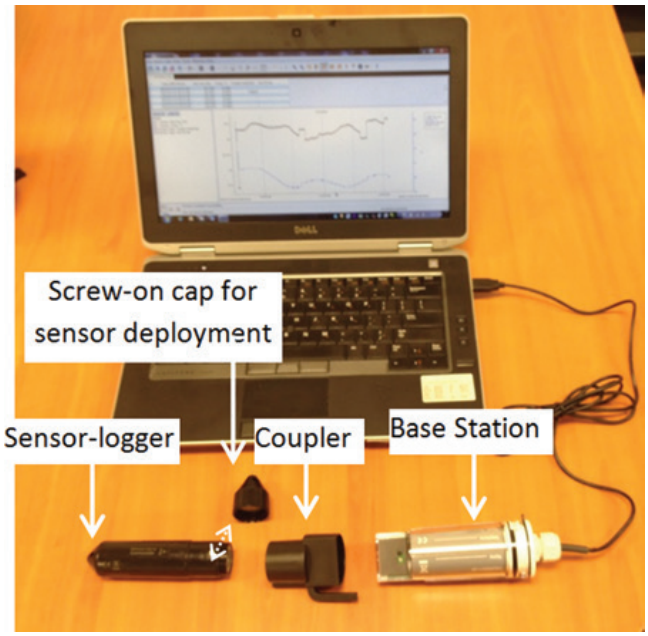


Figure 4.8 An absolute pressure sensor setup to download data to a laptop computer. The sensor has been retrieved from the rainwater tank (for demonstration purposes only).

A capacitance water level sensor and data logger (Figure 4.9) uses the varying potential between two concentric plates within the logger to determine the depth of water in the tank. The levels are recorded every 15 minutes and stored in the data logger until the data can be downloaded to a computer. Capacitance water level sensors are applicable to both absolute and differential type pressure sensors. Users should investigate the suitability of the commercially available sensors based on their needs. The water level sensors were not used in the case studies described in this chapter, however Moglia *et al.* (2014) used these sensors for rainwater tank water level monitoring in Melbourne.

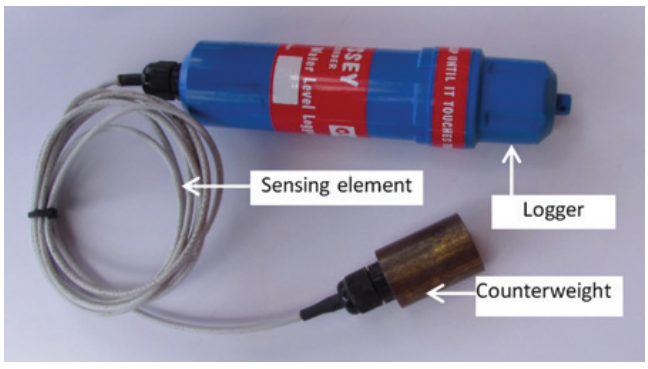


Figure 4.9 A capacitance water level sensor (for demonstration purposes only).

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4.4.2.6 Protective casing

Outdoor monitoring equipment must be well protected from possible environmental damage. Equipment can be encased in a protective enclosures or casing to shield from weather damage caused due to rainfall, humidity, dust, extreme temperatures and from direct sunlight. Ideally, all equipment that is susceptible to weather damage should have an Ingress Protection (IP) rating (IEC, 2004). Equipment specifications should be consulted when deciding the level of protection required ensuring safe operating conditions are provided.

Disruptions in data logging have been observed in the past as a result of accidental damage to the wiring, hence data monitoring equipment should preferably be placed away from common reach. Metering and logging equipment malfunction due to accidental or environmental damage could also be a contributing factor towards discrepancies in logged data. Enclosing equipment casing in waterproof bags can also provide added protection.

4.4.2.7 Recent developments in monitoring instrumentation

An advanced real-time water and energy monitoring system has been set up to study the water usage in an urban development (Lochiel Park) in South Australia (Whaley *et al.* 2010). The houses and apartments (total of 106) in the development are designed to receive their water supply from three sources (mains, rainwater and recycled stormwater). All connected water sources in the development are being monitored at medium (1-minute) to high (5-second time intervals) resolution, with a pulse ratio of 1 litre per pulse. The digital outputs from each sensor are connected to an in-home touch screen display (EcoVision) (Ecovision Systems, 2014).

This is a part of a detailed monitoring system consisting of various analogue (rain tank level, temperature, relative humidity) and digital (water use, electricity use, gas and photovoltaic) sensors (Whaley *et al.* 2010). The EcoVision display unit (Figure 4.10) allows homeowners to monitor their water consumption in real time, together with electricity and gas usage. This feedback information is highly beneficial in aiding consumer self-management of their energy and water use, including detection of leaks within their water supply plumbing.



Figure 4.10 Screenshot of the in-home 'EcoVision' display screen (for demonstration purposes only).

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A system such as the Ecovision system is very sophisticated and requires installation by qualified plumbers and electricians.

4.4.3 Sample number and ethics approval

For research purposes, a statistically representative sample sizes is required to ensure that population error is within acceptable limits of precision. The number of participants required to represent the behaviour of an area's entire population of rainwater tanks owners can be estimated using Equation 4.1.

$$n \geq \frac{\left(\frac{1}{\varepsilon^2}\right)N}{\frac{1}{\varepsilon^2} + N} \tag{4.1}$$

where, n is the sample size, N is the population size, and ε is the sample error expressed as a fraction of the mean value and can be chosen as anywhere between 0.01 and 0.2 (Chowdhury, 2013; Ghisi & Ferreira, 2007). In this case, the population size 'N' is the number of households with rainwater tanks in a local council area and 'n' is number of households required to achieve representative monitoring.

An important aspect of participant recruitment for research activities involves adhering to the appropriate research conduct guidelines, including obtaining necessary ethics approvals from the concerned research ethics committees or similar bodies. Methods adopted for participant recruitment may differ between organisations and institutions and from country to country, as will ethics code requirements for recruiting the participants. A letter of offer detailing the monitoring procedures, together with a concise description of research outcomes that are expected from the study, and any related ethics code consideration should be provided to prospective participants. In order to be accepted, participants are required to acknowledge to the letter of offer granting approval for the proposed monitoring/audit activities.

Initial involvement of the participants is necessary during the planning of equipment installation. However, participation cooperation may also be required during later stages in case of the need of replacing failed sensors and so on. Participation incentives such as gift vouchers can be considered if required.

4.4.4 Site inspections and audits

On-site activities involving monitoring equipment are not confined to setting up meters and loggers. Necessary inspections of the rainwater tank system and other attributes that are external, but related to the system, such as the rainwater pumping system, building setup, tank connections, rainwater catchment areas, and associated end uses (appliances and fixtures) need to be audited to gain a better understanding of the system. This in turn helps tailoring the monitoring setup for each specific household. Detail on household rainwater tank audits is presented in Chapter 5.

4.4.5 Correlation with weather and seasonal patterns

Monitoring studies of household rainwater use and yield can be correlated to the local rainfall in 'case study' areas. Previous research on household water consumption (including those with a focus on rainwater tanks) have treated rainfall as a homogenous entity over the study area (Khastagir & Jayasuriya, 2010). Monitored households with rainwater tanks are generally distributed over a suburb or a township, and may often have different rainfall patterns. Weather and rainfall data from the nearest weather station can be acquired from organisations such as the Bureau of Metrology in Australia (www.bom.gov.au).

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Studies in Australia can also access rainfall data from an enhanced climate database, SILO, hosted by the Science Delivery Division of the Department of Science, Information Technology, Innovation and the Arts (DSITIA, 2013) which contains Australian climate data from 1889 in various formats that are suitable for research.

4.4.6 Monitoring duration and intervals

Determining the best time-step for continuous monitoring is directly associated with the objectives of the monitoring study. Monitoring at very short time-steps or intervals (i.e., 1 second) will provide the most detailed outcome but data management and analysis of this fine grained data can become very difficult over long monitoring periods.

For studies that focus mainly on the supply aspect of rainwater usage in households, time-steps up to 1-minute data intervals is satisfactory. Time-steps of longer than 1 minute will limit the user's efficiency to cleanse the data.

Smaller time-steps may improve end use analysis for high flow rate water use events, but the resulting large data files may be very difficult to manipulate over longer monitoring periods. Table 4.1 summarises the limitations associated with the duration of monitoring-based analyses.

Table 4.1 Data monitoring frequency and Limitations of data interpretation.

Monitoring period	Limitations
>1 yearly basis	Change in ownership or household population confound results
Yearly	As above + Annual rainfall difference
Half-yearly (6 months)	All the above + Seasonal differences in water use
Monthly	All the above + Effect of rainfall/dryness + Public holidays, school holidays, Christmas effects
Weekly	All the above + Weather effect (e.g., hot week) + Data loss
Daily	All the above + Weekend vs weekday effects
Sub-daily	All the above + End user effects + Impact of fixtures and appliances

Demand distribution at annual intervals may be influenced by water saving schemes or legislation affecting water consumption in households. Demand distribution measured at monthly intervals can provide information on seasonal effects such as rainfall, temperature and household usage patterns, including use of gardening equipment, swimming pools, frequency of showers and so on. Intensive monitoring (small intervals) for short periods (such as 2 weeks) during each season can provide insights into water use behaviour and rainfall yield if costs of continuous long-term monitoring are not affordable. This approach is often used in detailed end use studies that analyse water use signal data (using software tools such as Trace Wizard) to disaggregate the data from one water meter into the multiple end uses (Nguyen *et al.* 2013).

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4.5 DATA MANAGEMENT

Data loggers are installed on-site to store information collected by the water flow meters. Recorded data files can be retrieved by wireless telemetry at a time frequency determined by study requirements. The instrumentation can include mains water, rainwater, mains top-up supply, rainwater end uses and energy consumption data. Initially collected data should be checked at short intervals (i.e., weekly) to ensure correct functioning of the meters and loggers. In order to avoid long-term system malfunctions, data loggers can be equipped with alarms that report when no water flow is recorded for a specified time period. This enables early intervention of monitoring equipment malfunction before any significant loss in data occurs.

There are possibilities for loggers to be accidentally disconnected post installation. During case studies conducted in SEQ and Sydney by Umapathi *et al.* (2012) and Ferguson (2011) respectively, loggers were found disconnected due to cut wires and other types of circuit breakage. In some cases, loggers malfunctioned or were damaged by water penetration, and required replacement. It is highly recommended that regular on-going review of data should be undertaken to ensure the proper functioning of monitoring instruments.

Data management and processing is critical if monitoring data are to be used effectively. The type of monitoring undertaken, whether periodic or continuous, will affect the protocol for data management. Loggers can aggregate recorded data over a specified period for recording purposes based on the study needs and format.

4.5.1 Data cleansing and validation

Data 'cleansing' is the most time consuming part of data analysis. As problems inevitably occur over time, collection of high quality data requires constant tracking of the loggers' performance. Data from continuous monitoring will require a large amount of cleaning before any analysis. This is due to a number of factors discussed below.

Some perceived discrepancies in data may be more apparent than real. For example, changes can occur in water consumption patterns within individual premises due to the absence of occupants over some part of the monitoring period. Change in ownership or occupant numbers may also change the pattern of water consumption due to varying water use habits/demand.

Although remote monitoring is a convenient and reliable method for assessing the performance of rainwater tanks, regular visual and logical cleansing of data is essential for reliable results. In some previous case studies (Ferguson, 2011; Umapathi *et al.* 2012), one-minute water flows and energy consumption data logged for each home were reviewed for discrepancies and validated. Collected records were checked for accurate data, consistency, range and format by both manual screening or program codes of which, one of the most accessible and easily programmable is the 'macros'/VBA function in Microsoft Excel®.

A reliable method to check the validity of monitoring outcomes is by collating and comparing all recorded data into simple graphical outputs using a daily time-step, a short period (i.e., 15 minute) time-step, and a high resolution time-step (i.e., 1 minute). Smoothing of data may eliminate noise in the data series. Removal of a recurring peak water use identified as a water leak is an example of data smoothing. Elimination of selective recorded data to achieve a smoothing effect for effective data comparison is termed as 'binning' (Fane *et al.* 2011). Binning helps address minor discrepancies in the data, sometimes through replacement with representative values without causing significant changes to the overall outcome of future data analyses.

Comparing water use across the graphical outputs with different time bases can help detect ambiguities in the data. In addition, the ability to compare mains water and rainwater uses is critical in identifying underlying changes to water use patterns, such as identifying and differentiating between homeowners on

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holiday vs. pump faults. A data preparation process needs to be carried out using reliable data analysis software as large and comprehensive data sets need to be organised and assessed following the data validation process.

4.5.2 Data analysis

A clear understanding and visualisation of monitored data prior to data analysis is important. There are various methods that can be used for analysis. A commonly used method is water balance analysis.

Water balance analyses are conducted on a basic mass balance principle where water flows within a residential development are measured at the entry and exit points to determine consistency of total water use. The energy consumption by rainwater pumps can also be recorded and assessed to determine the corresponding energy efficiency (i.e., kWh/kL) of the system. Monitoring studies can be used to evaluate the accuracy of residential efficiency programs by matching the detailed monitored data with consumption data from water billing agencies to check for data reliability (Umapathi *et al.* 2012) using cross-sectional analysis.

For more detailed analyses, household appliances such as washing machines can be assessed for their unique water consumption patterns. In such cases, their distinct usage cycles can be obtained from the manufacturer (Aravinthan *et al.* 2012). Knowing the typical water flow rates of toilet flushes and taps is also helpful in assigning water flow patterns to the related end uses. The following sections discuss the data analysis methodologies and outcomes of two Australian case studies that investigated water supply and use from rainwater tanks in South East Queensland and Sydney.

4.6 CASE STUDY 1: RAINWATER TANK MONITORING, SOUTH EAST QUEENSLAND, AUSTRALIA

The study focussed on validating the expected reduction of 70 kilolitre/household/year (kL/hh/yr) in potable water consumption in newly build households with internally plumbed rainwater tanks in South East Queensland. They were constructed under the requirements of the Queensland Development Code MP 4.2, which is detailed in Chapter 5.

The water flow data from 20 such households were recorded over a period of 12 months to assess the rainwater systems for their volumetric reliabilities and to determine their water use profiles. Monitoring a sample size sufficiently large to represent the South East Queensland region would have been too expensive because of the high cost in installing monitoring equipment and remote data transfer. Hence, this study can be considered as a pilot project to provide finer grained detail on the water savings estimated from billing data methods (see Chapter 3).

Monitoring data was initially collected at four instalments over a period of two months on a fortnightly basis, followed by monthly intervals (Umapathi *et al.* 2012) to ensure the system was working effectively before the collected data was analysed. The instrumentation setup (Figure 4.11) recorded water flows associated with the rainwater system in individual households including: (1) mains water supply; (2) tank top-up from mains water supply; (3) total water flow out of the rainwater tank; and (4) water supply to the external garden tap. All monitored water flows were measured using water flow meters that had a pulse ratio of 0.5 L/pulse. The mains water meters, installed by the water utility, were configured at 5 L/pulse. Each monitored household also had energy meters installed to record the energy consumption by the rainwater pumps. The system generated 1 pulse per watt-hour. The water flow and energy consumption data were recorded in 1-minute time intervals. Recorded data was retrieved on a monthly basis using wirelessly enabled data loggers.

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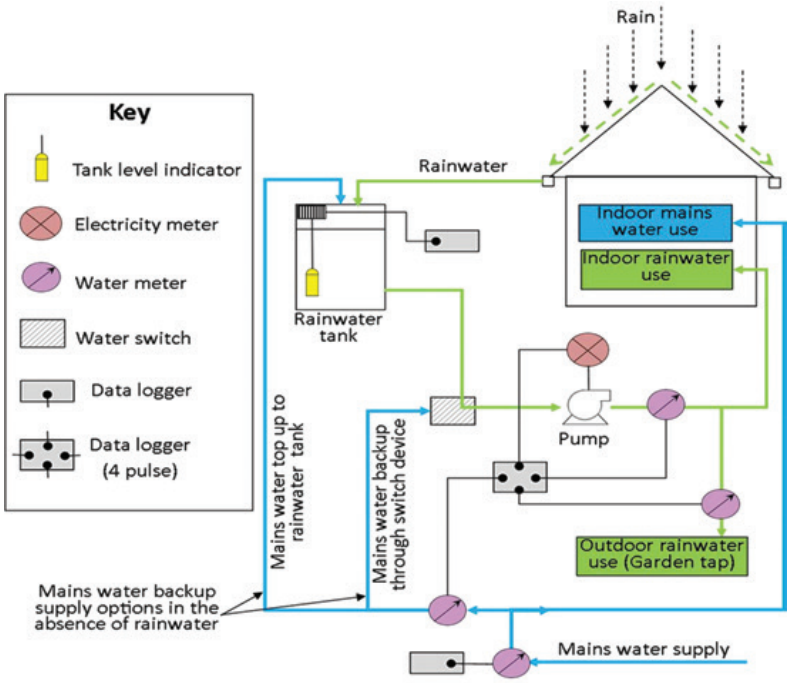


Figure 4.11 Schematic of the metering and logging system setup at 20 households with rainwater tanks in South East Queensland.

The monitored data for each household was assessed for mains water usage, mains water savings as a result of rainwater consumption, rainwater backup required in the absence of rainwater, household rainwater consumption (internal and external), and energy consumption by the rainwater pumps (Umapathi *et al.* 2012, Umapathi *et al.* 2013). The study also examined diurnal pattern and peak water demand analysis wherein the water use data for the initial 4-month period was converted to visual diurnal demand patterns. Hourly demand patterns were also generated to obtain average household water use behaviour for the 20-home cluster. The energy use monitoring also allowed measurement of the two types of top-up systems used in the 20 households, that is, the trickle top-up type (requiring pumping water from the rainwater tank) and the switching device type (which continuously consumed electricity, but result in mains water by-passing the tank). These systems are described in Chapter 5.

The study also examined correlations between measured rainfall patterns and the rainwater collected in individual tanks (Umapathi *et al.* 2012).

4.6.1 Data analysis and results

The average rainwater consumption per household (which equates to mains water savings) was 36.1 kL/hh for a total period of the 11 months during which a complete data set was available over the 12-month monitoring period (Umapathi *et al.* 2012). The total water use per household (combination of rainwater and mains water) was 136 kL/hh. Scaling up the data to a 12-month period gave an average rainwater use of 40 kL/hh/yr and a total water demand of 151 kL/hh/yr (Figure 4.12). As shown in Figure 4.12, the rainwater consumption in the households varied between 0.6 to 69 kL/hh/yr and the total water consumption from 50 to 398 kL/hh/yr. The validity of the monitored potable water use data was verified

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through cross-correlation with the water billing records obtained from the local water utility. The correlation coefficient was 0.98.

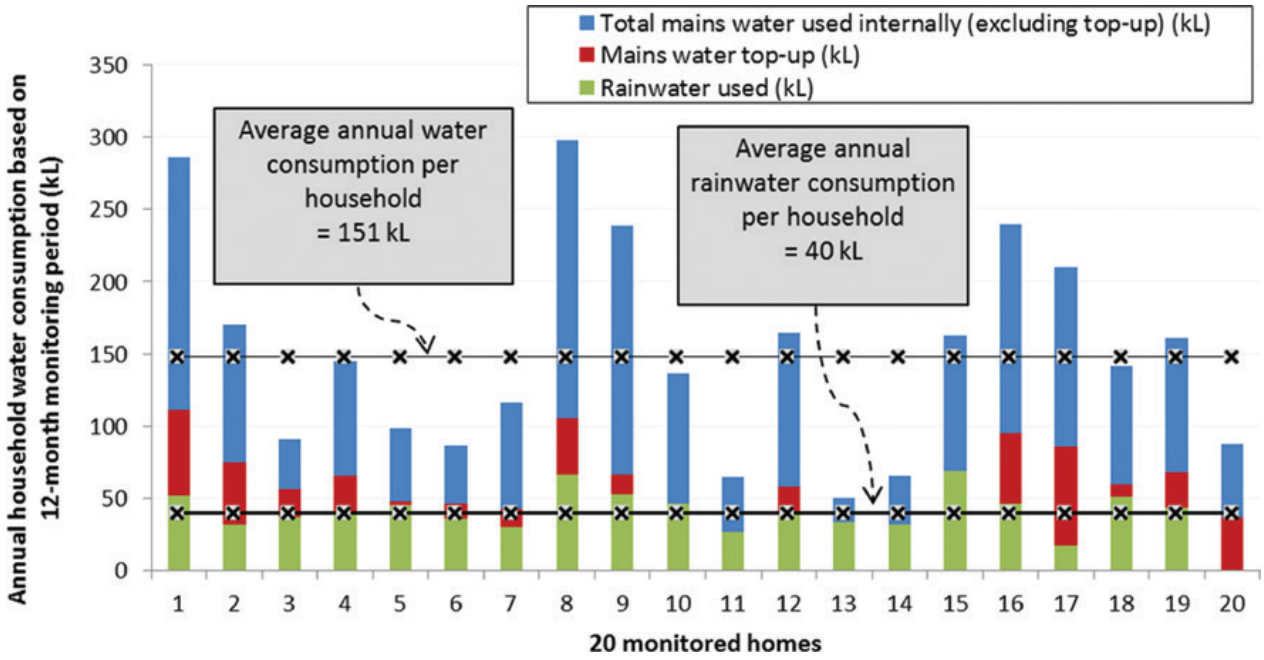


Figure 4.12 Partitioning of the 12 month consumption for 20 monitored homes in SEQ. Data includes total potable, total rainwater, and mains top-up to the tanks. Source: (Umapathi *et al.* 2012).

The results obtained are in contrast with findings from desktop studies (Chong *et al.* 2011) of 691 households using rainwater tanks under very similar circumstances in South East Queensland, which identified an average annual mains water saving of 58 kL/hh/yr and 59 kL/hh/yr for 2009 and 2010 respectively. It may be due to the small sample size of 20 homes. Although the study represented a smaller sample, the results obtained gave a better indication of the various factors that can be involved in influencing the water consumption patterns in everyday households. These factors were: differences in per capita water usage; effects of locally imposed water use restrictions; differences in external water use (irrigation) habits; and variations in local rainfall which varied substantially between households that were located only a few kilometres apart.

The rainwater supply as a percentage of total household water demand for 20 homes is shown in Figure 4.13. The average overall rainwater supply based on the 20 households was 31% and the contribution of rainwater top-up (backup supply) was 14% of total household water usage (Umapathi *et al.* 2012). The results suggests that physical factors such as rooftop collection areas and rainwater tank sizes have a direct impact on the mains water offset, and hence the rainwater reliability of the rainwater in the system. The rainwater tank system could be better designed to reduce backup supply (from 14% of total demand) by either increasing the tank sizes, or the rainwater catchment areas, or a combination of both.

Figure 4.14 depicts the household rainwater demand on the tank for intended use and the corresponding supply of rainwater from the tank. Household rainwater tank systems on, or close to, the optimum demand-supply line demonstrate high volumetric reliability. The rainwater demand was almost completely satisfied by rainwater supply in 6 households as shown by their proximity to the water demand-supply

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line in Figure 4.14 also corresponding to very low mains water top-up for these households, as shown in Figure 4.12. The homes farthest from the optimum demand-supply line were the least rainwater sufficient.

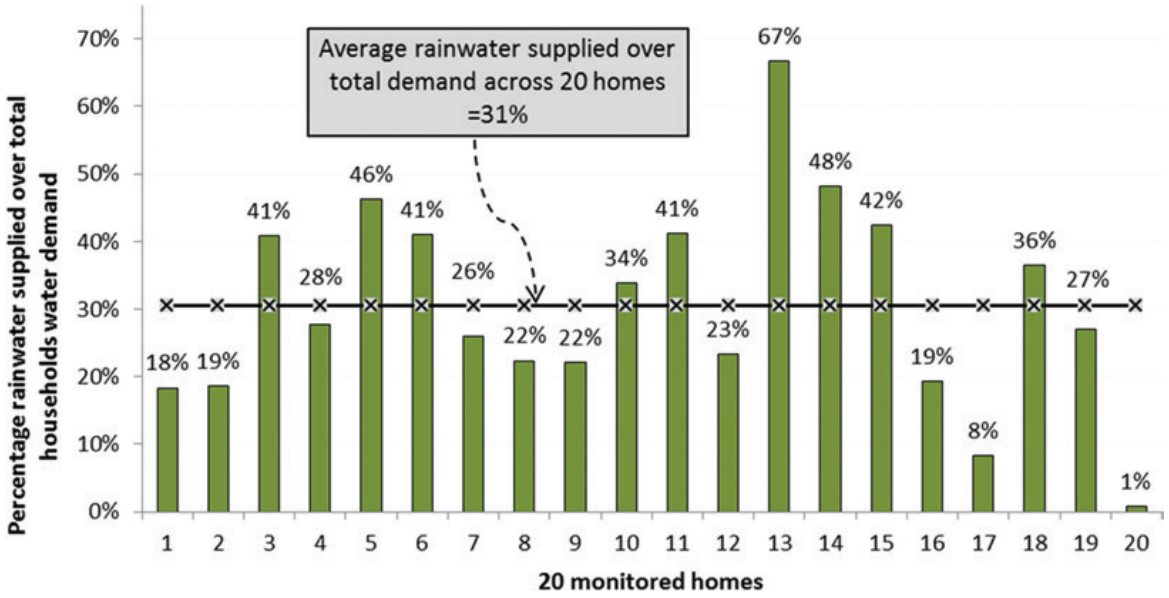


Figure 4.13 Rainwater reliability of rainwater tank systems at 20 monitored homes.

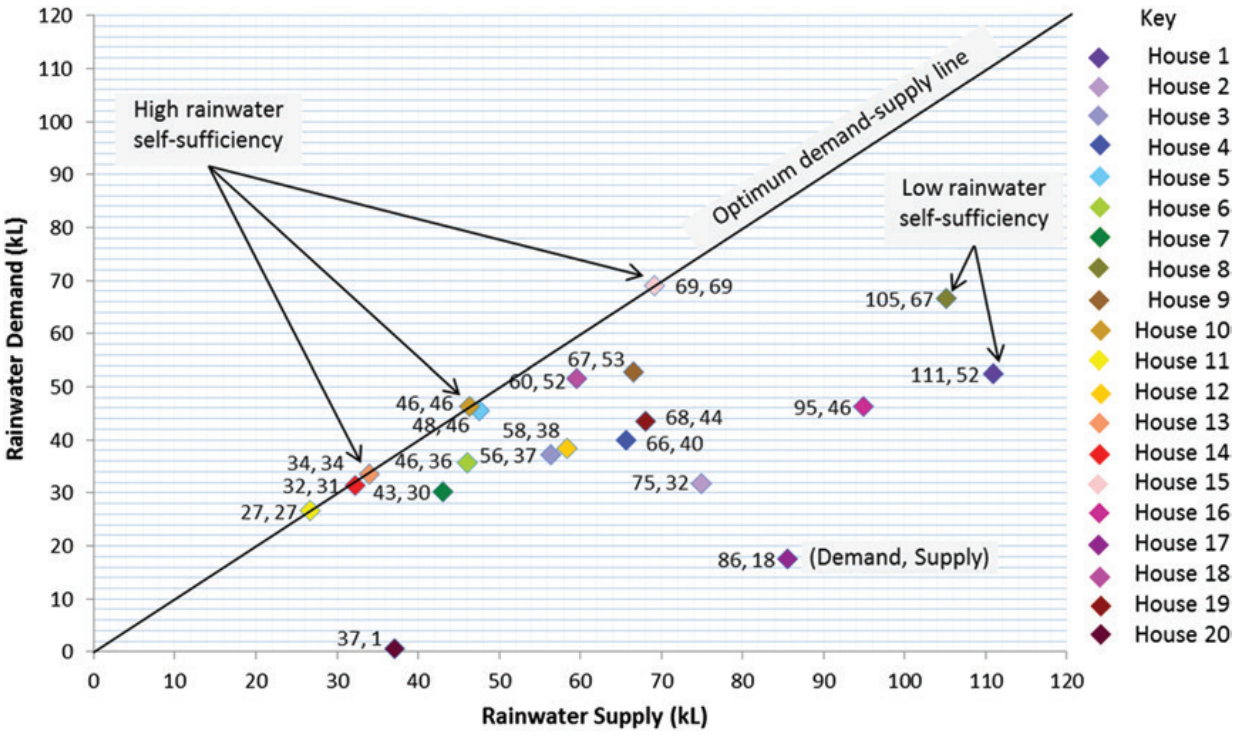


Figure 4.14 Rainwater demand and rainwater supply of 20 households.

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Figure 4.15 shows the hourly diurnal water demand pattern for one of the 20 studied households using data recorded over a 4-month period. The graph shows the average hourly water demand of 29.1 L/day, with average peak water usage of 61.4 L/day. The peaking water use factor (ratio of average peak demand divided by average hourly demand) is 2.1, which is low compared to the peak factor of 5 suggested for the design of water supply network systems for developments with a population below 2000 (Swamee & Sharma, 2008). This may be due to a very low external water demand for garden irrigation recorded during the study period. Figure 4.15 also shows the diurnal pattern water supplied from the mains for top-up to the rain tank (MIRW), and the water supply from rainwater tank (TRW).

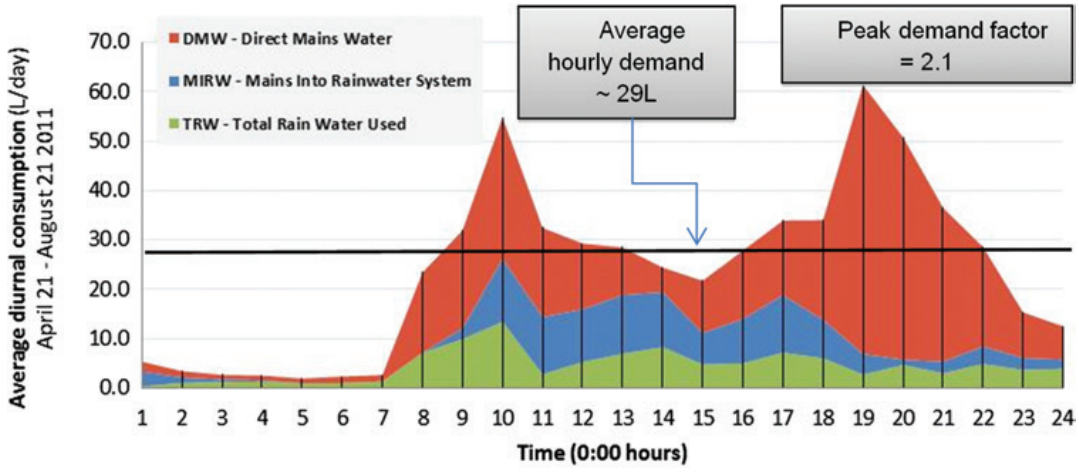


Figure 4.15 Diurnal water use pattern averaged over 4 months for one of the 20 households in the South East Queensland monitoring study.

On the energy front, the average specific energy (SE) for the pumping systems at 19 homes was 1.52 kWh/kL (one home was omitted due to a faulty pump). The average SE for homes with trickle top-up system was slightly higher than those with automatic switching devices, at 1.59 kWh/kL and 1.46 kWh/kL respectively. In the case of the trickle top-up systems, the total water (rainwater + mains water top-up) supplied from the tank would require pumping. In comparison, other alternative potable water supplies such as indirect potable reuse require more than 2.8 kWh/kL and energy required to make freshwater from seawater by desalination is around 3.5 kWh/kL. Thus, rainwater is the least energy intensive alternative water source compared to desalination and indirect potable reuse. Traditional potable water supply from catchment reservoirs, which is often gravity assisted, is less energy intensive than rainwater supply, requiring less than 0.9 kWh/kL (Tjandraatmadja, 2012).

Further information on the performance of pumping systems and the energy use associated with rainwater tank systems is detailed in Chapter 6.

4.7 CASE STUDY 2: SYDNEY WATER, SYDNEY, NEW SOUTH WALES, AUSTRALIA

The New South Wales Government introduced BASIX (the Building Sustainability Index) policy in 2004, which required all single and multi-unit residential buildings to be designed to use less potable water and emit fewer greenhouse gases (NSW Department of Planning, 2008). BASIX set the reduction targets at

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40% less for potable water use and 40% fewer greenhouse gas emissions than the average NSW dwelling (Ferguson, 2011). The main objective of the 12-month study conducted by Sydney Water in 2011 was to confirm the water savings being achieved for 52 newly built BASIX compliant households spread broadly across the Sydney basin to capture the variation in climatic range (Ferguson, 2011). The study also aimed at identifying opportunities for improving the water saving capacity and reducing the pumping energy use at the rainwater tank.

The metering arrangement was setup to monitor: 1) the water supply from the rainwater system for connected non-potable end uses; 2) mains water demand for the top-up system; and 3) total mains water use in the household (including top-up), and energy demand from the rainwater tank pumping system. The instrumentation setup was similar to that shown in Figure 4.11. The monitoring set-up used in this study was adopted in the South East Queensland study by Umapathi *et al.* (2013), which additionally monitored the external water use for garden irrigation. All water flow data were logged in one-minute intervals using meters that generated 0.5 L/pulse.

4.7.1 Data analysis and results

Using a sample size of 40 detached households out of 52 monitored homes, Ferguson (2011) found that the total household water demand ranged from 84 to 556 kL/yr, with a mean demand of 197 kL/yr. These results were shown to coincide closely with the potable demands for new homes built under BASIX regulations. The water demand from the rain tanks ranged from 5 to 161 kL/year with a mean demand of 59 kL/yr.

The water savings achieved from rainwater use in 46 households with complete data ranged from 0 to 96 kL/yr (Figure 4.16), with a mean savings of 38 kL/yr (median of 39 kL/yr). Hence, although the demand for water from the rainwater tank was on average of 30% of the total household water demand, only 19% was met by rainwater from the tanks. The difference was supplied by mains water top-up.

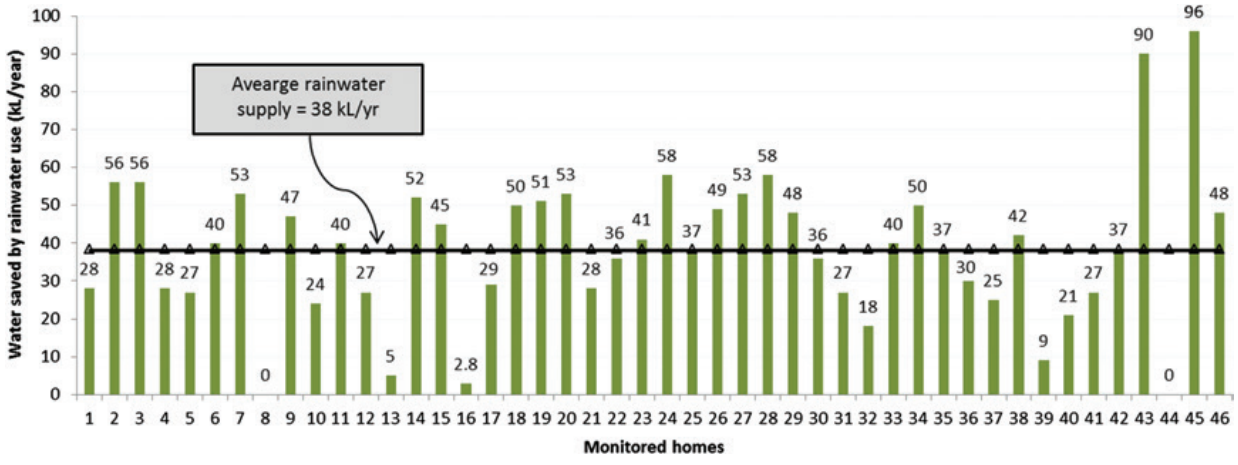


Figure 4.16 Water savings from rainwater tanks in 46 monitored households in the Sydney study.

The study found that the connected roof area (rain catchment area) has a major impact on the volumes of rainwater collected in the tanks. A case study on a single home with a 5 kL rainwater tank and 140 m^2 of connected roof area found that the demand for rainwater was 161 kL/yr out of a total household demand of 556 kL/yr (Ferguson, 2011). Modelling using household specific data with local rainfall showed that

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the water savings (i.e., rainwater yield) could be increased by 12 kL to 81 kL/year by increasing the roof collection area to 210 m^2.

Modelling assessment of another single household indicated the underperformance of the rainwater tank system that achieved a savings of 28 kL per year, compared with a potential of 45 kL per year. This could be attributed to an unusually high cut-in level in the tank for activation of the backup system, thus leaving less capacity in tank for captured rainwater. Hence, notwithstanding the system having adequate roof catchment area and storage capacity, there is a need to have a clear understanding of settings for the other system components which are determined at the time of tank installation.

The 12-month study period also allowed researchers to assess the seasonality of water use in the households. Water demand for indoor end uses such as toilets and washing machines was found to be constant throughout the year in contrast to outdoor end uses that showed seasonal fluctuations (water demand was higher in summer season than the winter season). The study also found that the water demand between November 2009 and January 2010 (summer months in Australia) appeared to be met by both potable (mains water) and non-potable (rainwater) water sources.

A major part of the study focussed on linking the water use from the rainwater tank systems with the energy consumed in supplying the assigned end uses. Energy use by rainwater pumps was found to be an average of 78 kWh/hh/yr per household per year, with the median energy intensity of 1.48 kWh/kL. The median active pumping energy (energy used for pumping water only) intensity was 1.42 kWh/kL. The dormant (stand-by) energy use was a negligible 4 kWh/year. Due to the detailed nature of the data obtained, significant uses of dormant energy (up to 8 Wh/minute) were identified in some households which warranted further investigation as they suggest faulty pumps or leaks in the rainwater system.

Results also showed that most household water uses had low flow rates, with over 75% of the household uses being 10 L/minute or less and 50% were 6 L/minute or less. The maximum water flow rates measured ranged from 10 to 22 L/minute. However, some of the installed pumps (more specifically, submersible pumps) were designed for much higher flow rates, which suggest they were oversized for the task and hence used more energy than needed to provide the acceptable level of service.

The majority of water use events were between 4.5 to 9 L per event, which were most likely full-flush toilet events. Flow events between 50 and 90 L accounted for 15% of the demand and were most likely washing machine end uses, whereas large water use events (>99 L) that contributed about 20% of the total demand may have been associated with some (top loading) washing machines and garden uses. The study highlighted the significance of choosing the correct pump capacity (kW) matched to the flow rates of the connected end uses. The study also suggested the positive benefits of connecting large volume, high flow rate end uses, such as garden taps, to rainwater tanks to ensure effective use of tank storage (adequate storage space preceding rainfall events) and efficient pumping operation. These aspects in details are also covered in more detail in Chapter 6.

4.8 OTHER COST CONSIDERATIONS ASSOCIATED WITH MONITORING

Apart from the obvious costs involved in the procurement of monitoring equipment such as loggers, meters, cables and so on, there are some other factors that affect the overall cost of the monitoring, and these should also be considered in the contingencies for planning the study.

Participant recruitment – This can be done by a contractor or the water utility with a mail out to selected properties known to have rainwater tanks. The records of rainwater tanks are varied, depending on the location. In the Australian state of New South Wales (NSW), the Department of Planning holds records on BASIX certification and details on size and end use for rainwater systems. Councils and utilities may also have records of tank installations as a result of rebates.

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Installation scheduling – The installation process requires careful coordination with participant homeowners. Maps are used to determine the location of households, the time required to install equipment, and then the travel time to the next location.

Other factors – Other issues can arise during the installation process which adds to the time and cost of the project, these include:

- *Rescheduling:* Occasional delays in installation of equipment may be expected due to unforeseen circumstances which may prolong installation time periods.
- *Damage or failure of equipment:* Equipment, particularly for mains meter monitoring, can be damaged by vandals, lawn mowers and even cars throughout the project. These faulty units need to be replaced as soon as practicable to maintain dataflow.
- *Mobile phone reception:* Some areas have insufficient mobile phone reception to regularly upload the data, requiring site visits for manual downloads.
- *Inaccessible or inappropriate systems:* There have been cases where the plumbing required to install the meters on the inlets and outlet lines cannot be accessed because the pipes are located within walls or covered by other materials, or the pipe fittings were of a particular material unavailable to the installer. There are about 15 different pipe types (in Australia) with different fittings, which need different crimping tools. In many cases, it was easier to move on to another house than purchase a new set of tools and fittings for just the one installation.

4.9 CONCLUSION

The increasing integration of rainwater tanks and any alternative water supply technologies is expected to have an impact on the future demands of centralised systems. Therefore, the need to validate and assess the influence of these alternative systems on existing centralised infrastructure is important. Monitoring the rainwater tanks will help determine the reliability of these systems and enable better planning by policy makers. Studying the rainwater use patterns within households enables governments and utility planners to develop suitable guidelines for installing rainwater tanks to reduce the reliance on potable water.

Nonetheless, monitoring is a comprehensive process. Monitoring programmes may face a range of setbacks, from exorbitant costs to the inability to obtain statistical significance in analytical outcomes due to variations in the samples, or simply the failure of all or part of the monitoring equipment. The chapter has also briefly discussed an emerging trend in instrumentation available for water consumption assessments. Experimental and analytical methodologies, and also issues associated with monitoring based assessments have been discussed using studies conducted in a few major cities across Australia as examples. The monitoring studies have identified a gap between modelled and monitored data on household rainwater usage, providing valuable information for water planners for developing regional strategic water plans. The main conclusions are summarised below:

- Technology allows sub-hourly monitoring of water use, tank water supply and energy consumption for investigating the rainwater usage, diurnal patters of water supplied by various sources and specific energy consumption in rainwater supply.
- High cost of installation (approximately $5000 per house) limits the number of monitoring sites. Hence, these studies are generally conducted at pilot scale and the data collected may not be representative of suburb-scale tanks behaviour.
- Technology supports rich data collection of rainwater supply, which can be done remotely. However, this can be labour intensive and more time consuming if the study sites are wide

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spread. Daily or sub-daily data collection will also be impossible, thus limiting the scope of the study.

- Rainwater tank monitoring allows checking on compliance with government policies and building codes, for example, the Queensland Development Code and BASIX. The South East Queensland and the Sydney Water studies both showed significant rainwater supply undershoot (40 kL/hh/yr and 38 kL/hh/yr respectively).
- Water flow data collected at hourly, monthly or even daily time-steps (intervals) are sufficient if the objective of the research is to quantify the gross water consumption in households. However, smaller sub-hourly intervals, such as one-minute intervals (or lower), help in understanding the finer details associated with end use consumption characteristics and can provide insights into leakage occurrence, malfunctioning of monitoring equipment or of the end-use appliances, as well in the design of reticulation pipe sizing in new suburbs with mandated tanks. Nevertheless, analysis of fine resolution data can be cumbersome and thus the selection of the time interval should be based on the study objectives.
- One minute monitoring intervals were chosen in this case study to avoid problems attributed to larger time intervals, however study indicated that 6-minute monitoring intervals will also be suitable for understanding diurnal flow patterns.
- Tank water level monitoring provides rain catch figures on an event basis, which can be compared with modelled rain capture information data. Very few studies of this type are reported in the literature.

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Chapter 5

Physical verification of household rainwater tank systems

Sharon Biermann and Reid Butler

ABSTRACT

When rainwater harvesting is promoted or even mandated by governments in order to achieve potable water savings, it is critical that harvesting systems are installed correctly to achieve the planning objectives and targets. Whilst there are numerous design guidelines available for the installation of systems, there is little evidence of post installation monitoring of rainwater tank installation to assess if the *as built* systems follow the *as designed* specifications, on which all modelled gains of water supply are based. Responding to this knowledge gap in installation monitoring, and focussing on the physical installation factors of collection, storage and connections to designed end uses, this chapter describes a generic rainwater tank installation compliance audit protocol, and describes its application in South East Queensland (SEQ), Australia. The on-site physical assessment established that installed rainwater tank storage capacity, in kilolitres (kL), is mostly above requirements (5 kL), with only 16% of sites below requirements; connected roof catchment area (100 m^2 or 50% of roof area) does not meet requirements in 40% of cases; whilst connection to toilets, washing machine and external tap meets requirements in most cases. Except for the installation of backflow devices that prevent contamination of reticulated town water supply, requirements for water quality protection are adequately met. A high level of compliance exists for the requirement for a continuous supply of water to internal fixtures supplied from a rainwater tank by installing a mains water supply backup system.

Keywords: Rainwater tank installation; installation monitoring framework; verification.

5.1 INTRODUCTION

Capturing and using rainwater for the purposes of reducing the demand for potable water, boosting water supply and reducing negative environmental impacts and costs is well documented, particularly in the contexts of increasing population, dry and variable climatic conditions, limited or unreliable access to potable water and fiscal constraints. Governments and water authorities have promoted rainwater capture and use through public campaigns, financial incentives such as rebates, and in some cases, regulatory enforcement. Some form of rainwater harvesting is mandatory for buildings and homes in various cities

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and states in India, Catalonia in Spain, Flanders in Belgium (UN-HABITAT, 2005; Environmental Agency UK, 2008) and in Jordan (Abdulla & Al-Shareef, 2009). In North America, rainwater harvesting is mandatory in new buildings in Tucson, Arizona, Santa Fe County in New Mexico and several Caribbean islands. In Australia, the states of South Australia, New South Wales (NSW) and Queensland, require all new buildings to install a rainwater harvesting system or some other alternative source of water supply (New South Wales Government, 2004; DLGP, 2008; Government of South Australia, 2010), although this regulation has recently become optional in Queensland (Department of Housing and Public Works, 2013).

There has been considerable attention given to the planning and design aspects of rainwater harvesting. Determining the potential feasibility and cost-effectiveness of roof rainwater harvesting, mainly at the scale of cities, has been a primary focus of investigation involving modelling and projections of potential potable water savings under contextual climatic, household demographic and tank design regimes (Hermann & Schmida, 1999; Coombes & Kuczera, 2003; Coombes *et al.* 2003; Handia *et al.* 2003; Villareal & Dixon, 2005; Ghisi, 2006; Ghisi *et al.* 2007; Abdulla & Al-Shareef, 2009; Aladenola & Adeboye, 2010; Tam *et al.* 2010). Studies to improve tank performance have been undertaken largely at the household or building scale, focussing on optimising the collection, storage and use of rainwater under specific contextual conditions, usually involving simulation modelling (Fewkes, 1999a, 1999b; Vaes & Berlamont, 2001; Ghisi, 2010; Khastagir & Jayasuriya, 2010; Imteaz *et al.* 2011). Numerous best practice guidelines have been prepared in support of policy implementation (Sehgal, 2005; Texas Water Development Board, 2005; Chapman *et al.* 2008; Commonwealth of Australia, 2010; Environment Agency UK, 2010; Canada Housing and Mortgage Corporation, 2012).

However there is much less evidence relating to measuring the actual on-the-ground implementation of policy objectives, for example, potable water savings. Evidence of actual water savings through performance monitoring has been provided at the building and individual settlement levels (Coombes *et al.* 1999; Zaizen *et al.* 1999; Coombes *et al.* 2000; Coombes *et al.* 2003; Coombes *et al.* 2004; Coombes *et al.* 2006; Domènech & Saurí, 2011; Umapathi *et al.* 2012). At the wider city level, the most comprehensive evidence of actual potable water savings achieved is found in research undertaken in South East Queensland (SEQ), Australia (Beal *et al.* 2012; Chong *et al.* 2011b). Other than the research in SEQ, on which this chapter is based (Biermann *et al.* 2012), and another 'on-ground truthing' water savings monitoring study in Sydney (Sydney Water, 2012), no other published evidence has been found of implementation or installation monitoring. In situations where rainwater tanks are mandatory, and authorities are depending on the savings achieved in order to defer the construction of additional potable water infrastructure, it seems to us essential that post-installation monitoring studies be conducted to ensure success of planning expectations and optimisation studies. In addition to monitoring the achievement of planning goals, post-installation monitoring is important for the following crucial quality reasons:

- If a tank is not installed or connected properly, it will not function as designed and may result in the tank being turned off or removed by the owner.
- A tank may be assumed to be functioning correctly while actually not, and the benefits will either be reduced or lost.
- Non performing tanks will damage the credibility of rainwater tanks in general and impact on future uptake.
- A badly installed tank may pose a health risk through poor water quality or mosquito breeding allowing the transmission of arboviruses.

A rainwater tank system normally includes a rainwater tank connected to a roof area as the rainwater catchment for rainwater harvesting through roof gutters and downpipes, a pump for supplying rainwater at the required flow and pressure to connected end uses, and a backup mechanism to supply mains water when the tank water level falls below a certain level. Any aspect of this system, if not installed properly,

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will result in reduced performance benefits. There is agreement in the literature that the critical factors influencing the water supply performance of rainwater tanks include:

- *Tank size* – 'The most important factor relating to the efficiency of the rainwater system is the correct sizing of the rainwater tank' (Ghisi, 2010, p 2381). 'Water saving efficiency is more sensitive to changes in storage capacity [than collection area]' (Villarreal & Dixon, 2005, p. 1180). '. . . increases in water supply benefits from rainwater tanks diminish with larger tank volumes while stormwater management benefits increase with tank volume' (Coombes & Kuczera, 2003, p. 242).
- *Connected roof area* – Ghisi (2010a) reported a good correlation between potable water savings and rainwater tank capacity for cities with high rainfall or where roofs are greater than 200 m^2. In Western Sydney, Coombes and Kuczera (2003, p. 241) reported that 'mains water savings provided by the rainwater tanks increase with larger roof areas'.
- *Demand for non-potable water* – 'We argue that the volume of rainwater consumed and the economic feasibility are determined by the end-uses given to rainwater, which are frequently limited to a few purposes.' (Domènech & Saurí, 2011, p. 598). The economic feasibility increases with the increase in rainwater consumption.
- *Rainfall supply factors* – Imteaz *et al.* (2011) found that in the cases of two underground rainwater tanks at Swinburne University in Melbourne, the tanks were effective in wet and average years but less effective in dry years. Vaes *et al.* (2001) concluded that 'rainfall is the most important input for many hydrological and hydraulic design calculations'. 'Brisbane and Sydney, with larger annual rainfall depths, provided greater yields from rainwater tanks' (Coombes & Kuczera, 2003, p. 242).

This chapter relates to the physical factors of tank size, connected roof area and the physical aspects of increasing demand through the connection of appliances to rainwater supply. Responding to the identified knowledge gap in auditing the installation of rainwater tank systems, the purpose of this chapter is to present a generic rainwater tank installation audit protocol, and describe its application in SEQ, Australia. The objectives are to identify any installation issues which could adversely impact on achieving potable mains water savings, and also to highlight potential improvements to the audit protocol based on the learnings gained from its application.

5.2 RAINWATER TANK INSTALLATION COMPLIANCE MONITORING FRAMEWORK

The audit protocol used to evaluate physical installation compliance in SEQ was based on the initial assessment framework developed as part of a pilot study to test the compliance of new housing units in Sydney, NSW with the Building Sustainability Index BASIX certification requirements (New South Wales Government, 2004). This initial audit protocol was further developed for application in SEQ by incorporating the requirements of the 2007 Queensland Development Code Mandatory Part 4.2 (QDC MP 4.2) (DLGP, 2008).

5.2.1 Sydney BASIX assessment

BASIX, the Building Sustainability Index, was introduced in 2004 by the NSW Government and required all new houses and units to achieve a 40% reduction in potable water and energy consumption, compared to the average 'pre-BASIX' home. Each complying development needs to complete an on-line application for a BASIX certificate. This certificate outlines the requirements the household needs to achieve to comply with the regulation. Examples of requirements include installing a toilet of a certain minimum water

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efficiency (i.e., minimum water star rating), installing a rainwater tank of a certain size, and connecting certain internal end uses (e.g., toilets and washing machines) to the tank.

BASIX requires that all tanks are installed according to Australian Standard 3500 of the National Plumbing and Drainage Code (Standards Australia, 2003) and the installing plumber can certify whether this has been done. Inspection of the tank installation, however, is often overlooked during other building inspections as tanks are not necessarily fully installed until all other building work is complete. When local council or private certifiers assess whether all BASIX requirements are met, which includes elements such as insulation, glazing, window shading and water efficient and energy efficient electrical fixtures, these can be accepted as complete based on receipt of specification details, and no site check is carried out. This means that several critical design elements including the connected roof area, number of connected fixtures and filter systems are not checked. Also, the simple task of turning on the rainwater pump can be missed when a home owner moves into their new home, with the assumption that it is already running. In NSW, the Department of Fair Trading inspects plumbing installations; however, this often does not include rainwater tanks, which can be installed after the inspection.

An assessment of the potable water savings attributable to rainwater tanks was undertaken in 2009 at a pilot scale of 52 households to test whether this sample of properties was in compliance with BASIX requirements, and to quantify whether the expected 40% water saving was being achieved (Sydney Water, 2012). This included monitoring of water use from the rainwater tanks and is detailed in Chapter 4. Another on-ground truthing study was undertaken in 2010 to check the installations and water using fixtures in a larger sample of 475 houses in Sydney. The information collected will help clarify whether the BASIX savings are likely to be maintained in the long-term. The analysis results are not yet (2014) publically available from Sydney Water.

5.2.2 Queensland Development Code Performance criteria

The QDC MP4.2 required all detached residential dwellings built after 1 January 2007 to save mains water through the use of supplementary water sources (DLGP, 2008). In SEQ, the water savings target was 70 kilolitres/household/year (kL/hh/yr). Installing a rainwater tank internally plumbed to the washing machine cold water tap, toilet cisterns and at least one outdoor tap for external use was the typical compliance method chosen. Other acceptable solutions included communal rainwater tanks, greywater treatment plants, dual reticulation of recycled water and stormwater reuse, or a combination of these sources.

However, buildings in Queensland no longer have to meet compulsory water savings targets, following the repeal of laws mandating the installation of water supply systems on 1 February 2013 (Department of Housing and Public Works, 2013). Provisions have been made for local governments to opt-in to water savings requirements in recognition of Queensland's varying climatic conditions and regional circumstances. Builders in these local government areas still need to comply with water savings requirements.

Under the (now superseded) QDC MP 4.2, Performance Criteria P2-P6 related to the requirements for rainwater tank installation, capacity and water quality protection for Class 1 buildings (detached dwellings) supplied directly from the reticulated town water supply. Acceptable solutions (A2-5) listed in the QDC for achieving the performance criteria for a detached Class 1 dwelling, where rainwater tanks are selected as the alternate source for achieving water savings targets, were as follows:

- Water savings targets:
  - *Capacity* – minimum storage capacity of 5000 litres (L).

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- *Catchment* – installed to receive rainfall from a minimum of 50% of total roof area or 100 m^2 (whichever is the lesser).
- *Connection to* – (1) toilet cistern/s and washing machine cold water taps (other than those connected to a greywater treatment plant or alternative water substitution measure); *and* (2) an external use.

- Water quality protection:
  - *Prevention of contaminants from entering rainwater tank* – (1) screened downpipe rainhead having a screen mesh 4–6 mm to prevent leaves from entering downpipe; *and* (2) discarding a minimum of 20 litres of first flush runoff where rainwater is connected to showers, wash basins, kitchen or hot water services.
  - *Prevention of mosquito breeding and vermin entering the rainwater tank* – (1) either mosquito-proof screens (suitable material and not coarser than 1 mm aperture mesh); or flap valves at every opening of tank; *and* (2) a vermin trap; or (3) in case of wet systems, mosquito-proofing in accordance with Standard HB230 for rainwater tank installation and design.
  - *Continuous supply of supplementary water to internal fixtures from the reticulated town water supply* – by either (1) an automatic switching device; or (2) a trickle top-up system.
  - *Prevention of contamination of the reticulated town water supply from the rainwater tank* – a backflow prevention device is installed.

5.2.3 Rainwater tank installation audit protocol

This chapter focuses on a study undertaken as part of the Urban Water Security Research Alliance (UWSRA, www.urbanwateralliance.org.au) project on decentralised systems, which, *inter alia*, aimed at understanding the effectiveness of achieving the mandated 70 kL/hh/yr water saving target specified under the SEQ Water Strategy (2010) (Queensland Water Commission, 2010). Whilst other parts of the project considered demographic and behavioural factors influencing water savings, this chapter relates to that part of the study which considered physical installation factors.

The audit protocol initially developed for the Sydney BASIX compliance assessment (Sydney Water, 2009) was adapted to accommodate the requirements of the SEQ-specific QDC MP 4.2 water savings target. This protocol formed the basis of the household inspection protocol undertaken in SEQ in 2011. The final framework was the result of a number of iterations based on inputs obtained from a number of key stakeholders, including the water service provider, after piloting the survey for ten households. The final protocol covers the following aspects (Figure 5.1):

- characteristics of individual dwellings (e.g., dwelling type, total roof area, property dimensions);
- installation of water efficient appliances and fixtures (e.g., showerheads, washing machine);
- information on the rainwater tank systems (e.g., tank volume, roof area connected, type of rainwater conveyance system – wet or dry, pump size);
- internal connections for rainwater supply (e.g., plumbing connections to/from the tank); and
- other water related features on the property (e.g., swimming pool, spa).

For each of these components, a number of detailed parameters was identified and a measurement method determined (Table 5.1). The protocol has been designed to be inclusive of water quality aspects as well as quantity. However, in the application of the protocol to the case study area, the focus of the assessment was on water quantity aspects because the specific research question related to potable water savings.

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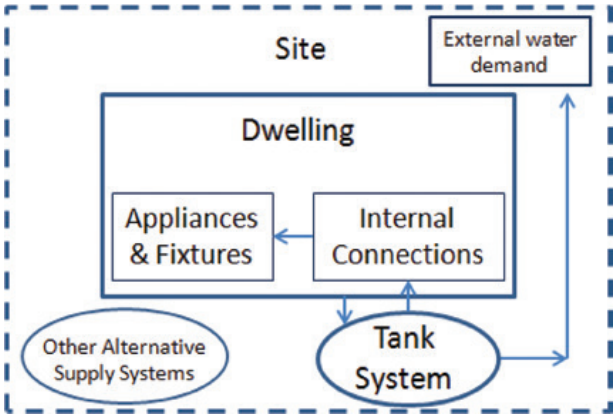


Figure 5.1 Physical components comprising the rainwater tank installation compliance audit protocol.

Table 5.1 Tank installation compliance audit protocol for SEQ.

Parameter	Measurement method
Characteristics of Individual Dwelling	
Dwelling type	Visual inspection. The dwelling types are: detached house; semi-detached house; townhouse; studio/ granny flat; or other (described).
Total roof and garden area	The total roof area for each site to be determined using aerial photography, where available, to mark out and measure the garden and roof catchment areas.
Number of bedrooms	Visual inspection and count of all of the bedrooms in the house.
Water Efficient Appliances and Fixtures	
Number of showers and showerheads – check/ calibrate the flow rate in litres per minute for each showerhead	The number of showers and shower heads determined through inspection of each bathroom and asking the owner. Occasionally there are showers located in the garden. For each shower head, determine the flow rate using a stopwatch and measuring jug. Record the time required to fill a 3 L measuring jug.
Number of washing machines, including type, brand, model and load size (kg) for each machine	The manufacturer's plate has the information required.
Are any of the washing machines connected to the rainwater tank? If yes, Is it connected to the cold tap? Specify other washing machine cold tap Configuration (if any)	Two effective methods of assessment. The first is turning on the washing machine and checking whether the rainwater pump is activated. The second is to turn off the rainwater supply while leaving the mains water supply on and check whether water flows into the washing machine. Also, some washing machines are plumbed with a separate rainwater cold tap.

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Table 5.1 Tank installation compliance audit protocol for SEQ (*Continued*).

Parameter	Measurement method
Number of toilets – check /calibrate the flush volumes for half and full flushes	The number of toilets determined through inspection and asking the owner. To determine the flush volumes of the toilet, turn off the water leading into the cistern, noting the water level and then flushing the toilet. A measuring jug is then used to fill the cistern back up to the previous level and the water required to do this is noted.
Is/are the toilet(s) connected to the rainwater tank?	The same method used as for testing the connection of the washing machine. Either the toilet will be flushed and the system examined for rainwater pumping, or the rainwater supply will be switched off and the toilet checked to see if mains water fills the cistern.
Information on Rainwater Tanks	
Number of rainwater tanks	Inspection and ask the owner, check for underground/hidden tanks.
For each tank, record the type and shape of tank	Visual inspection – either underground, above ground or bladder style.
Tank dimensions (height × length × width)	Measure in millimetres using a tape measure. Underground tanks cannot be measured in this way and the assessor must rely on the manufacturer's certificate.
Tank diameter	Measured using a tape measure.
Tank volume (claimed)	If the tank has a manufacture's volume stamp on it, record this.
Tank materials (e.g., Polyethylene, galvanised steel, stainless steel, concrete)	Determine by visual inspection. Unless convincing evidence can be given by the owner (such as a receipt), the material of underground tanks will not be able to be determined.
Actual tank volume in storage	Determine by noting the shape, measuring the height of the off-take, cut-off switch, overflow and total height of the tank. It may not be possible to measure the float level where there is a trickle top-up system or the water level threshold used to activate the automatic switching to the reticulated water supply. These are located in the tank and accessing them is a safety issue. The measurements that are able to be obtained will give valuable information on the effective tank volume and any dead spaces in the tank.
Size of roof catchment area connected to the tank	If the system is uncharged (that is, the downpipe drains completely into the tank, with no water held in the pipe – Figure 5.2a), it is relatively clear which

(*Continued*)

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Table 5.1 Tank installation compliance audit protocol for SEQ (*Continued*).

Parameter	Measurement method
	downpipes feed rainwater to the tank. Once this has been determined, examination of the roof shows which area drains to the downpipe. Where a section of roof is drained by two downpipes, one draining to the tank and one not, the slope of the gutter will be used to determine which part of the roof drains to which downpipe and from there the tank. Charged systems, (where the downpipes feeding the tanks are full of water – Figure 5.2b), can be checked by tapping the pipes to hear if they are full. After that, the same method outlined above can be used to determine the roof catchment area connected to tank. Mark this information on a satellite image or aerial photographs of the house to determine the area.
Rainwater pump brand and model number	Determine from the manufacturer's plate on the pump. Where plates are in an awkward position to access, damaged or lack required data, pump parameters can be determined from manufacturer's specifications.
Minimum level setting in rainwater tank (in litres)	This will be either the level of the cut-off switch or the off-take height (see Figure 5.3).
Is there an automatic switching device or a trickle top-up system providing supplementary water from the reticulated town water supply?	Note type of potable top-up system (description and model). The difference between trickle top-up and automatic switching devices can be determined by a simple examination of the presence of a switching system on the pump *or* a mains top-up valve on the top of the tank. The switching device has an in-tank water level sensor that causes the switching valve to change over to mains water based on the water level in tank. That is, no mains water enters the tank. The trickle top-up system operates through a float valve that allows mains water to recharge the tank between two defined water levels.
Is there any backflow prevention system?	Backflow prevention systems are located either immediately upstream of the mains input into a switching device, or on the mains meter. They are quite distinctive fittings.
Is there any screened downpipe rainhead, having screen mesh 4–6 mm and designed to prevent leaves from entering each downpipe?	Rainheads are easy to identify visually. Use a measuring tape to measure the screen mesh.

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Table 5.1 Tank installation compliance audit protocol for SEQ (*Continued*).

Parameter	Measurement method
Is there any first flush device installed. If yes, what is the volume capacity of the device?	First flush devices are easily recognisable visually. Volume of first flush devices can be estimated either by measuring the length and diameter of the structure and calculating the volume, or by taking a photo, writing down the product name and comparing with manufacturers specifications.
Is there a mosquito-proof screen of brass, copper, aluminium or stainless steel gauze not coarser than 1 mm aperture mesh or flap valves at every opening of the rainwater tank?	This can be assessed through visual inspection.
Is there a vermin trap, wet system used to harvest rainwater, mosquito proofing in accordance with Standard HB230?	Visual assessment.
Are the rainwater tank's openings constructed to prevent ingress of surface stormwater and groundwater?	This can only be assessed to a limited degree for underground tanks. Where possible, assess all water entry points into the tank to ensure there is no potential contamination from groundwater or surface water. This may include assessment of invert levels, quality of fittings and quality of lid design and construction.
If multiple tanks exist, are they connected to each other?	Visual inspection of connections, usually at the base of tanks.
Number of external taps connected to each rainwater tank	Assessed by turning on the tap and checking for flow from the rainwater pump.
Is the rainwater tank connected to the hot water system?	This is done by turning off the rainwater tank system and operating a hot water tap. No flow indicates a rainwater source.
Is the rainwater used for drinking water and other household supply?	Turn off the rainwater tank system and operate a kitchen tap, laundry tap, bathroom tap, and so on for flow. No flow indicates a rainwater source.
Is the overflow connected to the stormwater drain? If yes, is there a physical air break or non-return valve on the rainwater tank overflow outlet before connecting to the stormwater drainage system?	Visual assessment. From NSW experience, this has been almost impossible to determine without either digging up the pipes or running enough water through the rainwater overflow to discharge into the stormwater drain.
Condition of Tanks, Gutters and Pumps	
What is the rainwater tank condition (good, satisfactory or poor)	Visual inspection including: leaks from the tank; rust or corrosion; and quality of foundation
Rainwater tank installation year	Assessed by questioning the owner. There is rarely an installation date placed on the tank.

(*Continued*)

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Table 5.1 Tank installation compliance audit protocol for SEQ (*Continued*).

Parameter	Measurement method
Condition of the gutters (good, satisfactory, poor)	Assess gutters with respect to the quality of joins, sufficient fall to tank, and amount of sediment. Sediment and litter can be assessed using a mirror on the end of a pole.
Condition of the pump (good, satisfactory, poor)	Assess the pump for: whether the pump is working; presence of rust; leaking of pipes; previous downtime; and improper running.

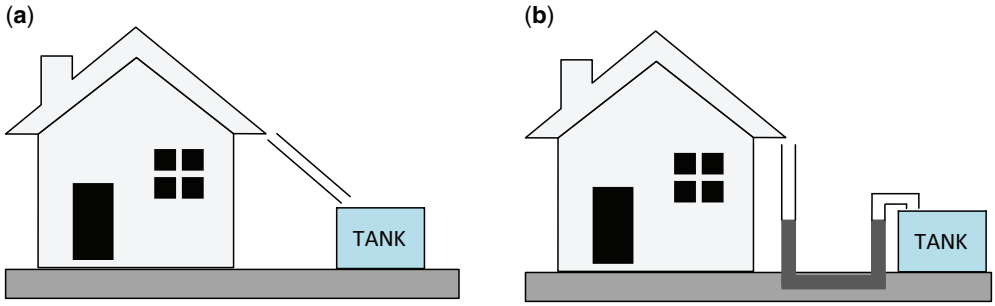


Figure 5.2 Schematic of (a) uncharged and (b) charged rainwater conveyance systems from roof to tank.

5.3 APPLICATION OF THE METHOD TO THE SEQ CASE STUDY AREA

5.3.1 Context

Under the (now repealed) QDC MP 4.2 for detached dwellings in SEQ, the water savings target was 70 kL/hh/yr (DLGP, 2008). The combination of a 5 kL rainwater tank connected to at least 100 m^2 of roof area was deemed to be an acceptable method to achieve the water saving target. According to the QDC, the tank must also be internally plumbed to toilet cisterns, the cold water washing machine tap in the laundry, and one external tap, and have either a trickle top-up or an automatic switching device installed to provide back-up supply of potable water to internal fixtures supplied from the tank.

Research to validate the efficacy of individual rainwater tanks in augmenting the mains water supply, and delivering the water saving as per QDC MP 4.2, is important. This information can build confidence in, and help inform and guide the SEQ Water Strategy (Queensland Water Commission, 2010). It can also help guide the development of policy and regulations addressing issues such as an inspection and maintenance protocols. Knowledge and understanding of how rainwater is perceived among the general public and how it is used in urban SEQ is important in developing and encouraging future sustainable water practices in SEQ.

Desktop studies of mains water savings by Beal *et al.* (2012) and Chong *et al.* (2011b), using statistical analysis of potable water billing data, both revealed that a combination of 5 kL tanks and 100 m^2 connected roof area may not achieve the expected mains water saving target. Both studies reported savings of less than 60 kL/hh/yr. Possible reasons for these lower than expected savings are: (1) water restrictions which may reduce external water use; (2) the possible use of other water resources (e.g., recycled water systems) to achieve the QDC MP 4.2 targets; (3) different household demographics including household

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occupancy rates (Chong *et al.* 2011a); (4) different attitudes, behaviours and perceptions toward the utilisation of rainwater (Mankad *et al.* 2012); and (5) non-compliant installation of mandated rainwater tanks at individual residential dwellings (e.g., inappropriate tank size and connected roof area, tanks not internally plumbed, etc.).

The aim of the SEQ study was to assess the degree to which the 223 selected Class 1 (detached) residential dwellings in four Local Government Areas (LGA) of SEQ, met the physical tank installation requirements deemed necessary to achieve the SEQ Water Strategy's water savings target of 70 kL/hh/yr.

5.3.2 Data collection

An on-site inspection was conducted of 223 consenting individual households with mandated rainwater tank systems in the four LGA of Caboolture, Gold Coast, Pine Rivers and Redland. These particular LGA were selected for the study as part of a wider suite of research projects conducted in SEQ at the time, investigating a range of aspects relating to water savings from individual rainwater tanks. These areas were originally selected on the basis that they are high growth residential areas and hence were expected to have a high proportion of dwellings constructed after January 2007 when mandated rainwater tanks came into effect. Previous research indicated discrepancies in water savings results, particularly in Caboolture and Pine Rivers where lower than expected water savings were identified, and so, larger samples were drawn from these areas (Table 5.2).

Table 5.2 Sample and population sizes.

LGA	Number of sites inspected	Number of dwellings with tanks
Caboolture	59	4000
Gold Coast	45	3300
Pine Rivers	78	5000
Redland	41	3300
Total	**223**	**15,600**

Households who had previously indicated a willingness to allow an on-site inspection as part of a separate, broader study into water savings from individual rainwater tanks (443 households), were sent a follow-up letter providing details of the intended research and requesting that a consent form be completed, signed and returned. Written consent was provided by 223 households and these were subsequently contacted by email and post, provided with details of the intended site inspection, and asked to provide telephone contact details for the purpose of appointment scheduling. The site inspections were conducted during the third quarter of 2011.

It was found during the site visits that connected roof area could not be obtained for those systems with charged (wet) downpipes due to low rainfall. This was particularly the case for charged systems connected to underground tanks, 10% of the sample population. The survey contractor revisited these sites during late January 2012 following plentiful rain and was able to measure connected roof area.

Drawing on the known population of households with mandated tanks, it is possible to calculate a statistical measure of the accuracy provided by the sample used in this study. This calculation is based on the size of the sample, the size of the population from which the sample is drawn, the level of statistical confidence desired (typically 95%), and the variability in the sample (typically estimated from a worst-case

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assumption of a sample proportion of 50%). In the results reported below, all the proportions reported for the full sample (e.g., the proportion of all the inspected installations that are fully compliant, etc.) are 95% certain to be an accurate reflection of the true proportion in the entire population of installations, with a margin of error of +/–6.5%. Proportions reported for specific LGA are less accurate, given their smaller sample sizes. The margins for error for individual LGA range from +/–11.1% for Pine Rivers to +/–15.4% for Redland. Clearly, larger samples would provide greater precision, and a smaller margin for error. For example, a sample size of 1000 would provide a margin of error of +/–3%, whilst a sample of around 6000 households is required for a +/–1% error. Due to funding constraints, it was not possible to inspect such large sample sizes.

5.4 RESULTS

5.4.1 General rainwater tank characteristics

For the purposes of this study, a rainwater tank system is defined as a single tank or group of tanks on a site that share a common catchment area or pump. If multiple tanks on one property do not share a common pump or catchment area, they are classified as belonging to two different tanks systems. In all cases of tank systems with multiple tanks in this study, the tanks were found to have similar shape and size.

Of the 223 sites inspected, most had only one rainwater tank system, with 14 sites having two rainwater tank systems and two sites having three rainwater tank systems to collect rainwater. Whereas most (93%) single tank systems at households comprised only one tank, 6% had two tanks and two sites in Caboolture had three tanks. Redland had the greatest number of two-tank systems. All second and third rainwater tank systems comprised only a single tank.

Most tank systems comprised cylindrical shaped tanks (47%), while 37% of tank systems comprised rectangular shaped tanks. Irregular shaped tank, including one bladder tank, made up 5% of the tank systems audited. It was not possible to determine the shape of the 24 underground systems (10%).

5.4.2 Rainwater tank storage volume

Although QDC MP 4.2 is not specific about which measure of volume it is referring to when it specifies a minimum storage capacity of 5000 L, it is generally accepted that this refers to the net volume *below* the overflow pipe, and this is referred to as storage volume in this paper. Compliant storage volume is calculated from the cross sectional dimensions of the tank, whether rectangular or cylindrical, and the height of the overflow level.

It was possible to calculate storage volumes for 180 sites, with 43 sites having insufficient dimension data available due to tanks being underground, inaccessible for measurement, or irregular in shape. Storage volume, calculated from the basic geometric dimensions of the tank, was on average 6659 L with a median of 5716 L (Table 5.3). There are 15 sites which have a capacity greater than 10,000 L. It was considered likely that these households were aiming for self-sufficiency in water supply, rather than compliance with the 5000 L specified in QDC MP 4.2, and were accordingly excluded from the average compliance analysis following discussions with main stakeholder (Queensland Water Commission). If the tanks with a volume larger than 10 kL are excluded from the analysis, storage volume reduces to an average of 5521 L with a median of 5385 L (Table 5.3), which is still greater than the requirement specified in QDC MP 4.2.

Manufacturer's claimed volume is based on the same calculation used in this study to calculate storage volume. It is expected that manufacturer's claimed volumes would be more accurately calculated, accounting for exact shaping of tanks (such as rounded edges of rectangular tanks) and resulting in slightly

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Table 5.3 Calculated on-site rainwater tank storage volumes.

LGA	Number of sites per tank volume range (kL)								Compliance		Tank volume (L)	
	No vol.	<4	>4–<5	>5–<6	>6–<7	>7–<10	>10	Total	% Comply	20% Variance[1]	Average	Median
Caboolture	12	4	7	26	4	1	5	47	77%	91%	6818	5664
Gold coast	12	0	4	17	7	3	2	33	88%	100%	7575	5766
Pine rivers	10	4	3	43	11	3	4	68	90%	94%	6174	5733
Redland	9	2	5	19	1	1	4	32	78%	94%	6509	5445
Total (all tanks)	43	**10**	**19**	**105**	**23**	**8**	**15**	**180**	**84%**	**94%**	**6659**	**5716**
Excl. tanks >10KL											**5521**	**5385**
Calculated volume[2]											**7126**	
Claimed volume											**6372**	

[1] The % compliance increases if tank volumes within 20% of the target volume of 5000 L are included.

[2] Average calculated volume for 86 sites where both claimed and calculated storage volumes were available, including large tank sites, showing a 12% overestimation compared to the manufacturer's claimed volume.

lower net claimed volumes than the storage volumes calculated in this study, which do not account for exact shapes. A direct comparison between sites where both claimed and calculated storage volumes were available (86 sites), including large tank sites, confirms that, on average, calculated storage volume (7126 L) is 12% higher than claimed volume (6372 L) and this should be factored in when considering compliance (Table 5.3).

Over all four LGA, 84% of all sites with calculated storage volume were at or above the QDC MP 4.2 minimum compliance volume of 5000 L, with most sites (58%) falling into the 5000 L to 6000 L class and 13% into the 6000 L to 7000 L class (Table 5.3). Only 16% of sites had storage volumes less than the required 5000 L. Including those sites which are within a 20% variance of the minimum volume, 94% of sites are at or near the minimum compliance level, but there are still 10 sites (0.5%) which fall outside the 20% variance level (Table 5.3). Caboolture has the lowest level of compliance at 91%, compared with 100% compliance at the Gold Coast after allowing volume criteria relaxation of 20% variance (Table 5.3). Allowing for the 12% overestimation in calculated storage compared to the manufacturer's notified volume, average compliance in all LGA is well above the required 5000 L as specified in QDC MP 4.2. There are, however, 16% of tanks with volumes below the required 5000 L, most of which occur in Caboolture (Table 5.3).

Effective or active volume, which excludes the 'dead' volumes both above the tank overflow level and below the outlet or pump cut-off switch levels, was also considered to illustrate the real volume available for use by the household. Two methods are available for calculating effective volume. In Case 1, a reasonable estimate of the effective volume is obtained by simply deducting the dead volume below the outlet pipe to the pump *and* the air space above the height of tank overflow. However, the pump cut-off water level (measured with a pressure transducer) used to activate the switching valve to the reticulated water supply (Figure 5.3a), *or* the float level that triggers the trickle top-up system (Figure 5.3b) are set higher than the tank outlet to prevent pump cavitation and ensure adequate water supply to the house during trickle top-up events. The threshold water level is almost certainly higher than the installed level of the pressure transducer. Therefore for Case 2, a more accurate estimate of effective volume is to exclude the volume below the pressure transducer or float valve level rather than just considering the dead volume below the pump outlet pipe (Figure 5.3). It is suggested that readers should also look at Figure 6.5 in Chapter 6 for additional information.

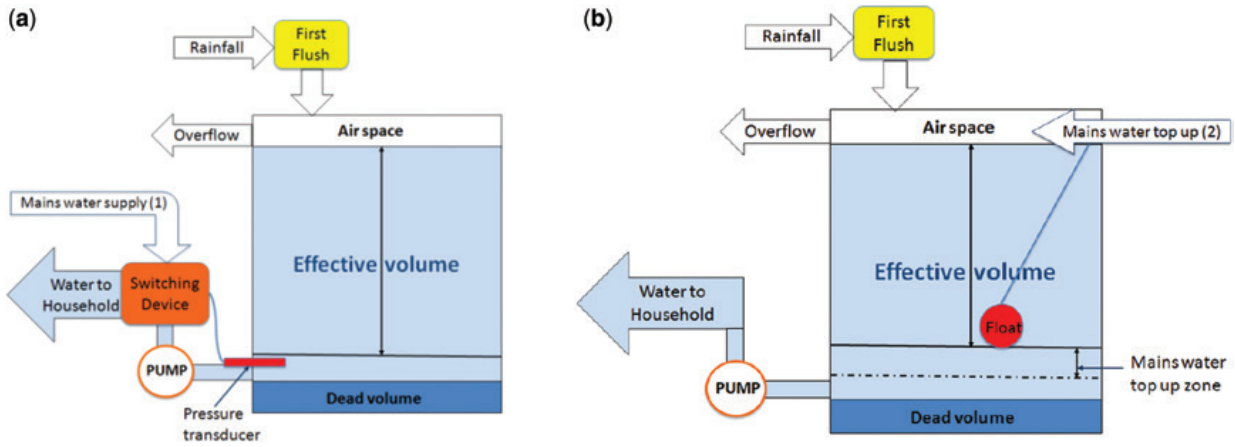


Figure 5.3 Diagram showing effective volume of a tank using Case 2 for (a) an automatic switching device and (b) for mains water top-up.

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Average effective volume for Case 1 is 6342 L per site, with a median of 5451 L (Table 5.4), which is still above the QDC MP 4.2 requirement of 5000 L. However, there are 48 sites which have a lower effective volume than the minimum required volume of 5000 L, although 34 of these are within a 20% variance (Table 5.4). More than half the sites (89 sites, or 52%) fall into the >5000–<6000 L category (Table 5.4).

The second estimate of effective volume (Case 2) is less than for Case 1 due to the location of the pump cut-off (pressure transducer) or the float level that triggers the automatic switching device or trickle top-up system, respectively. Only 60 sites had sufficient measurements for calculating site level effective volume for Case 2, so these results should be considered with caution. The reason for this low data return is that, in addition to underground and inaccessible tanks, the pressure sensor and/or the float are located inside the tank. Accessing them is a safety issue, so it is not always possible to measure the level the pump cut-off or trickle top-up system is activated. Similarly, the geometry of submerged pumps cannot be measured.

Nonetheless, the effective volume for Case 2 is greater than the QDC MP 4.2 minimum capacity requirement of 5000 L, but this time only marginally so at an average of 5019 L, with the median now just below the minimum volume at 4947 L (Table 5.5). Using this method to calculate effective volume reduces the average volume by approximately 20% compared to Case 1, with only 43% of sites having volumes of at least 5000 L (Table 5.5). Including height to pump cut-off level reduces effective volume to the extent that 8 of the 60 sites (13%) are now below the 4000 L volume mark (Table 5.5).

The results indicate that all of the different gross and net measures of volume return, on average, volumes mostly above 5000 L. However, when pump protection cut-off effects are included, indications are that volumes start to reduce to below the 5,000 L minimum capacity. Measuring the level at which pump cut-off takes place is difficult. Manufacturer's claimed volumes (which already account for the 'dead' volume above overflow level) may be adequate for future modelling, possibly allowing for a reduction of around 10% to account for the dead volume below the outlet level (difference between claimed volume and effective volume Case 1 averages), or around 20% if pump cut-off factors are also included (as described for Case 2). Further investigation of the effect of pump cut-off levels on effective volume are required before this proposed 20% reduction factor could be accepted with certainty. The sample size of tanks with cut-off levels provided ($n = 60$) was too small in this survey to provide an adequate level of confidence.

In the absence of manufacturer's claimed volumes, if storage volumes are calculated using in situ physical tank dimensions, calculated volume should be reduced by a further 12% (approximately) to account for volume lost due to tank shapes which generally round off edges and are not perfectly square or round.

5.4.3 Connected roof area

To achieve the water savings target, QDC MP 4.2 requires that rainwater tanks be connected to either a minimum of 50% of total roof area or 100 m^2, whichever is the lesser. A simple approach was developed to measure connected roof area as rainwater catchment for the tank. The connected roof area was estimated using the position and direction of the roof drainage system, the direction of the gutter slope, and location/number of downpipes connected to rainwater tanks. The gutter slopes were determined either visually in case of double storey dwellings where access was an issue, or with a spirit level for single storey dwellings. The inflexion point of the change in slope direction of the gutter between downpipes was marked on the working aerial photograph sheets for households (Figure 5.4). All these working sheets were processed in the office with either Google Earth or NearMap, to mark the location and inflexion points of gutters, as well as determining the tank catchment area, and the total roof area. An example of a marked up aerial photograph used as the working sheet is shown in Figure 5.5 (from Chong *et al.* 2012).

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Table 5.4 Effective site rainwater tank volume using overflow and outlet heights (Case 1).

LGA	Number of sites per tank volume range (kL)								% Comply	Compliance after a 20% variance allowance	Average (L)	Median (L)
	No volume	<4	>4–< 5	>5–< 6	>6–< 7	>7–< 10	>10	Total				
Caboolture	12	4	10	17	3	0	4	38	63%	89%	6393	5380
Gold coast	11	1	7	17	3	3	3	34	76%	97%	7276	5623
Pine rivers	10	5	9	40	8	2	4	68	79%	93%	5939	5570
Redland	9	4	8	15	0	1	4	32	63%	88%	6130	5202
Total	**42**	**14**	**34**	**89**	**14**	**6**	**15**	**172**	**72%**	**92%**	**6342**	**5451**

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Table 5.5 Effective site rainwater tank volume using overflow and pump cut-off heights (Case 2).

LGA	Number of sites per tank volume range (kL)								% Comply	Compliance after a 20% variance allowance	Average (L)	Median (L)
	No cut-off	<4	>4–< 5	>5–< 6	>6–< 7	>7–< 10	>10	Total				
Caboolture	50	0	6	2	0	0	1	9	33%	100%	5562	4947
Gold coast	30	0	7	5	2	1	0	15	53%	100%	5256	5258
Pine rivers	52	3	12	9	1	1	0	26	42%	88%	4834	4937
Redland	31	5	1	3	1	0	0	10	40%	50%	4656	4377
Total	**163**	**8**	**26**	**19**	**4**	**2**	**1**	**60**	**43%**	**87%**	**5019**	**4947**

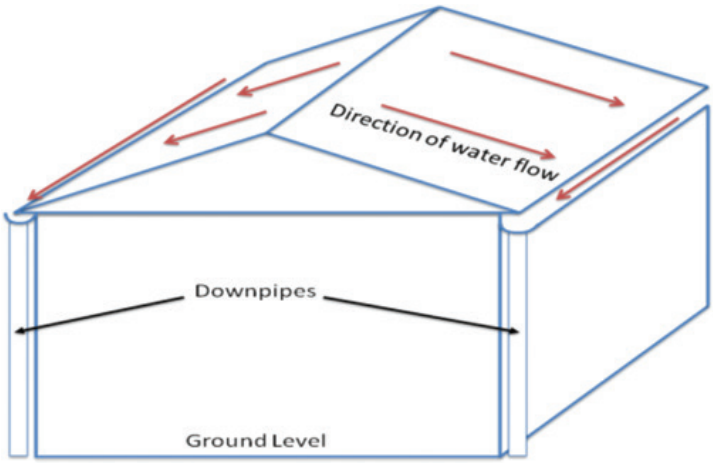
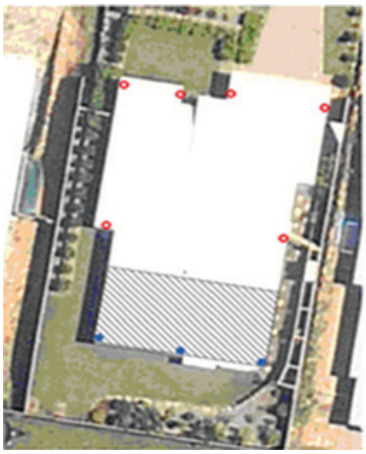


Figure 5.4 Identifying slope and direction of flow in gutters and location of downpipes.



LEGEND

- Downpipes connected to tank
- Downpipes not connected to tank
- Tank catchment

Measurements	
Total roof area (m2)	307
Tank catchment area (m2)	70
Total downpipes	9
No of downpipes draining to tank	3

Figure 5.5 Marked up aerial photograph to estimate tank catchment area.

The average roof area across the four LGA is 300 m^2 (Table 5.6), which means that, on average, houses would have 150 m^2 of roof area connected to the rainwater tank system if the 50% minimum option is applied. However, this is very difficult to achieve in practice due to the location of downpipes and their connection to the rainwater tank whist achieving an aesthetically pleasing outcome. A charged pipe system is one option for connecting the larger roof area, but it is often expensive. With an average measured connected roof area of 118 m^2, it is not surprising, therefore, that the most common option to achieve compliance across the four LGA was the lower 100 m^2 requirement rather than the 50% of total roof area option (Table 5.7).

Of all sites, 58% have connected roof area of >100 m^2, with most sites belonging to the 100–200 m^2 category (Table 5.7). Only 24% of sites have more than 50% of their roof area connected, with 55% of sites falling into the <40% roof area connected category (Table 5.7).

To assess overall compliance with the QDC MP 4.2 'either/or' rule, the following method has been adopted. For the house population with roof area >200m^2, houses that have at least 100 m^2 connected to

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the tank will be compliant. For the population of houses with roof area <200m^2, houses that have 50% or greater of their roof area connected to the tank will also be compliant. The weighted sum of these numbers is the percent compliance for the population of houses. Applying the 'either/or' rule for the SEQ study, there is an overall compliance of only 60% across all four LGA, with Gold Coast being the least compliant at 54%, and Caboolture being the most complaint at 64% (Table 5.7).

Table 5.6 Average detached house roof area (m^2) across four LGA.

LGA	Average roof area (m^2)
Caboolture	310
Gold coast	326
Pine rivers	281
Redland	294
Total	**300**

Unlike the situation with tank volumes which include sites within a 20% variance of compliance criteria, a similar relaxation of connected area requirements did not significantly improve overall compliance. A large percentage of sites still remain in the lowest category of compliance (either <80 m^2, or <40% connected area), after allowing for a 20% variance factor.

5.4.4 Connection to toilets, washing machines and external use

The more household appliances that are plumbed or connected to the rainwater tank, the more rapidly the water level in the tank will be drawn down, resulting in a higher probability there will be a larger air space to capture a larger fraction of the subsequent rainfall event. Hence, both rainwater utilisation and mains water savings increase. QDC MP 4.2 (A2(c)) requires that rainwater tanks be connected to: (1) toilet cistern and washing machine cold water taps; and (2) an external use.

Most of the sites inspected were fully compliant with the required connection to household appliances and to an external tap. All homes inspected had one washing machine present and only 2% of households (five sites in Caboolture) did not have their washing machine connected to the rainwater tank system. 93% of sites had two toilets connected to the rainwater tank, with only five sites not having any toilet connected at all. Except for one site, all homes inspected had at least one external tap connected to the rainwater tank system.

5.4.5 Continuous supply

As part of the section relating to water savings targets, QDC MP 4.2 (P5) requires a continuous back-up supply of mains water to internal fixtures supplied from a rainwater tank through either a trickle top-up or an automatic switching device (see Figure 5.3). The most commonly used device is an automatic switching valve (70% of audited sites), with 23% employing a trickle top-up system and 6% having no device (Table 5.8).

5.4.6 Water quality protection

Although water savings – related issues were the main focus of this study, information regarding the presence of the QDC water quality protection measures (Performance Criteria 3 (P3), P4 and P6) was also collected as part of the site inspection.

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Table 5.7 Number of sites for each class of connected roof area (m^2), or percentage of total roof area connected to rainwater tanks, and overall compliance level.

LGA	No. sites per connected roof area class (m^2)						No. sites per % roof area connected class					
	<80	80–<100	100–200	>200	Av.	% Comply >100	<40%	40–<50%	≥50%	Av.	% Comply	% Overall comply*
Caboolture	14	5	28	6	119	64%	26	16	11	44%	21%	64%
Gold coast	12	7	15	5	136	51%	23	6	10	41%	26%	54%
Pine rivers	23	10	37	6	110	57%	42	17	17	39%	22%	58%
Redland	9	7	18	4	113	58%	22	4	12	41%	32%	63%
Total	**58**	**29**	**98**	**21**	**118**	**58%**	**113**	**43**	**50**	**40%**	**24%**	**60%**

*% overall compliance is based on the lesser of 50% of total roof area or 100 m^2 (as per QDC MP 4.2).

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Table 5.8 Type of continuous back up water supply device installed.

	No.	%
Trickle top-up	51	23%
Automatic switch	155	70%
None	14	6%
Total	220	

QDC MP 4.2 (A3) requires screened downpipe rainheads and first flush devices as suitable measures to prevent contaminants from entering the rainwater tank. 95% of rainwater tanks inspected in the study had a screened downpipe rainhead installed. Only 37% of rainwater tanks inspected had a first flush device installed, but this requirement is only necessary when the rainwater tank is connected to showers, wash basins or hot water services, which are not the end uses for most of the rainwater tanks inspected.

QDC MP 4.2 (A4) requires mosquito-proof screens, flap valves, or, in cases of wet systems, mosquito-proofing in accordance with Standard HB230 (MPMSAA, 2008) and vermin traps to prevent mosquito breeding and vermin entering the rainwater tank system. Of the sites inspected, 96% had some form of mosquito breeding prevention device installed, and 95% had a vermin trap installed.

Similarly, QDC MP 4.2 (P6) requires a backflow prevention device to prevent contamination of the reticulated town water supply with tank water. All tanks with a trickle top-up system (23% of households) had an air gap present between the overflow and the trickle top-up device and this operates as a backflow prevention device. Only 45% of rainwater tanks inspected had an additional backflow prevention device present. Accounting for both forms of backflow prevention, 68% of tanks were compliant.

5.5 SUMMARY AND CONCLUSION

In response to an identified knowledge gap in post tank installation monitoring, this chapter has presented a generic rainwater tank installation compliance audit protocol, and described its application in SEQ, Australia, to assess compliance of rainwater tank systems and validation of water savings and quality objectives required by QDC MP 4.2.

This chapter has summarised the results of applying the audit protocol in the assessment of household rainwater systems of 223 Class 1 detached dwelling sites with mandated rainwater tanks in SEQ. The audit identified installation factors which may impact adversely on achieving the 70 kL/hh/yr water savings target for detached dwellings in SEQ.

The three main installation requirements of QDC MP 4.2 relate to: rainwater tank storage capacity, roof catchment area and connection to appliances. The results of the on-site assessment have shown that:

- Installed storage capacity is mostly greater than the required 5000 L, although 16% of sites inspected had storage volumes less than 5000 L.
- Roof catchment area does not meet requirements in 40% of cases, either by having <100 m^2 or <50% of total roof area (whichever is the lesser), connected to the tank.
- Connection to toilets, washing machine and external tap meets requirements in most cases.

The study has concluded that in estimating effective tank volume from manufacture's claimed volumes, claimed volume should be reduced by about 10% to account for the dead volume below the outlet level. In addition, the active storage volume should be further reduced due to the water level setting on the pressure

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switch and the operating levels of the float valve, with an overall total reduction in effective tank volume of about 20% if pump water level cut-off factors are also included. In the absence of information on claimed volumes, storage volumes can be calculated using in situ physical tank dimensions (after allowing for dead volumes etc.), but should first be reduced by about 12% to account for volume lost due to tank shapes which generally round off edges and are not perfectly square or round.

Of greater concern is the higher level of non-compliance in roof area catchment connected to the rainwater tank system, which we report with a reasonable degree of confidence. Even relaxing the level of compliance to within a 20% variance does not significantly improve the compliance. Certainly, in any policy and management intervention to improve the yield from rainwater tank systems in SEQ, this aspect of increasing the connected roof catchment area is the single most important physical installation factor to be considered. This level of non-compliance in connected roof area has implications for potable water savings across the region, most likely resulting in lower actual savings than those predicted, and thereby reducing the time period of deferred infrastructure investment. Specification of the area of the roof to be connected, rather than the percentage of roof area, is a more easily achievable target in situations when average roof area is greater than 200m^2.

The practical reasons for this low compliance probably stem from construction phase issues such as cost, difficulty in getting the downpipes to connect to the tanks past windows, doors and other obstructions, and the aesthetics of having horizontal pipes running along external walls. Clearly, it is important to consider the overall design of the house when planning rainwater tank installation so that the anticipated benefits can be realised.

Charged systems, where the downpipes are usually full of water and run along the ground or beneath the house before rising up to discharge into the tank, are often used to achieve the maximum roof area connection. A caution is given here in that several sites with charged systems had the potential of cracking and delivering water to the house foundations. Silting up with leaf debris over time is also a problem if adequate inspection is not carried out and cleaning points are not installed.

The lack of detailed inspections by a dedicated agency of all aspects of rainwater tank installation has the potential to both reduce the anticipated savings and to cause health and safety problems in the future. Inspection of connected roof area is probably the single most important aspect as this seems to be most problematic in terms of compliance.

QDC MP 4.2 also includes requirements for water quality protection through prevention of contaminants and vermin from entering the rainwater tank, prevention of mosquito breeding and prevention of contamination of reticulated town water supply. Except for the installation of backflow devices that prevent contamination of reticulated town water supply, requirements are adequately met. The results of the on-site inspection have shown that:

- Screened downpipe rainhead installation largely meets requirements.
- First flush device installation were infrequent but were not required as rainwater was generally not connected to showers, wash basins or hot water services.
- Mosquito breeding prevention device installation meets requirements.
- Vermin trap installation mostly meets requirements.

Backflow prevention device installation does not meet requirements, with only 45% of those rainwater tanks with switching valves having a backflow device installed. However, all tanks with a trickle top-up system (23%) had an air gap present between the overflow and the trickle top-up device which serves the purpose of a backflow prevention device.

The results indicate a high level of compliance with QDC MP 4.2 (P5), which states the requirement for a continuous back-up supply of potable water to internal fixtures supplied from a rainwater tank using either a trickle top-up or an automatic switching device.

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In applying the rainwater tank installation compliance audit protocol in SEQ, a number of shortcomings were identified. The protocol needs further enhancement in relation to the measurement of underground tank systems, and the timing of the assessment in relation to rainfall events is important so that measurement occurs when conveyance pipes are sufficiently charged with water.

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Chapter 6

Understanding energy usage in rainwater tank systems through laboratory and household monitoring

Grace Tjandraatmadja, Monique Retamal, Shivanita Umapathi and Guenter Hauber-Davidson

ABSTRACT

There is limited understanding by rainwater tank owners and water planners about the energy requirements associated with rainwater tank supply. The design and set-up of rainwater systems can be improved to reduce the energy requirements for rainwater supply in urban areas whilst maintaining service requirements. This chapter examines the factors that influence the energy use in commonly used rainwater pump systems (pump characteristics, end uses, system and infrastructure design and, indirectly water policy). It provides recommendations on how system configuration could be improved to reduce pumping energy requirements, and how it can be influenced by regulatory policies. The typical set-up adopted for domestic rainwater systems has pumps operating well outside their optimal energy efficiency due to a mismatch between pump design and the low flow rates required for most of the end uses in urban dwellings. Increased focus on the energy footprint and awareness of the energy consumption should lead to improved system design and optimise the energy requirements for residential rainwater pumping, making rainwater supply more sustainable and the least energy intensive of all the alternative urban water supplies.

Keywords: Energy footprint; pumps; rainwater tanks; specific energy; rainwater harvesting.

6.1 ENERGY USAGE IN RAINWATER SYSTEMS

Energy usage in water supply contributes to the generation of greenhouse gases, and to the overall cost efficiency and sustainability of water services.

The energy and costs associated with traditional centralised water supply and distribution services in urban areas have been thoroughly characterised (Kenway *et al*. 2008; Apostolidis, 2010), however limited data is available on the energy associated with residential rainwater supply systems. This is partly because, historically, rural dwellings that depended on rainwater as their sole water supply (i.e., no mains water

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sources available) have not been concerned with rainwater pump energy usage, but rather with the level of service from water delivery. However, as rainwater systems are increasingly implemented in urban environments where they co-exist and/or complement other water supplies (e.g., mains water, recycled water, desalinated water, stormwater) there is greater need to understand their energy contribution to water supply and their environmental impact.

A few studies have estimated energy savings to the water industry or costs for pumping rainwater to residential dwellings using average energy values reported in the literature, 0.9–2.0 kWh/kL (Marsden Jacob Associates, 2007; Hall *et al.* 2009; Tam *et al.* 2010; Apostolidis, 2010). Apostolidis (2010) examined the energy-water nexus for water supply across Australia. Others compared rainwater energy use of centralised and alternative water services in Australia (Lane *et al.* 2010) and overseas (Proença *et al.* 2011; Chiu *et al.* 2009). Proença *et al.* (2011) and Chiu *et al.* (2009) considered rainwater pumping energy a relatively minor component compared to other energy needs in the water industry and extolled the potential savings that rainwater harvesting could bring to water providers. However, Hall *et al.* (2009, 2011) have shown that in areas of high rainwater tank uptake, such as South East Queensland, Australia, the combined energy consumption by rainwater tanks could equate to the amount of energy used in the centralised water supply system. Furthermore, the uncertainty associated with energy estimates for residential rainwater supply is high, +/–50%, whilst energy estimates for centralised water supply have a much lower uncertainty margin of +/–15% (Hall *et al.* 2011). In the United Kingdom, the operational energy for rainwater supply has been reported to range from 0.6 to 5 kWh/kL (Parkes *et al.* 2010).

Likewise, across Australia, in-situ studies on the energy consumption for rainwater tank pumping systems have been conducted for 164 residential dwellings in a range of climatic zones and jurisdictions (Gardner *et al.* 2006; Beal *et al.* 2008; Retamal *et al.* 2009; Cunio & Sproul, 2009; Hauber-Davidson *et al.* 2010; Hood *et al.* 2010; Talebpour *et al.* 2011; Umapathi *et al.* 2012; Ferguson, 2011). These studies have covered dwellings located from tropical to temperate climates, on flat to sloping topography, with a wide range of characteristics (single and double storey and various sizes) and various system set-ups (pumps, storage and control types), occupancy (from single to multiple occupants), from standard dwellings to ecovillages, and various rainwater end uses (from single uses to all household uses).

The specific energy for rainwater pumping reported in those studies ranged from 0.4 to 11.6 kWh/kL of rainwater used, indicating a large variability in the energy for supply of rainwater to urban dwellings. However, the median specific energy was around 1.4 to 1.8 kWh/kL, which compares favourably with other alternative supplies such as desalination or recycled water (>2 kWh/kL) as shown in Figure 6.1. Dwellings that used rainwater for all end uses in the house, recorded a median energy consumption of 1.4 kWh/kL, which is within the same average range verified for selected end uses (Hood *et al.* 2010).

Figure 6.1 compares the energy requirements for water supply using various sources. The energy associated with conventional centralised water supply in major Australian capital cities in 2006/07 ranged from 0.09 to 1.85 kWh/kL, with the minimum and maximum applicable to the cities of Melbourne and Adelaide respectively and the capital cities average of 1.03 kWh/kL(Retamal *et al.* 2009; Kenway *et al.* 2008). Recycled water and desalinated seawater supply tend to have energy requirements in excess of 2 kWh/kL. Hence, by reducing the spread of energy for rainwater supply, the energy requirements for rainwater supply becomes comparable to the requirements of other alternative water supply sources (Figure 6.1).

By understanding the actual operation of rainwater tank systems and the factors that influence energy consumption in rainwater pumping, a range of opportunities to optimise the energy associated with rainwater supply can be identified (Cunio & Sproul, 2009; Retamal *et al.* 2009; Hauber-Davidson & Shortt,

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2011; Tjandraatmadja *et al.* 2013). This, in turn, is important for increasing the operating efficiency of rainwater harvesting in comparison to other alternative water sources. The following sections summarise the key factors in the design and set-up of rainwater harvesting systems that impact energy consumption and examine how it can be reduced.

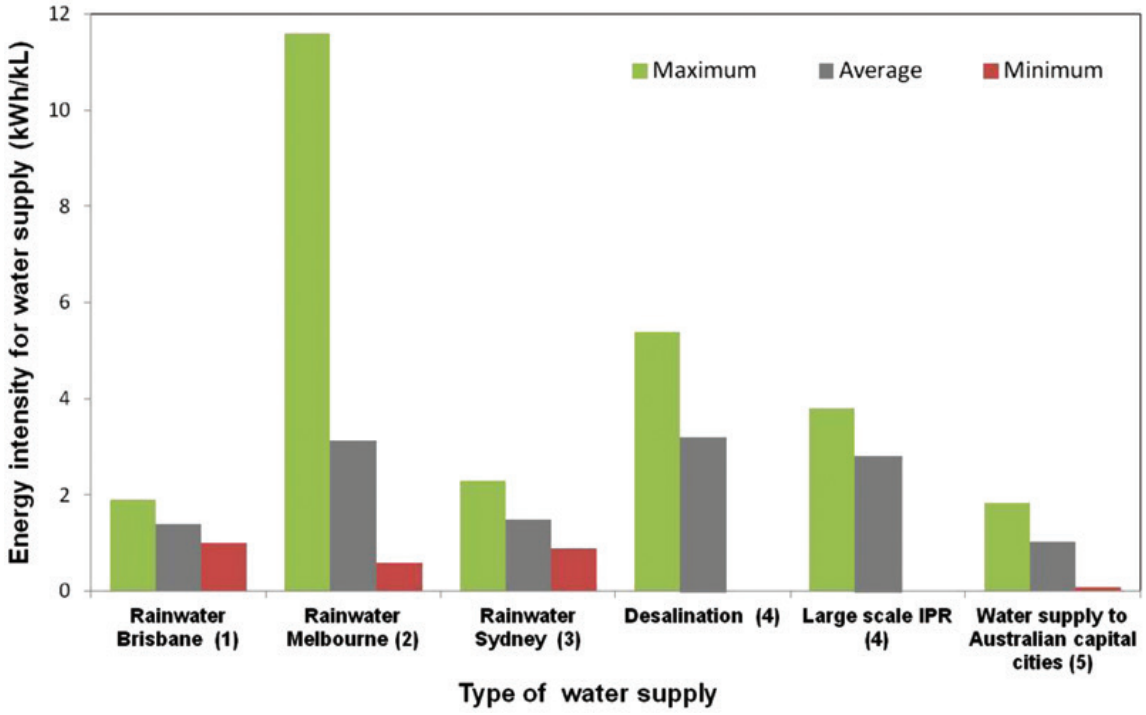


Figure 6.1 Examples of energy requirements for water delivery in major Australian capital cities. (*Sources*: (1) Gardner *et al.* (2006); (2) Hauber Davidson *et al.* (2010); (3) Retamal *et al.* (2009); (4) NSW Government (2006); (5) Kenway *et al.* (2008)).

6.2 RAINWATER SYSTEM SET-UP

Rainwater supply systems are typically designed for residential, commercial and industrial applications. A rainwater system comprises a series of components including tanks, pumps, flow control devices, switching valves, back-up systems, and ancillary components such as pressure vessels and filters, as listed in Table 6.1 (Retamal *et al.* 2009; Hauber Davidson *et al.* 2010; Umapathi *et al.* 2012). A more comprehensive review of key system components and configurations adopted in rainwater supply can be found in Retamal *et al.* (2009).

In urban settings, the most common system adopted consists of an above ground rainwater tank with a fixed-speed pump (either external or submersible) and a trickle top-up or an automatic switching valve to allow mains water back-up. Figure 6.2 shows a typical set-up, with rainwater flowing from the roof into the tank after passing through a leaf-guard to remove leaves. The bottom of the tank is connected to an external fixed-speed pump equipped with an automatic switching device for mains water back-up. The pump provides rainwater for non-potable, fit-for-purpose water use applications such as toilet flushing, laundry cold water taps and garden irrigation. When the tank is full, rainwater overflow is discharged to the stormwater drain.

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Table 6.1 Components that can be adopted in a rainwater system.

Component	Description
Pump	Pumps water from the rainwater tank to the dwelling under pressure. There are various types: Fixed-speed external or submersible, variable-speed, jet pump, and so on (Retamal *et al.* 2009).
Rainwater tank	Tanks are supplied in a range of shapes and volumes including above ground, below ground and bladder tanks.
Back-up system	Ensures continuous water supply. There are two types: (a) trickle top-up which fills a tank with mains water via a float activated mechanical valve; or (b) automatic mains switch valve that sources water directly from mains water if the rainwater tank falls below a threshold water level measured with a pressure transducer.
Pressure vessel	Device that releases water from a vessel whilst maintaining the pressure in the line from the pump to the vessel above the threshold value that would otherwise activate the pump. They are particularly useful to prevent pump activation for small water demand events such as hand washing or water leakage. They come in a range of sizes from 3 L to >100 L. Pressure vessels used in residential dwellings typically have small volumes (<10 L).
Filter	Device used for removal of particulate matter before supply to the dwelling. Resistance to flow increases as they become clogged.
Header tank	Balancing storage between a rainwater tank and the end use of a dwelling. It is located above the ceiling line and is filled by the pump and supplies water to end uses by gravity.

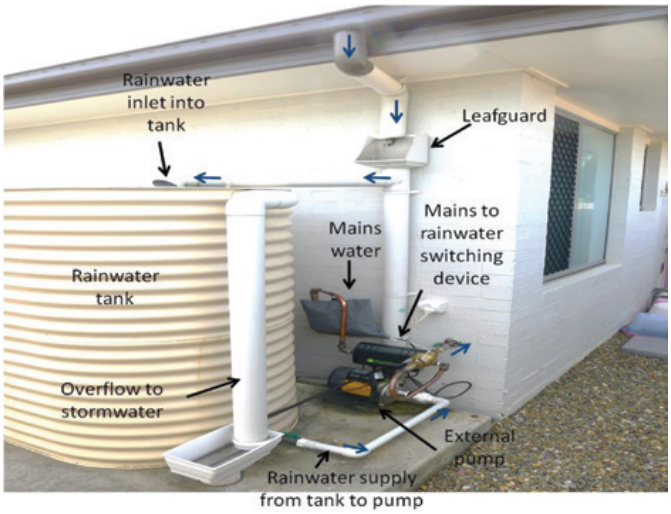


Figure 6.2 Example of a typical residential rainwater system set-up with an external fixed-speed pump equipped with an automatic rainwater to mains water switch. The rainwater flow path into the dwelling is shown by the blue arrows. (*Source*: Umapathi *et al.* 2012).

Fixed-speed pumps are much more common than variable-speed pumps as they are significantly lower in cost (Retamal *et al*. 2009; Tjandraatmadja *et al*. 2012). Most importantly, a fixed-speed pump draws almost the same amount of electrical energy irrespective of the water flow rate. The typical energy

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associated with pump operation is characterised by three stages, as shown in Figure 6.3: (a) *Start-up* as the inertia of the pump motor is overcome; (b) *Operation* at steady flow and pressure; and (c) *Over-Run* as the flow is stopped and the system is re-pressurised to the set pressure. The start-up stage is characterised by a transient peak in power lasting less than 1 second, followed by constant power draw during the steady water supply regime (Retamal *et al.* 2009; Tjandraatmadja *et al.* 2012). The energy required for the start-up, operation and over-run stages are a function of the design of each pump. This is illustrated in Figure 6.4 which shows the energy consumed during each of those stages for three pumps during the filling of a toilet cistern after a half and a full flush. In Figure 6.4, the start-up energy contributed to a larger share of pump A's total energy use than for pumps B and C, whilst for pump C, the over-run energy was higher than for the other pumps. Analysis of 11 pumps sold in Australia showed that the over-run energy can contribute from 5% to 25% of the total energy required to fill a toilet cistern after a full flush depending on the pump model and its pressure settings (Hauber-Davidson & Shortt, 2011).

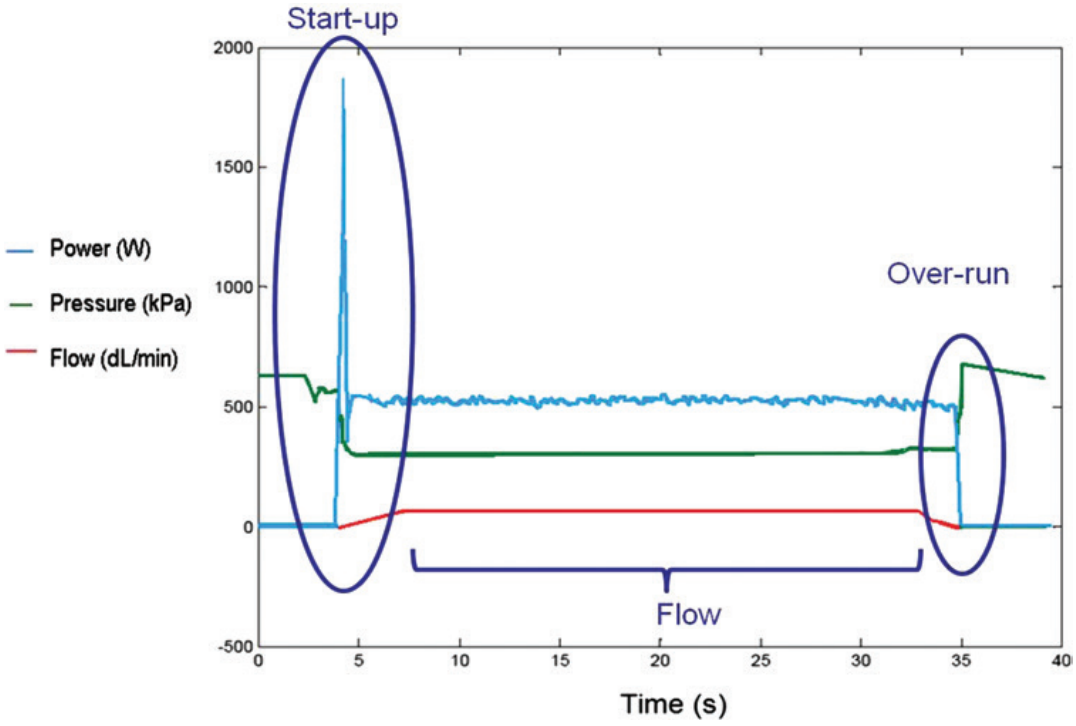


Figure 6.3 Typical operation profile for a fixed-speed pump showing the power consumption, pressure and flow delivered by the pump at the start-up, operation (flow) and over-run of pump operation. (*Source*: Tjandraatmadja *et al.* 2011).

Rainwater tanks adopted as a supplementary water supply system are usually fitted with a back-up system, that is, a mechanism to switch to the mains water when the tank water level falls below a threshold level set by a float or pressure transducer. There are two types of back-up systems commonly used: trickle top-up and switching device. A trickle top-up system (Figure 6.5a) uses a mechanical float device within the storage tank, so that when the water level reach a threshold, a mechanical valve opens and mains water is trickled into the tank to maintain water supply to the household. A trickle top-up system has adverse energy implications as mains water is depressurised when it enters the tank, after which it is re-pressurised by the

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household pump. A switching device (Figure 6.5b) uses a pressure sensor to measure the water level in the tank, and once a threshold value is reached, it signals a solenoid valve to open which connects directly to the mains water supply. The switching device is placed on-line after the pump and does not depressurise the mains water supply. However, energy is used to operate the sensor circuitry and the stand-by energy use of the devices in the market vary substantially. In some cases, the non-pumping related energy (stand-by and over-run time) can contribute up to 20 to 40% of the total energy consumption depending on pump type and operation (Water Conservation Group, 2010). However Umapathi *et al.* (2013) examined 20 dwellings with rainwater tanks with the two different mechanisms and found a slightly higher energy consumption for the trickle top-up system (1.59 kWh/kL) compared to the switching device (1.46 kWh/kL).

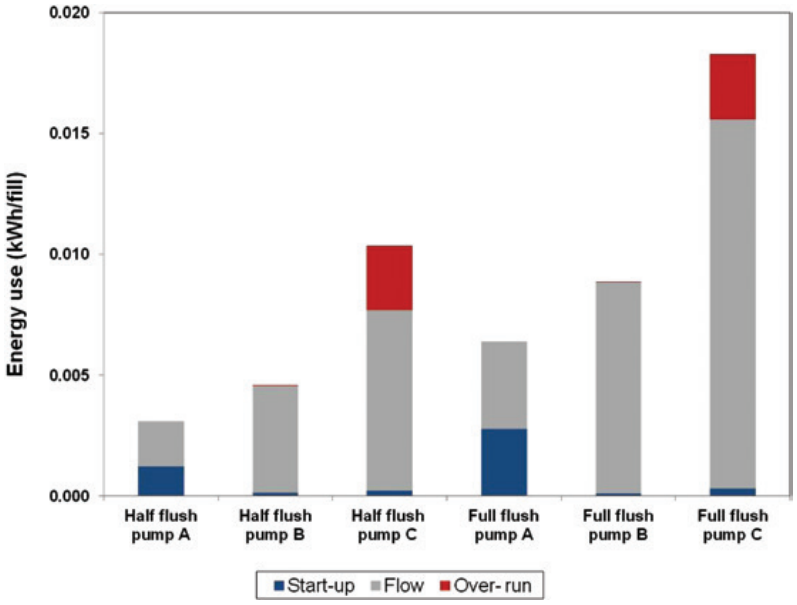


Figure 6.4 Energy use during supply of rainwater to a toilet cistern by three different pumps A, B and C with motor capacities of 0.2 kW, 0.55 kW and 0.75 kW respectively. (*Source*: Tjandraatmadja *et al.* 2011).

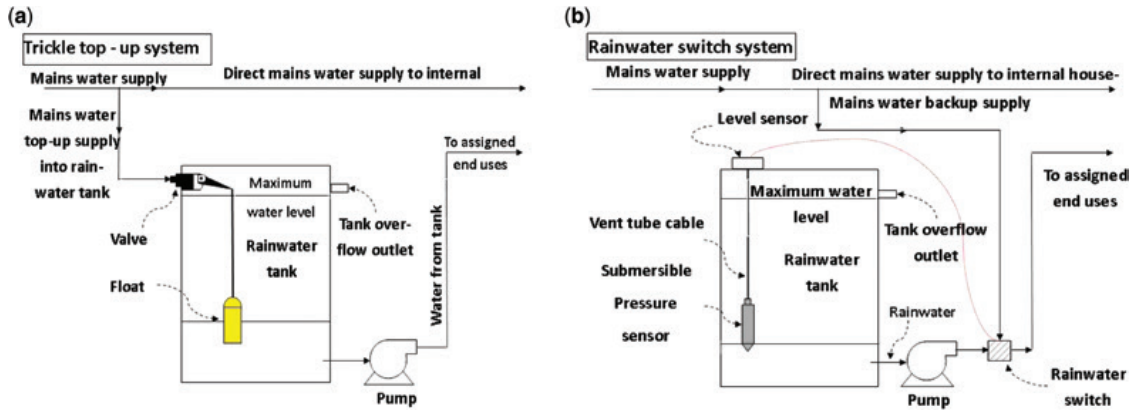


Figure 6.5 Illustrative diagram for a rainwater tank system working on: (a) a 'Trickle top-up' mechanism; and (b) a 'Rainwater Switch' mechanism.

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The energy usage for rainwater supply is mainly dependent on the pumping of water from a rainwater tank to the end uses in a building (Retamal *et al.* 2009). Hence, thoughtful system design and the proper selection of ancillary components can help to reduce the energy usage for rainwater pumping.

6.3 ENERGY USE ESTIMATION

6.3.1 Factors impacting energy consumption

Energy needs vary due to seasonal change, storage capacity and intensity of rainwater use. Studies conducted in urban areas across Australia showed that rainwater end uses vary across the country due to system configuration, household characteristics and home owner motivation and preferences. However, legislation, standards and codes promoting the use of rainwater tanks can also play an important role in determining rainwater system configurations adopted (Gardiner *et al.* 2008; Gardiner, 2009).

Energy usage for rainwater supply is influenced by a range of factors: pump selection, system configuration and infrastructure, end use requirements, appliances and fittings in the dwelling, and dwelling occupancy. To understand energy performance of a rainwater system and to evaluate the system in its entirety it is necessary to understand how rainwater is used in a dwelling and the role of the various system components (Talebpour *et al.* 2011; Beal *et al.* 2011). So, in order to theoretically estimate pump energy use for a household rainwater system, two key pieces of data are required:

- A relevant pump power curve to understand the relationship between the electrical power draw of the pump and water flow rates; and
- A profile of household water consumption with information on the frequency, duration and flow rate of water end-uses supplied by the tank.

The need for such information is explained in the following sections.

6.3.2 Pump performance

The performance of a pump is summarised in its power curves. Figure 6.6a provides an example of a pump power curve. The flow rate and power curve data can be used to estimate the total energy consumed by a rainwater system as well as the rainwater volume delivered over a given period of time. Each pump has an optimal range of water flow rates where the pump operates most efficiently, the Best Efficiency Point, shown in Figure 6.5a.

In addition, to compare the energy efficiency of a system to others with different water use and pump characteristics, the *Specific energy* or *Energy intensity* is calculated. This is an expression of the total energy consumed by a pump (e.g., in kilowatt-hours (kWh)) divided by the total volume of rainwater delivered (e.g., in kilolitres (kL)) at a set flow rate as shown in Figure 6.6b. The specific energy (in kilowatt-hours per kilolitre (kWh/kL)) decreases as pump flow rate increases.

The other key parameter adopted for the evaluation of the energy use for water delivery in a dwelling is the *Total energy consumption* over a set period of time in KWh per time unit (e.g., year). This measures the energy footprint for rainwater supply over a set period of time irrespective of differences in pump operating systems.

6.3.3 Pump design and characteristics

The individual design and characteristics of each pump influence the energy use. Retamal *et al.* (2009) demonstrated that pump type and application impact its specific energy use, as shown in Figure 6.7 for a

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selection of fixed-speed, submersible and variable-speed pumps and high and low flow uses in urban dwellings. Figure 6.8 compares the specific energy for running a range of pumps at two set flow rates, 8 L/min and 17 L/min, and shows that, as expected, pumps of higher motor power capacity tend to have higher specific energy requirements, for example, Davey HP45-05 and Davey HM60-10. However, there are examples where pumps of the same type with the same nominal power capacity differ in specific energy requirements depending on the manufacturer, such as Storm and Onga SMH55 (Hauber-Davidson & Shortt, 2011).

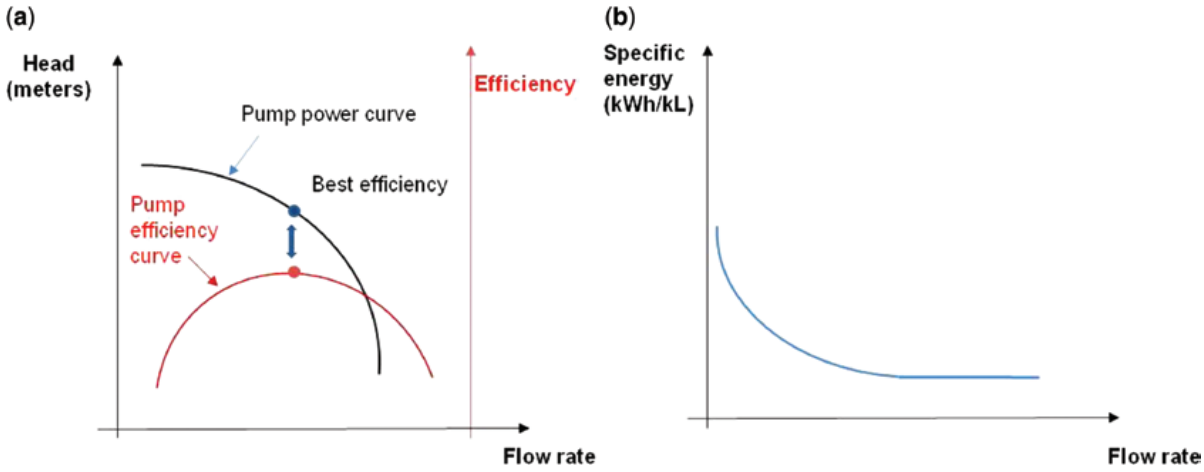


Figure 6.6 (a) Pump power curve for a fixed-speed rainwater tank showing the relationship between water head versus flow rate (black curve) and pump efficiency (red curve) and the Best Efficiency Point; (b) Specific energy (kwh/kL) used by the pump as a function of flow rate.

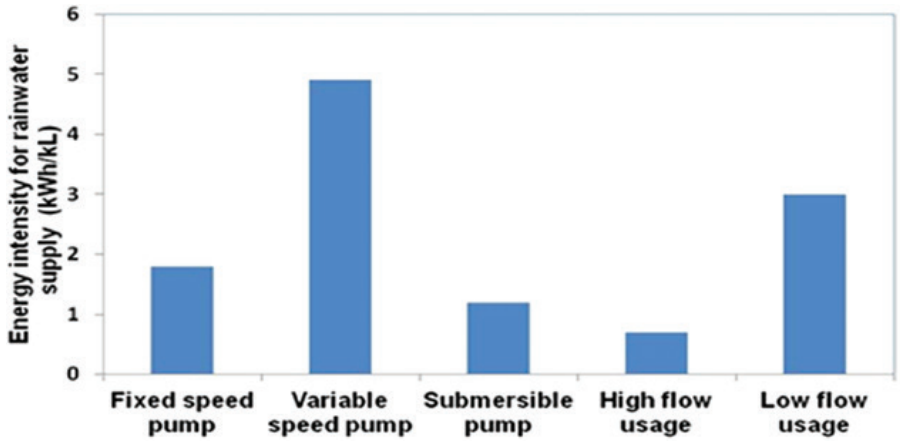


Figure 6.7 Specific energy use for rainwater supply using a fixed-speed, submersible and variable-speed pumps in Sydney homes. (*Source*: Retamal *et al.* 2009).

Clearly individual pump design impacts energy use, and each pump has its own specific energy curve as shown in Figure 6.9 for a range of pumps sold in Australia (Hauber-Davidson & Shortt, 2011). The figure also shows that the specific energy for pump operation decreases as the flow rate increases, particularly for flow rates >10 L/min.

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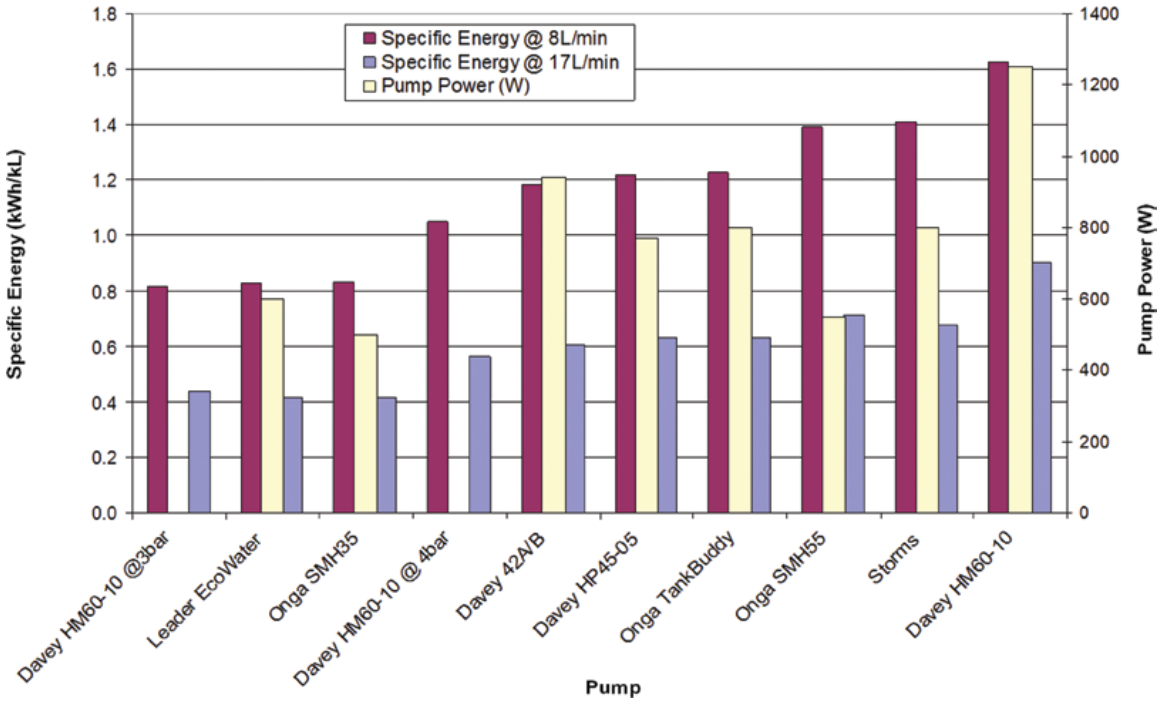


Figure 6.8 Comparison of the specific energy for operation of various pumps at flow rates of 8 L/min and 17 L/min. (*Source*: Hauber-Davidson & Shortt, 2011).

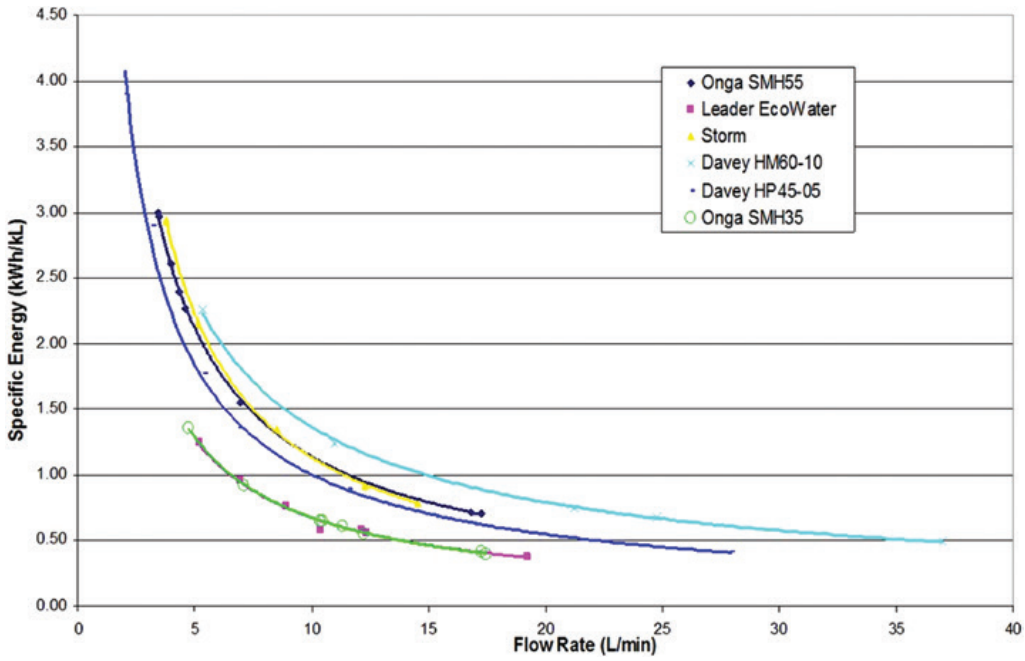


Figure 6.9 Comparison of specific energy curves for a selection of rainwater supply pumps sold in Australia. (*Source*: Hauber-Davidson & Shortt, 2011).

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6.3.4 End use water requirements

The number of times a pump starts, the duration of its operation, and the flow and volume of water supplied will vary with the water use pattern for each individual appliance, and with the pump settings.

Water end uses in a household have specific service requirements for volume, pressure, flow and pattern of water supply. Table 6.2 provides a summary of typical operating requirements for appliances such as washing machines, dishwashers, showers and taps. Water fittings such as taps, showerheads and irrigation devices are designed to operate within a pre-set flow rate range. Likewise, household appliances, such as washing machines, toilet cisterns and dishwashers are designed to operate within a specific range of flow and pressure conditions. In addition, in Australia water efficient appliances and fittings that comply with the Water Efficiency Labelling Scheme (WELS) are designed to use less water and/or supply water at lower flow rates than non-WELS appliances.

Table 6.2 Service and design parameters for water appliances and fittings. (Adapted from Tjandraatmadja *et al.* 2013).

Appliance or fitting	Specifications set by manufacturer		Service conditions	
	Minimum operating pressure (kPa)	Maximum operating pressure (kPa)	Flow rate (L/min)	Volume of water (L/use)
Washing machine	40–100[1]	800–1000[1]	<13[4]	WELS[6]: 5–30L/kg load Non-WELS: >30L/kg load
Dishwasher	30–150[2]	800–1000[1]	<4.1[4]	16[4]
Toilet cistern	35–50[2] (conventional)	400[1]	<6.3[4]	Full/half flush[6]: 9/4.5L, 6/3 L and 4.5/3 L
Tap	n.a.	n.a	Indoor tap: Non-WELS: 15–18 WELS[6]: 2–7	Standard: 15–18[3] Hand basin: 3.3[5] Kitchen sink: 19.4[5] Laundry through: 26[5]
			Outdoor tap: Non-WELS: 16–30 WELS: Automatic irrigation device: max. 9[6] Hand held hose trigger: 7–12[6]	Spray type[7]: Full: 6 L/min Shower: 3.8 L/min Jet: 4 L/min Soaker: 6 L/min Mist: 2.2 L/min
Shower head	n.a.	n.a	Non-WELS: 15–25 WELS: 6–12	

Note: [1]Manufacturer specifications, [2]Standards Australia (1999), [3]Australian Government (2011), [4]Measured (adapted from Tjandraatmadja *et al.* 2011), [5]Measured by Roberts (2005), [6]Water Efficiency Labelling Scheme (WELS) is a water efficient rating scheme for all major water using fittings and appliances in Australia (Australian Government, 2011 (http://www.waterrating.gov.au/index.html)), [7]Measured by Water Conservation Group (2010), n.a. Not applicable.

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The most common end use applications for rainwater in dwellings are toilet flushing, washing machine supply and outdoor irrigation. Toilet flushing and washing machines typically require low flows, less than 6 L/min and 13 L/min respectively, and limited volumes of delivery, up to 4 to 6 L for a toilet cistern, 40 to 60 L for a front loader washing machine, and 100 to 150 L for a top loader washing machine (Tjandraatmadja *et al*. 2012).

The pattern of water supply also varies with end use (Tjandraatmadja *et al*. 2012). For instance, washing machines require a pump to stop and start multiple times during a wash. Tjandraatmadja *et al*. (2012) showed that the wash cycle in a top loader washing machine comprised two to three major water supply episodes of 40 ± 18 L each, and four to five short water top-up episodes in the spray cycle (Figure 6.10a). The rainwater pump operated on average for 21 ± 4 min. In comparison the wash cycle of a front loader washing machine was characterised by three to four water supply episodes of 11 ± 0.5 L each, and up to five small injections of water (Figure 6.10b). The rainwater pump operated on average for 5 +/–2 min during the cycle. In contrast filling a toilet cistern is a short duration single event where the pump operated for 0.5 min to 1 min depending on a half or a full flush, (Figure 6.10c).

Laboratory and in-situ studies show that the flow rate associated with end uses is the key influence on the energy intensity of pump operation, with low flow end uses typically using more energy per kL than high flow uses. In addition, Hauber-Davidson has also shown that pumping energy is barely affected by the pumping distance to the various end uses supplied, in a double storey house (Water Conservation Group, 2010). Retamal *et al.* (2009) estimated that the energy intensity associated with individual end uses varied from 0.4 to 2.9 kWh/KL for pumps with motor sizes between 0.5 to 0.9 kW. Talebpour *et al.* (2011) examined the energy associated with individual end uses in five dwellings equipped with a popular pump and switching valve system and measured energy intensities from 1.04 to 1.67 kWh/kL for garden irrigation and toilet flushing respectively. Hauber-Davidson and Shortt (2011) determined the energy for the operation of a washing machine, hose spray for outdoor irrigation, toilet cistern and a hot-cold water mixing tap and found specific energies ranging from 1.13 to 4.73 kWh/kL. Tjandraatmadja *et al.* (2012) verified that the specific energy for rainwater supply to various appliances (dishwasher, toilet cistern, top and front loading washing machines and header tank) depended on the end use and on the pump motor capacity, ranging from 0.39 kWh/kL to fill a header tank with a 0.2 kW pump, to 5.3 kWh/kL for a dishwasher with a 0.75 kW pump, as shown in Figure 6.11.

Hauber-Davidson and Shortt (2010) and Tjandraatmadja *et al.* (2012) have shown that the typical operating requirements for rainwater end-uses in urban dwellings (toilet flushing, washing machine and irrigation) are below the best efficiency point for the majority of pumps adopted in rainwater systems. This is shown in Figure 6.12, which reports on the service flow requirements for typical end uses, and the associated specific energy requirements for pumps of 3 different sizes (0.2 to 0.75 kW). Figure 6.12 shows more generally that low flow water supply events of short duration, such as toilet flushing and opening a tap briefly for hand washing, result in higher specific energy use than longer duration events with higher flows, such as filling a washing machine or garden irrigation. In comparison the best efficiency point for most pumps was achieved at flow rates greater than 25 L/min.

Ferguson (2011) verified, in a one-year study of 52 dwellings constructed after 2009 in Sydney, that 40% of rainwater pumping events are short duration events supplying volumes of 2.5 to 9.5 L, such as toilet flushing, whilst less than 20% required over 100 L (for irrigation and washing machine use), which are characterised by higher flow rates. Similarly, toilet flushing was also identified as the predominant end use for rainwater in Melbourne studies (Hauber-Davidson & Shortt, 2011).

Thus, a fixed-speed pump will often operate inefficiently and outside its optimal range for many of the end uses. Consequently, it is almost impossible to select a fixed – speed pump that is suitable for all water uses using the pump curve alone (as shown in Figure 6.6a).

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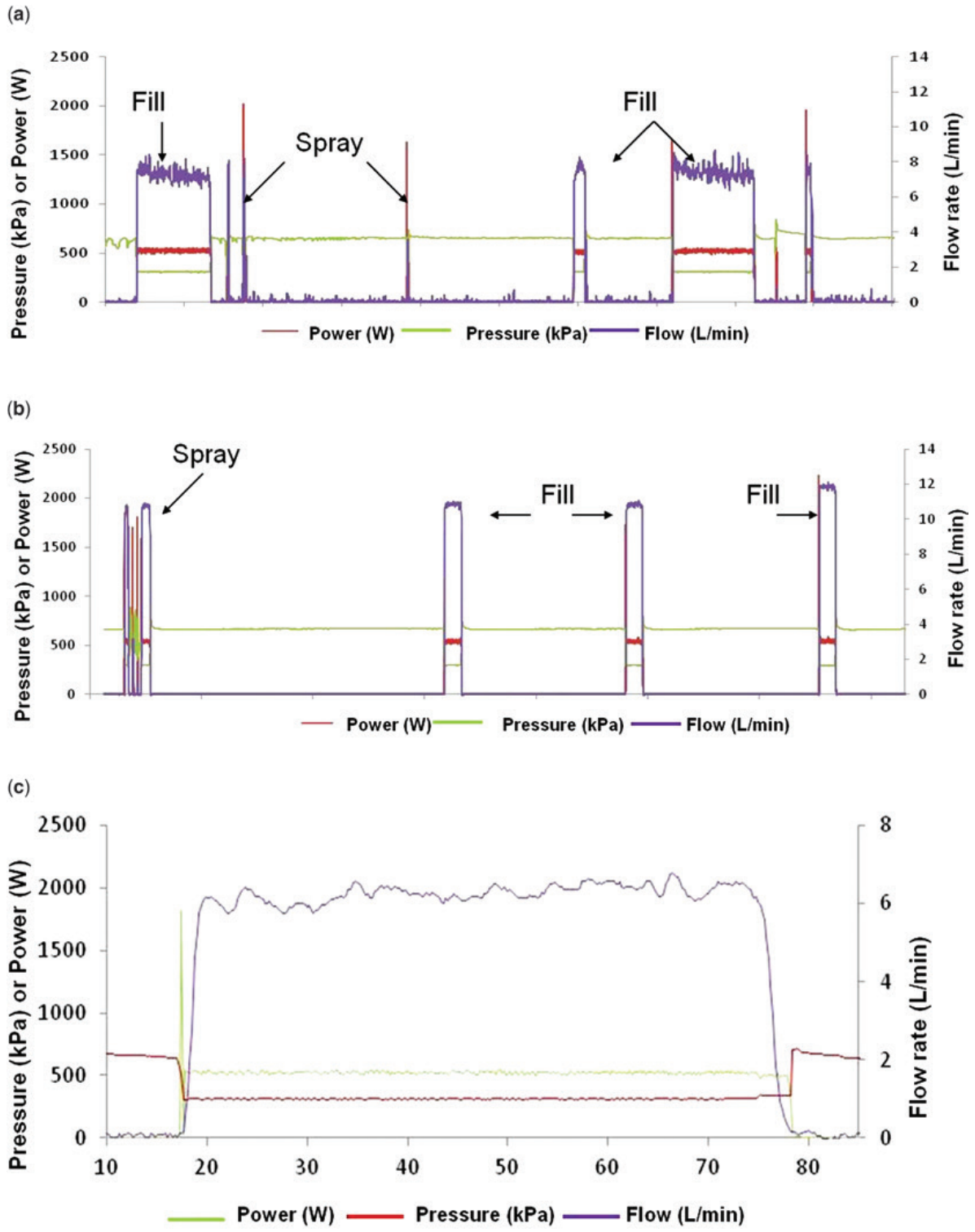


Figure 6.10 Pump energy use and water supply flow and pressure patterns during operation of (a) Top loader washing machine, (b) Front loader washing machine and (c) Filling of a toilet cistern. Note that the x-axis (time) does not have the same scale for all three events. (*Source*: Tjandraatmadja *et al.* 2012).

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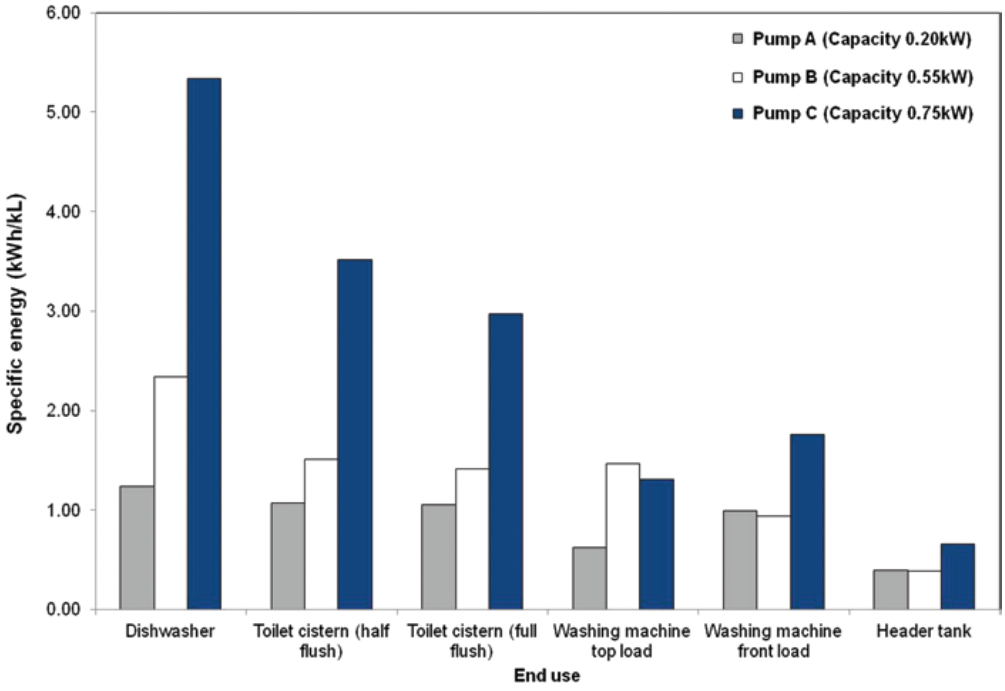


Figure 6.11 Specific energy requirements for rainwater supply to a dishwasher, washing machine, toilet cistern and a header tank using pumps of motor capacities ranging from 0.2 to 0.75 kW. (*Source*: Tjandraatmadja *et al.* 2012).

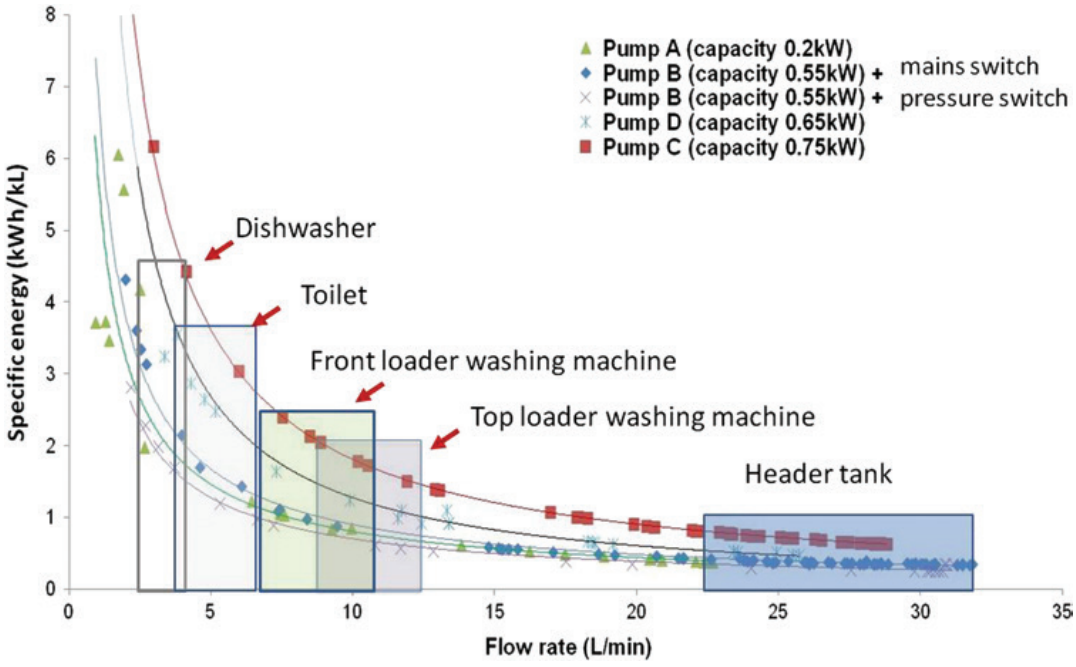


Figure 6.12 Relationship between specific energy and flow required for rainwater uses in a dwelling. (*Source*: Tjandraatmadja *et al.* 2012).

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Yet, pump motor size also matters as demonstrated in Figure 6.11. In Figure 6.12, pumps of various motor sizes fulfilled the individual service requirements of the common household end uses. In addition Pump B was tested also with an automatic water mains switch (i.e., when the tank is empty mains water is provided to the dwelling). In particular, the smaller size pumps were able to deliver a satisfactory level of service at a lower specific energy (Hauber-Davidson & Shortt, 2010; Ferguson, 2011; Tjandraatmadja *et al.* 2012, 2013).

Cunio and Sproul (2009) showed that under-sizing a pump runs the risk of limiting the flow rate and pressure of the rainwater supply. However, the common perception that a 'one size bigger is better' for pumps has resulted in many pumps being oversized and not optimised for their operating range, particularly in urban areas where rainwater supply is connected to limited end uses instead of to the entire household demand. However the quality of service (flow rate & pressure) does not vary markedly between a 0.2 kW and a 0.75 kW pump for supply to end uses such as toilet cisterns and washing machines (Tjandraatmadja *et al.* 2012). Most household rainwater users typically only notice the performance of their rainwater pump when they water the garden and expect a high flow rate and pressure similar to their mains water supply.

6.3.5 Dwelling occupancy and characteristics

Household occupancy, that is, the number of inhabitants in a dwelling, and the water use habits of the household impact the pattern and the frequency of rainwater use, and hence the *total energy* use in a dwelling. Dwellings with more occupants generally use larger volumes of rainwater and consequently consume more energy as shown in Figure 6.13. On the other hand, the pattern of rainwater use and the end uses will also differ among dwellings. For instance, a pump that supplies the toilet cistern alone tends to be less energy efficient than the same pump supplying both a toilet and a washing machine. This will also be influenced by how often the washing machine is used. In addition, indirect factors, such as climate, season and lifestyle, can influence water use patterns also impact energy use indirectly (Beal *et al.* 2010; Umapathi *et al.* 2012).

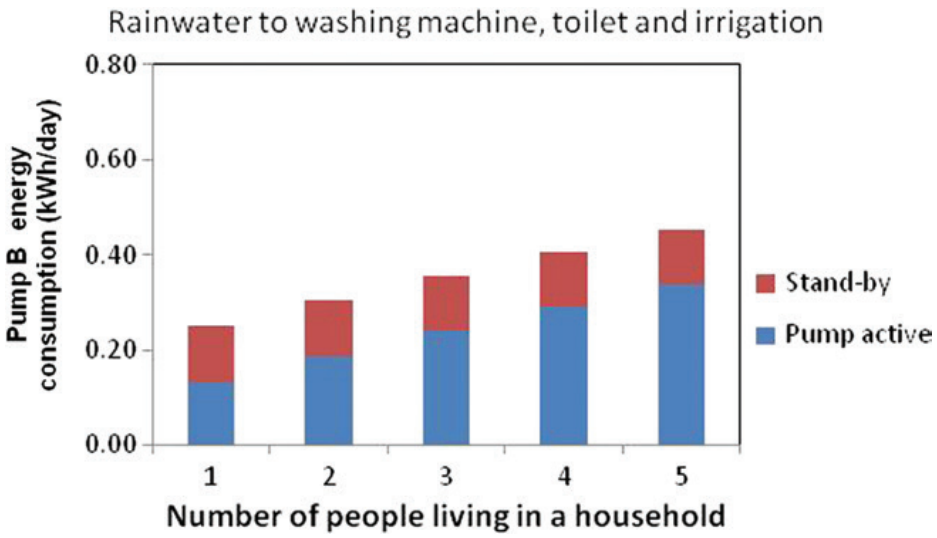


Figure 6.13 Estimated daily energy consumption for stand-by use and pump active use to supply rainwater to households of various sizes using pump B (0.55 kW) assuming a same end use pattern. (*Source*: Tjandraatmadja *et al.* 2012).

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Examination of individual tank set-ups confirmed that the high specific energy consumption in a number of dwellings was caused by incorrect system configuration and oversizing of pumps for the end use needs (Retamal *et al.* 2009; Hauber-Davidson *et al.* 2010; Ferguson, 2011).

6.3.6 Friction losses

The friction loss expected in an actual dwelling is determined by the plumbing characteristics and the flow rate of water. Details on how to estimate friction losses are provided in Cook *et al.* (2012), Swamee and Sharma (2008) and Tjandraatmadja *et al.* (2012). In domestic dwellings, rainwater tanks tend to be placed at a variety of locations and hence the distance between the rainwater tank and end-use appliances will vary with the design of the house, its land size and property layout. However, energy losses due to pipe friction as water travels through a rainwater system into a dwelling are considered to be minimal. Instead, the majority of the energy is used for running a pump for rainwater supply in the typical dwelling (Retamal *et al.* 2009; Tjandraatmadja *et al.* 2012). Retamal *et al.* (2009) estimated that losses in pumping energy in a typical domestic dwelling attributed to friction losses during delivery of water amounted to only 2%.

However, pump motor size can also impact on friction losses and care is required to prevent the oversizing of pumps for a required end use. For example, Cunio and Sproul (2009) reported an experiment where use of an oversized (high pressure) pump for the delivery of water to a toilet cistern resulted in 90% pressure losses in friction alone. However, on the other hand, Tjandraatmadja *et al.* (2012) verified in a laboratory model house that the friction losses within the pipes for a given system set-up did increase with pump capacity, but rather ranged from 1% to less than 6% of the total pressure supplied for pumps of motor sizes 0.2, 0.45 and 0.75 kW.

Overall, whilst friction losses are expected to constitute only a minor energy loss component, they also reinforce the benefit of matching pump size to end use and system requirements.

6.3.7 Other components

6.3.7.1 Pressure vessels

Pressure vessels can be used to mitigate the problem of inefficient pump operation, particularly where a pump is switching on and off frequently for short duration low flow rate water use events. A pressure vessel is a tank that contains an internal diaphragm which is partially filled with air as shown in Figure 6.14a. Pressure vessels are placed in-line after the pump and essentially store pressurised water. When the diaphragm in the pressure vessel is empty and a tap is turned on, the pump will start operating initially at maximum flow and will continue to pump until the pressure vessel is full as shown in Figure 6.14b. The next time a tap is turned on, water is drawn from the pressure vessel until the internal pressure reaches a threshold value, thereby delaying the start-up of the pump. The volume of water delivered by a pressure vessel is a function of the nominal volume of the vessel and the pump trigger pressure settings. However it is always less than the nominal volume as shown in Figure 6.15a.

Pressure vessels come in a range of sizes (nominal volumes of 5 L to over 1000 L). Small pressure vessels of 5 to 8 litres volume are sometimes installed with pumps to reduce the number of pump start-ups caused by small leaks in the water reticulation of a dwelling. The larger sizes are usually adopted for industrial applications.

A properly sized pressure vessel can reduce pumping energy by two mechanisms:

- It reduces the number of pump starts provided the volume required for a given end use is less than the water volume contained in the vessel.

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- The flow rate at which the pressure vessel is filled is often greater than that at which an appliance is filled. This is particularly advantageous for low flow end uses such as filling a half-flush toilet cistern or brief operation of a tap for hand washing a glass of water (Tjandraatmadja *et al.* 2012).

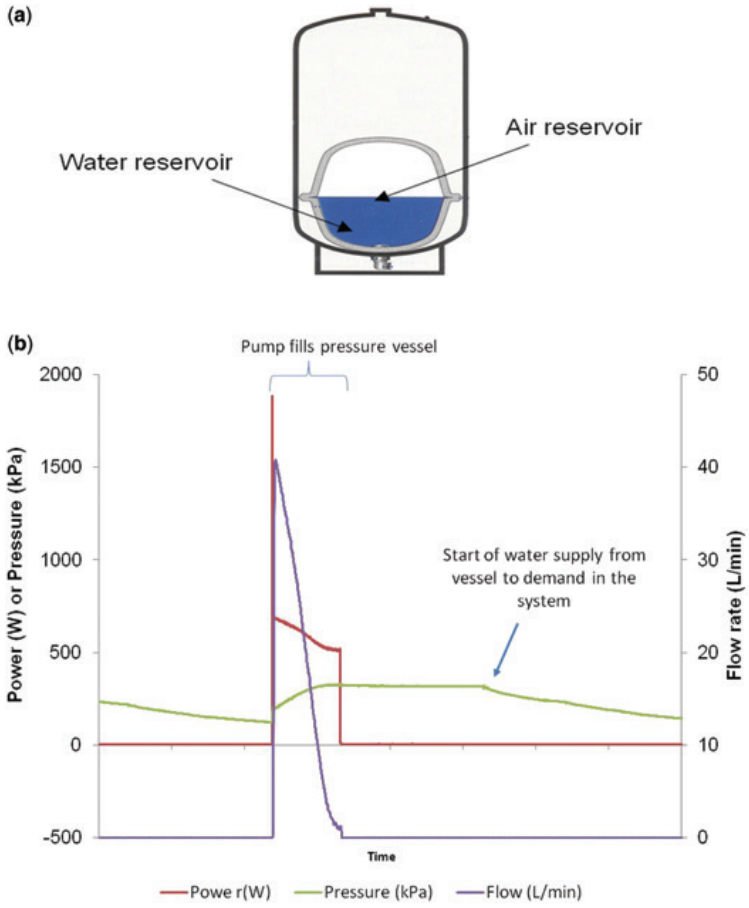


Figure 6.14 Pressure vessel details: (a) Schematic diagram of pressure vessel components and (b) Pump operation with pressure vessel operation (*Source*: Tjandraatmadja *et al.* 2012).

Energy savings are generated if the volume of water that the pressure vessel provides is equal to or greater than the total volume of water required for an end use. For instance, a 5 L pressure vessel provides low volumes of water (1 to 2 L) before the pump starts, reducing stop-starts associated with small leaks in the system. However it offers negligible energy savings (Water Conservation Group, 2010). In comparison a larger pressure vessel, such as an 18 L pressure vessel with a 0.75 kW pump, can provide up to 6.3 L of water prior to the start-up of a pump, thereby reducing the energy used for rainwater pumping, particularly for low duration and high energy intensity water uses. This is shown in Figure 6.15b where the addition of an 18 L pressure vessel halves the specific energy required for low volume end uses such as the supply to a tap for a short duration or dishwasher operation (Tjandraatmadja *et al.* 2011).

Some caution is required regarding the set-up for pressure vessels. Installation of a pressure vessel in a system with a mains switching device can cause the pressure vessel to malfunction as the switching device controls the pump on-off cycling via a flow sensor (Retamal *et al.* 2008).

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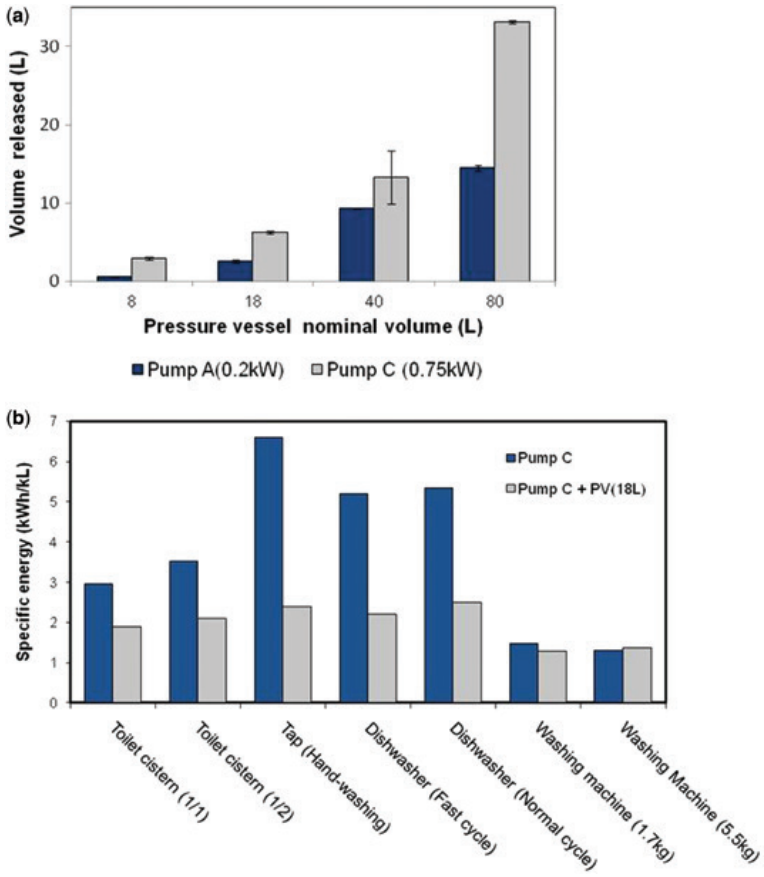


Figure 6.15 Impact of a pressure vessel on pump operation: (a) Volume of water released by pressure vessels of nominal volumes of 8 to 80 L coupled with pumps of 0.2 kW and 0.75 kW capacity; (b) Specific energy for rainwater supply to common end uses by a 0.75 kW pump with and without an 18 litre pressure vessel coupled. (*Source*: Tjandraatmadja *et al.* 2012).

6.3.7.2 Header tanks

A header tank is a localised storage vessel on the roof (or at similar height in a building). Water is pumped to the header tank and that supplies water by gravity to various end uses. This set-up is adopted in many parts of the world, for example, Asia, UK and South America. In Australia, header tanks can be found in commercial or industrial settings, but are not common in domestic residences.

Header tanks can provide large storage, (e.g., 100 to 300 L), reducing the number of pump start-ups compared to direct pump supply, and the pump operates at high flow rates to fill the header tank, increasing the energy efficiency. A properly sized header tank could provide the daily water needs of a dwelling with a single pump start-up per day, provided a proper switch is used. Thus in principle, header tanks could offer high energy savings for rainwater supply.

Laboratory studies in a simulated dwelling, shown in Figure 6.16, estimated that energy savings of 58% to 79% could be achieved by a 300 L header tank when compared to direct supply to individual appliances by pumps ranging from 0.2 to 0.75 kWh motor capacity (Figure 6.17). This is equivalent to a reduction in the specific energy for rainwater supply ranging from 0.39 to 0.66 kWh/kL depending on pump size (Tjandraatmadja *et al.* 2012).

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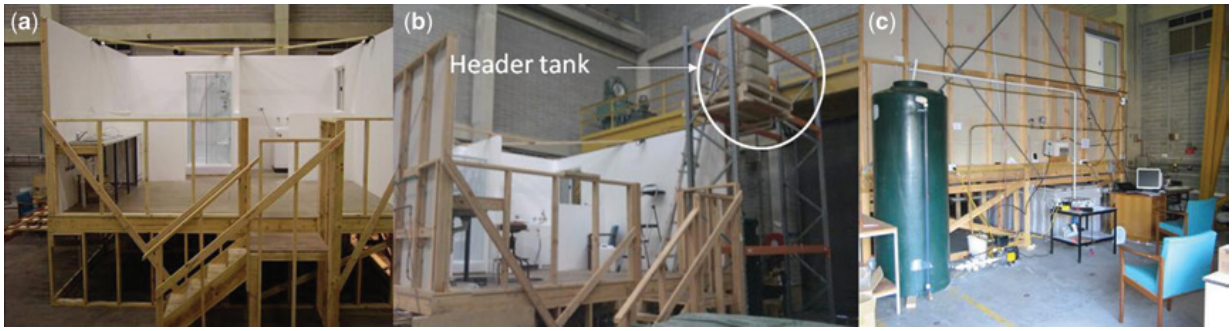


Figure 6.16 Simulated dwelling for evaluation of energy use for rainwater supply (a) Overview of major end uses (washing machine, toilet, taps and dishwasher), (b) Set-up for rainwater supply with a 300 litre header tank, (c) Rainwater tank supply and monitoring instrumentation.

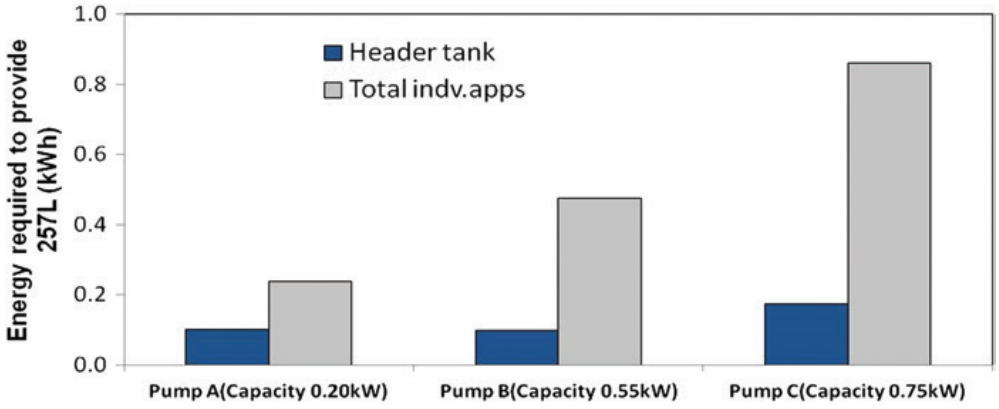


Figure 6.17 Energy use for rainwater supply using a 300 litre header tank compared to direct supply of individual appliances (*Source*: Tjandraatmadja *et al.* 2012).

The caveat, however, is that a minimum height is needed for gravity supply from the header tank to provide the minimum pressure to open the solenoid valves that control water ingress into the appliances. The installation adopted in Figure 6.14b placed the header tank at a height of 2.7 m above floor level, corresponding to the ceiling height, and provided a service pressure of <25 kPa, which was well below the minimum pressure requirements for operation of household appliances in Australia (31–100 kPa). However, by increasing the header tank to 5m, (higher than the ceiling height for a single storey dwelling) an adequate minimum service pressure of 50 kPa for toilet cistern filling would have been achieved. The appliances can also be manufactured to work on low pressures if there is a significant market for the industry to consider.

Therefore, in designing a header tank set-up, building design needs to allow adequate height for the header tank installation to generate sufficient hydrostatic pressure for solenoid operation (Tjandraatmadja *et al.* 2013). Alternatively, changes to the solenoid valve design in common appliances could be considered to allow for low pressure operation.

6.3.7.3 Different types of storages (under-floor bladders, gutter storage)

In urban areas, a variety of different rainwater storage methods have been adopted to overcome space constraints. For example, large plastic 'bladders' are sometimes used to store rainwater beneath the floor

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of older style houses and have the advantage of a flexible shape in addition to making use of 'dead' space. In one Sydney home with an under-floor bladder that was monitored, the rainwater system used a more powerful Venturi-style pump (a fixed-speed ejector pump that operates by creating a vacuum), to draw up the rainwater from beneath the house (Retamal *et al.* 2009). A combination of very efficient water use and a powerful pump caused the energy intensity of this particular system to be high at approximately 5 kWh/kL.

Some other innovative storage types also have the potential to reduce energy intensity, for example, gutter storages which provide some gravitational pressure, reducing pumping requirements (Retamal *et al.* 2009). However, other operational factors such as the potential mosquito breeding hazard may limit the uptake of such options. Overall, the type and location of storage also needs to be considered for optimising pumping energy.

6.4 REDUCING ENERGY USE FOR RAINWATER SYSTEMS – LESSONS FROM AUSTRALIA

Since 2007, Australia experienced a high uptake of rainwater tanks in urban areas. Rainwater tanks are found in 23% of suitable dwellings across major capital cities increasing to 43% in selected capital cities. Rainwater tank installation is particularly strong in new dwellings, with approximately 57% of all dwellings less than 1 year old in south east Queensland connected to rainwater supply (Government of Queensland, 2009; ABS, 2010). Australia has also had the largest number of studies which examined the energy associated with rainwater pumping in urban settings.

Marsden Jacob Associates (2011), Stewart (2011), Gurung *et al.* (2012) and Gurung and Sharma (2014) have examined the life cycle costing of individual tanks systems. Electricity costs for operation of a rainwater tank are considered minor and estimated to represent only 2% of total operating costs over the life of the tank in Gurung *et al.* (2012). Ferguson (2011) recorded low energy consumption for rainwater supply in 52 dwellings in the Sydney area, with a median energy consumption of 62 kWh per dwelling per year. In monetary terms, this is equivalent to AUS$15 per year assuming an energy intensity of 1.48 kWh/kL and current electricity prices of A$0.20 /kWh.

Notwithstanding the low costs associated with rainwater harvesting, the end use requirements for rainwater in urban dwellings in Australia cause pumps to operate well below their best energy efficiency point. Thus, there are significant benefits still to be gained by improving the energy efficiency in rainwater pumping through better matching end use service requirements and pump operation, and the use of ancillary devices such as pressure vessels and header tanks.

By adopting a smaller 0.2 kW pump instead of a 0.75 kW pump, electricity usage for rainwater supply in a typical dwelling can be reduced from 213 kWh per year to 66 kW per year, that is, a 73% reduction in energy consumption (Tjandraatmadja *et al.* 2012).

The use of devices such as pressure vessels and header tanks that could further reduce the energy consumption is uncommon, however their potential for energy savings has been demonstrated in laboratory studies (Tjandraatmadja *et al.* 2012) and in examples of dwellings where the energy intensity for pumping was 30–36% lower with the use of pressure vessels in-situ (see Section 6.3.7) (Retamal *et al.* 2009). The larger the pressure vessel with respect to the end use volume requirements, the least often the pump needs to start. However, almost no information is available to the public on the performance of pump and pressure vessels combinations.

Furthermore, header tanks coupled with an adequate level switch as previously discussed in section 6.3.7 have the potential to generate the largest energy savings of all ancillary devices and should be further examined.

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In addition, significant improvements could be achieved by further investment in product design in areas such as the development of pumps customised for low flow urban end uses; improving the design of mains switching valve systems to reduce energy consumption, and facilitate their integration with pressure vessels; and the redesign of solenoid valves in household appliances for low pressure operation.

Investing in education, greater emphasis in current design and set-up of rainwater pumping systems followed by the development of benchmarks and guidelines that can inform and assist consumers to better select pumps could further reduce the energy requirements and lead to more sustainable practices.

6.4.1 Policy considerations for rainwater system energy use

Policy and legislation can play a significant role in the uptake and set-up of rainwater systems and subsequently on associated impacts such as energy needs. In Australia, severe drought and increase in demand on water resources due to population growth resulted in the introduction of demand management, water use efficiency and the diversification of water sources through policy and legislation (Tjandraatmadja *et al.* 2012). Across Australia, education campaigns, financial incentives and/or mandatory water demand reduction targets have driven the uptake of water efficient appliances and rainwater tanks (Tjandraatmadja *et al.* 2013).

Because adoption of rainwater tanks has focused on reducing mains water consumption, little consideration has been given to energy by industry, government or rainwater users. In addition, the awareness and expectations of tank owners regarding the operation of rainwater systems varies markedly in urban settings compared to rural settings where tanks are the sole source of water supply (Gardiner *et al.* 2008; Gardiner, 2009).

Overall, there is a lack of benchmarks and policy in Australia and around the world on energy efficiency for rainwater pumps and there is limited awareness and guidance to tank owners on how to minimise their energy usage or how to compare pump performance based on energy efficiency (Tjandraatmadja *et al.* 2012; Hauber-Davidson & Shortt, 2011). Typically, home dwellers rely on the knowledge of rainwater system and pump distributors and installers for system selection (Tjandraatmadja *et al.* 2012).

At the same time, the design of household pumps has not evolved at the same pace as water efficient appliances and demand management approaches. Whilst water requirements for end uses have decreased over time, the pumps sold for rainwater pumping are designed to achieve optimal performance at high flow rates, which is at odds with the low flow rates needed for most internal end uses as discussed in section 6.3.4.

The uptake of rainwater tanks in urban areas as a supplementary water source resulted in a large variety of pumps and system set-ups with large variance in the energy performance and many of the systems currently installed in dwellings may be oversized for their service requirements.

6.5 CONCLUSIONS

There is a need for a holistic perspective to assess the overall performance of rain supply systems, including cost and environmental implications such as energy consumption. Traditionally, rain tanks have been introduced as a water saving measure, but with little concern about optimising energy requirements until tens of thousands of systems had been installed (in Australia). Reducing the energy associated with rainwater supply will lead society closer to sustainable practices.

The current experience shows that:

- In assessing the energy efficiency of a rainwater supply system, it is important to consider not only the pump but the whole rainwater supply system including the intended end uses in a dwelling;
- Pumps are designed so that high flow rates correspond with lower specific energies. However the typical residential end uses often require low flow rates, causing pumps to operate well below their best efficiency point;

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- Pump size, (i.e., kW), has a dominant effect on specific energy. Undersizing a pump can risk providing a poor level of service. However, more often, pumps in rainwater systems are oversized, leading to unnecessary energy consumption;
- Total energy use per day for a dwelling can be calculated for the various appliances connected to rainwater. Whilst the literature shows large variability in the energy associated with rainwater pumping, the median specific energy across Australian studies ranges from 1.4 to 1.8 kWh per kL. Whilst this is in the upper range for mains potable water supply in Australian capital cities (0.06–1.84 kWh/kL), it is much lower than the energy required for recycled water using reverse osmosis (2.8 kWh/kL) and desalinated sea water (3.5 kWh/kL);
- The energy use from internally plumbed rainwater systems represents only a small fraction of total household energy use (about 2% of average household use) (Gurung *et al*. 2012). However the overall energy and its variability could be reduced further. A number of simple measures can assist in reducing the energy requirements;
- Header tanks have the potential to significantly reduce specific energy. Laboratory studies in a simulated dwelling identified energy savings of 58% to 79% could be achieved by a 300 L header tank. However, their installation height in a dwelling needs to ensure that the hydrostatic water pressure will be sufficient to operate the solenoids on most domestic appliances. Alternatively the design of appliances could be modified to work at low water pressures. Header tanks do not seem to be viable in single story dwellings under current conditions;
- Pressure vessels reduce specific energy values by reducing the number of start-ups but more importantly because of the high flow rates on their refill cycle. In-situ tests undertaken at two households with pressure vessels reduced the overall energy intensity of rainwater supplied by 30–36% and lab studies have shown that energy savings will be proportional to the pump, vessel size and end uses in a dwelling, for example, the specific energy for filling a top loading washing machine using a 0.55 kWh pump is 1.47 kWh/kL, however this can be reduced by 7% and 50% respectively by the addition of vessels of 40 and 80 L capacity. This will further require life cycle cost analysis for comparison.

Overall, better education can reduce the installation of oversized pumps. It is important to advance the awareness and education among manufacturers, the plumbing industry, consumers and government on the energy associated with rainwater pumping systems. Such measures could lead to significant improvements in the design, and the overall efficiency and sustainability of rainwater systems and their components.

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Chapter 7

Management and operational needs for urban rainwater tanks

Magnus Moglia, Andrea Walton, John Gardner and Grace Tjandraatmadja

ABSTRACT

Urban rainwater tanks are infrastructure assets that provide important public and private benefits, but which also have operational and maintenance requirements to avoid key risks. Adequate asset management should be in place to address any potential risks. The risks of inadequate management of urban rainwater tanks relate primarily to non-achievement of water savings targets as well as public health risks. Public health risks arise from water quality issues, but also from the risk of mosquitoes breeding, thus potentially spreading arbovirus diseases such as dengue fever to humans. Failure of rainwater tanks due to poor maintenance or installation practices can lead to the risk of collapse of walls or fences due to rainwater tanks leaking or leaning onto them. The management requirements are not onerous for a single rainwater tank; however ensuring that the entire stock of rainwater tanks is maintained is a complex task, given their distribution in private backyards as well as ownership. The main difficulty for urban water planners and health officials is that private owners of rainwater tanks are, in many cases, not motivated to undertake maintenance. Therefore there is a need to find strategies, preferably in cooperation with owners, to ensure that private rainwater tanks remain both functional and safe.

Keywords: Asset Management; Risk Assessment; Socio-technical analysis; Water Supply.

7.1 THE NEED FOR MANAGING RAINWATER TANKS

This chapter focuses on the management and maintenance aspects of rainwater tanks; a topic that is scarcely covered in academic literature although some basic guidelines exist authored by the WHO (2008). A handful of household surveys have partially considered this topic (Rodrigo *et al.* 2010; Karim, 2010; Gardiner, 2009). These surveys have explored self-reported maintenance behaviours, but only one report has covered the physical inspection of rainwater tanks (Biermann *et al.* 2012). In the context of rural Uganda, Baguma and colleagues (2010) have shown a positive correlation between experience in managing rainwater tanks, self-reported maintenance behaviours and public health outcomes; but it is

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noted that these communities use rainwater for potable purposes. In Botswana, Gould (1996) has argued that maintenance requirements and associated problems is one reason for the poor level of uptake and diffusion of this technology at the time. With the rapid and widespread uptake of rainwater tanks in Australian urban settings, research has been undertaken to understand maintenance and management needs for rainwater tanks (Moglia *et al.* 2013a; Moglia *et al.* 2012b; Moglia *et al.* 2013b) and this research is reported in this chapter. Whilst the chapter content is influenced by the situation in Australia, many of the conclusions and findings should be applicable to other locations globally as well.

Rainwater tanks are water management infrastructure assets, contributing to household water supply in both urban and rural settings. An advantage of rainwater tanks when compared to other water supply technologies is the relatively small scale of the systems; they do not require any economy of scale to become viable except optimal rainwater tank sizing, based on demand and supply modelling. This makes them particularly popular in rural areas where population densities are low. They have also become increasingly popular in urban areas, even when rainwater tanks are not always the cheapest option, in the belief that rainwater tanks are 'more environmentally friendly'. In several states in Australia, the mandated requirements for rainwater tanks in new dwellings have led to a very large increase in the number of rainwater tanks in Australian cities.

Unlike rural settings, the risks to an urban household's water supply of not maintaining a rainwater tank are relatively small. In rural settings, with no alternative water supply, failure of the rainwater tank will lead to a loss of supply, the need for immediate attention, and potentially having to truck water onsite in the interim. In such settings, rainwater is often used for drinking water, and thus poor water quality potentially poses significant and immediate health risks to the consumers of the water. In contrast, in urban settings, there is almost always an alternative water supply, and failure of the rainwater tank may go un-noticed. Furthermore, it is relatively unusual that urban dwellers, at least in places like Australia, would use rainwater for drinking purposes. This means that in urban settings the risks of rainwater tank failure are relatively low because the consequences of failure are low. This situation is referred to as the 'low stakes' setting of urban rainwater tanks. Due to the low stakes setting of urban rainwater tanks, it is thought that the motivation for maintaining rainwater tanks in urban settings is low. There is a growing body of evidence confirming this premise. However, although the risk of failure of an urban rainwater tank is less than that for rural rainwater tanks, a number of important and related risks persist in rainwater tank systems, and these are summarised in Table 7.1.

7.2 ISSUES TO CONSIDER IN THE MANAGEMENT OF URBAN RAINWATER TANKS

The management of rainwater tanks across a city requires the understanding of a number of issues:

- Irrespective of whether there is a serious problem with rainwater tanks or not, there is a need to develop management strategies if it is reasonable to expect that many rainwater tanks are not kept in a good condition. This can have serious consequences for public health risks and/or for water planning.
- The maintenance needs, which vary depending on how people use the collected rainwater, the risk of pollution and the public health risk of mosquitoes breeding in the rainwater tank.
- The behaviour of rainwater tank owners, which is influenced by:
  - The reasons for installation of rainwater tanks across the urban landscape, as these influence maintenance behaviours.
  - The historical context of rainwater tanks: the past experiences with tanks in the local area.

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Table 7.1 Risks of urban rainwater tank related failure events. The consequences, likelihoods and risks are rated as L (Low), M (Medium), or H (High).

Failure events	Consequence (L, M, H)	Likelihood (L, M, H)	Risk (L, M, H)
Foundation becoming unstable or leaning	H: With a rainwater tank's weight, an unstable or leaning foundation may lead to collapse of walls or fences, or the rainwater tank itself may fall off, with potentially fatal consequences.	L-M: If overflow has not been correctly installed, the water may erode the foundation or make it unstable. The foundation may also be poorly installed to start with.	M-H: The risk of this type of event may be catastrophic, but the likelihood can be managed through good design and installation and checks after installation.
Faulty switching or top up valves	M: Switching valves are often installed to allow mains top up into rainwater tanks or a direct connection to mains supplies. When these devices fail, the water savings potential is significantly reduced.	H: Indications are that this is a very common fault.	H: With a severe consequence of considerably limiting any water savings, and being a common fault, this is a high risk issue.
Broken pump	M: When a pump fails, it makes it difficult to use the rainwater in the rainwater tank. But the pump can be repaired or replaced (at a cost), thus restoring the capacity of the tank.	M-H: Data indicates that problems with pumps are common, and that it may be necessary to replace pumps every 3–5 years.	M-H: The remaining risk is due to the fact that broken pumps are often not noticed (particularly in systems equipped with automatic switching between rainwater and mains water), and thus making the tank ineffective as a capture/storage device. This risk can be managed through inspections and repairs.
Blocked gutters	L: Blocked gutters and screens limit the flow of water into the tank and can also impact on the water quality in the tank.	H: The likelihood of this type of event is very high; especially if there are over-hanging trees.	M: This is a low-consequence event, but due its high frequency, if it is not managed, only a small amount of water will be collected.
Removal or damage of mosquito meshing	H: Mosquitoes in tanks in urban settings are generally considered by health departments as a serious issue, potentially leading to the spread of diseases such as dengue fever.	L: Good design and rigorous installation should minimize the likelihood of this type of event. A regular check of meshing can easily be carried out and replacement of the meshing is inexpensive.	M: Whilst the likelihood of this event is low and manageable, the consequence can be very high, particularly in places where serious mosquito born disease may spread.

(*Continued*)

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Table 7.1 Risks of urban rainwater tank related failure events. The consequences, likelihoods and risks are rated as L (Low), M (Medium), or H (High) (*Continued*).

Failure events	Consequence (L, M, H)	Likelihood (L, M, H)	Risk (L, M, H)
Poor water quality	L-M: People can get ill if they ingest poor quality water. Poor water quality may also lead to discolouration of toilets, other fixtures or washing.	M: The likelihood of poor water quality is situation dependent. Discolouration can be managed by regular cleaning of gutters although leaves may contaminate water in wet downpipe systems. Where small mammals such as possums and birds can access the roof, a number of pathogens are likely to be found in the water.	M: Water quality in tanks is difficult to manage. If alternative potable water sources are available, rainwater should not be used for drinking purposes. Alternatively, proper disinfection treatment is recommended. If so, this risk is limited.
Incorrect plumbing	L-M: The consequences depend on the type of error. Failure to properly install backflow prevention can lead to contamination of drinking water.	L: This appears to be a relatively common problem but should be identified in post-installation inspections and therefore the likelihood is Low, subject to such checks.	L: The consequences depend on what error has been made, but the risk is manageable.
Sedimentation in tank	L: Unless water is used for drinking purposes this only really becomes a problem if severe sedimentation exists and water quality is affected or pipes become blocked.	M: Sedimentation is inevitable but it is usually a very slow process and can be managed with regular desludging.	L: This is not a serious issue, but desludging is necessary at regular intervals (typically at intervals of minimum 3 years).

- The practice of installation and design of rainwater tanks, which may or may not be influenced by guidelines and regulations.

Furthermore, if plans for rainwater tank management are to be established, it is also important that strategies are developed which are:

- Accepted by stakeholders;
- Effective in achieving outcomes; and
- Aligned with the current legislation and regulation.

The stakeholders in this instance are those individuals or organisations with a strong interest or concern relating to rainwater tanks. Rainwater tank owners, plumbers and tank industry professionals, government agencies, local government and urban water planners, property developers and house builders, and health officials all have an interest in rainwater tank installation and maintenance.

Strategy outcomes would usually be defined by the stakeholders, in what they hope to achieve or avoid with the rainwater tanks. These issues are described in detail in this Chapter for the benefit of the wider water professional community across the globe. A methodology for exploring the relevant issues and the associated management strategies is described. The application of this methodology will be demonstrated using a case study in South East Queensland (SEQ), Australia. SEQ is a primarily urban area. It is acknowledged that extrapolation of study results to other countries is influenced by the context of the case study, but it is also noted that there is little written on the topic for other locations. This is an emerging topic with very little prior research to report on.

7.3 PRIVATE OWNERSHIP VS PUBLIC BENEFIT

Why is it a public concern if private rainwater tanks are not functional and safe? Why is it not just the problem of the individual owners? We argue the following premises make it a public concern:

- Rainwater tanks are sometimes a legal requirement for home owners under local policies. For example, in some circumstances local building regulations require rainwater tanks to be installed, or rainwater tanks have been a key feature in getting building approvals.
- Rainwater tanks that are not maintained may pose public health risks, via poor water quality (if used for drinking), mosquitoes breeding, or structural collapse of foundations, walls or fences. This is not acceptable, as health risks may impact on others and not just the rainwater tank owners.

There are compelling reasons why urban water planners have a strong interest in keeping rainwater tanks functional. Rainwater tanks can play an important role in ensuring that water supply is adequate for the water demand of the city; the potential for water savings is further described in Chapter 3. By installing rainwater tanks, homeowners are reducing the load on mains water supply. This means that if rainwater tanks are not maintained, increased demand is placed on mains water supplies. To deal with increased demand, new supply infrastructure may be required or fast-tracked with a consequent increase in the price of water. Water planners also see rainwater tanks as helping to reduce urban stormwater flows and the pollution of the city's waterways; this is considered in more detail in Chapter 13.

Furthermore, if rainwater tank owners have received public sector rebates for the installation of their rainwater tank, ensuring the ongoing optimal functioning of the rainwater tank will maximise the return of public investment in rainwater tank assets. It could be argued that non-subsidised tank owners have invested in public infrastructure providing urban water supply at their own expense. This can be perceived, although disagreement about this exist, as an implicit social contract between citizens and the government, given

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it is the government's responsibility to provide basic services to the urban community. Viewed from this perspective, the government is morally and perhaps even financially obligated to rainwater tank owners.

An implication of private ownership of rainwater tanks is that it is likely to be perceived by some as over-stepping the mark if government and/or water utilities penalise rainwater tank owners that do not look after their rainwater tank adequately. Similar community attitudes may arise if such organisations were to mandate owners to maintain their rainwater tank.

In situations when water tariffs are based on consumed water alone, with no separate volumetric tariff for wastewater disposal, water service providers may also argue that rainwater tank owners should be charged for rainwater used for indoor purposes such as toilets or laundry as they pose a burden on wastewater collection, treatment and disposal systems. Moreover collection, treatment and disposal of wastewater is often more expensive than providing water in the first place.

These issues combine to create a situation that is ripe for controversy and discussion. However, it can also be argued that the motivations of urban planners, health professionals and rainwater tank owners are aligned. Also, it is in the best interest for rainwater tank owners to ensure their tanks provide value rather than become a liability, especially as rainwater tanks are often perceived to increase the value of a property. This means that stakeholder motivations for keeping rainwater tanks maintained and well-managed are aligned, and that collaborative solutions are recommended rather than 'command and control' type strategies, which are likely to alienate rainwater tank owners and engender non-cooperation. Some sort of regulation of certain aspects of rainwater tank management may still be required in addition to collaborative solutions; for example, if there is a high risk of mosquito born disease. As an example, for onsite sewage systems, the public health risk from treatment failure is considered so high that maintenance is mandated by most state regulators or local authorities at the owner's expense. Such moves were initially resisted by the community, but this obligation is now widely accepted.

7.4 FACTORS THAT INFLUENCE CONDITION

Rainwater tanks are relatively straightforward infrastructure systems, when considered on an individual basis. In fact, a well-designed rainwater tank that has been adequately installed and maintained is likely to operate in a safe and effective manner, although individual components of the system will break down at the end of their asset life. Through our research, it has been found that water experts agree that maintenance, design and installation are the fundamental factors that impact on the likely condition of rainwater tanks.

7.4.1 Maintenance

Rainwater tanks need to be maintained to ensure their efficient water capture and to minimise public health risks. The maintenance needs are relatively well-established, as shown in Table 7.2. The World Health Organisation notes similar maintenance activities, but are not specific regarding frequencies (WHO, 2008).

7.4.2 Design

In Australia, the Rainwater Tank Design and Installation Handbook (Standards Australia, 2008) is the key reference document providing guidance on design and product issues. There is a vast array of designs, materials and types for rainwater tanks and those differences can impact on performance, ease of access, as well as the need for maintenance. A number of plumbing professionals and industry representatives have indicated that, among the various rainwater tank systems, there have been a number of components with common faults, such as poor design restricting access for cleaning and maintenance, poor durability

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or inadequate quality (Moglia *et al.* 2012b). There are, however, quality products available at competitive prices that fulfil their intended purpose and are easy to maintain. In each local context, different products and services are on the market – and it is important that there is guidance to customers on the performance of different products, but this is currently scarce, limited to specialist magazines or rainwater tank enthusiasts' forums. Future innovation in products and designs also has the potential to remove much of the maintenance needs of rainwater tanks, for example by developing switching valves that require minimal maintenance (inspection programs are yet to confirm what types of switching valves that require minimal maintenance) and development of monitoring systems that will enable notifications to the owner of any faults.

Table 7.2 Recommended inspection and maintenance activities for rainwater tanks.

Frequency	Activity	Maintenance required
3 months	Inspect and clean gutters.	Remove leaves and debris.
	Inspect and clean first flush devices and leaf guards on rainheads.	Clean, repair or replace if necessary.
	Check screens on overflow outlet.	Repair or replace if necessary.
	Check switching valves	Repair or replace if necessary.
6 months	Check roof and flashings for defects and remove overhanging branches.	Repair if necessary and remove overhanging branches.
	Checks tank for defects, ensure screens and lids are in place and functional.	Repair if necessary.
	Check water quality.	Identify cause for quality change, if any.
	Check rainwater taps have correct signage.	Repair or replace if necessary.
	Check pump for operation, noise, pressure, leaks and acoustic enclosure if applicable.	Repair or replace if necessary.
Annual	Check tank support for structural integrity.	Repair or replace if necessary.
2–3 years	Check sediment level in tank, and desludge if necessary[1].	Organise removal with a qualified contractor if sediments pose a risk to block tank outlet.

Source: Adapted from guidelines authored by Queensland Health (2007) and Standards Australia (2008).
[1]*Note:* HB230 (Standards Australia, 2008) recommends placing of rainwater outlets to dwellings at a minimum height to prevent uptake of sludge upon water extraction. In addition, it recommends desludging at a frequency of 2–3 years, however sludge build-up varies with tank set-up and gutter maintenance. Note also that, in urban areas, mandated uses are restricted to non-potable uses (toilet flushing, washing machine and outdoor irrigation), hence the risk of ingestion by users is considered low.

7.4.3 Installation

Installation of domestic rainwater tanks can be of variable standard and can present problems to the rainwater tank owner if installed incorrectly (Moglia *et al.* 2011c; Moglia *et al.* 2012a). Rainwater tanks are usually installed by plumbers or licensed tradespersons. However, many are installed by the householder. Problems with installation may lead to issues such as faulty drainage and plumbing connections, inadequate pump sizing, and incorrectly installed mosquito meshing or first flush devices. Different industry codes

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govern rainwater tank installation and vary between different jurisdictions. For example in Queensland, Australia, the location of our case study, certification of rainwater tank installations is two-part. An accredited building certifier certifies the installation because rainwater tanks are defined as structures under the Building Code; and a plumber inspects the connections to water fixtures and piped water supply because this falls under the local Plumbing Code. Despite such differences, post-installation inspection of rainwater tanks is a good way to ensure that rainwater tanks are appropriately installed, although this requires the inspection protocols to be sound, and for inspectors to be knowledgeable to ensure standards are maintained.

7.5 LOCAL CONTEXT

The local context is an important factor in rainwater tank management. Specifically, it needs to be acknowledged that rainwater tanks exist in a regulatory and legal environment; and any strategy will need to consider the socio-psychological aspects of the domestic rainwater tank owners. Regardless of situation, without the broad cooperation of rainwater tank owners, any strategy to manage rainwater tanks is likely to fail. Even if maintenance were mandated as per onsite sewerage systems, it is likely that upholding such regulations would still be largely dependent on community cooperation.

7.5.1 Local regulatory environment

For the purpose of our topic, the regulatory environment relating to rainwater tanks in a given location is important. In some locations, regulatory or legal frameworks relating to rainwater tanks may not exist, or if such frameworks do exist, may not be widely adhered to. In other locations, such regulations may be stringent and people tend to follow them. The key components of the regulatory environment include:

- Whether domestic rainwater tanks are mandated (i.e., a legal requirement for new dwellings) or rebated (incentives for the purchase and installation of rainwater tanks), and so on. The reasons why people install rainwater tanks influence the behaviour of tank owners (Mankad, 2012; Mankad *et al.* 2012; Mankad *et al.* 2013) (see Chapter 8).
- The available technical guidelines to support rainwater tank owners, developers and plumbers in installing and maintaining rainwater tanks (Standards Australia, 2008; Standards Australia, 2004; WSAA, 2002; Queensland Government, 2011; Queensland Health, 2007).
- The approval process to certify that rainwater tanks have been designed and installed appropriately. These may follow the process outlined in Table 7.3. For example in the case of South East Queensland, a number of agents are involved throughout the process (Moglia *et al.* 2012a).
- Guidelines and legal requirements regarding public health issues. What is the legal requirement to ensure that mosquitoes are not breeding in the rainwater tank? What are the guidelines and legal responsibilities relating to using the rainwater for drinking and other purposes? What organisation is responsible for making sure that domestic rainwater tank owners comply with public health related legal requirements? In the case of South East Queensland, local councils are responsible for this.
- Stakeholders. What agencies have vested interests in making sure that rainwater tanks are adequately maintained? Urban water planners and health officials, but also environmental managers, should have an obvious interest in this topic. It is likely that it is these stakeholders that will have to drive a management strategy – assuming they are given adequate resources.

The roles of various agencies, departments and stakeholders vary between jurisdictions. There are also relevant guidelines regarding design and installation, as discussed in Sections 7.4.2–7.4.3.

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Table 7.3 Process for installation of rainwater systems.

Step	Relevant documentation	Agent responsible for step
Government/Regulatory requirements	Building codes of Australia • Setback distances • Height restrictions • Source of rainwater/stormwater catchment • Plumbing code of Australia and AS/NZD series • Rebates eligibility	Government
Site conditions assessment and product selection	System design including • Tank type • Pump • Filtration	Developer, builder or homeowner
Install tank and connections	• HB230 for technical guidelines • Local guidelines • Pump • Filtration, and so on	Developer, builder, third party or homeowner
Provide documentation	• Regulatory reporting • Rebates (must be certified by plumber) • Certificate of installation by certified building inspector • Informing client of on-going maintenance program	Developer, builder or homeowner
Ongoing maintenance	• Local guidelines • Manufacturer's instructions	Homeowner, third party

Source: Adapted from HB230 (Standards Australia, 2008).

7.5.2 Understanding behaviour

Tank maintenance is a voluntary behaviour, unless (or until) some form of regulation is introduced. Tank maintenance actually reflects a suite of different activities, performed at regular but infrequent intervals (see Section 7.4.1). Psychological research suggests that the drivers of this sort of voluntary behaviour are twofold: a *motivation* for keeping the tank maintained; and a sense of one's own capability (or *self-efficacy*) in being able to undertake maintenance activities (Walton & Gardner, 2014; Walton *et al.* 2012).

7.5.2.1 Motivation

The motivations that drive tank maintenance can be grouped into three broad sources. Firstly, individuals are motivated to take action to the extent that their perceived benefits outweigh the costs of keeping the tank maintained. The 'costs' in this situation reflect concerns for the effort, inconvenience, and time required to conduct maintenance, as well as financial cost. The benefits of rainwater tank system maintenance also reflect a range of factors, for example, it may provide access to a personal source of water where the rainwater tank owner has autonomy regarding its use for garden watering, swimming pool top-up, or an indoor connection to the washing machine and toilets. Many rainwater tank owners also regard tank water

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as cheaper than mains water – 'it comes for free as rain from the sky'. This perceived cost advantage, although probably incorrect (see Chapter 12), is seen as a benefit to the home owner, especially in a situation of increasing mains water prices and other cost of living pressures. Some rainwater tank owners also strongly support water conservation, and see rainwater tank ownership as a way of drawing maximum benefit from water that would otherwise be 'wasted', thereby helping to mitigate future drought impact.

As well as these personal benefits that are associated with keeping a rainwater tank maintained, some tank owners feel what is best described as a sense of 'moral obligation' towards rainwater tank system maintenance. Such feelings relate to the notions of preventing public health risk associated with mosquito breeding in unmaintained rainwater tanks, and of reducing the overall demand for mains water. This type of motivation is especially strong in people who have experienced severe drought and/or grew up in rural areas and were fully dependent on rainwater tank water. Further, the idea of maximising the return on money invested in the rainwater tank can also appeal to a person's sense of obligation and act as a motivator to keep the rainwater tank maintained. Many people received their rainwater tank through a government subsidy or rebate and are aware of the considerable public money invested in providing households with roof-water harvesting facilities. People who paid for their own rainwater tank system, often as part of building their own home, may also feel a sense of obligation in keeping it maintained and not wasting their own investment.

The third source of motivation for keeping a tank maintained is the rainwater tank owner's self-image: a perception of themselves as someone who keeps things well maintained and in sound working order. For some people, this self-image helps to shape their behaviour, prompting water tank maintenance along with other household maintenance tasks, like pest control, swimming pool and garden maintenance. Self-reported confidence to maintain things may also reflect a capability to undertake practical tasks.

These three sources of motivation obviously can vary among tank owners, and can vary depending on the proposed use of the tank water. Research has indicated that motivations for keeping a tank maintained were lower in those tank owners that only used their water for outdoor use, and higher amongst owners that had their tanks connected to indoor devices. This finding supports other research, which suggests that the level of personal contact someone has with a water source is an important driver of how they behave towards that water (Hurlimann, 2011; Mankad & Tapsuwan, 2011). For example, when recycled water is used for outdoor use, people find it more acceptable than if it is for indoor use. As personal contact with the water increases, for example using the water for showering or drinking, the more people become concerned about aspects of water quality such as colour, odour and safety (Nancarrow *et al*. 2010).

7.5.2.2 Self-efficacy

This is the second broad driver of tank maintenance: this construct revolves around issues of knowledge, skills, and capacity for performing the maintenance tasks. The starting point for a sense of efficacy is a degree of awareness of the problem, in this case awareness that water tanks need to be maintained. The majority of tank owners are not aware that a rainwater tank needs to be regularly maintained (Walton & Gardner, 2014). Also, self-efficacy requires knowledge of the actual maintenance tasks: how and when they are to be done. The tank owner then needs to feel a sense of confidence in being able to perform these tasks. This confidence may involve the physical capability to actually perform the tasks, for example depending on age and fitness levels, such as clearing gutters and checking first flush devices. Another factor is the financial capability and willingness to outsource the tasks, such as desludging the tank. Successful outsourcing will also depend on access to suitable services. Self-efficacy can be viewed as a 'necessary condition' for tank maintenance: even if motivation levels are high, if a person does not feel capable of performing the required tasks, the tank may go unmaintained.

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As well as the internal drivers of tank maintenance described above, there are other external factors that could influence tank maintenance behaviour.

7.5.2.3 External influences

Regulations, penalties, incentives, education programs and awareness campaigns are all policy instruments that may potentially influence tank maintenance behaviour. However, these approaches may or may not result in increased tank maintenance because they interact with a person's views and opinions of the approach, as well as with their own levels of motivation and self-efficacy. For example, a person who feels very motivated and capable of keeping a tank maintained may view any form of intervention by an authority as inappropriate interference. Indeed, the intervention may actually decrease motivation for keeping the tank maintained. Furthermore, research suggests that people who were 'forced' to get a tank as part of adhering to building codes have different levels of motivation towards maintaining their tank compared to those who chose to retrofit a tank, especially if they also received a subsidy from the government to install the tank (Gardiner, 2009; Mankad & Greenhill, 2014). Those householders who were mandated to install a tank were less motivated to maintain a tank than those who had retrofitted their tank. Increased government intervention to maintain the tank could again act as a further de-motivator in the mandated tank owner case. Thus, the public's acceptance of a policy instrument designed to change behaviour is important if the intervention is to succeed.

Research indicates that people's judgments about the features of a policy will influence acceptance, particularly judgments about how fair and how effective they feel the intervention will be. The most widely studied policy feature in the environmental psychology literature is the type of behaviour change mechanism embodied in the policy, which can be more or less coercive. The literature uses a variety of names to describe these mechanisms (Garling & Schuitema, 2007; House of Lords Science and Technical Committee, 2011; Osbaldiston & Schott, 2012). At the non-coercive end, there are 'soft' and 'pull' approaches. *Soft approaches* include education and awareness campaigns, and activities to encourage and facilitate voluntary undertaking of the target behaviour. *Pull policies* are those that provide incentives and rewards as ways to encourage a change towards the target behaviour.

In contrast, the more coercive policy options include 'hard' and 'push' approaches, and use increasing levels of regulation to bring about change. *Hard approaches* can include regulatory mechanisms designed to enforce behaviour, and *push policies* use disincentives, such as penalties and increased taxes or prices, to bring about change. In general, less coercive mechanisms are perceived to be more acceptable, fairer, and more effective. Perceptions of fairness involve the concepts of equality, equity, and personal freedoms. The notions of personal freedom and fairness are important to tank owners who participated in surveys and focus groups, where the freedom to 'do what I want with my water' is seen as an important benefit of having a rainwater tank (Walton *et al.* 2012).

7.6 RESEARCH FRAMEWORK

Strategies for managing rainwater tanks need to address the broad topics of design, installation and maintenance of tanks; whilst also considering the local context, legislation and regulation (if present and followed) as well as behavioural considerations relating to tank owners. Within these broad areas, there are some choices to be made before a strategy can be formulated. As such, research needs to be undertaken to collect information about community attitudes, preferences of stakeholders, possible creative and effective local solutions, appropriate success criteria, and the resourcing of solutions. Strategies need to be evaluated to assess if they are likely to achieve success criteria. This research needs to be carried out in

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acknowledgment that management of rainwater tanks can be a contentious issue. There is public interest in making sure that tanks are well maintained, but householders and the community may not be motivated to cooperate. The need to find collaborative solutions and to address a potentially contentious issue suggests that a participative approach to research is warranted.

A methodological framework for this type of approach to research is outlined in Table 7.4 and address three important research functions fundamental to achieving the following (Jones *et al.* 1999):

- Increasing the legitimacy of the process of knowledge generation.
- Allowing greater integration of more sources of knowledge and information, hence improving the capacity for problem solving.
- Trying to help build collaborative relationships to assist with implementation of strategies and for reducing conflict.

Table 7.4 Methodological implications of developing collaborative solutions around a contentious issue.

Consideration	Methodological implications – there is a need to...
Stakeholders	Identify and involve all stakeholders affected by the issue. Allow stakeholders to have some input into the identification and evaluation of strategy alternatives.
Transparency	Communicate and engage with all stakeholders. Strive to increase the awareness of the interest and preferences of all stakeholders.
Protect Core Values	Identify issues that can create real strife or moral outrage amongst stakeholders. Handle and attempt to resolve conflict in a way that aims to find compromise or consensus solutions.
Substance	Be clear about the role of researchers in collecting and disseminating information and to facilitate discussion. Ensure that research process provides multiple alternatives from which decision makers can choose.

Note: These points have been adapted from HarmoniCOP (2005) which is a key output of a major EU project into improving participation in water management.

Based on these principles, a research process to define a management strategy for urban household scale rainwater tanks would involve the following four steps.

(1) Develop an *understanding of the context*. Typical questions to answer are:
   (a) How many tanks are there and what type are they?
   (b) What were the different reasons why tanks were installed?
   (c) What are the regulations regarding design and installation?
   (d) What condition are the tanks thought to be in?
   (e) Are data available on tank condition?

(2) *Define the strategies* to be considered for further exploration. Typical questions to answer are:
   (a) What strategies can increase the likelihood of adequate tank design?
   (b) What strategies can increase the likelihood of adequate tank installation?
   (c) What strategies can increase the likelihood of adequate tank maintenance?
   (d) What are the community and stakeholder attitudes to different strategy features?

(3) *Assess strategies* using available data synthesized in a computational model to evaluate likely effectiveness of a strategy. Typical questions to answer are:

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(a) What are the success criteria for a strategy (as defined by those key stakeholders who care a lot)?
(b) What combination of strategy features will help achieve satisfaction of the success criteria?
(c) Will a given combined strategy be acceptable to stakeholders?

(4) *Plan, implement and evaluate* a chosen strategy. Typical questions to answer are:
(a) How will the strategy be paid for? Does the strategy need to change to make it financially viable? If so, go back to step 3.
(b) Who should be responsible for each of the tasks in the strategy?

These activities, tasks and knowledge bases are further described in the following sections through examples based on research in SEQ, Australia. Figure 7.1 provides an overview of the research framework.

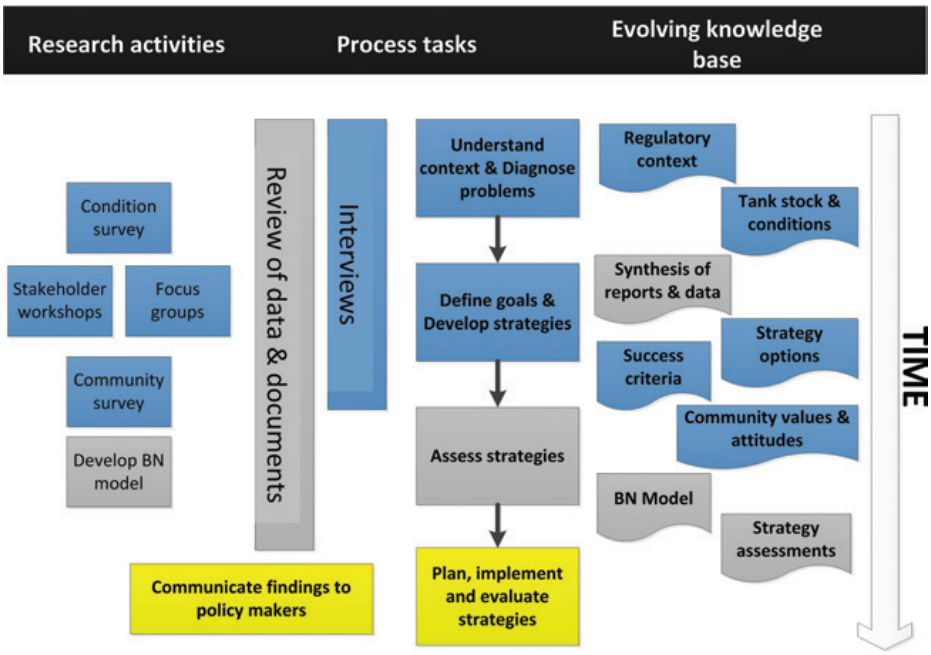


Figure 7.1 Research framework for identifying and assessing management strategies. Note: BN means to Bayesian Networks; Blue colour indicates generation of information/data; Grey colour indicates synthesis or analysis; Yellow colour indicates actions to change the system and/or implement new policy.

7.7 APPLICATION OF THE RESEARCH FRAMEWORK: THE SOUTH EAST QUEENSLAND CASE STUDY

7.7.1 South East Queensland context

In the South East Queensland study, the research process was initiated through meetings with the Queensland Water Commission which at the time (2011) provided independent policy advice to Government on South East Queensland regional water security, demand and supply options (thus their interest in rainwater tanks). In these meetings, concerns were raised about the condition of household tanks across the region, noting the need for a coherent plan to ensure the acceptable condition of these tanks. Through these meetings, an initial list of stakeholders was established: primarily state government departments with some role or

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responsibility relating to tanks, local governments with responsibilities relating to tanks, as well as experts within various professional organisations. It was also identified that the community is an important player in this issue. The researchers then set out to establish the context of tanks via interviews with stakeholders and experts as well as review of relevant reports and documentation.

7.7.1.1 Historical context

The history of urban rainwater tanks in South East Queensland, further described in Text Box 1, was established through discussions with experts. Broadly speaking, household rainwater tanks in South East Queensland were classified into three categories: those tanks installed without a rebate or financial incentive to promote tanks; those installed with householders receiving rebates for their installation; and many tanks installed to meet the water savings target which was in place for some time (see Text Box 7.1) for new dwellings required under the Queensland Development Code Mandatory Part 4.2 (QDC MP 4.2).

TEXT BOX 7.1 EXTRACT DESCRIBING THE HISTORY OF RAINWATER TANKS IN SOUTH EAST QUEENSLAND (MOGLIA *ET AL.* 2013, PP. 1–2):

'Rainwater tanks have always been part of the rural and urban landscape in Australia, ever since the days of early settlement. Growing concern about rainwater tanks as a potential breeding site for the *Aedes aegypti* mosquito and the spread of dengue fever saw the demise of rainwater tanks in urban areas across Queensland during the 1960s and early 1970s. With the onset of the millennium drought in Australia at the turn of the twenty-first century, rainwater tanks were widely promoted in urban areas as a supplementary water source for non-potable uses to alleviate the demand on centralised potable water supply and increase resilience to drought. Financial incentives such as rebates were provided by all levels of government to promote and encourage the uptake of rainwater tanks.

'Legislation enforcing installation of rainwater tanks in new housing has also been enacted in various Australian jurisdictions. Rainwater tanks in urban areas are currently mandated for new dwellings in South Australia and New South Wales. The SEQ Water Strategy advocates the reduction of household mains water consumption to increase the security of water supply, with alternative water resources (rainwater and stormwater) in new developments expected to reduce demand on bulk water supplies by nearly 7% by 2056 (QWC, 2010). The Queensland Development Code (QDC) Mandatory Part (MP) 4.2 (2007) required all new Class 1 residential dwellings in SEQ built after 1 January 2007 to meet a water savings target of 70 kilolitres/household/year (kL/hh/yr) (Queensland Government, 2009). A common approach to meet this water savings target was a 5 kL rainwater tank connected to at least 100 m^2 of roof area and internally plumbed to the toilet for toilet flushing, to the cold water tap in the washing machine and to an external tap(s) for outside water use and garden irrigation.

'In SEQ alone, approximately 59,000 homes with rainwater tanks have been built since 2007 (ABS, 2010). There are over 300,000 tanks in SEQ (Gardiner, 2009). An additional 745,000 new dwellings are projected to be built by 2031 (QWC, 2010). Following the repeal of laws mandating the installation of alternative water supply systems on 1 February 2013, buildings in Queensland no longer have to meet compulsory water savings targets (Department of Housing and Public Works, 2013). Local governments can now choose to opt-in to water savings requirements in recognition of Queensland's varying climatic conditions and regional circumstances. Builders in these local government areas will still need to comply with water savings requirements. Rainwater tanks can still be installed voluntarily by homeowners and builders in all areas of the state, but must comply with the health and safety standards set out in QDC MP 4.2.'

7.7.1.2 Regulatory and practical context

The regulatory and practical context involves both the formal legislative context, as well as the informal context, how things are done in practice. The formal legislative context was explored by means of relevant

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documentation, such as the QDC MP 4.2 (Queensland Government, 2008), the Public Health Act 2005 (Queensland Government, 2005), and guidelines to minimise mosquito and biting midge problems in new development areas (Queensland Health, 2002). Further details relating to standards and guidelines applicable to rainwater harvesting systems, and other relevant regulation can be found in Moglia *et al.* (2012a). The informal context was explored by means of interviews and discussions with experts and professionals. The type of information collected in these interviews related, for example, to how the approval process for tanks is or isn't carried out in practice, and the rich and colourful stories of times when people have had problems with tanks. Through these stories, a list of different ways that tanks fail (failure modes) was identified, as well as some initial indication as to causative chains leading to failure. Furthermore, through this process, the research team was also able to provide a more complete picture of all the stakeholders relating to rainwater tanks (see Moglia *et al.* 2012).

7.7.1.3 Tank stock and general condition

After interview discussions, the research team soon established that there was no reliable available data on the condition of tanks in the region, leaving the team unclear as to the extent of the problem with poorly maintained tanks. A handful of studies had explored the motivations and practices of householders (Gardiner, 2009; Gardiner, 2010; Gardiner *et al.* 2008; Tilbrook, 2009) but no data existed on the physical condition of tanks. Furthermore, it was widely argued that it would be difficult to fund and carry out a large scale survey of the physical condition of the 300,000 tanks in the region.

In a study related to our research, an inspection program of 200 tanks was undertaken by Biermann *et al.* (2012) (see Chapter 5), but these data were only available halfway through our study. It was therefore thought that in the absence of physical data, it would be appropriate to canvas water professionals including plumbers on their expectations and experiences relating to tanks; especially when these water professionals are also tank owners. Over 250 water professionals were surveyed via email, to elicit their experiences. This generated some data that could be used to establish a base estimate of the extent of the problems (Moglia *et al.* 2013a). This data provided expert judgments as to the likely time before failure of system components, as well as the likely causes of any failures. Using the data in combination with Monte Carlo computer modelling simulations, the team established a rough estimate of what percentage of tanks would be under inadequate condition if various frequencies of inspection and maintenance were occurring (see Table 7.5).

Table 7.5 Relationship between frequency of inspection and estimated rates of inadequate tank condition (or failure) in a simulated population of tanks.

Frequency of inspections	Proportion of tank systems with blocked gutters (overhanging trees)	Proportion of tanks with broken pumps	Proportion of tanks with broken meshing	Proportion of tanks that are structurally broken
1 month	17%	1%	1%	0%
3 months	39%	4%	4%	0%
6 months	54%	8%	10%	1%
1 year	67%	19%	21%	2%
2 years	75%	37%	38%	5%

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7.7.2 Definition of strategies

With the results of the Monte Carlo simulations indicating that, in all likelihood, a good proportion of tanks were expected to have some problems, it was concluded that there is a need for a management strategy. Having established the need for a management strategy, there was a real need to further explore exactly how the issue of tanks in South East Queensland ought to be managed. It was also acknowledged that there was a remaining knowledge gap regarding the actual state of tanks, and that the topic was contentious. From the previous stakeholder discussions, many ideas as to what can be done to manage tanks had emerged, and these proposed ideas were not all consistent with each other. For example, industry stakeholders suggested that a register of existing tanks should be established whilst others suggested that this would aggravate home owners and make management difficult. The team recognised two key points regarding the situation:

(1) Without the cooperation from tank owners, it is unlikely that any strategy to manage tanks would succeed. Therefore, serious consideration will have to be given to the views and preferences of tank owners.
(2) Stakeholders, such as the Queensland Water Commission and Queensland Health have good reasons for making sure that tanks across the region are operated in a safe and efficient manner.

It was further recognised that to find solutions to this problem would require creative ideas, as well as cooperation between multiple stakeholders. To develop solutions, the research team designed a two-part process, engaging both with the community, and with government and industry stakeholders and experts. The first step was to engage with relevant industry and government stakeholders through a dedicated workshop to identify and explore possible options for improving the management of tanks, with follow-up interviews with individual industry professionals. The second step was to engage with community stakeholders using focus groups to understand public impressions and to investigate possible community responses to alternatives.

7.7.2.1 Industry and government stakeholder engagement: Workshop

A stakeholder workshop was conducted to identify the various ways in which the management of rainwater tanks could be improved. Participants were stakeholders from across six different sectors; state government; regulatory entities; water utilities; local council; academia, and industry representatives including rainwater tank designers and manufacturers, engineers, plumbers and the plumbing industry representative body. All stakeholders had involvement in some aspect of the life cycle of rain water tank systems.

The workshop process was designed to identify and explore a range of possible strategies for encouraging and ensuring rainwater tanks are well maintained and managed. The research team specifically wanted to understand the benefits and barriers associated with each potential strategy, assess participants' perceptions of the difficulty in implementation of a particular strategy, and the strategy's potential effectiveness. Following an initial short presentation of relevant background information, the workshop included three activities: a brainstorming session; an in-depth analysis of key strategies; and a voting task. The brainstorming session identified a diverse range of possible strategies, which were then grouped and key strategies prioritised for more in-depth analysis. The in-depth analysis focussed on discussion of benefits, barriers, and implementation issues. A perceptual map was created, which summarised each strategy in relation to the others in terms of the perceived impact on rainwater tank maintenance and ease of implementation. The voting task identified participants' preferences for each strategy (Figure 7.2).

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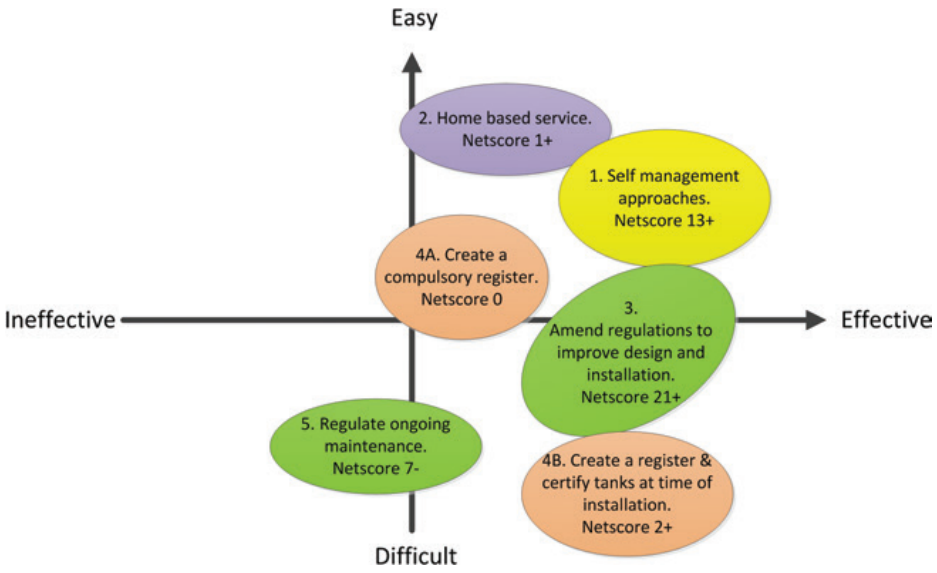


Figure 7.2 Perceptual map of groups of strategies and net voting preference scores. *Source*: Adapted from Walton *et al.* (2012). *Note*: A net preference score was calculated for each group of strategies, with the most preferred and least preferred votes added together. A positive net score indicated a strategy was liked overall, whereas a negative net score indicated a strategy was not liked overall.

Workshop participants generated a range of potential approaches, including improvements in installation practices, improvements in design to reduce maintenance requirements, and various methods of supporting/encouraging householders to manage tank maintenance by themselves. There was little support for setting up a register of tanks to help track and enforce maintenance, nor for taking the responsibility for tank maintenance away from householders (e.g., by making the local council responsible for maintenance). Participants believed that enabling options, such as education and awareness campaigns and the introduction of a dedicated and interactive website to provide tailored information to tank owners about tank maintenance, were preferable to regulatory processes. Interventions that focussed on improving tank design and ensuring correct installation were favoured because participants viewed such changes as capable of reducing potential maintenance problems. In addition, participants felt that regulatory processes would be both difficult and costly to implement and manage, and that compliance within the community would be low. Enabling strategies were considered easier to implement and likely to be more effective (Walton *et al.* 2012).

These views about likely community responses needed to be tested with community members themselves.

7.7.2.2 Community stakeholder engagement: Focus groups

A series of community focus groups were held to gain a deeper understanding of what the public thinks about rainwater tank maintenance and how people might respond to various strategies to promote or encourage maintenance. Focus group participants included tank owners (28 participants) and non-tank owners (14 participants) and the sessions were conducted in small groups (7 participants) with a research facilitator. A series of eleven different strategy ideas, developed from the industry and government stakeholder workshop, were put to the groups (Table 7.6), and each idea was discussed in terms of its potential effectiveness to achieve change and its likely acceptance by the community.

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Table 7.6 List of strategy ideas presented to focus groups.

Number	Strategy ideas
1	Leave it to householders to manage for themselves; the status quo
2	Leave it to householders, but provide them with support
	• *Advice on what's to be done; fact sheets; helpline; directory of plumbers and tank cleaning services*
3	Leave it to householders, but increase householder awareness
	• *Promote benefits of keeping a tank maintained; highlight the consequences of not keeping a tank maintained; reminders and prompts*
4	Home service – you pay to have someone come and inspect your tank
5A	Create a register of tanks – rely on tank owners co-operation
5B	Create a register of tanks – make it compulsory to have tanks registered
6A	Inspect tanks – make it compulsory to have your tank inspected when it is first installed; to check it has been installed properly
6B	Inspect tanks – make it compulsory to have your tank inspected every couple of years
6C	Inspect tanks – make it compulsory to have your tank inspected when your house is sold
7	Tank design – make it compulsory to improve the design of the tank so that less things will need maintaining
8	Maintenance information – make it compulsory to be given information about tank maintenance when you have it installed

Open-ended questions were used to explore the benefits and barriers associated with each strategy idea. An output of these focus groups was a preliminary model to describe the socio-psychological factors that influence whether householders intend to undertake maintenance, and whether they are likely to put that intention into action. The community focus groups also reinforced the idea that registers of tanks would be highly unpopular and suggested that there was a strong mandate for householders' self-management approaches. Perceptions of each strategy, in terms of how effective and how acceptable the strategy would be at fostering tank maintenance, were mapped onto a perceptual diagram (Figure 7.3).

7.7.3 Assessing strategies

With a large array of strategies identified for managing rainwater tanks, the next step is to construct a framework for strategy evaluation. Key success criteria need to be established and a multi-criteria assessment model developed. A knowledge base capable of generating inferences of likely strategy success also needs to be developed for the assessment model. This knowledge base synthesises all existing information and formulates coherent judgments about the possible success of each strategy. To fulfil these requirements in the South East Queensland case, a research process involving three steps was undertaken:

(1) Establishing success criteria for strategies; that is, establish what a successful strategy would achieve.
(2) Undertake a survey that quantitatively measures the socio-psychological factors relating to householder tank-related behaviours.

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(3) Synthesize the existing data and survey findings using computer simulations that can model different strategies for their chances of achieving the success criteria.

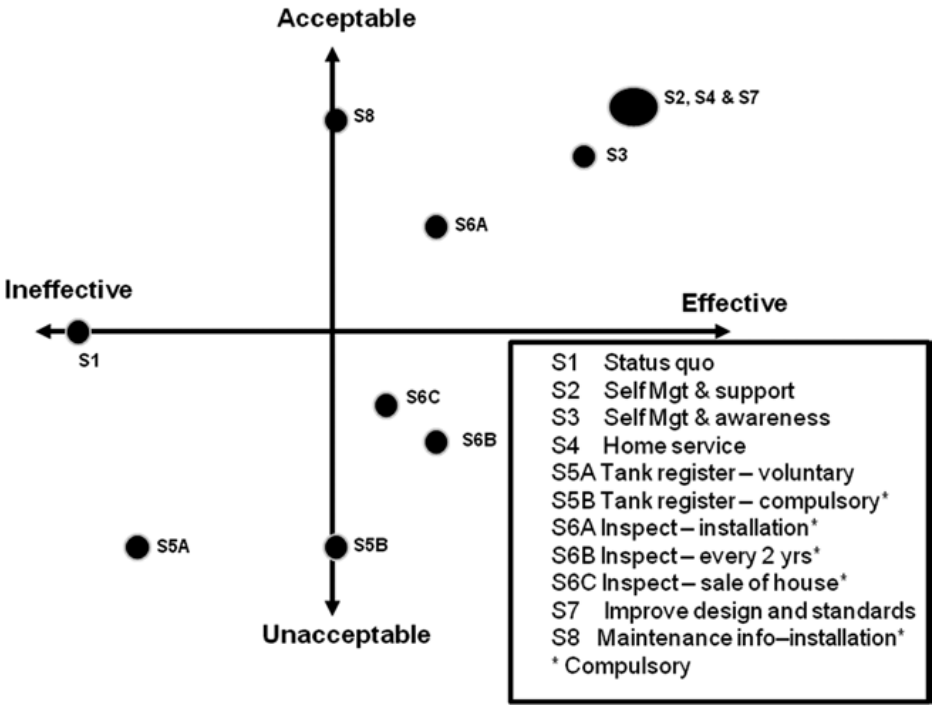


Figure 7.3 Perceptual map of strategy ideas from focus groups. *Source*: Adapted from Walton *et al.* (2012b).

7.7.3.1 Establishing success criteria for strategies

Interviews were undertaken with those stakeholders who had indicated a strong interest in tanks being adequately looked after. The research team interviewed staff members at the state government entities: Queensland Water Commission, Queensland Health, the Department of Natural Resources and Mines, as well as local engineering consulting firms with significant experience in designing tank systems for new developments. The focus of the discussions was to establish clear and unambiguous criteria that help evaluate whether a rainwater tank management strategy is successful. Not all of those interviewed stated any success criteria. Domestic rainwater tank owners are also considered as key stakeholders, but it is not practical or appropriate to allow them to define assessment criteria. However, their views and preferences about strategy options were measured through a household survey and incorporated into the modelling. The criteria for successful rainwater tank management developed from the stakeholder interviews are presented in Table 7.7.

7.7.3.2 Survey of householders

To quantitatively evaluate the behavioural response from the community to various management strategies, a survey was undertaken of 533 domestic tank owners from South East Queensland (Walton & Gardner, 2012; Walton & Gardner, 2014). The survey used a choice modelling approach to test tank owners' preferences

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for different types of intervention mechanisms that could be used to encourage them to maintain their tanks. Based on the strategies identified in the previous workshop, the interventions varied in the level of coerciveness embodied in the intervention, from a regulatory and 'push' approach through to an enabling and 'pull' approach. Six different strategies were evaluated: 1) introduction of tank registers; 2) introduction of tank inspections; 3) use of penalties (fines); 4) leaving tank owners to their own devices; 5) provision of information and regular awareness campaigns; and 6) use of an incentive (rebate). The strategies were combined in random order into eight different choice sets and each strategy evaluated for perceptions of fairness, effectiveness, and acceptability. The survey also investigated the links between socio-psychological factors and tank maintenance based on previous focus group findings (Walton *et al*. 2012).

Table 7.7 Criteria for successful rainwater tank management in the South East Queensland case study.

Criteria	Details
A. Adequate water savings	At least 90% of tanks need to provide the projected water savings from now and into the future. From the *water planning* perspective this also needs to be certain fact, backed up by sampling of the condition of tanks and statistical analysis of the condition data (see criterion D).
B. Acceptable low risk of mosquito breeding in tank systems	In the context of South East Queensland, at least 99% of tanks need to be protected by mosquito meshing. Furthermore, a general household requirement is that the amount of stagnant open water needs to be kept to a minimum.
C. Acceptable low risk of health risks related to poor drinking water quality	Stakeholders consider that it will be impossible to ensure drinking water quality at an adequate level with adequate certainty. Information campaigns need to ensure that the community are advised not to drink rainwater when safer options are available.
D. Knowledge of the condition of tanks	It was argued by the key stakeholders that the condition of tanks needs to be known. Not all tanks need to be inspected, but an adequate sample of randomly selected tanks needs to be inspected regularly. Adequate water savings need to be assessed every 3–5 years, and acceptable low health risks need to be assessed on an on-going basis every year. To support the inspection program, there is a need for knowledge of the tank stock (see criterion E).
E. Knowledge of the tank stock	In order to undertake a program of random inspections of rainwater tanks, there needs to be a database of tanks and their locations. Currently this type of information is managed by local councils, but there is a need to centralise this dataset into a single location. Whilst the community have indicated that they do not want a register of tanks, a database could be developed based on collection of existing available information about rainwater tanks from councils, and so on.

Source: Moglia *et al.* (2012b)

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Survey results indicated that, although tank owners had low levels of awareness of the tasks involved in keeping a tank maintained, there were high levels of support among respondents for the introduction of measures that could foster tank maintenance within the community. Approximately 63% of survey respondents either didn't know that a tank had to be maintained or didn't know what needed to be done to maintain a rainwater tank. Only 37% of respondents reported being both aware of the need for tank maintenance and knowing what to do. Nonetheless, the mean score for supporting the introduction of measures to encourage tank maintenance was 5.13 (SD = 1.66) on a scale of 1–7 with higher scores indicating a more favourable view (Walton & Gardner, 2012). Clearly, information campaigns aimed at rainwater tank owners is a first step in order to raise awareness of tank maintenance issues but it is uncertain the level of success that can be expected from such a campaign.

However, community acceptance for the various interventions revolved around how fair and how effective the public viewed each intervention, with fairness twice as important as effectiveness. This meant that the more fair and effective the policy seemed to a person, the greater their acceptance of that policy. Interventions that were based on 'enabling' tank maintenance, and those that provided incentives for tank maintenance, were viewed as being more fair, effective and acceptable than interventions based on penalties and monitoring through registers and inspections. This is consistent with research into social acceptance of for water recycling and other alternative water supply systems (Nancarrow *et al.* 2010).

These preferences for incentives and enabling interventions were in line with the socio-psychological factors that seemed to underpin tank maintenance behaviour. The survey also found that favourable attitudes towards tank maintenance, a strong self-image as someone who likes to keep things well maintained, and perceptions of capability and self-efficacy were all important predictors of a person's intention to undertake tank maintenance.

These results suggested that policy makers could not only focus on policies that are based around 'enabling' factors and incentives, but also develop programs that address the socio-psychological issues. Based on the survey findings, strategies to foster a favourable attitude towards tanks maintenance could also include interventions which promote the benefits of tank maintenance and highlight the 'costs' of not keeping a tank maintained. Costs could include costs to both the individual, such as the loss of unrestricted water use for the garden, and to the wider community, for example, the risk to public health and the increased burden to the mains water supply. Similarly, solutions that link tank maintenance with other home maintenance activities could be appealing to those who see themselves as someone who keeps things well maintained.

Finally, interventions that support a person's belief in their own capability and provide confidence to undertake tank maintenance could be effective. Education initiatives, awareness campaigns and information services could result in improved self-efficacy beliefs, and ultimately influence tank maintenance behaviour. Furthermore, survey results demonstrated that even with a positive intention to undertake tank maintenance, if people don't feel capable or confident of their ability, then tank maintenance is less likely to occur. This finding further highlights the importance of providing enablers as a policy intervention to support tank maintenance behaviour.

7.7.3.3 Synthesising the data and using models for evaluation of strategies

It is necessary for policy makers to make choices about what type of management approach should be in place for domestic rainwater tanks. This choice is neither obvious nor straightforward, because there are many different factors to consider and a large body of information to incorporate into the decision making process. In fact, such factors also interact with each other, creating considerable complexity and placing this type of analysis beyond cognitive mental models. Furthermore, rigorous analysis of decision problems

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leads to better and more sustainable decisions and computer-based analytical tools can help to structure and analyse the decision problem. The likely effectiveness of strategies for rainwater tank management was evaluated using a Bayesian Network model, which can incorporate existing data, judgments and understanding. The model is described in detail in (Moglia *et al.* 2012b). Other models and/or decision analysis approaches may also be suitable for analysing this decision problem.

A Bayesian Network model is a probabilistic model describing a system of logical statements, albeit where the statements are probabilistic rather than absolute – thus more realistically reflecting the uncertainty that is ever-present in real-world decision problems (Pearl, 2000). As such, Bayesian Networks can incorporate (probabilistic) deductive, inductive and abductive reasoning – which are all key mechanisms by which humans and their computers can make inferences. Technically, Bayesian Networks are constructed as a system of equations. To define this system of equations, the modeller needs to define model factors, their possible states, as well as the interactions between factors. Interactions between factors are described through conditional probability tables, and the model is initiated by specifying the probability distributions of under-lying conditions.

As input into the model, the research team used the household survey results to describe socio-psychological factors contributing to behavioural response to strategy features, the judgments by engineering experts on what contributes to keeping a tank in good condition, and the stakeholder-identified success criteria. The model is shown in Figure 7.4.

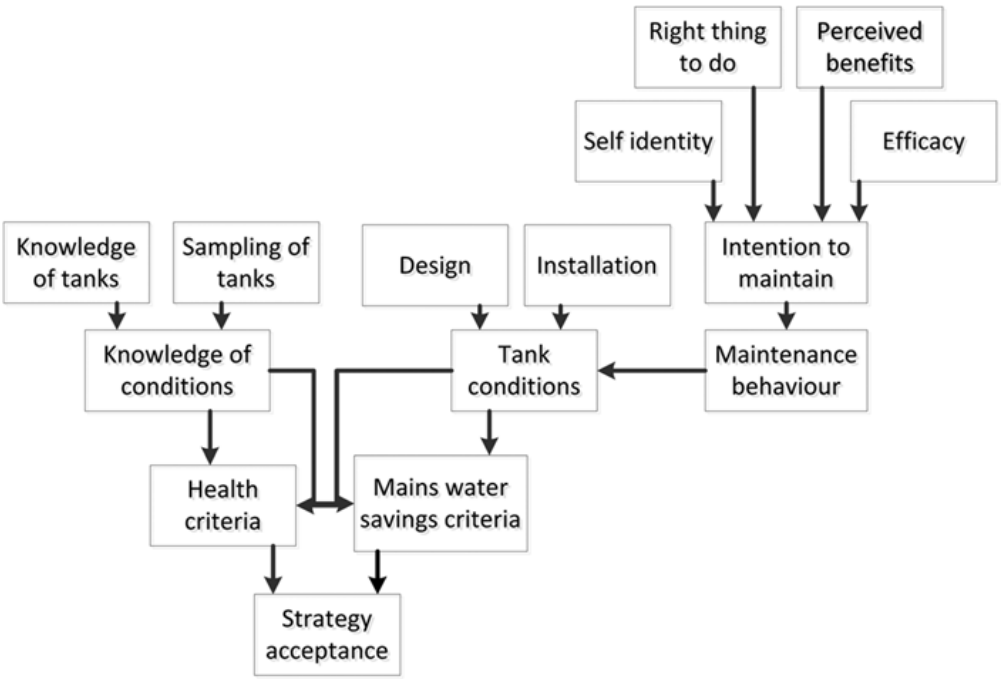


Figure 7.4 Bayesian Network model of the effectiveness of rainwater tank management strategies.

The way that the model is structured and populated with data is as follows:

- A domestic tank owner's motivation to maintain his/her tank is influenced by the perceived benefits, the self-identity, the efficacy, and whether the person thinks it is the right thing to do. The conditional probability tables describing this are defined through the householder survey.

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- The motivation to maintain a tank does not always translate into action, that is, actual householder maintenance. The assumed likelihoods for this occurring for the different cases (motivated, unmotivated, or undecided) is set in a conditional probability table that can be subject to sensitivity analysis to explore various assumptions.
- A tank's condition is influenced by the design, installation and maintenance of the tank. This influence has been defined in conditional probability tables by an engineering consultant, and the assumptions can be explored using sensitivity analysis.
- The initial conditions describing what percentage of tanks have been adequately installed and designed, and so on, have been defined through professional judgments from email-based survey (Moglia *et al.* 2013a), but this should be defined through physical surveys of tank conditions, such as those reported by Biermann *et al.* (2012).
- The likelihood of adequate water savings and/or mosquito problems for a tank in poor condition has been defined by research team members, but again this should be established through physical surveys of tank conditions as per Biermann *et al.* (2012).
- The knowledge of tank conditions is influenced by the judged knowledge of the tank stock and whether regular inspections are being undertaken. The influence has been established on the basis of assumptions made by stakeholders in the interviews on defining clear and unambiguous criteria for strategy success. These are relatively straightforward and unambiguous, but these assumptions can also be explored using sensitivity analysis.

The model should not be viewed as an exact representation of reality, but rather an approach for synthesising the existing information in a single analysis. The model is a tool to help with structured logical reasoning and synthesis of existing information beyond the capabilities of human cognitive abilities. Problems with underlying data or assumptions will remain, but it is possible to explore sensitivity of conclusions to data and assumptions. A key premise for the modelling is that the model makes data issues and assumptions underlying the decision problem more transparent.

Figure 7.4 shows the nodes and arcs of the Bayesian Network model that was developed and encapsulates the main factors contributing to achieving the criteria in Table 7.7. The key factor is the condition of tanks, which is influenced by design, installation and maintenance behaviours. Maintenance behaviours are in turn dependent on the intention to maintain a tank, which in turn relates to a number of socio-psychological factors. However, the fact that tanks are in good condition is not sufficient by itself to meet the success criteria of stakeholders. For example, knowledge of tank condition is an important factor contributing to meeting health and water savings criteria, which in turn depends on both an understanding of where tanks are located (knowledge of tank stock) as well as a condition assessment program (sampling of tanks) to confirm that tanks are in good condition. State government departments also need some certainty that all key criteria are being met.

Behind the nodes and arcs of this diagram are conditional probability tables set up with available data and judgments by key informants (for detailed information see Moglia *et al.* 2012b). Using the Bayesian Network model, it is possible to input various conditions such as the distribution in the community of socio-psychological factors related to maintenance behaviour, as well as various design, installation and maintenance strategies and various levels of knowledge of tanks and condition assessment programs. The output of the model is a likelihood/probability of achieving the success criteria, allowing for scenario analysis as per Table 7.8, showing that success is dependent on a broad approach that considers all relevant factors.

Using the collected data synthesized into the Bayesian Network model, and running scenarios as per Table 7.8, a number of recommendations for a tank management program were made (Moglia *et al.* 2012b).

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Table 7.8 Scenarios based on Bayesian Network modelling: running scenarios describing different situations of design, installation and maintenance for rainwater tanks in South East Queensland, and showing the resulting likelihoods of tanks being in good condition and success criteria fulfilment.

Scenario	% of tanks in good conditions	Knowledge of the tank stock (highest likelihood state)	% likelihood of health and potable water savings criteria fulfilment
1. **Worst case:** poor design & installation; poor knowledge of stock and too small sample of tanks. Status quo maintenance.	61%	Anecdotal	25%
2. **Benchmark design:** same as worst case but benchmark designs	74%	Anecdotal	29%
3. **Benchmark installation:** same as worst case but benchmark installations	72%	Anecdotal	28%
4. **Benchmark installation & design:** same as worst case but benchmark installations and design	86%	Anecdotal	32%
5. **Benchmark design & installation and rigorous knowledge:** same as Scenario 4 plus benchmark knowledge of stock and sampling of tanks	86%	Good knowledge	86%
6. **Best case:** like Scenario 5 but with socio-psychological factors significantly improved	93%	Good knowledge	91%

The recommendations centered on improving the three pillars of rainwater tank management – promoting good design, promoting good installation, and promoting good maintenance – in a three-phase process. The first steps relate to collecting information and better data management, as well as reviewing the need for legislative and other changes to the institutional framework. Some things that could be implemented in first phase at relatively low cost are the strategies to motivate, remind and enable owners to maintain tanks by addressing the underlying factors that contribute to the intention to maintain the tank. This would be done by providing information and developing the skills and ability of tank owners, as well as promoting the public and individual benefits of tank ownership. In the second phase, there is a move towards action including randomised inspections of tanks, changes to the design and installation guidelines and standards, and implementation of a training program for plumbers. The third phase is to review the efficacy of the chosen strategies, and to evaluate what is working and what is not working. It will also be important at this stage to make a fair assessment of the public health risk, and to evaluate whether such risk can be managed or whether further actions would be required.

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7.8 DISCUSSION

Without adequate management of rainwater tanks at a regional/urban level, it is foreseen that there will be difficulties with achieving water savings targets (as discussed by Beal *et al.* in Chapter 3) and there are some public health risks that may materialise. The need to manage rainwater tanks would appear to be mainly driven by state government and local council needs and desires to ensure adequate water supply for the city/region and that health risks are adequately managed. An ongoing inspection program is required in order to fulfil these criteria of key stakeholders. This will come at a financial cost, regardless of whether householders have the key responsibility for maintenance. On the basis of experiences in a ongoing project in Melbourne, Victoria, it is now known that an inspection takes about one hour once it has been scheduled; and about 5 inspections a day a can be carried out (1.6 hours per inspection including travel time). Someone would need to coordinate the inspection process, and to have responsibility for the adequate management of tanks across the region. Fairness principles would dictate that this cost is carried by government and not householders.

However, government investment in rainwater tanks could perhaps be viewed as equivalent to investments in large dams. There are ongoing operations and maintenance costs associated with managing dams and these costs are passed on to householders via their water bills. Rainwater tanks can be viewed as 'small dams'. Therefore, it seems reasonable that the costs for the condition assessment and inspection programs for rainwater tanks, and the cost of any information campaigns, are also passed on to all householders via their water bills. On the basis that a suburb of mandated tanks can be likened to a small, central reservoir, all the community should pay for the tank inspection and condition assessment programs, not just the tank owners. The additional cost to the average water bill would be minimal and rainwater tanks would still be a cost-effective way to supplement water supplies for the city.

Related to the cost of the condition assessment and inspection programs is how the tank management requirements impact on the lifecycle costs of tanks, and thus on the competitiveness, or cost-effectiveness, of urban domestic rainwater tanks when compared with other options. The extent of the lifecycle costs depends on whether there is a cost attached to the labour for the maintenance tasks. By allocating some reasonable times to undertake the tasks in Table 7.2 (~17 hours per annum) and at a cost of AUS$50 per hour for labour, the annual cost of completing the maintenance tasks would be around AUS$830. This is equivalent to a net present value of just under AUS$9,500 over 15 years with a 5% discount rate. However, the reality is that much of the work is not charged for, as maintaining a rainwater tank can be considered as part of the regular upkeep of a property by the householder. This is a further reason why householders should have the responsibility for maintaining the domestic tanks, although considerations have to be made for the elderly and those who for various reasons do not have the confidence to undertake such tasks.

Due to the need for multiple perspectives when defining detailed intervention strategies, the process would be greatly assisted with input from a panel including representatives with deep knowledge and understanding of the various aspects of the rainwater tank management problem, including urban water planners, public health officials and representatives from the plumbing industry. It is unclear at this stage who should take on this responsibility. Furthermore, in the case of SEQ, the housing construction industry is likely to be affected by any policy regarding whether houses are required to have rainwater tanks installed, and is also often involved in the installation of tanks, and should therefore also be engaged in the process. Stakeholders need to coordinate amongst themselves to do something about this problem, or the future of domestic urban rainwater tanks looks questionable.

Whilst these issues appear to pose some questions about the viability of rainwater tanks, we argue that domestic urban rainwater tanks have a future in Australia and elsewhere. Domestic rainwater tanks complement other urban water supplies, especially at times of restricted mains supplies. However, there is

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a need to take the management of tanks seriously. The overall cost of devising a management strategy for tanks would not amount to much on a per-tank basis, but will require stakeholders to take control of the situation and move towards well-resourced action. Action needs to be implemented in acknowledgment that this is a new problem, with significant amounts of uncertainty attached to it, requiring significant buy-in from a range of stakeholders as well as the collection of adequate biophysical data through tank surveys and water savings assessments.

It is clear that there is a dilemma in the management of rainwater tanks in SEQ because on one hand householders want minimal interference from governments at any level, but on the other hand there is a need to ensure that public health risks are acceptable and water savings are achieved, plus key stakeholders need some certainty about such matters. Philosophically, rainwater tanks are an uncommon type of assets which provides key public good outcomes but that are in private ownership. Very few precedents exist for how to manage this type of infrastructure asset, although septic tanks appear to potentially fit into this category. It could however be argued that incentive structures are rather different.

From a theoretical perspective, if one assumes a *Homo Economicus* worldview where people are rational, self-interested and behaviour is dictated by personal incentives, the likelihood of contributing to the public good and thus maintaining private rainwater tanks depends on the presence or lack of incentives, that is, carrots and/or sticks (i.e., inherent incentives plus push or pull policies). The *Homo Economicus* perspective is largely discredited as unrealistic (Kahneman & Tversky, 2000; Gintis, 2000; Henrich *et al.* 2001) and we adopt the view that people are much more complex than what the *Homo Economicus* worldview dictates. In fact, even laboratory experiments may not adequately describe behaviour and case studies are now commonly the favoured approach for understanding behaviour (Levitt & Lis, 2008).

In the case of rainwater tank maintenance, we currently do not have data on what works and what doesn't work in terms of inciting rainwater tank maintenance behaviours. However, a reasonable assumption seems to be that it is probable that householders, to a large degree, want to do the right thing and to look after their own property. If that is the case, then providing information and promoting an understanding of the need to maintain tanks will have a significant positive outcome. It is important to remember that ultimately, householders are legally free to choose whether to maintain their rainwater tanks but are also liable to ensure that their assets do not pose health risks to themselves or their fellow citizens.

The alternative to a 'softly' approach to managing urban rainwater tanks also requires costly enforcement. A middle ground is recommended where a condition assessment program of private rainwater tanks is undertaken on an ongoing basis. Such a condition assessment program may be linked to penalties if rainwater tanks are thought to pose health risks to the community (a small stick); acknowledging that householders are legally liable for public health risks but not for water savings. Householders may also need to concede that a centralised database containing information about all rainwater tanks is necessary in order to manage public health risks associated with rainwater tanks.

The research framework to develop rainwater management strategies outlined in this Chapter is based on a participatory framework involving both qualitative and quantitative data collection through surveys and interviews as well as modelling using Bayesian Networks. The Bayesian Networks help synthesize the findings into a coherent system of probabilistic causation statements; and this model can be used to help develop and assess management strategies for their likelihood of achieving success. The case study and modelling undertaken in South East Queensland shows that any strategy to improve rainwater tank maintenance will need to consider multiple factors (i.e., not just behaviour, or design, or installation) and will have to deal with factors in combination. Furthermore, due to the uncertain and socially complex nature of this problem, an adaptive and participative approach will be necessary, reiterating previous calls by Moglia *et al.* (2010, 2011a, 2011b) where the efficiency of a strategy is assessed before moving on to

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any amendments. This then demands adoption of a systematic schedule of tactics, combined with random inspections of rainwater tanks to evaluate outcomes and promote learning.

7.9 CONCLUSIONS

This chapter has described the issues involved with rainwater tank management, and has provided a research framework to develop management strategies, exemplified with a case study application in South East Queensland, Australia. The research has shown that there is need for policy or interventions aimed at encouraging rainwater tank maintenance by tank owners. Rainwater tanks have a future in Australia and elsewhere. Domestic rainwater tanks complement other urban water supplies, especially at times of restricted mains supplies. However, there is a need to take the management of tanks seriously.

The long-term benefits from rainwater tanks in urban areas require the proper design, installation and maintenance of the tank assets. The risks associated with inadequate installation and maintenance can impact not only the security of future water supply, but also pose risks to public health by creating habitats for mosquitoes which can act as vectors for diseases such as dengue fever. Such risks can be mitigated by simple maintenance practices. But scarce information is available on the upkeep and condition of rainwater tanks post-installation in urban areas.

The undertaking of tank maintenance tasks by tank owners is driven by their motivation and their perception of competence (or self-efficacy) to undertake such tasks. Adequate knowledge of the maintenance needs and the ability to fulfil such tasks is required; however these vary markedly among urban rainwater tank owners. Any strategy to ensure tank maintenance will need to consider multiple factors (i.e., not just behaviour, or design, or installation) and will have to deal with factors in combination. The interventions strategies that are most likely to promote the operation and maintenance of rainwater tanks need to be perceived as being *fair* to generate acceptance by tank owners. In particular, the strategy needs to reinforce the benefits associated with tank use and to provide tank owners with knowledge on tank maintenance tasks.

Another major consideration for rainwater tank management is the associated cost. There is a cost involved with management of tanks, regardless of whether householders have the key responsibility for maintenance. The annual cost of completing the tank maintenance tasks is estimated to be approximately AUS$830 (~17 hours per annum, at a cost of AUS$50 per hour). However, much of this work is not charged for and is considered as part of the regular upkeep of a property by the householder. This is a further reason why householders should have the responsibility for maintaining the domestic tanks. An ongoing inspection program is required in order to fulfil the tank water supply security and public health obligations, and this also comes at a financial cost. It seems reasonable that the costs for condition assessment programs for rainwater tanks, and the costs of any information campaigns, are passed on to all householders via their water bills, not just the tank owners.

Due to the uncertain and socially complex nature of this problem, an adaptive and participative approach will be necessary, where the efficiency of a strategy is assessed before moving on to any amendments. A systematic schedule of tactics needs to be adopted, combined with random inspections of rainwater tanks, to evaluate outcomes and promote learning. The strategies will need to be periodically reviewed and re-assessed by field survey for effectiveness as tank owner motivation evolves.

Whilst these recommendations are those of the authors, it is also important to remember that this is a situation that requires cooperation from a broad alliance of stakeholders. In such situations, it is usually not constructive to enforce solutions that do not have wide support, but instead, stakeholders, including householders, need to take part in fair and transparent negotiations. However, that is a step which is outside the scope of our research framework.

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Chapter 8

Public perceptions, motivational drivers, and maintenance behaviour for urban rainwater tanks

Aditi Mankad, Kelly Fielding and Sorada Tapsuwan

ABSTRACT

The purpose of this chapter is to present approaches to examine psychosocial factors influencing rainwater tank adoption and maintenance and their application in South East Queensland, Australia. The chapter reviews the limited social research on these issues that has been conducted to date and addresses three research areas: 1. Key dimensions of public acceptance for rainwater tanks, 2. Exploring relationships between key dimensions of public acceptance and water-related attitudes and perceptions, and 3. Investigating key psychological variables likely to influence rainwater use and tank maintenance beyond public acceptance. Psychological theories used to frame and interpret the psychosocial research findings are also introduced, namely, protection motivation theory and self-determination theory. Appropriate methodologies are discussed to address these research areas and a case study example provided to illustrate the methodological approach. The research presented explores attitudes of users and non-users of rainwater tanks, examines perceptions of water shortage threat, and helps to understand the management and maintenance of rainwater systems at the household level. Psychological and behavioural data is also compared across those with voluntary (retrofitted) rainwater tanks installed in existing homes and those implemented subject to a local development code (mandated). The role of willingness to pay for rainwater tanks is also considered. A general summary brings together all relevant research findings and considers the 'way forward' for social research on rainwater tanks.

Keywords: alternative water; amotivation; community attitudes; protection motivation; self-determination.

8.1 INTRODUCTION

Rapid population growth and changing climatic conditions around the world mean that there is increasing pressure on traditional water supplies to cope with high demand within urban environments (Brown *et al.* 2008). To address these water shortages there is a need to adopt alternative water sources, including household-level rainwater tanks, designed to supplement mains water for non-potable applications such as gardening, toilet-flushing, and laundry. Rainwater harvesting is certainly not a new option, and is one that

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has been voluntarily adopted in various other parts of the world, such as in Africa (e.g., Zambia; Handia *et al.* 2003), the USA (e.g., California, Colorado; Adrian *et al.* 2002), the UK (e.g., Ward *et al.* 2007) and Europe (e.g., Spain; Farreny *et al.* 2011). Although there is an extensive international literature on the viability of domestic rainwater harvesting, there has been very little attention paid to the social dimensions of this issue, in particular to the question of why people do or do not install rainwater tanks and to the motivational drivers of rainwater tank maintenance. This is surprising when considering the relatively low levels of uptake of rainwater harvesting systems in some countries. For example, only 26% of Australian households utilise a rainwater tank (ABS, 2010) and even in Queensland (Qld) where government rebates and regulation have been in place to encourage greater adoption, that proportion is only slightly higher with 36% of households using a rainwater tank (ABS, 2010). This suggests that the majority of Australian households, particularly in urban areas, have not adopted on-site rainwater harvesting as part of their domestic water supply.

In some urban regions the installation of rainwater tanks for non-potable uses has been legislated as part of building development codes to meet potable water savings (e.g., New South Wales, Queensland, India, urban areas in New Zealand). As an example, from January 2007 to February 2013, all new homes built in South East Queensland (SEQ) were required to install a water collection/conservation device that enabled households to save 70 kL of water annually (DHPW, 2013). This was typically achieved through a 5 kL rainwater tank plumbed into the internal fixtures within a home, such as the washing machine cold water tap and toilets, as well as an external tap (Queensland Development Code (QDC) MP 4.2; DPI, 2010). The recent repeal of QDC MP 4.2 still allows local councils to 'opt-in' to QDC MP 4.2 if they can demonstrate that introducing the requirements will deliver a benefit to the community (DHPW, 2013). Prior to the QDC MP 4.2 legislation coming into effect, state and local governments offered home owners of existing dwellings substantial rebates to assist in covering the costs associated with purchasing and installing (i.e., retrofitting) a rainwater tank. Despite these rebates, which varied between $1000–$1500, less than 20% of home-owners in the urbanised area of SEQ retrofitted their homes with a rainwater tank prior to the introduction of QDC MP 4.2 (RWIMU, 2009). Water administrators and researchers were not equipped with available knowledge to explain why the uptake of rainwater tanks was not higher, despite the obvious advantages of rainwater tanks in providing increased water supply to homes, minimising the impact of water restrictions and unlimited rainwater use outdoors for tanks not internally plumbed.

The example of SEQ, where there was low uptake of household rainwater collection systems despite financial incentives that helped to overcome any cost barriers to their implementation, suggests that social and psychological factors may be playing a role in residents' decisions to install a rainwater tank. Therefore, social research can help to identify underlying reasons why people do or do not install rainwater tanks. Until recently, there was little empirical investigation of the psychological underpinnings of intended or actual rainwater use and/or maintenance of rainwater tanks. Much of the general social research on rainwater tanks conducted in the past was carried out by Gardiner and colleagues in SEQ (Gardiner *et al.* 2007; Gardiner *et al.* 2008; Gardiner, 2009; Gardiner, 2010). However, more recent research conducted by Mankad and colleagues (Mankad *et al.* 2010; Mankad *et al.* 2011; Mankad & Tucker, 2013) examined psychosocial issues surrounding rainwater use and maintenance and this research will be presented in the case studies provided in this chapter.

In the remainder of the chapter we provide a review of the social literature on rainwater use. The research on this topic has been conducted in Australia and therefore the literature reviewed is focused on the Australian context. We then outline two psychological frameworks that may be particularly relevant to social research on rainwater tanks. We present methodological recommendations for addressing two key social research questions relating to rainwater tanks: 1) Investigating public acceptance and uptake

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of rainwater tanks; and 2) Identifying motivational drivers of rainwater tank maintenance behaviours. We also provide case studies to illustrate the use of these methodologies to address the two key research topics.

8.2 PAST SOCIAL RESEARCH ON RAINWATER USE IN URBAN AUSTRALIA

Historically, Australians have had a preference for using harvested rainwater in their homes, until local governments introduced mandatory charges for centralised mains water within urban areas, whether homes used the mains water or not (Coombes & Kuczera, 2002). As Coombes and Kuczera explain, this mandatory charge was to ensure the economic viability of a centralised water supply for councils and steer people away from their preferred, independent, rainwater supply. Thus, Australia's water culture shifted in the late 19th century from having a reliance on rainwater tanks to relying on a centralised water grid (Brown *et al.* 2008). Even as recently as the 1990s, rainwater tanks (mainly built from galvanised iron) were strictly discouraged in urban areas by local governments because they were considered to be hazardous to public health due to the risk of breeding mosquitoes, leading to the outbreak of arboviruses such as dengue fever (WHO, 2002). This historical context is likely to have had a prevailing and significant influence on present-day community concerns about the quality of rainwater harvested from tanks, and helps to explain why the adoption of rainwater tanks in urban areas remains lower than advocates would hope. An unrestricted supply of relatively inexpensive centralised urban water may also help to explain why rainwater tanks are more widely used in peri-urban areas (where connections to centralised supplies are not feasible due to technical and economic considerations) than in urban areas, where all homes are connected to a centralised town water supply.

In addition to a shift in water provision processes in urban Australia, the introduction of modern cultural innovations, such as hot water systems and water-intensive appliances like washing machines, meant that people could no longer rely on their rainwater tanks to adequately and reliably provide the amount of water required to support these modern water use habits (Moy, 2012; Shove, 2003). These modern changes were not designed with water conservation in mind. Rather, they reflected society's changing views on how water was used and its functional value in society; water was no longer seen as a basic need for survival. Instead, water had become a tool in creating new expectations about the ideal standards for quality of life (e.g., the expectation that hot water could be accessed immediately and that a washing machine will produce clean clothes and maintain personal hygiene). As a consequence, generations of Australians were losing touch with Australia's historical affinity with, and reliance on, rainwater and all that came along with that, such as frugal water use habits and a working knowledge of the water cycle.

There has been much social science research on the acceptance of alternative water sources in modern urban Australia, however, it has mainly been limited to public and industry acceptance of centralised forms of alternative water, such as recycled municipal wastewater and desalinated seawater. Specific social science research on rainwater tank acceptance has been limited. The research that does exist on rainwater suggests that the public are accepting of rainwater harvesting and, in some instances, indicate a preference for rainwater over other forms of alternative water (e.g., Hurlimann, 2007; Hurlimann & Dolnicar, 2010). In Marks *et al.*'s (2008) survey of public acceptance of alternative water sources, participants viewed rainwater as the cleanest form of water and a majority of respondents were willing to use it for drinking and domestic uses.

Gardiner's (2009) descriptive research on rainwater tanks demonstrated that rainwater tanks were highly valued in the community because of their benefits at the household level, and their perceived

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positive impact on the environment by reducing reliance on the mains water supply grid. Her research suggested that there were distinct groups of tank owners: environmentally committed tank owners (i.e., had a tank to reduce their environmental impact), garden-focused retrofitters (i.e., used their tank primarily for recreational gardening), and disinterested tank owners (i.e., saw tank as only useful during drought and were unlikely to persevere with a tank in the long term). These findings suggest that due to their differing perspectives on tank use, these groups would likely have differing motivational interests in learning more about appropriate tank maintenance, and they may embrace the lifestyle of independent water use in different ways.

Although the use of alternative water supply systems is increasing worldwide, it is still not widespread in many developed areas and the growth rate in rainwater tank use from 2007 to 2010 in Australia was 6% (WWAP, 2012; ABS, 2010). Further, the cost of rainwater from a tank is still high when compared to the cost of town water supply from a large, centralised system. Thus, cost savings may not necessarily be the main driver for the adoption of rainwater tanks as the literature (Marsden Jacob Associates, 2007; Tam *et al.* 2010; Hall, 2012) indicates that the cost of water supplied from rainwater tanks is higher than from centralised water supplies.

Arguably, cost-effectiveness may not be the main driving factor for the adoption of rainwater tanks because the pay-off period is long and the upfront cost is high. Other non-economic factors, such as quality of life, lifestyle and the freedom to avoid water restrictions may be the key to encourage rainwater tank adoption. It is clear that little research has focused on rainwater tank adoption or the role of psychological and economic factors in adoption, acceptance and use of this alternative water source. Given this dearth of existing knowledge, in this chapter we focus on how we can gain a better understanding of public perceptions of rainwater tanks as well as the motivational drivers for adopting and maintaining rainwater tanks. In the next section we provide a brief overview of two psychological theories that can help us to understand these issues. These theories provide the broad theoretical framework for the case study research presented later in the chapter.

8.3 THEORETICAL FRAMEWORKS FOR UNDERSTANDING PUBLIC ACCEPTANCE, ADOPTION AND MAINTENANCE OF RAINWATER TANKS

One way to think about the installation of rainwater tanks is as a way for householders to deal with the threat of drought and water scarcity. Protection Motivation theory (PM theory; Rogers, 1975; 1983), which is a framework that outlines the cognitive processes that underpin people's decisions to respond to threat (i.e., to take protective action), is therefore relevant to understanding rainwater tank installation decisions. According to this perspective, there are two processes that feed into decisions: threat appraisal and coping appraisal (see Figure 8.1). People will experience greater threat if they think they are vulnerable to a severe situation. In the context of rainwater tank adoption, residents are likely to perceive greater threat if they believe that drought conditions will directly affect them and that the effect of drought on their lives will be severe. The other process that feeds into decisions is the coping appraisal. This appraisal process involves perceptions of how effective the recommended response will be in overcoming the threat (response efficacy), one's ability to carry out these recommended responses (self-efficacy), as well as an assessment of the costs of responding (e.g., time, effort, money). So, if residents believe that rainwater tanks can help to reduce the threat of water scarcity, if they believe that they have the means and capability to install a rainwater tank, and that the time, effort or financial costs are not too onerous, then people will be more likely to intend to install a rainwater tank. Bringing these two processes together then, the decision to install a rainwater tank will be more likely to the extent that householders feel threatened by drought and water scarcity and that they believe that a rainwater tank is an effective way to address that threat.

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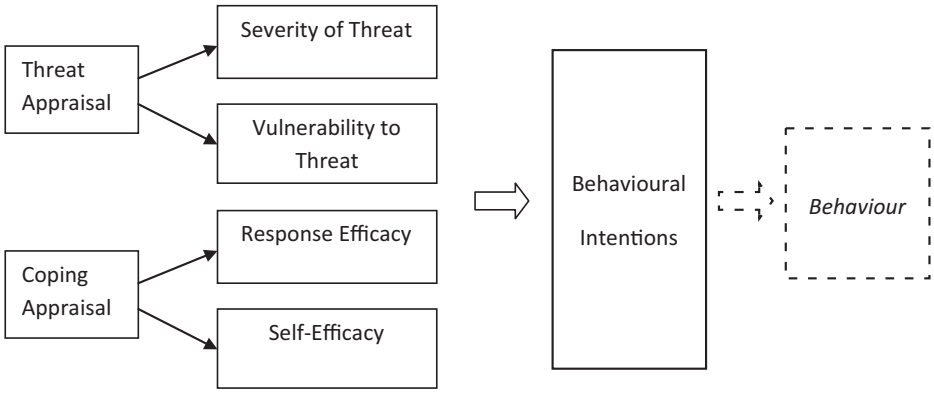


Figure 8.1 An abbreviated depiction of variables associated with protection motivation theory (Rogers, 1983).

When considering the issue of rainwater tank maintenance behaviour, the motivation that people experience to engage in this behaviour is particularly important. Self-determination theory (SDT) (Deci & Ryan, 2000), a meta-theory of human motivation, is therefore particularly relevant to this issue. Self-determination theory proposes that the social environment influences the quality of motivation that people experience. Better quality motivation (defined as more self-determined motivation) is more likely when the social environment satisfies three basic human needs, that is: for autonomy, competence and relatedness. Autonomy refers to people having choice and agency in their decisions, competence refers to a sense of self-efficacy in relation to specific actions, and relatedness refers to a sense of belonging and connectedness to others. It is hypothesized that social environments that foster greater autonomy, competence and relatedness result in more internalized, self-determined motivation and, therefore, better behavioural outcomes (Deci & Ryan, 2000).

Self-determination theory theorises about the quality of motivation by distinguishing between different types of motivation, which sit along a continuum from less self-determined to more self-determined motivation (Grolnick & Ryan, 1987). At one end of the self-determination continuum (Figure 8.2) is *amotivation,* which reflects a lack of action stemming from not valuing a particular behaviour, not feeling competent to engage in the behaviour or the belief that it will not yield the desired outcome. Any of these rationales could underpin residents' amotivation or apathy for engaging in rainwater tank maintenance. At the other end of the continuum is *intrinsic motivation* whereby individuals engage in behaviours for the inherent interest, enjoyment and satisfaction derived from the behaviour. As described in Figure 8.2, Ryan and Deci (2000) acknowledge that much of human activity is extrinsically (externally) motivated, rather than intrinsically (internally) motivated, although behaviours vary with regards to how much they are internally or externally motivated. As it seems unlikely that many people maintain their tank for the sheer enjoyment of it, the motivation for rainwater tank maintenance may be more likely to be externally motivated, for example, by government regulation or by neighbourhood norms of what other householders do to maintain their tanks. Self-determination theory is also relevant to the issue of retrofitting versus mandating rainwater tank installation. Although mandating installation of rainwater tanks has the advantage of encouraging greater uptake, the downside may be that the lack of choice reduces people's sense of autonomy and reduced autonomy has been shown to have negative impacts. One potential negative impact in relation to rainwater tanks is that people may be less likely to maintain their tanks.

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Lowest----------SELF-DETERMINATION----------Highest					
Amotivation	External regulation	Introjected regulation	Identified regulation	Integrated regulation	Intrinsic motivation

Figure 8.2 The self-determination continuum (Grolnick & Ryan, 1987).

8.4 INVESTIGATING PUBLIC ACCEPTANCE OF RAINWATER TANKS: QUALITATIVE METHODS

An important social research question in relation to rainwater tanks is to understand what influences public acceptance and adoption of these systems. Results from past research have indicated that there is a high level of overall acceptance of rainwater for non-potable applications, however, adoption of domestic rainwater tank systems is low in urban areas. This high level of community acceptance coupled with low levels of adoption suggests a need to understand the barriers that may exist to uptake of these systems. The question of identifying barriers and facilitators is particularly amenable to qualitative research as this approach can provide a deeper understanding of the issue and allow researchers to gain insight into the issue from the perspective of the participants (Silverman, 2013). For research topics that have received little attention, it is helpful to begin with an exploratory qualitative approach, such as focus groups and semi-structured interviews, and, if appropriate, quantitative research can be conducted subsequently to investigate whether the qualitative findings generalise to the broader population.

Qualitative interviews can be unstructured and represent an interaction between interviewers and respondents that has a general plan but no specific questions. However, addressing the issue of barriers and facilitators to rainwater tank adoption lends itself more to a semi-structured interview approach whereby the interviewer has a set of questions that guide the interaction, but there is also scope to follow-up other issues that are raised during the interviews. Focus groups are another qualitative method that could be used to investigate this issue. Focus groups have the advantage of being quick and relatively low-cost and the group dynamic can sometime allow additional information to come to the fore. On the other hand, the researcher has less control than when conducting individual interviews and there are more complex logistics required to organise focus groups.

In Section 8.4.1 below we provide a case study of the use of semi-structured qualitative interviews to explore the facilitators and barriers to the adoption of rainwater tanks in SEQ. The case study represents a first phase of a broader research program undertaken as part of the Urban Water Security Research Alliance (UWSRA) seeking to identify determinants of public acceptance and adoption of rainwater tanks.

8.4.1 Identifying facilitators and barriers to rainwater tank adoption in South East Queensland

The qualitative interview case studyfocused on exploring attitudes and perceptions of household decentralised systems (rainwater tanks and greywater systems) among those with and without such systems on their property (Mankad *et al.* 2010; Mankad & Tucker, 2013). Throughout the study, it became evident that rainwater tanks were the most salient of decentralised systems, and therefore we limit our discussion here to the results on key dimensions of acceptance of rainwater tanks.

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This case study comprised qualitative semi-structured interviews with homeowners who did and did not have functional rainwater tank systems on their property (i.e., Users and Non-Users respectively). The aim of this study was to identify key themes or drivers of acceptance that could be used in future quantitative research (e.g., assisting in survey development). Participants with rainwater tanks were sampled from three locations. The first was an eco-development located within Gold Coast local council, approximately 100 kilometres south of Brisbane, and 7 km inland from the coast. The location was chosen as it is the site of a relatively recent development with a strong focus on environmentally sustainable living and the development relied solely on several decentralised water supply systems working in tandem. The second location was within Brisbane local council, situated approximately 15 km west of Brisbane city. This location was chosen because it was the site of a new sustainable greenfield development that included decentralised water systems, which will eventually comprise 22 lots when completed. At the time of data collection, only six lots had been developed and residents had been living in their homes for a minimum of 12 months. The third location, within Moreton Bay local council, is a region 45 km north of the city of Brisbane designed for environmental sustainability with just over 100 lots in the development. Participants without rainwater tanks were recruited from the same localities in areas adjacent to the eco-developments. The Users and Non-users groups were matched on dwelling location and were comparable on demographic criteria such as age and gender.

Participants were recruited via:

- *Telephone recruitment,* using a specialised research recruitment company;
- *Door-knock recruitment,* where research assistants approached individual home owners and explained the study's purpose, as well as participation requirements; and
- *Emailed newsletter*, where housing developer restrictions meant that researchers were not permitted to access the community's residents. Instead, an email outlining the study and participation requirements was forwarded to residents via the community's intranet and residents were asked to contact researchers directly if they were interested in taking part.

Involvement in the study was voluntary and all respondents gave written consent for their participation. Participants were assured of confidentiality and were given a $100 gift voucher in recognition of their participation (Dillman, 2007). Participant selection was based on the following criteria:

(1) Respondents were homeowners or paying their mortgage; this was a delimitation applied to participant recruitment to exclude renters because, typically, renters do not have the authority to make decisions regarding modifications to the property, such as the installation of a rainwater tank.
(2) Users and Non-users were matched on locality of residence to ensure similarities in the surrounding environmental condition of both groups and to minimise demographic differences related to variables such as income and education.
(3) As noted above, those with rainwater tanks (Users) were recruited from purpose-built eco-developments and those without rainwater tanks (Non-users) were recruited from established suburbs adjacent to those eco-developments.
(4) It was necessary that the Non-users were not using any type of decentralised water system so as not to confound the interpretation of results.

Interviews took place in individual respondents' homes, with two researchers present. The interviews varied between 25–60 minutes in duration and were conducted within a single week. Participants were asked to respond openly and honestly to the questions and were informed that they were free to withdraw at any time without penalty. Individuals were also asked their permission for researchers to audiotape the interview to maintain accuracy of the data being obtained.

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Given the semi-structured format, interviewers began the session by asking both groups of respondents what their general background knowledge was of the water supply being plumbed into their homes. This was to encourage participants to think more broadly about their household water and its use, before moving on to discuss more detailed aspects of their beliefs, values and knowledge regarding decentralised systems. After the initial question, the interview guidelines for the two groups varied, due to differences in exposure to, and experience with rainwater tanks:

- *Users of rainwater tanks* were asked to describe their current residential water systems and to identify the main reasons why their household had chosen to adopt this water supply. Respondents were encouraged to demonstrate their knowledge of the systems adopted and any related issues, such as maintenance and functioning. Advantages and disadvantages associated with a rainwater tank were discussed and respondents were asked to think about ideal changes or improvements they would make, if given the opportunity. Householders were asked to consider how others (i.e., Non-users) may feel about their rainwater tank systems and highlight any concerns they had as users of rainwater systems.
- *Non-users of rainwater tanks* were asked a number of preliminary questions, relating to their understanding of what an on-site rainwater tank system was, awareness of rainwater tank systems available for residential use, and general thoughts concerning these alternative water supplies. Interviewers then guided the topic of conversation towards gaining insight into the reasons why current Non-users would or would not consider adopting rainwater tanks in the future, as well as their thoughts about why others may choose to install rainwater tanks. Participants' perceptions of the associated advantages and disadvantages were explored, and respondents were encouraged to discuss concerns they had regarding alternative water supplies.

Interviews were transcribed verbatim and participants were not identified within the transcript at any stage. Data were then coded and content analysed using NVivo 8 (QSR International, 2008) by two researchers directly involved in the study, plus one team member who was not involved in data collection to limit interpretation biases. Analysis of the data included identifying and extracting recurrent themes and sub-themes within the interview text, to gain an understanding of participants' beliefs regarding rainwater tanks, the existing level of knowledge among both Users and Non-users of rainwater tanks, as well as personal and social values attributed to rainwater tanks. Inter-rater reliability was high amongst the three raters.

As a qualitative and exploratory study, it is important to understand that this research methodology was not concerned with a population sample which would be subject to statistical analysis. Therefore, the final number of participants in this study was determined based on *data saturation* being achieved (Marshall, 1996; Sandelowski, 1995). Saturation refers to a completion of the analysis process when no new concepts are identified in the data. The ultimate sample size is, therefore, determined by data saturation or peak, and traditional 'rules' about an appropriate sample size should not be applied to qualitative data.

8.4.2 Case study findings

Results indicated a high level of overall acceptance for the use of rainwater for non-potable applications. Both groups indicated that living sustainably was a desirable way of life (e.g., utilising a rainwater supply to supplement household water). However, participants acknowledged that the decision to live sustainably was usually influenced by external factors such as property regulations and financial constraints (e.g., rainwater tank infrastructure was significantly more expensive than 'normal' infrastructure). Both groups also cited the benefits (or potential benefits for the Non-users) of having increased water supply around the home, especially with regards to an increase in the quantity of water available to water gardens and lawns.

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The majority of respondents from the Users group stated that property characteristics, such as locality, outlook and geographic orientation, were dominant factors for choosing to live in their current homes. Environmental benefits associated with using rainwater were of secondary importance. Users cited many advantages of having a rainwater supply; the primary advantage being the superior quality of drinking water produced from the rainwater tanks, which was perceived to be free of chemicals such as chlorine and fluoride, unlike council water. Cost savings from harvesting one's own water supply were also mentioned as another benefit. However, most Users conceded that the true financial benefits of using an alternative water source (rainwater) would probably only become apparent after at least 10 years of continuous use, usually because of high running costs.

Users cited the high amount of electricity required to pump water from a rainwater tank to the household taps as a major disadvantage of using a tank and, in some locations, participants raised concerns regarding poor installation of rainwater tanks, which led to problems such as leakage and back flow. This then led to tensions between water system providers and the residents. Amongst a number of other concerns raised, Users cited maintenance issues as a disadvantage of owning and using rainwater systems, as they required ongoing maintenance, which could be costly in some instances. Such problems were cited as a severe disadvantage of living in an area that had employed an innovative building approach where water efficient infrastructure was being trialled and was, thus, still experiencing teething problems. These problems caused residents to be less confident in the quality of their harvested water and, as a result, people cited being less likely to use the water for potable *or* non-potable purposes (Figure 8.3).

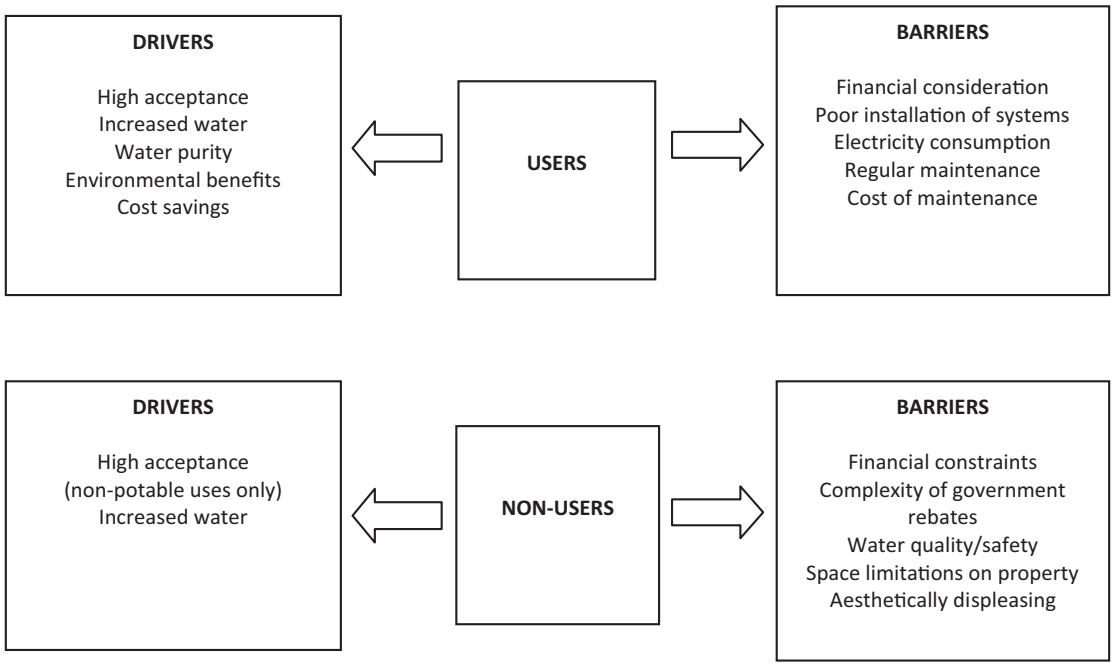


Figure 8.3 Drivers and barriers to living with rainwater tanks, as cited by users and non-users of the infrastructure (Mankad *et al.* 2010).

Non-users typically formed their attitudes and perceptions about rainwater tanks based on observations of rainwater tank use of friends and neighbours (i.e., a type of normative comparison). These observational experiences were reportedly positive, possibly explaining why the data highlighted such high acceptance of

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rainwater tanks among Non-users. However, there was consistent doubt among Non-users of the ability of rainwater tanks to adequately treat the water to drinking standards. This is likely to be because participants typically reported seeing acquaintances using their rainwater primarily for outdoor applications, such as watering the garden and washing vehicles. Consequently, Non-users stated their intentions for installing a rainwater tank would be for non-potable uses, as they were reluctant to use rainwater for indoor applications, particularly drinking and cooking. Non-users consistently mentioned three dominant barriers to adopting rainwater systems around their homes: 1) financial limitations (particularly in low-income areas), 2) perceived complexity of applying for government rebates, and 3) space constraints on their property (Figure 8.3). Most Non-users stated that, if building a new house, they would opt for installing an underground rainwater tank at the building stage, despite the greater capital costs, rather than installing a tank outside the new home. Non-users felt that their homes were not designed to accommodate a rainwater tank and there seemed to be a clear perception among this group that external rainwater tanks damaged the housing aesthetic (Figure 8.3).

Interestingly, when talking about water use patterns, a majority of participants, both Users and Non-users, explained that they were no longer as 'strict' in their water savings behaviour because they believed there was little threat of water shortages 'these days' following significant rainfall events and reported consequently having longer showers and watering their gardens more than they used to when the drought was 'on'. This attitude demonstrated a low perceived threat for future water shortages among all participants and was evidently influencing their current water use behaviours. This finding alluded to the importance of threat and risk perceptions in water use behaviours and intended adoption of rainwater tanks. Therefore, the data highlighted a need to understand the influence of perceived threat and vulnerability to threat on rainwater tank adoption and use.

8.5 INVESTIGATING PUBLIC ACCEPTANCE OF RAINWATER TANKS: QUANTITATIVE METHODS

While qualitative approaches can provide rich data that allows researchers to drill down into the experiences of specific groups within society, quantitative approaches such as surveys can reach representative samples to gain a broader understanding of issues. Quantitative surveys also allow researchers to test for statistical relationships between variables and can assess the utility of specific theoretical perspectives for understanding an issue. It also allows researchers to investigate whether themes that emerged from qualitative research can be generalised to the broader population of interest. In the following section we provide a case study of a quantitative survey that was conducted in SEQ as part of the UWSRA social research program to explore acceptance of rainwater tanks.

8.5.1 Predictors of rainwater tank adoption in South East Queensland

The quantitative case study was guided by Protection Motivation Theory as well as testing the importance of dominant themes emerging from the qualitative phase (discussed in Section 8.4). It aimed to examine the role of perceptual and motivational factors in predicting rainwater tank ownership. Protection Motivation Theory was outlined in Section 8.3; according to this perspective the likelihood of an individual carrying out risk-reduction behaviours, such as installing a rainwater tank in response to a perceived water shortage threat, is increased if there is: 1) belief in one's vulnerability to the water shortage threat; 2) belief in the severity of the water shortage threat; 3) belief that the suggested risk-reduction (protective) behaviours are effective ways to mitigate the risk of water shortage; and 4) belief that one is capable of carrying out protective behaviours to successfully avoid water restrictions associated with the water shortage threat. A quantitative survey that includes measures of these variables can help to identify whether these factors

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are key determinants of public acceptance of rainwater tanks. As cost had emerged in the qualitative interviews as an important barrier to rainwater tank adoption, we also incorporated a choice experiment in the survey that assessed willingness to pay for a rainwater tank.

An online survey method was chosen to collect quantitative data on 'protective' motivations surrounding water shortage threat (Mankad *et al.* 2011; Mankad *et al.* 2013). Participants were recruited from local government areas within SEQ: Brisbane city, Gold Coast, Logan, Moreton Bay, Redland city, and Sunshine Coast. Participants were verified as SEQ residents through their self-reported postcode. The survey comprised:

- *Standard demographic questions* (e.g., age, income, occupation), as well as other more specific descriptive items relating to rainwater (e.g., uses for rainwater, treatment process for rainwater at home, number of bedrooms/bathrooms in the house, actual household water consumption).
- *Perception and motivation* items adapted from qualitative findings (Mankad *et al.* 2010) and the structure of items adhered to existing psychological theory (Rogers, 1983; see relevant PM theory discussion in Section 8.3). Responses to the psychological items in the survey (i.e., threat severity, threat vulnerability, response costs, response efficacy, self-efficacy, subjective knowledge, norms) were typically made using a 5-point Likert format, where only the lowest and highest points were named (e.g., 1 = strongly disagree; 5 = strongly agree). Reliability coefficients were generated for each of the psychological sub-scales, as a measure of internal consistency and reliability between items within the same scale. For more detailed information regarding the items used in this online survey, please refer to Mankad *et al.* (2011) and Mankad *et al.* (2013).
- *Intentions to install a rainwater tank* was the main dependent variable and was measured on a scale from 1 (very unlikely) to 5 (very likely). Participants were also asked if they had already installed a rainwater tank on their property.
- *Willingness to pay* for rainwater tanks was evaluated using the choice experiment method (see Louviere & Hensher, 1982; Louviere & Woodworth, 1983) to determine how much households in SEQ were willing to pay for various rainwater tank sizes, when faced with choices of near perfect substitutes, which were greywater systems and bores or spear pumps. The amount of money that an individual is willing to pay is used to reflect his or her preferences for one system over another. The questionnaire and experimental design of the choice experiment study is detailed in Tapsuwan *et al.* (2014).

The study consisted of a cross-sectional survey targeting residents within SEQ, a region identified as hydrologically 'at risk' (QWC, 2009). The aim was to ensure that the sample population was comparable with the most recent Australian Bureau of Statistics population data available (ABS, 2007). Participants were recruited through an online research panel (database) from local government areas within SEQ; potential participants were verified as SEQ residents through their self-reported postcodes. People initially received an invitation email to take part in the survey and were then directed to the survey by following the survey hyperlink. Participants were also informed via the invitation email that if they completed the survey, they would receive 'reward points' through the online research company as incentive for participating in the study. An appropriately weighted incentive can enhance participation rates (Dillman, 2007).

A total of 406 participants fully completed the online survey; respondents were screened prior to participation to ensure that they were home owners or paying a mortgage of a free-standing dwelling, which was connected to the centralised town water supply. This was to exclude short-term renters, apartment owners and rural property dwellers from participating in the survey, ensuring that participants only comprised urban citizens who actively engaged in water supply-related decisions within their homes. The survey took approximately 20 minutes to complete. After completing the component of the survey

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that assessed psycho-social factors, participants completed the demographics section and then moved on to take part in the choice modelling component.

8.5.2 Case study findings

8.5.2.1 Psychological predictors of rainwater tank adoption

Results indicated that subjective knowledge, threat appraisal, response efficacy, response costs, subjective norms and social norms accounted for 43% of variance in intentions to install a rainwater tank, which is considered a moderate to high amount of explained variance in the psychological sciences (Cohen, 1988).

Table 8.1 lists the key unique contributors to the model of rainwater tank adoption intentions in order of relative contribution (Mankad *et al.* 2011; Mankad *et al.* 2013). Response efficacy was the strongest predictor of intentions to install a rainwater tank. That is, individuals who felt that they could manage these systems well were more likely to express intentions to install rainwater tanks in the future and more likely to already have a rainwater tank system at home. The next most important predictor was threat appraisal. This relationship shows that the more residents felt that they were threatened by future water shortages the more they intended to install a rainwater tank. Subjective knowledge, which refers to how much people thought that they knew about the water situation in the region was also positively related to rainwater tank adoption. Interestingly, participants' social awareness of what was expected of them as citizens (i.e., the extent to which they perceived that important others think they should install a rainwater tank) was also an influential factor in their intention to own a rainwater tank.

While the factors discussed to this point are positively related to rainwater tank adoption, response costs was negatively related. This means that the more that residents felt there were costs (e.g., time, affordability, space) related to rainwater tanks, the less likely they were to install a tank. It was also evident that those residents who had installed a rainwater tank perceived significantly lower costs associated with using a rainwater tank, as well as greater response efficacy (i.e., higher confidence that a rainwater tank can protect the householder from the negative effects of future water restrictions).

Table 8.1 Relative contribution of the five key variables that significantly predicted protective behavioural intentions towards rainwater tank adoption (Mankad *et al.* 2013).

Predictor	Beta coefficient
Response efficacy	0.253
Threat appraisal	0.237
Response costs	–0.228
Subjective knowledge	0.168
Subjective norms	0.141

Note: Higher beta scores indicate a greater weight (i.e., greater contribution to the explanatory model) and a negative sign indicates a negative relationship (i.e., greater perceived response costs is associated with poorer tank adoption).

The results suggested that motivational factors played a significant role in rainwater tank adoption. In particular, the strength of perceived effectiveness of rainwater tanks (i.e., response efficacy) as a driver of intentions to install a rainwater tank, suggests that it is critical to clearly communicate how the installation

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of rainwater tanks in homes can serve as a protective response to the threat posed by urban water stress. For example, if people believe that a rainwater tank is effective in protecting the individual, their lifestyle and their property from a water shortage threat, they may be more likely to report strong intentions to engage in rainwater tank adoption and actively seek out knowledge specific to rainwater tank installation and use.

8.5.2.2 Willingness to pay for a rainwater tank

The online survey also included a series of choice questions to evaluate the influence of rainwater tank cost and the cost of near perfect substitutes on the adoption of rainwater tanks (see Tapsuwan *et al.* 2014). Designing an efficient water supply management strategy requires an assessment of consumer preferences, as consumers contribute to the augmentation of supply through the adoption of rainwater tanks or other decentralised water systems (e.g., greywater or groundwater). Consumer preferences can be understood through their stated willingness to pay levels for various types of water supply sources. In the context of rainwater tank adoption, willingness to pay can help inform policy-makers whether rainwater tanks are preferred over other types of decentralised water systems or not.

In addition to ascertaining preferences through a series of choice questions, socio-economic variables are also collected in willingness to pay studies because there are many factors, in addition to the water system itself, that determine how much an individual is willing to pay. Theoretically, the most important economic factor is income because an individual can only pay as much as he or she can afford. More recently, sophisticated statistical software packages, such as MPlus (Muthén & Muthén, 2012), enable the estimation of structural models where psycho-social factors can be integrated into the willingness to pay models. Hence, we now have a better understanding of the underlying socio-economic and attitudinal factors that drive preferences and willingness to pay.

Although rainwater tanks are considered market goods, there is a lack of market data to reliably associate socio-economic and attitudinal information to people's purchasing behaviour, especially when consumers have to choose between installing a rainwater tank versus other types of decentralised water technology. Additionally, finding out how much people are willing to pay for future installations is in fact ascertaining preferences in the context of a hypothetical market. Given the current policy practice of intervening in markets and encouraging adoption through the use of consumer subsidies or mandated adoption, it is important to find out the gap between the willingness to pay value placed on these technologies and the actual market price.

Results from the willingness to pay study shows that the willingness to pay for rainwater tanks ranged from $2100 to $5000 for small rainwater tanks (<5000 ltr), $2100 to $7400 for medium-sized rainwater tanks (5000–25,000 ltr), and $800 to $3600 for large rainwater tanks (>25,000 ltr). For comparison, willingness to pay for greywater systems ranged from $1700 for greywater diversion devices for outdoor use only to $14,000 for greywater treatment devices for both indoor and outdoor non-potable uses. (Tapsuwan *et al.* 2014). The willingness to pay estimates for rainwater tanks show diminishing marginal return on tank size, as indicated by the low willingness to pay for large tanks relative to medium-sized tanks. As the sample consist mostly of urban households, large rainwater tanks would not be as desirable as small and medium size tanks because of space requirement. Households may even view the size as excess to their needs. When compared to actual market prices (Figure 8.4), willingness to pay was substantially lower and subsidies would be required to encourage people to buy rainwater tanks. Subsidies of $1650, $2650 and $4950 for small, medium and large rainwater tanks, respectively, would increase the adoption level to 63% of the sample and a full price subsidy would be required to achieve 100% adoption. In order for the remaining 33% of the sample to install rainwater tanks, the technology would essentially have to be given out for free. Of course, considerations must be made about whether investments in government subsidies

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or hand-out programs are worth the cost savings associated with not having to augment a new source of supply. Having said that, at least 17% of the sample will buy small or medium size rainwater tanks at market price (i.e., no subsidies required).

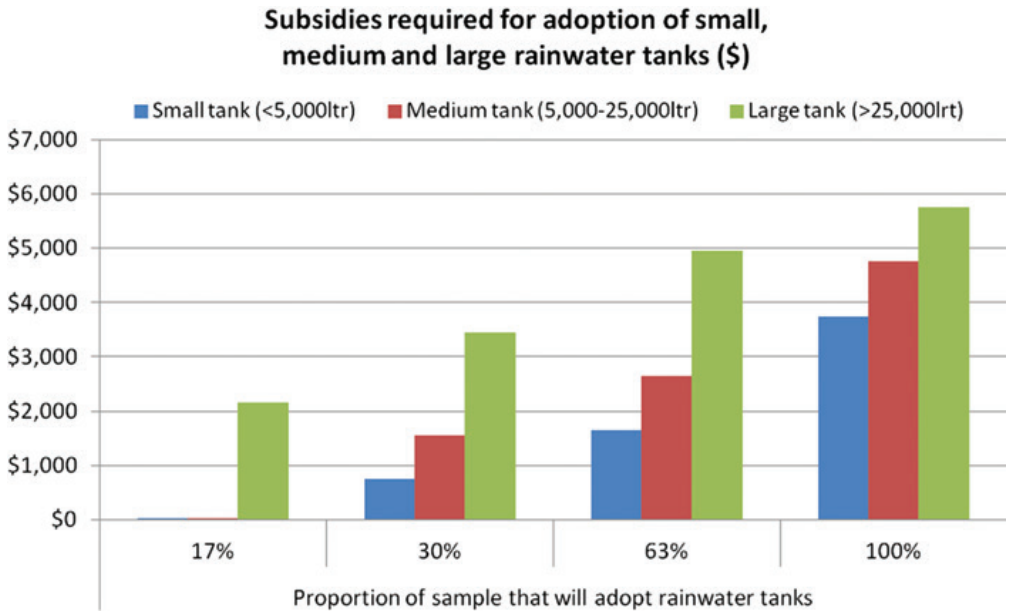


Figure 8.4 Subsidies required for the adoption of small, medium and large rainwater tanks.

8.6 IDENTIFYING MOTIVATIONAL DRIVERS OF RAINWATER TANK MAINTENANCE: QUANTITATIVE METHODS

A second important social research question relating to domestic rainwater tanks is to understand what motivates residents to maintain and manage their tanks. If rainwater tanks are to be an integral and effective part of the domestic water supply system in the long term it is important that they are maintained to ensure their safety and proper functioning. This question could fruitfully be addressed through qualitative and quantitative social research approaches. Conducting qualitative interviews or focus groups with householders who have rainwater tanks that have been retrofitted or that have been mandated in a new home would provide important insights into the facilitators and barriers of tank maintenance. Representative quantitative surveys of the same two groups (i.e., retrofitters and mandated installers) can describe the general level of tank maintenance being undertaken by households as well as the factors that predict householders' willingness to engage in maintenance activities. Quantitative surveys also allow researchers to statistically assess the size of the relationship between predictors and outcomes (i.e., rainwater tank maintenance).

In the following sections we provide two case studies that adopt quantitative research methods to identify the extent of householders' maintenance behaviour, whether maintenance activities vary between households that have retrofitted their tanks or been mandated to install them in a new dwelling, and what factors (including psychological factors) motivate householders to engage in maintenance activities. The two case studies are drawn from research conducted as part of the UWSRA in SEQ.

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8.6.1 Drivers of rainwater tank maintenance behaviour for mandated tank owners

The first case study used a population-based mail out survey to examine the rainwater tank maintenance activities of residents with 'mandated' rainwater tanks in SEQ. The survey was broadly framed by self-determination theory and examined the basic motivational needs that are considered prerequisites of motivated behaviour (Mankad *et al.* 2012c). The mail out survey comprised a range of questions, designed to collect descriptive information about participants' rainwater tank set-up, as well as questions within the motivational orientations framework (Deci & Ryan, 2000), to provide greater insight into maintenance-related attitudes and behaviours of rainwater tank owners. Categories of items included:

- *Filtering questions* – to ensure the sample only included households with rainwater tanks and other sample requirements.
- *Demographics and general psychosocial descriptors* – age, gender, income, household composition, occupation, education, ethnicity, past history of living with a rainwater tank, householder satisfaction with rainwater, willingness to use rainwater for household uses, and perceptions of responsibility for maintaining their rainwater tank. Some items used a structured response format (i.e., male or female) and other items utilised the Likert format (e.g., 1 = Strongly disagree, 5 = Strongly agree), depending on which was most appropriate to measure participant responses.
- *Physical tank set-up* – tank volume, tank connections, plumbing, water level indicator, purposes for rainwater use (e.g., 'toilet flushing', 'clothes washing', 'garden irrigation'), estimate of how much of the household's total water use was from the rainwater supply, how often householders used their rainwater (e.g., daily, weekly, monthly), and a description of the types of water appliances and fixtures installed in the home (e.g., low flow taps and shower heads, dual flush toilets).
- *Psychological perception subscales* – perceived competence, perceived autonomy and perceived relatedness; responses were made using a 5-point Likert format (e.g., 1 = Not at all true, 5 = Very true) to indicate level of agreement to statements.
- *Attitudinal subscales* – perceptions of tank ownership, perceived water culture, perceived water rights; responses were once again made using a 5-point Likert scale as a measure of agreement (see Mankad *et al.* 2012a for a more detailed description of survey items and wording).
- *Regularity of rainwater tank maintenance (Dependent Variable)* – how frequently participants self-reported carrying out particular tasks on a rainwater tank maintenance schedule. The list of 13 maintenance tasks included checking and cleaning the first flush device, checking mosquito screens and repairing holes and other damage, inspecting and clearing gutters, checking pipes for structural integrity, and so on. All tasks were described using a specific time frame (e.g., 'check mosquito-proof screen . . . *every 6 months*', 'check for evidence of bird or animal access . . . *every 3 months*'), so that participants could indicate whether their maintenance behaviour aligned with the correct maintenance guidelines, as outlined through the Australian Government (DHA, 2004; Queensland Health, 2007). The response scale was a 5-point Likert scale (1 = Never, 2 = Rarely, 3 = Sometimes, 4 = Almost always, 5 = Always).

Any householders who had been contacted to participate in any previous rainwater tank associated social research studies were not approached for the present study. Units and apartment blocks were also not sampled, as it was unclear if householders residing in these complexes would be responsible for maintaining their own rainwater tanks. Recruitment was limited to Local Government Areas (LGA) of SEQ where mandated lists were supplied. These LGA included: Gold Coast, Logan, Moreton Bay, Redland and Sunshine Coast. The target sample size for each LGA was determined based on an estimation of the

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proportion of residents living in that area. A conscious effort was made to avoid suburbs that were affected by the severe flooding events that occurred in the region in January 2011. In particular, Brisbane City, Ipswich and Lockyer Valley local government areas were excluded from the study for this reason. Surveys were mailed out to relevant homes in SEQ using a three-staged mail-out strategy, with the first stage involving an introductory postcard, to notify potential participants of the upcoming survey on rainwater tanks, followed by a mail-out questionnaire, reply paid envelope and eco-friendly shopping bag, intended to serve as a minor incentive to encourage participants to complete their surveys (Dillman, 2007). Two weeks later, a reminder postcard was sent to participants encouraging them to return their completed surveys. Participants were given approximately six weeks to return completed surveys.

8.6.2 Case study results

Descriptive analyses of participants' knowledge of their physical tank set-up showed that most (76%) participants knew the size of their rainwater tanks and the large majority (95%) knew that their tank was connected to a pump. There were two areas where there was less knowledge. First, as shown in Figure 8.5, only 61% of participants knew whether their rainwater tanks were connected to mains water for back-up supply, whereas the remainder (39%) either did not know or were not sure of such a technical aspect of their mandated tanks (Mankad *et al.* 2012c). Second, 44% of participants were not aware of any trickle top-up or automatic switching device installed on their tanks to allow mains water flows if the rainwater is not available, which is a compulsory feature of mandated tanks. The overall absence of knowledge among a high percentage of mandated homeowners indicates that these homeowners might not be maintaining their tanks to the required standard for the tank to be effectively saving mains water.

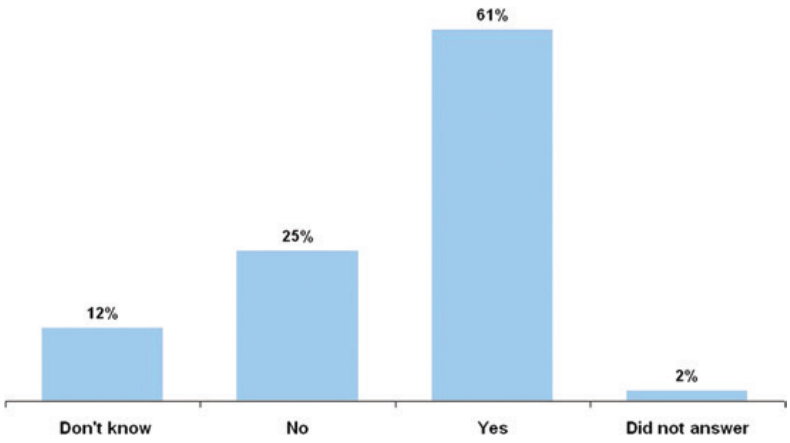


Figure 8.5 Homeowners' knowledge of the existence of mains water top-up in their mandated tanks.

Table 8.2 displays the descriptive statistics for the psychosocial factors (competence, autonomy, relatedness) as well as for frequency of tank maintenance behaviours. The table also shows the results of the multiple regression analysis. The mean score of 2.18 on a 5-point scale for frequency of tank maintenance demonstrates that, on average, homeowners were rarely engaging in tank maintenance behaviours. Mean scores on the perceived competence, autonomy, and relatedness could range from 4 to 20. The means on these variables therefore suggest moderate levels of perceived competence, autonomy, and relatedness in relation to tank maintenance. Multivariate analysis (i.e., multiple regression analysis) was conducted to investigate the extent

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to which the psychosocial factors (competence, autonomy, relatedness) predicted tank maintenance behaviour. Multiple regression analysis allows an examination of the relative contribution of each of the variables in predicting tank maintenance frequency. The beta weights represent the standardised regression weights for each of the predictor variables included in the regression model and the p values indicate the significance of the contribution of each of the predictor variables. As Table 8.2 shows, homeowners' perceptions of their own competence in maintaining their tank had the largest beta weight and it was therefore the most important predictor of regularity in tank maintenance behaviours (Mankad *et al.* 2012c). The positive relationship shows that the more perceived competence homeowners reported, the more tank maintenance they engaged in. When we consider that most mandated participants had limited knowledge of their tank set-up (as noted above), and that participants reported only moderate perceptions of competence with respect to tank maintenance, it is perhaps not surprising that there is also poor frequency of tank maintenance behaviour (Table 8.2). The regression results suggest, however, that if householders perceived competence increased, that this might also increase the frequency of their tank maintenance behaviour. This finding is further supported by self-determination theory, which posits that people will be more motivated when they feel more competent although we also acknowledge that because our data is correlational we cannot establish a causal link between competence and maintenance behaviour in this study. Autonomy was also found to be a significant factor in determining tank maintenance behaviours, however, as the beta weight shows, it is a weaker predictor of tank maintenance behaviour than competence. In this study, autonomy was conceptualised as the government supporting homeowner independence with respect to water supply (e.g., '*the government gives me freedom to make my own decision about my rainwater tank*'). Results showed that higher perceptions of autonomy support were related to a greater regularity in reported maintenance behaviours. That is, participants who perceived the government as supportive in allowing citizens the freedom to make their own decisions about installing a rainwater tank tended to engage more when maintaining their tank. However, results indicate that this form of autonomy is a significant, but weak positive predictor of maintenance behaviour. Relatedness was only very weakly related to frequency of maintenance behaviour.

Table 8.2 Descriptive and regression results for the influence of basic psychological needs.

Predictor	*M*	*SD*	β	*p*
Competence	13.697	4.827	.467	<0.001
Autonomy	12.92	3.20	.110	0.003
Relatedness	13.18	4.14	–.070	0.038
Dependent variable			*F* (3, 750)	*p*
Frequency of maintenance	2.18	1.48	79.999	<0.001

Note: Scores on competence, autonomy and relatedness could range from 4–20 with higher scores indicating higher perceived competence, autonomy and relatedness; scores on frequency of maintenance could range from 1–5 with higher scores indicating more frequent maintenance.

Results also showed that feelings of personal choice with respect to tank adoption were important to homeowners and encouraged *more regular* tank maintenance behaviours. Participants said they were happy to maintain their rainwater tanks themselves (57%), or with assistance from the local council (25%), rather than paying someone to maintain their tanks (Figure 8.6). An overwhelming majority of participants were not in favour of water utilities being responsible for tank maintenance. Therefore, enabling householders by increasing their levels of competence (e.g., applied education about maintenance) could go some way in increasing rates of tank maintenance.

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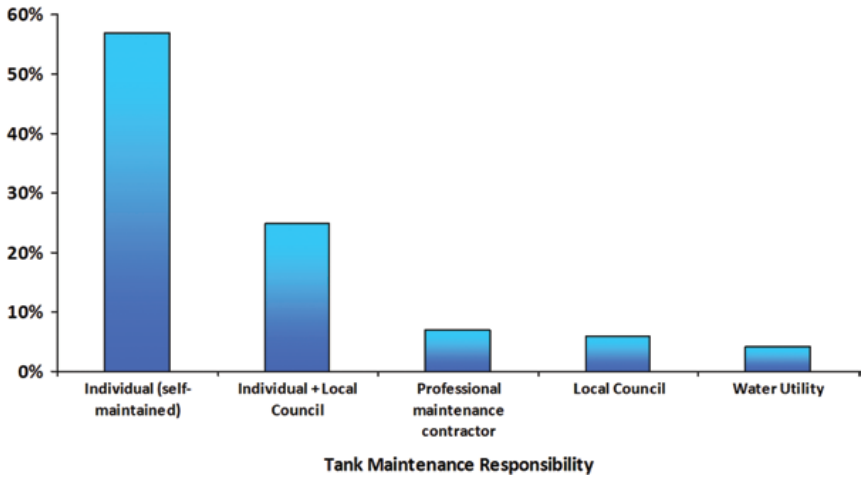


Figure 8.6 Perceptions of tank maintenance responsibility among householders with mandated rainwater tanks (Mankad *et al.* 2012c).

8.6.3 Drivers of rainwater tank maintenance behaviour for retrofitted versus mandated tanks

In this second quantitative case study in SEQ, a survey was conducted to compare tank maintenance behaviour among retrofitted and mandated rainwater tank owners (see Mankad & Greenhill, 2014). Participants were SEQ residents from local government areas (Gold Coast, Logan, Moreton Bay, Redland and Sunshine Coast) who had a rainwater tank installed on their property, either voluntarily (retrofitted) or because of development guidelines (mandated). Participants for the mail out survey were randomly selected from a database of households known to have rainwater tanks. The selection of participants was defined by two criteria:

1. *Households with* retrofitted *rainwater tanks* – these households applied for government rebates to install rainwater tanks at home. They were not required by legislation to have rainwater tanks at home but chose to have them (in conjunction with government rebates).
2. *Households with* mandated *rainwater tanks* – these households applied for new water accounts from 2007 onwards. New legislation was introduced in 2007 mandating that all new residential homes require internally plumbed rainwater tanks. Therefore, any new water accounts opened from 2007 include the mandated rainwater tanks.

The main categories of question included in the survey were (see Mankad & Greenhill, 2014):

- *Self-determined motivation* was measured with the 23-item Motivation toward the Environment Scale (Pelletier *et al.* 1998). Householders responded on a 7-point Likert scale (1 = strongly disagree, 7 = strongly agree) to statements that tapped into each of the type of motivation. Consistent with recommendations, a self-determination index was created.
- *Amotivation* was measured with the Amotivation toward the Environment Scale (Pelletier *et al.* 1999). Participants responded to 16 items that assessed capacity, strategy, effort and helplessness in relation to rainwater tank maintenance on a 7-point Likert scale (1 = strong disagree, 7 = strongly agree). The items were combined into an overall amotivation scale.

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- *Tank maintenance behaviour including*:
  - *Engagement in tank maintenance behaviours* was measured by asking householders whether they engaged in 11 maintenance behaviours (e.g., check and clean first flush devices, check tank mosquito-proof screens and flap valves for rips, holes and defects, check inside of tank for accumulated sediment, check pipes for leaks or damage). Response options included: [3] already undertaken the behaviour, [2] planned on undertaking the behaviour, [1] had not undertaken the behaviour.
  - *Frequency of tank maintenance behaviours* was assessed by asking householders how often they undertook each of the 11 maintenance behaviours. Respondents rated their frequency of behaviour on a scale that ranged from: after it rains (considered the most frequent behaviour and coded as 5), through to every 2 to 3 years (least frequent and coded as 1); householders were assigned 0 for those behaviours they had not engaged in at all.
  - *Adequacy of tank maintenance behaviours* was measured through matching responses to the frequency questions described above with the frequency recommendations of the Australian Government guidelines (DHA, 2004; Queensland Health, 2007). Householders' responses to the frequency questions were recoded so that answers matching recommended frequencies were scored 2, and those not congruent were scored 1.

SEQ residents were randomly selected to participate in this study, from a database of households known to have rainwater tanks. The final sample comprised 570 mandated and 1443 retrofitted householders (*see* Mankad & Greenhill, 2014 for more details on the study's methodology). The study showed that mandated and retrofitted households had an average tank volume of approximately 8,500 Litres (8.5 kL) and, interestingly, only 87.6% mandated householders said their tank was plumbed into their home (compared to 20.9% of retrofitted tanks). Given the development code required all mandated tanks to be internally plumbed, this suggests some lack of knowledge or adherence on the part of householders.

8.6.4 Case study results

Comparisons were made using self-determination theory, specifically, the self-determination continuum presented in Section 8.3 and Figure 8.2 (Grolnick & Ryan, 1987; Deci & Ryan, 2000). Basic descriptive information on participants with mandated and retrofitted tanks and their engagement, frequency and adequacy of rainwater tank maintenance showed that retrofitted tank owners consistently reported higher scores (e.g., a mean score of 23.87 for engagement in tank maintenance) than mandated tanks owners (mean score of 20.31), and the t-tests confirmed that the differences were statistically significant (see Table 8.3).

More complex hierarchical multiple regression analyses were conducted to explore the relationship between motivation and tank maintenance behaviours, where type of tank installation (i.e., mandated vs. retrofitted) was included at the first step of the regression. The expected differences between Retrofit and Mandated householders emerged on motivation, and participants who voluntarily retrofitted their rainwater tank were more likely to engage in maintenance than mandated rainwater tank owners. Specific results showed that:

- Amotivation was the strongest predictor of poor engagement in tank maintenance.
- Amotivation was also a strong predictor of infrequent maintenance behaviours and less adequacy in the frequency of tank maintenance.
- Mandated participants reported higher amotivation and thus had a lower self-determined motivation than retrofitted participants.

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- Retrofitters reported higher intrinsic, self-determined motivation than mandated participants.
- Retrofitters demonstrated a higher sense of tank ownership compared to mandated participants.
- Higher self-determination scores were aligned with greater engagement in tank maintenance, higher frequency of maintenance behaviours and greater adequacy in the frequency of tank maintenance.

Table 8.3 A comparison of mandated and retrofitted rainwater tank owners on the three tank maintenance dependent variables (Mankad & Greenhill, 2014).

Subscales	TYPE	Mean	SD	*t*	df	Sig. (*p*)	Cohen's *d*[a]
Engagement in tank maintenance[b]	Mandated Retrofitted	20.31 23.87	6.95 6.62	–10.632	1986	0.000	0.48
Tank maintenance frequency[c]	Mandated Retrofitted	1.28 1.97	1.16 1.15	–12.061	1986	0.000	0.54
Adequacy of maintenance frequency[d]	Mandated Retrofitted	1.23 1.91	1.39 1.48	– 9.475	1986	0.000	0.43

Note: for simplified explanations of statistical terms used in social psychology (t, df, p, d), please see Pallant, 2007.
[a] Interpretation guidelines proposed by Cohen (1988): .2 = small effect size, .5 = moderate effect size.
[b] Score range 1–33
[c] Score range 0–11
[d] Score range 0–5

Although the differences in motivation between the two groups was found to have a relatively small effect size (Cohen, 1992), the relationship between motivation and maintenance is consistent across the three measures (see Figure 8.7). More in-depth analysis of participants' motivational drivers showed that people who engaged in greater tank maintenance were those who likely identified themselves as 'water savers' or 'environmentally friendly', where engaging in maintenance behaviour was part of the householder's self-concept and was aligned with their other personal values (e.g., sustainability). These individuals were less amotivated in that they had a purpose to their maintenance behaviour; this was also the case for those who engaged in more *frequent* and *adequate* tank maintenance. Results showed that people who engaged in more frequent tank maintenance were also likely to do so because of an inherent pleasure or satisfaction derived from the activity itself. Finally, individuals who engaged in maintenance behaviours that were aligned with frequency recommendations (i.e., *adequacy*) were found to also be motivated by the value they placed on the maintenance behaviour. That is, they may have viewed their rainwater as a valuable resource for recreational gardening and, therefore, placed more value on tank maintenance as it allowed them to reach their goal of a productive garden.

In summary, consistent with self-determination theory, when residents had not chosen to install their rainwater tanks, they felt more amotivated and less intrinsically motivated to maintain their tanks than residents who had voluntarily installed their tank. Not surprisingly, the mandated tank owners also engaged in less tank maintenance than the retrofitted tank owners. A reason for their greater amotivation was perhaps a lack of understanding of what needed to be done and a lack of willingness to put in the effort because they had not necessarily made the choice to install the tanks.

8.7 CONCLUSION

In this chapter we have outlined key social research questions that relate to understanding public acceptance and adoption of domestic rainwater tanks and the predictors of householders' rainwater tank maintenance

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behaviour. There has been very little research addressing these topics and the research that does exist has been conducted within the Australian context. We have outlined methodological approaches and case study examples that can help to develop an evidence base to answer these social research questions. In the remainder of this chapter we summarise the lessons that have been learned from the research conducted to date.

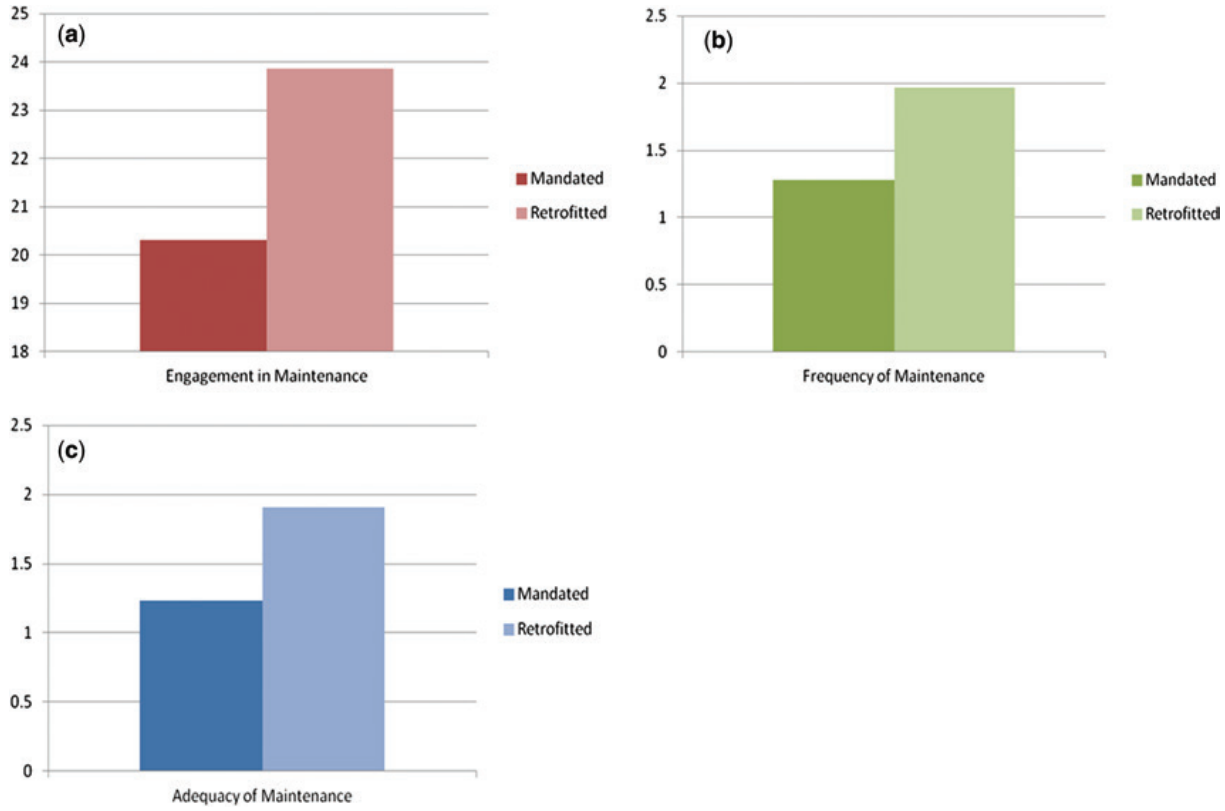


Figure 8.7 A comparison of mandated and retrofitted mean scores on the three maintenance dependent variables: (a) engagement, (b) frequency, and (c) adequacy (Mankad & Greenhill, 2014; Mankad *et al.* 2012a).

8.7.1 How can we influence public acceptance and adoption of rainwater tanks?

The findings to date suggest that the perceived costs, for example, financial costs or the time, effort, knowledge and capability associated with installing rainwater tanks can act as a barrier to installation. While rebate programs can help to overcome the financial burden on households, the bureaucratic process involved in applying for rebates may be a further hurdle that some people cannot get past. This finding suggests the need to streamline rebate programs to ensure the process is as easy as possible. The findings also suggest the importance of providing easy access to step-by-step information that helps householders navigate the installation of a rainwater tank. This has the added benefit of raising householders' self-efficacy in relation to tank installation – a factor that was shown to be an important predictor of householders' intentions to install a tank in the case study research. The space constraints that some householders experience on their property are a real barrier that cannot always be overcome, but the

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aesthetic considerations that were mentioned by some householders in the qualitative interviews can be addressed through a wide range of tank sizes, shapes and colours and also by installation of underground tanks, but at an increased cost. There is also the likelihood that aesthetic responses to tanks may be influenced by the prevailing norms: the more ubiquitous that tanks are, the more likely they will be to seem 'normal' and an integral part of a home.

Knowledge of the water context in the region and the potential for individual householders to be threatened by water scarcity and drought may be an important part of the decision to install a rainwater tank. It makes sense that people need to feel some sense of vulnerability in order to be motivated to take action to protect themselves against this threat. What needs to go hand in hand with this sense of vulnerability, though, is the belief that rainwater tanks can be an effective way to protect against the threat of water scarcity. Hence, the effectiveness of programs that promote the installation of rainwater tanks may be increased if they focus on the benefits of rainwater tanks for householders and the community more broadly. While this conclusion seems straightforward, research has shown that people may value water for different reasons. Past research suggests that people typically retrofit rainwater tanks when they have an interest in water-based activities where a greater supply of 'personal' water is required, such as for gardening, topping up swimming pools, or washing large vehicles (e.g., boats, caravans) (Gardiner, 2009; 2010; Gardiner *et al.* 2008; Mankad *et al.* 2010). Hence, although it makes sense to focus on the benefits of rainwater tanks for protecting the individual, their lifestyle and their property, it is also important to communicate that in times of extreme drought the chief contribution of rainwater tanks could be to reduce the pressure on drinking water supplies and thereby increase water security in urban areas.

8.7.2 How can we encourage more effective maintenance of domestic rainwater tanks?

The research outlined in the case studies in this chapter provides some important preliminary insights into householders' current rainwater tank maintenance behaviours. It appears that householders have relatively low levels of knowledge about their tanks and are not engaging in appropriate maintenance activities. Householders are not supportive of outsourcing tank maintenance to professionals so programs are needed that help people to build the knowledge and skills that allow them to effectively maintain their tanks. Perceived competence emerged as a significant predictor of tank maintenance behaviour: the more competent householders felt, the more likely they were to maintain their tanks. This finding emphasises the importance of providing rainwater tank owners with information that helps them to the build competence in this area. Of course, there is widespread recognition that information alone does not always lead to behaviour change but accompanying the 'how to' information with 'why to' information can provide people with important rationales for engaging in new behaviours (see Osbaldiston & Schott, 2012 for an evaluation of other effective environmental behaviour change strategies). Agencies seeking to change behaviour sometimes try to achieve this end through highlighting that people in the community are not engaging in particular actions (like rainwater tank maintenance). But research suggests that this may have paradoxical effects whereby people take their cues from others and this may lead them to think: 'if no one else is doing it, how important/effective can it be?' Therefore messages that emphasise that other rainwater tank owners think that rainwater tank maintenance is important may be an appropriate norm to communicate to rainwater tank owners.

Another important consideration for agencies seeking to promote rainwater tank adoption and appropriate ongoing maintenance of these systems are the findings in relation to installation of retrofitted versus mandated tank systems. It is clear that where rainwater tanks have been mandated, householders have less sense of ownership of the system, have less knowledge about it, and engage in less maintenance

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of their rainwater tanks than householders who have voluntarily chosen to retrofit them. Householders with mandated tanks appear to feel greater apathy and less intrinsic satisfaction for tank maintenance. These findings raise important issues for government agencies seeking to address water security through rainwater tank adoption. On the one hand, legislation that mandates installation of rainwater tanks could result in much broader uptake of these systems than measures that encourage voluntary uptake. On the other hand, the lack of choice that legislation introduces may undermine householders' willingness to maintain their systems. These findings suggest the need for agencies to pay particular attention to households with mandated tanks and to encourage greater engagement with the tank as well as greater knowledge of its functioning. Strategies that help to overcome the resentment that some may feel about having to maintain a system that they didn't choose to install may be helpful (e.g., by communicating the benefits of the system that could offset the costs).

Future research is needed to develop the evidence base for strategies to promote greater rainwater tank adoption and maintenance. The current research has been conducted in Australia and there is clearly a need to examine whether the findings generalise to other national, legislative, cultural, and environmental contexts. Qualitative research that explores householders' experiences of managing their rainwater tanks could also be beneficial as it may provide a deeper understanding of the barriers that people face in relation to these activities. Finally, qualitative (e.g., focus groups) and quantitative (e.g., field experiments) research that examines the efficacy of different informational and engagement strategies to encourage rainwater tank maintenance would also provide useful data for agencies with oversight of domestic rainwater tanks.

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Chapter 9

Chemical quality of rainwater in rain tanks

Mirela I. Magyar and Anthony R. Ladson

ABSTRACT

The number of rain tanks in urban areas is increasing rapidly and although most tank water is for non-potable use there are a large number of households where tanks supply water for drinking. Comparing tank water with drinking water guidelines shows that high lead concentrations and low pH are common issues. We identified 32 studies where elevated metals concentrations in tank water were of concern with lead being an issue in 31 of these studies. A meta-analysis suggests that, in urban areas in Australia, about 22% of tanks can be expected to provide water with lead concentrations that do not meet drinking water standards. The risk of lead contamination needs to be taken seriously and there are opportunities to improve water quality through treatment, by better maintenance and improved tank design.

Keywords: water quality; rain tanks; heavy metals; lead; water supply.

9.1 INTRODUCTION

This chapter reviews the chemical quality of water captured and stored in rain tanks and supplied to various end uses. Any discussion of water quality involves a comparison; we need to compare the quality of water supplied by a rain tank with that required by its intended use. Water that is acceptable for drinking may not be of sufficient quality for say, electronic fabrication processes, whilst water that doesn't meet drinking water standards may be fine for garden irrigation.

Water captured in rain tanks will be appropriate for many uses. Problems can arise when the quality of water supplied by a tank is lower than required for its intended use. There is now sufficient information to indicate when problems with the quality of tank water are likely and where intervention is appropriate. We will highlight key issues in this chapter.

Generally, our focus is on domestic tanks in urban areas. This is justified for two reasons. First, pollutants in dust and in the air in urban areas may compromise water quality. Second, use of rainwater tanks in many urban areas is increasing rapidly. For example, in Brisbane, for dwellings less than 1 year old, the proportion with a rain tank increased from 27% in 2007 to 57% in 2010 (White, 2014). The rapid

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expansion of rainwater tanks in cities is new and there are some important water quality issues which, we will show, are not being taken seriously enough.

9.1.1 The uses of tank water

What can tank water be used for in an urban domestic setting? Wong (2006) discusses the concept of fit-for-purpose water supply for domestic water uses. He suggests that tank water is preferred or compatible with all domestic uses although drinking mains water is recommended if it is available (Table 9.1). The potential compatibility of rainwater with many domestic demands is consistent with the use of rainwater tanks to augment mains water supply (see Chapters 2 and 3 of this book).

Table 9.1 Suggested domestic uses for tank water from Wong, 2006.

	Preferred use	Compatible use	Notes
Garden		✓	Lower quality sources are preferred
Kitchen – cold water		✓	Treatment may be required to improve microbial quality
Kitchen- hot water	✓		
Laundry	✓		
Toilet		✓	
Bathroom – cold water		✓	Treatment may be required to improve microbial quality
Bathroom – hot water	✓		

A significant difference between water supplied from a tank compared to that from the mains is the lack of centralised control. In developed countries there is substantial background effort to keep mains water to a consistent high standard. Infrastructure is maintained, water is treated, quality is monitored and people are warned if the standard drops. There is an organised response to extreme events including boil-water advisories if there is a risk to health (Fitzgerald *et al.* 2014).

The use of rain tanks means that ownership, operation, and maintenance of part of the water supply infrastructure is transferred from urban water authorities to property owners and occupants. Therefore, tank maintenance, and more importantly, the quality of water supplied from the tanks is the householders' responsibility. The lack of monitoring and control and the limited expertise of householders suggest we should be conservative when selecting uses for tank water. It is likely this happens in practice. We know that in urban areas the majority of rain tanks supply water for non-potable uses, such as for garden watering because, in capital cities, 67% of tanks are not plumbed into dwellings (ABS, 2013). Guidelines recommend against the consumption of tank water if there is an alternative potable supply available (Coombes & Mitchell, 2006; DHS, 2007).

There would be little interest in the quality of tank water if it all just ended up on gardens. Significantly in a large number of houses (but small overall percentage), tank water is supplied for uses involving human contact and occasional ingestion. Rain water supplied to hot water systems has the potential to be used for cooking (Chapman *et al.* 2006) and there are also many cases in urban areas where people drink rain tank water even when mains water supply is available. Table 9.2 shows that around 127,000 households in Australian capital cities use tank water for drinking.

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Table 9.2 Number of households in capital cities where rain tanks are the main source of water for drinking (ABS, 2010).

Capital City[1] (State)	Number of households using rainwater tanks for drinking	Households (%)
Sydney (NSW)	23,600*	1.4*
Melbourne (VIC)	17,300*	1.2*
Brisbane (QLD)	29,500*	4.0*
Adelaide (SA)	33,400	7.0
Perth (WA)	17,900*	2.7*
Hobart (TAS)	5300*	6.3*
Total	**127,100**	**2.5**

[1]Estimates for Darwin and Canberra were not available; *estimate has a relative standard error of 25% to 50% and should be used with caution (ABS, 2010)

9.1.2 Water quality guidelines

There are no specific recommendations for water quality from rainwater tanks, but as a substantial number of tanks are used to provide water for drinking, it is appropriate to compare tank water quality with drinking water guidelines. In this chapter we mainly use the Australian Drinking Water Guidelines (ADWG) as a reference (NHMRC & NRMMC, 2014). There are also water quality recommendations for recreational water use and the use of water for agriculture (ANZECC & ARMCANZ, 2000). A selection of guideline values are provided in Table 9.3, mainly focussing on metals which are the chemical water quality constituents of most concern in tank water (as we discuss below). Lead is one chemical water quality parameter of particular interest because of the risk to health from lead exposure. Lead is also a common contaminant of tank water, as we will show in this chapter.

Table 9.3 Recommended concentration values (units of µg/L) for metals in water for different human exposures and end uses.

Guidelines	Cd	Cr[1]	Cu	Fe	Mn	Ni	Pb	Zn
Australian Drinking Water Guideline (ADWG) **health** concentration upper limits (NHMRC & NRMMC, 2014)	2	50	2000	–	500	20	10	–
ADWG **aesthetic** concentrations upper limits (NHMRC & NRMMC, 2014)	–	–	1000	300	100	–	–	3000
Agricultural **irrigation** long-term trigger value (ANZECC & ARMCANZ, 2000)	10	100	200	200	200	200	2000	2000
Recreation guideline maximum value for primary contact (ANZECC & ARMCANZ, 2000)	5	50	–	–	–	100	50	

[1]Guidelines are for hexavalent chromium. If total chromium exceeds 0.05 mg/L in drinking water a separate analysis for hexavalent chromium is required.

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The potential adverse health effects of lead contamination of drinking water are both serious, and well known. A maximum lead concentration of 10 µg/L is specified in the ADWG and in guidelines published by the World Health Organisation (WHO, 2008). Exposure to high concentrations of lead in drinking water has been associated with spontaneous abortion, still birth and high rates of infant mortality (Edwards, 2014). Lead exposure also has implications for children's intellectual functioning (Lanphear *et al.* 2005) and premature adult mortality (Nawrot & Staessen, 2006). Lead can also cause harmful effects on the gastrointestinal tract, joints, reproductive system, kidneys and haemoglobin synthesis (Goyer, 1993) and may increase risk of hip fractures (Dahl *et al.* 2013). Lead is a cumulative toxin with long term chronic effects from the accumulation of lead in the human skeleton, as well as short term acute effects from episodic high doses (Shih *et al.* 2007). Drinking lead contaminated tank water has been linked to elevated blood lead levels (Body, 1986; Maynard *et al.* 2003). Substantial adverse health effects have been reported for lead concentrations in drinking water of 40 to 80 µg/L (Edwards, 2014).

Another important water quality guideline is pH. The ADWG state that the pH should be between 6.5 and 8.5 to minimise the risk of corrosion and encrustation of pipes and fittings. The degree of saturation of calcium carbonate in water, the Langelier Index, can also be a useful indicator of the risks of corrosion or the formation of scale. Low pH can increase the concentration of metals dissolved in tank water.

9.2 WATER QUALITY FROM RAINFALL TO ROOF TO TANK

The quality of water provided by a rain tank depends on the quality of water that enters the tank, the processes within the tank, and any contamination as water passes to a supply point. In this section we review rainwater quality, the influence of roof materials, and ways to improve quality of tank inflows.

9.2.1 Rainwater and atmospheric influences on inflow quality

The quality of water entering a tank is influenced by the quality of rain and the runoff from the roof. In the literature, distinctions are made between the following processes.

- Wet deposition is the material carried in by rain. Its composition depends on anthropogenic, marine or natural sources.
- Dry deposition refers to particulate contaminants in the air that settle on the roof surface between rain events. Dry deposition is influenced by the sources of pollution and their proximity, the number of days between rain events, and the aspect of the roof (Huston *et al.* 2009). Generally, the longer the time between rain events, the greater the deposition and the higher the contaminant loads that will be washed into tanks.
- Bulk deposition is the term used when both dry and wet deposition concentrations are combined.

Another important process is the chemical interaction of rainwater with roof materials which may enhance the concentration of constituents such as metals. We discuss this in the next section.

Before providing a statistical overview of the roof runoff quality, we first mention some specific results from two studies which aimed to relate contamination of stored rainwater to atmospheric sources. In a study in Sydney, Australia (average annual rainfall 1200 mm), wet deposition was found to have high concentrations of some metals (Kus *et al.* 2010a; Kus *et al.* 2010b). In particular, lead exceeded 10 µg/L which is the limiting value for the Australia Drinking Water Guideline (Table 9.3). The source of these high lead values, as suggested by earlier work in Sydney (Birch & Taylor, 1999; Birch & Scollen, 2003) is from the dust near roads with heavy traffic. Copper and Manganese were also detected in rainfall but at concentrations below drinking water guidelines.

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In Brisbane, Australia (average annual rainfall 1000 mm/year), bulk deposition (dry + wet) was investigated on a monthly basis between April 2007 and March 2008 at 16 sites (Huston *et al.* 2009). The samples were analysed for 30 metals and 155 organic compounds. The main water quality concerns related to the concentrations of lead and cadmium which exceeded the ADWG recommended values in 10.3% and 1.7% of samples respectively.

Daily flux values for metals in Brisbane were also measured by Huston *et al.* (2009); a selection of average flux values is shown in Table 9.4. These are comparable to fluxes in other cities (Venice, Paris, Los Angeles) but lower than Taiwan and Tokyo. For the Brisbane data there were substantial differences between monitoring sites depending on land use. Fluxes (μg/m^2/d) increased from outer suburban to inner suburban to city/heavy traffic/light industrial. The main water quality concern in the Brisbane data relates to lead.

Table 9.4 Concentrations of metals in wet and bulk deposition in Sydney (Kus *et al.* 2010b) and Brisbane (Huston *et al.* 2009).

Metal	Sydney (Wet deposition) (μg/L)	Brisbane (Bulk deposition) Mean annual concentration (μg/L)	Brisbane (Average daily fluxes) (μg/m^2/d)
Al	108	–	–
Cd	–	0.1	0.32
Cr	–	0.7	1.8
Cu	6	2	5.5
Fe	72	–	–
Mn	17	–	–
Ni	–	0.4	–
Pb	17	2.1	5.9
Zn	77	16.4	45.5

We can put these lead fluxes into perspective as follows. Consider a tank of rainwater which is contaminated with lead at a concentration that just exceeds the ADWG value of 10 μg/L. For a 5 kL tank, a typical size for an urban allotment, this means the tank water contains 0.05 g of lead. The average daily lead flux in Brisbane is 5.9 μg/m^2/d so 100 m^2 of connected roof area could supply about 0.2 g of lead per year to the tank. This is 4 times that required to contaminate the water.

9.2.2 The effect of roof material on the quality of tank inflows

Along with atmospheric wet and dry deposition, metals can be supplied from roof materials which are commonly a source of zinc, lead and copper. Zinc is a widely used roofing metal, with galvanised steel roofs common in Australia. Over time, particularly in coastal environments, solid zinc is converted to soluble zinc chloride and will be washed off the roof and into a rain tank. Chang *et al.* (2004) also found high zinc concentrations from timber shingle roofs which they attributed to chemical treatments for fungi protection.

Lead flashing has also been widely used for weather proofing joints on roofs, although this is less common in new developments. Guidelines such as AS/NZS 3500.3 (Standards Australia, 2003), Building Code of Australia (ABCB, 2012) and manufacturers' web sites advise that lead flashing is not recommended, and should be avoided especially on any roof that is part of a potable water catchment area (ABCB, 2012). Nonetheless there is lead flashing on many existing roofs in Australia.

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Where researchers have sampled water on both roofs and in gutters, they have found that roof materials contribute metals loads to tanks (Yaziz *et al.* 1989; Forster, 1996; Zobrist *et al.* 2000; Gromaire *et al.* 2001; Polkowska *et al.* 2002; Chang *et al.* 2004; Huston *et al.* 2012). Roof type has a significant influence on runoff quality. There are the obvious links between galvanised roofs and zinc, lead flashing and lead concentrations, and copper flashing and copper concentrations. There are also less obvious associations. Timber roofs may contribute zinc, asphalt roofs are a source of lead, and gravel roofs can retain and release metals (Zobrist *et al.* 2000; Van Metre & Mahler, 2003; Chang *et al.* 2004).

9.2.3 A statistical overview of roof runoff quality

The runoff quality to any individual tank will be influenced by a larger number of factors. Examining individual roofs and roof runoff provides useful information on sources of contaminants and processes of contamination. However it is difficult to generalise these results to the large number of rain tanks that are used in urban areas. A statistical description of roof runoff quality can provide a broader view and flag likely water quality issues.

A number of reviews of roof runoff quality area available (Meera & Ahammed, 2006; Lye, 2009; Abbasi & Abbasi, 2011), but here we focus on the work by Duncan (1999, 2006) which summarised the results from a large number of studies providing information on mean concentration values and variability for a range of water quality constituents. Where literature data was sufficient, Duncan (1999, 2006) also related roof runoff quality to broad classes of land use for example, urban and rural. Information assembled by Duncan is the basis of pollutant generation in the widely used stormwater management model MUSIC (eWater, 2009).

Roof runoff concentrations (mean and ±1 standard deviation) for lead and cadmium are shown in Figure 9.1 along with allowable concentrations from the Australian Drinking Water Guidelines. Pollutant concentrations are considered on a log scale because they approximate a log normal distribution (Duncan, 1999, 2006).

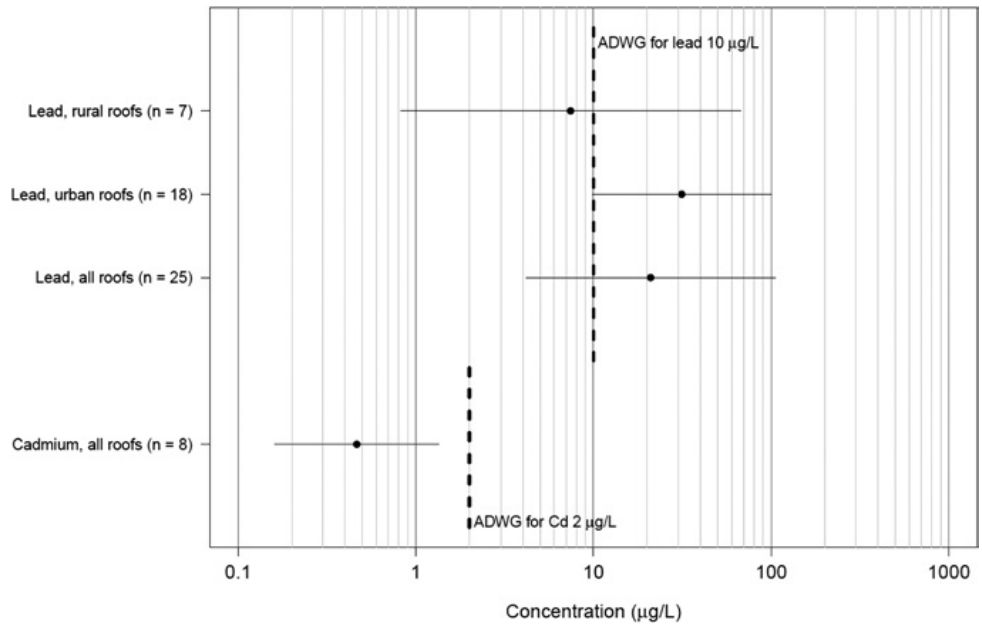


Figure 9.1 Concentration of lead and cadmium in roof runoff compared to the Australian drinking water guidelines. Data show mean concentrations ±1 standard deviation. The number of studies is shown in brackets (Duncan, 1999, 2006).

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These data suggest that the lead concentration of roof runoff is likely to be high, with the potential to contribute to poor water quality in a rain tank. The mean lead concentration for runoff from urban roofs, is greater than the drinking guideline values. Even runoff from rural roofs can supply water with high lead concentrations. In contrast, the mean concentration of cadmium in roof runoff is substantially less than the recommended drinking water concentration. Hence it is much less likely for tank inflows to exceed guidelines for cadmium than for lead.

The pH of roof runoff has also been measured in a number of studies (Figure 9.2). Roof runoff is usually acidic and generally has a pH well below drinking water guidelines although there are exceptions. For example naturally occurring limestone dust may moderate pH (Al-Khashman, 2009). There can also be temporary periods of high pH following extreme weather (Vialle *et al*. 2011)

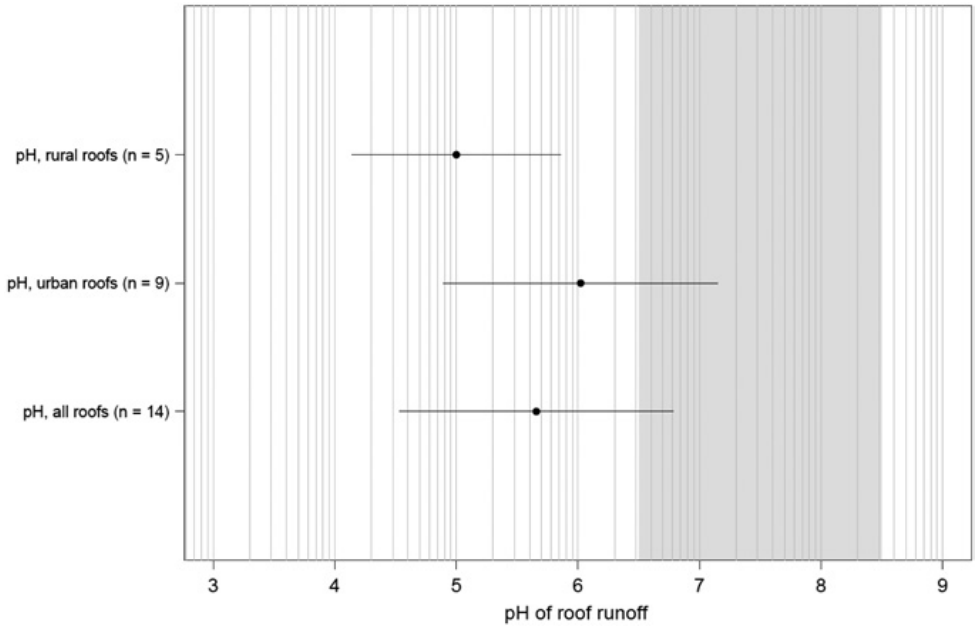


Figure 9.2 pH of roof runoff. Data show mean values ±1 standard deviation. The shaded area corresponds to drinking water guidelines for pH. The number of studies is shown in brackets (Duncan, 1999, 2006).

The data from Duncan (1999, 2006) can also be given a probabilistic interpretation. Probability densities for lead concentrations for three roof types are shown in Figure 9.3. These are based on the mean and standard deviation of lead concentrations in rainwater as documented by Duncan (1999, 2006). The substantial likelihood of roof runoff exceeding drinking water guideline is shown with a large proportion of the probability mass to the right of the ADWG value. It is also possible to quantify the probability that roof runoff concentration will exceed guidelines using standard probability theory (Walpole & Myers, 1978). For example, based on data provided by Duncan (1999, 2006) the probability that the lead concentration in runoff from an urban roof will exceed 10 µg/L is 84%.

Similar probability calculations were undertaken for a range of other water quality constituents using data compiled by Duncan (1999, 2006). Those chemical constituents where roof runoff is least likely to meet drinking water guidelines can be flagged as requiring further consideration (Figure 9.4). These results show that roof runoff in both rural and urban areas is likely to fail to meet drinking water guidelines because of low values of pH and high concentrations of lead.

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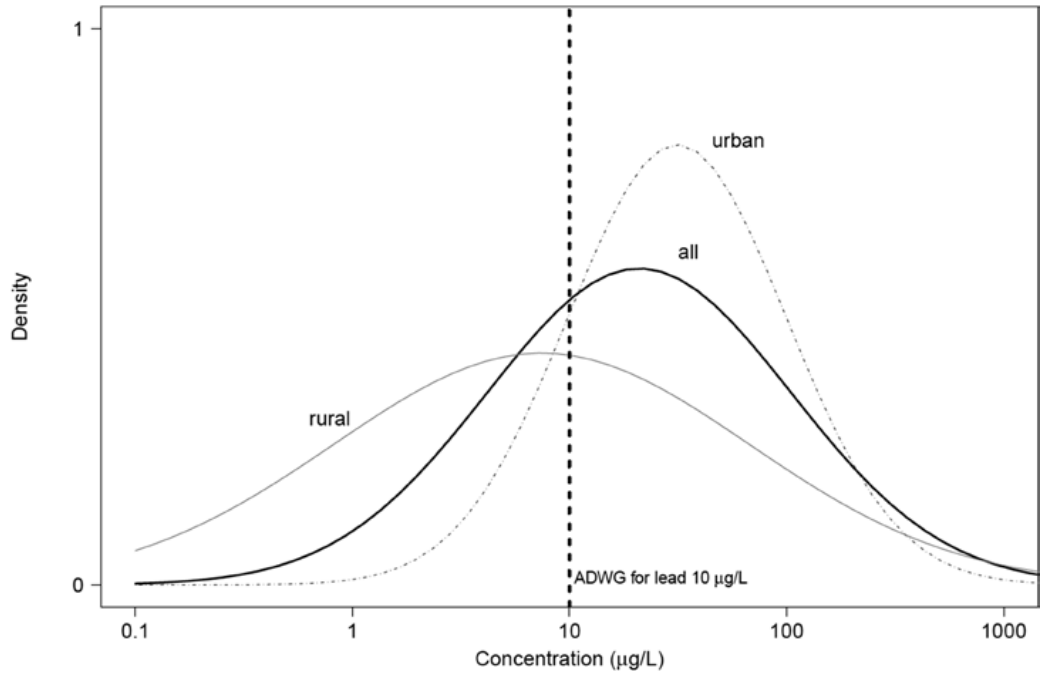


Figure 9.3 Probability density of lead concentration in roof runoff from roofs in urban and rural areas (and combined data) (Duncan, 1999, 2006).

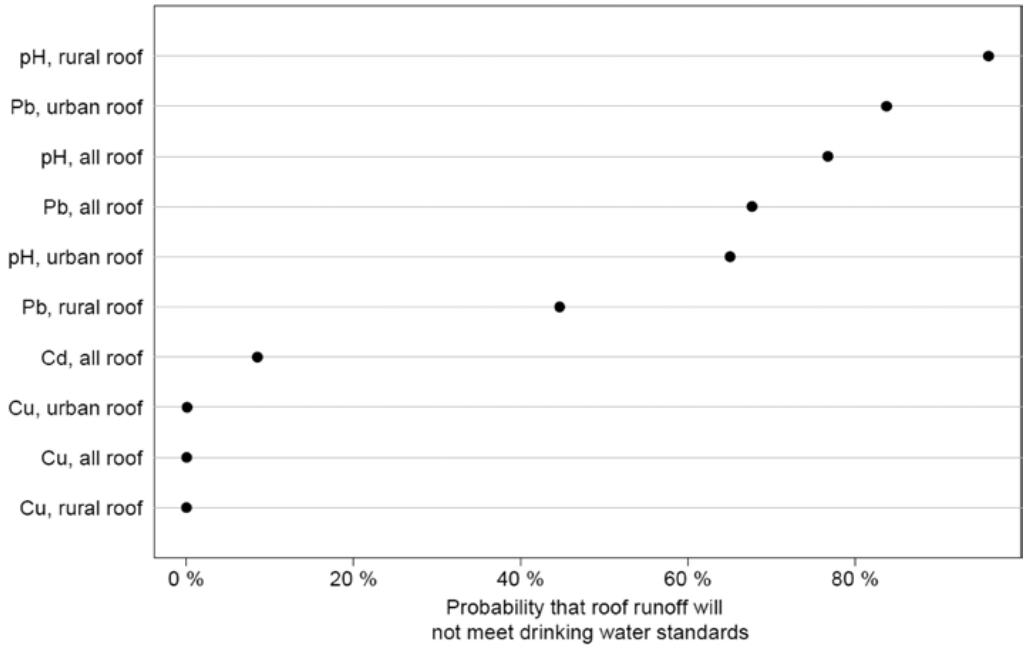


Figure 9.4 Probability that roof runoff will not meet drinking water standards for a range of water quality constituents in runoff from roofs in urban and rural areas (and combined data). Lead and pH stand out as the major issues (analysis based on Duncan, 1999, 2006).

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9.2.4 Improving tank inflow quality

We have suggested three sources of contamination for inflows to tanks, pollutants in rain, dry deposition, and interaction with roof materials. From the point of view of a householder, there is little that can be done about the quality of rain or dry deposition. Several studies suggest that lead flashing on roofs can be a source of lead in tank water, so painting or removal of lead flashing may improve water quality (Huston *et al.* 2012; Magyar *et al.* 2014). The Building Code of Australia (Volume 2, Clause 3.5.1) (ABCB, 2012) states that lead flashing should not be used on any roof that is part of a potable water catchment.

There are several strategies that can be undertaken to reduce wash off of materials that deposit on the roof. Gutters can be cleaned to reduce the amount of material entering the tank. Installation of leaf guards may also be advantageous as lead dissolution is increased in the presence of leaf litter (Body, 1986). The other common strategy is to install a first flush device to catch and discard the first proportion of roof runoff which usually has the highest concentration of contaminants (Bach *et al.* 2010; Kus *et al.* 2010a).

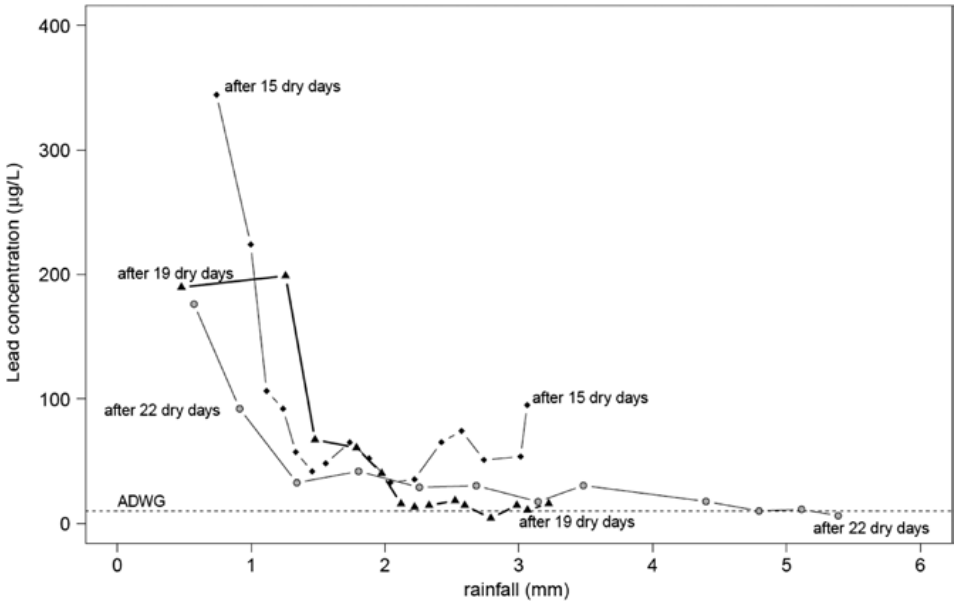


Figure 9.5 Lead concentrations in roof runoff for three events following dry periods. The high initial concentrations were attributed to a first flush effect (Kus *et al.* 2010a). There was no lead flashing on this roof.

First flush devices aim to reduce the loads from material washed off in the early part of a rain storm. They will be most effective in situations where dry deposition contributes a relatively high proportion of contaminants. This could include circumstances where there are long dry periods between intense rain events, or where the air-shed above the roof contributes contaminants that settle on a roof. Monitoring by Kus *et al.* (2010a) in Sydney showed a first flush effect for suspended solids, turbidity, lead and other constituents. The results for lead are shown in Figure 9.5 for three events following extended dry periods. For the first millimetre or two of rain, the concentration of lead in roof runoff was 10 to 30 times the concentration in rainfall. After 5 mm, the concentration had decreased to a similar value to that in rain which was about the drinking water guideline value of 10 µg/L. Most domestic first flush devices only discard about 20 L because they are limited by the storage in the first flush device; commonly a 2–3 m length of 100 mm pipe. For a connected roof area of 100 m^2, this is equivalent to only 0.2 mm. Gardner *et al.* (2004) showed that

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discarding the first 1 mm of roof runoff had very little effect on the event mean concentration of lead and other contaminants. Where a first flush device discards a significant amount of runoff they will substantially reduce the proportion of rainfall harvested by a rainwater tank (Gardner *et al*. 2004).

The proportion of houses that use first flush devices was measured in a number of studies and is highly variable, ranging from 3% to 40% with highly inconsistent results even in the same city (Table 9.5)

Table 9.5 Number of tanks with first flush devices as reported by various studies.

City	No. Tanks with a First Flush device (%)	Reference
Adelaide	7 (36.8%)	Rodrigo *et al.* (2012)
Adelaide	(8%)	Heyworth *et al.* (2006)[1]
Adelaide	100 (30.8%)	Rodrigo *et al.* (2010)
Brisbane	12 (39%)	Huston *et al.* (2012)
Melbourne	2 (3%)	Magyar (2010)
Northeast Victoria	9 (18%)	Spinks *et al.* (2006)
Sydney	40 (40%)	Ferguson (2011)
Tamborine Mountain	14 (5%)	Mark Rigby and Assoc. (2002)

[1]The number of tanks in the study by Heyworth et al. (2006) is not recorded but is likely to be at least 500.

9.2.5 The rain tank as a water treatment device

The above discussion suggests it will be common for water with low pH and high lead concentration to enter a rain tank. Ideally, processes in the tank, such as settling of sediment, should mean that the water supplied to users is cleaner than the inflows into the tank. However commercial tank design is not focussed on achieving the delivery of the cleanest water.

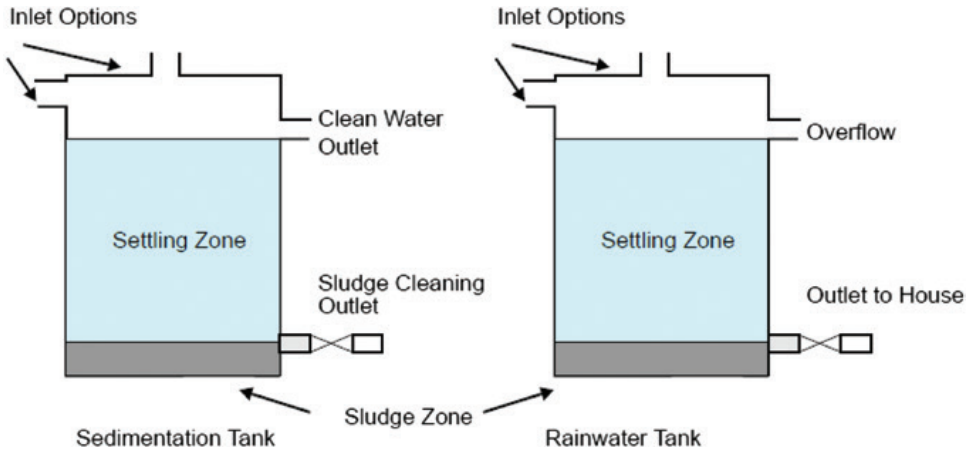


Figure 9.6 Comparison of a sedimentation tank and a rainwater tank. Adapted from Kiely (1997) and Magyar (2010).

Generally, water from a tank is supplied through an outlet situated close to the bottom of the tank, usually between 50 mm to 200 mm above the base (Figure 9.6). The overflow of the tank is situated at the top of the tank, just below the inlet and is connected to the urban stormwater system Magyar (2010). This

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arrangement of inlet/outlet/overflow maximises the volume of water stored in the tank. Unfortunately it also means that solid pollutants that settle at the bottom of the tank are potentially re-entrained and hence are exported in the supplied water, unless they are removed. The highest quality water in a rain tank is in the layer close to the tank surface and it will be lost via the overflow when the tank spills.

The performance of a rain tank can be contrasted with that of a sedimentation tank used for water treatment. In a sedimentation tank, high quality water is delivered via overflow of surface water while contaminants settle on the base and are periodically removed. There have been suggestions that delivered tank water could be improved in quality by, for example, using a floating inlet. Whilst these are commercially available, they are not widely used. There are also a range of other potential design improvements such as the position of the entry compared to the outlet and the shape of the tank base (Magyar *et al.* 2011a).

Another factor that militates against the delivery of high quality water from tanks is the pH of the tank water. Water that enters a tank will likely have low pH, and except for concrete tanks, there are no processes that will result in the pH increasing to the desired range. pH below 6.5 can lead to metals being present in dissolved form in tank water and may contribute to corrosion of plumbing.

9.3 MEASUREMENTS OF RAIN TANK WATER QUALITY

9.3.1 Introduction

The discussion so far has highlighted possible water quality issues for rain tanks. It is clear that inflows are likely to have lead concentrations that exceed drinking water guidelines and low pH. Sediments will settle in the tank but these will be vulnerable to disturbance and re-entrainment in the extracted water. Sampling of tank water can test the extent of these problems. In this section we systematically review the literature on tank water quality and key processes within tanks.

9.3.2 Studies of tank water quality: A summary

There have been many studies of tank water quality including: assessment of water delivered from a tank tap; from hot and cold water taps inside a house which are supplied from a tank; and sampling of the bulk water within the tank. In terms of chemical water quality, most studies test for metals. Far fewer studies consider organic contaminants although some results are available (Bannister *et al.* 1997; Spinks *et al.* 2006; Huston, 2009; Huston *et al.* 2009).

Lead has been found to exceed drinking water standards in many tanks. Our literature review identified 32 studies where chemical water quality issues associated with tank water were mentioned. In all but one, lead was key concern (Table 9.6). Across the range of studies, cadmium concentrations exceeding drinking water standards was the second most common chemical contaminant, followed by a much smaller number of papers that reported issues with metals such as arsenic and nickel. High zinc concentrations were also common, but as there is no health related guideline for zinc concentration we will not consider this further. In some studies metal contamination can be linked to a specific source. For example in Brisbane, most occurrences of high cadmium concentrations in tank water were linked to emissions from a glass factory, which is the largest emitter of cadmium to the atmosphere in Brisbane (56 kg during 2003–2004) (Chapman *et al.* 2008). In contrast, lead contamination of tanks in Melbourne could not be linked to an individual source (O'Conner *et al.* 2009).

Where water has been tested for organic pollutants, they have not been found to be a health issue. Huston (2009) tested water in 26 tanks in Brisbane for 122 pesticides, 19 polycyclic aromatic hydrocarbons and 16 phenolic compounds, and found that there were no concentrations that would present a chronic or acute health hazard. Similarly Spinks *et al.* (2006) undertook a study of water quality in 49 tanks

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following a large bushfire in north east Victoria, Australia. This study was motived by concerns about contamination of tank water by polycyclic aromatic hydrocarbons (PAHs) from incomplete combustion of organic matter, and arsenic from burnt, copper chrome arsenate (CCA) treated wood. However these compounds were found not to be a significant issue. Rather, the main concerns related to cadmium which was found at levels above ADWG in tanks at two properties. In both cases, the roofs were galvanised iron over 50 years old and Spinks *et al.* (2006) suggest the corrosion of the roof was the likely source.

Table 9.6 Studies of tank water quality where metals have been identified as a water quality issue.

No	Study	City/region	No. tanks in study	Metals exceeding health drinking water standards in some tanks[1]
1	Fuller (1981)	South Australia	80	Pb
2	MWAWA (1983)	Perth	92	Pb
3	Sharpe and Young (1984), Young and Sharpe (1984)	Ohio	30–40	Pb, Cd
4	Gumbs and Dierbert (1984)	Antilles	46	Pb
5	Body (1986)[2]	Port Pirie	31	Pb
6	Haebler and Waller (1987)	Caribbean	11	Pb
7	Olem and Berthouex (1989)	Kentucky-Tennessee	25	Pb
8	Duncan and Wight (1991)	Melbourne	25	Pb, Cd
9	Bannister *et al.* (1997)	Victoria	21	Pb
10	Simmons *et al.* (2001)	Auckland	125	Pb
11	Zhu *et al.* (2004)	Northern China	12	Pb
12	Spinks *et al.* (2005)	Urban areas, East Coast Australia	6	Pb
13	Handia (2005)	Zambia	5	Pb
14	Spinks *et al.* (2006)	NE Victoria, Australia	49	Cd
15	Hart and White (2006)	Alaska	50	Pb, Cu
16	Martin *et al.* (2007)	Newcastle	1	Pb
17	Morrow *et al.* (2007)[3]	NSW, Qld, Vic, SA	40	Pb, Ar, Ni
18	Chapman *et al.* (2006, 2008)	Brisbane	30	Pb, Cd
19	Chapman *et al.* (2008)[4]	Australia	69	Pb
20	Magyar *et al.* (2008)	Melbourne	64	Pb, Cd
21	Peters *et al.* (2008)	Bermuda	112	Pb, Se
22	Huston *et al.* (2009)	Brisbane	26	Pb
23	Radaideh *et al.* (2009)	Jordan	92	Pb, Cr
24	Morrow *et al.* (2010)	East Coast, Australia	10	Pb
24	Kus *et al.* (2010b)	Sydney	11	Pb
25	Daoud *et al.* (2011)	Palestine	44	Pb

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Table 9.6 Studies of tank water quality where metals have been identified as a water quality issue (Continued).

No	Study	City/region	No. tanks in study	Metals exceeding health drinking water standards in some tanks[1]
26	Huston *et al.* (2012)	Brisbane	31	Pb
27	Rodrigo *et al.* (2012)	Adelaide	19	Pb
28	Morrow and Dunstan (2012)	Brisbane, Sydney, Melbourne	30	Pb
29	Stump *et al.* (2012)	Texas	36	Pb
30	van der Sterren *et al.* (2013)	Sydney	5	Pb
31	Magyar *et al.* (2014)	Melbourne	6	Pb
32	Malassa *et al.* (2014)	Hebron, Palestine	44	Pb, Cr, Mn, Ni, Ag

[1]Although many studies report high concentrations of zinc, there is no health-based guideline value for zinc in the Australian Drinking Water Guidelines so zinc concentration is not considered in this chapter. The aesthetic (taste) guideline value is a maximum of 3000 µg/L.
[2]The study by Body (1986) was specifically focussed on tanks with high lead concentrations in Port Pirie, SA, a town with a lead smelter.
[3]High arsenic concentrations were recorded in a single sample.
[4]Combined results from Adelaide (6 tanks), Brisbane (6), Broken Hill (6), Canberra (5), Sydney (6), Wollongong (6).

Although we found 31 studies that identified lead concentration as a concern, it should also be pointed out that not all studies of tank water found concentrations of lead that exceeded drinking water guidelines. In particular, work undertaken by Coombes in Newcastle, Australia did not find high lead concentrations in tank water (Coombes *et al.* 2000a, 2000b, 2002, 2005, 2006). There are also studies in Tamborine Mountain Queensland (Mark Rigby & Associates, 2002) and Kefalonia Island, Greece (Sazakli *et al.* 2007) where lead levels were not elevated. Huston (2009) speculates that there may be particular characteristics of these studies that explain these results. For example, the study by Sazakli *et al.* (2007) sampled large (>300 kL) concrete tanks and samples were drawn from the middle of the water column. Concrete tanks generally have high pH water so are less likely to have metals in dissolved form. The pH of rainfall in the study by Sazakli *et al.* (2007) is also unusually high which is possibly related to $CaCO_3$ dust from the limestone geology of the island (*sensu* Conlan & Longhurst, 1993; Al-Kashman, 2009). In addition, there is limited industrial land use near the tanks. The studies by Coombes *et al.* (2000a, 2000b, 2002) included tanks that had mains water top up so any contaminants in tank water would have been diluted. The Coombes *et al.* (2002) study was of a concrete tank. At Figtree place, central Newcastle, Coombes *et al.* (2000a, 2000b, 2005) found that rainwater exceeded drinking water standards for lead but tank water did not; suggesting it was processes within the tank that resulted in cleaner water for example, settling of particles (Spinks *et al.* 2003b). Sludge in these tanks was found to contain high concentrations of lead (Spinks *et al.* 2005). In the Tamborine Mountain study, 79% of tanks were concrete and 28% contained a mixture of rainwater and other water – imported and bore water (Mark Rigby & Associates, 2002).

9.3.3 Meta-analysis: Proportion of tanks with high lead concentrations

A systematic review of the literature in Table 9.6 was undertaken to estimate the proportion of rain tanks that supply water with lead levels greater than drinking water guidelines. Our focus is on Australian

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capital cities so we choose recent Australian studies that included a random sample of tanks. Only recent studies are relevant as there have been interventions to reduce the amount of lead in the environment over time. For example, lead-free petrol was introduced into Australia in the 1980s, and mandated in 2002; lead concentration in paint has been decreased from up to 50% before 1950, to a maximum of 0.1% from 1997 (enHealth, 2004). The selected studies are summarised in Table 9.7. The proportion of tanks with lead concentrations exceeding drinking water guidelines ranged from 9% to 45% (Figure 9.7).

Table 9.7 Selected studies that estimate the proportion of tanks that exceed drinking water guidelines for lead.

Study	City	No. tanks in study	No. tanks exceeding drinking water guidelines for lead (percentage)	95% confidence limits on percentage of tanks exceeding drinking water guidelines
Chapman *et al.* 2008	Brisbane	30	9 (30%)	14.7%–49.4%
Chapman *et al.* 2008	National	69	6 (9%)	3.3%–18%
Magyar *et al.* 2008	Melbourne	49	16 (33%)	19.9%–47.5%
Huston *et al.* 2009	Brisbane	38	5 (14%)	4.4%–28.1%
Kus *et al.* 2010b	Sydney	11	5 (45%)	16.7%–76.6%
Rodrigo *et al.* 2012	Adelaide	19	3 (16%)	3.4%–39.6%
Average (meta-analysis)			**21.8%**	**12.8%–34.7%**

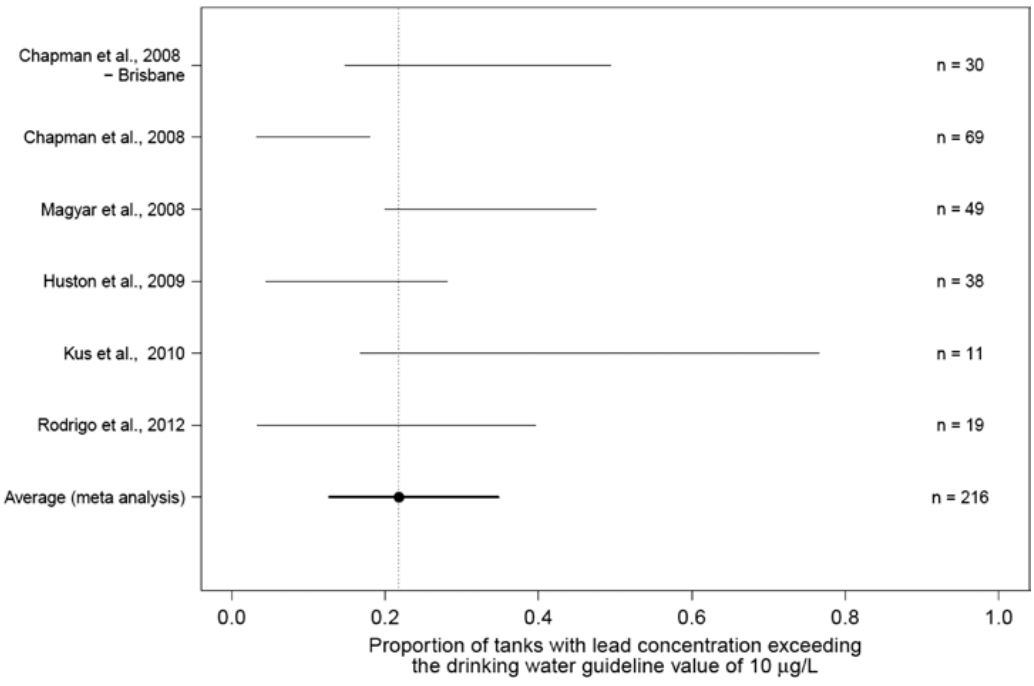


Figure 9.7 Proportion of tanks from recent studies in Australian capital cities where lead concentration exceeded drinking water guidelines.

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We used meta-analysis to estimate the average proportion of tanks with high lead concentration. Our analysis followed the recommendations of Trinquart and Touze (2009) and used the meta package in R (Schwarzer, 2014; R Core Team, 2014). Using a random effects model, the average proportion of tanks predicted to exceed drinking water guidelines for lead is 21.8%, with the 95% confidence limits of 12.8% to 34.7%.

As shown in Table 9.2, it is estimated that 127,000 households in Australian capital cities drink tank water. We can now estimate that 21.8% of these tanks will supply water with lead concentrations greater than drinking water guidelines. This is a total of 27,700 tanks (95% CI 16,300–44,000 tanks).

9.3.4 pH of tank water and relationship with lead concentration

As discussed in section 9.2.3 roof runoff is usually acidic. For water supplied by rain tanks, the main issue associated with low pH is enhanced metal solubility with main concern being lead which, as we have seen, is commonly found in roof runoff and tank water. Although the solubility behaviour of lead is complex and depends on other factors including water temperature and the concentrations of other solutes in water, Hem (1976) notes that lead may be soluble in dilute natural water below pH 6.5, with solubility increasing as rapidly as pH decreases (Rickard & Nriagu, 1978; Bodek *et al.* 1998). This behaviour was broadly confirmed in rain tanks sampled by Magyar *et al.* (2011b) who measured the partitioning between soluble & particulate lead as the pH of the water changed.

Tank water has been found to be acidic except where there is a strong influence of tank material. For example, Huston (2009) in a study of 29 tanks in Brisbane found a mean value of pH of all tank water samples of 6.1 (SD = 1, n = 325) (Figure 9.8). This is much lower, and more variable than Brisbane mains water, reported by Chapman *et al.* (2008) as 7.9 (SD = 0.14, n = 607). In Huston's (2009) study, tank water pH was generally outside the guideline values for drinking water (Figure 9.8) and in the range where metallic lead is increasing in solubility. The high lead concentrations in tank water samples measured by Huston (2009) were strongly linked to low pH (Figure 9.9). Where pH exceeded 7, lead concentration met drinking water standards. Similar results were reported by Simmons *et al.* (2001). They found that systems with pH < 6.5 were 4 times more likely to have elevated lead levels than those with pH > 6.5.

In Huston's study, the water from concrete tanks had significantly higher pH than plastic or steel tanks. Other studies have also found that concrete tanks can lead to higher pH (Thomas & Greene, 1993; Simmons *et al.* 2001; Handia, 2005) although the effect decreases with tank age (Handia, 2005; NHMRC & NRMMC, 2014).

There is also an interaction between pH in tank water and sediments that settle at the bottom of the tank. Low pH water can liberate lead and other metals from these sediments. High concentrations of lead have been reported in tank sediments in a number of studies and reviews (Sharpe & Young, 1984; Michaelides & Young, 1984; Gumbs & Dierbert, 1984; Scott & Waller, 1987; Spinks *et al.* 2005; Coombes *et al.* 2006; Magyar *et al.* 2007; Abbasi & Abbasi, 2011; Magyar *et al.* 2014). Tank sediment can also be re-suspended and supplied to end uses (Magyar *et al.* 2011b). If tank water is acidic then we can expect lead to be present in dissolved form and delivered in dissolved form to end uses.

9.3.5 Quality aspects of tank supply to hot water systems

The supply of tank water to domestic hot water systems has been suggested as one way to reduce microbial contamination (Spinks *et al.* 2003a; enHealth, 2004). However, Chapman *et al.* (2008) found that the use of rainwater in hot water systems can lead to increases in lead concentrations. In their analysis, 16% of hot water samples had lead concentrations greater than drinking water guidelines compared to 4% of samples collected prior to the hot water system. They recommended that where hot water systems are supplied from a rainwater tank, hot water should not be used for drinking or cooking. Although Chapman *et al.* (2008) did not propose a process for the observed increase in lead concentration in hot water, a potential mechanism is the increase

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in solubility of lead salts that occurs with increases in water temperature, especially when pH is low (Clever & Johnston, 1980). Lead contamination of water can also occur from brass fittings inside hot water systems or in house plumbing (McCafferty *et al.* 1995). This will be exacerbated when water is hot and has low pH.

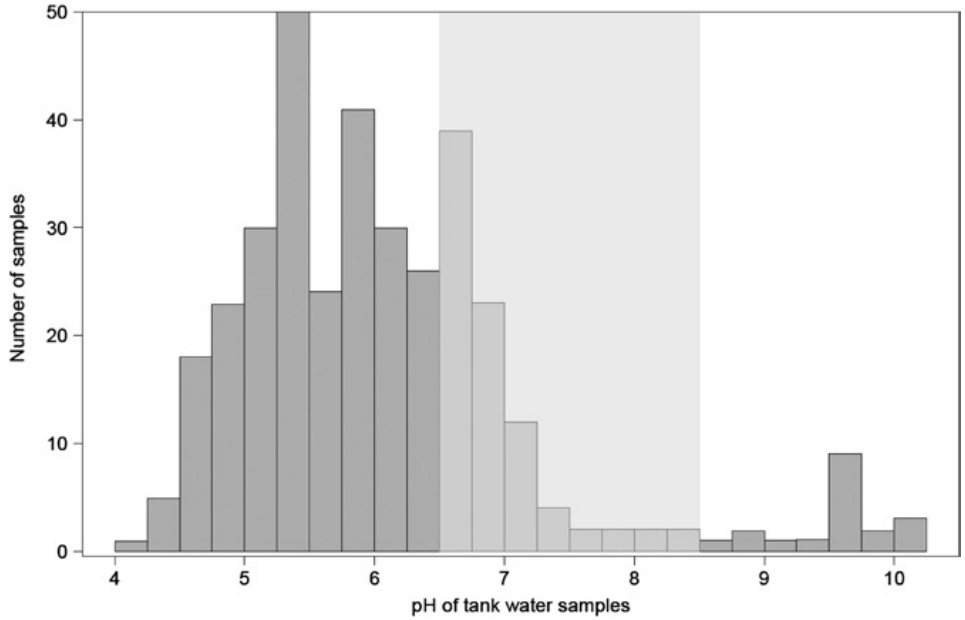


Figure 9.8 The distribution of pH from all the water samples in 29 Brisbane tanks ($n = 352$, Huston, 2009). Lightly shaded region is acceptable pH range specified in the Australian drinking water guidelines.

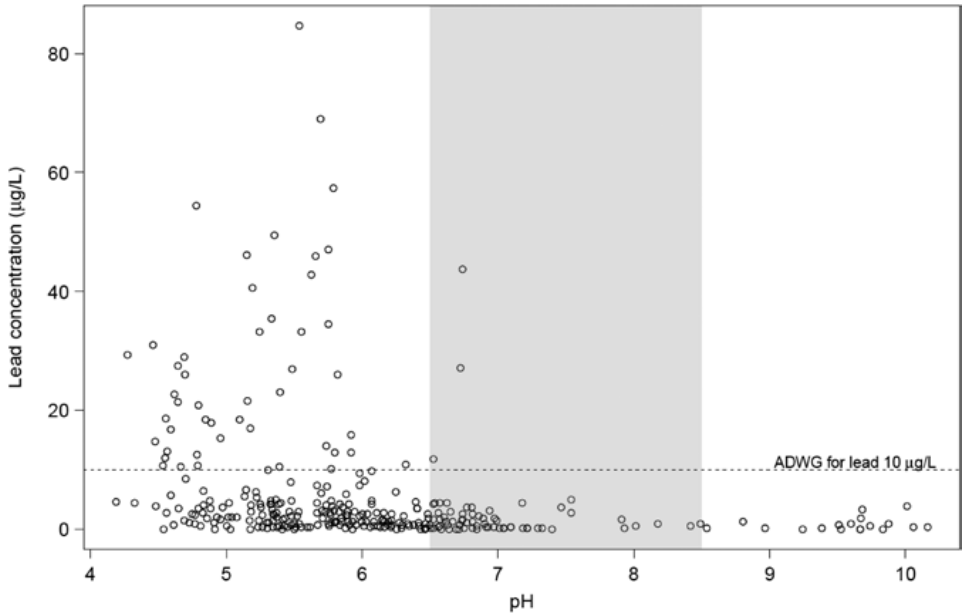


Figure 9.9 In a study of tank water quality in Brisbane, water samples with high lead concentration (>10 ug/L) occurred when pH was less than 7 (Huston, 2009). The shaded region corresponds to pH values as recommended in the Australian drinking water guidelines.

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9.4 IMPROVING THE QUALITY OF WATER SUPPLIED BY RAIN TANKS

Although not the focus of this chapter, we can suggest some ways to improve the quality of water delivered from rain tanks. The first step must be to take the risk of lead contamination seriously. We have identified 31 studies where lead concentration in tank water exceeded drinking water standards and only a few studies where it did not. Once the problem is acknowledged, researchers and designers can work to mitigated it. Currently, many guides aimed at practitioners who design and install tanks, place little emphasis on lead contamination and how it can be avoided (e.g., Melbourne Water, 2005; Coombes & Mitchell, 2006; MPMSAA, 2008).

A particular issue is tank maintenance, which if carried out appropriately, has the potential to improve water quality. However recommended procedures are seldom undertaken by householders and even if they were, water quality issues would not necessarily be avoided. For example tank inspection for accumulated sediments is recommended only every 2–3 years (Cunliffe, 1998; enHealth Council, 2004; NRMMC *et al.* 2009) yet Magyar *et al.* (2014) found that sediments in tanks were already heavily polluted after only one year post installation. Several researchers have found it is common for householders to undertake little or no maintenance. In a survey of 10,000 households in Brisbane, almost all (95%) had never had their rainwater tank professionally cleaned (Mankad & Greenhill, 2014). In their study of the health effects of the consumption of tank rainwater in South Australia, Heyworth *et al.* (2006) described maintenance procedures as rudimentary. Sludge had never been removed in at least 42% of tanks (26% of respondents were unaware of whether sludge had ever been removed). Other studies confirm the lack of maintenance (Bannister *et al.* 1997; Spinks *et al.* 2006; Rodrigo *et al.* 2010; Van der Sterran *et al.* 2013; Moglia *et al.* 2013). An ABS survey of 2558 households with rain tanks found that 58% had done no maintenance in the last 12 months that is, they had not cleaned gutters, checked or repaired inlets, insect screens or pipe work, nor had they checked or cleaned tank sediments (ABS, 2013). If tank water is to be used for drinking then clearly tank maintenance must become a priority. A suggested list of maintenance tasks is provided by Moglia *et al.* (2013).

Other ways to improve tank water quality include pH adjustment, better tank design (Michaelides & Young, 1984; Magyar *et al.* 2011a), floating outlets and water treatment for example, filtration.

9.5 CONCLUSION

Our conclusion is that the chemical quality of rainwater in rain tanks is of concern if tank water is to be used for drinking. Lead concentration exceeding the drinking water guideline of 10 ug/L is common. Based on a meta-analysis of 6 studies, we estimate that 22% of tanks in Australian capital cities will have high lead levels. Low pH is also widely reported which can increase the proportion of lead in dissolved form. High lead concentrations in rain tank water are widely reported in the literature, with 31 studies identifying lead as a water quality issue. Only a few studies have found lead concentrations that always meet drinking water standards.

Other than lead, the chemical quality of tank water generally meets water quality guidelines. A few studies mention excursive concentrations of other metals such as cadmium, nickel, selenium, copper and arsenic. In some cases; these can be linked to specific sources. However organic pollutants such as polycyclic aromatic hydrocarbons (PAHs), pesticides and herbicides do not seem to be a common or widespread issue. Even when high concentrations of PAHs were expected, such as after a bushfire or tanks located close to a freeway, they were not detected in rain tanks.

If tank water is not be used for drinking then there is less concern. The trigger value for lead in agricultural water supply (2000 µg/L) is much larger than that for drinking water (10 µg/L) and is unlikely to be exceeded unless there is a specific contamination issue.

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The potential for high lead concentration in tank water needs to be taken seriously with better advice required for tank system designers and the general public. Tank water quality can be improved by regular maintenance, but this is currently not widely practiced. There is also a need to reconsider rain tank design to focus on delivery of high quality water.

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Chapter 10

Microbiological quality and associated health risks with the use of roof-captured rainwater

Warish Ahmed and Simon Toze

ABSTRACT

This chapter reviews the available research reporting on the microbial quality of roof-captured rainwater (RCR) and provides insight on the potential health risks associated with the consumption of untreated tank water. The chapter also highlights a series of studies that were undertaken in South East Queensland to determine the microbial quality of tank water; identify the possible sources of faecal pollution in tank water; and provide information on the inactivation of faecal indicator bacteria in a RCR system. The studies indicated that the quality of the tank water is highly variable in terms of the presence of faecal indicator bacteria and zoonotic bacterial and protozoa pathogens. One of the studies identified possum and birds as the likely sources of faecal contamination in tank water. It remains prudent to disinfect RCR before using it as a potable water source.

Keywords: Faecal indicator bacteria; Zoonotic pathogens; Quantitative PCR; Health risks; Quantitative microbial risk assessment; Roof-captured rainwater.

10.1 INTRODUCTION

Water authorities worldwide are exploring alternative water sources to meet ever-increasing demands for potable water due to the adverse impacts of climate change on water supply. Roof-captured rainwater (RCR) has been considered as an alternative water source for both potable (drinking) and non-potable uses (irrigation, toilet flushing, car washing, showering, and clothes laundering). Australia, Canada, Denmark, Germany, India, Japan, New Zealand, Thailand and the United States have investigated the potential benefits of RCR (Despins *et al.* 2009; Evans *et al.* 2006; Uba & Aghogho, 2000). The numbers of rainwater tanks as a source of water for Australian urban and rural households are increasing. For example, 26% of Australian households used a rainwater tank as a source of water in 2010 compared with 19% in 2007 and 17% in 2004 (ABS, 2010). South Australia continues to have the highest proportion of households with a rainwater tank (48% and 49% in 2004 and 2010, respectively) but there was a marked increase in the proportion of households with a rainwater tank in Queensland (17% in 2004 to 36% in 2010) and

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Victoria (16% in 2004 to 30% in 2010). There are several advantages to using rainwater tanks, including: (i) reducing the demand on the town water supply; (ii) providing an alternative water supply during times of water restrictions; and (iii) reducing stormwater runoff that can often degrade creek ecosystem health (see Chapter 13). Despite rainwater tanks being widely used for potable water supply in rural and peri-urban areas in Australia, tank water has not been widely used for drinking in urban settings due to a lack of information on the presence and risk from microbiological and chemical pollutants. Another shortcoming is the lack of appropriate guidelines specifying the use of tank water for both drinking and non-potable uses, and how the human health risks from microbiological and chemical pollutants can be managed. The most significant issue in relation to untreated tank water for drinking is the health risks associated with microbial pathogens (Ahmed *et al.* 2008; Crabtree *et al.* 1996; Simmons *et al.* 2001). A wide array of pathogens could be present in the faeces of birds, insects, mammals, and reptiles that have access to the roofs. Consequently, following rain events, animal droppings and other organic debris deposited on the roofs and gutters can be transported into the tanks via runoff. In this scenario, if the untreated water collected from the roof were used for drinking, there are potential disease risks for people consuming this water. Only limited information is available, however, regarding the actual health risks associated with the uses of tank water.

Many countries have provided subsidies to encourage the installation of RCR systems for drinking and non-potable uses with the specific aim of decreasing the use of mains water. For instance, in 2006, the Queensland Government initiated the 'Home Water Wise Rebate Scheme' which provided subsidies to residents who used rainwater for non-potable domestic uses. More than 260,000 householders were granted subsidies by December 2008 when the scheme was concluded (Beal *et al.* 2011). The Queensland Department of Health does not recommended using RCR for drinking where municipal (town) water is available. However, Queensland regulations do not prohibit the plumbing of rainwater tanks to supply drinking water. Thus, if a person chooses to use rainwater for drinking or any other purpose, then that person is responsible for ensuring that the quality of the water is good enough for its intended use.

A general community perception is that tank water is safe to drink without having to undergo prior treatment. For example, there are 22% of rural households in Australia that are completely dependent on rainwater for their domestic supply (ABS, 2010). The safety of drinking rainwater was further supported by the epidemiological surveys of gastroenteritis in South Australia that concluded tank water poses no increased risk of gastroenteritis when compared with town water (Heyworth *et al.* 2006; Rodrigo *et al.* 2010). In contrast, a number of studies on the microbial quality of tank water have reported the presence of specific zoonotic pathogens (i.e., capable of being transmitted from animals to humans) in individual or communal tank systems, suggesting that a real health risk exists (Ahmed *et al.* 2008; Birks *et al.* 2004; Crabtree *et al.* 1996; Lye, 2002; Simmons *et al.* 2001; Uba & Aghogho, 2000).

The purpose of this chapter is to: (i) highlight international research studies investigating the microbiological quality of tank water; and (ii) discuss disease outbreaks linked to the consumption of untreated tank water. The chapter includes a review of a series of studies associated with microbial pollution of tank water undertaken in South East Queensland (SEQ), Australia.

10.2 FAECAL INDICATORS AND PATHOGENS IN ROOF-CAPTURED RAINWATER

10.2.1 Faecal indicators

Drinking water guidelines have been used to assess the microbial quality of the tank water. For most guidelines, this entails the non-detection of *Escherichia coli* in 100 mL of water (NHMRC–NRMMC,

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2004; WHO, 2004). Even when tank water is not used for drinking, the assessment of the microbial quality is usually undertaken by monitoring the presence of faecal indicator bacteria (Ahmed *et al.* 2008, 2010; Appan, 1997; CRC WQT, 2006; Dillaha & Zolan, 1985). The World Health Organization (WHO) recommends that for drinking water, the total coliform numbers should be <10 colony forming units (CFU)/100 mL in 95% of samples collected from a particular water source (WHO, 2004). These guidelines also indicate that if the numbers of total coliforms are >20 CFU/100 mL water, further treatment should be undertaken prior to drinking. It should be noted that total coliforms may not be a suitable indicator of faecal contamination in RCR. Total coliforms in water can comprise microorganisms that could be faecal in origin but also could be from other sources such as soil and vegetation. Thus, their presence in rainwater tanks could be through contamination from dust and plant materials. *E. coli* and enterococci are considered much better indicators of faecal contamination, and most guidelines stipulate that the numbers of these organisms should be zero CFU/100 mL for drinking water. Such stringent guideline values have been established for these indicators as they are commonly found in high numbers in human and animal faeces. Their presence in drinking water, therefore, indicates a strong likelihood that faecal sourced pathogens also occur, and that the water is not suitable for drinking (Baudisöva, 1997).

Most research studies on tank water reported to date used faecal indicator bacteria to assess the microbiological quality of the water. Figure 10.1 shows the percentage of positive samples for faecal indicator bacteria in tank water samples reported in 17 international research studies. In Micronesia, 176 tank water samples were surveyed for faecal coliforms. Of these, 68% of the samples contained measurable numbers of faecal coliforms (Dillaha & Zolan, 1985). Despite the high numbers of samples not complying with the guidelines, the authors suggested that the tank water could be reasonable for drinking. Lye (1987) also reported that the microbiological quality of tank water was consistently good in a study of the occurrence of faecal coliforms in tank water samples in Kentucky, USA, where only one sample out of 30 had faecal coliforms numbers >10 CFU/100 mL.

In contrast, several studies reported higher numbers of faecal indicators in tank water samples, which therefore, did not comply with acceptable drinking water guideline values (Figure 10.1). A recent study in South Korea reported that 72% of tank water samples were positive for *E. coli* and the numbers were above the WHO drinking water guideline value of zero CFU/100 mL (Lee *et al.* 2010). High numbers of *E. coli* were also found in tank water samples in Denmark, where *E. coli* was observed to be present in 11 out of 14 systems, with numbers ranging from 4 to 900 CFU/100 mL. The conclusion made in this study was that the presence of *E. coli* indicated that the water may not be suitable for drinking (Albrechtsen, 2002).

In Victoria, Australia, 49 rainwater tanks surveyed for the presence of *E. coli* and enterococci found that 33% were positive for *E. coli* and 73% positive for enterococci, therefore exceeding the Australian Drinking Water Guidelines of zero CFU/100 mL (ADWG, 2004; Spinks *et al.* 2006). High numbers of *E. coli* (ranging from 4 to 800 CFU/100 mL) and enterococci (5 to 200 CFU/100 mL) were also reported in tank water samples tested in South East Queensland, Australia (Ahmed *et al.* 2008). In this study, 63% and 78% of the 27 samples were positive for *E. coli* and faecal streptococci, respectively. Ahmed *et al.* (2008) concluded that, as *E. coli* could not be detected in a number of the water samples that were positive for enterococci (a sub-group of faecal streptococci), tank water should be tested for both *E. coli* and enterococci, as well as relevant indicators (where possible) to obtain multiple lines of evidence on the occurrence of faecal contamination. On the basis of these results, they concluded that *E. coli* by itself as an indicator may be of limited use to assess the microbial quality of tank water samples.

Several studies also reported that enterococci are more prevalent in tank water samples compared to *E. coli* (Ahmed *et al.* 2008, 2010; CRC WQT, 2006; Spinks *et al.* 2006), and thus may be a better indicator for assessing faecal contamination. The greater prevalence of enterococci in tank water may be due to the fact that enterococci persist in the water longer than *E. coli* (Anderson *et al.* 2005; McFeters *et al.* 1974).

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It has also been reported that enterococci are better indicators of faecal contamination in environmental waters compared to *E. coli* (Kinzelman *et al.* 2003). Nonetheless, more studies on the potential sources and the relative persistence are needed that compare the usefulness of *E. coli* versus enterococci in tank water samples before any recommendations can be made concerning which indicators may be the most suitable.

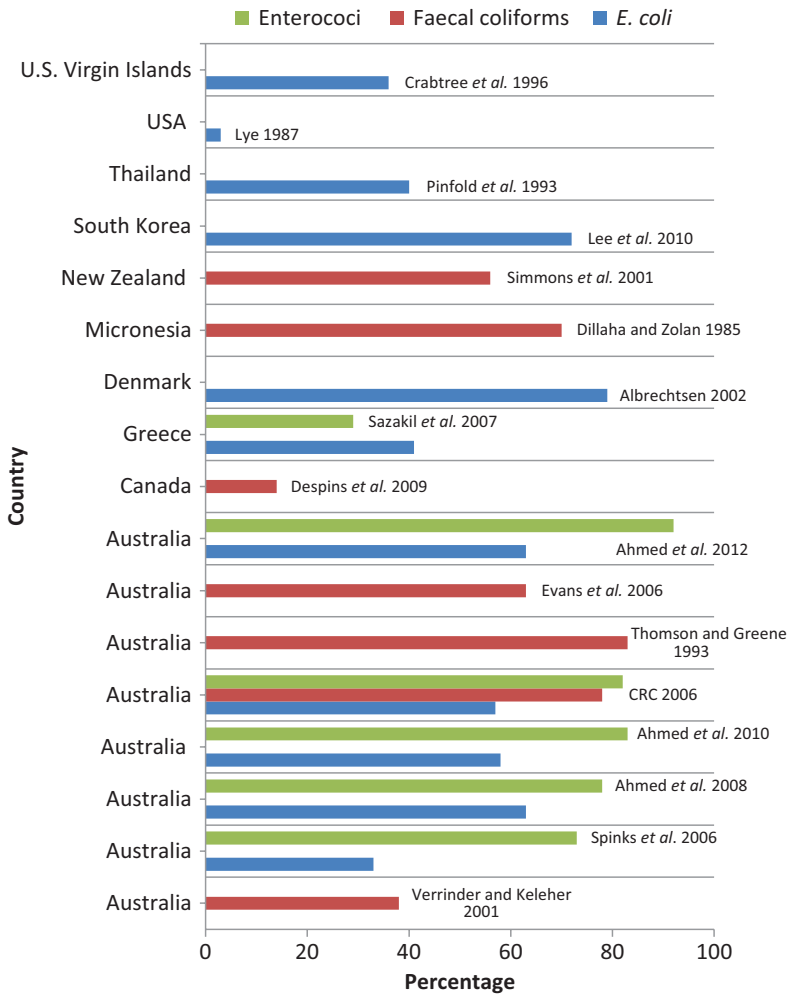


Figure 10.1 Percentage of samples positive for faecal indicators in tank water samples (Ahmed *et al.* 2011).

10.2.2 Bacterial pathogens

Faecal indicator bacteria such as *E. coli* and enterococci generally used to detect and estimate the level of faecal contamination in water. These are relatively harmless to human health but are used to indicate the presence of potential health risks. To date, only a relatively small number of studies have investigated the presence of bacterial pathogens in tank water samples (Table 10.1). In one of these studies, Simmons *et al.* (2001) reported the presence of *Salmonella* spp. in 1% of the 115 tank water samples tested in Auckland, New Zealand. *Campylobacter* spp. has also been detected in tank water samples in New Zealand using

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polymerase chain reaction (PCR) (Savill *et al.* 2001). In all, 37.5% of the samples tested were positive for *Campylobacter* spp., with numbers ranging from <0.06 to 0.56 most probable number (MPN)/100 mL tank water. *C. jejuni* have also been detected in tank water samples in Denmark (Albrechtsen, 2002). On the basis of these findings, the author concluded that connecting rainwater tanks to the drinking water systems would increase the level of risk of gastroenteritis and respiratory illness. A recent study that used PCR to detect evidence of bacterial pathogens in tank water in South East Queensland, Australia, found that approximately 20% of tank water samples were positive for *Campylobacter* spp. and *Salmonella* spp. that can cause gastrointestinal illness (Ahmed *et al.* 2010a). The authors suggested that tank water samples tend to decrease in microbiological quality after rain events, although the impact of duration of the intervening dry periods between rain events on runoff water quality remained unknown. Similarly, the tank storage time required after rain events for improvement in microbial quality also remained unknown.

Table 10.1 Percentage and number of samples positive for bacterial pathogens in rainwater samples.

Country	Percent of samples (number of samples in brackets) positive for bacterial pathogens				References
	***Campylobacter* spp.**	***Salmonella* spp.**	***Shigella* spp.**	***Vibrio* spp.**	
Australia	45 (27)	11 (27)	–	–	Ahmed *et al.* (2008)
Australia	20 (100)	17 (100)	–	–	Ahmed *et al.* (2010)
Australia	2 (67)	3 (67)	–	–	CRC WQT (2006)
Denmark	12 (17)	–	–	–	Albrechtsen (2002)
New Zealand	37 (24)	–	–	–	Savill *et al.* (2001)
New Zealand	ND (125)	1 (125)	–	–	Simmons *et al.* (2001)
Nigeria	–	67 (6)	67 (6)	67 (6)	Uba and Aghogho (2000)

ND: Not detected; –: Not tested.

10.2.3 Opportunistic bacterial pathogens

To date, only a small number of studies have investigated the presence of opportunistic bacterial pathogens in tank water samples (Table 10.2). Opportunistic pathogens such as *Legionella* spp. and *Aeromonas* spp. are considered to be of concern for respiratory and gastrointestinal aspects of human health. In addition, these opportunistic pathogens are also responsible for urinary tract infection, skin and soft tissue infections, pneumonia and wound infections. The links between water and *Legionella* infections is well known, and a recent study by Khajanchi *et al.* (2010) demonstrated a link between *Aeromonas* spp. isolated from clinical and water samples, indicating transmission from water. Simmons *et al.* (2001) reported the presence of *Aeromonas* spp. in RCR samples collected in Auckland, New Zealand, with 20% of the 125 samples tested being positive for *Aeromonas* spp.

Based on the positive detections obtained, the authors concluded that tank water samples were not suitable for drinking, and recommended further research on the *Aeromonas* spp. because of its high prevalence and association with gastroenteritis in both adults and children. *Aeromonas* spp., along with other opportunistic pathogens such as *Pseudomonas* spp., *Legionella* spp., and *Mycobacterium* spp., have also been detected in tank water samples in Denmark (Albrechtsen, 2002). The author concluded that if collected rainwater is used for drinking, it would increase the risk of illness from opportunistic pathogens.

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Another study that used PCR to detect evidence of opportunistic bacterial pathogens in tank water in South East Queensland, Australia, found that around 7% of the 100 samples were positive for *Aeromonas hydrophila* (Ahmed *et al.* 2010a). In addition, 8% of the samples were positive for the respiratory opportunistic pathogen *L. pneumophila*.

Table 10.2 Detection of opportunistic bacterial pathogens in roof-captured rainwater.

Country	Percent of samples (number of samples in brackets) positive for opportunistic bacterial pathogens				References
	***Aeromonas* spp.**	***Pseudomonas* spp.**	***Legionella* spp.**	***Mycobacterium spp.***	
Australia	15 (27)	–	26 (27)	–	Ahmed *et al.* (2008)
Australia	7 (100)	–	8 (100)	–	Ahmed *et al.* (2010)
Australia	32 (56)	–	15 (67)	–	CRC WQT (2006)
Denmark	14 (14)	7 (14)	71 (7)	7 (14)	Albrechtsen (2002)
New Zealand	20 (125)	–	ND (125)	–	Simmons *et al.* (2001)
Nigeria	–	83 (6)	–	–	Uba and Aghogho (2000)
U.S. Virgin islands	–	–	80 (10)	–	Broadhead *et al.* (1988)

ND: Not detected; -: Not tested.

10.2.4 Protozoa pathogens

Despite a well-established zoonotic (i.e., transmission of diseases from animals to humans) link, the presence of protozoa pathogens in rainwater tanks has not been extensively investigated, with only a few studies examining tank water samples for the presence of *Giardia* spp. and *Cryptosporidium* spp. (Table 10.3). Crabtree *et al.* (1996) reported that 45% and 23% of 45 water samples tested from private and public rainwater systems in the U.S. Virgin Islands were positive for *Cryptosporidium* oocysts and *Giardia* cysts, respectively. The levels of cysts and oocysts were found to range from 1 to 10 organisms/100 L, with one sample containing 70 oocysts/100 L. The numbers of *Cryptosporidium* oocysts in all the positive samples were well above the acceptable guidelines of zero tolerance of protozoa pathogens. Simmons *et al.* (2001) also reported the presence of *Cryptosporidium* spp. in 4% of 50 tank water samples in Auckland, New Zealand. However, unlike Crabtree *et al.* (1996), Simmons *et al.* (2001) were unable to detect any *Giardia* cysts. Albrechtsen (2002) similarly reported the presence of *Cryptosporidium* spp. in Danish tank water samples. They tested 17 rainwater samples, of which 6 were positive for *Cryptosporidium* spp. The numbers of *Cryoptosporidium* spp. were as high as 50 oocysts/L. However, as reported in Simmons *et al.* (2001), *Giardia* spp. was not detected in any of the samples.

In contrast, another study in South East Queensland, Australia, reported the presence of *G. lamblia* in 19% of 21 tank water samples tested, yet none of the samples were positive for *C. parvum* (Ahmed *et al.* 2008, 2010). One possible reason for the differences in the type of protozoa pathogen detected in the Australian study and those from overseas may be the different wildlife that has access to roofs. In South East Queensland, for example, marsupial possums are a common animal in and around urban dwellings and frequently traverse roof tops in their nocturnal movements. Possums are known to be carriers of *Giardia* cysts (Ahmed *et al.* 2012a; Marino *et al.* 1992). Thus, possums could be a major source of *Giardia*

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spp. in tank water samples in South East Queensland, whilst birds or other wild animals are the likely source of the *Cryptosporidium* spp. in the overseas studies.

Table 10.3 Detection of protozoa pathogens in roof-captured rainwater.

Country	Percent of samples (number of samples in brackets) testing positive for protozoa pathogens		References
	***Cryptosporidium* spp.**	***Giardia* spp.**	
Australia	–	19 (21)	Ahmed *et al.* (2008)
Australia	ND	15 (100)	Ahmed *et al.* (2010)
Denmark	35 (17)	ND (17)	Albrechtsen (2002)
New Zealand	4 (50)	ND (125)	Simmons *et al.* (2001)
U.S. Virgin islands	45 (45)	23 (45)	Crabtree *et al.* (1996)

ND: Not detected; -: Not tested.

10.2.5 Likely sources of *Escherichia coli* harboring toxin genes in rainwater tanks

E. coli is often characterized as a *commensal* or harmless bacterium (Hartl *et al.* 1984). However, certain strains of *E. coli* can be pathogenic and responsible for both intestinal and extraintestinal infections (Kaper *et al.* 2004). It has been reported that faeces of warm-blooded animals may contain high numbers of *E. coli* bacteria carrying virulence genes (Ishii *et al.* 2007). These virulence genes allow pathogenic *E. coli* to cause a wide array of infections, such as diarrhoea, urinary tract infections (UTIs), neonatal meningitis, soft-tissue infections, and bacteremia. Pathogenic *E. coli* strains that are capable of causing diseases in humans and animals can be categorised as intestinal pathogenic *E. coli* (InPEC) or extraintestinal pathogenic *E. coli* (ExPEC) (Russo & Johnson, 2000). These pathotypes contain various combinations of virulence genes for the attachment and elaboration of hemolysins and enterotoxins (Bertin *et al.* 2001). ExPEC strains have the special ability to cause extraintestinal infections such as UTIs, neonatal meningitis and sepsis, and wound infections which can lead to serious complications and death. ExPEC strains possess virulence genes combinations that are distinct from those of strains that cause intestinal infections. Despite increasing evidence that *E. coli* strains from several animal hosts contain virulence genes, and the fact that some have been shown to cause intestinal and extraintestinal diseases in humans, none of the studies have determined whether *E. coli* bacteria found in rainwater tanks carry virulence genes and are potentially able to cause intestinal or extraintestinal infections in humans.

Ahmed *et al.* (2012b) report on a study to identify the likely sources of *E. coli* strains harbouring toxin genes in rainwater tanks. Understanding the contamination sources could enable better control of the sources, thus minimising the potential public health risks. In their study, 200 *Escherichia coli* isolates from 22 rainwater tank samples in SEQ, Australia were tested for the presence of ten toxin genes (stx_1, stx_2, *hlyA*, *ehxA*, LT1, ST1, *cdtB*, *east1*, *cnf1*, and *cvaC*) associated with intestinal and extraintestinal pathotypes. 428 *E. coli* isolates from bird and possum faecal samples were also tested for the ten toxin genes as these animals had been previously identified as potential sources of faecal contamination of RCR (Ahmed *et al.* 2012a).

Among the 10 toxin genes tested, 4 genes (i.e., ST1, *east1*, *cdtB*, and *cvaC*) were detected in 43 of 200 *E. coli* strains. The remaining toxin genes stx_1, stx_2, *hlyA*, *exhA*, LT1, and *cnf1* could not be detected in

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any of isolates tested. Among the 200 isolates tested, 8 (4%), 25 (13%), 19 (10%), and 1 (0.5%) strains were positive for the ST1, *east1*, *cdtB*, and *cvaC*, respectively (Table 10.4). Among the 214 *E. coli* isolates tested from birds, 30 (14%), 11 (5%) and 18 (8%) strains contained the *east1*, *cdtB*, and *cvaC* toxin genes, respectively. Similarly, among the 214 possum *E. coli* isolates, 74 (35%) contained only the *east1* toxin gene (Table 10.4). Biochemical phenotypes of 14 (33%) *E. coli* strains from seven rainwater tanks and nine (21%) *E. coli* strains from six rainwater tanks were identical to a number of biochemical phenotypes of *E. coli* strains isolated from bird and possum faeces, respectively, suggesting that these animals are probably the sources of these *E. coli* strains in rainwater tanks.

Table 10.4 Occurrence of *Escherichia coli* harbouring toxin gene in rainwater tanks, bird and possum faecal samples.

Samples	No. of *E. coli* tested	No. of *E. coli* isolates harbouring toxin genes (%)	Distribution of *E. coli* harbouring toxin genes into intestinal and extraintestinal pathotypes (%)			
			ETEC	EaggEC	EPEC/ExPEC	ExPEC
			ST1	*east1*	*cdtB*	*cvaC*
Rainwater tanks	200	43 (22)	8 (4)	25 (13)	19 (10)	1 (0.5)
Birds	214	55 (23)	ND	30 (14)	11 (5)	18 (8)
Possums	214	74 (35)	ND	74 (35)	ND	ND

ND: Not detected.

The presence of these toxin genes in *E. coli* strains from rainwater tanks is of concern as toxins are the most obvious virulence factors in pathogenic *E. coli*. For example, *E. coli* strains harbouring *east1* toxin gene alone have been reported to show a clear association with diarrhoea. Similarly, *E. coli* strains harbouring the *cdtB* or ST1 toxin genes are known to cause extraintestinal as well as intestinal infections. The authors acknowledged however that in the absence of any *in vivo* study, it was not possible to determine whether strains harbouring toxin genes in rainwater tanks were in fact capable of expressing pathogenicity, and because of that, these strains can be considered only as potential pathogenic strains.

To identify the likely sources of these potential clinically significant *E. coli* in rainwater tanks, a source-tracking approach was undertaken. All *E. coli* strains isolated from bird and possum faecal samples harbouring toxin genes were biochemically fingerprinted. The principle of the biochemical fingerprinting with the PhPlate system has been described previously (Möllby *et al.* 2003). This method uses quantitative measurements of the kinetics of several biochemical reactions of bacteria in microtiter plates with dehydrated substrates (Möllby *et al.* 2003). Biochemical fingerprints of *E. coli* obtained from rainwater tanks were compared with those found in bird and possum faeces cal to establish a potential link.

Of the 43 strains from rainwater tank samples, 14 (from seven tanks) and nine (from six tanks) had identical biochemical phenotypes to those found in bird and possum faecal samples, respectively. Five strains from 4 rainwater tanks were identical to those isolated from both bird and possum faecal samples. Based on the results, the authors concluded that the presence of potential clinically significant *E. coli* in rainwater tanks most likely originated from bird and possum faeces.

Based on these results, Ahmed *et al.* 2012 a,b recommended that rainwater be treated with effective disinfection procedures such as filtration, ultraviolet disinfection or simply boiling the water prior to drinking. Maintenance of good roof and gutter hygiene and elimination of overhanging tree branches

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and other structures where possible to prevent the flocking of possums and birds should be considered for improved water quality.

10.2.6 Presence and source of faecal indicators and zoonotic pathogens in household drinking water taps fed from rainwater tanks in South East Queensland

Many householders who drink tank water use an under-sink filtration (USF) system to reduce exposure to pathogenic microorganisms, suspended solids and harmful chemicals. Little is known regarding the prevalence of zoonotic pathogens in household drinking water taps fed by rainwater tanks. Little is also known of the prevalence of zoonotic pathogens in wild animals, such as birds and mammals, which are most likely contaminating rainwater tanks. Mammals can get access to the roof via overhanging trees or electricity cables, or by climbing to the roof via walls or other structures attached to the house. Birds are attracted to a roof by overhanging trees or structures mounted on the roof, such as television aerials and solar panels. Knowing the source of pathogenic microorganisms is important in order to design management strategies to reduce public health risks.

Ahmed *et al*. (2012a) investigated the prevalence and numbers of faecal indicators (*E. coli* and enterococci) and zoonotic bacterial (*Campylobacter* spp. and *Salmonella* spp.) and protozoa (*Cryptosporidium parvum* and *Giardia lamblia*) pathogens in water samples from rainwater tanks and corresponding connected household taps in South East Queensland. They also investigated the prevalence of the above-mentioned pathogens in faecal samples from possums and various species of wild birds. Conventional culture-based methods were used to enumerate *E. coli* and enterococci, and qPCR was used to obtain the numbers of zoonotic pathogens in roof captured rainwater (RCR), connected household tap water (CHTW), and animal faecal samples.

Their study area, Currumbin Ecovillage, is located on the southern end of the Gold Coast, South East Queensland, Australia. The Ecovillage is known for its sustainable residential developments and is often viewed as a blueprint for future urban development. Twenty-four households participated in the study. All the households use RCR for drinking, as well as other non-potable water uses such as car washing, clothes laundering, showering, and gardening. Two water samples were collected from each household (i.e., one from the rainwater tank and one from the connected household tap), giving a total of 48 samples from the 24 households. Samples were collected within 1 to 4 days after a rain event. Brush tail possum faecal samples ($n = 40$) were obtained from the possum removal service. Bird faecal samples ($n = 38$) were collected from botanical gardens, bird sanctuaries, and a veterinary hospital. DNA was extracted from all water and animal faecal samples and tested with qPCR.

Amongst the 24 households, *E. coli* was cultured from 15 (62%) RCR and 14 (58%) connected household tap water (CHTW) samples. Similarly, 22 (92%) RCR and 20 (83%) CHTW samples contained cultured enterococci. The numbers of *E. coli* bacteria in these samples ranged from 1 to 230/100 mL (for RCR) and 1 to 300 CFU/100 mL of water for CHTW. For enterococci, the numbers were 2 to 110 CFU/100 mL (for RCR) and 1 to 110 CFU/100 mL (for CHTW). Among the 24 households, 5 (21%), 1 (4%), and 3 (13%) RCR samples contained *Campylobacter* spp., *Salmonella* spp., and *G. lamblia*, respectively (Table 10.5). Similarly, 5 (21%) and 3 (13%) of the CHTW samples contained *Campylobacter* spp. and *G. lamblia*, respectively. The *Salmonella* spp. could not be detected in CHTW samples. The numbers of *Campylobacter* cells in RCR and household tap water samples ranged from 5 to 110 (in RCR) and 12 to 19 (in CHTW) cells/L of water. Similarly the estimated number of *Salmonella* cells was 7,300 (in RCR)/L of water. The numbers of *G. lamblia* cysts ranged from 120 to 580 (in RCR) and 110 to 140 (in CHTW)/L of water. The numbers of faecal indicators and pathogens were pooled for all RCR and CHTW samples to determine whether the numbers were correlated between RCR and CHTW samples.

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Table 10.5 Numbers of zoonotic pathogens in roof captured rainwater and connected household tap water samples in four houses at Currumbin Ecovillage.

Household ID	Numbers (mean) of bacterial and protozoa pathogens/L of water			
	Campylobacter spp.		*G. lamblia*	
	RCR	CHTW	RCR	CHTW
H1	ND	ND	120	140
H7	ND	ND	160	140
H14	5	12	580	110
H15	30	19	ND	ND

ND: Not detected; RCR: Roof-captured rainwater; CHTW: Connected household tap water.

The number of *E. coli* ($P > 0.78$), enterococci ($P > 0.64$), *Campylobacter* ($P > 0.44$), and *G. lamblia* ($P > 0.50$) in RCR did not differ significantly from the numbers observed in the CHTW samples. Table 10.5 shows the numbers of *Campylobacter* spp. and *G. lamblia* detected in RCR and CHTW samples in four households.

Around 58% of households in this study did not use any filtration methods; therefore, the presence of faecal indicators and zoonotic pathogens in the CHTW samples was not unexpected. Ten of the 24 households had USF installed; however, these systems did not appear to be effective in removing faecal indicators and zoonotic pathogens.

G. lamblia was detected in three of the 24 tanks tested in this study. All three corresponding CHTW samples also contained *G. lamblia*. It should be noted that these households did not apply any filtration methods prior to drinking. The high numbers of *G. lamblia* cells in both tank water (120 to 580 cysts/L) and connected household tap water samples (110 to 140 cysts/L) may pose health risks to the consumers because of the low (1–10 cysts) infectious dose of *G. lamblia*. A little is known regarding the occurrence of Giardiasis in the community. Giardiasis is not notifiable in Queensland by clinicians but several medical doctors have expressed their concerns that rainwater may have increased the levels of Giardiasis in the community. It is also possible that the qPCR method used in the study overestimated the levels of *G. lamblia* in tank water samples because PCR cannot distinguish between viable and non-viable cysts.

Among the 40 possum faecal samples tested, *Campylobacter* spp., *Cryptosporidium parvum*, and *G. lamblia* were detected in 60%, 13%, and 30% of samples, respectively. Among the 38 bird faecal samples tested, *Campylobacter* spp., *Salmonella* spp., *C. parvum*, and *G. lamblia* were detected in 24%, 11%, 5%, and 13% of the samples, respectively. In all, 60% of possum and 24% of bird faecal samples contained *Campylobacter* spp. All bird faecal samples contained *C. jejuni* but none of the possum faecal samples contained *C. jejuni*. Possum and bird faecal samples also contained *G. lamblia*, with the numbers of cysts ranging from 21 to 1600 (for possums) and 1.3 to 120 (for birds) per gram of faeces suggesting these animals are the likely sources of *G. lamblia* in rainwater tanks.

10.2.7 Inactivation of faecal indicator bacteria in a roof-captured rainwater system

The presence of clinically significant *E. coli* in rainwater tank samples in South East Queensland (Ahmed *et al.* 2012b) raises questions regarding the persistence of faecal indicator bacteria and pathogens in

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rainwater tank samples, as well as in faecal deposits on the roof and in the gutter. A range of climatic and biological factors have been shown to influence the inactivation of faecal indicator bacteria and pathogens. These factors include temperature, moisture content, solar radiation, relative humidity, pathogen type, presence of biodegradable organic matter and interaction with other micro-organisms. The faecal indicator bacteria and pathogens from bird and animal droppings deposited on the roofs and in the gutters are expected to inactivate rapidly due to harsh environmental conditions such as temperature, UV radiations and loss of moisture. However, certain conditions such as the shaded portion of the roof, precipitation, availability of biodegradable organic matter in the gutter may prolong the inactivation of faecal indicator bacteria and pathogens. However, very little has been documented about the inactivation of bacteria and pathogens on the roofs, in the gutters, and in the tank water.

Ahmed *et al.* (2014) undertook experiments in South East Queensland, Australia to obtain information on the inactivation of faecal indicator bacteria in those time periods between faeces being deposited on the roof and washing off into the tank. The study investigated the persistence of *E. coli* and enterococci on the roof and in the gutter of a 'model' RCR system to determine: (i) the time required to achieve a one $\log_{10}$ (i.e., 90% or T_{90}) reduction of *E. coli* and enterococci on the corrugated iron roof and in the gutters; and (ii) the inactivation time (T_{90}) of faecal indicator bacteria in the tank water.

A model RCR system (similar set up to RCR systems commonly in use in Australian domestic dwellings) was built comprising a 5000 L polyethylene tank, 2 m^2 roof constructed of corrugated iron sheets with steel guttering and plastic downpipe leading water into the tank. The tank was placed in direct sunlight (received minimum 5 h sunlight per day during the experiment). Faecal indicator bacteria contamination of roof and gutter was simulated using homogenized possum faecal slurry spiked with known numbers of *E. coli* and enterococci.

For the roof and gutter inactivation experiments, 5 mL of faecal slurry was poured into a series of 50 mm petri dishes and placed on the corrugated iron roof and in the gutter of the experimental structure. The petri dishes were exposed to diurnal cycles of insolation. Moist sediment containing vegetation and organic debris was added to the gutters to simulate typical unclean, urban household gutters. The petri dishes were kept under the vegetation and organic debris and the numbers of surviving faecal indicator bacteria were enumerated. The inactivation experiment in tank water was undertaken using diffusion chambers as described by Toze *et al.* (2004).

For each faecal indicator bacteria all determined numbers in each replicate at each sampling occasion were converted to $\log_{10}$ values and plotted over time. One $\log_{10}$ reduction time (T_{90}) for each fecal indicator bacteria was determined from each plot using the following equation as previously described (Gordon & Toze, 2003).

$$T_{90} = -t/(\log_{10} C_t/C_0)$$

where C_0 is the number (CFU/mL) at day 0, C_t is the final number (CFU/mL) at day t. A linear regression was fitted to each plot and the slope was taken as the inactivation rate. The inverse of these calculated inactivation rates was then used as the determination of the one $\log_{10}$ reduction time (T_{90}). The average T_{90} on each sampling occasion was determined from replicates of each faecal indicator bacteria. Where the inactivation in some experiments was biphasic, two T_{90} values were calculated, one for the initial inactivation (first phase) and the other for the second stage of the inactivation (second phase). An analysis of variance (ANOVA) was performed on the T_{90} values on the roof and in the gutter under different conditions. For statistical comparison, T_{90} values derived from the first phases of various experimental conditions were used. Details of the statistical analysis can be found in Ahmed *et al.* (2014).

The inactivation rates of faecal indicator bacteria in possum faecal slurry placed on the roof were evaluated under sunlight and shade conditions and are shown in Figure 10.2. Under direct sunlight, *E. coli*

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is rapidly inactivated (T_{90} = 2 h) compared to shade, where a slow non-linear (biphasic) inactivation rate [T_{90} = 53 h (first phase) and 9 h (second phase)] was observed (Table 10.6). Similar results were also obtained for enterococci. No significant ($P > 0.05$) difference was observed in T_{90} value of *E. coli* compared to enterococci under sunlight conditions. Significant ($P < 0.001$) difference, however, was observed in T_{90} value of *E. coli* compared to enterococci for shade conditions (Table 10.6).

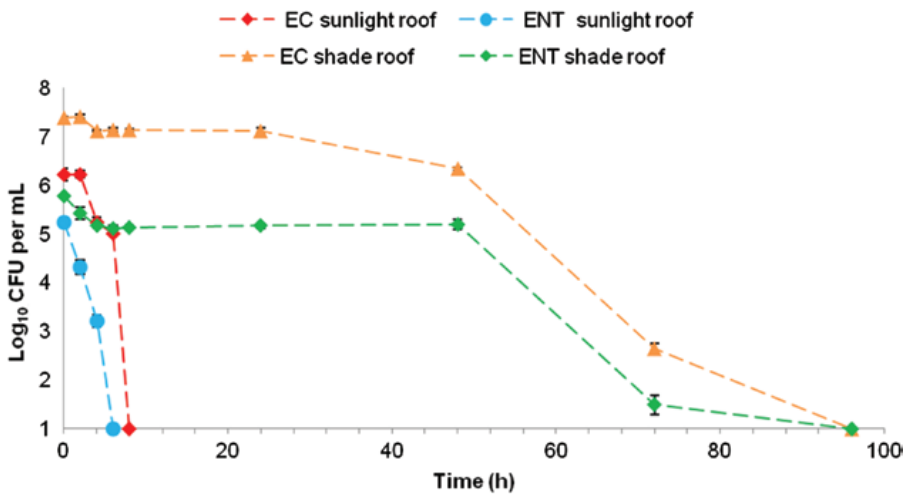


Figure 10.2 Log_{10} (mean ± standard deviation) colony forming units (CFU) of culturable *Escherichia coli* (EC) and *enterococci.* (ENT) during the course of inactivation on the roof under direct sunlight and shade conditions.

Table 10.6 T_{90} inactivation time of *Escherichia coli* and enterococci on the roof, in the gutter and tank water. R^2 of the regression line used to calculate T_{90} is shown in brackets.

Faecal indicators	Experiments	Conditions	T_{90} (h) (R^2)	
			First phase	Second phase
E. coli	Roof	Sunlight	2 (0.72)	
		Shade	53 (0.85)	9 (0.95)[a]
	Gutter	Clean	22 (0.66)	3 (0.99)[a]
		Unclean	20 (0.73)	6 (0.88)[a]
	Tank water		72 (0.86)	273 (0.84)[c]
Enterococci	Roof	Sunlight	2 (0.95)	
		Shade	9 (0.92)	18 (0.80)[c]
	Gutter	Clean	2 (0.80)	
		Unclean	6 (0.97)	
	Tank water		38 (0.99)	195 (0.94)[d]

[a]Three data points were used to calculate T_{90} inactivation times.
[b]Four data points were used to calculate T_{90} inactivation times.
[c]Five data points were used to calculate T_{90} inactivation times.
[d]Six data points were used to calculate T_{90} inactivation times.
R^2: Coefficient of determination.

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The inactivation rates of faecal indicator bacteria were evaluated in the clean and unclean gutters under direct sunlight (Figure 10.3). The organic matter and vegetation in the unclean gutter shaded the faecal slurry from sunlight. *E. coli* showed biphasic inactivation rates under both clean and unclean gutter conditions [$T_{90} = 22$ h (first phase) and 3 h (second phase)] for the clean gutter conditions and [$T_{90} = 20$ h (first phase) and 6 h (second phase) for the unclean gutter conditions. Enterococci showed much more rapid initial inactivation ($T_{90} = 2$ h) for the clean gutter and the unclean gutter ($T_{90} = 6$ h) compared to *E. coli*. The T_{90} values for *E. coli* and enterococci were significantly different ($P < 0.001$) from each other for both clean and dirty gutters. Significant ($P < 0.001$) differences in T_{90} values occurred for enterococci between clean and unclean gutter conditions.

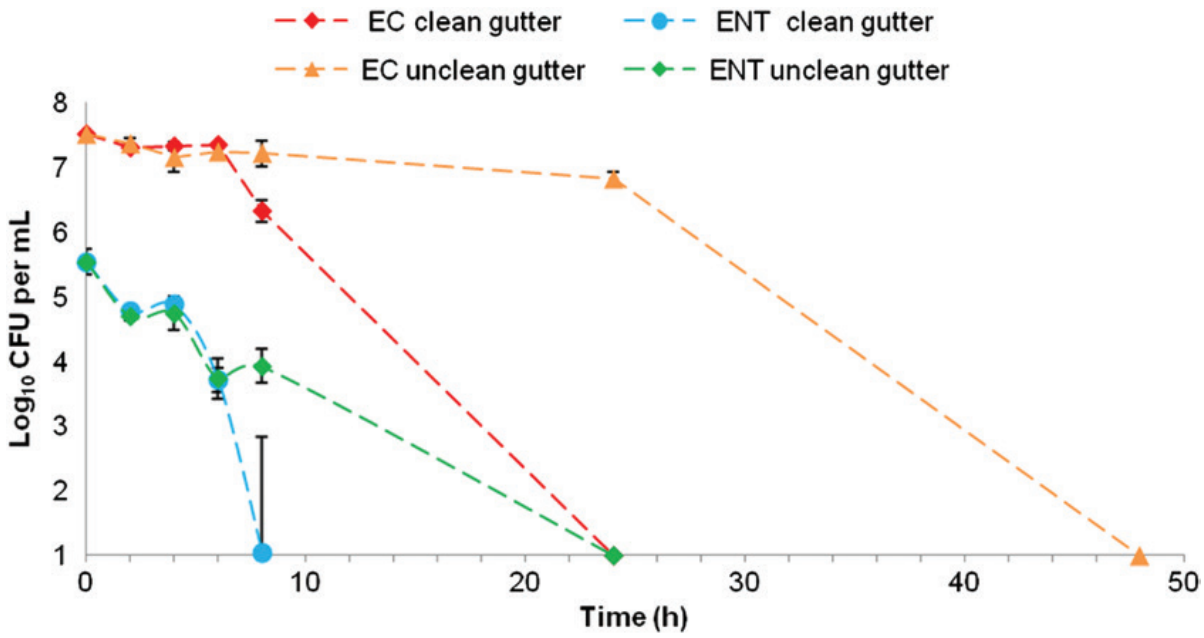


Figure 10.3 Log_{10} (mean ± standard deviation) colony forming units (CFU) of culturable *Escherichia coli* (EC) and *Enterococcus* spp. (ENT) during the course of inactivation in the clean and unclean gutters.

The inactivation rates of faecal indicator bacteria were determined under *in-situ* conditions in the rainwater tank exposed to natural sunlight (Figure 10.4). Here *E. coli* fell below detection limit after 576 h whereas enterococci were detected up to 816 h. Both *E. coli* [$T_{90} = 72$ h (first phase) and 273 h (second phase)] and enterococci [$T_{90} = 38$ h (first phase) and 195 h (second phase)] showed non-linear biphasic inactivation. Significant difference was observed between the T_{90} value of *E. coli* inactivation compared to enterococci (paired t-test, $P = 0.0003$) in the tank water.

In conclusion, faecal indicator bacteria, especially *E. coli*, can survive longer ($T_{90} = 53$ h) on the roof under shade conditions compared to sunlight conditions. This could have an impact on health risks associated with tank water use. If there is a rainfall event after the deposition of faecal matter on a shaded roof, it is highly likely that faecal indicator bacteria and other faecal pathogens could be transported to the tank water. When introduced to the tank, a slower inactivation process may take place ($T_{90} = 38$–72 h). Further research is required to understand the persistence of bacterial and protozoa pathogens on the roof and in tank water in comparison to faecal indicator bacteria because certain pathogens are known to be more persistent in the environment than faecal indicator bacteria.

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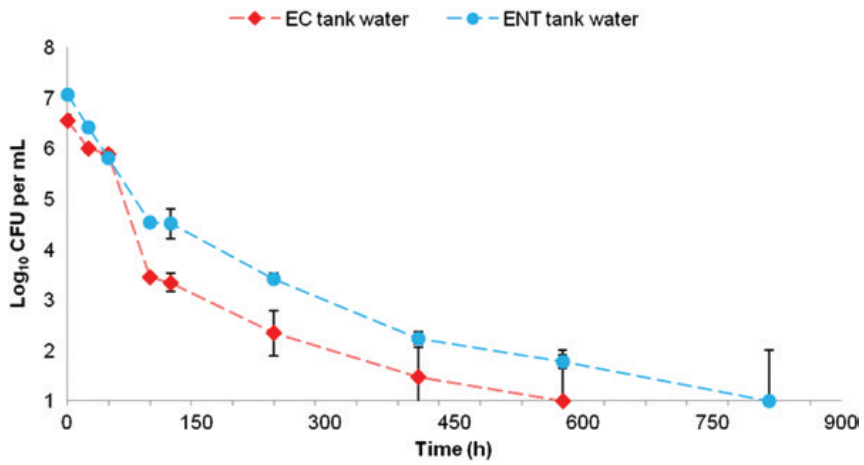


Figure 10.4 Log_{10} (mean ± standard deviation) colony forming units (CFU) of culturable *Escherichia coli* (EC) and enterococci (ENT) during the course of inactivation in the tank water.

10.3 HEALTH RISKS ASSOCIATED WITH ROOF CAPTURED RAINWATER

While most studies relating to RCR have focused on the detection of microorganisms in the tank water samples, there have also been eight case control studies reporting on sporadic gastroenteritis associated with the consumption of untreated tank water (Figure 10.5). The factors that can influence the level of actual risk include the type and numbers of pathogen carried by the infected animals, the time between deposition of faecal matter on the roof and pathogens being flushed into the tank, the size (kL) of the tank, the form of human exposure (consumption from drinking vs. exposure to droplets in the shower or toilet flushing), and the relative inactivation of the different pathogens in the roof to tank ecosystem.

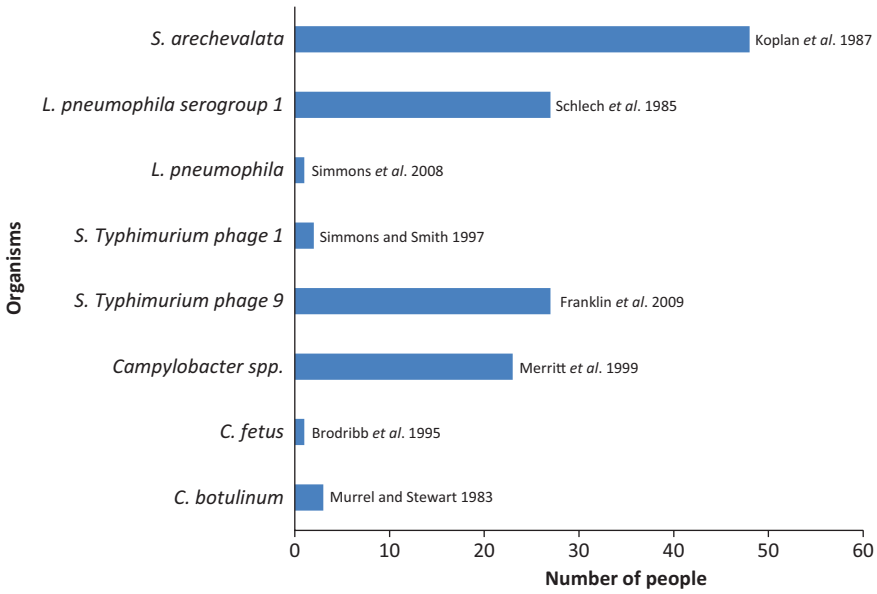


Figure 10.5 Reported cases of illnesses associated with the use of roof-captured rainwater.

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An example of how all these factors can create a human health risk is a *Salmonella arechevalata*-related gastroenteritis outbreak reported by Koplan *et al.* (1978) that occurred among 83 campers (48 positive cases) in Trinidad, West Indies. Epidemiological and bacteriological studies were performed to identify the source of *S. arechevalata* infection. Through patient surveys, food items were ruled out as the source of the gastroenteritis. However, water samples collected from two kitchen taps connected to a RCR system were found to be positive for *S. arechevalata*, although the bacterium could not be isolated from the tank water sample itself. A sanitary survey suggested that rainwater washed faecal matter containing *S. arechevalata* from the roof into the tank, leading to the gastroenteritis outbreak. To further test this hypothesis, a number of intestinal samples were collected from local birds, rodents, and reptiles that were assumed to be the source of the contamination. Somewhat surprisingly, *S. arechevalata* could not be isolated from the faeces of these animals.

Another description of a potential link between pathogens and tank water was an outbreak of three cases of infant botulism in New South Wales, Australia, where *Clostridium botulinum* type B was isolated from soil around one house and in the rainwater tank from another house (Murrell & Stewart, 1983). *Clostridium botulinum* type A was also present in soil, dust from a vacuum cleaner, and the rainwater tanks. The presence of *C. botulinum* spores in the rainwater tanks was suggested as contributing to the occurrence of the infant botulism cases. As a result of this study, consumers with infant children were advised to disinfect water for the first 6 months of the infants' lives.

Another study reported the isolation of *Campylobacter fetus* from a 64 year old patient, which was subsequently linked to the tank water (Brodribb *et al.* 1995). Three sets of blood cultures from the patient were positive for *C. fetus* using PCR. The rainwater was the only source of water supply for this particular household. To confirm the source of infection, a sample of the tank water was tested and *C. fetus* was isolated from as little as 200 mL of water sample. The patient was advised to boil the tank water before consumption, and no further incidence of the illness was reported.

Merritt *et al.* (1999) reported an outbreak of *Campylobacter* enteritis among 23 resort staff in Queensland, Australia where untreated tank water was used as a potable supply. Food was initially suspected as the possible source of infection. However, none of the food samples were positive for the *Campylobacter* spp., but four rainwater tanks were positive for total coliforms and *E. coli*, with particularly high total coliform numbers found in one tank. The authors reported a strong association between gastroenteritis and consumption of water from a dispenser that had probably been filled from one of the contaminated tanks. It was hypothesized that the *Campylobacter* spp. that caused the outbreak may have been introduced into one or more of the tanks by contamination with the faeces of wild animals.

Another reported outbreak of gastroenteritis with a strong link to contaminated tank water occurred in Melbourne, Australia. An outbreak of *Salmonella* Typhimurium occurred at a rural school camp supplied by a rainwater tank (Franklin *et al.* 2008). Twenty seven of 55 students at the camp showed the disease symptoms (gastroenteritis). *Salmonella* (phage type strain DT9) was found in both the faecal specimens of patients and water taps supplying the untreated rainwater used for drinking, indicating a direct link between the tank water and the disease outbreak. Simmons and Smith (1997) also reported the isolation of *S.* Typhimurium (phage type I) from two of four family members who sought medical attention due to gastrointestinal symptoms. The family lived in a beach-side house and used tank water for all household uses. *S.* Typhimurium phage type I and faecal coliforms were isolated from the house's tap water, leading the authors to conclude that tank water was the likely source of infection, although the original contamination source in the tank water could not be confirmed.

An outbreak of Legionnaires' disease in an isolated suburb of Auckland, New Zealand, was linked to tank water. Isolates of *L. pneumophila* serogroup 1 (Lp1) from patient's clinical specimens (one out of four) were identical to the same serogroup of *L. pneumophila* present in the nozzle of a local marina water

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blaster used to clean boats. Sampling of nearby rainwater collection systems revealed that spray from the water blaster had been deposited on the roofs of houses in the local area. The *L. pneumophila* was washed into rainwater tanks, and residents were then exposed through bathroom showers (Simmons *et al.* 2008).

In a reported outbreak of 27 cases of Legionnaire's disease amongst tourists visiting the U.S. Virgin Islands, the infections were thought to have originated from inhalation of *L. pneumophila* detected in the drinking water system of a local hotel (Schlech *et al.* 1985). Case control and microbiological studies were undertaken to identify the mode of transmission. The exact mode of transmission during this outbreak could not be determined, but the potable water was strongly implicated as the most probable cause in the absence of other sources. The hotel obtained its potable water from a RCR system, and the identical serogroup of the *L. pneumophila* isolated from the infected patients was found in the stored tank water, as well as in hot and cold water taps. No further cases of Legionellosis were identified after the hotel water system was chlorinated.

The most recent incidence of RCR-acquired infections was reported in a case control study in Tasmania, Australia, where single variable associations were found between drinking untreated water and cases of infection with *Salmonella mississippi* (Ashbolt & Kirk, 2006). The second highest risk was found to be associated with exposure to untreated tank water.

The above studies strongly suggest that the untreated rainwater may be a causal or contributing factor for gastroenteritis and other illnesses. Several authors highlighted the need for evaluating the actual health risks from drinking untreated tank water (Ahmed *et al.* 2008; Lye, 1992; Simmons *et al.* 2001). An epidemiological study to identify the risk of gastroenteritis among 4 to 6 year old children who drank tank water compared with children who ingested treated mains water in South Australia noted that the consumption of tank water did not increase the level of self reported gastroenteritis relative to mains water consumption (Heyworth *et al.* 2006). The authors concluded, however, that their data could also have reflected a level of acquired immunity among regular users of tank water, and therefore may not reflect the actual risk to the new users. A later study investigated whether drinking untreated rainwater contributed to the incidence of gastroenteritis in the community in Adelaide, Australia (Rodrigo *et al.* 2010). The authors conducted a double-blinded, randomised controlled trial installing sham water treatment units and recorded incidences of gastroenteritis for 12 months in a total of 300 households. The results clearly indicated that consumption of untreated rainwater did not contribute appreciably to community gastroenteritis. However, the generality of the results must be qualified as susceptible and immunocompromised persons were not included in the study.

Dean and Hunter (2012), in a search of relevant bibliographic databases, also reported that there was no significant difference in health risks between RCR and water supplies. However, their analysis only included a small number of studies. In contrast, in New Zealand, numerous cases of campylobacteriosis have been associated with rainwater collection systems (Eberhart-Phillips *et al.* 1997). A case control study found a strong association between gastrointestinal diseases caused by *Campylobacter* spp. and the consumption of tank water. It was hypothesised that the RCR systems in their study had been contaminated by birds roosting on the roofs.

It is also probable that incidences of gastrointestinal diseases associated with tank water are underreported. It is generally accepted that only a portion of people with gastroenteritis seek medical attention, and most faecal specimens (if collected) from patients are not tested for the presence of pathogens. In Australia, it has been estimated that only 8% to 11% of *Campylobacter*- and *Salmonella*-related food-borne gastroenteritis cases are reported (Hall *et al.* 2006), whereas in the United States, it has been estimated that only 10% to 33% of water-related gastroenteritis is reported (Frost *et al.* 1996). These statistics suggest that any gastroenteritis cases from ingesting tank water would have at least similarly low reporting levels, if not even lower.

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Another limitation is that cases of gastroenteritis from drinking untreated rainwater could also be masked by the background levels of gastroenteritis from other sources, such as consumption of food and community-based infections. The most credible epidemiological study to date reported that the consumption of tank water did not increase the risk of gastroenteritis compared to consuming mains water (Heyworth *et al.* 2006; Rodrigo *et al.* 2010). However, such results should be interpreted with care due to the lack of sensitivity of the epidemiological tool to detect gastroenteritis (Craun *et al.* 2004; Hrudey & Hrudey, 2004). It has been estimated that to detect illness at an annual rate of 100 cases/10,000 people/year would require samples of 416,000 participants (Eisenberg *et al.* 2006). Considering the high costs and time required, epidemiological studies of infection from sources such as RCR may not be practical for the sensitive detection of gastroenteritis in the community.

10.3.1 Quantitative Microbial Risk Assessment to determine health risk from the use of roof-captured rainwater

Risks associated with contamination of RCR may be difficult to document using epidemiological tools since infections are likely to affect a small number of individuals. More comprehensive approaches are needed to examine relative risks and risk-reduction strategies. One such approach is Quantitative Microbial Risk Assessment (QMRA), which can examine and account for various environmental biases associated with environmental trials (Enger *et al.* 2012). QMRA is a four-step probabilistic tool for estimating the human health risk associated with defined scenarios from exposure to specified pathogens (NRC, 1983). The four steps are: (i) hazard identification; (ii) exposure assessment; (iii) dose – response assessment; and (iv) risk characterisation. Although, QMRA models have been used to quantify disease risk in many contexts, only a few studies have attempted to identify the inherent risk of infection associated with the drinking and non-potable uses of tank water. One such study was undertaken by Fewtrell and Kay (2007), who investigated the risk of infection of *Campylobacter* from toilet flushing with tank water in homes in the United Kingdom. A QMRA estimate was performed on *Campylobacter* infection via ingestion of aerosols. The outcomes of this QMRA estimate concluded that any risk from flushing the toilet with captured rainwater would be well within the acceptable range of 1×10^{-6} DALYs (disability-adjusted life years) per person per year.

QMRA was also used to quantify the risk of infection associated with the exposure to zoonotic pathogens from drinking and non-potable uses of tank water in South East Queensland, Australia. Ahmed *et al.* (2010b) applied QMRA analysis to estimate the health risk from the use of roof-captured rainwater as potable or non-potable water. The aims of this research study were to: (i) to quantify the number and frequency of occurrence of *Salmonella*, *G. lamblia*, and *L. pneumophila* microorganisms in 214 tank water samples from 82 rainwater tanks in South East Queensland by using qPCR based methods; and (ii) to apply QMRA analysis in order to estimate the risk of infection from exposure to these pathogens found in RCR. The uniqueness of this study stems from the fact that instead of measuring faecal indicators, pathogens capable of causing illness were quantified and this ingested dose information was combined with QMRA to assess the human health risk of using RCR for potable and non-potable end uses.

The authors used qPCR to obtain the numbers of potential pathogens in rainwater tank samples. A subset of samples were also analysed to identify the occurrence of pathogens in tank water samples. The authors used a four-step QMRA analysis for estimating the human health risk associated with defined scenarios involving exposure to specified pathogens. The pathogen number in tank water and the volume ingested/inhaled by a person are estimated. Because of a lack of information regarding the proportion of PCR-detected cells and cysts that are viable, it was assumed all the PCR-detected cells and cysts were viable and capable of causing infections (conservative approach). To estimate the possible pathogen dose received

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by an individual, the likely infection routes appropriate to each pathogen must be considered. Considering possible routes, the infection risk associated with each of a total of six scenarios was estimated.

For salmonellosis and giardiasis risk, the scenarios were (i) liquid ingestion due to drinking of rainwater on a daily basis, (ii) accidental liquid ingestion due to garden hosing twice a week, (iii) aerosol ingestion due to showering on a daily basis, and (iv) aerosol ingestion due to hosing twice a week. For legionellosis risk, the scenarios were (i) aerosol inhalation due to showering on a daily basis and (ii) aerosol inhalation due to hosing twice a week. The volumes ingested and inhaled were extracted from relevant literature. An exponential dose-response model was used for *G. lamblia*, while for *Salmonella*, a beta-Poisson dose response relationship was used. Finally the risks were characterized by combining dose-response assessment and the probability of infection (expressed as likely numbers of infections per 10,000 persons per year) for the urban South East Queensland community, and comparison with an arbitrary but commonly accepted risk level of one extra infection per 10,000 persons per year.

Of the 214 samples tested during phases one and two, the *Salmonella* spp., *G. lamblia* and *L. pneumophila* were detected in 23 (10.7%), 21 (9.8%), and 12 (5.6%) rainwater samples, respectively. The numbers of *Salmonella* spp., *G. lamblia* and *L. pneumophila* in quantifiable samples ranged from 65 to 380 cells/L, 0.6 to 3.6 cysts/L, and 60 to 170 cells/L of water, respectively. The risk of infection from *Salmonella* spp., *G. lamblia*, and *L. pneumophila* associated with the use of rainwater for showering and garden hosing was calculated to be well below the threshold value of one extra infection/10,000 persons/year in urban South East Queensland. However, the calculations for infection based on the 'worst-case' assumptions indicated that if undisinfected rainwater were ingested by drinking, then the infection incidence is expected to range from 9.8 to 54 (*Salmonella* spp.) and from 20 to 130 (*G. lamblia*) cases per 10,000 persons/year in urban South East Queensland per year (Table 10.7).

Table 10.7 Infection risks for individuals exposed to contaminated tank water for risk scenarios determined using a QMRA analysis of 214 water samples from 82 rainwater tanks in South East Queensland.

Pathogen exposure and risk scenario	Range of infection risk/10,000 people in South East Queensland from a single event	Range of infection risk/year (no./10,000 people/year)
***Salmonella* spp.**		
Liquid ingestion via drinking	5.4×10^{-1}–2.9×10^{0}	9.8×10^{0}–5.3×10^{1}
Liquid ingestion via hosing	3.0×10^{-3}–1.5×10^{-2}	1.0×10^{-2}–8.0×10^{-2}
Aerosol ingestion via showering	1.0×10^{-3}–5.0×10^{-3}	1.9×10^{-2}–1.0×10^{-1}
Aerosol ingestion via hosing	5.0×10^{-6}–2.9×10^{-5}	2.6×10^{-5}–1.5×10^{-4}
G. lamblia		
Liquid ingestion via drinking	1.1×10^{0}–6.9×10^{0}	2.0×10^{1}–1.3×10^{2}
Liquid ingestion via hosing	5.0×10^{-3}–3.4×10^{-2}	3.0×10^{-2}–1.8×10^{-1}
Aerosol ingestion via showering	2.1×10^{-3}–1.3×10^{-2}	3.9×10^{-2}–2.4×10^{-1}
Aerosol ingestion via hosing	1.0×10^{-5}–6.5×10^{-5}	5.3×10^{-5}–3.3×10^{-4}
L. pneumophila		
Aerosol inhalation via showering	1.4×10^{-4}–4.0×10^{-4}	2.6×10^{-3}–7.3×10^{-3}
Aerosol inhalation via hosing	4.0×10^{-4}–1.1×10^{-3}	2.1×10^{-3}–5.8×10^{-3}

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One major limitation of the health risk estimates presented in the study is that PCR method does not provide information regarding the viability and infectivity of detected pathogens, which is critical for QMRA analysis. In the absence of such data, the authors assumed that 100% of the PCR-detected cells and cysts are viable and infective. This assumption is likely to overestimate the risk of infection, as 100% of the PCR-detected cells and cysts may not be viable. However, the overestimation of risk could be preferable to an underestimation obtained via culture-based methods.

L. pneumophila at the levels detected in the RCR samples, did not present a threat for uses of tank water as potable water. Uses of the tank water as non-potable water also presented no unacceptable threat to human health at the pathogen numbers detected.

This study concluded that the risk of infection from *G. lamblia* and *Salmonella* spp. associated with the use of rainwater for bi-weekly garden hosing was below the acceptable threshold value of one extra infection/10,000 persons/year. However, the estimated risk of infection from drinking the rainwater daily was 20 to 130 (for *G. lamblia*) and 9.8 to 54 (for *Salmonella* spp.) infections/10,000 persons/year. Both of these risk assessments are well above the acceptable guideline levels outlined in the Potable Reuse section of the Australian Guidelines for Water Reuse (NRMMC–EPHC–NHMRC, 2008).

Nonetheless, the overall predicted health risk appeared to be much higher than the reported incidences of giardiasis in the community where the study was undertaken. The incidences of these diseases are 5.7 cases of salmonellosis per 10,000 people in Queensland and up to 5 cases of giardiasis per 10,000 people in other Australian states over the past 10 years (noting that giardiasis is not a notifiable disease in South East Queensland). A number of explanations for this discrepancy are possible. There is a naturally high incidence of gastroenteritis in the community (e.g., 8000 cases per 10,000 people per year), which may mask the actual disease (Hellard *et al.* 2001). Before the disease can be reported in the Notifiable Diseases Surveillance System Database, it must first be identified, and not every individual will seek medical attention if the illness is mild and lasts only for a few days. Consequently, the incidence of disease indicated in the Notifiable Diseases Surveillance System Database is at best a minimum value and may be substantially underestimating actual disease incidence.

The methodology used to estimate health risk could have inflated the risk calculated due to the assumption of 100% of pathogen cells or cysts being viable and infective. In fact, a significant proportion of PCR detected cells or cysts may have originated from nonviable organisms. The QMRA also did not take into account households that used effective disinfection treatment of rainwater before using it as potable water. Another factor is the possibility of individuals acquiring immunity to certain pathogens due to frequent exposure. However, to counterbalance this, no attempt was made to include the greater infection risk to the elderly or immunocompromised for a given dose, since the dose-response relationships were based on healthy adults, and these relationships were applied uniformly across the population. There are also uncertainties about the dose-infection response relationship and its relationship to illness response. But perhaps more importantly, there were also uncertainties in the proportion of time that pathogens occurred in the tank due to the limited frequency of the bimonthly sampling regime.

The authors noted that further work is needed to improve the assumptions made in the analysis, such as the proportion of gene copies that represent both viable and infective organisms, since quantitative PCR (qPCR) does not provide information regarding viability or infectivity. In addition, longitudinal monitoring of the pathogens concentrations over about a year are needed to confirm or otherwise the assumption of continuous pathogen presence used in the model. Nevertheless, until more data become available to reduce some of these uncertainties, the results indicate that it would be prudent to disinfect RCR, such as by the installation of a UV disinfection unit, boiling, or other forms of disinfection.

Lim and Jiang (2013) challenged the current U.S. EPA acceptable risk benchmark (<1 case/10,000 persons/year) by quantifying the microbial risks associated with the consumption of domestic tank

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water-irrigated produce (lettuce, cucumbers and tomatoes). Their results showed that the lettuce presents the highest risk followed by tomato and cucumber. They found that the annual infection risks are very likely to exceed the U.S. EPA risk benchmark (1 infection/10,000 persons) by one order of magnitude. de Man *et al.* (2014) performed a QMRA using *L. pneumophila* as a target pathogen to quantify the risk of infection for using RCR as source water for splash parks. The results indicated that using rainwater as source water for splash parks may pose a health risk.

These studies show that health risk analyses is an important step in aiding the use of RCR, but they are currently restricted by the lack of comprehensive work on the prevalence of pathogens in tank water. Improved levels of available data would enable more accurate calculations of the level of risk and allow an assessment of the required levels of reductions in pathogen numbers for different end uses (drinking vs. non-potable uses). This can then enable appropriate treatment measures such as filtration and ultraviolet disinfection to be undertaken to reduce the risk of infection from tank water (Jordan *et al.* 2008).

10.4 CONCLUDING REMARKS AND RECOMMENDATIONS

The review of the published literature combined with specific case studies in South East Queensland suggest that the microbial quality of RCR may be of much lower quality than commonly perceived. On the basis of the reported case studies, it appears that the microbial quality of RCR is strongly influenced by the season, the number of dry days preceding a rainfall event, animal activities on and around the roof, geographical location, and other exposure factors (Lye, 2009; Kus *et al.* 2010). Microbial assessment should involve the analysis of tank water for actual pathogens, not just the faecal indicator bacteria. The limited data in the literature have predominantly indicated that the commonly used indicators such as faecal coliforms and *E. coli* may not be suitable indicators of the public health risk from a microbial point of view due to their often poor correlation with pathogens (Ahmed *et al.* 2010).

Little information is currently available on the number of enteric and opportunistic microbial pathogens that can be present in RCR. The majority of the studies reported in the literature assessed the quality of the tank water on the basis of the presence or absence of specific microbial pathogens, with little information available regarding the actual numbers of enteric and opportunistic pathogens. Detection and quantification of pathogens using culture based methods and PCR-based assays both have their limitations. qPCR-based assays quantify DNA from both viable and non-viable cells of a target organism and therefore yield higher numbers compared to culture-based methods. On the other hand, culture-based methods may underestimate the numbers of a target microorganism due to the presence of viable but non-culturable cells. However, the overestimation of risk could be preferable than the underestimation via culture based methods for scenarios where the tank water is used for drinking, as it indicates that a contamination event has occurred. Further studies, including longitudinal surveys of rainwater tanks would be required to shed some light on pathogen frequency of occurrence in tank water samples.

Several case control studies have established links between gastroenteritis and consumption of untreated tank water. However, these reported outbreaks tended to involve small numbers of individuals, and the reported illnesses were often related to use of a common tank (Brodribb *et al.* 1995; Franklin *et al.* 2008; Murrell & Stewart, 1983). On the other hand, other studies could not identify tank water as a source of infection, and therefore, could only hypothesize that tank water was the likely source of infection via circumstantial evidence (Koplan *et al.* 1978; Merritt *et al.* 1999; Simmons & Smith, 1997). It should be noted that most of these case control studies used culture-based methods to establish a link between tap water and faecal specimens from patients.

Additional studies that focus on the collection and matching of pathogenic strains from faecal specimens from self-reported incidences of gastroenteritis, and from potential sources such as tap water and tank

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water using sensitive molecular typing methods would provide valuable information to determine if there is a direct link between gastroenteritis and consumption of tank water. This could be more practical than a comparable epidemiological study due to the complexity and costs of such epidemiological studies, and the fact that the most incidences of gastroenteritis remain unreported. The use of a QMRA is a critical tool to assess overall health risks associated with tank water uses, particularly drinking.

The public health risks are likely to be higher if the untreated tank water is used for drinking compared to other non-potable uses. Our research findings indicate that certain householders had under-sink filtration installed. However, these systems did not appear to be effective in removing faecal indicator bacteria and potential zoonotic bacterial pathogens, because of poor maintenance or inappropriate choice of treatment device for the pathogens of concern.

Very little has been documented about the inactivation rates of faecal indicator bacteria and pathogens on the roofs, in the gutters and in the tank water. If there is a rainfall event within a week after the deposition of faecal matter on the roof, it is highly likely that faecal indicator bacteria would be transported to the tank water. When introduced into the tank, their 90% reduction may take 2–10 days. Further research is required to understand the persistence of bacterial and protozoa pathogens in tank water because certain pathogens are known to be more persistent than faecal indicator bacteria. The faecal contamination of RCR appears to be more common in improperly designed systems, as well as systems that are not well maintained. We recommend that all RCR systems should be appropriately maintained, including the cleanliness of the systems before rainfall events. Roofs and gutters especially should be cleaned frequently, whilst the receiving tanks should be cleaned at least two times per year to improve the quality of the water. The roof should be kept clear of overhanging trees, which may provide access for wild animals which may harbour high numbers of bacterial and protozoa pathogens. It is recommended that rainwater should be treated with effective treatment procedures such as filtration, ultraviolet disinfection or simply boiling the water prior drinking.

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Chapter 11

Cluster-scale rainwater harvesting

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ABSTRACT

Rainwater tanks have been adopted in cities as a non-potable water source that complements mains drinking water supply. The uptake of rainwater tanks in countries such as Australia has been driven by the need to reduce demand for drinking water, whilst also taking a more integrated approach to urban water management. Rainwater harvesting can provide a fit-for-purpose water source that minimises the impact of the urban water cycle on the local environment and receiving waters. Rainwater tanks are typically installed at the household scale for non-potable water source uses such as toilet flushing, laundry and garden irrigation in urban areas. However, this chapter reports on the design principles, case studies and literature of cluster-scale rainwater harvesting. The cluster-scale rainwater harvesting system collects rainwater from multiple household roofs, and then transports it by gravity to a communal storage tank. After treatment and separate storage, a dedicated pressurised water distribution system supplies treated rainwater to the individual homes for uses that could include potable. Cluster-scale rainwater harvesting can offer multiple benefits, including: economies of scale for capital costs, reduced land footprint on individual allotments, centralised treatment and disinfection, and flexibility in matching supply and demand for different sized households. Cluster-scale harvesting also offers the opportunity to formalise management and maintenance of local water sources, which address some of the serious limitations of household-scale harvesting.

Keywords: rainwater harvesting; decentralised systems; community infrastructure; integrated urban water management.

11.1 INTRODUCTION

Centralised water supply systems in cities have traditionally relied upon surface water catchments and groundwater to meet demand, however a burgeoning urban population has created the need to diversify the water supply source mix. These diversified water supply systems, which include rainwater harvesting systems, have the purpose of reducing pressure on drinking water supplies, as well as developing resilience

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to climate change and variability (Sharma *et al.* 2005; Ruth *et al.* 2007; Moglia *et al.* 2011). In Australia, governments have encouraged the adoption of rainwater harvesting systems through financial incentives and regulations. These household rainwater systems are secondary to mains drinking water supply, and are mostly used for non-potable purposes such as toilet flushing, laundry, and external uses including garden irrigation. Rainwater harvesting is part of a strategy to diversify water supply sources by reducing reliance on traditional water catchments and centralised infrastructure. They can also offer benefits to other parts of the water cycle, including: moderating peak stormwater runoff, reducing discharge of nutrients to receiving waters, and improving ecological health (Villarreal & Dixon, 2005; Farreny *et al.* 2011; Kim & Furumai, 2012), as outlined in more detail in Chapter 13.

In Australian cities, the most common form for rainwater harvesting has been household-scale rainwater tank systems. However, there are a number of limitations with this type of system including a lack of householder understanding of health risks (Domènech & Saurí, 2011) and inadequate maintenance that can result in supply failure (Moglia *et al.* 2013). Furthermore, cities around the world are moving to a more compact urban form (Chhetri *et al.* 2013). This urban densification has implications for rainwater harvesting as the land area for storage on individual allotment becomes limiting. This raises the need to consider alternative configurations for local water harvesting, such as communal storages on public land. The concept being tested in this chapter is that cluster-scale rainwater and stormwater systems system can provide improve reliability, performance and system management, relative to household-scale harvesting, in many development contexts.

Geisinger and Chartier (2005) referred to cluster-scale systems (in discussing decentralised wastewater) as servicing a group of dwelling or businesses that are relatively close together. The distinction between a cluster-scale harvesting scheme and a traditional large-scale regional scheme is ill-defined. We defined a Cluster-scale Rainwater Harvesting (CSRH) system as any system that supplies more than one user. This may be a few households or businesses that have a communal system, but it also includes systems at a scale of a small suburb. For example, rainwater runoff could be collected from the roof area of a few dozen households, stored centrally, and then reticulated back to households. Figure 11.1 provides a schematic of a cluster-scale rainwater harvesting system.

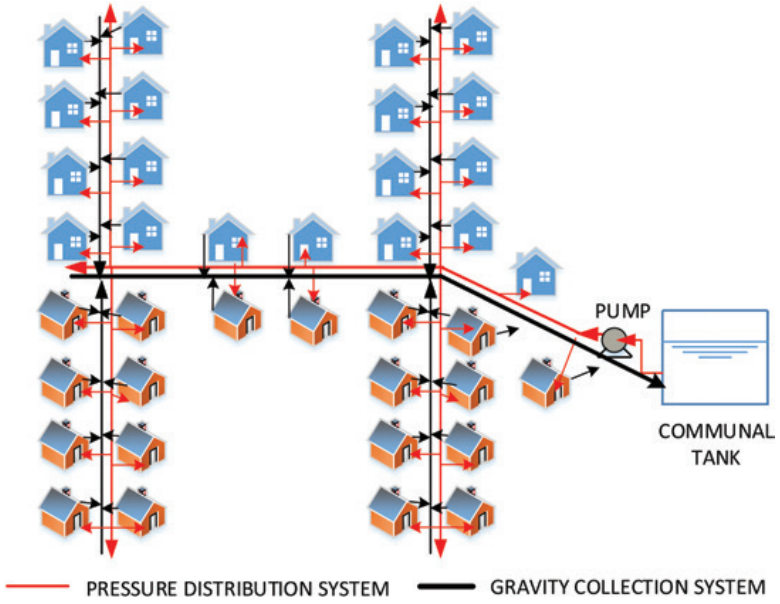


Figure 11.1 Schematic of a cluster-scale rainwater harvesting system.

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The objectives of this chapter are to explore the potential benefits of harvesting, using and managing a rainwater system amongst a group of households relative to a single household. Following this, the chapter will also identify the development contexts where a CSRH scheme may be more suited compared to a household scheme. Suitability criteria include: rainwater yield, reliability of supply, water quality that is fit-for-purpose, impact on stormwater management, community acceptance, suitability to urban form, and appropriateness to management capacity and regulatory framework.

CSRH systems can be used in two development contexts. They can be used in areas that don't have access to reticulated mains water supply. CSRH systems that include treatment and back-up supply, can allow medium density developments in peri-urban and rural communities that don't have access to mains water supply. CSRH systems can also be used to provide a non-potable water supply in urban areas with traditional mains water supply. This will reduce demand for potable water as well as provide a water source for uses such as irrigation that is not subject to water restrictions during drought conditions.

In this chapter, firstly we present a literature review that highlights Australian and international experiences with CSRH. This literature review provides insights on the development contexts where CSRH has been applied, the drivers for their adoption, and the impediments for greater mainstream adoption. Four Australian case studies of CSRH are then presented, followed by a modelling study that compares cluster-scale approaches to household-scale rainwater systems. The chapter then explores the principles for the design of CSRH systems and the management implications, including identifying suitable management models.

11.2 LITERATURE REVIEW

11.2.1 Examples of cluster-scale rainwater harvesting

While literature on the application of rainwater harvesting at the scale of a single household is extensive, there is a dearth of reported studies on CSRH schemes. Makropoulos and Butler (2010) noted that the paucity of documented studies has lead to knowledge gaps such as context-independent characteristics that can be used to predict likely system performance and cost of CSRH systems. Sharma *et al.* (2009) presented a framework that can be used to assess the feasibility of alternative water servicing configurations, such as CSRH systems. This literature review focuses on the few reported example of CSRH systems.

Farreny *et al.* (2011) compared the performance and cost-effectiveness of four different configurations for rainwater harvesting in a dense urban area of Barcelona. The four different configurations included household-scale rainwater systems for both a retrofit and new development, and *neighbourhood-scale* rainwater systems for both a retrofit and new development. Their results showed that a neighbourhood-scale rainwater system for new developments was the most cost-effective as it did not require pavement disturbance and re-installation (Farreny *et al.* 2011). The economic feasibility of the neighbourhood-scale system was also strongly influenced by the housing density of the development. This supports the findings from Roebuck *et al.* (2011) who noted that rainwater systems at the scale of a single household are rarely cost-effective when all costs are taken into account.

Figtree Place is a medium density (45 dwellings per hectare) development in Newcastle, Australia. Figtree Place was designed to be a water sensitive development, which included CSRH systems that were used to satisfy demand for hot water and toilet flushing. Each CSRH system connected between four and eight dwellings. Coombes *et al.* (2000) described a detailed monitoring program undertaken to quantify the performance of the CSRH system in terms of water quality, mains water savings, stormwater management, costs and community acceptance. The study found that household hot water systems combined with other passive treatment processes in the rainwater tank (such as settling), effectively

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treated harvested rainwater to the microbiological standard required by the Australian Drinking Water Guidelines (National Health and Medical Research Council, 2011). The CSRH system also reduced demand for mains drinking water by around 60% (Coombes *et al.* 2000), and rainwater tanks as part of a water sensitive urban design approach reduced infrastructure costs by around 20% when compared to traditional stormwater practices.

Cook *et al.* (2012) presented a case study of a commercial high-rise building in Brisbane, Australia, where a CSRH system was used for toilet flushing and amenity garden irrigation. Monitoring studies showed that the system provided non-potable water with moderate reliability, but that the system yield was constrained by installation faults. Cook *et al.* (2012) highlighted the fact that because the rainwater system was not part of the building management system, faults were not identified and fixed in a timely manner, resulting in the system being offline for extended periods of time. Wannon Water provides an example of CSRH system that is integrated with the existing mains water supply system. This example and other case studies are presented in more detail in Section 11.3.

11.2.2 Impediments and benefits

The impediments faced by developers in achieving mainstream adoption of CSRH schemes are similar to those for decentralised wastewater systems. However there are some impediments that are specific to CSRH schemes.

The main impediments for mainstream adoption of alternative urban water systems are related to social and institutional factors, rather than technical factors (Brown *et al.* 2007). In particular, the inconsistency and fragmented nature of governance, regulations, and guidelines associated with water sensitive urban design (WSUD) and integrated urban water management (IUWM) are significant impediments (Tjandraatmadja *et al.* 2008; Sharma *et al.* 2010; Brown & Farrelly, 2009). This fragmentation has been attributed to the 'silo' administrative/governance structures of water authorities, local government, government departments and private industries that have evolved to deliver conventional water services (Mitchell, 2004). Brown and Clarke (2007) summarised the main institutional impediments to adopting WSUD (of which CSRH is a sub-component) as: insufficient skills and knowledge, organisational resistance, lack of political will, limited regulatory incentives, and unsuitable institutional capacity.

The skills and knowledge base required to adequately maintain and operate a CSRH scheme differ from those needed for conventional urban water systems. Moreover, management of decentralised water assets provides a challenge to the centralised management paradigm. There is also the need for the development of appropriate standards and guidelines to assist understanding by professions such as engineers and contractors and trades such as plumbers (Roy *et al.* 2008; US EPA, 2013).

As a cluster-scale approach to harvesting runoff is relatively novel in Australian cities, there is a lack of documented experience as to how a community-based harvesting scheme is likely to perform (Makropoulos & Butler, 2010). Well-studied projects such as Figtree Place (Coombes *et al.* 2000) provided a rich source of data, but there is the need for other studies in different development contexts. The paucity of demonstration projects can impede the development of suitable guidelines and effective regulatory frameworks (Brown & Farrelly, 2009). Demonstration projects that incorporate validation through ongoing monitoring can provide relevant data on environmental benefits (water quality improvement, flow management), associated risks, life cycle costs, externalities, adequacy of engineering standards and guidelines, and energy consumption (Fletcher *et al.* 2008; Domènech & Saurí, 2011).

The broader adoption of CSRH can also be impeded by a perceived lack of direct economic benefits (US EPA, 2013). Fane and Mitchell (2006) highlighted that decentralised water supply systems can be considered more expensive due to 'unfair' assessments of sunk and avoided infrastructure costs. Whilst

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comprehensive studies have been conducted on the cost-effectiveness of individual rain water tanks, see for example Coombes (2002) and Hall (2013), very few economic studies have been conducted on CSRH systems (Gurung *et al.* 2012; Gurung & Sharma, 2014). An exception is the work of Gurung *et al.* (2012) who undertook a conceptual analysis to determine the relative economies of individual rainwater tanks versus cluster-scale schemes, assuming a flat topography and a density of 20 dwellings per hectare. This analysis used Net Present Value (NPV), to assess the servicing from four to 576 homes with a CSRH scheme, and found around 200 homes as the most economic number on a per house basis. Nonetheless, Gurung *et al.* (2012) concluded that individual tanks cost less per household ($8,568) than a 200 home communal rainwater tank system ($10,180). The analysis also identified that the collection and distribution network costs of the CSRH system had dis-economies of scale; with the more houses connected, the higher the costs. However, this was slightly offset by economies of scale for the storage tanks. Changing the scenario from a steep slope to a gently sloping topography substantially reduced the NPV of the communal system. This was due to reduced pipe trenching and collection pumping costs due to shallower collection pipes depth and the use of a gravity fed system. We argue that although the cost of communal rainwater tank systems can be higher than the individual rainwater tanks, the communal systems have operational and management advantages, discussed later in this chapter. Chapter 12 contains more details on the economics of rainwater tank systems.

The case for the adoption of cluster-scale harvesting systems, relative to household-scale rainwater harvesting, is based on the following suppositions:

- That cluster-scale rainwater harvesting offers economies of scale by sharing the capital and operational expenses of the system among multiple users;
- That compared to household-scale rainwater tanks, there are better opportunities to balance supply and demand among households with different demand patterns; and
- The scale of cluster-scale rainwater harvesting can make it financially feasible to have formal arrangements in place for maintenance and operation, thus over-coming one of the major difficulties of maintaining household-scale rainwater harvesting systems.

The above factors are explored in more detail in this chapter.

11.3 CASE STUDIES OF CLUSTER-SCALE HARVESTING

The following section discusses four examples of cluster-scale rainwater harvesting and reuse. These Australian examples are situated in a range of development contexts and highlight the range of drivers for the adoption of CSRH schemes.

11.3.1 Capo di Monte

Capo di Monte (CDM) is a 46 home development at Mount Tambourine located in the hinterland ranges of the Gold Coast, South East Queensland. The development lies outside of the area serviced by municipal water and wastewater services, so for the development to proceed, it had to build a decentralised water and wastewater system. The communal rainwater system was designed to meet internal household uses that usually require potable water quality: kitchen, bathroom and laundry. A wastewater recycling scheme (described in Sharma *et al.* 2012; 2013) is used to satisfy non-potable demands: toilet flushing and garden irrigation. A groundwater bore is used to supplement both systems in times when demand is greater than can be supplied from harvested rainwater. The layout of the rainwater collection system and the location of communal rainwater storage tanks are shown in Figure 11.2.

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Figure 11.2 Capo di Monte cluster-scale rainwater harvesting system (Courtesy: Bligh Tanner Consulting Engineers, Brisbane, Australia).

CDM was planned as a retirement village, therefore residents are mostly 60 years or older and retired. The CDM population is 75 people, with an average household occupancy of 1.65 persons compared to a Brisbane average of 2.6 persons per dwelling. The Mount Tambourine weather station recorded an average annual rainfall of 1,318 mm/year over the period 1982 to 2005. Analysis of the rainfall record showed a pattern of relatively wet years with up to 2,000 mm, interspersed with drier years with rainfall of around 1,000 mm.

The communal rainwater system collects roof runoff through a network of household downpipes that feed into two main collector pipes which transfer the water by gravity into two 200 kL storage tanks. The 200 kL communal tanks are operated to have an active volume of 100 kL each, with 100 kL reserved for emergency fire-fighting capability, in accordance with state regulations. The total connected roof area is around 10,700 m^2, with houses having an average roof area of 222 m^2, and the community centre providing 488 m^2 of connected roof area.

A water treatment plant, comprising sand filtration, UV sterilisation and chlorination sends water to a 40 kL balance tank for subsequent pressurisation and distribution of *potable water* to each house and the small community centre which includes a swimming pool. A local bore provides supplemental water in times of insufficient rainfall or excess demand. The water supply components of the communal rainwater system are shown in Figure 11.3. The system is managed by an appropriately trained person who reports to the Body Corporate entity, which is legally responsible for management of all communal components of the development including sewage treatment, public open space irrigation, gardens and so on.

Monitoring studies detailed in Cook *et al.* (2012) demonstrated that the cluster-scale harvesting provided a reliable water source, albeit with an energy penalty. The rainwater system met around 80% of the potable demand (43 kL/hh/year) during the 4-year monitoring period. However, the energy required to provide this water was around 4 kWh/kL, with 75% of the energy use required for pressurising the reticulation system. Whilst the steeply sloping topography of CDM influenced this high specific energy

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use, Cook *et al.* (2012) found that the major cause was the oversized pump installed. A reduction in the pump size, while still meeting head and flow requirements, could reduce the specific energy for pumping by around 50%.

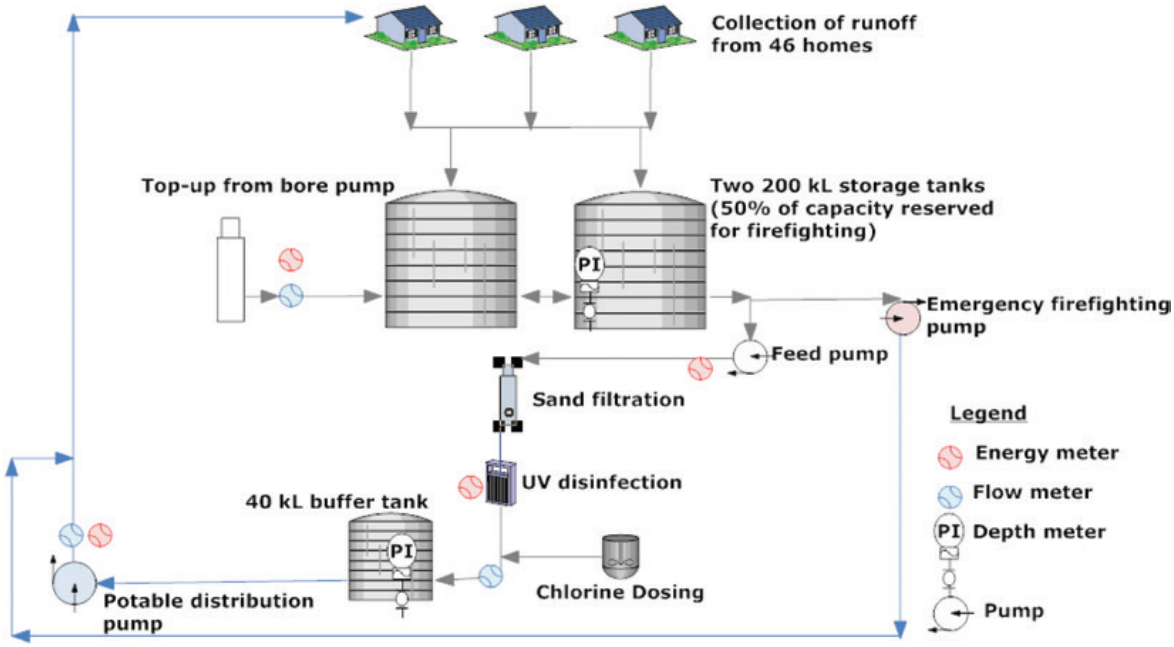


Figure 11.3 Capo di Monte hydraulic circuit, and water and energy meters.
Source: Cook *et al.* 2012, pg. 7.

11.3.2 Wannon water's roof water harvesting project

Wannon Water, a water utility in western Victoria, initiated an innovative project to harvest roof runoff from a housing estate to augment Warrnambool's drinking water supply. The harvesting scheme is located in an urban growth corridor of Warrnambool. The harvesting scheme was piloted for a 142 lot subdivision and it is envisaged that 3,000 homes will connected at full development.

The roof water harvesting scheme involved the construction of a dedicated network of roof water collection pipes. These collector pipes feed into a 2,000 metre trunk main, which transfers the water by gravity to the town's raw water storage. This impoundment primarily stores water collected from surface water sources such as the nearby Gellibrand River. The harvested roof water mixes with untreated stormwater in the basin (sourced by rural catchment runoff) prior to treatment at the Warrnambool Water Treatment Plant. The treated water is then supplied to the city's potable water reticulation system. Initial estimates indicated that (treated) rainwater harvested from the 142 homes would meet 75% of the annual water demand of these properties (Wannon Water, 2011).

The roof water harvesting scheme was identified after Wannon Water prepared a water supply and demand strategy, with a planning horizon of 50 years. This strategy identified that projected growth in demand for water could not be met by existing water supply sources, which were also sensitive to likely climate change impacts. A high level analysis was undertaken to estimate maximum yield and compare relative costs of water supply alternatives. Based on this analysis, the preferred options were the roof water harvesting scheme and the development of new groundwater resources (Table 11.1).

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Table 11.1 Comparison of wannon water's selected augmentation options from the water supply and demand strategy.

Description of option	Estimated max yield (ML/yr)	CO_2 emissions (kg/ML)	Cost ($/ML)
Desalination of seawater	5000	2.66	$837
Desalination of groundwater	2000	2.29	$773
New groundwater resources	250–3400	0.26–3.47	$105–$246
Recycled water scheme from the wastewater treatment plant delivered by a dual reticulation network	488	Not calculated	$1,770
Winter flow harvesting from local river	1600	5.73	$487
Roof water harvesting form subdivisions via a separate pipe network	300	0	$240

Source: Wannon Water, 2012

Individual rainwater tanks had much higher operating costs than the regional roof water harvesting scheme due primarily to pumping costs from pumping energy, and pump maintenance and replacement. Major advantages at Wannon Water were that gravity could be used to transfer collected rainwater water to the storage basin, and existing infrastructure (storage basin, treatment plant and reticulation pipe network) used to reduce capital costs compared to schemes operating a dual pipe reticulation network (Wannon Water, 2012).

Also, it was considered that regional roof water harvesting would have a lower risk profile than individual rainwater tanks. This was because water harvested from the communal roof water scheme undergoes rigorous treatment at the regional centralised water treatment plant prior to being supplied to residents. This does not occur on individual rainwater tanks, even those with disinfection units installed (Ahmed *et al*. 2010). Another advantage is water supply back up from the other water sources as individual rainwater tanks do not have 100% supply reliability.

The most significant challenge faced by the Wannon scheme was that some developers were reluctant to implement the scheme due to the perceived cost burden. The cost per lot of connecting houses to the roof water harvesting scheme varied between $2,325 and $4,450. However, this cost was offset by removing the mandated requirement of installing a rainwater tank in each house, plumbed to the toilet. This avoided cost was estimated at around $4,000.

The initial capital investment needed to construct the scheme, was made possible by a Federal Government grant. This grant has meant the system is well documented and is supported by a toolkit that enables others to estimate the expected yield and costs associated with constructing and operating their own roof water harvesting scheme (Wannon Water, 2011).

11.3.3 Christie walk

Christie Walk is a brownfield medium density residential development, located in Adelaide's central business district. The development was initiated in 1999 and completed in 2006 (Downton, 2005). The development is situated on a 2,000 m^2 lot and contains 27 dwellings of varying types (detached, duplex, apartments etc.) housing a population of 50 people. Christie Walk was designed to demonstrate a sustainable approach to urban development and living using the concept of an eco-city. The water

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supply, wastewater and stormwater services were designed to be water efficient, minimise environmental impacts, and enhance the local ecological processes and liveability of the development. A feature of the development is a cluster-scale rainwater and stormwater harvesting scheme that supplies non-potable water (Downton, 2005).

Runoff from impervious surfaces at Christie Walk (roofs, paving, balconies, etc.) is collected via downpipes and grates to a stormwater collection pipe that drains by gravity to two underground concrete storage tanks (40 kL total capacity). The impervious collection area is approximately 1,300 m^2, which is around 65% of the total site area. The harvested runoff is reticulated back to the development via a ring main, providing non-potable water for toilet flushing and garden irrigation. The intended uses means there is no need for a treatment process. The non-potable supply is guaranteed with a mains back-up supply to the tanks, controlled by water level sensors. The system is fitted with non-return valves to prevent backflow and cross-contamination of mains water pipelines.

Excess rainwater and stormwater flow (i.e., overflow) that cannot be captured in the storage tanks is directed to a surface drain at the rear of the development. Monitoring of the harvesting and reuse scheme showed it reduced mains water demand by 45% compared to similar traditional households in South Australia. In fact, water use for Christie Walk households is actually significantly lower than the average water use for one person households in SA Water's service area. This is despite the average household size at Christie Walk being closer to two people (the average Adelaide household size is 1.85 people). The following may influence the lower water demand at Christie Walk:

- The built form and landscaping was designed to be water efficient. This included efficient household appliances and also the extensive use of native plants that are adapted to dry conditions; and
- Residents are highly motivated by a sustainable behaviour ethic, which is consistent with their choice of living in a development such as Christie Walk.

Christie Walk is managed as a community title development, so it has a standard body corporate arrangement comprised of owners. The ongoing maintenance is conducted by a team of volunteers from the residents. The management of the rainwater and stormwater harvesting system was formalised in a users' guide. This guide provides the technical details of the systems and also trouble-shooting steps in case of system failure.

11.3.4 Fitzgibbon chase potable roof water (PotaRoo) scheme

Fitzgibbon Chase is a residential development of the Urban Land Development Authority (ULDA) located in the northern suburbs of Brisbane, Australia. The development covers an area of approximately 295 hectares, and had the purpose of providing affordable, sustainable housing. This is demonstrated in the area's water management systems which include the reuse of rainwater and stormwater as alternative water sources; the former for potable uses, and the latter for non-potable purposes. The following information in this section has been taken from Dark and Hamlyn-Harris (2009).

11.3.4.1 Rainwater collection

The potable roof water project (PotaRoo) harvests rainwater from 1,230 homes, with a total roof catchment of about 110,000 m^2. Rainwater from the roofs is diverted into collection systems and collected in a series of satellite, subsurface communal rainwater tanks, from where it is pumped to a 0.8 ML centralised storage and treatment facility. Excess runoff overflows into the stormwater drainage system. The collected rainwater is treated to potable standards, and initially will be injected into the non-potable, stormwater

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reticulation line until the system is validated for potable quality, at which time the water will be connected into the main potable water supply network. A schematic layout of the roof water collection system depicting local and central rainwater storage tanks and their connections is shown in Figure 11.4.

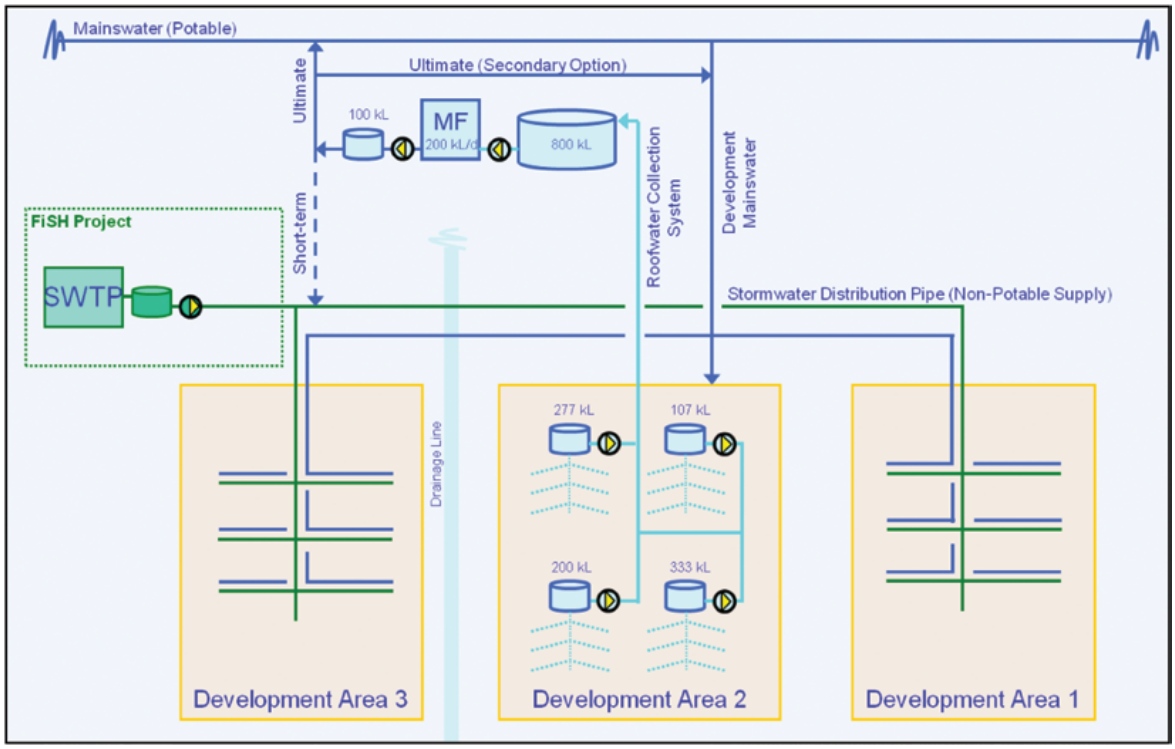


Figure 11.4 Schematic of fitzgibbon chase potable roof water systems (Courtesy Bligh Tanner Consulting Engineers, Brisbane, Australia).

11.3.4.2 Water balance

A daily water balance analysis was carried out over a 30-year period with various water treatment capacities (160 kL/day–500 kL/day). This study determined the optimum storage tank size for treated water to be 2 ML. Preliminary cost estimates indicated a treatment capacity of 200 kL/day was the most cost-effective. The water balance analysis showed that the scheme had the potential to supply approximately 44 ML/year (121 kL/day) of treated rainwater, approximately one third of the projected total potable demand.

11.3.4.3 Collection system

Analysis of rainfall intensity records showed that the majority (75%) of rainfall runoff occurred for events less than 30 mm/hr. Further analysis determined that limiting rainfall capture to events <30 mm/hour had only minor (<0.5 ML/year) impact on harvesting potential. The hydraulics of the gravity based collection system was therefore capped at 30 mm/hour. Each dwelling, with an average roof size of 100 m^2, has the potential to harvest a maximum flow of 0.83 L/sec, based on the capped flow capacity of the communal collection system. Communal collection pipes ranged between 100 mm to 375 mm uPVC pipe, with the majority no more than 225 mm in diameter (Dark & Hamlyn-Harris, 2009).

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11.3.4.4 Storage systems

As shown in Figure 11.4, the flat topography of the area required the rainwater from the roofs to be first collected by gravity into four underground concrete tanks and then pumped to a centralised above-ground tank of 800 kL capacity for subsequent treatment, storage and distribution The combination of a gravity and pumping system for rainwater collection and transportation substantially reduced project costs.

11.3.4.5 Distribution and treatment system

The treatment plant has the ability to process 200 kL/day of rainwater and consists of a multi-barrier approach including pre-filtration, coagulation, pH adjustment, microfiltration, activated carbon, ion exchange and UV disinfection and fluoridation.

11.3.4.6 Supply of potable water

Initially, the treated rainwater will be distributed through the non-potable stormwater recirculation system, for use in toilets, cold water laundry washing and outdoor uses. After validation and regulatory approval (over a period of approximately three years) to ensure the treated water's suitability as a potable source, the water will be supplied into the mains water system, which incidentally also supplies houses outside of the Fitzgibbon development.

11.4 MODELLING THE PERFORMANCE OF INDIVIDUAL VS. CLUSTER RAINWATER HARVESTING

The performance of cluster-scale rainwater harvesting systems was explored using Urban Developer®, an integrated urban water cycle modelling tool which simulates urban water systems including water supply, stormwater, and wastewater at scales ranging from allotment up to clusters or subdivisions (eWater Cooperative Research Centre, 2011). The model scenario we chose simulated a hypothetical 42-house greenfield development in Melbourne, Australia, (average annual rainfall of 649 mm) where rainwater was used to augment non-potable uses. The performance of a CSRH scheme of different storage sizes was compared to the traditional approach of installing a rainwater tank of equivalent *pro rata* storage capacity in each allotment. The model scenarios included harvested rainwater being used for indoor non-potable uses only (toilet flushing and laundry), or indoor and outdoor uses, for different household occupancy rates of between one and four persons. Based on local census data, assumed model occupancy of one person, two, three and four persons represented 15%, 25%, 14% and 46% of Melbourne households, respectively. Estimates of the demand for rainwater were based on recent Australian end-use studies, in particular Beal *et al*. (2010). Indoor demand was estimated on a per capita basis, whilst outdoor demand was considered on a per household basis. For example, for a three person household, estimated indoor demand for rainwater was 50 kL/year, with an additional 6 kL/year for garden irrigation per household.

The impervious area (catchment) for the development was estimated from digitizing the layout of a representative greenfield development on the outskirts of Melbourne. The average lot area was 366 m^2 with 53% of this area estimated as roof catchment and a further 23% as other impervious surfaces (driveways, paved paths, etc.). The modelling considered two possible configurations for rainwater harvesting at the development:

(1) Individual household rainwater tanks with 100% of dwelling roof area connected to the tank. The simulations considered 3 tank sizes – 1 kL, 2 kL and 5 kL.
(2) Cluster-scale rainwater harvesting system with 100% of roofs in each household connected to the cluster-scale rainwater tank of the communal harvesting system.

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We note that it may not be possible to connect 100% roof area in large houses due to problems with down pipes configuration and their connectivity, including aesthetic considerations.

Figure 11.5 shows that volumetric reliabilities increased as storage size increased, as expected. The simulated cluster-scale harvesting scheme used a storage volume equivalent to the combined storage of the individual houses. The CSRH showed a higher volumetric reliability compared to the average for households' volumetric reliability when non-potable demand was supplied from individual rainwater tanks. However, Figure 11.5 depicts via the vertical bars that reliability differed depending upon household occupancy (which was used as a surrogate for demand). Households with a lower occupancy rate are likely to achieve higher volumetric reliability with an individual tank than they would when connected to a CSRH scheme. The inverse is true for higher occupancy rate households.

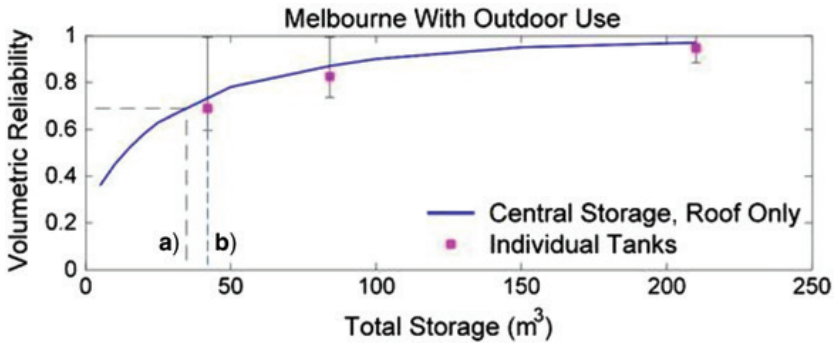


Figure 11.5 Volumetric reliability for a CSRH system compared to the average, maximum and minimum volumetric reliability when storage volume is supplied from individual household rainwater systems.

Also, it was possible to estimate the storage required for a cluster-scale system to achieve the same average reliability as that provided by the combined storage of individual rainwater systems. For the scenario where all 42 households have a 1 kL rainwater tank, the average volumetric reliability is 0.73 for a total combined storage of 42 kL. However, the same reliability can be achieved by using a cluster-scale harvesting scheme with a storage volume of 34 kL, a 19% reduction in total storage volume. This reduction in storage volume for cluster-scale systems has implication for both capital costs for storage tanks and the land footprint of rainwater harvesting systems. The *a* and *b* dotted lines in Figure 11.5 indicate that less storage volume is required for a CSRH system: (a) than the aggregate storage volume of individual rainwater systems; and (b) to achieve the same reliability.

11.5 METHOD FOR THE DESIGN OF CSRH SYSTEMS

The method for the design of CSRH systems presented in this section serves as the basis for the economic calculations of cluster-scale rainwater systems reported in Chapter 12.

11.5.1 Designing the CSRH system

The design of CSRH system is described in detail by Gurung and Sharma (2014). The main steps are summarised below:

(1) Develop a typical housing layout for use in a greenfield site, using collected information such as average lot size, roof area, housing density, street width and historical rainfall data.

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(2) Use the collated information to develop various scales of housing layouts (4, 8, 16, 24, etc. houses).
(3) Assign the location of the rainwater storage tank within the development considering the overall topography.
   – For a flat topography, the communal rainwater tank should be situated in the centre to minimise costs of the rainwater collection and supply networks (Figure 11.6a);
   – In a sloping topography, the communal rainwater tank should be situated in the lower elevation side of the development to capture water easily by gravity (Figure 11.6b).

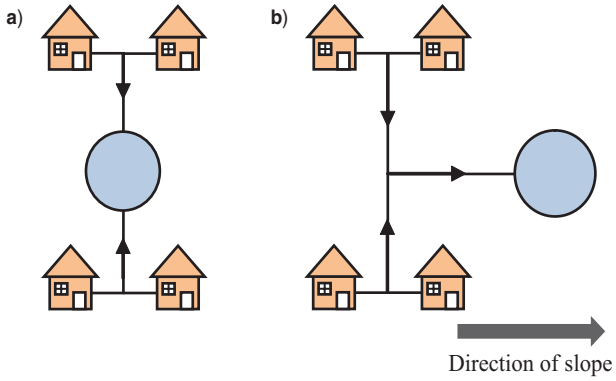


Figure 11.6 (a) Rainwater tank in the middle for flat topography; (b) Rainwater tank at lower elevation side for sloping topography.

(4) Plan the layout of the collection and distribution systems for each housing layout.
(5) Decide on the use of the rainwater; potable or non-potable purposes, and collate information on the consumption rates for various end uses.
(6) Estimate peak flows in rainwater collection and distribution systems for each housing layout (Figure 11.7).
(7) For each layout, estimate the size of main rainwater storage tanks, satellite tanks (interim storage tanks before the main storage tanks) if required, pipe sizes of collection and recirculation networks, and pump capacity. If satellite tanks are not considered, rainwater tanks will have to be placed underground, which may be very deep and thus uneconomical to construct and operate.

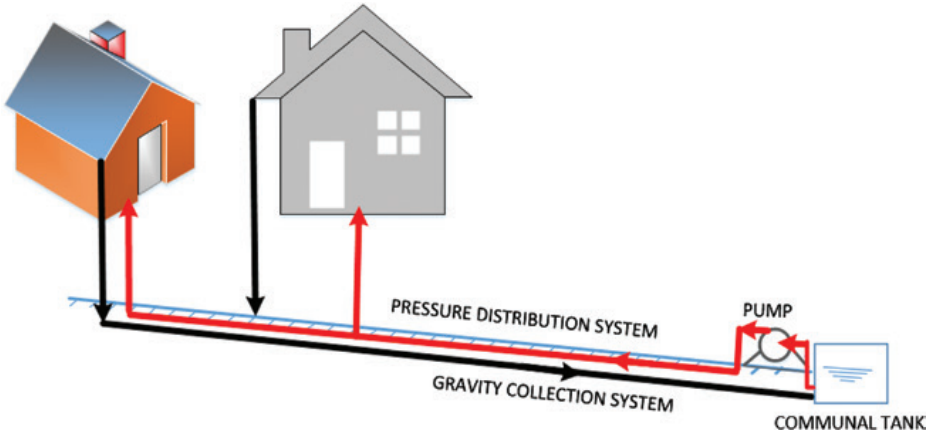


Figure 11.7 Communal rainwater tank systems – collection and distribution systems.

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The method is illustrated here using the Capo di Monte (CDM) development example, which is used as the case study described in a previous section.

11.5.1.1 Rainwater collection pipes

Collection pipes transport the rainwater from roofs to the storage tanks and need to be adequately sized (Figure 11.7). Peak flow contributions from each household's roof can be calculated using the Rational Method (DERM, 2007). The size of the connection (pipe connectors) from the household downpipes to the communal rainwater collection pipe determines the runoff flow rate that can be harvested by the collection system.

At CDM, hydraulic analysis demonstrated that the size of the household's connector limited the peak rainfall intensity entering the communal system to <2 mm/5 min. In-ground pipe installed around the dwelling is connected to the household downpipes. The connector is then used to join the in ground pipe to the main communal collection pipe network, as shown in Figure 11.8.

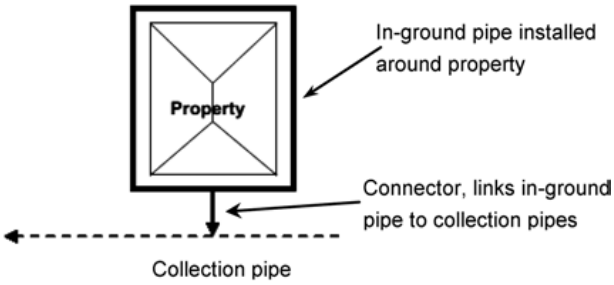


Figure 11.8 Schematic of a typical connection to the CRWH collection system.

Using this intensity with the Rational Method, the peak flow able to enter the system was found to be 1.28 L/s per dwelling assuming a roof size of 220 m^2 with 100% connectivity, and fractional rainfall catch losses of 0.875 mm. Manning's equation can be rearranged and used in the sizing of the gravity flow collection pipes (Figure 11.7), depending on the pipe material chosen (Rossman, 2010).

$$d^{8/3} = \frac{4^{5/3} \cdot Q \cdot n}{\pi \cdot S^{1/2}}$$

Where: d = diameter of pipe (m), Q = flow in pipe (m^3/s), n = Manning's roughness coefficient, and S = slope.

A minimum pipe-full flow velocity is required to ensure that self-cleansing of the pipe is maintained and scour does not occur (DERM, 2007). Local guidance recommends minimum pipe-full flow velocity for self-cleansing purposes to be 0.6 m/s (DERM, 2007). For polyvinyl chloride (PVC) pipe with an estimated roughness of 0.01 (Rossman, 2010) the minimum slope required to produce this velocity within the study area was 0.5% for a 100 mm diameter pipe.

11.5.1.2 Rainwater storage tanks

The sizing of storage tank for a CSRH system needs to consider the demand of intended end uses, rainfall pattern and reliability of supply. For the CDM case study, the harvested water is treated and used for all indoor potable demand. This implies a water demand pattern which has a typical diurnal, bimodal

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distribution, with peaks during the morning and early evening, but little seasonal variation (Cook *et al.* 2013). In contrast, harvested water used for irrigation is likely to have a pronounced seasonal variation in demand. Studies that partition household water consumption into specific end uses, such as those conducted in South East Queensland by Beal *et al.* (2010) are very useful in estimating the likely demand for a CSRH system.

For CDM, the urban water balance tool UVQ (Mitchell & Diaper, 2006), was used in the sizing of rainwater tanks. Historic rainfall data spanning 20 years was obtained from the BOM weather station and then 'censored' to exclude rainfall greater than 2 mm/5 min intensity, as per the flow limitation of the connector pipes. We found that the demand for rainwater could be satisfied on 98% of days over the 20-year period using a storage volume of 160 kL (Figure 11.9). To increase the reliability to 99.5% would require an impractically large storage of 280 kL. This is a large increase in storage volume for only a marginal gain in reliability (Cook *et al.* 2013). However, at CDM there was back-up supply from a groundwater bore to ensure reliable service, so rainfall did not have to meet all of the water demand. It was found that 90% of the daily demand could be met with an 80 kL tank, half the tank volume required to meet demand on 98% of the days. This analysis highlights that the availability of a back-up supply can minimise the need for large storage tanks whilst still maintaining a high level of service.

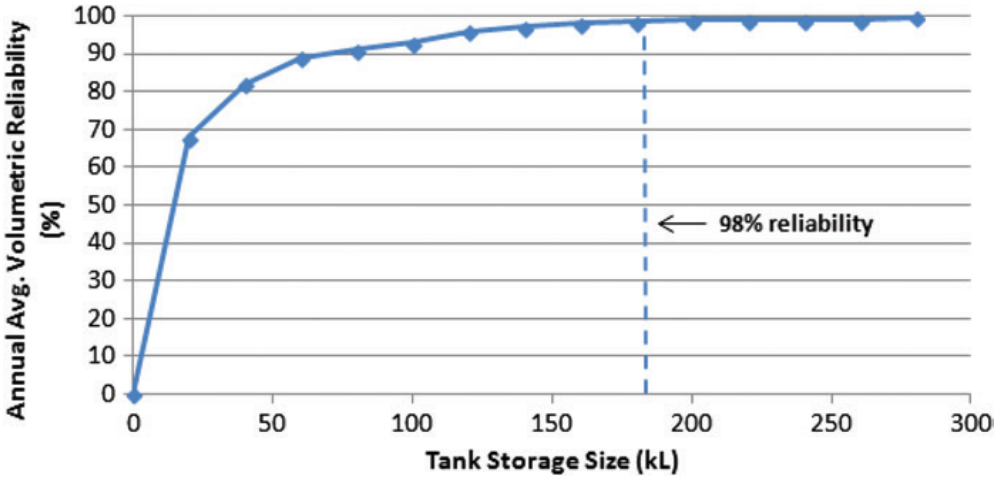


Figure 11.9 Volumetric reliability of a CSRH system at Capo Di Monte for different tank storage sizes. *Source*: Cook *et al.* 2012.

11.5.1.3 Rainwater distribution systems

Water distribution pipe sizes were estimated considering local planning guidelines and hydraulic methods for pipe sizing (Swamee & Sharma, 2008). Under local guidelines (GCCC, 2008), the minimum diameter of potable mains water is 100 mm with velocity not exceeding 2.5 m/s to prevent pipe failures. Checks for maximum velocity within the network can be calculated by dividing peak supply flow by the area of the pipe.

11.5.1.4 Pump capacities

The Darcy-Weisbach formula (Swamee & Sharma, 2008) is used to calculate head loss in pipes to ensure the network design meets the minimum pressure required at the property boundary for potable water, in this case 22 m of head (GCCC, 2008). The head required for distribution pumps is calculated using

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Bernoulli's equation (Swamee & Sharma, 2008). The power required to pump the water to residents is then calculated using methods described in Swamee and Sharma (2008). A manufacturer's pump curve can then be used to choose the appropriate sizes of the pumps.

The energy usage by pumps is based on pump duties, sump well and sump capacities, and life cycle costing of the entire system can be conducted using methods described in Swamee and Sharma (2008) and Gurung and Sharma (2014). The economics of scale analysis of CSRH is described in Chapter 12.

11.6 WATER TREATMENT

CSRH offers the opportunity to use rainwater to meet potable water demands, such as drinking, as it provides economies of scale for the treatment plant. Another advantage of cluster-scale treatment of rainwater is that it enables the use of appropriate monitoring and management practices to ensure that treatment processes are operating to specification. Rainwater can be used for potable uses with adequate preventive risk management, including proper system design and maintenance and adequate treatment. The chemical and microbiological rainwater qualities for allotment-scale rainwater tanks are discussed in Chapters 9 and 10 respectively, and a similar quality can be expected in communal rainwater tanks as the roof area is still the rainwater catchment. The main water treatment objectives for potable use is reducing the turbidity and killing the pathogens. Hence, filtration (sand or MF membranes) and UV disinfection to ensure protozoan destruction is generally sufficient. Chlorine also needs to be added to prevent bacterial regrowth in the reticulation system, and this may cause disinfection by-product (DBP) problems if organic carbon content is high in the rainwater. This issue may require further research. More sophisticated treatments (e.g., ozone, RO, ion exchange, activated carbon) should only be required if stormwater is part of the raw water supply. Real-time monitoring of various parameters (eg. UV transmissivity, turbidity, residual chlorine, membrane integrity, etc.) will provide a high quality assurance that the treatment systems are working to specification.

The common treatment options provided for potable/non-potable use of harvested rainwater are illustrated in Figure 11.10 and summarised in the following sections.

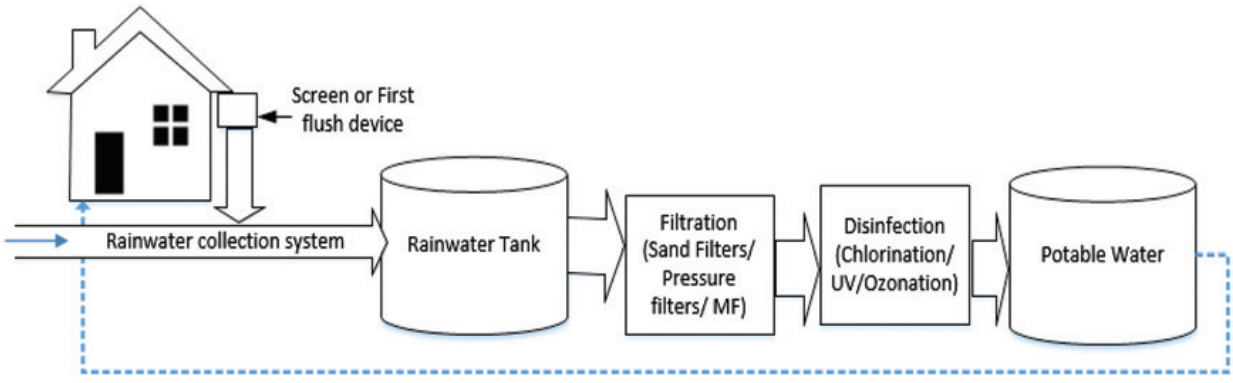


Figure 11.10 Arrangement of various rainwater treatment systems.

11.6.1 Preliminary treatment and filtration

Screening and first flush is considered as a preliminary treatment for improving harvested rainwater quality, followed by a filtration process which aids the effective removal of suspended impurities. Sand

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filtration using pressure filters is the most commonly used methods, where graded sand layers remove the fine sediments from the roof runoff. Regular backwashing is required for preventing clogging. Alternatively, membrane microfiltration can be used to reduce turbidity, organic matter and some microorganisms.

11.6.2 Disinfection

The most common technologies used for rainwater disinfection include chlorination, UV disinfection, ozonation and hydrogen peroxide disinfection. Liquid chlorine is generally dosed into a batch system or in-line system suited to the local conditions (Mintz *et al.* 1995; Salahuddin *et al.* 2011). However, chlorination is not suitable for water highly contaminated with organic matter due to the risk of DBP formation.

UV disinfection, on the other hand, is the most commonly used disinfection system for community supplies due to its ease of use, chemical free application, shorter retention time, small potential to form DBPs, but provides no residual disinfection in the distribution system (Roebuck *et al.* 2011; Keithley, 2012). Such systems can be installed in the pipe work delivering water either to the storage tank (as in the case of Capo di Monte), or from the tank to the receiver, or selectively to specific taps. To ensure the effectiveness of UV disinfection there is the need for upstream treatment that removes particles (through clarification and/or filtration). Even effluent with low measured turbidity (≤2 NTU) can still be difficult to disinfect due to large, undetected particles (Metcalf & Eddy, 2003). Other options for disinfection include ozone and hydrogen peroxide.

11.6.3 Post-treatment methods

Membrane filtration methods such as microfiltration, ultrafiltration (microfiltration uses 0.2-μ pores, while ultrafiltration excludes particles >0.02 μ), nanofiltration and reverse osmosis can be used as post-treatment steps to reduce trace contaminants if required. The influent is usually forced through the membrane by applying pressure, (Varbanets *et al.* 2009).

11.7 MANAGEMENT OF CSRH SYSTEMS

The broader adoption of CSRH systems requires consideration of business case and management models for the maintenance and operation of these systems. CSRH systems require cooperation amongst neighbouring households in a formal manner. For this reason, we have drawn upon experiences with decentralised wastewater systems in indentifying potentially suitable management models. Body corporate or community title arrangements can be applied when the CSRH system is part of a shared land title. However, there is the need to consider other management models where ownership of land is not shared.

CSRH systems offer a number of advantages for ensuring effective management when compared to household-scale rainwater systems. A CSRH system provides economy of scale and the option of sub-contracting operation and maintenance to industry specialists. This means that individual householders can adopt a more passive role thereby reducing the burden on householders who may lack the knowledge, time or motivation to maintain their rainwater system correctly. In this manner, CSRH systems offer the opportunity to formalise management arrangements. Using terminology coined by the US EPA (2005) in relation to decentralised wastewater treatment systems, CSRH require setting up a *Responsible Management Entity* (RME) The management of CSRH involves two phases: setup and ongoing management. The individual tasks are identified in Figure 11.11.

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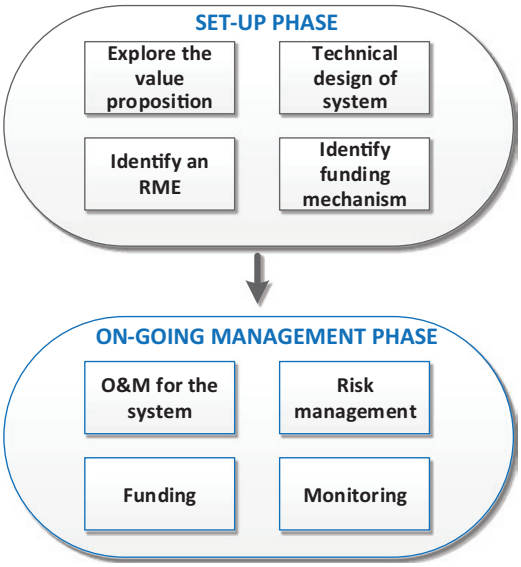


Figure 11.11 Responsible management entity tasks for a CSRH system.

Table 11.2 Management related decisions for CSRH systems.

Decision type	Choices	Considerations
Type of Responsible Management Entity (RME)	– Water utility – Local council – Home owners association – Body corporate or community title corporations – Privately owned businesses – Cooperative – Sub–contracting services – State agencies, urban land development authorities	– Experience in being an RME – Financing capacity of the RME – Long term continuity and stability of RME – Legal rights to enforce payments – Accountability and transparency of RME – Tax rules – Ease of set–up
Roles of RME	– Collect bill payments – Turn off services – Pay bills – Operate systems – Maintain systems – Monitor performance	– Technical capacity of the RME – Awareness of regulatory requirements – Motivation of the RME
Utilising O&M service providers	– Operate systems – Maintain systems – Monitor performance	– Contract arrangements – Continuity of services – Liability issues – Insurances – Accreditation and regulation
Payment approach	– Taxes – Water bills – Council rates – Body corporate fees – Bills to private company	– Can the RME enforce the payment of bills? – Can the RME turn off services if non–payment? – Motivation of householders/water users

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In the early stage of planning, there are a number of decisions to be made in relation to RME activities (Table 11.2). This table has been developed based on experience with decentralised wastewater treatment systems which we believe can be adapted to CSRH systems. The decisions are:

- type of Responsible Management Entity;
- roles of the Responsible Management Entity;
- outsourcing Operation and Maintenance to service providers; and
- Choosing a payment approach that ensures financial sustainability, fairness, and adequate resourcing to cope with unexpected problems.

In addition to the decisions described in Table 11.2, it is also important to undertake *risk management planning* so that risks are identified and mitigated through adequate risk management strategies. Whilst the major risks relate to water quality and health issues, other key risks include financial viability and the capacity to ensure the ongoing operation of the system.

11.8 CONCLUSIONS

A cluster-scale approach to rainwater harvesting can provide a local, decentralised water supply in non-reticulated peri-urban areas, as well as reducing demand on drinking water in traditional urban areas. Household-scale rainwater harvesting systems have been the dominant mode of providing a rainwater source in established urban areas. However, this chapter has shown that cluster-scale systems *may* provide a better option for local water harvesting than household-scale systems. Specific findings included:

- There are a number of examples in different development contexts where cluster-scale approaches have been successfully implemented as a local, decentralised water source;
- Cluster-scale rainwater systems can allow for urban development in peri-urban areas not serviced by mains water supply;
- Cluster-scale rainwater harvesting can also be used in cities to reduce demand for mains water and remove the need for individual rainwater tanks as a non-potable water source;
- Cluster-scale systems can improve water quality management and reduce the land footprint required for storage, which can free some land for other purposes such as house extensions and so on;
- Cluster-scale harvesting can increase the overall yield and average reliability of rainwater harvesting, relative to household-scale systems;
- A back-up water supply is required in cases where the system is used for non-discretionary uses, such as potable demand or toilet flushing, to ensure 100% supply reliability;
- A cluster-scale approach can be used to extend the uses of harvested rainwater to potable uses by providing economies of scale for the more sophisticated treatment systems;
- There can also be economies of scale for cluster-scale collection and storage systems; and
- Cluster-scale harvesting offers the opportunity to formalise management of local water sources, which address some of the limitations of household-scale rainwater harvesting due to lack of householder skills or motivation to undertake adequate maintenance to ensure water quality and supply.

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Chapter 12

Economics of individual and communal rainwater tank systems

Murray R. Hall, Thulo Ram Gurung and Kym Whiteoak

ABSTRACT

This chapter considers the economic performance of rainwater tanks. The chapter starts at the scale of individual rainwater tanks and then considers communal rainwater tank systems. The chapter also progresses in scope by expanding analysis from cost-effectiveness to cost benefit analysis. The chapter presents general methods and demonstrates the approach by drawing upon recent research in South East Queensland, Australia where several hundred thousand rainwater tanks have been installed over the past decade.

The economics of individual rainwater tanks focuses on the variation and uncertainty in cost-effectiveness calculations. It illustrates that variation in assumptions such as the discount rate and the maintenance assumptions can have as large an impact as a standard deviation increase in the yield. When a number of modelling assumptions are changed to form a new scenario the mean cost-effectiveness can change by 50% even though the yield and basic cost data remain the same.

The economics of communal rainwater tanks focuses on design considerations such as scale and the effect on cost-effectiveness. The results suggest that there is an optimal scale for communal rainwater tanks and under or oversized systems will be less cost-effective.

The cost benefit analysis of rainwater tanks provides a focus on the importance of other benefits from rainwater tanks such as delayed infrastructure upgrades and reduced stormwater flows to receiving waters. The case study suggested that additional benefits for rainwater tanks were relatively small. Nonetheless, in some circumstances, rainwater tanks may provide a greater net benefit than options such as augmentation of the existing supply.

Keywords: Cost benefit analysis; cost-effectiveness; rain water tanks and systems.

12.1 INTRODUCTION

Over the past decade a number of articles have reviewed the financial performance of rainwater tanks for individual houses. These articles come from countries across the world including Australia, India, Bangladesh, China, Spain, UK and Italy. Some articles suggest rainwater tanks are very cost-effective,

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have short payback periods and are competitive with mains supplies (Alam *et al.* 2012; Coombes, Kuczera & Kalma, 2003; Ghisi & Schondermark, 2013; Islam, Chou & Kabir, 2011; Knights & Wong, 2008; Tam, Tam & Zeng, 2010). Other articles suggest that rainwater tanks are likely to have long payback periods and will be more costly than mains supplies for many years to come (Domenech & Sauri, 2011; Farreny, Gabarrell & Rieradevall, 2011; Morales-Pinzon, Luruena, Rieradevall, Gasol & Gabarrell, 2012; Roebuck, Oltean-Dumbrava & Tait, 2011).

Part of the difference may be due to the local context and differing water yields, social and institutional factors. However, there also appears to be a large variation in the scope of costs considered, the rationale for defining financial parameters such as the discount rate, the type of data used and the uncertainty, the system design as well as the consideration of additional benefits. Each section of this chapter presents a method and considerations for undertaking an analysis of the economic performance of rainwater tanks. The analysis begins at the level of an individual rainwater tank and considers the variation and uncertainty in cost-effectiveness. The section on communal rainwater tanks investigates the effect of scale on the cost-effectiveness. Finally, the third section of the chapter broadens the scope of benefits and considers Cost Benefit Analysis of rainwater tanks.

12.2 COST-EFFECTIVENESS OF INDIVIDUAL RAINWATER TANKS

12.2.1 Method

The method draws upon Life Cycle Costing and Cost-effectiveness Analysis (CEA). Cost-effectiveness Analysis is an established economic method for evaluating the cost of an option to achieve an objective (Pearce, Atkinson, and Mourato, 2006). Life Cycle Costing methods, which aim to capture costs over the entire life cycle, are also well established and standardised, for example StandardsAustralia (1999). The following steps provide general guidance for undertaking cost-effectiveness analysis and are demonstrated using a case study in South East Queensland (SEQ), Australia.

12.2.1.1 Step 1: Define the objectives and limitations

The cost-effectiveness of a rainwater tank will consider the cost to provide water over a period of time and can support decisions about whether or not to invest in a rainwater tank. However, the objective, costs and decision may be different for a homeowner, water utility or government entity. This means that the user group, and the decision to be made, needs to be clearly defined to justify the costs included in the calculation. For example, the cost-effectiveness of a rainwater tank for:

- a household may consider rebates, a market value for the water saved, and the market cost of money used to finance the tank system. Financial measures such as the payback period may be important for the household to decide upon investing in a rainwater tank.
- a water utility may limit costs to the rebates that it provides (and not the remaining costs incurred by the household) and use a Weighted Average Cost of Capital (WACC) for its access to finance. The WACC provides an average cost of capital that reflects the asset base and sources of finance for an organisation. The water utility may be interested in the levelised cost of rainwater tanks compared to other marginal supplies to decide whether or not to provide rebates. The levelised cost is the ratio between total life cycle cost and the total life time rainwater usage. The levelised cost is further defined in the following case study.
- a government policy perspective may consider all the capital and operating costs for a rainwater tank and the cost of money based upon government bond rates. The levelised cost of rainwater tanks may be an important consideration for a 'prudent and efficient' government policy for rainwater tanks.

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An advantage of cost-effectiveness analysis is the focus on the costs to achieve a single objective. The focus on a single objective is justified where other benefits are small and will not affect the evaluation. These assumptions should be defined as limitations of the study. A broader framework for capturing benefits is discussed in the Section 12.4 dealing with Cost Benefit Analysis of rainwater tanks.

12.2.1.2 Step 2: Define the data variation and uncertainty

The calculation of cost-effectiveness can draw upon a number of different types of data. This has implications for the consideration of variability and uncertainty in the results. For example, capital costs for tanks and pumps may be based upon a survey of quotes from suppliers. The variation in results can be calculated and may be expected to be relatively small in a competitive market. Similarly, the water yield from rainwater tanks can be measured and a distribution developed. The yield may also be compared to modelled yield which may be based upon measured inputs such as rainfall, roof area, tank size and water consumption patterns. The information on the measured yield is generally unknown and thus the estimations are based on modelled yield, which is generally higher than the measured yield.

Thus, measured or modelled data may not be available for all variables and there will be uncertainty in the results beyond the variation in the data. For example, future costs such as interest rates, electricity and water as well as the life span of tanks, future yields and the future maintenance practices of households. The uncertainty can be considered using scenarios and sensitivity of the results. These variables need to be clearly identified to assess the rationale for the data selected and the sensitivity of the results. For example, the cost of maintenance practices for cleaning tanks could be estimated using a typical or 'nominal' cost to provide a scenario for future practice (Domenech & Sauri, 2011; Khastagir & Jayasuriya, 2011; Marsden Jacob, 2007; Tam *et al.* 2010). However, an alternative scenario may also be justified if current maintenance practices do not meet health guidelines. This is discussed in more detail in the following case study, in Section 12.12.2.2.

12.2.1.3 Step 3: Calculate the cost-effectiveness and test the sensitivity

There are a number of ways of expressing the cost-effectiveness (Pearce *et al.* 2006); the estimation of levelised cost is demonstrated in the following case study to understand cost-effectiveness. A sensitivity analysis can provide a way to understand the importance of variables for the cost-effectiveness results. This provides a way of understanding the effect of assumptions upon the results, and may also highlight the need for further data collection. The sensitivity analysis may begin with an analysis of the effect of each variable upon the results. This may involve changing each variable by a standard deviation if the distribution is known, or by some other factor if not. Variables that have a large effect on the results can be investigated to check the validity of the assumptions.

12.2.2 Case study – mandated rainwater tanks in South East Queensland, Australia

12.2.2.1 Define the objectives and limitations

The objective of the study was to consider the cost-effectiveness of rainwater supply for an internally plumbed five kilolitre (kL) rainwater tank. This tank configuration (size) was common in the region because it's performance was assumed to meet Queensland Development Code MP 4.2 requirements for a potable water saving of 70 kL per annum. These mandatory requirements were subsequently repealed in 2013. The analysis aimed to support a water company or government policy investment decision. In

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2008, it was estimated that there were 313 000 rainwater tanks in the SEQ region of Australia (Gardiner, 2009). This was projected to increase to a total of 1.11 million tanks by 2056 due to building regulation requirements (QWC, 2008). Figure 12.1 shows the SEQ region and its local government areas.

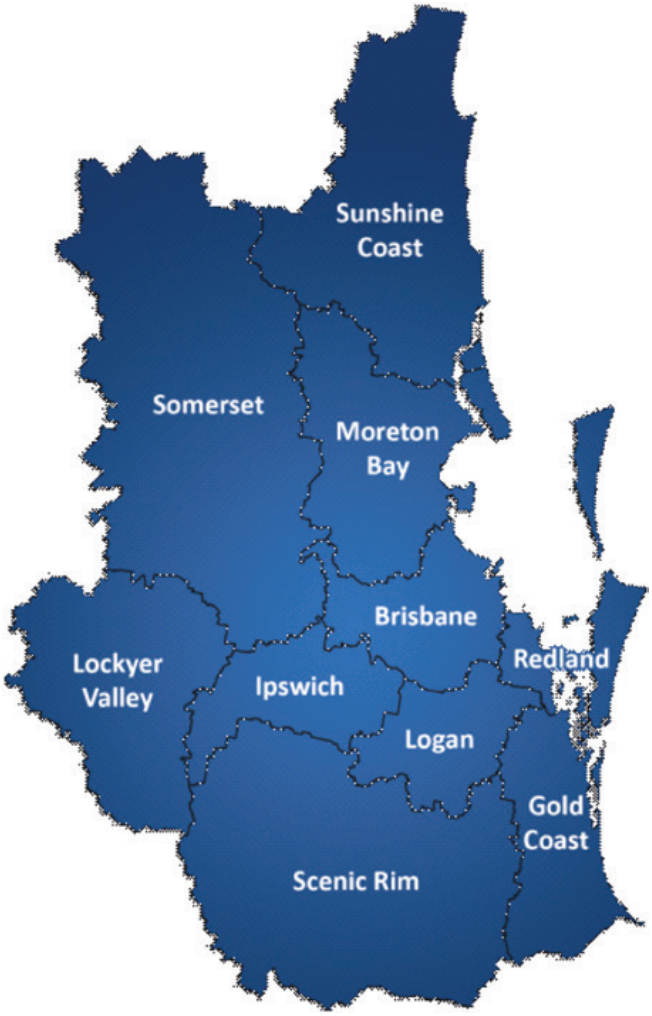


Figure 12.1 Local government areas in South East Queensland, Australia (http://en.wikipedia.org/wiki/South_East_Queensland).

Cost-effectiveness was expressed as a levelised cost as outlined in Equation 1. This approach considers the physical flow of water as a revenue stream and assumes that the unit cost of water (the levelised cost) as well as the discount rate is constant over the period of analysis. The analysis of levelised cost follows the approach outlined for the water and energy sectors (Fane, Robinson, and White, 2002; OECD, 2010).

$$\text{Levelised Cost} = \frac{C + \sum_1^n A_n/(1+i)^n}{\sum_1^n Y_n/(1+i)^n} \tag{12.1}$$

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where C is the capital cost ($), n is the year in the period of analysis, A is the annual payment ($), i is the discount rate, Y is the annual yield (kL). These parameters are further described in the following section.

Each term in Equation 12.1 has a number of input variables which can be defined following local Life Cycle Costing (LCC) standards as defined in StandardsAustralia (1999). Capital may include the cost of the rainwater tank, the pump, laying of a concrete slab for the tank foundation, as well as plumbing and installation of both the tank and the pump. Annual costs may include operating costs such as electricity use by the pump, maintenance costs such as pump repair, roof gutter and screen maintenance and desludging, as well as capital replacement cycles for pumps and tanks over the period of analysis. The calculation of energy costs includes the specific energy of pumps as well as assumed price paths for electricity. Residual values of tanks and pumps were estimated as the fraction of the useful life of an asset remaining at the end of the period of analysis. For example, if the period of analysis was 30 years and the tank was replaced after 25 years, then only 20% of the value of the replacement tank was considered in the analysis.

The discount rate reflects the time cost of money and the risk profile of the borrower. From this perspective, an organisation seeking to finance an investment adopts a discount rate based on the interest rate of their borrowings. However, the discount rate also expresses how much *less* something is worth in the future compared to the present. This can raise a number of ethical and intergenerational issues (Ruth, 1993). The discount rate can also be the largest uncertainty in an economic analysis for environmental impacts over long time periods (Weitzman, 2007). For this reason, a number of authors have suggested that long-term analysis of costs and benefits should have lower discount rates than the market cost for money (Garnaut, 2008; Weitzman, 2001).

12.2.2.2 Define the data variation and uncertainty

Table 12.1 provides a summary of the data, scenario and sensitivity assumptions for the study. Probability distributions were developed for input variables to facilitate a Monte Carlo simulation for the cost-effectiveness. The differing availability of data meant that a number of approaches were possible for developing the input distributions. In some cases, detailed monitoring and modelling data was available which defined the probability distribution. In other cases, the amount of data was limited and there was insufficient information to define the distribution. A simplifying assumption was made to assume a triangular distribution for all input variables based upon IPCC recommendations for addressing uncertainty in data (IPCC, 2000). The distribution was defined by the most likely and upper and lower values for a 95% confidence interval. The effect of the choice of distribution was considered in the sensitivity analysis.

Other variables such as the discount rate, period of analysis and maintenance were defined in the scenario and sensitivity analysis. A 3% discount rate was assumed to capture a government perspective of investment as well as long periods of analysis (Weitzman, 2001, 2007). A 3% discount was adopted based on the benchmark Weighted Average Cost of Capital (WACC) for the 2013–15 period for price monitoring of SEQ water and wastewater retail activities (PWC, 2013). This discount rate is considered to be 'risk free' because it was based on the government bond rate (PWC, 2013). A 6% discount rate was also considered in the sensitivity analysis and reflects the current benchmark WACC which considers the cost of equity and debt for SEQ water utilities.

The maintenance of tanks was also an important consideration due to the apparent difference between current and recommended practice to manage health risks (Moglia, Tjandraatmadja & Sharma, 2011). For example, a survey of rainwater tank maintenance in SEQ indicated that relatively few respondents checked for the build-up of sediment in the tank and even less removed it as required (Mankad, Tucker & Greenhill, 2012) despite health guidelines. Tanks installed as part of mandatory building requirements in

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Table 12.1 Summary of data, scenario and sensitivity assumptions for individual rainwater tank cost-effectiveness analysis.

	'Basic Scenario'			'Alternative Scenario'			Sensitivity	Note
	Triangular distribution			Triangular distribution				
	Min	Most likely	Max	Min	Most likely	Max		
Financial								
Discount rate (%)		3			6		6	Note 1
Period of analysis (years)		50			25		Same as 'alternative scenario'.	Note 2
Capital and installation ($AUD2012)								
Rainwater tank (5 kL)	1401	1544	1657					Note 3
Pump	722	790	962					
Plumbing	759	900	1017	Same as 'basic scenario'				
Tank installation	334	350	400					
Laying concrete slab	597	700	803					
Pump installation	200	250	300					
Operating, maintenance and replacement								
Energy								
Specific energy (kWh/kL)	1.1	1.48	1.9					Note 4
Unit cost for energy in 2012 ($/kWh)		0.228						Note 5
Retail energy price real growth rate (%)	3	5	7					
Useful lives (years)				Same as 'basic scenario'				Note 6
Pump life	5	10	15					
Rainwater tank life	15	25	35					
Plumbing		50						

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Maintenance ($AUD2012)	0	20	54	54	104	184	Same as 'alternative scenario'	Note 7
Yield (kL/year)								Note 8
Brisbane	18	42	76				Fitted distribution	
Moreton Bay	16	43	78					
Sunshine Coast	24	48	90	Same as 'basic scenario'				
Ipswich	10	34	66					
Gold Coast	18	44	74					

Notes

1. Long period of analysis discount rate based upon (Weitzman, 2001, 2007). Water utility discount rate and period of analysis based upon (Queensland Competition Authority Accessed 25 February 2013 http://www.qca.org.au/) (PWC, 2013)
2. Considered as a single value for the period of analysis and not considered as a distribution
3. Based upon (Gurung, Sharma & Umapathi, 2012) with comparison to (Marsden Jacob, 2007)
4. Based upon (Umapathi, Chong, and Sharma, 2012) with comparison to (Beal, Hood, Gardner, Christiansen & Lane, 2008; Ferguson, 2012; Lane & Gardner, 2009; Retamal & Turner, 2010)
5. (AEMC, 2011); (IES, 2010)
6. (Gurung et al. 2012; Marsden Jacob, 2007; Stewart, 2011)
7. Costs based upon (Gurung et al. 2012) and scenario based upon (Gardiner, 2010; Marsden Jacob, 2007; Moglia et al. 2011) (Mankad et al. 2012; Walton, Gardner, Sharma, Moglia, and Tjandraatmadja, 2012)
8. Yield distributions based upon (Maheepala, Coultas & Neumann, 2013) with reference to measurements and modelling from (Beal et al. 2011; 2012; Chong et al. 2011; Umapathi et al. 2012).

SEQ were less likely to be maintained than voluntary installations (Mankad *et al.* 2012). These results followed earlier research in SEQ that indicated that 'half of the owners of required tanks reported that they never cleaned their screens and gutters or inspected inside their tanks or did so only when there were obvious problems' (Gardiner, 2010). These variables need to be clearly identified to assess the rationale for the data selected and the sensitivity of the results. For example, the cost of maintenance practices for cleaning tanks could be estimated using a typical or 'nominal' cost to provide a scenario for future practice (Domenech & Sauri, 2011; Khastagir & Jayasuriya, 2011; Marsden Jacob, 2007; Tam *et al.* 2010). However, an alternative scenario may also be justified if current maintenance practices do not meet health guidelines. This is discussed in more detail in the case study, in the next section. The uncertainty in maintenance practice and costs was captured in the following scenarios. Current maintenance is minimal and a nominal cost was assumed based on previous studies. Maintenance costs based on health guidelines was also considered.

A 'basic scenario' was developed for a long-term *government perspective* based on current practice. A 50-year period of analysis was selected with a 3% discount rate and maintenance based on current practice. The sensitivity analysis considered changes in the discount rate, period of analysis, tank maintenance as well as the effect of refining the distribution for the yield. An 'alternative scenario' was also developed to provide an upper range estimate that may reflect a *water utility* perspective. The 'alternative scenario' used the WACC for the discount rate of 6%, a period of analysis for infrastructure appraisal of 25 years as well as tank maintenance according to recommended practice. These scenarios are described in Section 12.2.1 Step 1.

12.2.2.3 Calculate the cost-effectiveness and test the sensitivity

Table 12.2 presents the levelised cost for the 'basic scenario' based on the data presented in Table 12.1. In summary, the basic scenario has a 50-year period of analysis, 3% discount rate and maintenance based on current practice. The levelised cost is presented for various locations in SEQ as well as an average for the region. The results were calculated using software called *@risk*. This program is an add-on to excel and uses distributions of input variables to simulate a distribution of the output variable. The results show the parameters for the cost-effectiveness distribution such as the mean, the 95% confidence interval and parameters describing the skew. The skew in the distribution shows that a relatively small number of tanks are very costly for the amount of water provided. The skew effects measures of central tendency such as the mean. The mean is important for capturing the effect of poorly performing tanks on the average for a region. The median provides an indication of central tendency that shows typical performance for most of the tanks and reduces the effect of the tail of the distribution, in this case the poorly performing tanks. The data in Table 12.2 can also be presented as probability distributions. Figure 12.2 shows the results for Brisbane to illustrate the shape of the distribution and the 95% confidence interval. The cost-effectiveness differed across the region in terms of the mean as well as the skew. The Sunshine Coast was the most cost-effective location for a rainwater tank, with a mean levelised cost of $7.62/kL. Ipswich was the least cost-effective location for a rainwater tank, with a mean levelised cost of $11.17/kL. The distribution for Ipswich also had the highest skew and produced a relatively high upper 95% confidence limit of $22.19/kL.

Figure 12.3 illustrates sensitivity of the cost-effectiveness to the input variables. The effect on the cost-effectiveness is calculated by increasing each input variable by one standard deviation while the other input variables remain unchanged. For example, a one standard deviation increase in the yield means a greater yield for the same cost and improves the cost-effectiveness by $2.17/kL. Conversely, a one standard deviation increase in the cost of laying a concrete slab worsens the cost-effectiveness by $0.036/kL. This illustrates that the results are sensitive to yield while they are not very sensitive to the cost of the concrete

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slab. Figure 12.3 shows the cost-effectiveness is sensitive to assumptions about the yield, pump life, tank life, maintenance and growth rate for electricity prices. Interestingly, the cost-effectiveness was more sensitive to assumptions about the life of a pump and tank as well as the price path for electricity rather than the actual capital costs and operation of the pump. The results are more sensitive to the uncertainty associated with projecting these input variables over the period of analysis than the variation in the collected or modelled data. In general, the results were more sensitive to operating rather than capital costs. Note that cost variables were considered as independent variables and this assumption needs to be explored further in future research. For example, a high initial capital cost for a pump may be associated with a longer life and lower energy costs.

Table 12.2 Summary of 'basic scenario' levelised cost for rainwater tanks in SEQ.

Region	Mean ($/kL)	Mode ($/kL)	Median ($/kL)	Std dev ($/kL)	Skewness	2.5% ($/kL)	97.5% ($/kL)
Brisbane	8.93	7.18	8.42	2.46	1.12	5.59	15.10
Moreton Bay	8.97	7.12	8.38	2.70	1.32	5.49	16.10
Sunshine Coast	7.62	6.19	7.28	1.91	0.95	4.90	12.23
Ipswich	11.17	8.15	10.17	4.05	1.64	6.40	22.19
Gold Coast	8.90	7.99	8.41	2.40	1.20	5.65	15.08
SEQ weighted av.	9.22	9.04	9.03	1.57	0.78	6.73	12.77

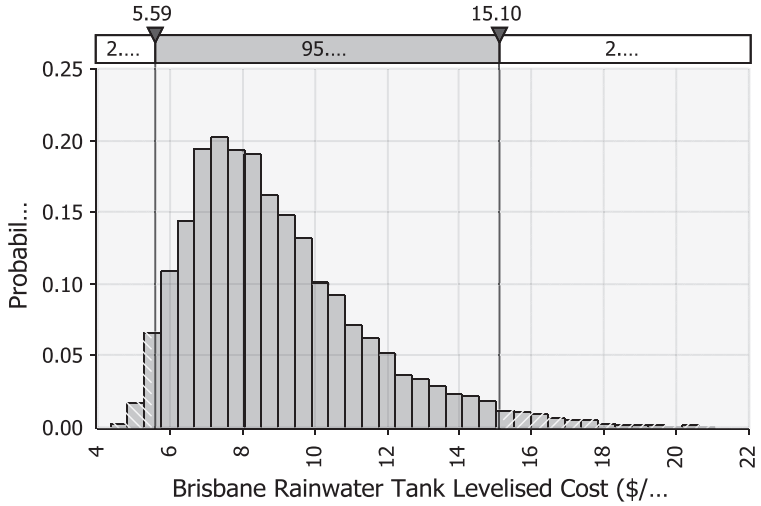


Figure 12.2 Brisbane rainwater tank cost-effectiveness probability density.

Table 12.3 further explores the sensitivity of the results by considering the uncertainty in the modelling assumptions including the discount rate, the period of analysis and the type of distribution assumed for the yield. Similar to Figure 12.3, the change in the cost-effectiveness is reported by changing each variable while the others are held constant. This enables comparison of sensitivity within Table 12.3 as well as in comparison to variables considered in Figure 12.3. For example, if maintenance is assumed to follow recommended health guidelines, it has a similar impact on the cost-effectiveness as a one standard

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deviation increase in the yield. Similarly, if the discount rate is changed from 3 to 6% it also has a similar effect as a one standard deviation increase in yield. Given the importance of the yield variable to the cost-effectiveness, the assumption of a triangular distribution was also reviewed by fitting a distribution to the yield data (Maheepala *et al.* 2013). The change to the yield distribution had a larger effect than a standard deviation increase in any of the variables presented in Figure 12.3 except for changing the yield itself. This illustrates that uncertainty in modelling variables is as important to the cost-effectiveness as the variation in the yield itself. Consequently, any apparent difference in cost-effectiveness requires careful scrutiny to ensure modelling assumptions are the same.

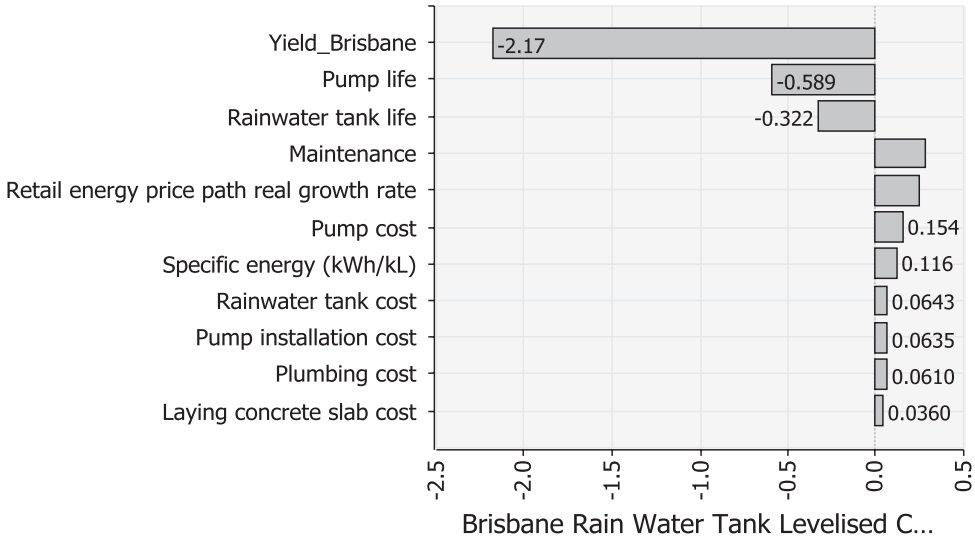


Figure 12.3 Brisbane rainwater tank cost-effectiveness Tornado chart.

Table 12.3 Sensitivity of the basic scenario to financial parameters, modelling and maintenance scenarios for Brisbane data.

	Increase in the mean levelised Cost ($/kL)
Maintenance following recommended practice	2.19
Increase discount rate from 3% to 6%	2.11
Fitted distribution*	0.92
Decrease period of analysis from 50 to 25 years	0.29

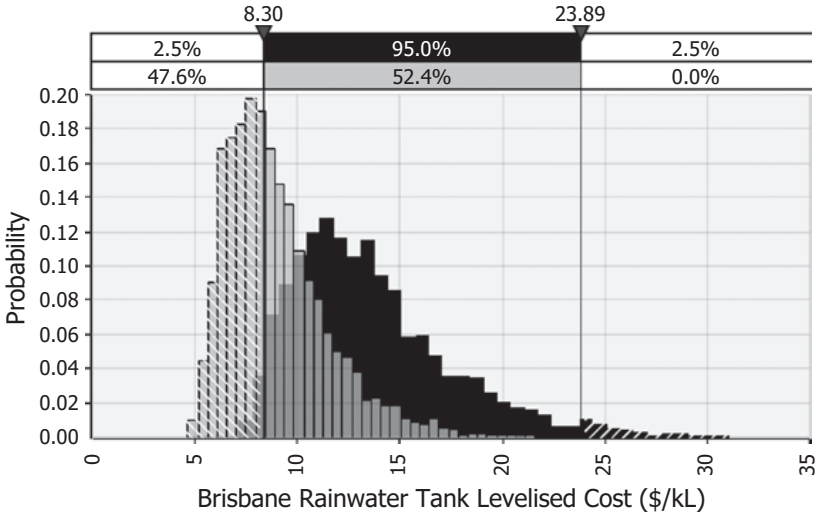
*The Johnson SU distribution was used and ranked the highest in terms of 'goodness of fit' for 65 distributions considered. The Johnson SU distribution had a Kolmogorov Smirnov statistic of 0.00606, Anderson-Darling statistic of 0.44284 and Chi Squared of 23.189.

12.2.2.4 Alternative Scenario

The 'Alternative Scenario' considers the effect of concurrent changes in a number of variables from Table 12.3 upon the cost-effectiveness. The assumptions for the Alternative Scenario are described in Table 12.1. In summary, the 'Alternative Scenario' provides a water utility perspective for the cost of capital with a

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6% discount rate, a time frame for infrastructure appraisal of 25 years as well as maintenance according to recommended practice. Figure 12.4 provides a comparison of the cost-effectiveness distributions of the two scenarios. The 'Alternative Scenario' had a mean levelised cost of $13.62/kL compared to $8.93 for the 'Basic Scenario'. This is approximately a 50% increase in the levelised cost and further emphasises that modelling assumptions can produce very different cost-effectiveness results even when the yield and cost data are the same. Changes to the modelling assumptions also have an effect on the distribution of the cost-effectiveness. For example, the distribution for the 'Alternative Scenario' shifted to the right, is less concentrated about the median and has a slightly greater skew. This means that almost half of the 'Basic Scenario' has a better cost-effectiveness than the best performing 2.5% of the 'Alternative Scenario'. The dashed lines in the Figure 12.4 show the values outside of the 95% confidence interval of the 'Alternative Scenario'.



	Name	Mean ($/kL)	Mode($/kL)	Median ($/kL)	Std Dev ($/kL)	Skewness	2.5% ($/kL)	97.5% ($/kL)
	Basic Scenario -Brisbane Rainwater Tank Levelised Cost	8.93	7.18	8.42	2.46	1.12	5.59	15.10
	Alternative Scenario -Brisbane Rainwater Tank Levelised Cost	13.62	11.00	12.88	3.96	1.14	8.30	23.89

Figure 12.4 Brisbane rainwater tank cost-effectiveness probability density comparison of 'basic' and 'alternative scenario'.

12.3 COST-EFFECTIVENESS OF COMMUNAL RAINWATER TANKS

12.3.1 Communal rainwater tank systems

Communal rainwater tank systems collect, store and treat rainwater across a residential development and supply treated water back to homes for either potable or non-potable use. In comparison to an individual household rainwater tank, a communal system has a single storage and treatment facility that services a cluster of houses, as shown in Figure 12.5. This type of water supply system is particularly suited for providing potable water to an off-grid community.

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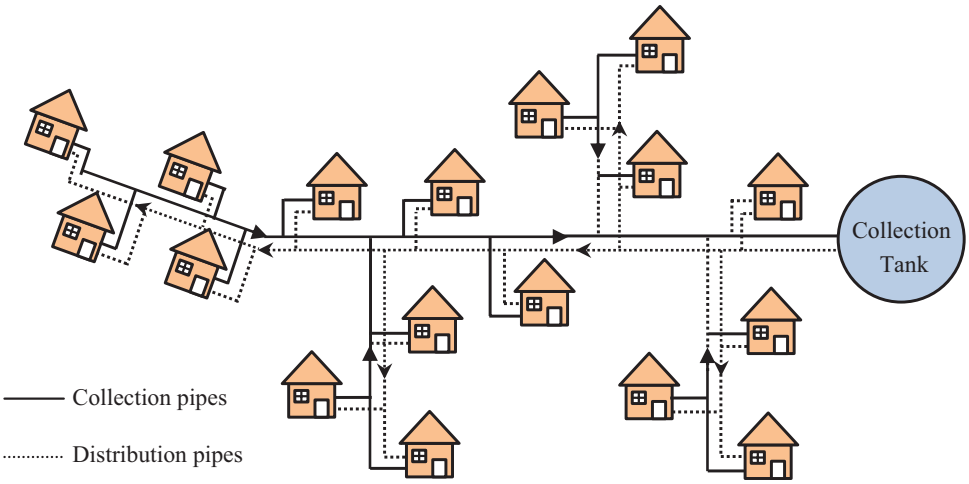


Figure 12.5 Communal rainwater tank with rainwater collection and distribution reticulation system.

A communal approach to storage and treatment may offer cost savings and address management and maintenance challenges experienced for individual rainwater tanks (Mankad *et al.* 2012; Walton *et al.* 2012). Achieving the cost savings will depend upon the level of treatment required (e.g., potable, Class A+ non-potable) and the additional cost for collection and distribution systems. However, examples of communal rainwater tank systems are very limited at this stage.

12.3.2 Method for cost-effectiveness estimation

The cost effectiveness analysis focused on the change in per household costs with changes in scale of the communal system. A conceptual design and life cycle costing was developed for a case study following the method of (Gurung & Sharma, 2014) which is described in detail in Chapter 11. Various configurations and scales were then considered to explore the effect on the system design and costing and to identify the optimum scale. The method did not explore the range of variables that may be expected to vary the cost from location to location. These factors include for example, topography of the area, end usages for rainwater supply, climatic conditions of the area (total annual rainfall and its pattern), connected roof area, tank size for the selected reliability of water supply, water pressure requirements, ongoing energy usage, and the overall density of housing development.

12.3.2.1 Case study – Results

Various housing layouts were developed for a location in South East Queensland assuming from 4 to 576 dwellings would be connected to the communal rainwater tank system, with a housing density not exceeding 20 lots per hectare and flat topography. Based on the information from current housing developments in the area, lot dimensions of 16 m by 25 m were adopted for this study. Other parameter values were based on local data such as: connected roof area of 200 m^2 (rainwater catchment), potable water demand of 82.3 L/person/day, household occupancy of 2.6 persons (OESR, 2012), historic rainfall data of the region, and sizing the communal rainwater tank based on 94% supply reliability. Cost data of the different components (e.g., pumps, pipes, tanks) required for the design of various layouts were sourced locally. An example of a layout for 24 homes is shown in Figure 12.6.

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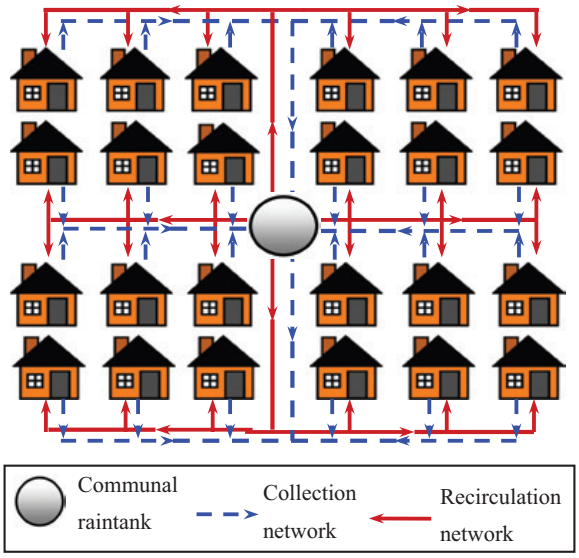


Figure 12.6 Layout of 24 homes in a communal rainwater tank system.

Life Cycle Cost (LCC) estimation using NPV method was conducted for a 50-year analysis period using a 3% discount rate. A sensitivity analysis of LCC was also conducted using a 6% discount rate. The analysis period of 50 years was selected for NPV as any longer period would make the present value of the future investment beyond 50 years insignificant (DFA, 2006) as shown in the following Equation 2 (Swamee & Sharma, 2008 and Newnan *et al.* 2002):

$$P = F(1+i)^{-n} \tag{12.2}$$

where P is present cost, F is future cost, i is discount rate and n is the analysis period.

Table 12.4 and Figure 12.7 show the life cycle cost in NPV for the selected discount rates for each layout.

Table 12.4 Life cycle cost per household at different development sizes and discount rates.

Number of dwellings	Cost per household with discount rates	
	3%	6%
4	$46,701	$37,856
8	$28,705	$23,842
16	$20,423	$17,351
24	$17,627	$15,305
48	$15,118	$13,154
96	$12,683	$11,238
192	$11,616	$10,390
288	$11,543	$10,404
384	$11,663	$10,555
576	$11,871	$10,838

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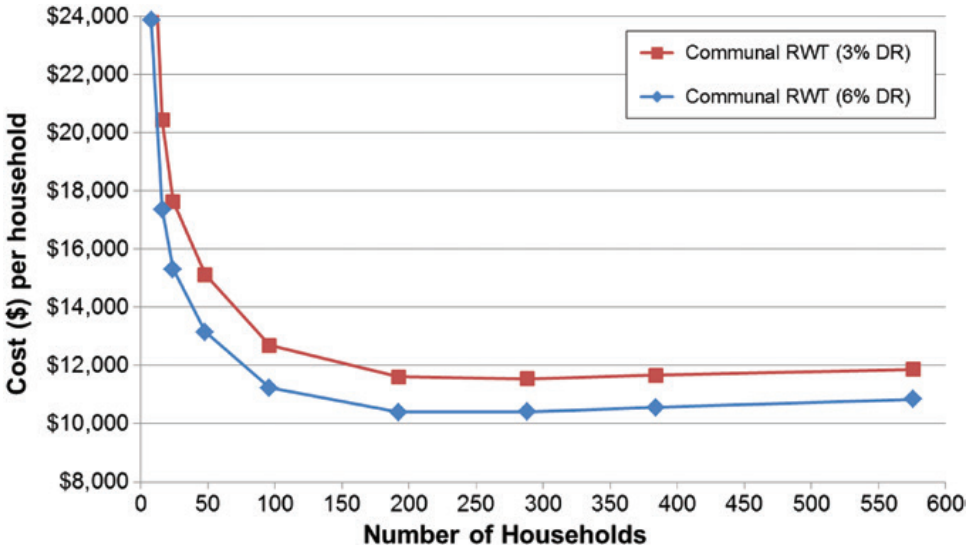


Figure 12.7 NPV costs per household in a communal rainwater harvesting system for a 3% and a 6% discount rate.

The results suggest that the optimal household scale was in the range of the 192 to 288 households, as shown in Figure 12.7. The lowest NPV was found to be $11,543 per household for a development layout of 288 households. The cost of the communal system per household starts increasing beyond this number of dwellings due to the dis-economy of scale from the increasing pipe costs not being adequately counter balanced by the economies of scale of other components within the system, as depicted in Figure 12.8. Within the optimal household layout, the cost of pipes made up 42% of overall costs, with treatment and storage units accounting for 33% and the rest made up of recurring costs.

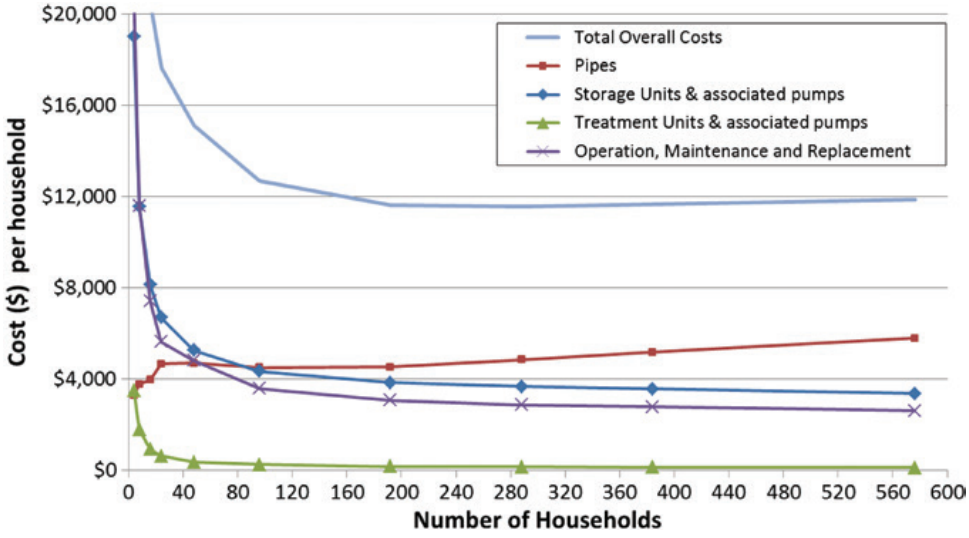


Figure 12.8 Cost per household of the various components required in a communal rainwater harvesting system.

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The sensitivity analysis doubled the discount rate to 6% and explored the effect on the system cost and optimal scale and layout. The overall costs are not heavily affected by discount rates in this case as the communal system is to be built within one year, incurring major capital investment in the first year. The increased discount rate only had a small effect on the cost because of the relative importance of capital costs to operating costs. In addition, the increased discount rate caused only minor change to the optimal housing scale and layout. A similar result was also noticed by Clark (1997) for his analysis of a communal sewer model.

The levelised cost of rainwater supply from various system configurations was also estimated for both discount rates over a 50-year analysis period. Levelised costs were obtained from Equation 1 in Section 12.2.2 and have been plotted for each household layout in Figure 12.9. The levelised cost for each layout and discount rate is also listed in Table 12.5. Comparison with the NPV chart shows that there was no difference in the optimal household scale, which occurs from 192 to 288 households for both discount rates. The levelised cost of a communal system at the optimal scale was \$6.11/kL for 94% supply reliability of the tank and household occupancy of 2.6 persons.

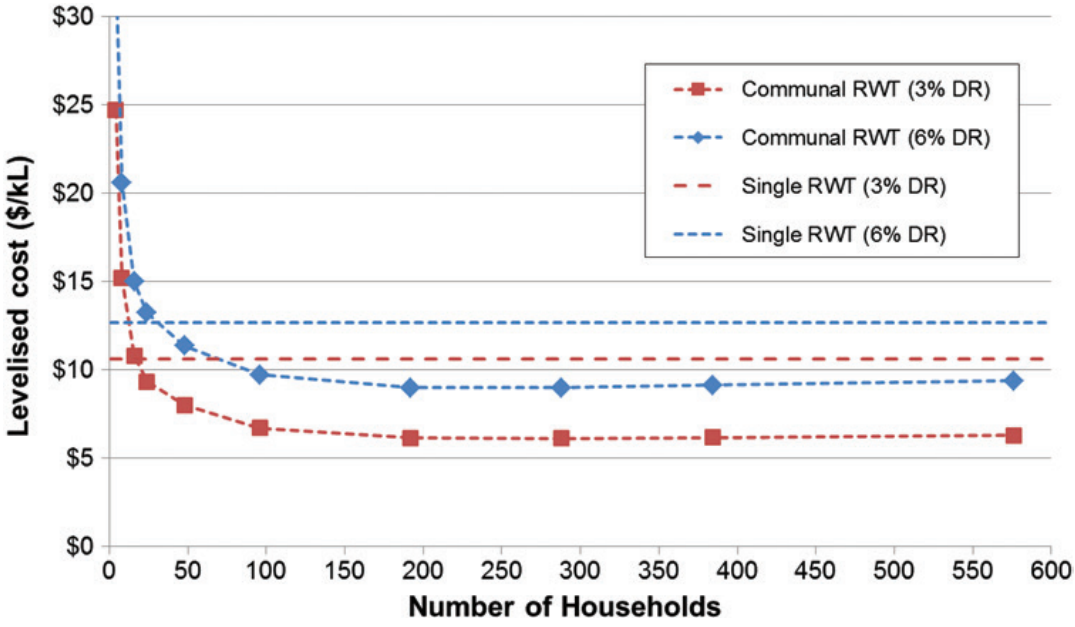


Figure 12.9 Levelised costs (\$/kL) per household for a communal rainwater harvesting system and a household rainwater tank (RWT) for 3% and 6% discount rates.

As a comparison, the NPV of a single household rainwater tank (RWT) for non-potable use (at 54 L/p/day) was calculated using similar parameters (e.g., system costs, analysis period, discount rates, household occupancy) to the communal system. Note that the performance of individual rainwater tanks can have a large range due to the variability in physical performance such as yield, which was explored in the Section 12.2.2. For a 5 kL household rainwater tank, the volumetric reliability was estimated to be 90% with a NPV of \$12,576 for a 3% discount rate, over the 50-year analysis period. The levelised cost was estimated as \$10.60/kL and is plotted in Figure 12.9 to compare against the levelised cost of communal systems. The levelised cost was lower for a communal rainwater harvesting system with more than 24 dwellings than for a single household rainwater tank.

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Table 12.5 Levelised cost ($/kL) at different development sizes.

Household numbers	Levelised cost ($/kL) with discount rates	
	3%	6%
4	$24.71	$32.69
8	$15.19	$20.59
16	$10.80	$14.98
24	$9.32	$13.22
48	$8.00	$11.36
96	$6.71	$9.71
192	$6.15	$8.97
288	$6.11	$8.98
384	$6.17	$9.11
576	$6.28	$9.36

12.4 COST BENEFIT ANALYSIS OF RAINWATER TANKS

As noted earlier in this chapter, comparing the levelised cost of water supplied by rainwater tanks with the levelised costs of alternative supply sources in a given location allows us an understanding of the relative cost-effectiveness of rainwater tanks as a water supply option.

In this section, we discuss the strengths and weaknesses of cost-effectiveness assessment, before outlining the role of cost-benefit analysis (CBA) in assisting decision-making, and presenting a CBA framework for rainwater tank assessment. We also provide a case study in the field. Benefits explored include those to the user (from increased water supply reliability), to the water supply system (from deferral of future supply augmentations), to the stormwater system (from reduced costs of stormwater management) and to the environment (from increased ecosystem services).

12.4.1 The role of cost-effectiveness assessment

Cost-effectiveness assessment is a very useful tool when project costs are well understood, but project benefits are poorly understood or difficult to quantify. In the calculation of levelised cost for water supply options, the benefit stream is typically limited to the volume of water supplied ($/kL).

However, some water supply options are recognised as having additional benefits to society beyond the volume of water produced for consumption. These could be, for example, the generation of improved environmental outcomes, diversifying the water supply risk profile, or the avoidance of other system costs. Many of these can be quantified and could therefore significantly affect the relative ranking of different water supply options.

The challenge then becomes how to incorporate these benefits into a framework for assessment that allows the full merits of each water supply option to be appropriately considered. It is possible to subtract the benefits from the cost stream within a levelised cost assessment. However, the output is not strictly a cost-effectiveness assessment and can be easily confused.

A preferred approach would be to use a framework expressly designed to incorporate all the costs and benefits of a water supply option compared with the water supply system in the absence of the option. This is a cost-benefit framework.

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12.4.2 Cost-benefit analysis

CBA is an economic tool used to aid decision-making in policy contexts such as water supply planning. It is often preferred by public policy decision-makers for its rigour and transparency, and has become a standard tool of Government in recent years (Commonwealth of Australia, 2006).

CBA compares the monetary costs and benefits associated with a policy, project or option, and can be used to compare alternatives or explore the justification of an option compared to a 'base case' (Commonwealth of Australia, 2006). In the context of rainwater tanks, the relative merits (or 'net benefits') of instituting compulsory rainwater tanks on new dwellings has been assessed using CBA (MJA, 2012).

CBA builds upon cost-effectiveness assessment described above by quantifying and incorporating the range of benefits that is attributable to an option over a given time period. CBA can be applied to rainwater tanks to develop a fuller understanding of the value of rainwater tanks in the context of water supply planning.

As per cost-effectiveness assessment, the full capital and operating costs of rainwater tanks are recorded over a chosen time period, along with the yield. These are discounted to present day values using an appropriate discount rate.

Critically, a CBA assesses costs and benefits from society's point of view, rather than from the perspective of the user or the water supplier. Many of the benefit streams accrue to parties that may not bear the private costs of rainwater tanks, posing important questions about who should pay and should the investment proceed. We will discuss this further below.

By quantifying the full range of benefits and costs in dollar terms, it allows us to make an informed choice on the relative merits of rainwater tanks. By subtracting total present value costs from total present value benefits, we produce the net present value (NPV) of rainwater tanks to society. Dividing present value (PV) benefits by PV costs informs us of the ratio of benefits to costs: that is, for every dollar spent, what is the scale of benefit produced? This Benefit/Cost ratio (BCR) allows us to compare rainwater tanks against other alternatives.

Importantly, CBA is only one tool to assist decision-making. The main challenge for applying CBA to rainwater tanks is appropriately delineating and quantifying the various benefit streams that rainwater tanks produce. Not all benefits are quantifiable, and a broad range of issues need to be considered by decision-makers.

12.4.3 Proposed economic framework

An economic framework for assessing the broader range of economic costs and benefits of rainwater tanks is presented in Figure 12.10. In this framework, we conceptually commence at cost neutrality ($0), with rainwater tank costs (red bars) adding in a downwards direction, and benefit streams (in green) adding upwards.

If the combined benefit streams total more than the combined cost streams, the economic viability threshold is exceeded, and hence rainwater tanks are a justifiable economic investment for society in that context.

12.4.3.1 Cost streams

Cost streams for rainwater tanks are relatively uncontroversial, and would not differ methodologically from those outlined for cost-effectiveness assessment. Essentially, they include:

- Capital costs of the rainwater tank, including the tank itself, siting and installation costs and any associated capital (such as pumps);
- Operating costs, essentially relating to energy use of the pump; and
- Maintenance costs to keep the system in good working condition.

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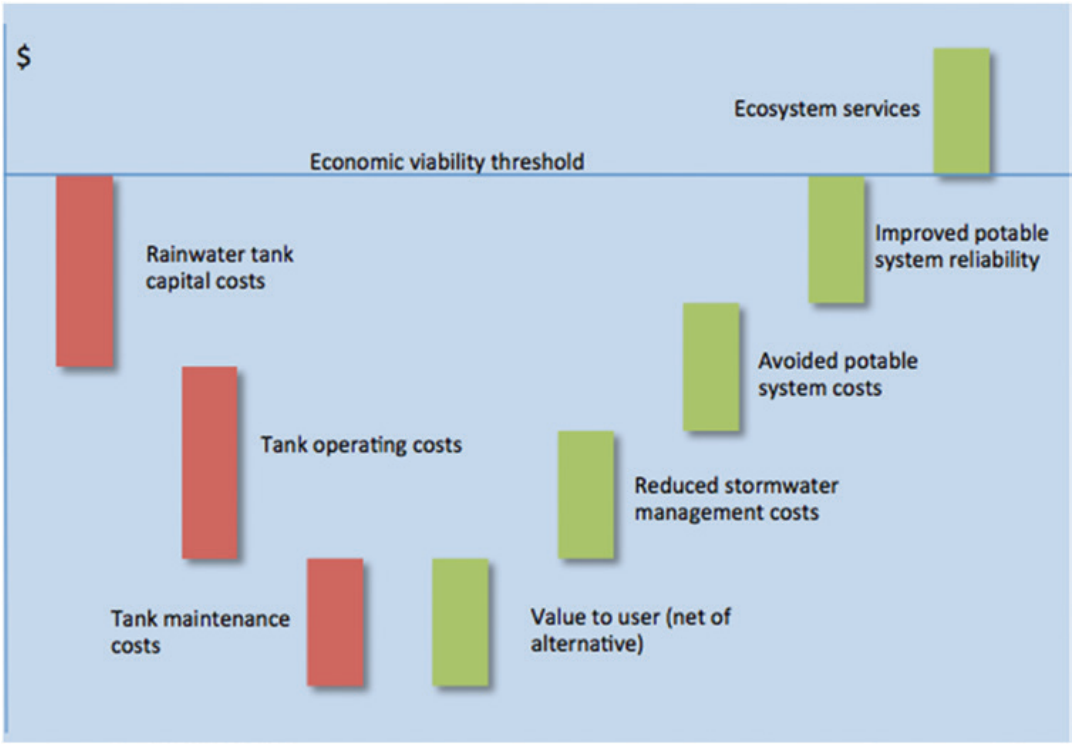


Figure 12.10 Economic framework for rainwater tank costs and benefits (adapted from Pickering, 2013).

Additional costs may be relevant, depending upon the specific circumstance. For example, potable consumption of rainwater may be found to incur health costs, which could be quantified and included.

12.4.3.2 Benefit streams

The economic benefits of rainwater tanks are significantly more complex than their costs, and accrue to different parties in different ways.

12.4.3.2.1 Value to the user

The economic value of rainwater tanks to the user refers to the additional value provided by rainwater tanks beyond which the user would have received without the tanks. In urban settings with a reliable potable water system, this economic benefit of rainwater refers predominantly to the greater water supply reliability to avoid outdoor water restrictions during times of mains water shortage.

Here we distinguish between the financial benefit to the user of avoided potable water charges, and the economic benefit of avoiding the production and delivery of potable water when substituted by rainwater tank supply. We address the latter in *avoided and deferred potable system costs* below. To include them both would double-count this benefit.

However, while values for avoiding water restrictions can be calculated, attributing these values to rainwater tanks is extremely problematic, as the reliability performance of tanks is often less than 100 per cent. That is, a 5 kL residential rainwater tank does not allow the user to overcome water restrictions 100% of the time.

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12.4.3.2.2 Reduced stormwater management costs

There are two ways that rainwater tanks may reduce stormwater management costs:

(1) by reducing infrastructure required to improve stormwater quality; and
(2) by reducing costs associated with stormwater conveyance (flood management).

In many urban settings, regulations are now in place to reduce the impacts of new urban developments on stormwater quality. Impervious surfaces in new urban areas increase run-off into local waterways, increasing pollutant loads (nitrogen, phosphorus and sediment), affecting both local waterway health and that of end receiving waters. Regulatory interventions can require that minimum pollutant load reductions be achieved in new developments. These are often met with stormwater filtration areas using biofiltration or wetland creation on public land.[1]

Recent analysis (WaterByDesign, 2010 a; b) suggests that the addition of rainwater tanks in new residential developments reduces the total stormwater pollution load exiting the development, by trapping stormwater during rainfall events. This allows for the reduction in sizing of water quality management capital investments, such as bioretention and constructed wetland areas (see Figure 12.11, which shows a one third reduction in area of bioretention (0.3 m extended detention) required to meet water quality regulations with the addition of rainwater tanks on new dwellings). This saves capital, operating and replacement costs of the water quality actions and is a quantifiable economic benefit of rainwater tanks in new developments. This benefit would not be attributable to retro-fitted tanks as the WSUD devices would already be in place.

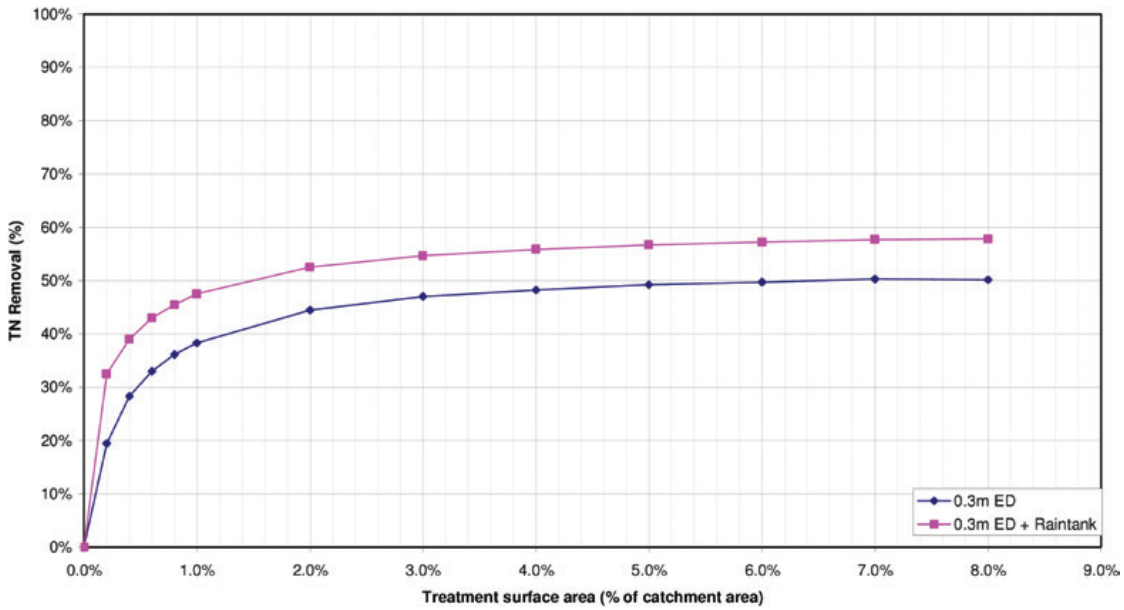


Figure 12.11 Nitrogen removal potential of bioretention with and without rainwater tanks, Weipa Australia (EDAW, 2009).

Evidence in support of savings due to a reduction in stormwater quantity is less clear, and rests on the ability of rainwater tanks to reduce the sizing of stormwater drainage infrastructure. While residential

[1]For example, the State Planning Policy for Healthy Waters in Queensland requires pollution load reductions in new residential developments.

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rainwater tanks appear successful in reducing the impacts of small and medium sized rainfall events, they appear less successful in reducing peak flow events. Also, the risk of homeowners not replacing tanks or pumps when they fail may prove an unacceptable risk to stormwater managers.

No documented evidence of the resizing of drainage infrastructure due to rainwater tanks could be found for this analysis. However, where such a reduction can be identified and applied in practice, such savings are legitimate and should be included in an economic analysis.

12.4.3.2.3 Avoided and deferred potable system costs

A tangible economic benefit of rainwater tanks is the ability to substitute for water delivered through the potable system. This produces economic benefits to the potable system in three main forms:

- avoiding the variable costs of potable water supply for every unit of rainwater that substitutes for potable water;
- deferring potentially large and expensive centralised supply augmentations to the potable system (such as water sources and treatment infrastructure); and
- indefinitely avoiding localised system augmentations.

The variable costs of potable water supply include water treatment costs and the pumping costs of water delivery, for every unit of potable water replaced with rainwater. The costs of existing assets are sunk and cannot be reduced by the addition of rainwater tanks to a water supply system.

The benefit to rainwater tanks of deferring water supply augmentations can be calculated in dollar terms. In practice, this has been undertaken for the system impacts of regulatory requirements for rainwater tanks on new residential dwellings in urban areas. For example in South East Queensland, compulsory rainwater tanks in new dwellings was estimated to defer water supply augmentations by 2–3 years (MJA, 2012). By deferring large costs by several years, significant savings can be realised.

Estimating the deferral impact of a single rainwater tank can be more problematic. If the Long Run Marginal Cost (LRMC) of water supply in the relevant area is known, this can substitute for estimate of variable cost savings and deferral savings.

> *'The term LRMC is used to signify the cost effect of a change which involves some alteration in the amount or timing of future investment. Short Run Marginal Cost (SRMC), on the other hand, takes capacity as given, so relates only to changes in operating costs for example when the transport of additional water requires only additional pumping costs.'* (Turvey, 2001)

LRMC will differ by location and will reflect not just the short term delivery costs of the water supply system, but also the unit impact on the amount or timing of future investments. Ideally, the variable water charge levied by the relevant water authority will reflect LRMC, but this may not be true in all cases.

From a policy perspective, the deferral impact of mandated tanks on all new dwellings could be very significant, especially where high population growth is expected.

In addition to the above, there may be other system costs that can be avoided due to rainwater tanks. For example, it may be possible to indefinitely avoid localised infrastructure augmentations if total local potable demand remains below certain thresholds. Where sufficient penetration of rainwater tanks within these areas maintains total demand below identified thresholds, these avoided costs can be attributable to rainwater tanks.

12.4.3.2.4 Improved potable system reliability

Sufficient penetration of rainwater tanks across a water supply system may improve the reliability of the broader potable system. This improved reliability can be evidenced in the reduced incidence of outdoor

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water restrictions, the value of which can be estimated by calculating the community willingness to pay (WTP) for such a reduction.

Estimating the benefit to a community of avoiding water restrictions has been undertaken in a number of circumstances in Australia, where residents have experienced restrictions on outdoor use regularly over the past decade. For example:

- a study of residents in the Australian Capital Territory (ACT) using the choice modelling method was conducted by Blamey *et al.* (2001) which found that residents were willing to pay an average of only $10 per year (in 1997 dollars) to prevent a 10% reduction in water use ($0.52/kL);
- a later study conducted in the ACT by Hensher *et al.* (2006) at the peak of a ten-year drought found that water consumers were prepared to pay up to $239 annually to avoid longer and/or more severe restrictions; and
- a study conducted in South East Queensland by DBM Consulting (2007) using a choice modelling approach found that consumers were willing to pay an average of $174 per year to reduce Stage 4 water restrictions from 50% of the time to less than 1% of the time.

Critically for any analysis, the quantified impact on changes to the expected incidence of water restrictions due to the use of rainwater tanks must be estimated, before exploring the community willingness to pay for such changes.

12.4.3.2.5 Ecosystem services

Rainwater tanks are associated with improved environmental outcomes, predominantly related to improved ecosystem function in local waterways and end receiving waters. Where appropriately identified and quantified, the impact on ecosystem function is another benefit attributable to rainwater tanks.

Community willingness to pay for improvements to waterway health can be established through a range of 'stated preference' techniques, including choice modelling and contingent valuation.

Critically, there is a strong risk of double-counting benefits when estimating environmental values. For example, the water quality benefits of rainwater tanks described in the section dealing with reduced stormwater management costs (above) reflect a regulatory intervention to protect waterway health. Quantifying this benefit and estimating the waterway health improvement benefit of rainwater tanks double-counts the same benefit.

12.4.3.3 Qualitative benefits

An economic cost-benefit analysis of rainwater tanks will seek to rigorously quantify as full a range of benefits and costs as is conceivably possible. However, not all benefits are feasible to quantify in dollar terms. There exist a range of additional benefits that may not be quantified, but should be considered in qualitative terms. For example:

- Water supply risk diversification: for areas with limited supply diversification (for example, surface water supply from one geographic location), rainwater tanks in urban areas my assist in the diversification of supply risk.
- Financial risk management: large centralised water supply augmentations are expensive and can be subject to significant financial risk due to available capital and debt. In contrast, the capital and operating costs of rainwater tanks are known and relatively stable. Estimates of their cost are relatively robust.

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- Water conservation message: during times of drought, governments invest considerable resources in reinforcing a water conservation message in households. A policy promoting rainwater tanks may strongly support this message, and provide households with a tangible reminder of water availability.

12.4.4 Case study – Toowoomba

A cost-benefit analysis was undertaken to assess the merits of requiring internally-plumbed rainwater tanks to be added to all new detached homes in the Toowoomba region of Queensland. Toowoomba has limited surface and groundwater storages and was significantly adversely affected by drought between 2004 and 2010.

16,000 additional rainwater tanks would be installed with new dwellings over the 40 year analysis period. In assessing a policy of compulsory rainwater tanks with new dwellings, it was accepted that replacement of tanks and pumps could not be influenced by the policy, so tank and pump replacement was excluded from the analysis. Tank and pump cost was estimated at $3,500, annual maintenance and operating costs estimated at $40 per year, and an annual tank yield of 50 kl.

The results of the analysis are summarised in Table 12.6. Quantified benefits include a significant deferral value to the water supply system of rainwater tanks, avoided potable system operating costs, and avoided stormwater management costs (reduced need for stormwater treatment through bioretention). Given high expected population growth in the region, numerous and expensive supply augmentations are planned for Toowoomba, with rainwater tanks allowing the deferral of these by several years. Some additional local augmentations can be avoided indefinitely if per-capita consumption remains below certain thresholds, which rainwater tanks are expected to critically achieve.

Table 12.6 Cost-benefit results of compulsory rainwater tanks on new houses in Toowoomba (RMCG, 2013).*

	NPV ($)	NPV ($) /tank installed
Benefits		
Deferred augmentation	38,298,434	2371
Avoided fixed operating expenditure	9,618,551	596
Avoided variable operating expenditure	3,317,062	205
Bioretention capital expenditure savings	4,797,120	297
Bioretention operating expenditure savings	540,866	33
Total benefits	56,572,032	3502
Costs		
Capital cost of tanks	56,531,715	3500
Pump replacement	0	0
Tank replacement	0	0
Operating costs	4,807,693	298
Abatement cost if tanks not replaced	354,852	22
Total costs	61,694,260	3820
Net cash flow	**–5,122,228**	**–317**
Benefit-Cost Ratio (BCR)	**0.92**	**0.92**

*40 year timeframe, 6.6% discount rate.

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Benefits to the user in terms of increased supply reliability were not calculated, nor were specific ecosystem services. It was assumed that stormwater quality regulations were designed to protect ecosystem health, and as such, counting stormwater management benefits and ecosystem health benefits would represent double-counting of this benefit.

Costs were unsurprisingly dominated by the capital costs of tanks, and also included operating costs as well as other stormwater treatment actions if pumps were not replaced at their end of asset life. Pump and tank replacement costs were not included as the policy could not influence whether this was undertaken or not.

As can be seen from Table 12.6, the quantified benefits of PV $56.6 m over 40 years fall short of the quantified costs of rainwater tanks ($61.7 m), for a benefit-cost ratio of 0.92. As a result, the case for rainwater tanks can only be made by considering various unquantified benefits in addition to the core quantified benefits. These include risk diversification, financial risk management and supporting the public water conservation message.

12.5 DISCUSSION

The costs and benefits of a rainwater tank depends upon a number of variables, many of which are context specific. This is particularly important when applying the results from one study to another location. For example, Alam *et al*. (2012) considered the feasibility for a rainwater tank in Bangladesh which will provide 25 litres per day for drinking and cooking uses for a family. In addition, the rainwater tank provides an alternative to ground water supplies which are potentially contaminated with arsenic. In comparison, in the case of developed countries, the household water use is at least a magnitude higher, health standards may preclude potable use of rainwater and there may be a portfolio of existing alternative supplies.

Cost-benefit estimates may also differ for similar contexts because of the method and perspective of the assessment. This can be partly resolved by specifying the decision to be made and justifying the scope of costs and benefits. Specifying the variation and uncertainty in the data may also account for differing estimates.

Cost-effectiveness analysis provides a relatively simple evaluation of costs for providing water. Nonetheless, this analysis may draw upon sophisticated modelling and provide insight for policy. For example, the case study for individual rainwater tanks provided the following insights:

- Some tanks had very low yields and performed much worse than the rest of the tanks within the same rainfall region. This suggests that simple measures such as maximising the roof area connected to the tank could improve the overall performance of tanks in a region.
- Some variables may not be independent and the calculation of cost-effectiveness may require further analysis. For example, a high initial capital cost for a pump may be associated with a longer life and lower energy costs. This requires further data collection of cost and performance which may also be useful to inform consumer choice.
- The cost of maintaining a rainwater tank increased greatly if recommended health guidelines were followed. This suggests the need for further understanding of the risks to health versus the cost savings for the owner for current practice.

Communal rainwater tanks systems provide an approach to simplify and coordinate maintenance issues as well as optimise the performance of the system. Similarly, the cost-effectiveness analysis of communal rainwater tanks draws upon detailed system modelling and provides the following insights:

- communal rainwater tanks can be more cost-effective than individual rainwater tanks. However, if there are too few households connected to the system (24 houses in the case study) then the benefits of a communal system are reduced. In addition, if there are too many households connected to the

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system (beyond 576 houses in the case study) then the benefits from greater economies of scale also begin to reduce (Gurung & Sharma, 2014).

- the type of end-use for the water can effect system design and scaling of infrastructure. For example, a system designed for non-potable end uses would avoid costs for treatment processes such as filtration and chlorination and may justify a lower reliability (from 94 to 90%) which would result in significant cost savings for the storage tank and pipe sizes.
- the topography of the land can also effect sizing and excavation costs. For example, steeper areas require smaller pipe sizes but potentially deeper excavations for rainwater collection pipes.

Cost-effectiveness analysis allows a simple comparison to the cost of other options for providing water. As noted above, some caution is required to account for variation in performance as well as other benefits that may not be considered. Nonetheless, a comparison of the cost-effectiveness can provide insight to the variation and other benefits required to counter the difference in cost-effectiveness of two options. For example, upper range estimates for the cost of water from measures such as demand management, sea water desalination and long distance pipelines are about $1.45, $3.00 and $9.30 per kilo litre respectively (Marsden Jacobs, 2007). Although these estimates are somewhat dated, it suggests that rainwater tanks are a relatively costly method of providing water based on the upper range estimates presented in this report. This suggests that other significant benefits beyond the supply of water may be required to justify rain water tanks.

Cost-benefit analyses can be used to consider the range of other benefits from rainwater tanks. Applied cost-benefit analysis of decentralised water supply options can be a complex task and benefit valuation can be challenging. However, significant benefits to the broader water supply system of rainwater tanks can be observed, as well as to the environment through stormwater management. These benefits extend beyond those to the direct user of rainwater, to all water supply customers and broader society.

This raises important questions about who benefits and who pays for rainwater tanks. Traditionally, rainwater tanks are paid for by householders as they are considered the main beneficiary of them. Government contribution is sometimes undertaken with a ‘rebate’ of varying value that may or may not be linked to the broader benefit of the rainwater tank to the supply system and the environment.

Using the approach described a case could be made for Government to bear the cost of the rainwater tank, with the tank yield being charged as per other water supplies (less the value of the land lost due to situating the tank on the householder’s land).

12.6 CONCLUSIONS

The economic evaluation of rainwater tanks needs to consider the decision to be made and the range of costs and benefits to be considered. This is particularly important for comparisons of alternative options.

A detailed analysis of the system design and variables can provide insight into design and policy. When coupled with cost-effectiveness analysis, a simple comparison between options for the cost of supplying water can be made. In the Australian context, rainwater tanks appear to be a relatively costly means of supplying water. However, there is large variation in the cost-effectiveness of rainwater tanks and theirperformance is dependent on a number of local factors.

Rainwater tanks can also provide a number of other benefits such as stormwater management and improved conditions for waterways. A detailed cost benefit analysis can provide insight into the benefits as well as their distribution. This can be used to compare the cost benefit ratio of water supply options as well as inform policy such as rebates to a household to account for the broader social and environmental benefits.

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Chapter 13

Impact of rainwater tanks on urban hydrology and stormwater quality

Matthew J. Burns, Anthony R. Ladson and Tim D. Fletcher

ABSTRACT

Urbanisation alters catchment hydrology and receiving water quality. These impacts have been identified as primary stressors to urban stream ecosystems. The protection or restoration of urban streams requires approaches to stormwater management which focus on protecting or restoring natural flow- and water quality regimes. Rainwater tanks have a major role to play in such approaches. They can reduce the frequency, magnitude and volume of urban stormwater runoff delivered to streams. They can also improve stormwater quality. Other benefits of using rainwater tanks include: urban cooling and mitigation of urban flooding. This chapter describes the changes in stormwater quality and quantity due to rainwater tank implementation in urban landscapes.

Keywords: flow-regime; harvesting; source-control; stormwater; retention waterway.

13.1 INTRODUCTION

Urbanisation alters catchment hydrology and receiving water quality. The creation of impervious surfaces (e.g., roofs, roads and pavements) and conventional stormwater drainage consistently results in a 'flashy' hydrograph and one which has increased pollutant concentrations. These changes have been identified as primary stressors to urban receiving waters and streams. Most urban streams are ecologically degraded (e.g., King *et al.* 2011; McIntosh *et al.* 2013a).

Urban stream protection or restoration requires approaches to urban stormwater management which intervene in conventional stormwater drainage and mitigates associated changes to catchment hydrology and receiving water quality. Such approaches aim to restore natural hydrology at allotment scales, ultimately to return catchment-scale flow and water quality regimes towards their pre-development condition.

A range of different stormwater source-control measures can be used to restore natural hydrology at small scales – for example, rainwater tanks, rain-gardens, infiltration trenches, and so on. Rainwater tanks, in particular, have a major role to play in mimicking natural evapotranspiration losses – a requirement to restore the ecological integrity of urban receiving waters.

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This chapter provides information on the impact of urbanisation on stream hydrology and water quality; conventional approaches to urban stormwater management in Australia; and how urban stormwater can be managed for stream protection or restoration. In particular, we describe the role of rainwater tanks in restoring hydrology of urban catchments and in protecting stream health. Other benefits of using rainwater tanks are also discussed.

13.2 IMPACTS OF URBANIZATION ON STREAM HYDROLOGY AND WATER QUALITY

13.2.1 Stream hydrology

When a catchment becomes urbanised, the land surface is substantially modified and this alters catchment hydrology (Booth & Jackson, 1997). Deep-rooted vegetation such as trees – which are high water users – is cleared and replaced with lower water using vegetation (e.g., gardens and lawns). This reduces catchment evapotranspiration (Zhang *et al.* 2001). In addition to vegetation clearance, soil compaction is common, which reduces groundwater recharge (Price, 2011). Probably the most unambiguous effect of urbanisation is the covering of land with impervious surfaces (e.g., roofs, roads, and pavements). Most rain falling on impervious surfaces becomes urban stormwater runoff – little is evaporated (~0.5–1 mm/day; Boyd *et al.* 1993) and none is infiltrated. In most urban catchments, urban stormwater runoff is routed directly to streams via conventional stormwater drainage (i.e., the stormwater network).

In a recent review, Burns *et al.* (2012) summarised the impacts of urbanisation on stream hydrology which included:

- Increased frequency, magnitude and volume of storm flow;
- Increased volume of total runoff;
- Reduction in the volume of summer and winter baseflow;
- Increased frequency of low-magnitude flows; and
- Reduced storm recession time.

In general, the impacts described above change the hydrograph from stable to 'flashy' (Figure 13.1). The hydrograph of the non-urban catchment is stable, with fewer high-flow events and plentiful baseflow. In contrast, the hydrograph of the urban catchment is 'flashy' with many peaks and little baseflow. Importantly, these impacts are driven by conventional stormwater drainage which transfers water from impervious surfaces directly to streams.

13.2.2 Water quality

Urbanisation not only effects water quantity and the timing of flows, there are also effects on water quality. The degradation of the water quality of receiving waters by urban stormwater has been extensively researched (e.g., Novotny & Olem, 1994; Soranno *et al.* 1996; Hatt *et al.* 2004). In the last few decades, there have been a number of major reviews of stormwater quality which have identified pollutant types, their sources and observed range of concentrations (Torno, 1984; Terstriep *et al.* 1986; Makepeace *et al.* 1995; Duncan, 1999; Fuchs *et al.* 2004; Duncan, 2006; Sidhu *et al.* 2012).

Pollutants are generally classified into sediments, nutrients, heavy metals, organic matter (and oxygen demanding material), pathogens, as well as pesticides, herbicides and micropollutants (Table 13.1). The sources, mobilisation and treatment of pollutants will depend on their characteristics, with dissolved pollutants typically being much more difficult to remove than those attached to sediment particles (Carleton *et al.* 2000).

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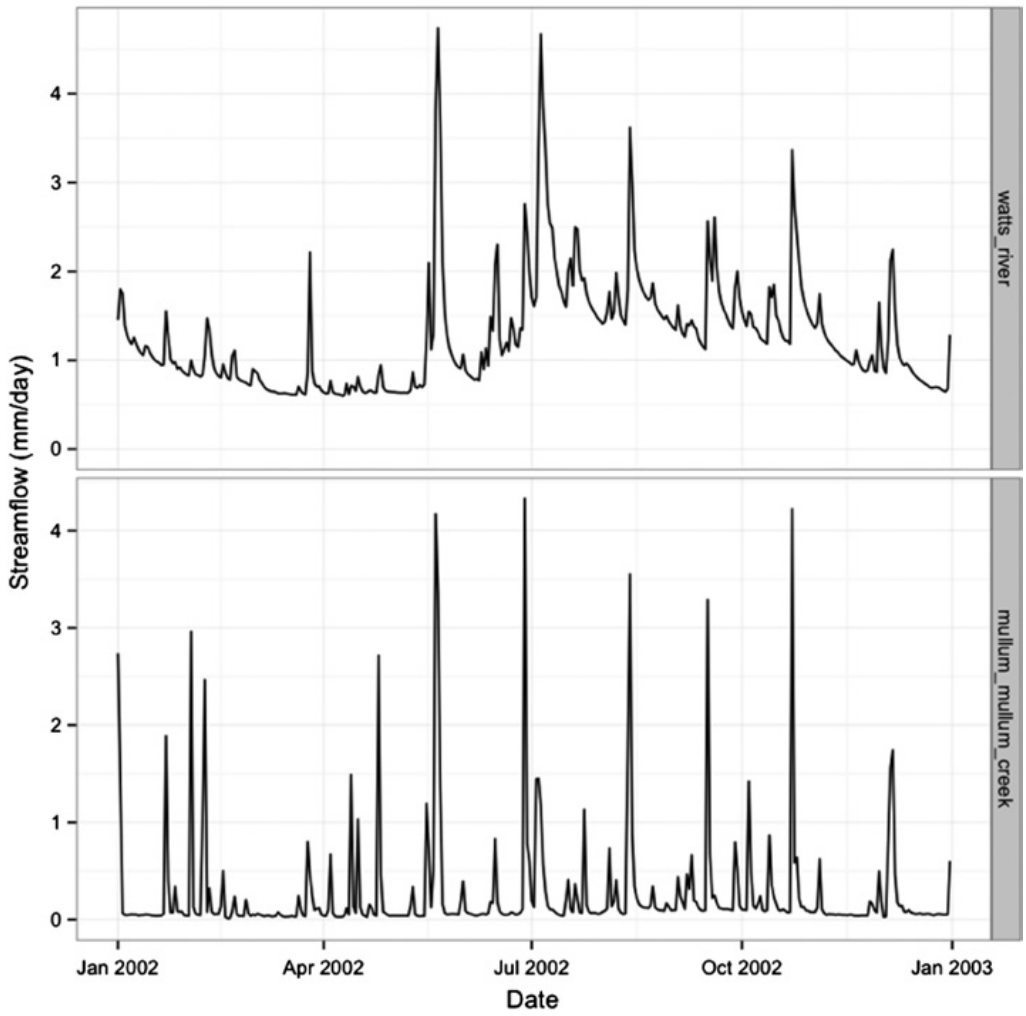


Figure 13.1 Comparison of the 2002 annual hydrograph of a non-urban (forested) catchment (top panel) with a nearby urban catchment 'flashy' (bottom panel) in Melbourne, Victoria.

Understanding the mechanisms by which urban stormwater runoff becomes polluted and which in turn, pollutes receiving waters, is critical to developing strategies to mitigate degradation. Urbanisation is a major generator of pollutants which are sourced from activities such as civil construction, house construction, transport, vegetation management and industrial processes (Ahlman *et al.* 2005). Urbaniszation also dramatically increases the efficiency with which any pollutants generated within the catchment can be mobilised and transported to receiving waters (Mason *et al.* 1999; Francey *et al.* 2011). Given this, attempts to reduce stormwater pollution are typically aimed either at reducing the mobilisation of pollutants at source (Taylor & Fletcher, 2007), treating and retaining them in appropriately designed treatment measures (Winer, 2000), or removing the runoff water altogether through rainwater and stormwater harvesting (Fletcher *et al.* 2008).

A number of reviews of roof runoff quality are available (Duncan, 1999; Duncan, 2005; Meera & Mansoor Ahammed, 2006; Lye, 2009; Abbasi & Abbasi, 2011). It is often assumed that water from roofs is relatively clean, but as can be seen from Table 13.1, the concentrations of pollutants from roofs can actually

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Table 13.1 Principal sources, concentrations, impacts and treatment of pollutants in (i) general urban stormwater runoff and (ii) impervious roof runoff (data only provided where available).

Pollutant type	Principal sources	Concentrations in general urban runoff and roofs typical value (range) (mg/L or as specified)	Typical impacts	Treatment mechanisms
Suspended sediments	Erosion (construction, catchment, channel), sewer inputs, transport, industry.	General: 140 (50–500) Roofs: 20 (5–100)	Transport of other (attached) pollutants, smothering of habitat.	Sedimentation (decantation), filtration.
Turbidity		General: 60 (15–300)	Reduction in plant growth in receiving waters.	
Nutrients *Total Phosphorus*	Erosion (construction, catchment, channel), sewer inputs, industrial emissions, atmospheric emissions.	General: 0.25 (0.08–0.8) Roofs: 0.13 (0.05–0.3)	Eutrophication, algal blooms, change in species composition, and so on.	Filtration and sedimentation (for particulates), adsorption, bacterial and plant uptake (biofiltration), denitrification for N removal.
Total Nitrogen		General: 2.2 (0.7–6) Roofs: 2 (0.7–6)		
Heavy metals *Lead*	Vehicle wear, industrial emissions, street furniture, roof washoff, pesticides.	General: 0.15 (0.04–0.6) Roofs: 0.022 (0.005–0.1)	Toxic effects on a range of organisms such as macroinvertebrates and plants.	Filtration and sedimentation (for particulates), adsorption.
Zinc		General: 0.3 (0.1–1.0) Roofs: 0.16* or 4** (0.05–20)		
Copper		General: 0.08 (0.02–0.3) Roofs: 0.024 (0.007–0.08)		
Cadmium		General: 0.005 (0.001–0.02) Roofs: 0.0006 (0.0002–0.002)		
Chromium		General: 0.022 (0.006–0.11)		
Nickel		General: 0.04 (0.02–0.08)		
Iron		General: 4 (0.08–9.0)		
Manganese		General: 0.3 (0.09–0.8)		
Mercury		General: 0.25 (0.06–0.8) µg/L		

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Organic pollution *BOD*	Fuels, sewer inputs, leaf material, erosion.	General: 15 Roofs: 4	Odours (e.g., SO2), asphyxiation of respiring organisms, release of P from sediment due to redox conditions.	Filtration, adsorption.
COD		General: 70 Roofs: 21		
Total organic carbon		General: 25 (15–45)		
PAHs, other hydrocarbons		General: 0.00024–0.013 (Total PAH)	Impacts on human health, aquatic organisms, and so on.	Adsorption, fine filtration, biological degradation.
Pathogens (and pathogenic indicators) *Total coliforms*	Sewer inputs, animal waste.	General: 7.0 to 1.8×10^7 CFU/100 mL	Impacts on health of humans and livestock. Restricts access to water for recreational purposes.	Filtration, exposure to sunlight, disinfection (UV, chemical).
Escherichia coli		General: 12 to 4.7×10^3 CFU/100 mL		
Faecal coliforms		General: 0.2–1.9×10^6 CFU/100 mL Roofs: 60 (6–600)		
Faecal streptococci		General: 3 to 1.4×10^6 CFU/100 mL		
Pesticides/herbicides	Landscape maintenance, agricultural land, industrial processes.		Impacts on health of humans, livestock and aquatic organisms. Possible accumulation effects through food chain.	Adsorption and fine filtration. Removal methods not yet well understood nor tested.
Glyphosate		General: <0.03–232 μg/L		
Diuron		General: 0.03–1.75 μg/L		
Dieldrin		General: <0.02–0.2 μg/L		
Isoproturon		General: <0.01–0.14 μg/L		
Metaldehyde		General: <0.02–0.58 μg/L		
AMPA		General: 0.14–9.37 μg/L		

Sources: Makepeace *et al.* (1995); Fletcher *et al.* (2005); Duncan (2006); Lawrence & Breen (2006); Zgheib *et al.* (in press).
*Non-zinc roofs
**Zinc roofs

be quite elevated, particularly for heavy metals, bacteria and nitrogen. Indeed, nitrogen concentrations from roofs are generally similar to those from stormwater runoff.

The level of atmospheric pollution can also be quite high (Gôbel *et al.* 2007), meaning that runoff even from a nominally clean roof surface can be elevated in some pollutants (Huston *et al.* 2009; Huston *et al.* 2012). For example, rainfall concentrations of nitrogen in urban areas can be around 2 mg/L (Duncan, 1999). Even particulate pollution can be elevated from roofs, due to build up and wash off of pollutants (Egodawatta *et al.* 2012; Gunawardana *et al.* 2012). Despite these observations, the concentrations of many pollutants are typically less from roofs than from other urban surfaces (roads, other paved areas), and many stormwater pollutants are not found at detectable concentrations on roofs.

The urban stormwater quality literature includes many studies that investigated variation in concentrations within a storm event (Sansalone & Buchberger, 1997; McCarthy, 2008; Davis & Birch, 2010). The concept of a 'first flush', whereby concentrations are elevated at the start of a storm due to washoff of accumulated pollutants, is regularly (although not universally) observed on roofs (Gardner *et al.* 2004; Bach *et al.* 2010; Kus *et al.* 2010; Egodawatta *et al.* 2012), leading to the use of 'first flush diverters' for rainwater harvesting systems.

While rainwater tanks (and the associated harvesting of water) are effective in reducing overall pollutant loads, due to their trapping and removal of both the water and the pollutants they contain, receiving waters may experience an increase in pollutant concentrations, as the proportion of relatively 'dirty' runoff from other impervious surfaces, will be increased (Taylor *et al.* 2005). Such an observation makes it imperative – from a stream health perspective – that rainwater and stormwater harvesting strategies be combined with effective treatment systems for runoff which is not captured and used. Given the observation that concentrations of some pollutants can be elevated even during baseflows, because of factors such as land use, leaking wastewater infrastructure and groundwater pollution (Taylor *et al.* 2005; Shepherd *et al.* 2006; Roy & Bickerton, 2012), it is important to recognise that harvesting strategies, for example, rainwater harvesting in tanks, should form just one part of an integrated approach for improving water quality in urban streams.

13.2.3 Stream ecological consequences

The impacts of urbanissation on stream hydrology and water quality have been identified as primary stressors to urban receiving waters and streams (Walsh *et al.* 2005; Wenger *et al.* 2009). In urban catchments, almost every time it rains stream biota are disturbed by poor quality urban stormwater runoff. In addition, during dry weather there is less habitat available to stream biota because of reduced baseflow.

Most attempts to restore degraded urban streams have focused on improving instream habitat or riparian zones (Walsh *et al.* 2005). Such attempts have not proved successful because they failed to address the source of stress in urban catchments – urban stormwater runoff. As discussed above, the stressors associated with urban stormwater runoff – altered flow and water quality regimes – are driven by conventional stormwater drainage. Thus to protect or restore urban streams, management should focus on intervening in conventional stormwater drainage and mitigating the associated changes to catchment hydrology and receiving water quality. Provision of rainwater tanks can be an effective mechanism to restore catchment hydrology and water quality.

13.3 CONVENTIONAL APPROACHES TO URBAN STORMWATER MANAGEMENT IN AUSTRALIA

Any discussion of the role of rainwater tanks in mitigating the effect of urbanisation on catchment hydrology needs to be considered in the context of conventional approaches to urban stormwater management. Burns

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et al. (2012) identify two dominant approaches which they describe as: 1) the drainage-efficiency approach; and 2) the load-reduction approach.

In the *drainage-efficiency approach*, the focus is on reducing flood risk. In general, runoff generated during minor storms (e.g., <5 year average recurrence interval [ARI]) is routed directly to streams via the stormwater network. For larger storms (e.g., >5 year ARI), runoff is typically conveyed to retarding basins, where peak flows are reduced to rates that equal the capacity of the downstream stormwater network (Figure 13.2). Inflows to the basin are temporarily stored and released downstream at reduced flow-rates. The amount of temporary storage controls inflow attenuation. The volume of outflow is equal to the volume of inflow. The drainage-efficiency approach alters flow and water quality regimes much to the detriment of urban streams. In most urban settings, there will always be a need for temporary storage (e.g., retarding basins) to protect the community from severe flooding (Smith *et al.* 2013). There are however, alternative ways to manage the runoff generated during minor storms (e.g., <1 year ARI) in order to protect or restore urban streams.

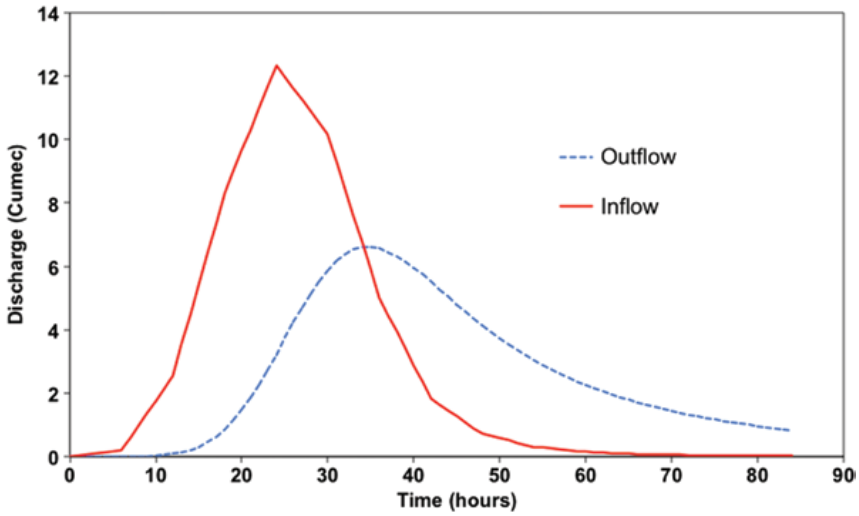


Figure 13.2 Conceptual effect of a retarding basin on catchment hydrology.

The *load-reduction approach* builds on the drainage-efficiency approach, and includes the additional objectives of reducing pollutant loads and the magnitude of geomorphically important flow events (e.g., 1.5 year ARI). This approach is commonly used in Australia, and has led to the installation of treatment strategies such as constructed wetlands in urban areas.

In the state of Victoria, the current load-reduction objectives are to reduce post-development loads of total suspended solids, nitrogen and phosphorus by 80%, 45% and 45%, respectively compared to the loads from a business as usual approach to development (Victorian Stormwater Committee, 1999). There is also an objective to ensure that the 1.5 year ARI peak runoff characteristics remain at pre-development levels, but this objective is rarely applied in practice (Wong *et al.* 2008). Loads-based targets are also common in other jurisdictions in Australia, although more recently these have been combined with flow restoration targets. For example, the state of Queensland requires new developments to retain the first 10–15 mm of impervious runoff (Queensland Government, 2010).

A focus on reducing pollutant-loads and the magnitude of large flow events fails to restore or protect streams because it does not address conventional stormwater drainage and its associated changes to hydrology and pollutant concentrations (Burns *et al.* 2012). Most running waters in the urban landscape are primarily degraded by the frequent delivery of polluted urban stormwater runoff (>100 times/year

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in Melbourne, Australia). Contaminant load-reduction may help protect large downstream waters (e.g., estuaries and bays), but alternative approaches designed for small streams are needed to protect or restore all running waters.

13.4 HOW URBAN STORMWATER CAN BE MANAGED FOR URBAN STREAM PROTECTION OR RESTORATION

This section describes the alternative approach to stormwater management that can protect streams. Rainwater tanks are an important aspect of this approach.

Urban stream protection or restoration requires approaches to urban stormwater management which focus on conventional stormwater drainage and its associated primary stressors (e.g., increased frequency and peak flow of runoff events accompanied by deteriorated water quality). Burns *et al.* (2012) proposed such an approach known as flow-regime management. The approach builds on the evolution of Low Impact Development and related concepts (Fletcher *et al.* 2014). Flow-regime management aims to restore natural hydrology and water quality at small scales, ultimately returning catchment-scale flow and water quality regimes towards their pre-development condition. Fundamental to flow-regime management is scale – by restoring natural hydrology from the hillslopes to the stream, all running waters are restored (even 'zero-order' streams).

To achieve flow-regime management, Burns *et al.* (2013) proposed several urban stormwater management objectives. The objectives target impervious surfaces in the landscape to achieve three things: increase volumetric losses, increase infiltration, and increase initial loss.

13.4.1 Increase volumetric losses

In the pre-development condition, most rain (>80%) falling on the landscape is evapotranspired (e.g., Benyon *et al.* 2012). In contrast, for impervious surfaces very little rainfall (<20%) is evapotranspired. This objective aims to return the amount of water lost from impervious surfaces back to the substantial volumes evapotranspired in the pre-development condition. Volumetric losses include water evapotranspired (e.g., from a rain-garden) and harvested water via rainwater tanks. Harvested water is then used for toilet flushing, clothes washing and then exported out of the catchment via the sewer network. Burns *et al.* (2014) found that achieving such levels of volumetric loss requires substantial stormwater harvesting using rainwater tanks.

13.4.2 Increase infiltration (filtered-flow)

Infiltrated rain that is not evapotranspired reaches the stream as filtered baseflow in pre-development conditions (Kirchner, 2003). For impervious surfaces, little or no rainfall is infiltrated, which is the reason baseflows are usually reduced in urban areas (Hamel *et al.* 2013). The purpose of this objective is to infiltrate some runoff from impervious areas locally, ultimately to restore baseflows. This objective can also be achieved by adding treated (filtered) impervious runoff at a low-flow rate directly to the stream (via the stormwater network). This low-flow rate (essentially a trickle) should approximate the baseflow of geographically similar, nearby undeveloped catchments, and is commonly expressed in units of L/m^2/hour.

13.4.3 Increase equivalent initial loss

For pre-developed catchments, the stream hydrograph typically begins to rise following moderate-to-large rainfall events (e.g., >15 mm). In the urban context, very small rainfall events (e.g., ~1 mm; Zaman & Ball, 1994) result in a catchment-scale response to the hydrograph. This occurs because the stormwater network

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connects 'hydrologically' active impervious surfaces directly to the stream. The objective is to make the 'effective ' initial loss (termed equivalent initial loss by Burns *et al.* 2013) of impervious surfaces more like natural initial loss – similar to the flow restoration target developed by the state of Queensland. Doing so means the rainfall-runoff response of urban catchments will be more like that of natural catchments as the number of small runoff events are reduced.

13.5 THE ROLE OF RAINWATER TANKS IN FLOW-REGIME MANAGEMENT

Rainwater tanks have a major role to play in restoring natural hydrologic processes at small scales for the protection or restoration of urban streams. Roofs make up approximately 40% of a developed area and contribute 50% or more of the impervious area depending on housing density (McIntosh *et al.* 2013b). Therefore, although improved treatment of roof runoff will not address all the hydrologic impacts of urbanisation, rainwater tanks provide the opportunity to address a major degrading influence. Through rainwater capture and reuse, tanks can mimic natural evapotranspiration losses, and if designed appropriately, can also deliver filtered water to the stream (either directly or through infiltration). In doing so, rainwater tanks can decrease the frequency and volume of surface runoff, thereby restoring many aspects of the natural hydrological response.

13.5.1 Increase volumetric losses

In cases where rainwater tanks supply internal end-uses (e.g., toilet flushing and washing machines), harvested water is ultimately 'lost' from the catchment via sanitary sewers. From the point of view of the catchment water balance, such losses are equivalent to evapotranspiration losses. For a parcel of undeveloped area in Melbourne, Australia, that is the same size as the impervious roof area (200 m^2) of a typical dwelling, approximately 96–116 kL/year of rainfall might be evapotranspired (Burns *et al.* 2013). If this same parcel of land were impervious, evaporation losses might only be ~24 kL/year (equivalent to 120 mm). To return the volumetric losses from this impervious area back to those levels in the pre-development condition, a typical rainwater tank would need to harvest approximately 72–92 kL/year of water (i.e., 96–116 kL/year minus 24 kL/year). Such volumes of water are substantial and represent a large proportion of total water demand in a typical domestic household in Melbourne (i.e., indoor water demand for a three person household in Melbourne, Australia can be ~131 kL/year; Roberts *et al.* 2011).

13.5.2 Increase infiltration (filtered-flow)

Rainwater tanks can be designed to help restore lost baseflows in urban catchments. A 'third' outlet pipe (i.e., not the overflow pipe or the mains water back up supply pipe) can be installed on rainwater tanks and be directed to either local soils or the stormwater network (Figure 13.3). Ideally, this pipe should have an orifice designed such that water is released at a rate which approximates the baseflow rate of nearby undeveloped catchments. Water released to local soils can be evapotranspired and infiltrated. Some infiltrated water will reach the stream as filtered subsurface flows. Alternatively, water can be released directly to the stream via the stormwater network. In this case it is suggested that water is treated using say a modular filter (Schang *et al.* 2011). An additional benefit of 'trickle release' of tank water is that it increases available tank storage which in turn decreases the frequency and magnitude of tank overflow events into the stormwater system. A simple MUSIC model of a typical allotment-scale rainwater tank (7 kL tank draining 200 m^2 of impervious roof; uniform demand of 175 L/day) and using 1 year of 6-minute rainfall data (recorded during 1959 in Melbourne, Australia), confirmed these results (Figures 13.4 and 13.5; Table 13.2). In this example, a

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standard design tank ('Tank_A') reduced the frequency of overflows by 64%. Configuring 'Tank_A' with a 'trickle release' pipe ('Tank_B') reduced the frequency of overflows by 88%. The diameter of the 'trickle release' pipe was sized to ensure that outflows did not exceed the baseflow rate of nearby undeveloped catchments (assumed to be 0.1 L/m^2/hour).

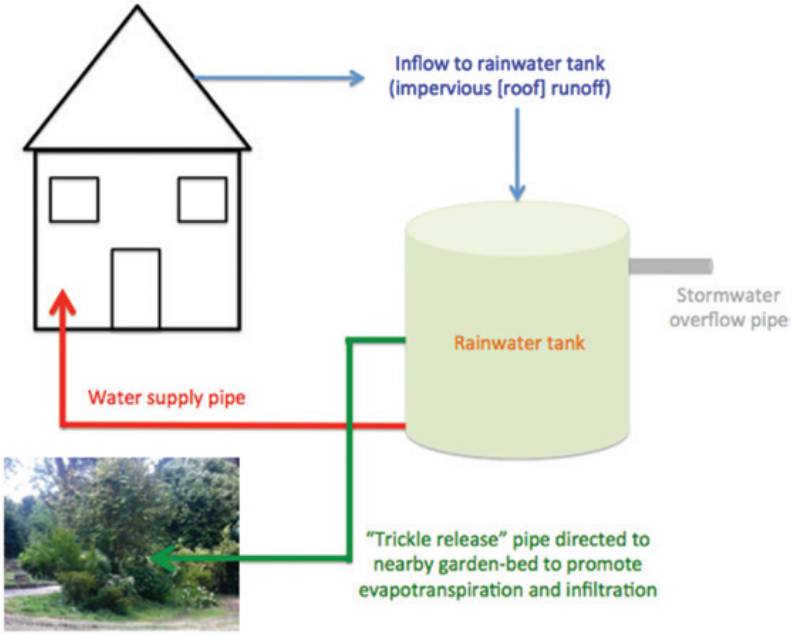


Figure 13.3 An allotment-scale rainwater tank configured with a 'trickle release' pipe.

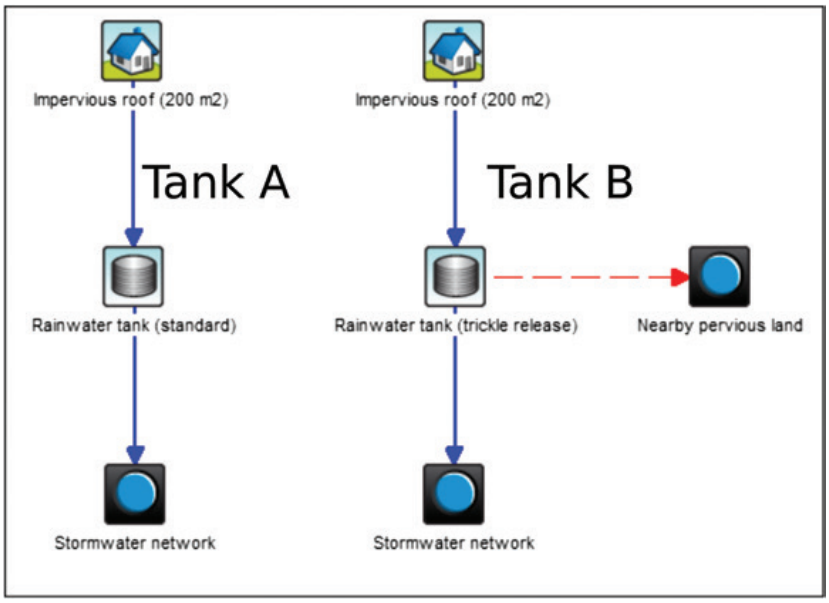


Figure 13.4 A music model for a typical allotment-scale rainwater tank. The tank configuration on the left is a 'standard design' (Tank A) whereas the one on the right is a design with a 'trickle release' pipe (Tank B).

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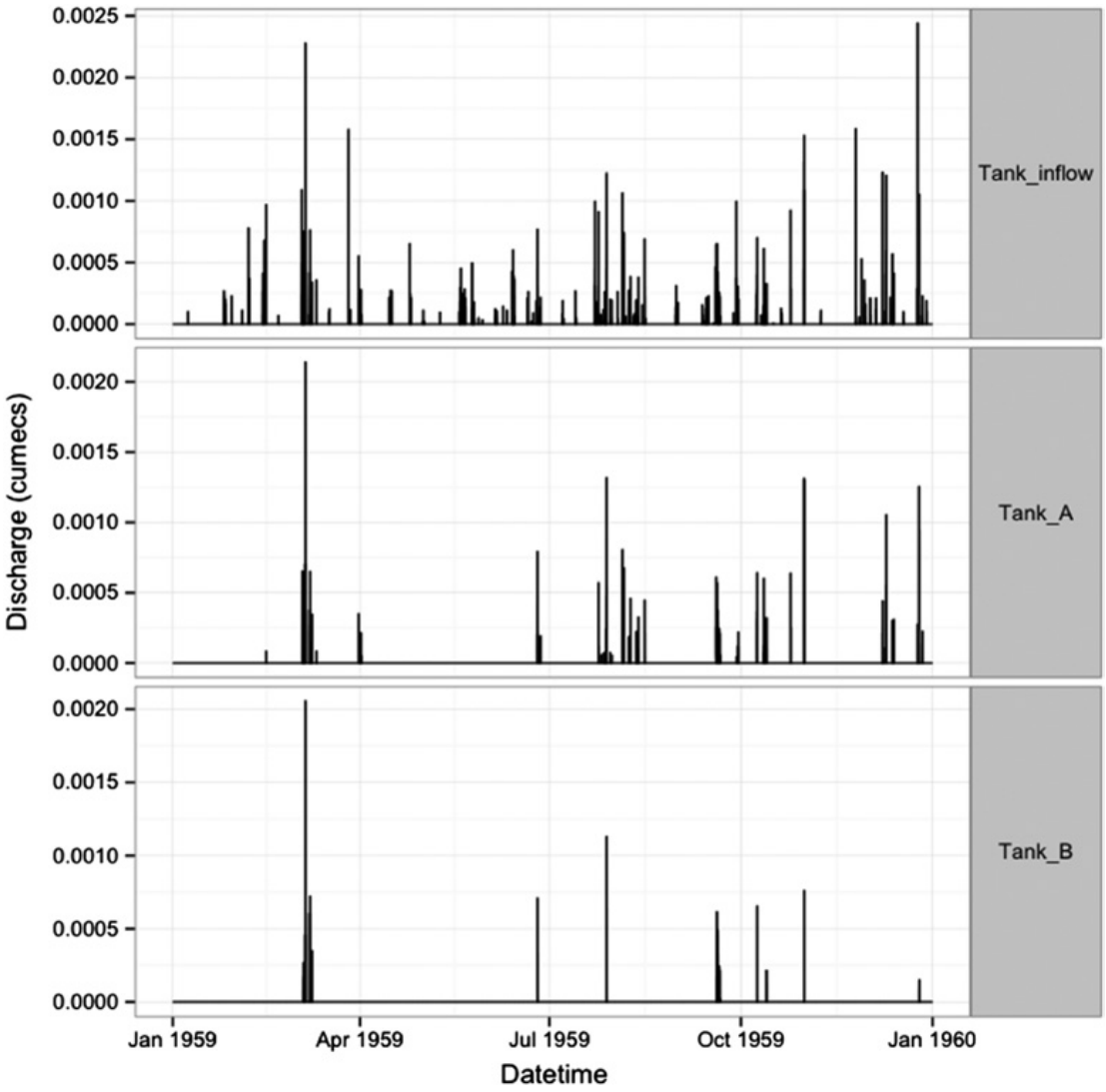


Figure 13.5 Model output from the music model shown in Figure 13.4. 'Tank_inflow' (top panel) predicted impervious (roof) runoff to the tank. The middle panel (Tank_A) shows outflow from the 'standard design' tank. The bottom panel (Tank_B) shows outflow from the tank with a 'trickle release' pipe. Tank_A did substantially reduce the frequency and magnitude of overflows; Tank_B performed even better.

Table 13.2 Stormwater overflow frequency (days/year) for each case presented in Figure 13.5.

Scenario	Frequency of stormwater delivered to streams (days/year)
Inflows to tank ('Tank_inflow')	107
'Tank_A' overflow	39
'Tank_B' overflow	13

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Burns *et al.* (2012) predicted that configuring allotment-scale rainwater tanks to 'trickle' could improve median retention capacity by ~10 mm (based on the connected roof area). They also predicted that such a design could halve the frequency of untreated stormwater overflows (Figure 13.6). 'Trickled' tank water represents a virtual additional water demand. Thus, in cases where demand for rainwater is low – for example, new urban developments with reticulated recycled water – 'trickling' tanks could play an important role in the management of urban stormwater runoff.

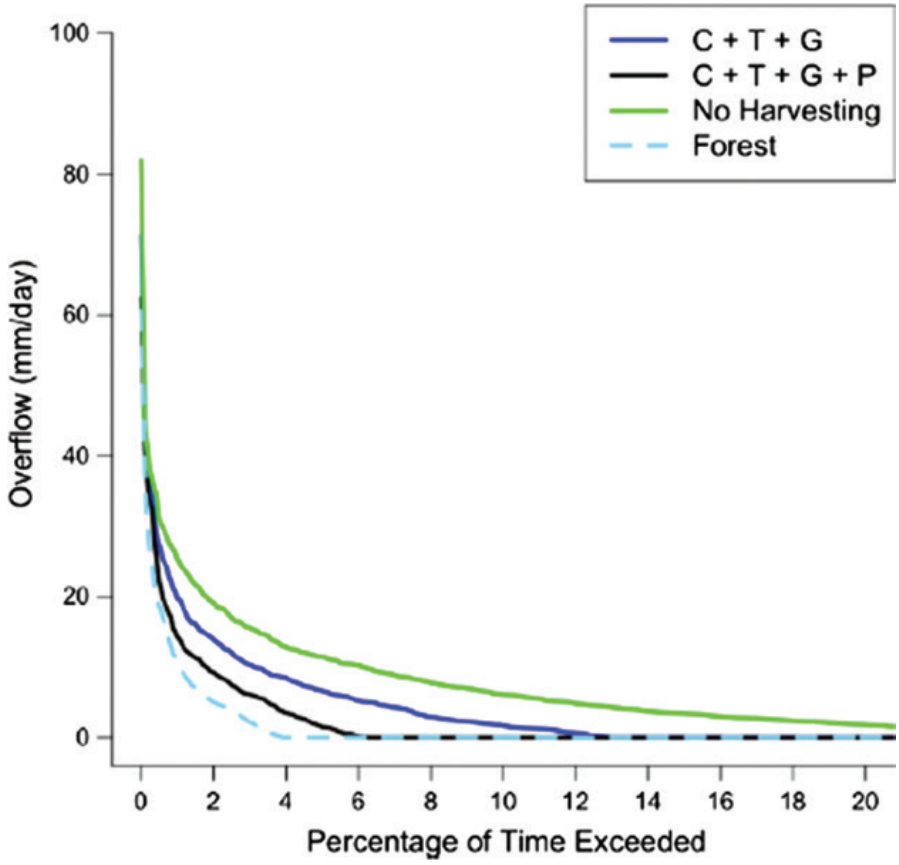


Figure 13.6 Overflow duration curves for a 10 kL rainwater tank draining a 250 m^2 impervious roof in Melbourne, Australia. The blue and black lines represent two different demand scenarios. Blue line = clothes washing (C), toilet flushing (T), and garden watering (G). Black line = same as blue, but rainwater tank is configured with a 'trickle release' pipe (P). Overflow duration curves are also shown for the conditions: 1) no rainwater tank (green line), and 2) the land-parcel was fully forested (dashed blue line). (Source: Burns *et al.* (2012).

The effectiveness of such trickle loss tanks can be improved using intelligent technologies. In Victoria, the company 'iota' (http://iota.net.au; owned and managed by the water retailer South East Water) are pioneering 'Talking Tank' systems. A 'Talking Tank' is a computer controlled rainwater tank linked via telemetry to the Bureau of Meteorology. Prior to a rain event, the computer calculates expected tank inflows based on predicted rainfall. If this inflow exceeds real-time tank storage availability, the computer actuates a solenoid valve in the tank outlet to release tank water in order to reduce stormwater overflows to the stormwater system. Ideally, tank release rates should not exceed the baseflow rate of nearby undeveloped catchments (as discussed previously).

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13.5.3 Increase equivalent initial loss

If a 7 kL rainwater tank draining 200 m^2 of impervious roof (with an initial loss of 0.5 mm) is half full, then it is said to have an equivalent initial loss of 18 mm (in this case calculated as tank storage availability of 17.5 mm + impervious roof initial loss of 0.5 mm). So, >18 mm of rain would be required to result in tank overflows. Given these initial conditions, the tank is helping to make the 200 m^2 of impervious roof, generate a rainfall-runoff response more like that of a pre-development catchment. For a rainwater tank to achieve ideal equivalent initial loss performance, it must be designed appropriately – generally large tanks connected to multiple end-uses are required (e.g., Burns *et al.* 2014).

13.5.4 Water quality and tanks

Although water quality issues in rainwater tanks need to be addressed to provide a fit-for-purpose supply of water for end use (see Chapter 9), there are a range of treatment process that occur in rainwater tanks that improve the quality of water released to the environment via tank overflow.

Roof runoff can be a source of pollutants but many contaminants are removed by sedimentation in the tank, so that water from tank overflow or the trickle outlet should have lower suspended solids than inflow concentrations (Spinks *et al.* 2003; Magyar *et al.* 2011; Egodawatta *et al.* 2012). Micro-organisms are deactivated by storage, and biofilms at the water surface may remove nutrients and contaminants. Coombes *et al.* (2002) showed that concentrations of feacal coliforms, total coliforms, Ammonia, Heterotropic Plate Counts, nitrate and lead were lower in tank water than in roof runoff. In addition, the MUSIC model predicts that a typical rainwater tank can substantially reduce pollutant loads through settling, in-tank processes and diversion of water to sewer via internal end uses (Table 13.3). Further reductions were predicted when the tank was configured with a 'trickle release'.

Table 13.3 Pollutant-loads predicted by the MUSIC model (presented in Figure 13.4) for overflow from a typical rainwater tank ('Tank_A') and a tank configured with a 'trickle release' ('Tank_B').

Scenario	Total suspended solids (kg/yr)	Total phosphorus (kg/yr)	Total nitrogen (kg/yr)
Inflows to tank ('Tank_inflow')	24.4	0.05	0.34
'Tank_A' overflow	3.03	0.011	0.122
'Tank_B' overflow	1.33	0.004	0.045

13.6 OTHER BENEFITS OF RAINWATER TANKS

Much modelling research has shown that rainwater tanks can retain large rainfall events. For example, Burns *et al.* (2012) showed that the median retention capacity (analogous to catchment initial loss) of typical small-scale rainwater tank systems in Melbourne can be ~20 mm.

Coombes and Kuczera (2003) found similar results when investigating the performance of rainwater tanks across Australia, for example, a 5 kL rainwater tank in Melbourne, draining 200 m^2 of roof and supplying water to five people, could retain on average ~3.5 kL (equivalent to 18 mm of roof runoff) before overflow to the stormwater system occurred. The fact that some urban flooding is caused by high-intensity, but low total volume (<20 mm) rainfall events (http://www.bom.gov.au/water/designRainfalls/ifd), highlights the substantial potential of rainwater tanks to reduce flood risk in small urbanised

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catchments. This potential however, remains relatively untested by experimental monitoring and model calibration.

Burns *et al.* (2010) used the RORB model (Laurenson *et al.* 2006) to investigate the catchment-scale implications of allotment-scale rainwater tanks on flood hydrology. They found that rainwater tanks only reduced the magnitude of post-development floods by 10–20% for a hypothetical urban catchment. A significant shortcoming of this and related studies (e.g., Coombes *et al.* 2003), is a lack of hydraulic modelling, thus providing little insight on flood extents.

To explore robustly the flood benefits of rainwater tanks, hydrologic models need to be coupled with hydraulic models. In doing so, consideration must be given to the stormwater network (e.g., Qin *et al.* 2013). Such an undertaking is a topic of future research.

13.7 CONCLUSION

Rainwater tanks have the potential to mitigate the effects of urbanisation on the hydrology and water quality of urban streams. Rain tanks capturing and using rainwater for household uses can compensate for the volumetric increase in runoff that inevitably occurs with urban development. Where there is storage available at the start of a storm, rainwater tanks can increase initial loss from about 0.5 mm, typical of an impervious surface, toward values of about 20 mm which are common in undeveloped catchments. This has the potential to reduce flood risk particularly in small urban catchments as well as reducing the frequency of small runoff events and their peak discharge. Connecting tanks to a range of regular demand end-uses (such as toilets and washing machines) and/or releasing water at a 'trickle' rate into the stormwater network promotes storage availability pre-storm, and helps protect stream ecosystem health.

Protection and restoration of streams impacted by urbanisation requires addressing the source of the hydraulic stress. Rainwater tanks are an important part of the flow regime management required to reduce the number of runoff events, hydrograph flashiness whilst restoring baseflow. There is also potential for rain tanks to substantially improve runoff quality from roofs. Further research is required to demonstrate that tanks can make substantial reductions to the size of stormwater conveyance infrastructure which is designed for large storms. Part of the unknown is the lack of detailed surface hydraulic modelling coupled to tank water balances.

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Chapter 14

Rainwater tanks in Australia: Their social/political context, a research overview, policy implications, future research needs, and application of findings to other countries

Ted Gardner, Don Begbie, Ashok K. Sharma and Grace Tjandraatmadja

ABSTRACT

This Chapter provides an overview of the findings from the preceding 13 chapters and discusses their policy implications for Australian States, and lessons for the international community. But first, it commences with a social/technical history of the development of rainwater tank systems in Australia which has the highest adoption of any country in the world (34% of households). The major end uses are potable substitution in urban areas, motivated by the Millennium drought which occurred during most of the 2000s, and potable supply in peri-urban and rural areas. In other developed countries, the major motivation for tanks is stormwater control, an application which is relatively under researched in Australia.

The major lessons from our systematic scientific study of an essentially trial and error expansion process over 10 years are: our ability to confidently predict rain catch and its reliability over the long-term (say 100 years) provided suitable climate data is available; potable water savings from tanks can be confidently assessed using clever statistical analysis of routine water billing records; that microbiological water quality is probably not sufficient to recommend its use for drinking if traditional potable supplies are available; that lead (Pb) is likely to be a common contaminant in urban Australia that warrants treatment if rainwater is to be used for drinking. Both these microbiological and chemical water quality issues can be overcome by communal tank systems with centralised treatment and management. However, the economics are debatable compared with mains supplied water, but are more attractive than that of individual tanks.

The biggest issues are ensuring that tank systems are installed to specification (requiring a post install audit process), and that they are adequately maintained over the longer term by often disengaged homeowners. The public health implications of poor maintenance (from mosquito borne arboviruses) are likely to be substantial in tropical and semi-tropical areas, but the balance of *who pays/who gains* has yet to be fully resolved by government. The future of tanks in urban society is uncertain as the major water authorities of Australia have invested large sums in climate resilient potable water supplies (e.g., seawater desalination plants) and are often reluctant to invest in alternative water supplies such as tanks or dual reticulation of recycled water. However, recent social research has indicated that Australian water professionals are very concerned with ensuring adequate water supplies given expected climate change,

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and that tanks and recycled water are likely to play a major role here. There are no such doubts about the importance of tanks in supplying water of superior quality to people in developing countries, and results of this body of research has a number of direct applications, albeit with modifications to account for the different social/technological/political contexts.

Keywords: Rainwater tanks; Australia; alternative water resources; potable water substitution; social context; policy implications; implementation drivers; international leanings.

14.1 INTRODUCTION

It's not surprising that this book originated in Australia as the country has a long history of rainwater tanks for domestic supply due to highly ephemeral streams, patchy groundwater (both in quantity and quality) and seasonal rainfall patterns – all combine to require a buffering storage that leads to rainwater tanks. Tanks were initially constructed *in situ* (with solder and rivets) using galvanized corrugated iron – a ubiquitous building product in urban and rural Australia in the 19th and 20th centuries. In fact, tanks for household water supply became as Australian as *meat pies, Australian Rules football, Holden cars and kangaroos*.

As reticulated water supplies became more common in cities and larger provincial towns, tanks fell out of favour, not least because galvanized tanks commonly rusted leading to a mosquito breeding hazard. This was not only an amenity nuisance, but also was a health hazard from mosquito borne arboviruses such as Dengue fever, Ross River fever and Murray Valley encephalitis. In fact, major outbreaks of Dengue fever occurred in South East Queensland (SEQ) from 1911 to 1942, with over 185 deaths and 200 hospitalisations in the mid-1930s (Hurst, 2012). It is not surprising that local authorities banned tank installation in many urban areas (especially SEQ) in the 1950s and this ban remained in force into the 1990s.

However, tanks were a mainstay of potable water supply in rural areas and peri-urban areas without reticulated water (and sewerage). In fact, in 2013 over 34% of Australian households had tanks, with 10% using them as their main source of drinking water (ABS, 2013). In rural areas, tanks tend to be large (e.g., 40 kL+) and connected to most of the dwelling roof area. Cheap electric pumps and pressure switches then allowed pressurised water for all household uses. As power outages are common in rural areas, elevated header tanks were often installed to ensure a 1–2 day's supply of gravity pressurised water was available. About 23% of households in regional and rural Australia (3,365,000 households) currently use tank water as their major source of drinking water (ABS, 2013).

Tanks were initially galvanized corrugated iron (as previously mentioned), but over the last two decades large precast (<25 kL) and cast *in situ* (>30 kL) concrete tanks became popular in rural areas as the manufacturing technology improved. Over much the same time, rota moulded plastic tanks (≤25 kL) came onto the market in a range of shapes and colours – a technology which spilled over into the urban market. These were complemented by corrosion resistant, zincalume corrugated tanks with colour baked in at manufacture – a further adaption from the Australian roofing sector.

Most of the rural/peri-urban tank installations were rudimentary in terms of catchment protection, animal ingress and treatment before consumption. For example, gutter guards were more the exception than the rule, first flush devices were almost unheard of, lead flashing was commonly used as part of roof water proofing, and screens to prevent entry of animals were made of short lived (<10 years) corrodible brass mesh.

As technology improved over the last two decades, rain head screens on downpipes to minimize leaf contamination of tank water (which causes colour/taste issues) and stainless steel mesh screens markedly

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improved the physical quality of rainwater. Many households also installed under kitchen sink filters to remove suspended sediment, with some adding additional filters to reduce bacteria and remove protozoans (e.g., Giardia). A smaller number of households installed disinfection devices such as silver impregnated filters or Ultraviolet (UV) light units.

However with all such devices, maintenance is critical for successful performance, and often the filters became *sources* of contaminants (especially bacteria) rather than *sinks* for contaminants. For example, with UV units the light source needs to be replaced at least yearly, but this is rarely done. On the other hand, those solely dependent on rainwater are very aware of the operation of their collection/storage/supply system and maintenance effort is generally of a high standard. For example, pump failure means no water supply, and if collection efficiency was impaired due to overflowing gutters and/or blocked downpipes, water supply reliability is reduced and potable water might need to be purchased via water truck (at about $210 per 15 kL). This expense focuses the minds of the peri-urban residents and leads them to be highly aware of water efficient practices.

14.2 DRIVERS FOR RAINWATER TANKS IMPLEMENTATION

14.2.1 Australian context

In the mid to late 1990s, environmental sustainability emerged as a fundamental philosophy of urban living which encouraged residents to consume less energy and water, to become more self-sufficient, and to reduce their greenhouse gas footprint. Consequently, energy and water efficient buildings became popular, usually incorporating rainwater tanks for non-potable end uses, as well as solar hot water systems, solar electricity, house insulation and natural ventilation and so on. In some cases, exemplar houses and housing clusters were built and documented to demonstrate just how much reduction in grid supplied water and energy could be achieved. Examples include the Sustainable House in Sydney (Mobbs, 1998), Healthy Home at the Gold Coast (Gardner *et al.* 2003), Fig Tree Place in Newcastle (Coombes *et al.* 2000) and The Currumbin Ecovillage on the Gold Coast (Hood *et al.* 2010). For example, an 80+ percentage in self-sufficiency for water supply from 25 kL household rainwater tanks was measured for the Brisbane eco-development of Payne Road (Gardner *et al.* 2006; Beal *et al.* 2008).

This concept of self-sufficiency gained popularity in Australia's coastal urban communities and led to an explosion in the installation of rainwater tanks. For example from 1995–2013, the percentage of households in Australian cities increased from 24% to 34% (ABS, 2013). Part of this increase was due to extended drought conditions that occurred in all Australian capital cities in the so-called 'millennium drought' from 2001 to 2009 (van Dijk *et al.* 2013), which led to a mixture of self-funded, government rebated and mandated tanks in most urban areas. For example in NSW, the BASIX program required all new dwellings in the Sydney area to reduce their potable water use by 40% by installing internally plumbed rainwater tanks or other alternative non-potable sources (NSW Dept. Planning and Infrastructure, 2004). A similar type of program was introduced by the Queensland government. The Queensland Development Code MP 4.2 – Water Savings Target (QDC MP4.2) required detached dwellings in SEQ built after 1 January 2007 to achieve a mains water savings of 70 kilolitres per household per year (kL/hh/yr) (DIP, 2008). The motivation was acute as SEQ's main water storages dropped to below 17% capacity in August 2007, with about 12 months' supply of drinking water in its reservoirs at the peak of the drought (QWC, 2010), an experience not too dissimilar to that in other capital cities of Australia.

These non-subsidised, mandated programs were complemented by voluntary installations that attracted a rebate of up to $1500 from local and/or state and/or commonwealth governments. In some cases, these rebates could be claimed cumulatively by the householder. In SEQ for example, over 257,000 subsidies for rainwater tanks (worth about $250 M) were granted over the period 2006–2008 under the now defunct

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Home and Garden WaterWise Rebate Scheme. The estimated total water savings was about 6,000 ML/year (Walton & Holmes, 2009). However, less than 7% of these tanks were connected inside the house for toilet flushing/washing machine end uses, as was required for the later mandated tanks. Rather, the water was used for garden irrigation and other external uses that were usually severely restricted by drought inspired water restrictions. In 2010/11 in SEQ, irrigation made up less than 5% of average total household water consumption (Beal & Stewart, 2011). That is, the externally plumbed tanks did NOT provide significant savings to potable water as potable water could not be used for external end uses in the first place under the severe water restrictions in place at the time.

Two main benefits that arose from the mandating/subsidy of rainwater tanks were, firstly, an explosion in the technology ranging from tank construction material, shape, colour and aesthetics to fit into small urban allotments (400 to 600 m^2), to collection (mainly stainless steel mesh screen and guards to prevent leaf/animal/insect ingress, and first flush devices), to mains water top-up (trickle float valve and electronic switching valve), to back flow prevention devices to stop rainwater entering the potable reticulation system, to under-sink treatment units (filters, membranes, UV disinfection units). The other major benefit was a raft of construction, installation and operational standards and guidelines (e.g., SA HB 230, 2006; Australian Government, 2004; WSAA, 2002; Chapman *et al.* 2008; QHealth, 2007; Queensland Government, 2011; NSW Health, 2007; DHS, 2003) which gave both the installing technician (i.e., the plumber) and homeowners an encyclopaedic suite of information *IF* they chose to use it.

New rainwater tank operation technologies are developing with dual objectives of potable water substitution and flood management. IOTA P/L (www.iota.net.au), a commercial arm of South East Water, one of the three water utilities in Melbourne, has developed a technology which monitors water levels in a rainwater tank and automatically releases water at a controlled rate down to a pre-defined level in the tank. The operation is governed by rainfall predictions communicated through remote link with the Bureau of Meteorology. Such a technology (which is very similar to the one in Seoul described by Han & Mun, 2011), if adopted at a large scale, can help in managing local flooding. However, successful, well-documented case studies in Australia are needed for future implementation at large scale.

14.2.2 International context

In the developed countries of Europe, the main driver for rainwater tanks is reducing stormwater inflows into the combined sewer system, thereby reducing sewer overflows, and in some cases local flooding. In Germany for example, there is a tax on impermeable areas in urban areas that increase urban runoff (both volume and peak discharge). Rainwater tanks is one method to reduce this inflow and subsidies and/or tax relief are often granted for this purpose, but do not carry over to promoting beneficial reuse of rainwater, as this would reduce the sales income of potable water utilities (Hermannn & Schmida, 2000; Nolde, 2007). Nonetheless, over 65% of new dwellings in Germany have installed rainwater tanks with an intention to augment potable water supply, adding to the existing stock of about 1.8 million systems (Schuetze, 2013). The motivation appears to be an environmental sustainability ethic, and a personal pride of partial self-sufficiency. Interestingly, Germany also has the highest penetration of domestic solar electricity systems in the world. Similar motivation occurs in some large public buildings, for example Potzdamer Platz in Berlin, as well as some large apartment buildings in Sweden (Villarreal & Dixon, 2005). Given that northern and central Europe are well watered, supplementing potable water supply with rainwater tanks does not seem to be a strong motivation for their adoption. In fact, some countries actively discourage rainwater use, with France actually banning it for even toilet and laundry uses (Vialle *et al.* 2011). This is reminiscent of that old, discredited Korean *saw* that ingesting rainwater will cause baldness (Han & Han, 2002).

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In southern Europe and parts of the northern Mediterranean (e.g., Spain and Greece) where surface/ground water supplies are less reliable, rainwater tanks have been adopted for potable substitution, especially for multi residency buildings in Barcelona and Catalonia (Domenech & Sauri, 2011). However, whilst there are now some official planning regulations to mandate tank installation, there seem to be no guidelines, and certainly no subsidies. Morales-Pinzón *et al.* (2012) noted that rainwater harvesting systems are rare in Spain despite policy frameworks, such as the European Water Framework Directive, which specify measures for more sustainable use of water resources such as rainwater harvesting.

In the United Kingdom, the domestic penetration of tanks is fairly low (<6000 new tanks per year) and notwithstanding adequate guidelines for their installation, maintenance and reuse, there are no subsidies to encourage their installation, even for reducing inflow into combined sewers (Ward *et al.* 2012; Farnsworth, 2012). As with Germany, there are some public icon projects that use rainwater for toilet flushing and/or water features and/or garden irrigation, for example, London Eye and the Millennium Dome (Hills *et al.* 2001).

Across the Atlantic, the USA has developed guidelines for rainwater installation and reuse in a number of States and municipalities (USEPA, 2013; Texas Water Development Board, 2005), but it is only in the arid states of Arizona, New Mexico and Texas that tanks are encouraged and in some cases, mandated. But in some states (e.g., Colorado), their use is prohibited unless they are tagged on to a well water use license because of the often arcane water rights law of the western United States (e.g., see: www.water.state.co.us). The main use encouraged is irrigation of private lawns (Gold *et al.* 2010) which has a low public health risk (Ahmed *et al.* 2010).

In north Asia where monsoons are common and potable water supply is ample, rainwater tanks have been pioneered for flood mitigation in urban areas. In Seoul, for example, such tanks are mandated for city buildings, and their water level is centrally managed by telemetry, that is, the water level is reduced before expected storm events (Lee *et al.* 2010; Han & Mun, 2011). Reuse was not the major motivating factor, although recent innovations in private dwellings (e.g., the 1300 apartments Star Apartment complex in Seoul) are now focusing on toilet and garden irrigation, as well as flood mitigation (Han & Mun, 2011). A hydraulic analysis showed that 10 kL of storage per 100 m^2 of impermeable area could reduce the flood flow characteristics of a 1:100 year event into a 1:5 year event (Kim & Han, 2001; Han & Mun, 2011).

Similar issues motivate rainwater tank installation in Japan where over 1100 large buildings in Tokyo have tanks installed for flood mitigation. End uses such as toilet flushing and public space irrigation have gained favour particularly for large sport stadiums (Furumai & Okui, 2010). Concepts of potable substitution are slowly gaining favour along with the broader social objective of disaster preparedness if natural disasters were to cut off mains supplies (Furumai *et al.* 2008; Furumai & Okui, 2010). Most of the storage is installed in large buildings (including apartment complexes), with no subsidy available. However, more recently subsidies for residential home owners are being offered by a number of prefectures (Tjandraatmadja & Sharma, 2014).

In south Asia, rainwater tanks are important for water supply in rural areas and are also being mandated for large (>300 to 5000 m^2) buildings in water stressed states such as Uttar Pradesh in India, and cities such as Bangalore and Hyderabad. In Tamil Nadu, over 5 million private tanks have been installed (CSE, 2013). Mumbai mandates tanks for buildings >5000 m^2 but compliance has been patchy due to absence of subsidies and lax enforcement (Tjandraatmadja & Sharma, 2014). The main end use for rainwater (from large buildings) is groundwater recharge, a major source of water in India.

In other developing countries of the world, especially South Africa, Africa, Brazil and rural China, rainwater tanks are promoted by NGOs and government to supply drinking water and associated sanitation to the urban and/or rural poor. These are basic human rights under Millennium Goal # 7C (http://www.un.org/millenniumgoals/environ.shtml and http://sustainabledevelopment.un.org/focussdgs.html). In Brazil

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for example, over half a million domestic 16 kL tanks have been installed in the arid north east quarter of the country as part of a program to supply one million tanks servicing 5 million people under their Program for 1 Million Cisterns (P1MC – Gomes *et al.* 2014). In rural Africa (and South African shanty towns), tanks provide a supply of 'potable' water which is of a much higher quality than that collected from transient surface sources. Of course, thatched roofs in rural African areas severely limit rainfall catch. The quality of life implications are substantial in terms of reduced gastrointestinal diseases (morbidities >10% especially in the young), reduction of chronic back pain complaints, as well as freeing up time for the traditional water gatherers – the women and children (Orrico, 2003; Baguma *et al.* 2010a,b; Kahinda *et al.* 2007).

Taken overall, the use of rainwater tanks for substitution of mains water inside domestic dwellings in developed countries seems to be essentially an Australian phenomenon, with the possible exception of Germany and some Mediterranean cities (Sazakli *et al.* 2007). Developing countries where rainwater is a critical supply of potable water can learn from Australian rainwater insights and technology development in improving their rainwater tank systems for long term operation.

14.3 CURRENT AVAILABILITY OF WATER RESOURCES IN AUSTRALIA

Today, in 2014, Australia finds itself in a very different situation to that of the mid-2000s. The reservoirs of most of the capital cities (except Perth) are >80% full and the water utilities have spent around $35 Billon in providing climate resilient water supplies. For example, $7 Billion was invested in new drought resistant infrastructure in SEQ, including the SEQ Water Grid, the Western Corridor Recycled Water Scheme, the Tugun Desalination Plant and new dams and weirs, leaving the State with this debt to service. Similarly, the $3.5 Billion, 150 GL/year Wonthaggi sea water desalination plant built to service greater Melbourne, costs $657 Million/year to manage on just a care and maintenance basis (Melbourne Water, 2014). At the time of writing this book (2014), it has still not been used to supply potable water.

It is really only Perth that continues to experience a multi-decade reduction in surface water inflows and has its two sea water desalination plants (300 ML/day capacity) in full production and integrated into its water supply grid. Perth also has a strong Mediterranean-like climate (wet winters, hot, dry summers) that makes it unattractive for installing domestic rainwater tanks due to extended low rain/no rain periods each year (approximately 4+ months per year). So it's not surprising that rainwater tank penetration in Perth is about 7%, the lowest of any of Australian capital cities (ABS, 2013).

After the drought in SEQ was broken by heavy rainfall in 2008/09, with further rain filling the region's dams by 2010, the voluntary installed tanks had an uncertain future unless their amenity value (i.e., flow rate/pressure) and operating costs ($/kL) were comparable to or better than the now unrestricted mains supply (costing about $3.50/kL in SEQ). Poorly maintained tanks are a serious potential health hazard from mosquito borne arboviruses such as dengue fever (Qld Health, 2007). Moreover, the owners of these tanks believe their use and operation are at their own sole prerogative, and strongly resist any suggestion of government inspection or maintenance levy (Gardiner *et al.* 2008; Gardiner, 2009).

14.3.1 Changes in approach to alternative water supplies in Australia

The focus of water authorities in Australia is now on cost recovery of sunk infrastructure costs and minimisation of operating and maintenance costs (AWA/Deloitte, 2014). Consequently, their interest in alternative water supplies is essentially nil for domestic dwellings (especially if it competes with potable water sales) and lukewarm for public open space uses such as parks and sporting grounds. This attitude has reflected the policy position of their government shareholders who are very conscious of increasing utility charges to voters who are still recovering from the 2008 global financial crisis, and ever rising

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energy costs. For example, in 2013 the Queensland Government repealed QDC MP4.2 (Department of Housing and Public Works, 2013) based on a combination of lobbying by the home building industry and an economic analysis (Qld Competition Authority, 2012) that demonstrated that mandated tanks were not cost-effective for society, notwithstanding the fact it was the home owners who ultimately carried all the costs.

These economic arguments, based on both the Benefit-Cost ratio and Levelised Cost of rainwater tanks ($/kL), appear not to have influenced other states in Australia, in that NSW still retains its BASIX program, Victoria requires internally plumbed tanks or solar energy to achieve a mandated housing sustainability score, South Australia requires at least a small tank (>1 kL) connected to the hot water system, whilst the ACT has sustainable housing rules similar to NSW, that is, 40% potable water saving (see Table 3 from Tjandraatmadja *et al.* 2012). As all these states/territories have installed large climate resilient water supplies (seawater desalination plants) or increased dam reservoir capacity for inland cities (ACT), one has to wonder as to their motivation for rainwater tanks, other than for philosophical reasons of environmental sustainability. In Victoria for example, this sustainability ethic is reflected in the Office of Living Victoria whose main charter is to *encourage* water utilities, local authorities and private urban developers to install alternative urban water supplies (e.g., reticulated stormwater or recycled water) to augment traditional mains supplies (see http://www.livingvictoria.vic.gov.au/MetroFramework/MetroFramework_discussionpaper.pdf). Furthermore, stormwater management and run-off reduction are seen as critical management strategies to prevent damage from the sediment and pollutant load into the Port Phillip Bay ecosystem (Melbourne Water, 2006; Harris *et al.* 1996).

The economics of these large schemes in capital cities is far from settled (e.g., AWRCOE, 2013) with many water utilities being quite reluctant, for example, to install dual reticulation of recycled water due to its high regulatory and operational costs. For example, Sydney Water has jettisoned its plans for dual reticulation in the high-growth urban areas of north west and south west Sydney, although a number of water utilities in Victoria, such as Yarra Valley Water, are still strong supporters of such schemes. In contrast, Gold Coast City Council (located in SEQ) has mothballed its $220 M, 2500 ML/year non-potable dual reticulation scheme in Pimpama-Coomera as the water use by the customers was well below expectations, and the running costs, especially those arising from the monitoring requirements imposed by the state regulator, made the scheme uneconomic (Taylor *et al.* 2013).

A partial exception to the reluctance to invest in alternative water supplies is stormwater that is captured, stored and reused for irrigation of public open spaces. A major proponent for this concept is the arid city of Adelaide (600 mm/year rainfall with hot, dry summers), where over 12.4 GL/year of stormwater is used for this purpose, basically greening an otherwise brown, summer city scape (South Australia Strategic Plan Progress Report, 2012). Similar enthusiasm is shown in Melbourne where dry, often very hot summers, urban heat island effects, and stream water quality implications all combine to encourage official enthusiasm for these public open space irrigation schemes. However, these alternative sources of water are usually not the responsibility of the water authorities. Rather, they are initiated by an urban developer or local government authority and then often handed over to the water utilities to operate. In some cases, a state planning authority (e.g., Office of Living Victoria) might actively encourage the establishment of water sensitive suburbs, but they do not fund the construction of the water services.

Of course, when the next El Nino inspired extended drought hits eastern Australia, as is currently (2014) occurring in California (Pacific Institute, 2014 and http://gov.ca.gov/news.php?id=18379), there will be a resurgence of interest in alternative water supplies, reinvigoration of water conservation behaviour by industry and residents, and probably water restrictions on external water uses. A recent survey on the State of the Australian water sector has clearly identified that water security affected by climate change is still

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top of mind for many of the (industry) respondents, and there is strong support for a diversified urban water supply (AWA/Deloitte, 2014). Rainwater tanks would seem well suited to help resolve all these problems. But until that time, *the elephant in the room* will be the maintenance of over 1,500,000 tanks in urban Australia.

14.4 POLICY IMPLICATIONS FROM THE CHAPTERS

Water yields (kL/yr) predicted by modelling need long-term, daily climate records and demonstrated that they are responsive to tank size, connected roof area and water demand, but all 3 parameters show a plateau-type, levelling out response (Vieritz, Neumann and Cook, Chapter 2). However by 'running a tank hard' by regular water withdrawals, the yield is maximised from an otherwise small tank. On a suburb or regional basis, the yield of a population of tanks is up to 15% less than the behaviour of an average tank (Maheepala *et al.* 2013) because of variation in tank sizes, connected roof areas, household water demand and water losses. Hence, other (statistical) modelling tools are needed when considering rainwater in regional water planning studies. Somewhat surprisingly, despite the plethora of rainwater tank models, there is a dearth of model validation studies. This needs resolution if tanks are to be used with confidence in regulations (e.g., BASIX in NSW) or water planning studies. The task should not be particularly onerous as covering the variation in connected roof area, tank size, demand and, most importantly, climate is more important than a large statistical study since it is the processes that need validation in a stochastically driven model. A starting point would be the detailed rainwater tank information collected in the monitoring study of 20 homes conducted by Umapathi *et al.* (2012) and reported in Chapter 4.

Vieritz, Neumann and Cook in chapter 2 also touch briefly on predicting the overflow volume/rate from a large cohort of rainwater tanks using a continuous simulation model, but they do not relate this to the discharge characteristics of stormwater flows in urban areas, which are also affected by impervious areas other than house roofs. It is possible that one of the eWater CRC software tools such as Source Urban (http://www.ewater.com.au/products/ewater-toolkit/) may be suitable for this task. Clearly more research is needed in this area.

Models notwithstanding, we need to answer the question *do rainwater tanks really supply substantial potable water savings?* In SEQ for example, the QDC MP4.2 water savings targets were formulated on a rainwater model that predicted tanks could supply 70 kL/hh/year (Le Muth & Barry, 2006). The methodologies described by Beal *et al.* in Chapter 3 and based on studies in SEQ can be extrapolated to any urban area that has an extensive, regularly-measured water meter database, and some limited demographic information on household occupancy. At the time this modelling was undertaken (in 2006), the average per capita water use was very high, approximately 300 L/p/day (QWC, 2010), with a large component of outdoor use/irrigation. During the time the water savings studies were undertaken, the per capita water use had reduced to 150–160 L/p/day due to a combination of water restrictions, increasing adoption of water efficient appliances, demand management practices and water conservation behaviour change (Beal & Stewart, 2011). For example, simply replacing a ≤2 star rated clothes washing machines with a star rating ≥4 provided a potential savings of 8.8 kL/hh annually. Hence, it is not surprising that Beal *et al.* (2011; 2012) reported that the estimated average mains water savings in 2008 was 50 kL/household/year (kL/hh/yr) rather than the 70 kL/hh/yr predicted by modelling. The subsequent study by Chong *et al.* (2011) in 2009/10 estimated rainwater tank yield averaged 58 kL/hh/year, but ranged from 40 to 81 kL/hh/yr, with the higher yields associated with higher local rainfall and higher household water use (including garden irrigation).

A related method to measure potable water savings is detailed instrumentation of a limited number of tanks systems (say <30 households) that allows collection of fine-grained water use and energy use data

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which is regularly interrogated using telemetry technology (see Chapter 4). A real-time monitoring study of 20 households in SEQ was conducted by Umapathi *et al.* (2012; 2013) with smart water meters over a 12-month period to validate the mains water savings from mandated household rainwater tanks and to also measure the diurnal water demand patterns and the energy consumption. The analysis showed that the average reduction in mains water for this small population of rainwater tanks was 40 kL/hh/yr over the 12-month monitoring period, during which time the average total household water consumption was 151 kL/hh/yr.

Clearly, a reduction in water demand through a range of water efficiency, demand management and water use behaviour measures will have a significant impact on the water demand from a rainwater tank and result in less potable water savings. However, it can be confidently argued that, overall, internally plumbed rainwater tanks make a very significant contribution to potable water savings (about 30% of total household demand).

Energy use of tank systems (Chapter 6) is of particular interest on both practical and philosophical grounds as early reports of high specific energy use (e.g., >3 kWh/kL) discounts the environmental benefits accruing from self-sufficiency in water supply. Detailed studies have now established specific energies of tank systems are more often in the range 1.5 to 1.7 kWh/kL (Tjandraatmadja *et al.* 2012). Umapathi *et al.* (2012, 2013) estimated the average energy usage for rainwater supply to 20 homes in SEQ to be 71 kWh/year, with an average specific energy of 1.5 kWh/kL. Similar results were reported for 52 homes in New South Wales (Ferguson, 2011). This is still substantially more than traditional mains supplied water (circa. 0.9 kWh/kL), but considerably less than that for recycled water (2.8 kWh/kL) or desalinated seawater (3.4 kWh/kL) (Tjandraatmadja *et al.* 2013). The key to low tank specific energy use is appropriately sized pumps and high water flow rates (i.e., >10 L/minute), as energy use per unit of time for most rainwater pumps is almost constant with flow rate (Chapter 6). Hence, systems that allow high pump flow rates, such as pressure vessels and header tanks, are to be encouraged, although for single story buildings, the latter seem to be incompatible with the operating pressures required by high pressure solenoid valves in domestic water appliances.

Policy implications include encouraging installation of pressure vessels (but they must be >20 L to be effective), and promoting research activities that encourage manufactures to install low pressure solenoid valves in their water appliances. The high market penetration of low volume dual-flush toilets (>80%) indicates that the market can respond rapidly to officially endorsed water efficiency measures and water conservation messages.

Audits are very useful to ascertain if tanks are installed as per regulations, for example, recommended tank size, connected roof area, first flush devices, insect screens, and so on. An on-site assessment of mandated rainwater tanks in 223 detached dwellings in SEQ (Chapter 5) suggested good overall compliance for most criteria for mandated tanks, with tank size and connection to household appliances (toilet and cold water washing machine tap) shown to comply with requirements. However, 40% of the houses failed to meet the requirement for connected roof area – the lesser of either 100 m^2 or 50% of the roof area connected to the tank. Connected roof area has been shown to be the greatest single variable limiting tank yield in SEQ.

Voluntary installed tanks seem to be less compliant, as suggested by ACT experience where the measured yield is substantially less than modelled yield; a phenomenon the authors of Chapter 3 termed the *Functionality Factor* where tank installation quality, operational standards and behavioural characteristics are all compromised.

Maintenance is a key issue for the long–term, sustainable performance of rainwater tanks, yet there is very limited data on this for SEQ (but see Chapters 5 and 7). The issue of tank system maintenance remains a tricky problem on a number of grounds. On one hand, the regulators/water utilities require

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regular audit information to confirm water savings (if tanks are a critical component of a regional water strategy) and low public health risk (i.e., no mosquitos). On the other hand, Chapters 7 and 8 identified that the tank owning public are largely unaware of the need for tank maintenance, have little idea of what needs to be done, has variable self-confidence to undertake the maintenance tasks, and strongly rejects the suggestion they should pay for a mandatory tank monitoring/condition assessment program. The mandated tank owners tend to be more negative on all criteria compared with the retrofit tank owners. The authors of Chapter 7 (Moglia *et al.*) make the perceptive observation that tanks are an uncommon type of asset which are in private ownership but provide public good outcomes (i.e., reduced demand on potable water). There are very few precedents on how to manage this type of infrastructure, but whatever strategy is chosen, Moglia *et al.* counsel that it should be implemented gradually, and assessed for outcome efficacy before moving onto any legislative amendments.

Much more 'on ground' information on the state of repair of rainwater tanks is available from a recent Smart Water Fund sponsored study in Melbourne (Moglia *et al.* 2014). This survey of over 450 homes identified a 60% failure rate on criteria ranging from major (e.g., 6% had failing foundations), to suboptimal (e.g., 35% had switching valve failure and 57% had discoloured water), to minor (e.g., 31% had roof gutters full of debris). There was generally a widespread ignorance of tank system maintenance needs, especially amongst mandated tank owners. As all the tanks were new (<5 years old), more fundamental issues of screen failure were relatively rare, yet 12% reported the presence of mosquito larvae, which presents the potentially serious public health implications of arboviruses (Qld Health, 2007). Other failure issues such as overflowing gutters, blocked downpipes, failed pumps and so on impact solely on the individual householder, and are not strategically important *unless* regional water planning policy has been predicated on an assumed, consistent non-potable contribution from rainwater tanks. Of course, tree leaf discoloured rainwater in toilet bowls and so on can be an unacceptable aesthetic affront to the householder who may disconnect their tank from these internal end uses, as happened in the Payne Road development in SEQ (Beal *et al.* 2008). These types of preventable failures add to the public discourse that rainwater may not be as good as potable water for *any* internal use, although user expectations do evolve with extended rainwater use experience (Moglia *et al.* 2014).

Monitoring of tank condition and mosquito breeding is an important public health activity for government and its regulatory agencies. But this will not be without its challenges given the sense of personal tank ownership by householders, an almost uniform resistance to imposed inspection programs paid for by the householder, and resentment of what is perceived to be government interference (Chapter 7; Gardiner, 2009).

In Chapter 8, Mankad *et al.* suggest that motivational factors play a significant role in rainwater tank adoption. The effectiveness of programs that promote the installation of rainwater tanks may be increased if they focus on the benefits of rainwater tanks for householders and for the community more broadly. It makes sense to focus on the benefits of rainwater tanks for protecting the individual, their lifestyle and their property. However, it is also important to communicate that, in times of extreme drought, the chief contribution of rainwater tanks could be to reduce the pressure on drinking water supplies and thereby increase water security in urban areas.

Mankad *et al.* (2012a) also found that homeowners were rarely engaging in tank maintenance behaviours, but the higher the self-assessed competence to maintain a tank that homeowners reported, the more they engaged in tank maintenance. Most mandated tank owners had limited knowledge of their tank set-up, and participants reported only moderate perceptions of competence to be able to maintain the tank. Enabling householders by increasing their levels of competence (e.g., applied education about maintenance) could go some way to increasing rates of tank maintenance. This education should focus on 'how to' and 'why to' information that helps homeowners to the build competence in this area.

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The lack of tank maintenance by mandated tank owners raises important issues for government agencies seeking to address water security through rainwater tank adoption. On the one hand, legislation that mandates installation of rainwater tanks should result in much broader uptake of these systems than measures that encourage voluntary uptake. On the other hand, the lack of choice that legislation introduces may undermine householders' willingness to maintain their systems. These findings suggest the need for agencies to pay particular attention to households with mandated tanks to encourage greater knowledge of their functioning, and increase ability to undertake tank maintenance.

Chemical water quality (Chapter 9) is always a concern if rainwater is used for drinking, as it is by about 2% of urban tank owners, and 23% of tank owners outside Australian capital cites (ABS, 2013). Results from Chapter 9 indicate that lead (Pb) is the major contaminant of health concern (health limit <10 µg/L) and after allowing for lead flashing used in roof construction, there seems to be a systemic rainfall contaminant issue in urban Australia. Maygar and Ladson (Chapter 9 authors) argue there is good experimental evidence to conclude that Pb concentration exceeds drinking water guidelines in 22% of *urban tanks* used for drinking water in Australia (27,700) increasing to 44,000 tanks if the 95 percentile figure is considered. Given that unpainted lead flashing can only explain part of this incidence, it is clear that steps need to be taken to avoid entrainment of Pb enhanced sediment at the bottom of the tank. A floating intake pipe located say 150 mm below the free water surface would seem a prudent, but under researched, mitigation practice. First flush devices are both recommended and popular, but are unlikely to have much effect on the Event Mean Concentration (see Duncan, 2006 for EMC definition) as the diverted runoff volume is usually very small (<20 L per device).

The microbiological quality of tank water is a major concern, especially if the water is used for drinking or showering. There was a general finding in SEQ that collected rainwater is contaminated with animal faecal bacteria, some of which may be pathogenic to humans (Chapter 10). There are also other zoonotic pathogens such as the protozoan parasites Giardia, and sometimes Cryptosporidium. Chapter 10 shows that natural disinfection processes can reduce faecal bacteria concentrations by 1 to 2 log10 in a matter of hours on roofs and gutters exposed to sunlight, and up to 5–8 days on the roof under shaded conditions. Once introduced to the tank, a slower inactivation process takes place over 10–15 days (Ahmed *et al.* 2014) but this is not sufficient to make the water safe to drink, based on Quantitative Microbial Risk Assessment (QMRA) methods (Ahmed *et al.* 2010; 2012). However, rigorous epidemiological studies in South Australia (Rodrigo *et al.* 2010) and anecdotal evidence from the 23% of residents in rural/peri-urban Australia that regularly drink rainwater (ABS, 2013) suggest these health risks may be overestimated.

At a policy level, the results of Chapter 10 (by Ahmed *et al.*) and the regularity of world-wide reports of zoonotic pathogens in collected rainwater (Ahmed *et al.* 2011) make it difficult to recommend rainwater for potable uses in urban areas unless it has been disinfected using chemical (e.g., chlorine, hydrogen peroxide, ozone) or mechanical methods (silver impregnated filters, UV light), or simply boiled prior to drinking. But effective operation of disinfection devices requires their regular maintenance, and the track record for this type of 'housekeeping' is not encouraging. Overall, the research supports the policy position of Australian health regulators that rainwater should *not* be used for drinking where a potable water supply is available.

Communal tanks seem the way to go in the more densely settled urban areas. Communal tanks allow centralised treatment, unlimited demand if connected to the potable mains, and a large fraction of the roof area connected to the 'catchment' area (Chapter 11). This configuration will maximise rainwater yield from connected roof areas as storage and demand limitations are essentially removed, treatment technology and quality assurance will equal that of traditional potable water, for example, as per the Australian Drinking Water Guidelines (NHMRC & NRMMC, 2014), and no extra reticulation infrastructure is required. The 45 ML/year Fitzgibbon scheme in SEQ, described in Chapter 11, is an excellent example of a communal

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scheme where much of the construction cost has been borne by the private sector. It is now up to the water utility/government to show that this scheme can operate safely and efficiently as per its design objectives, and hence become a precedent for similar types of schemes in eastern Australia. A problem for their wider adoption in conventional urban areas is the cost (>$4/kL) compared with traditional mains supply ($2–$3.50/kL), and the willingness of water utilities to manage a 'left field' technology on a day-by-day basis.

This raises the issue of the economics of rainwater systems. They do not seem to look financially attractive on either a Benefit Cost ratio or a Levelised Cost basis (Chapter 12). However, analyses to date have largely excluded positive externalities (e.g., stormwater quantity/quality/peak flow, reduced land take for WSUD devices) as well as some doubt on the realism of the assumed costs (White, 2014). We believe that unless tanks are mandated by some type of legislative instrument (e.g., BASIX), their future adoption will be limited to people with a high environmental sustainability ethic (as per many of the young German households). Anecdotal evidence suggests that many new home owners in Australia would prefer, say, a granite bench top in their kitchen rather than spend $5000 on an internally plumbed rainwater tank or roof mounted solar electricity panels in their fixed priced, project built homes. It's possible that steeply rising electricity and water prices in Australia and the next extended drought may moderate this attitude.

Stormwater benefits are an important driver for installing rainwater tanks in the highly urbanised European cities with a combined sewer system and a high frequency of flooding (e.g., England and Germany). This hydraulics issue is generally underexplored in Australia where dedicated sub surface stormwater conveyance infrastructure is usually built for the 1:2 year storm event, although overall flood protection of a suburb/city is based on a 1:100 year event (e.g., QUDM, 2013). The key question is whether tanks will reduce the peak discharge (Qp) such that the stormwater pipe sizing can be reduced.

In western Sydney, the Upper Parramatta River Catchment Trust (UPRCT) is responsible for stormwater management of an 11,000 ha catchment, which is administered for all other purposes by four different local authorities. The overall objective is ensure that any future urban densification (and hence increased impermeable area) since 1991 will not increase downstream flooding for any rainfall event less than or equal to the 1:100 year average return interval (ARI) event. They implement this policy by mandating distributed, on-site detention storages (OSD) which empty at a maximum controlled rate. The OSD characteristics are 455 m^3/ha of storage (about 20 kL per household), with a maximum discharge rate of 150 L/sec/ha, controlled using orifice plates. Part of this storage (the first 300 m^3/ha) is designed to discharge at the lower rate of 40 L/sec/ha to ensure that runoff rates from the 1:1.5 year ARI storm will mimic the natural stream flows, as close as is practical. The objective here is to protect creek ecosystem health.

UPRCT have subsequently modified their design guidelines (UPRCT, 2005) to account for detention storage by rainwater tanks, which is composed of a *dedicated airspace* volume (kL) which empties at the equivalent rate of 40 L/sec/ha, and a *dynamic airspace* (kL) which only empties by household water use. A formula based on tank volume, roof area and household water use is used to calculate the *dynamic airspace*, which is further discounted by a roof area formula before being credited against the mandated OSD volumes (i.e., 300 m^3 and 455 m^3/ha).

The Victorian study (see Chapter 13) confirms that rainwater tanks will reduce nitrogen and phosphorus export from roofs (by 60% to 80%) as well as reduce the frequency of those small runoff events caused by increased impervious areas. There are also clear benefits to urban creek ecosystem health, as well as reduction in the 1:1 year peak discharge (Qp) to near pre-development values. However, there is no analysis equivalent to that of Kim and Han (2008) in Seoul that showed 10 kL rainwater storage/100 m^2 roof could reduce a 1:100 year Qp event into a 1:5 year Qp behaviour, provided the tanks were automatically emptied before the storm event. This is a major research gap in Australia, as is the implication of tanks for reducing the size of WSUD devices such as bio-retention basins, which are common and often mandatory

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in most new urban developments (http://waterbydesign.com.au/wpcontent/uploads/drupals/seq_wsud_dos_nov_07_final_v2_0001.pdf and http://waterbydesign.com.au/techguide/).

14.5 LESSONS FOR OTHER COUNTRIES

In Australia, rainwater harvesting in urban areas has been used to substitute for mains water on a fit-for-purpose basis. The sustainability of such practice, as part of the provision of urban water services, is governed by a complex mix of social, institutional and technological factors.

Australia was also one of the first countries to try to mainstream rainwater harvesting in urban areas, often through policy trial and error, but more importantly it also conducted comprehensive scientific assessments of the systems both pre- and post-installation over the last 10 years. In other countries, especially the developing ones, the systems adopted will differ with some of the technologies used likely to be much less sophisticated. Hence, not all Australian insights may be applicable, but a number of the Australian insights have universal value.

Regions with plenty of water have historically been mostly interested in reducing stormwater inflows into the combined sewer system and stormwater management (Europe and North-Pacific Asia), but there is increasing interest in potable substitution. Germany seems a key country of interest for such purpose, given the high penetration of tanks in new domestic dwellings (about 65%). Regions subject to water scarcity, difficult water access, and stressed water resources due to overexploitation and/or climate, focus mostly on rainwater for water provision (Mediterranean Europe, parts of USA, semi-arid parts of Brazil, Africa and Asia) or recharge of traditional groundwater supply (as in India).

In developed countries such as Korea, Japan, USA and Australia, systems are designed based on the traditional service standards and often adopt telemetry and operating mechanisms that assume constant electricity supply and high labour cost. In other parts of the world, such as in developing economies, electricity may be intermittent, labour is often cheap and the mains water supply set-up differs, for example, header tanks are often adopted due to intermittent water supply, hence systems need to be designed differently, for example, more mechanical parts.

Irrespective of the system type, there is the need for models, guidelines and regulations to guide the system design, and in particular, to understand how it is possible to integrate rainwater tanks with traditional water supplies. Lessons and tools from Australia, and their impact may be useful for other countries to examine, and then modify as they develop their own standards, codes, policies, and so on suited to their needs. Examples include the impact of audits of the quality of installations in SEQ.

For those (developing) countries where rainwater replaces inferior water sources for drinking we suggest the following insights can apply:

- Rainwater is NOT pure and risk free. Hence, it is best to boil the water before drinking it. However, other end uses are probably OK without specialised treatment.
- Be careful with the roofing material used, especially lead flashing used to waterproof roofing joints, as lead leaching can be a serious contaminant in the collected rainwater. This is especially important in the young where constant exposure to lead, a neurotoxin, can cause serious development problems.
- Computer models can be used to size connected roof area/tank volume to achieve a given water supply (litres/day) for a given reliability and duration of supply. For example, it's important that tanks don't regularly run dry for extended periods of time (weeks/months) without a clear understanding of the need for a back-up plan.
- Electricity is likely to be non-existent, or intermittent at best. Hence, it's important to have a header tank to supply water by gravity 24/7. Using a petrol fuelled generator to power a cheap electric pump to fill a header tank will avoid the high specific energy use that often accompanies use of such pumps

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in developed countries. This system can also mitigate the high energy use to pump (other) sources of water over long distances or high elevations (e.g., from a deep well or over hilly terrain).

- Insect and vermin control is important, increasing to essential in tropical countries where arboviruses such as dengue fever can occur. Hence, limited cash resources should be preferentially allocated to high quality stainless steel mesh screens for the inlet and overflow structures on the tank to prevent mosquito ingress.
- Sediment in the tank is a double-edged sword. On the one hand, it can immobilise heavy metals and other contaminants as well as contribute to natural die-off of pathogens (Spinks *et al*. 2005). On the other hand, if ingested in the rainwater, the contaminant dose will be concentrated. A simple solution is to have a floating off take hose inside the tank to ensure that the best available water quality is flowing through the supply tap. Sophisticated first flush devices can also contribute to better quality of collected rainwater, but simple units operated manually in low wage areas should work equally well.
- Tank material should be constructed from durable material such as concrete or corrosion resistant corrugated metal, as appropriate to climatic conditions. Whilst polyethylene tanks are relatively cheap and easily transportable, longevity in extreme weather environments of high temperatures and high solar radiation, arid conditions can be questionable. Moreover, the more the local input into tank construction, the more affordable the system is likely to be.
- It is very important to have a local education/learning group on tank operation and maintenance to ensure the learnings are well distributed though the local community. The importance of keeping up the maintenance motivation of tank owners has been verified for villagers in Uganda, where familiarity with raintanks, shared learnings through communities of practice and reinforcement of education on maintenance methods were key factors to improve the overall health of raintank users (Baguma & Loishkandl, 2010).

In some cities of developing countries, rainwater tanks are installed in large public buildings as a show case for the utility of rainwater to the wider community. Whilst this type of application has not been covered in detail in this book, a report by Cook *et al.* (2012, 2014) based on experience in a high rise building in Brisbane, SEQ, has highlighted the potential problems with poor plumbing construction. This is balanced by the opportunities to harvest other sources of water (such as air conditioning condensate and groundwater seepage into basements) once the 'mind has focused' on the task of collecting alternate water supplies for toilet flushing and amenity irrigation end uses.

The focus of rainwater in developed countries is potable water substitution, and in this application, the Australian lessons on virtually all aspects of tank systems can be more or less directly applied. Of particular relevance are the learnings from roof area/volume sizing models, pump capacity (kW), tank technologies, construction standards and maintenance guidelines, post installation and maintenance audits, and education/feedback to the householder. Assuming rainwater will not be used for drinking in well-watered European countries, the chemical and microbiological quality should not be a major issue. However, improved stormwater runoff quality may be a key advantage, especially in reducing the heavy metal export (e.g., copper and zinc) from metal roofs.

The lessons for long-term maintenance are more complex, as potable water supplies in many other developed countries are probably designed without taking into account rainwater contributions. Similarly, the health implications of arboviruses from poorly maintained tanks in northern European and northern Asian countries is likely to be much less than that in Australia and the developing countries. Nonetheless, an education program seems to be sensible, something we have yet to undertake in Australia despite a plethora of guidelines. Given the motivation of many German householders to be environmentally

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responsible and partially self-sufficient, it seems likely they would be very amenable to implement sensible tank maintenances information.

Finally, communal rainwater tanks would seem to have lots of potential in closely settled urban areas, especially if surface slopes are greater than 0.5% to allow installation of above ground storages (Gurung & Sharma, 2014). Centralised management of rainwater opens up a raft of reuse/treatment opportunities.

14.6 CONCLUSIONS

The body of work reported in this book should have widespread implications to other states of Australia, other developed countries, and some developing countries. However, it should be noted that the biophysical/social context of this SEQ-centric work is for tanks as suppliers of non-potable water to urban domestic dwellings. Nonetheless, most of the rainwater tank systems' analyses, assessment, modelling, monitoring and validation approaches and methods presented in this book will be useful in enhancing scientific knowledge of water professionals engaged in this area in any part of the world. The social surveys of tank owners consistently found a widespread ignorance of tank system maintenance needs, especially amongst mandated tank owners, and an almost uniform resistance to an imposed inspection program paid for by the householder. Unless self-interest (i.e., saving mains water costs) and community health (i.e., mosquitos, aka arboviruses) issues are clearly communicated, this resistance is likely to remain unchanged.

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Rainwater Tank Systems for Urban Water Supply

Design, Yield, Energy, Health Risks, Economics and Social Perceptions

Ashok K. Sharma, Donald Begbie and Ted Gardner

Rainwater tank systems have been widely adopted across the world to provide a safe, local supply of water in developing countries, peri-urban areas of developed countries, non potable substitution for mains water in water stressed urban areas, and providing flood mitigation in monsoonal climates such as Korea, and combined sewer systems such as Germany. As cities have grown, water managers have tried to reduce supply constraints of traditional water supply systems by exploring a range of alternative climate resilient water supply options which include water recycling and rainwater tanks. Rainwater tank systems are now often implemented, especially in Australia, under integrated urban water management (IUWM) and water sensitive urban design (WSUD) philosophies, which take a holistic view of the urban water cycle.

Rainwater Tank Systems for Urban Water Supply is based on the results of a comprehensive, multi-million dollar field-based research program that was undertaken in South East Queensland (SEQ) Australia in response to the Millennium drought when the water supply level in the region's drinking water dams dropped to less than 17 % in July 2007, and the area came within 12 months of running out of water. The book provides insights and detailed analysis on the design, modelling, implementation, yield performance, energy use, economics, management, health risk, water quality and social perceptions of roof water runoff collection systems.

The approaches and methodologies included in *Rainwater Tank Systems for Urban Water Supply* provide unique insights into the expected performance and potential pitfalls of adopting rainwater tank systems in urban areas including:

- modelling tools to estimate yield and optimise sizing of rainwater tanks and roof collection area
- methods to estimate the actual yield (kL/year) and the resulting mains water savings
- post-installation physical verification of household rainwater tank systems for design guidelines compliance
- rainwater tank pumping configuration and energy consumption
- expected chemical and microbial water quality and its implications for managing public health risks
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Strength enhancement of the subgrade soil of unpaved road with geosynthetic reinforcement layers

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ABSTRACT

Geosynthetic reinforcement layers are often used to improve the performance of pavement structures. The performance of an unpaved road is routinely measured in terms of the California bearing ratio (*CBR*), which is an index of strength of subgrade soil of unpaved road. In the present study, an experimental investigation was carried out to evaluate the performance of the subgrade soil by placing a single layer and double layers of geosynthetic reinforcements (Glasgrid, Tenax 3D grid and Tenax multimat) horizontally at varying depths from the top surface of subgrade soil. Through a series of *CBR* tests in the laboratory, an attempt was made to determine the optimum depth of the reinforcement layer. The single layer of reinforcement has been placed at the middle, one-third and one-fourth of the height of the *CBR* specimen from the top surface of the soil in the CBR mould. The double layers of reinforcement were placed at one-fourth of the specimen height from the top surface and the bottom surface. The results show the significant contribution in terms of increased *CBR* value of the soil, resulting in reduced design thickness of the pavement layers above the subgrade soil. It has been observed that for a single layer reinforcement the Tenax 3D grid performs better than other geosynthetics used in this study while the Tenax multimat performs best for double layers. The results indicate that for the maximum benefit, the Tenax 3D grid reinforcement should be placed in between 0.3*H* and 0.36*H* where *H* is the height of the soil specimen. For Glasgrid and Tenax multimat reinforcements, the maximum effect of reinforcement is obtained when they are placed between 0.41*H* and 0.62*H*.

Introduction

In the current construction practice, the geosynthetic layers are often utilized for improving the weak/unsuitable soil subgrade for paved and unpaved roads. The geosynthetic layer as a reinforcement can be used effectively to reinforce the unpaved road built on soft soil subgrades, resulting in increased life of the road. The benefits obtained from the use of geosynthetic layers in unpaved roads can be observed not only with respect to performance and durability but also with respect to construction and economy [23]. The concept of using geosynthetic as reinforcement in paved/unpaved road construction started in the 1970s. Since then, many experimental and numerical studies have been reported in the literature to evaluate the benefits of using the geosynthetics in road construction [5,25]. Due to the successful application of geosynthetics in roads, different types of geosynthetics have been developed worldwide and their market is steadily growing [22].

Several researchers have shown the benefits of geosynthetic reinforcement in unpaved roads over weak subgrades to improve their performance [9,8,18,11]. The position of the reinforcement layer in the subgrade also influences the performance of the road [19,21,24]. Several field trials and full-scale laboratory investigations have illustrated that the geosynthetics used to reinforce the unpaved roads on soft ground facilitate confinement, reduce the depth of ruts, improve load-bearing capacity, extend the service life and reduce the necessary fill thickness [1,2,11,10]. Relatively thicker pavement sections and base-course layers indicate that more material is required for construction, and therefore it increases the cost. Geosynthetics have been used as an alternative to reduce the cost of these materials and improve the performance of reinforced road sections. Some studies have been carried out to quantify the benefit of using the geogrid base reinforcement [3]. Initial cost and maintenance cost of reinforced road section has been an important factor which should be considered for evaluating the benefits of geosynthetic reinforcement. Palmeira and Antunes [17] have shown that the presence of geosynthetic reinforcement in unpaved road

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reduces the maintenance cost which yields to the important savings in the overall cost of the road construction.

The behavior of the road surface depends on the strength of the fill material and the subgrade of the pavement. The strength of the subgrade is most often expressed in terms of the California Bearing Ratio (*CBR*), which is the ratio of test load to standard load at a specific penetration, by a standard plunger [12]. Many functions of geosynthetics have been reported such as separation, reinforcement, filtration, drainage, fluid barrier and protection [22]. One of the important applications of geosynthetics is reinforcement which is used to improve the strength of weak soil, that is to increase in *CBR* of soils [4,6,15,20]. The soils with low *CBR* value have higher benefits of geosynthetic reinforcement in terms of improved strength than those soils with higher *CBR* values [7]. The improvement in subgrade performance can facilitate compaction, reduces the aggregate layer thickness, delay rut formation and extend the service life of unpaved roads, particularly in cases of very soft subgrades with *CBR* value less than three [11]. In the literature very conflicting results have appeared for the position of geosynthetic as a reinforcement layer. Some researchers believe that the maximum effect of reinforcement layer is obtained when geosynthetic is placed near the load or at bottom half of the height of specimen in the CBR mould, while others have found that placing the geosynthetic reinforcement at the centre of the CBR mould is most beneficial [13].

This work presents a study on the use of three different types of geosynthetics as the reinforcement at different depths within the subgrade soil for improvement of its *CBR* value. The main objective of research is to investigate the optimum position of geosynthetic reinforcement layer within the subgrade soil thickness, which has not been given due attention in the past.

Materials used

Subgrade soil

The soil used in the present research was locally available soil obtained from the campus of Delhi Technological University, Delhi. The soil is classified as silty sand (SM) using the particle-size analysis and Atterberg limit tests as per Indian Soil Classification System (IS: 2720). The particle-size distribution curve of the soil is shown in Fig. 1. The basic properties of the soil are also determined in the laboratory and they are given in Table 1.

Reinforcement

Two types of geogrids (Glasgrid, Tenax 3D grid) and one geomat (Tenax multimat) were used as the geosynthetic reinforcement in this study. The geosynthetic samples are shown in Fig. 2. The properties of geogrids and geomat as provided by the manufacturer are given in

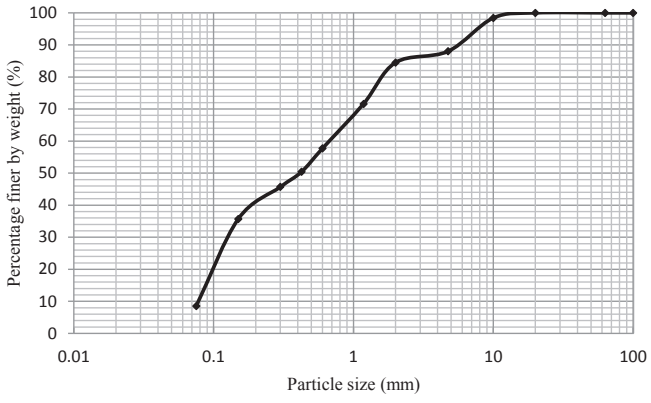


Fig. 1. Particle-size distribution of subgrade soil.

Table 1
Engineering properties of subgrade soil.

S. no.	Particulars	Subgrade soil
1	Specific gravity	2.55
2	Liquid limit (%)	29
3	Plastic limit (%)	20
4	Plasticity index (%)	9
5	IS Classification	SM
6	Optimum moisture content (%)	13.91
7	Maximum dry unit weight (kN/m^3)	18.74
8	California bearing ratio (*CBR*) (%)	1.66

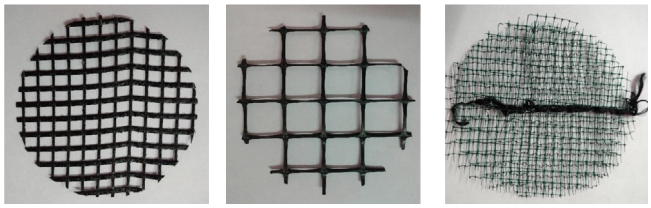


Fig. 2. Geogrids and geomat used in the study: (a) Glasgrid, (b) Tenax 3D grid, (c) Tenax multimat.

Table 2. Glasgrid is a high strength, open fiberglass grid custom knitted in a stable construction and coated with a patent-pending elastomeric polymer and self-adhesive glue. Every component of the matrix shall be stabilized against ultraviolet degradation and inert to chemicals normally found in a natural soil environment. Tenax 3D grid is manufactured from a unique extrusion technique resulting in a perforated sheet that is specifically shaped in three directions (3D). This unique extrusion technique produces a structure with vertical longitudinal ribs capable to guarantee the best possible interaction mechanism between geogrids and granular soils by restricting the horizontal movement of soil particles and preventing further displacements. This increase in interaction from the 3D Grids enables consistent reductions in aggregate layer thickness. Tenax multimat is a three dimensional mat composed by extruded and bi-oriented polypropylene grids, laid one upon each another and tied up by means of a black polypropylene yarn.

Geosynthetics are available with a variety of geometric and polymer compositions to meet a wide range of functions and applications. Selection of geosynthetic may have specific requirement depending on the type of application. Geogrids are used mainly for reinforcement and separation could be a function served by geogrids when soils are having very large particle sizes. Therefore, two types of geogrids were selected for the present study and the performance of the geogrid for reinforcement relies on its rigidity, strength, stiffness and aperture size, which accounts for its high capacity for interlocking with soil particles. The selection of a geosynthetic for a particular application is governed by several other factors, such as specification, durability, availability and cost [23,22].

Experimental investigation

The standard Proctor compaction test was carried out as per IS: 2720 (Part VII-1980) to determine the maximum dry unit weight (MDU) and optimum moisture content (OMC) for the soil. The MDU and OMC of soil were found to be 18.74 kN/m^3 and 13.91% respectively.

The design method that determines the required layer thickness of the aggregate with the reinforcement in the subgrade has been based on the *CBR* of the subgrade soil [9]. If the *CBR* of the subgrade is improved by providing the reinforcement, then the required thickness of the granular subbase/base layer can be reduced for a given traffic volume or, alternatively, the traffic volume can be increased for a given

Table 2
Properties of geogrids and geomat (Courtesy of H. M. B. S Textile Private Limited, New Delhi).

Geosynthetics	Description	Value	Unit	Test method
Glasgrid	Mass per unit area	405	g/m^2	ASTM D5261
	Grid size	12.5 × 12.5	mm	
	Material	Fiberglass reinforcement with modified polymer coating and pressure sensitive adhesive backing	–	–
	Tensile strength (Ultimate)	115 × 115 ± 15 (MD × TD)	kN/m	ASTM D6637 EN-ISO 10319:2008
	Tensile elongation (Ultimate)	2.5 ± 0.5%	–	ASTM D6637 EN-ISO 10319:2008
	Tensile resistance@2% strain	95 × 95 ± 20	kN/m	ASTM D6637 EN-ISO 10319:2008
	Secant stiffness EA@1% strain	4600 × 4600 ± 600 (MD × TD)	N/mm	ASTM D6637 EN-ISO 10319:2008
	Damage during installation	< 5%	–	Internal test method
Tenax 3D grid	Structure	Bi-oriented geogrids	–	–
	Mesh type	Quadrangular apertures	–	–
	Polymer type	Polypropylene	–	–
	Aperture size[c,d]	30 × 30 (MD × TD)	mm	–
	Transversal rib width[c]	2.6	mm	–
	Longitudinal rib thickness[e]	3.8	mm	–
	Junction thickness[c]	6	mm	–
	Stiffness at 0.5% strain[a,b,c]	550 × 350 (MD × TD)	kN/m	ISO 10319
	Installation damage factor	1	–	ASTM D5818
Tenax multimat	Structure	Three dimensional geomat composed by 3 layers	–	–
	Mesh type	Rectangular apertures	–	–
	Polymer type	Polypropylene	–	–
	Peak tensile strength[c,f]	3.8 × 13 (MD × TD)	kN/m	ISO 10319
	Yield point elongation[a,c]	23 × 23 (MD × TD)	%	ISO 10319
	Mass per unit area[a]	180	g/m^2	ISO 9864
	Thickness[a]	8	mm	ASTM D6525
	Aperture size[a,c]	7 × 9 (MD × TD)	mm	–

[a] Typical values.
[b] Tests performed using extensometers.
[c] MD: machine direction (longitudinal to the roll) – TD: transverse direction (across roll width).
[d] Aperture tolerance: ± 5 mm.
[e] Thickness/width tolerance: −5%.
[f] 95% lower confidence limit values, ISO 2602.

thickness of granular subbase/base layer. It is not always possible to get good quality granular material as per the design specifications either because of unavailability or increase in cost because of long haulage distance. Hence there is a need of subgrade soil stabilization with geosynthetic reinforcement to increase the strength and reduce the granular layer thickness over the subgrade soil. Therefore, the unsoaked CBR tests were conducted on the subgrade soil without reinforcement and with a single layer and double layer of different types of geosynthetic reinforcement as described in IS: 2720 (Part 16) – 1979. To evaluate the effect of geosynthetic reinforcement on subgrade strength, the single layer of reinforcement was placed at different positions, namely $H/2$, $H/3$, $H/4$ where H is the height of the soil specimen of the CBR mould from the top surface and double layer of reinforcement was placed at $H/4$ from top and bottom surface of the soil specimen.

The location of single and double layers of reinforcement within the subgrade were selected based on the literature because most of the researchers believe that maximum benefit of reinforcement is obtained when the reinforcement layer is placed in the upper half portion of the CBR mould. Half of the height of CBR mould was taken to place the reinforcement layers to get the maximum benefit of reinforcement. Therefore, three positions for single layers of reinforcement and one position for double layer of reinforcement were selected.

The geosynthetic reinforcement was cut in the form of a circular disk of diameter slightly less than the diameter of CBR mould. The dry weight required for filling the mould was calculated based upon the maximum dry unit weight (MDU) and the water corresponding to OMC was added in the soil and then the soil was mixed thoroughly. The mould is filled with this soil by placing geosynthetic reinforcement at predetermined depth as shown in Fig. 3. The cross section of the model



Fig. 3. Orientation of reinforcement layer placed at predetermined depth in CBR mould.

along with the position of geosynthetic reinforcement is shown in Fig. 4. The surcharge weights were placed on the specimen to stimulate the effect of the thickness of road construction overlying the layer being tested. Load is applied to the plunger into the soil at the rate of 1.25 mm/min. Readings of the load were taken at penetration of 0.5 mm to until a total penetration of 12.5 mm. The standard *CBR* tests were performed in the laboratory to compare the performance of various geosynthetics under the same subgrade soil condition. The soil specimen height in the *CBR* mould was taken as an equivalent to the thickness of the prepared subgrade soil in the field. Laboratory tests can

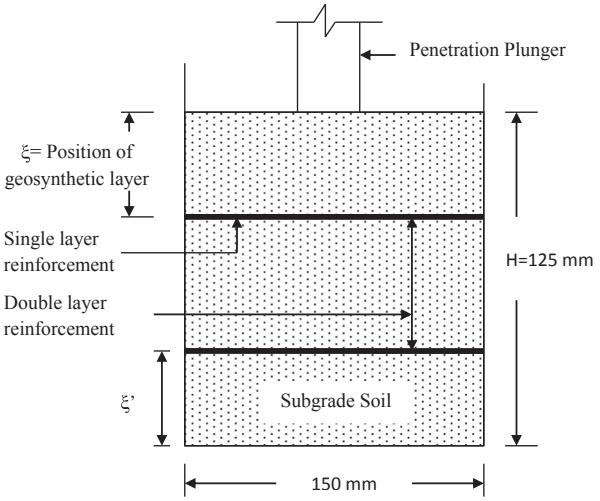


Fig. 4. Schematic representation of the specimen in *CBR* test model, position of geosynthetic is, $\xi = H/2$, $H/3$ and $H/4$ for single layer of reinforcement and $\xi = \xi' = H/4$, for double layers of reinforcement.

be conducted more quickly and usually have more alternatives but they are only able to simulate field conditions. Further, the scaling and boundary effect can have influence on the final results, but any change in specimen size will create difficulty for comparative analysis. Thus the measured values can be treated as relative measurements.

The improvement in *CBR* value of subgrade soil with reinforcement is measured in terms of the reinforcement ratio η, which is defined as a ratio of *CBR* value of soil with reinforcement (CBR_R) to that of original soil (*CBR*),[14,22].

$$\eta = \frac{CBR_R}{CBR}$$

This ratio indicates the contribution of geosynthetic reinforcement towards increasing the *CBR* value of a soil and compares the performance of geogrids and geomat reinforcement on the same soil. To quantify the role of reinforcement in increasing the strength, the reinforcement ratio is calculated for various cases (as shown in Table 3) and compared to distinguish the role of geosynthetic layer in improvement.

Table 3
Results of *CBR* tests for different positions of geosynthetics.

Type of geosynthetic	Position of geosynthetic reinforcement	*CBR* (%)	Increase in *CBR* with respect to unreinforced section (%)	Reinforcement ratio (η)
Glasgrid	*H*/2	2.21	33.13	1.33
	H/3	1.76	6.02	1.06
	H/4	2.04	22.89	1.23
	Double layers	3.52	112.05	2.12
Tenax 3D grid	*H*/2	1.76	6.02	1.06
	H/3	2.08	25.30	1.25
	H/4	2.04	22.89	1.23
	Double layers	6.25	276.51	3.77
Tenax multimat	*H*/2	2.63	58.43	1.58
	H/3	1.74	4.82	1.05
	H/4	1.94	16.87	1.17
	Double layers	7.05	324.70	4.25

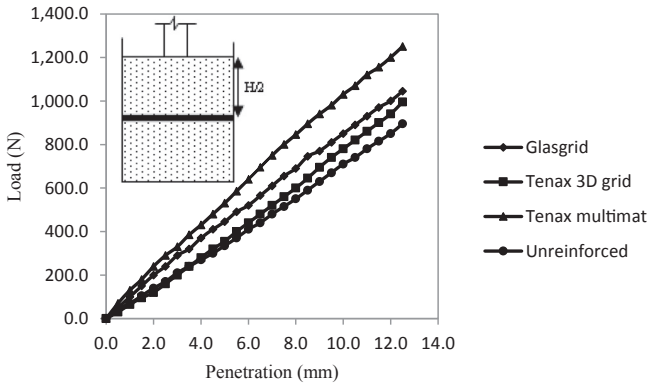


Fig. 5. Load penetration curve with geosynthetic placed at, $\xi = H/2$.

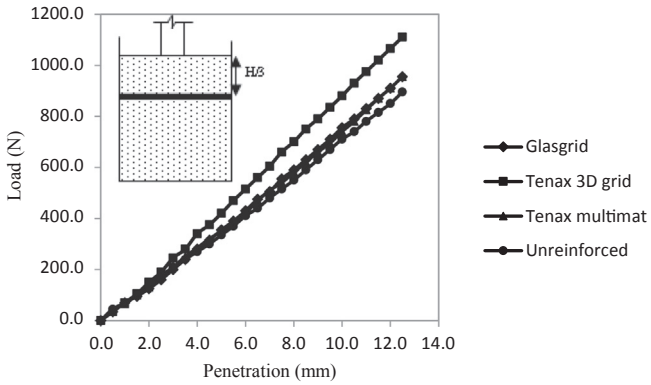


Fig. 6. Load penetration curve with geosynthetic placed at, $\xi = H/3$.

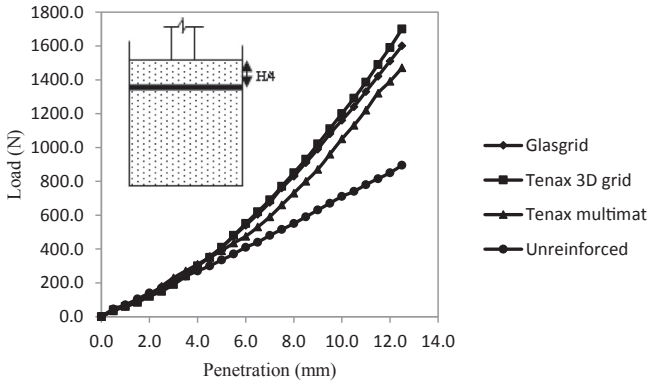


Fig. 7. Load penetration curve with geosynthetic placed at, $\xi = H/4$.

Results and discussion

CBR value

Figs. 5–7 present the variation of the load-penetration curves obtained from the *CBR* tests for unreinforced and reinforced sections with a single layer of reinforcement. It can be observed that placing the geosynthetic reinforcement at varying depths increases the *CBR* value significantly. The amount of increase in the *CBR* value depends on the position of geosynthetic reinforcement (ξ) and type of reinforcement. The *CBR* value of the unreinforced soil specimen corresponding to 2.5 mm and 5.0 mm penetrations were found to be 1.26% and 1.66% respectively as shown in Fig. 5, which were increased to 1.79% and 2.21% respectively, when Glasgrid reinforcement was placed at depth $H/2$. Further placing Tenax multimat reinforcement at same depth $H/2$, enhanced the *CBR* value to 2.16% and 2.63% respectively

corresponding to 2.5 mm and 5.0 mm penetrations. When Tenax 3D grid reinforcement layer was placed at the same depth $H/2$, it decreased the *CBR* value at 2.5 mm penetration to 1.19% but increased the *CBR* at 5.0 mm penetration to 1.76%. The maximum value of *CBR* obtained at 5.0 mm penetration is 2.63% when Tenax multimat reinforcement layer was placed at depth $H/2$. Similar results have been observed for other geosynthetic reinforcements placed at depth $H/3$ and $H/4$ as shown in Figs. 6 and 7.

Fig. 6 presents the variation of load-penetration curve for the soil specimen without reinforcement and soil specimen reinforced with different types of geosynthetic reinforcement layer at depth $H/3$. The increase in the *CBR* value of the Tenax 3D grid reinforced soil specimen corresponding to 2.5 mm and 5.0 mm penetrations were found to be 1.41% and 2.08% respectively. In case of Tenax multimat reinforcement it increased to 1.30% and 1.74% respectively corresponding to 2.5 mm and 5.0 mm penetrations. Only in case of Glasgrid reinforced specimen the *CBR* value decreased at 2.5 mm penetration to 1.19% and increased at 5.0 mm penetration to 1.76% as compared to the unreinforced specimen. The maximum value of *CBR* obtained at 5.0 mm penetration is 2.08% when Tenax 3D grid reinforcement was placed at depth $H/3$.

Fig. 7 represents the influence of the position of the reinforcing layer on the load-penetration curve for both unreinforced and reinforced specimens obtained from the *CBR* tests when the reinforcement was placed at depth $H/4$. The *CBR* value of the Tenax multimat reinforced soil corresponding to 2.5 mm and 5.0 mm penetrations were found to be 1.34% and 1.94% respectively. For Glasgrid and Tenax 3D grid reinforced soil specimen, the same *CBR* value was obtained at 5.0 mm penetration is 2.03% but it decreased to 1.19% and 1.12% at 2.5 mm penetration corresponding to Glasgrid and Tenax3D grid reinforcement respectively. The results are in good agreement with data presented by Williams [7] on effect of geosynthetic reinforcement on *CBR* strength of soil that leads to improve the strength of soil, resulting in a decrease in the surface penetration and deformation with stress distribution over a wider area. This means that the inclusion of single layer of geosynthetic reinforcement increases soil resistance against loading.

Fig. 8 shows the variation of the load-penetration curves obtained from the *CBR* tests for unreinforced and reinforced sections with double layers of reinforcement. The *CBR* value of the soil increased to 1.86% and 3.52% corresponding to 2.5 mm and 5.0 mm penetrations respectively when the subgrade is reinforced with double layers of Glasgrid reinforcement. The strength of the soil increased further by placing double layers of Tenax 3D grid reinforcement and Tenax multimat reinforcements. The *CBR* value of soil reinforced with double layers of Tenax 3D grid reinforcement corresponding to 2.5 mm and 5.0 mm penetrations were found to be 3.72% and 6.25% respectively as shown in Fig. 8, which were increased to 4.16% and 7.05% when the soil was reinforced with double layers of Tenax multimat reinforcement. It is clearly observed that Tenax multimat performs far better in terms of increase in *CBR* and load carrying capacity for double layers of reinforcement. The highest increase in *CBR* value was achieved when the subgrade soil was reinforced with double layers of reinforcement as compared to the unreinforced section and the section reinforced with a single layer of reinforcement.

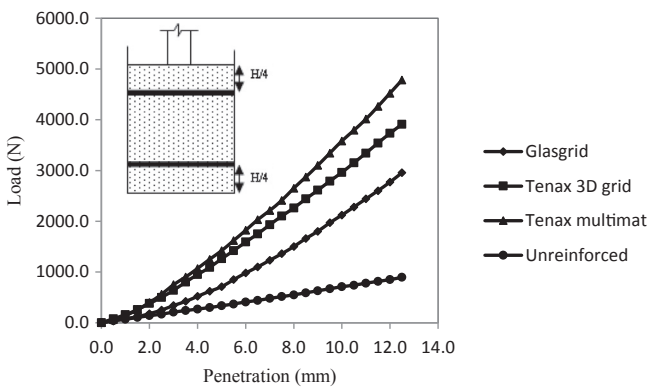


Fig. 8. Load penetration curve with double geosynthetic layer placed at $\xi = \xi' = H/4$.

The reason for the improvement in the strength of the subgrade soil reinforced with single and double layers of reinforcement is that, the geosynthetics used in the study has good interlocking and frictional capability which can provide tensile resistance to any lateral movements. Thus it improves the strength of the soil with low *CBR*. Another reason for the improvement in the strength of the subgrade with low *CBR* is that, through the inclusion of geosynthetic reinforcement layers the maximum vertical stress on the subgrade is reduced. The vertical stress on the subgrade is more uniformly distributed than on the absence of a geosynthetic. Therefore, reinforcement helps to improve the bearing capacity of the soil with low *CBR*. Also, the combining action of geosynthetic tension and geosynthetic improved load distribution results in vertical restraint of the subgrade.

Effect of multiple layer reinforcements

Table 3 shows the results of the *CBR* tests on soil reinforced with three different types of geosynthetics and presents the reinforcement ratio for these three types of geosynthetic reinforcement placed at depth $H/2$, $H/3$ and $H/4$ and double layers. It is clear that there is a considerable amount of increase in the *CBR* value of a soil reinforced with different types of geosynthetics at various depths. As the reinforcement ratio exceeds unity ($\eta > 1$) throughout the tests for different types of geosynthetic reinforcement used in the tests as shown in Table 3, which indicates the beneficial effect of reinforcement at varying depth to increase the subgrade strength of geosynthetic reinforced unpaved road. The location of the geosynthetic reinforcement within the subgrade is an important factor for the performance of unpaved road. The reinforcement ratio varies from 1.05 to 1.58 for a single layer of geosynthetic reinforcement and 2.12 to 4.25 for double layers of geosynthetic reinforcement respectively. Out of three types of geosynthetic reinforcement used in the study, geogrids perform better than geomat for soil reinforced with a single layer of reinforcement. Only in one case geomat reinforcement yields the maximum strength when it is placed at $\xi = H/2$ from the top, when compared to the other two geogrids. Geomat performs best among the three types of geosynthetic when soil is reinforced with double layers of reinforcement. An increase in the number of reinforcement layers led to the further increase in strength and load carrying capacity of soil. The reinforcement ratio lies between 2 and 5 which indicates that an introduction of geosynthetic as double layers of reinforcement offers a good resistance against the penetration.

Comparison of different types of geosynthetic reinforcement

Fig. 9 shows the relative influence of geosynthetic reinforcement at different positions on the reinforcement ratio. Three different types of geosynthetic were used in the test and properties of these geosynthetic material were presented earlier in Table 2. The comparison of the ability of different types of geosynthetic used in this study to reinforce the weak subgrade soil can only be accomplished if the conditions between each of the individual tests are identical. The comparison between the different types of geosynthetic reinforcement, in terms of reinforcement ratio is described in Fig. 9 for the section with a single layer of reinforcement placed at $H/2$, $H/3$, $H/4$ and double layers of reinforcement. It can be observed that the reinforced section with double layers of reinforcement has higher strength than the section reinforced with a single layer of reinforcement. Comparing the performance of different types of geosynthetic reinforcement is difficult because all three geosynthetics used are individually different from

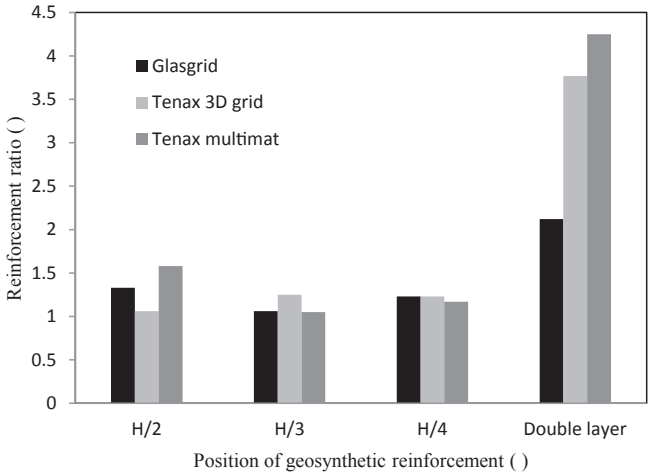


Fig. 9. Variation in reinforcement ratio for the various positions of geosynthetic reinforcement.

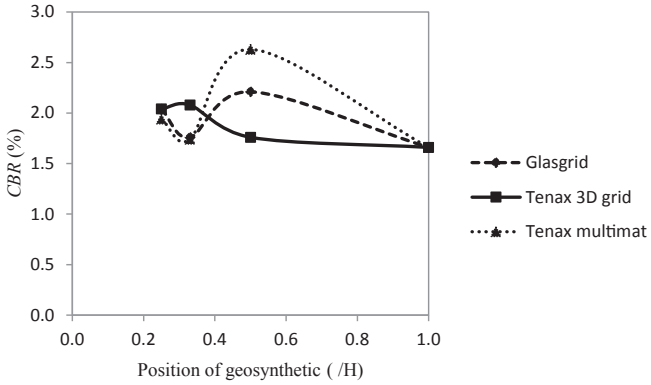


Fig. 10. Optimum position of geosynthetic based on *CBR* value of soil reinforced with different types of geosynthetics.

each other based on the properties given in Table 2. Important parameters which are responsible for comparing the performance of various geosynthetics to increase the subgrade strength are (1) type of geosynthetic used, (2) properties of geosynthetic, such as strength, stiffness, aperture size etc., (3) number of geosynthetic layers, and (4) depth of geosynthetic reinforcement. It is hard to identify which parameter has more important effect on the enhancement of subgrade strength reinforced with different types of geosynthetic. Therefore, it is better to investigate and quantify the mechanism that is responsible for the improved strength when different types of geosynthetics are used for comparison. The performance of the subgrade soil of an unpaved road is improved through three mechanisms: (1) impact of load distribution on subgrade soil resilient modulus, (2) subgrade soil vertical restraint, and (3) load transfer by the tensioned membrane effect [22]. The presence of geosynthetic in the subgrade soil reduces the maximum vertical stress on it and also more uniformly distributes the vertical stress on the subgrade soil than in the absence of a geosynthetic. Tensioned membrane effect becomes important only when large deformations occur in subgrade soil, when it is weak/soft.

Out of three types of geosynthetics used to reinforce subgrade with a single layer of reinforcement at varying depths, both geogrid reinforcements perform better than the geomat reinforcement except one case when geomat reinforcement it is placed at $\xi = H/2$ which yields the maximum strength when compared to the other two geogrids. Both geogrid reinforcements behaved similarly and gain the similar strength when placed at $\xi = H/4$. The same order was obtained for achieving the improvement when reinforcement layer was placed at $\xi = H/3$ and $\xi = H/4$ where Tenax 3D grid yields the maximum improvement. The results show that the behaviour of reinforced subgrade was better than that of the unreinforced subgrade and improvement with reinforcement is more pronounced when reinforcement layer is placed near to the load. The overall preference of choosing reinforcement type should be given to Tenax 3D grid which performs better than other geosynthetics because of the higher tensile strength and has relatively higher stiffness. Even handling of Tenax 3D grid over Glasgrid was easier because of the pressure sensitive adhesive provided at the back creates little inconvenience. Aperture size is different for all types of geosynthetic which governs the lateral confinement effect and justifies the selection of geogrid over geomat for subgrade reinforcement. To ensure effective interlocking between geosynthetic and soil, aperture size is a factor to be considered. The results of subgrade soil reinforced with double layers of reinforcement shows that Tenax multimat reinforcement type performs best because they offer good interlocking and frictional resistance. Increasing the number of reinforcement layers leads to enhance the strength significantly, as compared to the single layer of reinforcement and the extent of improvement is independent of type of geosynthetic. Tenax multimat is composed of tieing three layers of extruded and bi-oriented polypropylene grids. The non uniform texture of top and bottom layers of Tenax multimat offers good tensile resistance to the lateral movement. The relative cost of reinforcement type is also a factor which should be considered before the final selection is made.

Optimum position of the geosynthetic

Fig. 10 shows the effect of placement of a single layer of geosynthetic reinforcement along the height of the specimen on *CBR*. A set of experiments were carried out to determine the optimum position of placing the geosynthetic reinforcement along the depth of the subgrade in order to produce a maximum gain in the strength. The results of CBR tests indicates that for the maximum benefit, the geosynthetic reinforcement layer should be placed either at the middle of the height of specimen or between the upper one-third layer and middle layer which yields the higher strength as compared to the other locations. The tests were conducted at three different positions of geosynthetic and the maximum value of all strength parameters was obtained in the case when Tenax multimat reinforcement layer was placed at middle half of the specimen. Based on the properties of these geosynthetics, an increase in the strength of subgrade depends on the value of ξ i.e the depth of placement of reinforcement. Placing the geosynthetic at base of the specimen is just as good as having no reinforcement in the sample. The beneficial position of the geosynthetic reinforcement was obtained by plotting the graph between *CBR* of the soil and depth of the geosynthetic placement from top as shown in Fig. 8. The optimum position of the geosynthetic reinforcement layer should be taken as $0.3H$ to $0.36H$ for Tenax 3D grid reinforcement and $0.41H$ to $0.62H$ for Glasgrid reinforcement and Tenax multimat reinforcement where H is the height of the soil specimen. Naeini and Moayed [16] have also shown that the best location of geosynthetic reinforcement layer is at 30% of the thickness measured from the top of CBR mould. Reinforcement inclusion can be less effective if it is not placed at the proper location. Thus reinforcement layer should be located at the optimal depth to improve contribution of the geosynthetic reinforcement. For field applications, the finding of optimal location of geosynthetic reinforcement for maximum enhancement in *CBR* is essential.

Conclusions

In the present study, reinforcement benefits of different types of geosynthetics in unpaved road have been evaluated in terms of their *CBR* value. The performance of several geosynthetics in terms of increase in CBR value of soil with reinforcement can be compared with each other because all the tests are performed under the same

condition, that is, with the same subgrade soil. All these experiments can be related to an unpaved road as to whether the geosynthetic reinforcement can really improve the subgrade soil strength where the specimen height is considered as the depth of compacted subgrade soil in field. The findings indicate that there is a considerable amount of increase in strength of subgrade soil reinforced with geosynthetics and the amount of increase depends on the properties and type of geosynthetics, depth and number of reinforcement layers, and mechanisms involved. It is important to mention here that these findings are based on the laboratory investigations carried out in this study. It is possible that these findings may vary if conducted in the field. Therefore, actual field trials must be made to have more confidence in these results.

The important findings of this research are summarized below:

1. The inclusion of a single layer and double layers of geosynthetic reinforcements at varying depths in soil enhances the strength of the subgrade soil in terms of *CBR* value
2. The *CBR* value of the soil increases by 5–60% when a single layer of reinforcement is placed within the subgrade soil and strength increases by 112–325% when it is reinforced with double layers of reinforcement. The amount of improvement depends upon the position of reinforcement layer and type of reinforcement.
3. Placing the geosynthetic reinforcement in the double layers yields the largest improvement regardless of the type of geosynthetic.
4. The optimum benefit of reinforcement is evident if it is placed at middle height of the CBR mould and for better improvement in strength the reinforcement layer should be placed between the upper one-third layer and middle layer.
5. Of the three geosynthetics used in the study, Tenax 3D grid performed better than other two geosynthetics for soil reinforced with a single layer of reinforcement at $\xi = H/3 = H/4$ and Tenax multimat performed better than other two geosynthetics for soil reinforced with double layers of reinforcement and single layer of reinforcement at $\xi = H/2$.
6. Optimum location of reinforcement was found as $0.3H$ to $0.36H$ for Tenax 3D grid reinforcement layer and $0.41H$ to $0.62H$ for both Glasgrid reinforcement layer and Tenax multimat reinforcement layer.

Appendix A. Supplementary material

Supplementary data to this article can be found online at https://doi.org/10.1016/j.trgeo.2019.01.007.

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Swarm intelligence based optimal feature selection for enhanced predictive sentiment accuracy on twitter

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Abstract

A lot of uncertainty is generally associated with the micro-blog content, primarily due to the presence of noisy, heterogeneous, structured or unstructured data which may be high-dimensional, ambiguous, vague or imprecise. This makes feature engineering for predicting the sentiment arduous and challenging. Population-based meta-heuristics, especially the ones inspired by nature have been proposed in various pertinent studies for feature selection because of their probability to accept a less optimal solution and averting being stuck in local optimal solutions. This research demonstrates the use of two such swarm intelligence algorithms, namely, binary grey wolf and binary moth flame for feature optimization to enhance the sentiment classification performance accuracy. The study is conducted on tweets from two benchmark Twitter corpus (SemEval 2016 and SemEval 2017) and is initially analyzed using the conventional term frequency-inverse document frequency statistical weighting filter for feature extraction and subsequently using the swarm-based algorithms. The features are trained over five baseline classifiers namely, the Naïve Bayesian, support vector machines, k-nearest neighbor, multilayer perceptron and decision tree. The results validate that the population-based meta-heuristic algorithms for feature subset selection outperform the baseline supervised learning algorithms. For the binary grey wolf algorithm, an average improvement of 9.4% in accuracy is observed with an approximate 20.5% average reduction in features. Also, for the binary moth flame algorithm, an average accuracy improvement of 10.6% is observed with an approximate 40% average reduction in features. The highest accuracy of 76.5% is observed for support vector machine with binary grey wolf optimizer on SemEval 2016 benchmark dataset.

Keywords Binary grey wolf · Binary moth flame · Swarm intelligence · Meta-heuristic · Sentiment · Twitter

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1 Introduction

Proliferation of Web 2.0 has built strong social networks based on user's personal or professional interests. This has eventually intensified the research in the field of text mining especially sentiment analysis. *Social media* is often outlined as 'VUCCA' environment, i.e. volatile, uncertain, complex, chaotic, and ambiguous [21]. It generates a huge gamut of multimedia content which can be incessantly scrutinized for getting proper insights of market, business, and government intelligence [23, 25, 29, 30]. This social big data serves as a goldmine for mining thoughts, opinions, expressions, emotions and reviews. Analyzing sentiments from this huge and diverse user-generated multimedia content available on micro-blogging portals is the latest fad in social media analytics. *Sentiment analysis* or *opinion mining* is a typical text classification task [1] used to facilitate knowledge extraction of individual's sentiments for efficient decision making. It is defined as the computational study of people's opinions, attitudes and emotions towards an entity [22]. It is a specialized type of natural language processing task that relies on the analysis of the huge amount of user-generated online web content produced daily on social networks, blogs, e-commerce sites, and other user-editable web forums. Amongst all social media platforms, *Twitter* has emerged as a popular and powerful channel for testing, reasoning and extending the search capabilities of mining algorithms when applied to accomplish the 'generic sentiment classification task' [39]. Pertinent literature within the area report the use of various techniques such as machine learning, lexicon-based, hybrid and concept-based techniques (contextual and ontology based) etc. to mine the opinion [28]. Out of these, the application of supervised machine learning models to analyze sentiment and opinion polarity especially from Twitter data has been studied the most [26, 27]. One of the non-trivial sub-tasks for sentiment analysis is feature extraction and optimization [27, 31] which when implemented with optimal parameter setting can lead to an enhanced sentiment prediction. This task is computationally expensive and difficult [24]. Moreover, social media is an informal way of communication which includes colossal usage of slangs, mal-formed words, short forms, colloquial expressions and mash-up words. This amplifies the ambiguity, vagueness and imprecision within the available social web content. Mining and classifying such massive, noisy, incomplete and uncertain social web data affects the quality of sentiments derived and presents new challenges to *feature selection*. Past literature conforms that an optimal feature selection improves the classifier performance (in terms of speed, predictive power and simplicity of the model), reduces dimensionality, removes noise and helps visualizing the data for model selection. Hence to increase the predictive sentiment accuracy of learned models and to improve the learning efficiency with respect to reduce storage requirements and computational cost, it is imperative to build an intelligent feature selection model.

Many problems related to feature selection are NP -hard and finding an optimal subset of features is usually intractable [24, 35]. This necessitates examining new computational methodologies for finding optimal feature set which improves the performance of the sentiment classifier in terms of predictive accuracy and result comprehensibility. One such consortium of techniques is referred to as *soft computing,* which provides robust and low cost solutions to model the complexity associated with the real-world problems [43, 44]. Soft computing (SC) is a blanket term which comprises of a variety of techniques that use approximate calculations to provide imprecise but usable solutions to complex computational problems. Also, referred to as computational intelligence techniques, SC techniques are generally divided into following categories: machine learning, neural networks, evolutionary and swarm computing, fuzzy logic and probabilistic reasoning [44]. The unique property of all SC techniques is their power

of self-tuning, that is, they derive the power of generalization from approximating and learning from experimental data [44]. This generalization for improved precision and certainty is usually done in a high-dimensional space and the big social data space such as Twitter serves as the true source to testify the reasoning and search capabilities of SC techniques when extended to a generic sentiment classification task. Studies that comprehend the use of SC techniques for a supervised learning model of sentiment analysis on Twitter have continually motivated researchers and practitioners to explore the feasibility and scope of application.

Swarm intelligence algorithms (SI) are contemporary computational and behavioral metaphors for solving search and optimization problems which take collective biological patterns provided by social insects (ants, termites, bees, wasps, moths etc.) and other animal societies (fish, birds, grey wolves etc.) as stimulus to model algorithmic solutions. Several algorithms inspired by natural phenomena have been proposed in the past years and among them, some meta-heuristic search algorithms with population-based framework have shown satisfactory capabilities to handle high dimension optimization problems [5]. The work presented in this paper is an insight to this research trend which comprehends the adaptive learning and collective intelligence behavioral models of swarm-based algorithms. In this research, we demonstrate the application of two population-based meta-heuristic, nature inspired algorithms, namely the binary grey wolf (BGW) [38] and the binary moth flame (BMF) [36] on Twitter benchmark corpus for enhanced sentiment classification task. The conventional feature extraction using TFIDF (term frequency-inverse document frequency) [42] is done on the preprocessed dataset to generate a feature matrix. Swarm-based feature optimization using the BGW and BMF is then applied independently on the generated feature matrix to acclimatize to the increased dimensionality; complexity and fuzziness in the user-generated Twitter data and eventually enhance the classifier performance. The results are empirically compared using five baseline supervised machine learning algorithms namely Naïve Bayesian (NB), support vector machines (SVM), multilayer perceptron (MLP), k-nearest neighbor (k-NN), and decision tree (DT). The empirical analysis demonstrates the benefit of adding swarm-based feature selection optimizer and validates that the swarm-based feature selection optimization in sentiment classification task outperforms the intrinsic TFIDF filter based classifier.

The sentiment classification task is divided into four sub-tasks: (i) data collection and preprocessing (ii) feature extraction using TFIDF (iii) feature selection using BGW or BMF and (iv) training and testing baseline classifiers. The results are evaluated on the basis of various performance measures. Thus, the main contributions of this research are as follows:

- Implement five supervised learning algorithms for sentiment prediction with and without optimal feature matrix: NB, SVM, MLP, k-NN, DT
- Compare these to find the best sentiment prediction model on the basis of accuracy (Ac) and feature set reduction
- Performance analysis of classifiers to demonstrate improved prediction accuracy using swarm-based feature optimization

The evaluation is done on two benchmark Twitter datasets, SemEval 2016[1] (Dataset 1: DS1) and SemEval 2017[2] (Dataset 2: DS2). Using two datasets validates the results achieved and helps determine the robustness of each algorithm.

[1] http://alt.qcri.org/semeval2016/task4/
[2] http://alt.qcri.org/semeval2017/task4/

The rest of the paper is organized as follows. Section 2 discusses the related work in literature. Section 3 explains the background concepts about the techniques and algorithms used in this work. Section 4 elaborates the systematic workflow. Section 5 presents the results and its discussion. Finally, section 6 presents the conclusion of the work and the future scope.

2 Related work

The global presence of Twitter which connects millions of people world-wide eventually makes it a popular and leading sentiment rich corpus [22]. The term "sentiment analysis" was first given in the year 2003 by Dave et al. [10]. Since then, pertinent literature studies, both primary [21–23, 25, 26, 30, 39] and secondary [27, 28, 31] have been conducted within the domain. Finn and Mustafaraj, 2013 [15] proposed the use of Machine Learning (ML) techniques like NB, SVM, kNN for labeling the tweets under "political activist" and "general public" categories. NB outperformed the other two with an accuracy of around 92%. Another work reported in 2013 by Arias et al. [3] focused on the application of neural network, SVM and DT for building and evaluating the forecasting models for different time series data sets under different experimental conditions for Twitter. In 2014, Tuarob et al. [48] discussed the use of techniques like SVM, random forest, NB for health related tweets using varied feature sets. SVM performed the best with an improved F measure of 68.47%. In 2015, Burnap and Williams [8] proposed the use of SVM, random forest, DT and hybrid of these methods for monitoring public reactions to emotional hateful events like death of Rigby which could further be used by policymakers for efficient decision making process for such cyber hate on social media. In 2016, Sulis et al. [46] had briefly discussed about the figurative content of the tweets with hashtags 'not, sarcasm and irony' and applied techniques like DT, random forest, SVM, NB, logistic regression. Author aimed to explore the differentiating traits among these figurative tweet contents. In 2017, Kumar and Jaiswal, [22] did an empirical analysis on the two micro-blogs namely Twitter and Tumblr using supervised learning techniques like NB, SVM, MLP, kNN and DT.

The authors Lazar and Reynolds [34] defined meta-heuristics as the combination of Greek words "meta" meaning "beyond" or "higher level" and "heuristic" meaning "to know", "to find" or "to discover". Nature inspired algorithms imitate processes inspired from nature [24, 31]. These can be classified as evolutionary algorithms: genetic algorithms, differential evolution, genetic and evolutionary programming; bio-inspired algorithms: artificial immune system (AIS), bacterial foraging optimization algorithm (BFOA), dendritic cell algorithm (DCA); physics-chemistry algorithms: simulated annealing, gravitational search, harmony search, memetic algorithm and swarm intelligence algorithms: artificial bee colony algorithm (ABC), particle swarm optimization (PSO), ant colony optimization (ACO), bat algorithm (BAT), cuckoo search (CS), firefly algorithm (FA), bird flocking (BF) [5]. All these are population-based methods make use of the global behavior that emerges from the local interaction of individuals with one another and with their environment [5].

Few studies demonstrating swarm-based opinion prediction in social networks are available in literature. In 2013, Basari et al., [4] proposed a hybrid model using SVM and PSO for sentiment analysis of movie reviews using 10 fold cross validation method. The authors used PSO for optimization of feature selection for classifying the reviews as either positive or negative and the results showed that using PSO for optimized feature selection produced a rise in accuracy by 7%. In the same year, T. Sumathi et al. [47] used ABC algorithm for selecting optimal feature set for improved classification accuracy and reduced computational complexity. In this study, movie

reviews were classified on the basis of opinions using ABC based optimizer. This method produced improved classification accuracy in range of 1.63% to 3.81%. In 2014, Stylios et al. [45] proposed a hybrid methodology called as PSO/ACO2 algorithm and applied in the domain of sentiment analysis for e-governance using ten-fold cross validation technique. Authors compared the hybrid methodology with decision tree and an improved accuracy of around 91% was observed for the proposed model. In 2015, Gupta et al. [16] proposed aspect based sentiment analysis using PSO and performed feature selection with conditional random field on Twitter benchmark dataset, SemEval 2014. The proposed technique automatically determined the most relevant features for sentiment classification and experiments revealed that the system achieved better accuracy with a feature set having lower dimensionality. Authors obtained an enhanced classification accuracy of 78.48% for the restaurant and 71.25% for the laptop domain. In the same year, Dhruve et al. [11] investigated ABC algorithm for calculating weight of sentiments using 'Bag of Words' and 'Bag of Noun' features. Sphere benchmark function was used is this work for optimizing the best result of classification. Experimental results showed an accuracy improvement from 55% to 70%. Another study given by Zhang et al. [50] in 2017 depicted the use of distance based discrete firefly algorithm for optimal feature selection using mutual information criterion for text classification. The system proposed in this work used mutual information based criterion which measured association between two features selected by the fireflies and determined the corrections among the selected features. The proposed system was also compared with other techniques such as genetic algorithm, two variants of PSO and differential algorithm. The proposed approach yielded enhanced classification accuracy. In 2017, Kumar et al. [24] proposed a firefly algorithm based feature subset selection. SVM classifier was used for the classification task and four different datasets were used and the results were compared with feature selection using genetic algorithms. In 2018, Kumar et al. [33] proposed sentiment analysis using binary cuckoo search for optimized feature selection on Kaggle tweets and achieved higher classification accuracy combining optimizer with the TFIDF.

In this research, the *binary variants* of Grey wolf (GW) and Moth flame (MF) optimizers have been applied for feature selection in wrapper mode for sentiment classification on Twitter. In order to select the optimal subset of features, conventional greedy algorithms easily fall into suboptimal solutions. GW and MF optimizers and their binary variants, the binary grey wolf (BGW) and the binary moth flame (BMF) optimizers have demonstrated superior or comparable performance as contrast to other popular nature-inspired optimization algorithms [12, 19, 20, 40, 49]. These have proven capabilities in solving some optimization problems and NP hard problems because of their probability to accept a less optimal solution. These also help in avoiding being stuck in local optimal solutions. To the best of our knowledge, the use of BGW and BMF algorithms for feature selection in social media sentiment analysis has not been studied and this research investigates the application of these algorithms. The next section explicates the conceptual details of supervised learning techniques, TFIDF and the optimization algorithms.

3 Background concepts

Soft computing has emerged as a significant paradigm to solve real world problems which are pervasively imprecise, uncertain and complex. The guiding principle of soft computing is to exploit the tolerance for imprecision, uncertainty, and partial truth to achieve tractability, approximation, low solution cost, and better rapport with reality [43]. These techniques are basically *decision and optimization techniques* which aim to find robust and low cost solutions

of complex problems. Soft computing techniques have been categorized into five types as shown in Fig. 1.

Machine learning is one of the most prominent theories of computational intelligence where programs learn from data in a supervised, unsupervised or reinforced manner. In machine learning, classification is a supervised learning approach where the algorithm learns from the data input given to it and then uses this learning to classify new observation. Different types of classification algorithms are linear classifiers (logistic regression, Naive Bayesian classifier), support vector machines, decision trees, boosted trees, random forest, neural networks and nearest neighbor. Novel computational models for finding optimal training feature set which improves the performance of the classifier has been a current research trend.

Recently, various meta-heuristic optimization algorithms have been developed to solve complex real-world problems. Swarm intelligence and evolutionary algorithms are two major categories of meta-heuristics. Meta-heuristic optimization does the same operations as stochastic search, which lookouts the search space in distributed fashion for a current best solution. It is an iterative method which improves the current best solution by exploring the regions not yet explored and trying out new solutions. The movement patterns by the designs of the meta-heuristics are often inspired by the nature phenomenon or the behaviors of some animals or insects. Figure 2 depicts the meta-heuristic categories and the classification of population-based, nature inspired meta-heuristics as evolutionary algorithms, bio-inspired algorithms, physics/chemistry-based algorithms, and swarm-intelligence based algorithms.

Table 1 provides brief information about soft computing techniques used in this research.

The baseline supervised techniques have been studied extensively in literature [2, 22]. In the next sub-sections, we discuss the BGW and BMF algorithms, their architecture and respective pseudo-codes.

3.1 Binary grey wolf (BGW) algorithm

In this sub-section, the standard grey wolf optimization (GWO) algorithm is primarily explained to enable the understanding of its binary variant. The GWO algorithm is a population-based meta-heuristic optimization algorithm which mimics the social hierarchy and the hunting behaviour of grey wolves in nature. As given by Mirjalili et al. [38], grey wolves live in a pack of 5 to 12. The pack has a hierarchical ordering of ranks; wolves of the highest rank (alpha) being revered the most. The social hierarchy is as follows:

The wolf population is divided into four categories, namely '*alpha, beta, delta and omega*' as shown in Fig. 3. *Alpha* male or female is at the topmost position in the family pyramid and has clear dominance over other family members. This dominant wolf is the reigning leader and has authority to make leadership decisions about search spaces for hunting, resting and sleeping, and about food distribution etc. His decisions are almost obeyed by all other

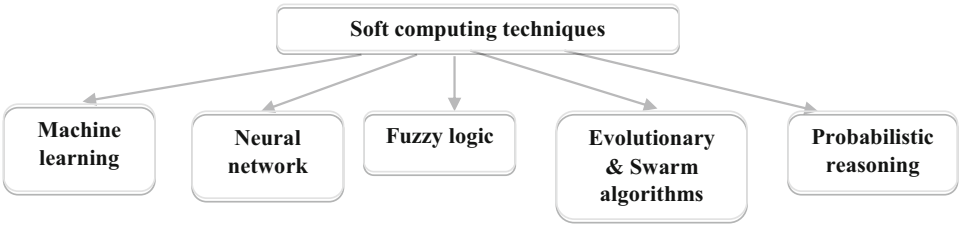


Fig. 1 Soft computing techniques

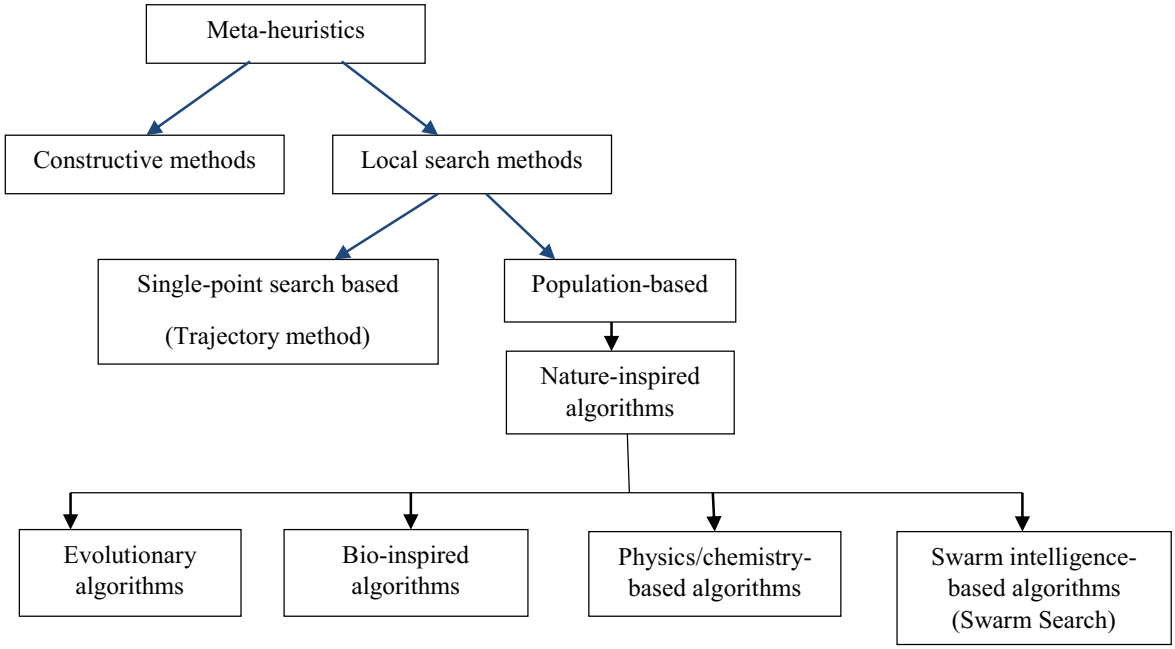


Fig. 2 Meta-heuristic categories

members in the family. Next to the *Alpha* wolf is *Beta* male or female wolf who is a second in command to the *Alpha* wolf. His/her responsibility is to make sure that all the rules and regulations laid down by *alpha* are being followed. *Beta* also has the power to guide the lower level wolves in the family besides acting as a counsellor to *alpha* in situations when needed. Next in the hierarchy are *delta* wolves, which are trusted by *alpha* and *beta*. These obey and follow the decisions and orders made by *alpha* and *beta*. They majorly have the responsibility

Table 1 Description of soft computing techniques used

Technique	Description
NB	It is a basic probabilistic model. It is based on the Bayes Theorem along with a strong independence assumption between every pair of features. They need trivial amount of training data for estimating the necessary parameters [15, 22, 46, 48].
SVM	The concept of SVM algorithm is based on decision plane that defines decision boundaries [3, 8, 15, 22, 46, 48]. A decision plane separates group of instances having different class memberships. It builds a hyper-plane or a set of hyper-planes that is further utilized for classification.
k-NN	It is often considered as the simplest approach amongst all. It is defined as a non-parametric method that relies on the 'category labels where an output is a class membership. The main ideology behind this approach is that the object is classified by the majority votes of its neighbors [15, 22].
MLP	MLP are a type of neural networks [22] consisting of input, hidden and output nodes. It is a data driven and self-adaptive technique that can regulate them according to the data without any explicit specification of functional or distributional form for the underlying model [3].
DT	It consists of branches, root and leaf nodes. Here, the corpus is broken down into smaller subsets and consequently builds an associated decision tree. It provides a convenient way of representing classification examples where the input features are associated with the non-leaf nodes [3, 8, 22, 46].
BGW	It is one of the recently proposed swarm based nature inspired meta-heuristic algorithm [37, 38] that often mimics the hunting behavior and strategy of grey wolves in nature to find the most optimum solution amongst the collection of all possible solutions.
BMF	It also belongs to the class of swarm based algorithms [36] that generally mimics the navigation behavior and strategy of moths in natural habitat. The most exciting phenomena of moth's navigator mechanism is that they employ moon light for travelling longer distances while remaining in a straight line.

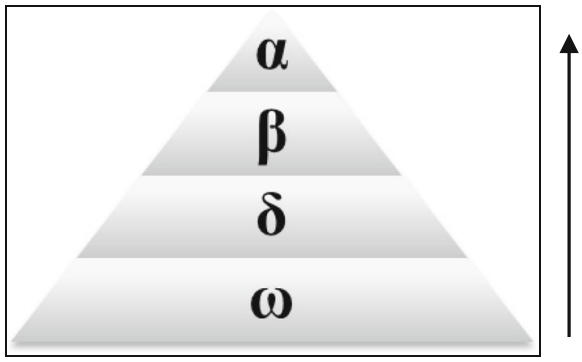


Fig. 3 BGW hierarchy (dominance increases from bottom up)

of protecting, defending and providing safety to all other wolves in the family [14]. At the lowest level of the pyramid are the *omega* wolves. The *omega* wolves always have to submit to all the other dominant wolves. They are the last wolves that are allowed to eat. They are referred to as scapegoats, and submit to all other wolves.

The group hunting behavior of grey wolves includes (as shown in Fig. 4):

- Tracking, chasing, and approaching the prey
- Pursuing, encircling, and harassing the prey until it stops moving
- Attack towards the prey

The optimization (hunting) model based on social hierarchy of grey wolves, the other wolves (i.e. omega) update their positions with respect to the alpha, beta and delta. That is, in the GWO algorithm, the set of possible solution sets is viewed as the wolf pack. Each solution is a wolf, and the fitness of the solution determines the position of that solution (wolf) in the hierarchy defined above. The fittest solution is regarded as the alpha (α), and the second and third regarded as beta (β) and delta (δ), respectively. The rest of the solutions are regarded as the omegas (δ). The optimization problem is analogous to a hunting scenario of the wolf pack.

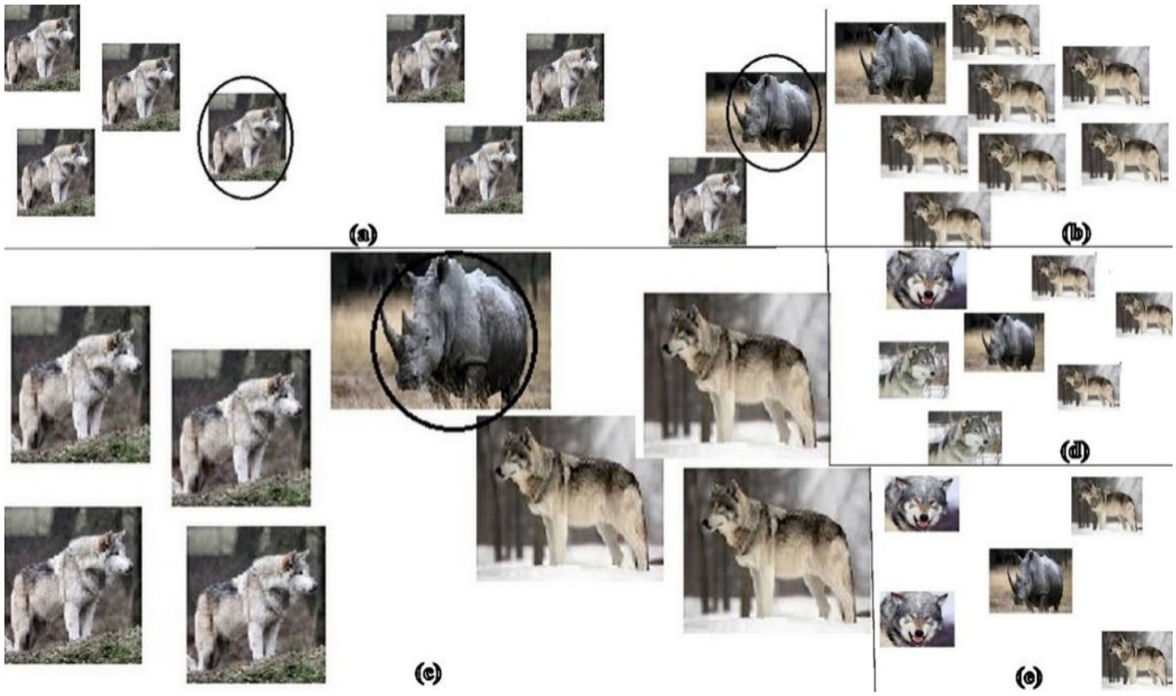


Fig. 4 Hunting mechanism of Grey Wolves: (a) Tracking, chasing, and approaching the prey (b-d) Pursuing, encircling, and harassing the prey (e) attacking the prey

The position of the prey is the coordinates of the most optimal solution, which is to be ultimately found. In a hunting situation, the wolves encircle the prey, and gradually close it down. The encircling behaviour is modelled using eqs. 1 to 4.

$$\overrightarrow{X}(t+1) = \overrightarrow{X_p}(t) + \overrightarrow{A}.\overrightarrow{D} \tag{1}$$

where, $\overrightarrow{D}$ is defined below, t is the iteration number, $\overrightarrow{A}$ and $\overrightarrow{C}$ are the coefficient vectors, $\overrightarrow{X_p}$ is the prey position, and $\overrightarrow{X}$ is the

$$\overrightarrow{D} = \overrightarrow{C}.\overrightarrow{X_p}(t) - \overrightarrow{X}(t) \tag{2}$$

The $\overrightarrow{A}$ and $\overrightarrow{C}$ vectors are calculated as

$$\overrightarrow{A} = 2a.\overrightarrow{r_1} - a \tag{3}$$

$$\overrightarrow{C} = 2\overrightarrow{r_2} \tag{4}$$

Here, a is linearly decreased from 2 to 0 over the iterations, $\overrightarrow{r_1}$ and $\overrightarrow{r_2}$ are random vectors.

The hunt is guided by the alpha, and the beta and delta occasionally participate in it. The fittest solution is regarded as the alpha, the next best beta, and the third best delta. All the other solutions are called the omegas. The first three best candidate solutions guide the omegas, whose solutions are updated to get closer to the prey. The updating of the wolves positions is shown via eq. 5.

$$\overrightarrow{X}(t+1) = \frac{\overrightarrow{X_1} + \overrightarrow{X_2} + \overrightarrow{X_3}}{3} \tag{5}$$

where, $\overrightarrow{X_1}, \overrightarrow{X_2}, \overrightarrow{X_3}$ are defined as:

$$\overrightarrow{X_1} = \overrightarrow{X_\alpha} - \overrightarrow{A_1}.\overrightarrow{D_\alpha} \tag{6}$$

$$\overrightarrow{X_2} = \overrightarrow{X_\beta} - \overrightarrow{A_2}.\overrightarrow{D_\beta} \tag{7}$$

$$\overrightarrow{X_3} = \overrightarrow{X_\delta} - \overrightarrow{A_3}.\overrightarrow{D_\delta} \tag{8}$$

where $\overrightarrow{X_\alpha}$, $\overrightarrow{X_\beta}$ and $\overrightarrow{X_\delta}$ are the first three best solutions in the swarm, respectively as shown via eqs. 6 to 8.

$\overrightarrow{D_\alpha}\overrightarrow{D_\beta}$, and $\overrightarrow{D_\delta}$ are defined via eqs. 9 to 11.

$$\overrightarrow{D_\alpha} = \overrightarrow{C_1}.\overrightarrow{X_\alpha} - \overrightarrow{X} \tag{9}$$

$$\overrightarrow{D_\beta} = \overrightarrow{C_2}.\overrightarrow{X_\beta} - \overrightarrow{X} \tag{10}$$

$$\overrightarrow{D_\delta} = \overrightarrow{C_3}.\overrightarrow{X_\delta} - \overrightarrow{X} \tag{11}$$

The pseudo-code of GWO is given in Table 2:

The algorithm starts with initialization of n random solutions (wolves), and calculation of their fitness values. Step 2 assigns alpha, beta and delta wolves from amongst the pack, according to the fitness. Steps 3–6 mark the repeated iterations. On each iteration, for every wolf, the wolf 'encircles' the prey and shifts closer to it according to the equations defined above.

Table 2 Pseudo-code of GWO

Input:
n: Number of grey wolves in the pack
N_{iter}: Number of iterations for optimization
Output:
x_α: Optimal grey wolf position
$f(x_\alpha)$: Best fitness value

1. Initialize a population of *n gray* wolves positions randomly.
2. Find α, β and δ solutions based on their fitness values.
3. While stopping criteria not met do:
4. for each Wolf $W_i \in$ pack do
5. Update current wolf's position according to equation.
6. end
7. Update a, A, and C.
8. Evaluate the positions of individual wolves.
9. Update α, β and δ
10. End

The GWO algorithm is a generic algorithm applicable directly on optimization (maximization) problems with continuous parameters. The feature selection problem, however, is a problem of maximizing the accuracy of classification wherein there are n parameters, corresponding to each of the n features. Each of the n parameters are discrete, assuming a value of 0 or 1, 0 implying the feature is not selected and 1 implying the feature is selected. Thus, a binary adaptation of the GWO given by Emary et al. [13], called the binary grey wolf optimization (BGW) is used in this research. Instead of the input variables being continuous in nature, it is a binary 1xd vector, where d is the number of features out of which a subset is to be selected. The purpose of BGW optimization is to find the minimum number of features that maximize the classification performance. Thus, the fitness function is the accuracy of the classification. In this research, the findings of BGW have been observed for sentiment classification in a corpus of tweets.

In this approach the main updating equation can be formulated as shown in eq. 12.

$$X_i^{t+1} = Crossover(x_1, x_2, x_3) \tag{12}$$

where Crossover(x, y, z) is suitable cross over between solutions x, y, z, and x_1, x_2, x_3 are binary vectors representing the effect of wolf move towards the alpha, beta, delta grey wolves in order. x_1, x_2, x_3 are calculated using eqs. 13 to 16 respectively.

$$x_1^d = \begin{cases} 1, if \ \left(x_\alpha^d + bstep_\alpha^d\right) \geq 1 \\ 0, \qquad\qquad otherwise \end{cases} \tag{13}$$

where x_α^d is the position vector of the alpha wolf in the dimension d, and $bstep_\alpha^d$ is a binary step in dimension d calculated as

$$bstep_\alpha^d = \begin{cases} 1, & if \ cstep_\alpha^d \geq rand \\ 0, & otherwise \end{cases} \tag{14}$$

where *rand* is a random number drawn from uniform distribution $\in$ [0, 1], and $cstep_\alpha^d$ is the continuous valued step size for dimension d and can be calculated using sigmoidal function.

Similarly,

$$x_2^d = \begin{cases} 1, if \left(x_\beta^d + bstep_\beta^d\right) \geq 1 \\ 0, \qquad otherwise \end{cases} \tag{15}$$

and,

$$x_3^d = \begin{cases} 1, if \left(x_\delta^d + bstep_\delta^d\right) \geq 1 \\ 0, \qquad otherwise \end{cases} \tag{16}$$

The pseudo-code of the BGW is given in Table 3:

The algorithm starts with initialisation of n random binary solutions (wolves), and calculation of their fitness values. Step 2 assigns alpha, beta and delta wolves from amongst the pack, according to the fitness. The fitness is calculated by training the classifier according to the selected features as specified by the solution (wolf), and measuring the corresponding accuracy of the classifier. Steps 3–7 mark the repeated iterations. On each iteration, for every wolf, the wolf 'encircles' the prey and shifts closer to it according to the equations defined above. The calculation of x_1, x_2, and x_3 is done as specified for the GWO.

3.2 The binary moth flame algorithm (BMF)

Moths are considered to have similarity with the butterfly species. They are often called as '*tiny fancy insects*'. They possess a unique navigation mechanism in which they use moon light for travelling to longer distances while remaining in a straight line. For maintaining a fixed angle with the moon light, they use '*transverse orientation*' where moths fly relative to the position of the moon [17] as shown in fig. 5. This navigation mechanism allows the moths to move in a straight line making a fixed angle with the light of the moon.

When moths encounter a man-made artificial luminous source, they attempt to maintain a constant angle with the light so as establish a straight line trajectory flight. Since this artificial source is significantly closer as compared to the moon, sustaining a constant angle to the light

Table 3 Pseudo-code of BGW

Input:
n: Number of grey wolves in the pack
N_{iter}: Number of iterations for optimization
Output:
x_α: Optimal grey wolf position
$f(x_\alpha)$: Best fitness value

1. Initialize a population of *n grey* wolves at random $\in$ [0, 1]
2. Find α, β and δ solutions based on their fitness values.
3. While stopping criteria not met do:
4. for each Wolf $W_i \in$ pack do
5. Calculate x1; x2; x3 using equations (14), (17), and (20)
6. $x_i^{t+1} \leftarrow$ crossover among x_1, $x_2$and x_3
7. end
8. Update a, A and C.
9. Evaluate the positions of individual wolves.
10. Update α, β and δ
11. End

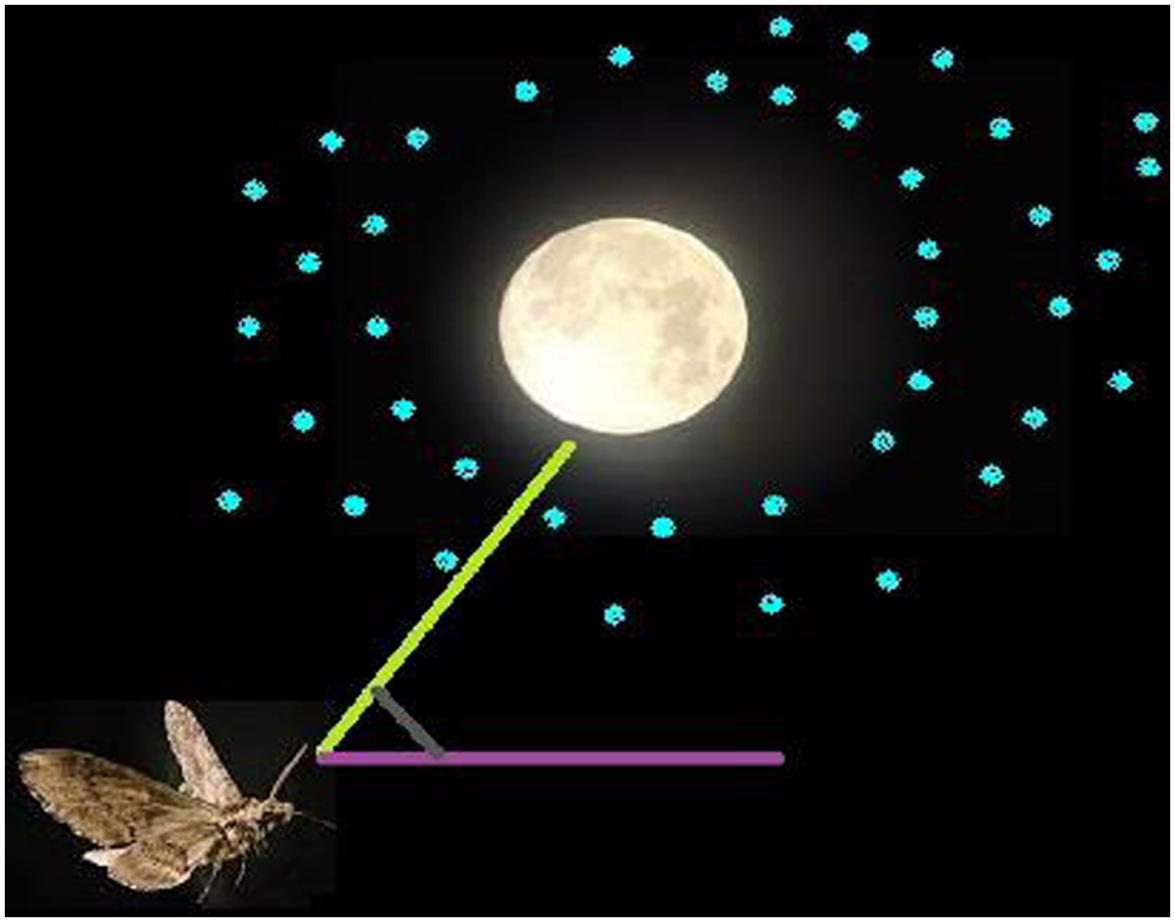


Fig. 5 Transverse navigation mechanism of moths in moonlight

source results in a useless or fatal spiral fly trajectory for the moths [41] as shown in Fig. 6. It is often observed that in the case of artificial light, the moths, in due course, converge towards the luminous source.

This behaviour of convergence of moths to such lights is being mathematically formulated to form an algorithm known as moth flame algorithm (MFO) proposed by Mirjalili [36]. It is

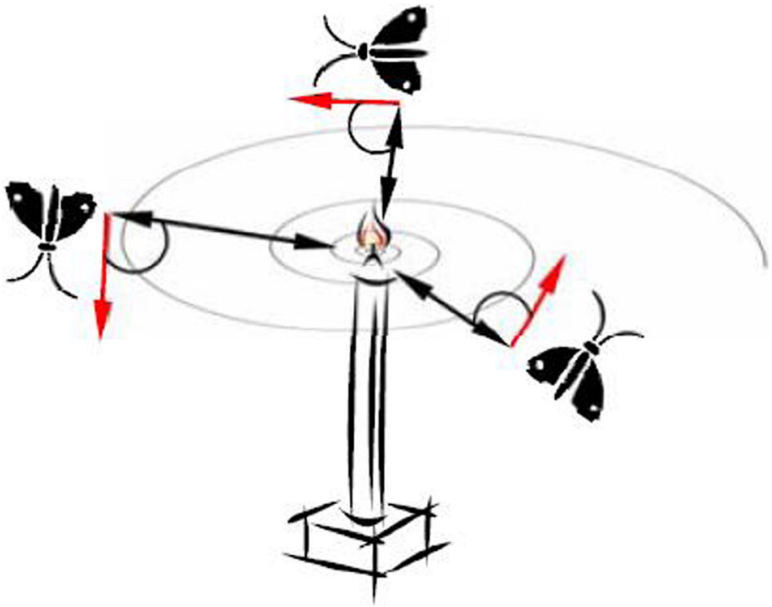


Fig. 6 Spiral flight trajectory around close luminous sources

based on the simulation of behaviour of moths and their interesting navigation techniques in the night, as explained above. It comprises of two major components i.e. *moth and flame* [36]. '*Moths*' represent the actual search agents that move and travel around the search space whereas '*flames'* represent the fittest or best position of the moths obtained till date. In reality, both of them are merely solutions but flames can be best understood as mid-level flags that are often dropped by these moths or agents while finding the search space. Using the transverse orientation navigation mechanism, a moth never loses its best or most optimum path (or solution) as each of the moth consistently and constantly searches around this flame or mid-level flags and consequently updates themselves to find a better solution [36]. Further, moths (Z represented in a form of matrix) can fly in any dimensional space (denoted as d), constantly changing their position vectors. The pseudo-code for the MFO is given in the Table 4:

It starts with the initialization of the position of the moths in a matrix, using the function I described in eq. 17, as shown in Step 1–5.

$$\mathrm{MFO} = (\mathrm{I}, \mathrm{P}, \mathrm{T}) \tag{17}$$

This equation signifies that the MFO Algorithm is a tuple of three values that approaches the global optimal of the optimization problems.

$$\mathrm{I} : \Phi \rightarrow \{\mathrm{M}, \mathrm{OM}\} \tag{18}$$

I is a function that institutes a random population of moths and their corresponding fitness values. The above eq. 18 depicts the methodical model of this function. Steps 9–35 mark the actual implementation of the said algorithm.

A loop from steps 10–36 is executed, which in each iteration, updates the number of flames according to eq. 24. Thereafter the matrix containing fitness values of moths is computed using fitness function given by eq. 25.

$$\mathrm{P} : \mathrm{M} \rightarrow \mathrm{M} \tag{19}$$

The P function is the principal function that is responsible for the movement of the moths around the search space. It receives the matrix M, and returns its updated version, as shown via eq. 19.

Steps 16–19 are executed for the 1st iteration, when we don't have any past populations of moths. Here, the moths are sorted according to their fitness values from best to worst. The flame matrix is thereby updated with these values. Steps 17–20 depict the case when a past population of moths exist, and can be used in updating of flame matrix. The previous and current populations are merged, and then sorted according to fitness values. Subsequently, updating are made on the flame matrix. Steps 21 to 35 depict the updating of moth positions using eqs. 21 and 22. The convergence constant r, and parameter t, is accordingly calculated as shown via eq. 20.

$$\mathrm{T} : \mathrm{M} \rightarrow \{\mathrm{true}, \mathrm{false}\} \tag{20}$$

The T function returns true if the termination norm is satisfied and false if termination norm isn't satisfied.

$$\mathrm{M_i} = \mathrm{S}\left(\mathrm{M_i}, \mathrm{F_j}\right) \tag{21}$$

$\mathrm{M_i}$ indicates the ith moth, $\mathrm{F_j}$ indicates the jth flame, and S is the spiral method, as shown via eqs. 21 and 22.

Table 4 Pseudo-code of MFO

Input : Number of dimensions, number of search agents (moths), maximum iterations

Output : Global best Positions of flames and moths

```
for each moth n_i (i = 1,……,m) do:
    for each dimension j (j = 1,…..,d) do:
        M(i,j) ← Random{0,1}
    end
end
for each moth n_i (i = 1,….,m) do:
        moth_fitness_i ← -∞
end
Initialize best_flames & best_flames_fitness with M(i,j) and moth_fitness respectively.
While (Iteration <= Max_Iteration)
        new_flame_no ← round( N – l*(N-1)/T );
        flame_no ← new_flame_no;
        for each moth n_i (i = 1,……,m) do:
                Train classifier over training set, evaluate over testing set, store acc
        end
        if iteration == 1 then:
            F = sort (M);
           OF = sort (OM);
        else
            F = sort (M_t-1, M_t);
           OF = sort (M_t-1, M_t);
        end
        r = -1 + iteration * ((-1)/Max_iteration);
        for each moth n_i ( i = 1….n) do:
            for each dimension j ( j = 1….d) do:
                if i <= flame_no then:
                    D ← | F_j – M_i |
                    b = 1;
                    t = (r-1) * random() + 1;
                    M(i,j) = D * e^bt * cos (2πt) + flame(i,j);
                else:
                    D ← | F_j – M_i |
                    b = 1;
                    t = (r-1) * random() + 1;
                    M(i,j) = D * e^bt * cos (2πt) + flame(flame_no,j);
            end
        end
end
```

Any types of spiral can be utilized here subject to the following conditions:

- Spiral's initial point should start from the moth.
- Spiral's final point should be the position of the flame.
- Fluctuation of the range of spiral should not exceed the search space.

$$S\left(M_i, F_j\right) = D_i.e^{bt}.\cos(2\pi t) + F_j \tag{22}$$

This is the definition of the logarithmic spiral is given via eq. 23.

$$D_i = |F_j – M_i| \tag{23}$$

Here D_i defines the distance of the ith moth for the jth flame, b is a constant that explains the shape of the logarithmic spiral, and t is a rand no. in [−1,1], as shown via eq. 24.

$$N_{flames} = \text{round}\left(N\text{–}l^{*} (N-1)/T \right) \tag{24}$$

Here, l is the current number of iteration, N is the maximum no. of flames, and T is maximum no. of iterations, as shown via eq. 25

$$f_{\theta} = \alpha.E + (1-\alpha)^{*} (\sum \theta_i)/N \tag{25}$$

Here, f_θ is fitness function given a vector θ sized N with 0/1 constituents depicting unselected/selected features, N is total no, of features in data set, E is classifier error rate and α is constant manipulating the significance of classification performance to number of features selected.

To facilitate the task of feature selection, a binary version of moth flame optimization (MBF) algorithm has been designed. Standard MFO provides continuous valued positions of solutions, which are, flames and moths. Using a sigmoid function, the continuous valued method is transformed into discrete binary values. A solution binary vector is used, where 1 represents feature selected and 0 represents otherwise. A threshold is applied to convert the value output by sigmoid function into binary values, in other words, discretize it. Table 5 presents the pseudo-code of BMF.

The steps 1–35 of the pseudo-code are the same as that of the generic (continuous) MFO algorithm. Steps 36–40 depict the binary version of MFO introducing an auxiliary function which compares the values obtained from the generic algorithm to a certain threshold, and thereby assigns binary values. A conditional operator is used to branch 2 different paths for the binary values.

The function S is called sigmoid function, which transforms the continuous valued positions provided by standard MFO Algorithm into discrete binary values, as shown via eqs. 26 and 27.

$$S\left(xi(t) = \frac{1}{1 + e^{-xi(t)}}\right. \tag{26}$$

Table 5 Pseudo-code of BMF

Input: Number of dimensions, number of search agents (moths), maximum iterations

Output : Global best positions of flames and moths

```
1. for each moth ni (i = 1,……,m) do:
2.
.
.
.
35.    M(i,j) = D * e^bt * cos (2πt) + flame(flame_no,j);
36.      sigma ← random(0,1)
37.                 if sigma < S(M(i,j)) then:
38.                     M(i,j) ← 1
39.                 else:
40.                     M(i,j) ← 0
41.               end
42.      end
43. End
```

Steps 1-35 are same as given in the MFO pseudo-code

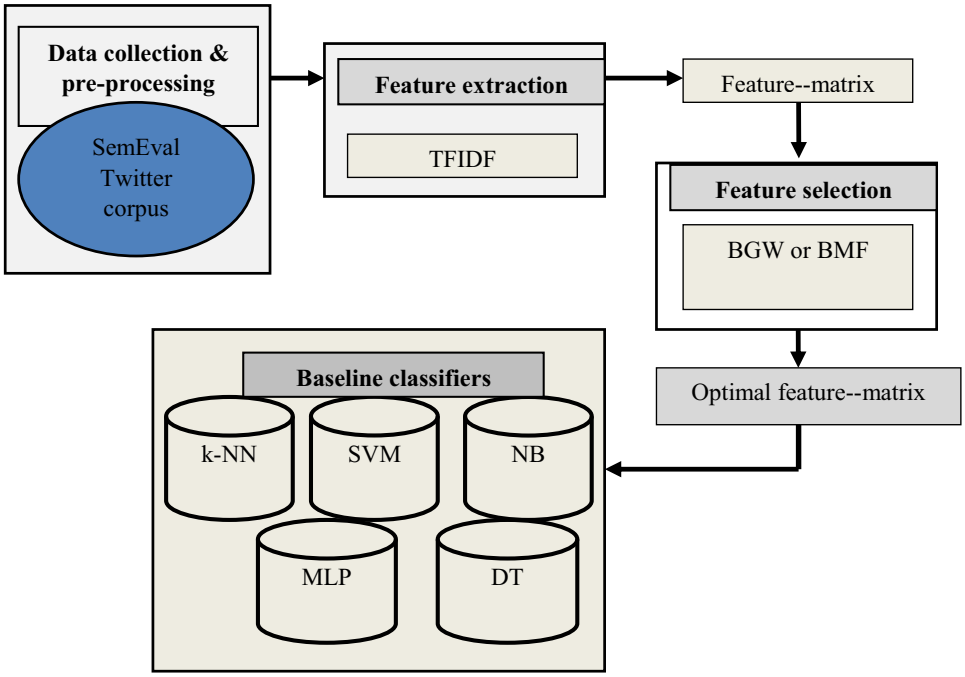


Fig. 7 Systematic workflow for optimized sentiment classification

$$M(i,j) = \begin{cases} 1, & S(M(i,j)) > \sigma \\ 0, & otherwise \end{cases} \text{and } \sigma \sim U(0,1) \tag{27}$$

The constants and parameters used are as follows:

- b: constant defining the shape of the logarithmic spiral
- r: convergence constant, decreases linearly from −1 to −2 over the course of iteration
- t: parameter defining how close should the next position of moth be to flame
- σ: sigma, random number generated from uniform distribution between 0 and 1.

4 Systematic workflow

Sentiment classification refers to the task of predicting the polarity of a social media post by assigning one of the following labels to the post, Y ε {positive, negative, neutral}. Figure 7 illustrates the workflow.

The task begins by collecting data, which are tweets from benchmark datasets, annotated for polarity as positive, negative or neutral. This collected data needs to be in a uniform structured format so that relevant features can be extracted. The pre-processing task includes consolidation, cleaning, transformation and reduction. The relevant features are then extracted using the conventional TFIDF technique to generate the feature matrix. The optimization algorithms are then applied to this feature matrix to generate an optimal subset of features

Table 6 Calculation of TFIDF score for the pre-processed sample tweet

happy	so	see	roger	win	championship
0.184	0.033	0.029	0.169	0.015	0.069

Table 7 Accuracy gain using BGW and BMF in SemEval 2016 dataset

Technique	Non-optimized approach (TFIDF) Accuracy (%)	Optimized approach (TFIDF + BGW) Accuracy (%)	Increase in accuracy (%)	Optimized approach (TFIDF + BMF) Accuracy (%)	Increase in accuracy (%)
NB	29.4	38	8.6	40.3	10.9
DT	54.6	63.9	9.3	64.9	10.3
SVM	65.4	76.5	11.1	74.8	9.4
MLP	59.6	67.9	8.3	70.2	10.6
k-NN	55.3	63.2	7.9	65.9	10.6

which is used to train and test the baseline classifier for predicting the sentiment polarity. Results obtained are then assessed for performance accuracy. The following sub-sections expound the details of each sub-task:

4.1 Datasets

To evaluate the performance of the optimization algorithms, two benchmark Twitter datasets have been used. These are: SemEval 2016 (Task 4, subtask-A) and SemEval 2017 (Task 4, subtask-A). The selected datasets consists of 'tweet id's' which were annotated as positive, negative and neutral. The SemEval 2017 dataset comprises of around 5742 neutral, 2352 positive and 3811 negative tweets, whereas the SemEval 2016 dataset consists of 10,341 neutral, 7059 positive and 3231 negative tweets. Few of the tweets were not available for download, some were removed and few had an altered privacy status that eventually left us with approximately 5000 tweets each for the datasets.

4.2 Pre-processing

Pre-processing is done to clean and transform the data for relevant feature extraction [32]. It involves cleaning the dataset from noise. Noise here basically connotes the language irregularities often present in any micro-blog text. As the noisy and unstructured data affects the quality of the sentiment classification task, the data is converted to structured input format [18]. The pre-processing procedure employed in this study involves the following tasks:

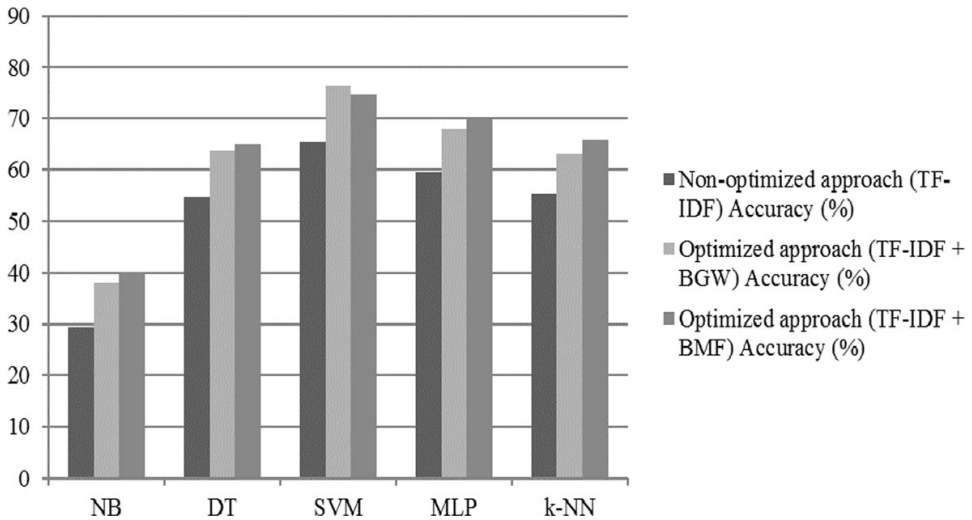


Fig. 8 Accuracy using non-optimized (TFIDF) vs. optimized (BGW and BMF) prediction for SemEval 2016

Table 8 Accuracy gain using BGW and BMF in SemEval 2017 dataset

Technique	Non-optimized approach (TFIDF) Accuracy (%)	Optimized approach (TFIDF + BGW) Accuracy (%)	Increase in accuracy (%)	Optimized approach (TFIDF + BMF) Accuracy (%)	Increase in accuracy (%)
NB	26.9	36	9.1	39.9	13
DT	58.6	69.3	10.7	67.7	9.1
SVM	62.9	74.5	11.6	73.8	10.9
MLP	60.6	69.6	9	70.9	10.3
k-NN	58.3	67	8.7	69.2	10.9

- *Removal* of all the *URL links, non-ASCII characters, non-English characters, numbers, stop words* like 'the, at, as, of, or, to' etc.
- *Transforming any negative mentions* to their original meaningful words by using Internet Slang Dict.[3] For example replacement of "couldn't to could not" etc., expansion of acronyms and slangs etc.
- *Replacing the emoticons to their original textual forms* by using emoticon dictionary.[4]
- *Stemming and tokenizing*. Stemming is done on text in order to preserve the root of the word, for example it reduces helping to its root word i.e. help. Tokenization is defined as process of chopping or splitting any text into "individual words or sequences of words (n-grams)". Tokenization was done using the Tweet-NLP [7].

Consider the following sample tweet:

'Happppppyyy, so so happy, to see Roger win the championship!! #tennis #sport'

After applying pre-processing, the output obtained is as follows:

'happy so see roger win championship'

4.3 Feature extraction

This phase identifies the characteristics of the datasets that are specifically useful in detecting sentiments. The main aim is to find the distinguishing features that can separate the data into positive, negative or neutral classes and produce improved sentiment classification accuracy. The term-frequency-inverse document frequency (TFIDF) [6, 9] is used to generate the feature matrix. This numeric statistic depicts the relevance of a word in the selected corpus. The TFIDF score matrix for the given pre-processed sample tweet is as shown below in Table 6:

4.4 Feature selection

Feature selection is the process of electing a subset of features from the original set of features forming patterns in a given dataset [38]. Feature selection is done to reduce the size of problem for learning algorithms which may improve classification accuracy due to reduction in

[3] https://www.noslang.com/dictionary
[4] http://en.wikipedia.org/wiki/List of emoticons

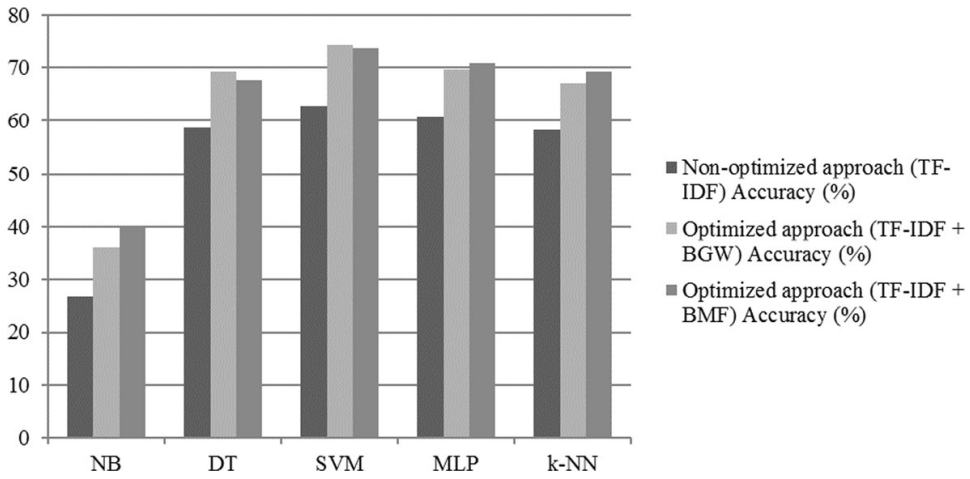


Fig. 9 Accuracy using non-optimized (TFIDF) vs. optimized (BGW and BMF) prediction for SemEval 2017

computation requirement as well as increase the speed of classification task as the size of data to train the classifier is reduced. Feature selection is done using optimization algorithms, BGW or BMF.

4.5 Training and testing of baseline classifiers

In this sub-task, the optimal feature set generated in the previous step is used to train and test the classifier into for three pre-defined sentiment polarity categories. In this work, five baseline classifiers namely, NB, SVM, DT, k-NN and MLP have been modeled. A brief description of these techniques was given in section 3. Python was used for implementation of all the selected algorithms. Python was chosen because of its suitability to intense mathematical programming, huge community support and numerous open source packages available. Various python libraries used were scikit-learn (it has been used to implement various supervised classification algorithms on which the accuracy is determined after feature selection), NumPy (this library has mathematical functions that has support to work with large arrays and matrices. It is optimized to reduce the computation time required to work with large matrices. Its implementation involved large matrices for extracting features with and without TFIDF), SciPy (it is the library

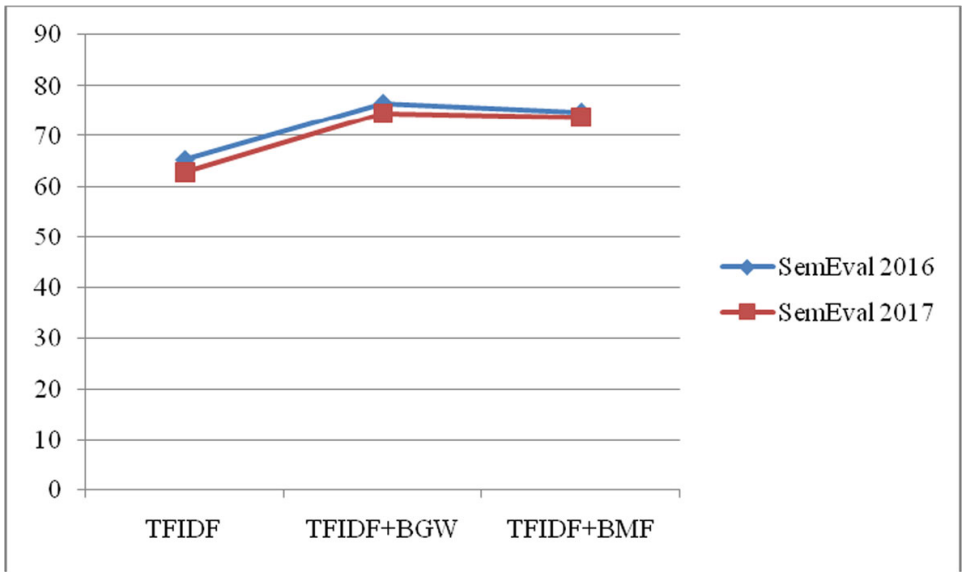


Fig. 10 Maximum performance accuracy achieved by SVM

Table 9 Percentage of features selected using BGW and BMF in SemEval 2016 dataset

Technique	Non-Optimized Approach (TFIDF) #Features	Optimized Approach (TFIDF + BGW) #Features	Features Selected (%) BGW	Optimized Approach (TFIDF + BMF) #Features	Features Selected (%) BMF
NB	2717	2156	79.35	1647	60.61
DT	2717	2111	77.69	1695	62.38
SVM	2717	2375	87.41	1628	59.91
MLP	2717	2332	85.82	1652	60.80
k-NN	2717	2215	81.52	1637	60.25

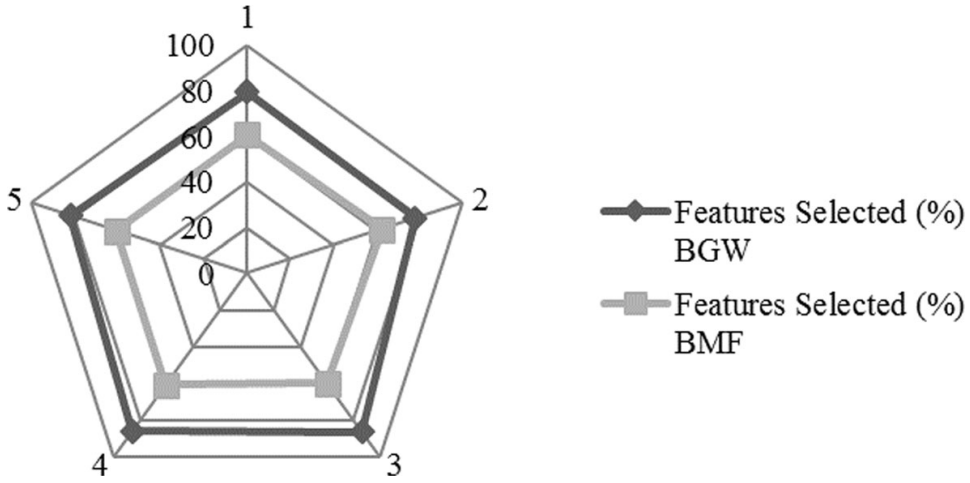


Fig. 11 Features selected using BGW and BMF in SemEval 2016 dataset

which is used for scientific computing, optimization etc.) and NLTK[5] (it is a very comprehensive collection of programs and libraries aimed at statistical and symbolic natural language processing for English language. It has lot of inbuilt functions like stemmers, lemantiser and tokeniser etc.).

5 Results and discussion

This section illustrates the performance achieved by the sentiment classifier using the optimization techniques on SemEval 2016 and 2017 datasets based on accuracy. Ten-fold cross validation method is used.

Table 7 depicts the accuracy achieved by baseline classification techniques without and with optimization for the SemEval 2016 dataset.

The results indicate that the best accuracy with BGW optimization is achieved by SVM on SemEval 2016 dataset, i.e. 76.5%. Amongst all, NB showed the lowest accuracy of around 38% using BGW optimizer. The maximum accuracy gain was obtained by SVM (11.18%) while DT showed an appreciable 9.3% gain in accuracy followed by approximately 8% gain for NB and MLP and k-NN. The average accuracy gain using BGW on SemEval 2016 dataset was of 9.04%.

[5] Natural Language Toolkit: https://www.nltk.org/

Table 10 Percentage of features selected using BGW and BMF in SemEval 2017 dataset

Technique	Non-Optimized Approach (TFIDF) #Features	Optimized Approach (TFIDF + BGW) #Features	Features Selected (%) BGW	Optimized Approach (TFIDF + BMF) #Features	Features Selected (%) BMF
NB	2658	2156	81.1	1411	53.08
DT	2658	1986	74.71	1494	56.20
SVM	2658	2192	82.46	1538	57.86
MLP	2658	1814	68.24	1552	58.38
k-NN	2658	2070	77.87	1447	54.43

The best accuracy with BMF optimisation is also achieved by SVM on SemEval 2016 dataset, i.e. 74.8%. NB again showed the lowest accuracy of around 40.3% using BMF optimizer. However, the maximum accuracy gain was observed for NB (10.9%) while MLP and k-NN showed an equally appreciable 10.6% gain in accuracy followed by approximately 10% gain for DT and SVM. The average accuracy gain using BMF on SemEval 2016 dataset was of 10.36%. The accuracy results are graphically shown in Fig. 8.

Table 8 depicts the accuracy achieved by baseline classification techniques without and with optimization for the SemEval 2017 dataset. The results are consistent to the ones achieved for SemEval 2016. Here too the best accuracy with BGW optimization is achieved by SVM, i.e. 74.5% and NB shows the lowest accuracy of around 36%. The maximum accuracy gain was obtained by SVM (11.6%) while DT showed an appreciable 10.7% gain in accuracy followed by approximately 9% gain for NB and MLP and k-NN. The average accuracy gain using BGW on SemEval 2017 dataset was of 9.82%.

The results indicate that the best accuracy with BMF optimisation is again achieved by SVM on SemEval 2017 dataset, i.e. 73.8%. NB showed the lowest accuracy of around 39.9% using BMF optimizer. Again, the maximum accuracy gain was observed for NB (13%) while SVM and k-NN showed an equally appreciable 10.9% gain in accuracy followed by approximately 10% gain for DT and MLP. The average accuracy gain using BMF on SemEval 2017 dataset was of 10.84%. The accuracy results are graphically shown in Fig. 9.

The best accuracy was achieved by SVM with or without optimization for both datasets, but a considerable accuracy gain was observed using both optimizers. Figure 10 illustrates the maximum performance accuracy was achieved using TFIDF+BWG on SemEval 2016 dataset.

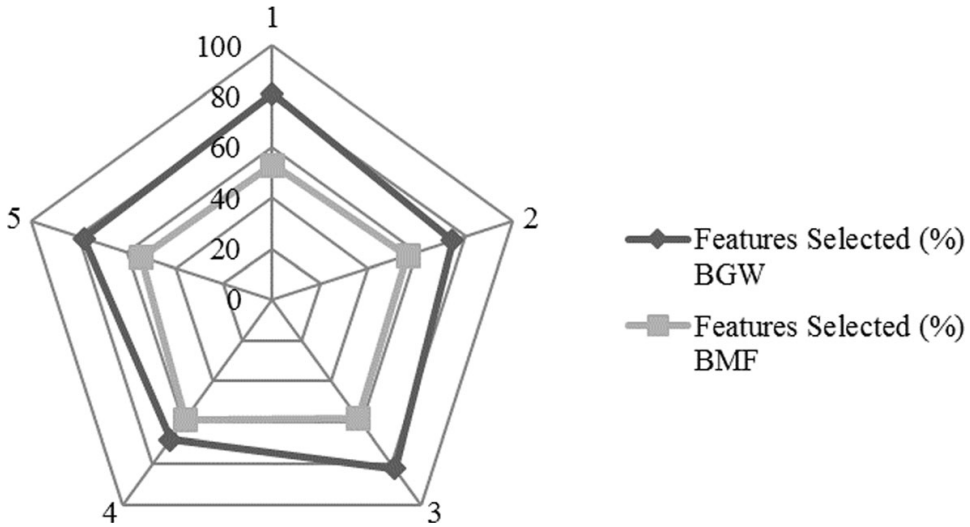


Fig. 12 Features selected using BGW and BMF in SemEval 2017 dataset

Table 11 Result summary

SemEval 2016 Dataset			SemEval 2017 Dataset	
Optimizer	Accuracy gain (%)	Features selected (%)	Accuracy gain (%)	Features selected (%)
BGW	9.04	82.13	9.82	76.876
BMF	10.36	60.79	10.84	58.38

Table 9 displays the number of features selected in SemEval 2016 dataset using the two optimizers. In non –optimised approach all the classification algorithms used the same number of features, which is 2717. After applying BGW for feature selection the minimum number of features selected were 2111 (DT) which is 77.69% selection and maximum were 2375 (SVM) which is 87.41% selection. The analysis shows that on an average 82.13% features were selected. On application of BMF the minimum number of features selected were 1628 (SVM) which is 59.91% selection and the maximum were 1695 (DT) which is 62.38% selection. The results show that on an average 60.79% features were selected, as depicted in Fig. 11.

Table 10 displays the number of features selected in SemEval 2017 dataset using the two optimizers. In non –optimised approach all the classification algorithms used the same number of features, which is 2658. After applying BGW for feature selection the minimum number of features selected were 1814 (MLP) which is 68.24% selection and maximum were 2192 (SVM) which is 82.46% selection. The analysis shows that on an average 76.876% features were selected. Using BMF the minimum number of features selected were 1411 (NB) that is, 59.91% features selected and the maximum were 1552 (MLP) which is 58.38% features selected. The results show that on an average 55.99% features were selected, as depicted in Fig. 12.

From the results, it can be interpreted that optimization algorithms produce more consistent and improved results across datasets when applied for a generic sentiment classification task. The result summary is given in Table 11.

6 Conclusion

Feature selection is significant in predictive analytics for removing the irrelevant and redundant features which are not useful. Moreover, as the size of search space increases exponentially with respect to the number of features of a given data set, an exhaustive search for the optimal or near optimal solution in an impracticable and suffers from stagnation in local optima. This research demonstrates the use of two meta-heuristic swarm-based optimizers, binary grey wolf and binary moth fame for selecting a subset of relevant features used to train and test the learning model which predicts the sentiment in a micro-blogs. The results have been evaluated for various baseline classifiers with and without optimization. The classifier accuracy is initially determined using conventional statistical feature extraction and fixed number of features. The optimizers are then employed to demonstrate the accuracy gain and reduction in features. Empirical analysis shows that the optimization algorithms simplify the feature selection process effectively and obtain higher classification accuracy. The use of optimization algorithms result in around 30% reduction in the number of features selected,

with the corresponding rise in the accuracy by approximately 10%. The study can further be extended to analyze the use of other bio-inspired and swarm-inspired algorithms for improving the sentiment classification accuracy. The use of different filter methods that is other than TFIDF can be explored to give interesting insights to this filter-wrapper arrangement for sentiment classification. Also, most of the work done to analyze the sentiments is on English textual web data, whereas multilingual (mash-up) and multimodal (non-textual: audio, video, image, gif's, emoticons) sentiment analysis make potential future directions.

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SYSTEMATIC LITERATURE REVIEW OF FUZZY LOGIC BASED TEXT SUMMARIZATION

AKSHI KUMAR AND ADITI SHARMA

Abstract. 'Information Overload'is not a new term but with the massive development in technology which enables anytime, anywhere, easy and unlimited access; participation & publishing of information has consequently escalated its impact. Assisting users'informational searches with reduced reading surfing time by extracting and evaluating accurate, authentic & relevant information are the primary concerns in the present milieu. Automatic text summarization is the process of condensing an original document into shorter form to create smaller, compact version from the abundant information that is available, preserving the content & meaning such that it meets the needs of the user. Though many summarization techniques have been proposed but there are no 'silver bullets'to achieve the superlative results as of human generated summaries. Thus, the domain of text summarization is an active and dynamic field of study, practice & research with the continuous need to expound novel techniques for achieving comparable & effectual results. Fuzzy logic has appeared as a powerful theoretical framework for studying human reasoning and its application has been explored within the domain of text summarization in the past few years. This paper is a systematic literature review to gather, analyze, and report the trends, gaps and prospects of using fuzzy logic for automatic text summarization on the basis of the findings in original studies.

1. Introduction

According to worldwidewebsize.com, the indexed Web contains at least 4.5 billion pages (Monday, 20 March, 2017). With the massive proliferation in the velocity, volume and variety of information accessible online and the consequent need to develop viable paradigms which facilitate better techniques to access this information, there has been a strong resurgence of interest in Web Information Retrieval (Web IR) research in recent years. The ultimate challenge of Web IR research is to provide improved systems that retrieve the most relevant information available on the web to better satisfy a users information need [9, 8]. A simple keyword search on the Internet results in hundreds of result in less than a second, some of which are not even relevant to the users query and finding the pertinent information is a difficult and time consuming task.

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*Key words and phrases:*Automatic Text Summarization, Fuzzy Logic, Systematic Literature Review.

Summarization has been identified as an effective Web IR task, which helps users to locate the right information at the right time thus facilitating timely decisions.Human summarization can be biased, context-dependent and may vary with human cognition. Thus, suitable techniques & tools are needed to extort pertinent and imperative sections such that critical information in the form of summary is acquired; providing a machine generated summary free from bias. The following real-world analogy helps us understand the meaning and need of summary: A person wants to decide his/her visit to an exhibition at a Local Art Gallery; the display list suggests the highlights of the exhibition giving an insight to what is the theme of the exhibition, though nothing really can be said about the quality of art-work presented but the visitation decision can surely be made depending on the person's interest to the summarized highlights.

Automatic Text Summarization (ATS) [35, 36] is defined as the process of creating a compact, coherent version of the original document by selecting, filtering, and extracting only relevant information and presenting it in a human-understandable manner. Applications of text summarization tools reportedly range from facilitating document selection & literature searches to generation of customised summaries for question-answering systems. No matter what the intent, type or context of summary generated is, the primary objective is to assist users'informational searches with reduced reading/surfing time and also improve the document indexing efficiency at the same time. Work on Automatic Text Summarization was first reported in late 1950s and there has been a continuous interest in this domain with pertinent literature reporting various studies on proposed paradigms and tools. But there are no 'silver bullets'to achieve the superlative results as of human generated summaries. Thus, the domain of text summarization is an active and dynamic field of study, practice & research with the continuous need to expound novel techniques for achieving comparable & effectual results.

Fuzzy logic has appeared as a powerful theoretical framework for studying human reasoning. It formalizes human reasoning by setting rules in natural language used to explain decisions from human reasoning [15]. It reinforces exibility for reasoning, which makes it possible to take into account inaccuracies and uncertainties. Use of fuzzy logic in WebIR has been amply investigated with valuable findings to ease the process of Information Retrieval, for example fuzzy logic has been used to extract key phrases from news articles [38] and from other web articles. The use of fuzzy logic in text summarization was first testified in 2003 by Witte & Bergler [51].Thus this survey includes all the papers which demonstrate the use of fuzzy logic for automatic text summarization from the first reported study till date. We identified and compared various automatic extractive text summarization techniques which use fuzzy logic on the basis of the results given in the original studies. The objective of this SLR is to gather empirical evidence and interpret results from existing research to proffer concluded information systematically and critically analyzed in order to summarize the existing trends in available research, identify gaps in current search and provide future prospects in the area by means

of answering the established research questions.

The paper is organised as follows: In the next section, the basics pertaining to the process and types of text summarization techniques are explained followed by the brief introduction to fuzzy logic. The section 3 elaborates the review methodology enlisting the Research Questions identified to conduct this study review. Section 4 overviews the literature survey of the selected studies concisely. Finally section 5 provides the results and discussion followed by the conclusion.

2. **Automatic Text Summarization**

Automatic Text Summarization is the process of finding a summary of a document available on the Web by a computer without changing the meaning of the original document for retrieving the useful information like the structure of document [44].Text summarizers have demonstrated their use in various application domains that range from stock market prediction to keyword extraction for search optimization. More recently, automatic Email summary generation using cue words has also been suggested by Carenini et al [13]. This categorization of text summarization techniques is depicted in the figure 1 below [16].

Primary categorization of text summarization techniques is on the basis of the type of summary generated. It can either be of extractive or abstractive type. Generating abstractive summary is cumbersome as it gives summary with sentences different from the original document, though the meaning of information is preserved. On the other hand, Extractive text summarization uses sentences from the document to provide condensed form of the document that is in simple terms, it is the subset of the actual document. Most of the studies on text summarization are on extractive techniques [28]. Other categorizations can be on the basis of the

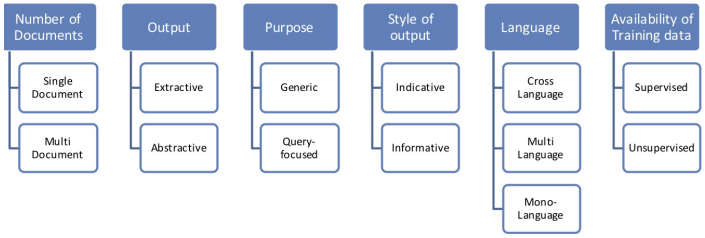


FIGURE 1. Categories of Text Summarization based on different characteristics.

purpose, that is, the summary generated can be either generic, for everyone like summary of a news article, or it can be query-specific/ topic specific, only for a particular user or group of users, generated on the request. Moreover, the document can be a single document or a set of documents and the techniques which are applicable to single document may not necessarily be applicable on multi-documents. Further, on the basis of the style of the output, the summaries can be indicative

or informative. The former tells what the document is about, and the later gives information on the topic of the document [16].

Summarization techniques can also be categorized on the basis of whether the training data is available or not, that is if its available they are referred to as supervised. If training data is not provided the techniques are known as unsupervised learning. Another categorization of summarization is on the basis of language. If the language of the document and the summary is same, it is known as monolingual summary. If the document to be summarized is available in various languages, it is called as multi-lingual. If the language of summary and the document is different, it is referred to as cross-lingual summarization [16].

The following sub-section describes the various summarization methods available across literature followed by an overview of a typical fuzzylogic based ATS.

2.1. **Summarization Methods :** Due to the inherent complexity of generating abstractive summary, extractive summaries have been more frequently generated and used in practical applications [16]. Significant literature studies establish that various types of methods can be used to generate extractive summaries[28]. These methods with their techniques are shown in the Figure 2.We briefly explicate these methods.

- *Statistical Based Methods:* The methods generate summaries using statistical features of the document like sentence position, centrality of the sentence, sentence length, numeric data in sentence, title similarity etc.[8]. These techniques are language independent and do not require much storage or fast processors.
- *Graph Based Methods:* In this method, the words or sentences are represented by nodes of the graph and edges between these node represents the similarity value between these nodes. The sentences to be taken in extractive summary are found by traversing the graph and selecting the sentences which have similarity index above the defined threshold. Some of the recognised graph based methods are Text Rank and LexRank [16].
- *Discourse Based Methods:* These methods require understanding the textual structure and are complex to use as they take into account the connections between sentences and parts in a text. The Inter-paragraph & Intra-paragraph analysis is also done. Three levels of discourse structure may be identified based on cohesion, coherence, and cross-document relations [16].
- *Topic Based Methods:* In this method the summary is generated by firstly identifying the subject or theme of the document. Then this is used to extract the sentences which are related to the subject [16].
- *Machine Learning Based Methods:* These include approaches which learn from the data provided to the machine for summarization. They can either be supervised where the training data is provided with the summaries of the document such that the machine can learn how to summarize the data

or unsupervised where only the documents are provided and the machine learns by analyzing the documents.

- *Optimization techniques:* The techniques use nature inspired or swarm algorithms for finding summaries or features for summaries employing optimization algorithms like particle swarm optimization, artificial bee colony. These techniques are usually used in combination with other techniques [28].

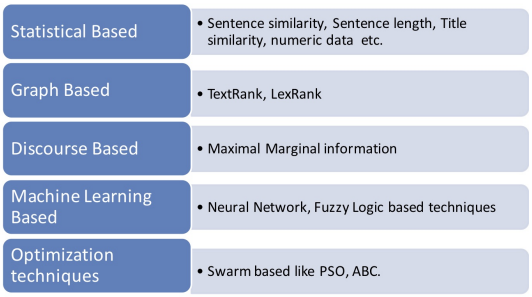


FIGURE 2. Summarization Methods.

A great deal of work has been done in these areas and the recent techniques proposed have mostly been machine learning based, swarm intelligence based or the hybrid of two or more types of summarization techniques.

2.2. **Text Summarization using Fuzzy Logic :** Fuzzy logic model intends to offer linguistic representation for handling uncertainties. Research on fuzzy logic started in 1965 by Zadeh [53] and since the inception it has been widely accepted and used in various application domains owing to the underlying primary notion which replicates a typical human inference process. Fuzzy logic handles uncertainties in the input better than other models, and no another method performs better in computing with words [53] and thus is preferably used for linguistic summarization [12]. A typical fuzzy logic based model for ATS takes as input eight features for each sentence (Title word, Sentence length, Sentence position, Numerical data, Thematic words, Sentence to sentence similarity, Term weight, Proper noun) to calculate its importance. Once the value of these eight features has been extracted, it is passed to a Fuzzy Inference System(FIS). Also, research has substantiated that a summary length is nearly 10% of the actual document length and the resultant summary consists of sentences extracted with the original order maintained. Figure 3 depicts this architecture. Main components of FIS are: *Fuzzification*- In this step the crisp values are converted into fuzzy value using membership function. Various types of membership functions like triangular, trapezoidal, ball, Gaussian distribution function, are available for mapping. For example, if a trapezoidal function is used, then each inputs'membership degree into a fuzzy set usually having three values low, medium or high. The generalized trapezoidal membership function depends

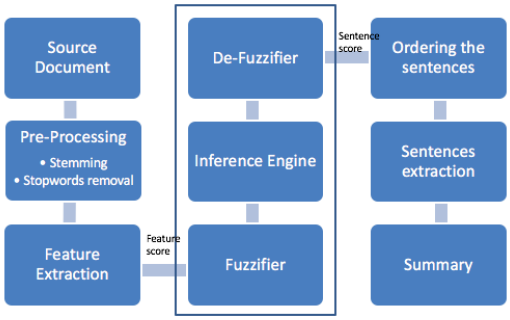


FIGURE 3. Text Summarization using Fuzzy Logic.

upon four parameters p,q,r and s as given by the following equation.

$$f(x,p,q,r,s) = max\left(min\left(\frac{x-p}{q-p}, 1, \frac{s-x}{s-r}\right), 0\right)$$

Where p and s represent the feet of the trapezoid and q and r represent the shoulders [53].

Inference Logic- A knowledge base is created with IF-THEN rules and the inference engine derives the output based on these rules taking the input value generated in the first step. IF-THEN rules are used to balance the weights of key and non-key factors.An IF-THEN rule is stated in following format:

If (title similarity is medium) and (sentence length is medium) and (sentence location is medium) and (numerical data is low or medium or high) and (sentence centrality is low) then (output is key)

Defuzzification : - In this final step, the results generated in second step are mapped to crisp values using membership function, i.e. it converts the linguistic result from inference engine into a numeric value. The output membership function could be taken same trapezoidal or any other depending on the situation. The centroid method is used to find the crisp value.

3. Review Process

Systematic reviews intends to identify, critically evaluate and integrate the findings of all relevant, high-quality primary studies addressing specific research questions pertaining to the research domain [23]. This review was conducted based on the format of Systematic Literature Review (SLR) defined by Ketchenham and Charters [23]. The review process was divided into six phases, namely, Research Question Formulation, Search Strategy Design, Study Selection, Quality Assessment, Data Extraction and Data Synthesis as shown in the following figure 4.

This phase-wise process supported the study to be conducted in a well-structured manner. The goal of the first phase was to ascertain & formulate the research questions within the domain recognized for survey. Then in the next phase, a Search



FIGURE 4. Review process.

strategy was designed & adopted to ascertain how the search would be conducted. This was primarily done to find and locate the relevant research studies addressing one or more research questions. The scope of the study was narrowed in the Study Selection phase by using a selection criterion known as inclusion-exclusion criteria. The worthiness of the papers was then calculated using weighted parameters in the Quality assessment phase. The purpose of the Study Selection & Quality Assessment phase was to ensure the quality and similarity of included studies, and clearly define the boundaries of the review. Post this screening and eligibility decisions on the articles, in the next phase, the data was extracted to answer the research questions to finally critically analyze the research domain.

3.1. **Research Question Formulation :** This SLR was planned to identify, appraise and synthesize research evidence from individual studies using Fuzzy logic for Automatic Text Summarization. For this purpose the following three research questions were formulated:

(1) ***RQ1: What is the need of using Fuzzy Logic in Automatic Text Summarization?*** RQ1 aims to identify the motivation behind the use of fuzzy logic in ATS. The limitations of conventional techniques used for ATS advocating the need to explore novel paradigms.
(2) ***RQ2 : What are the different techniques of fuzzy logic used in ATS till date?*** RQ2 identifies different techniques which have been proposed across literature studies on ATS using fuzzy logic. This question intends to explore the scope and extent of use of fuzzy logic in ATS including hybrid studies.
(3) ***RQ3 : What is the accuracy of different Fuzzy Logic Techniques on Automatic Text Summarization?*** RQ3 targets to quantify the best techniques by comparing them on the basis of performance accuracy and data set.

3.2. **Search Strategy :** A strategy for exhaustive search of all studies that have been conducted on the topic was set up to find as many potentially relevant articles as possible. Specifically in this phase, the research questions were broken into individual concepts to create search terms and databases, additional sources to be searched.
Thus, the following search terms were extracted from the research questions : text summarization using fuzzy logic, text summarization using ML techniques, document summarization and fuzzy logic. These search terms defined the initial search string which was enhanced using alternative search terms, such as synonyms and different spellings. In this SLR, six electronic databases namely IEEE Xplore, ACM Digital Library, Science Direct, Google Scholar, Springer and Wiley Digital Online

were used for selecting the relevant literature that cover the research questions. The search terms identified were then used to discover the conference and journals articles within these six electronic databases. The search indices were limited to the title, abstract, and keywords, except in google scholar where only the title was considered. The reference section of the relevant studies were also examined to extract cross-citations. Some secondary studies (existing literature surveys) were also obtained.

3.3. **Study Selection :** The primary and secondary studies which were identified from the search phase were then subject to a selection criteria known as the inclusionexclusion criteria. The goal was to limit the scope of search and also weed out the non- pertinent work. The following Inclusion-Exclusion criteria was considered for this SLR:

Inclusion Criteria: Articles with information restricted to following terms were only considered

- Empirical studies on text summarization using fuzzy logic.
- Studies proposing fuzzy inference system for document summarization (single or multiple)
- Survey of text summarization using machine learning or optimization techniques.
- Studies combining the fuzzy logic with other summarization technique
- Extensive literature studies of text summarization.
- Empirical studies comparing the fuzzy logic based text summarization system with other text summarization systems.

Exclusion Criteria: The following studies were omitted to narrow the search

- Studies having linguistic summarization using fuzzy logic.
- Studying without text summarization i.e. containing video, audio summarization.
- Studies of text summarization using ML techniques other than Fuzzy logic.
- Studies of manual or human summarization.
- Individual survey studies on either fuzzy logic or text summarization.

3.4. **Quality Assessment :** A systematic review requires investigators to identify studies of sufficient quality to include in the analysis; because, if the raw material is flawed, then the conclusions of systematic reviews cannot be trusted [21]. Hence, in this phase, the selected studies were evaluated for their significance and strength based on various weighted parameters.The following parameters were identified for quality assessment:

- *Novelty:* Is the technique proposed new or just an enhancement/improvement to an existing technique?
- *Technically content:* Is the motivation behind the proposed method clearly indicated? Is the scope and limitation of the proposed models evident and un-ambiguous.

Quality Level	Number of studies	Percentage
$Outstanding(9.5 < score <= 1)$	3	6.8%
$Excellent(8 < score <= 9.5)$	7	15.9%
$Good(7 < score <= 8)$	11	25.0%
$Average(5.5 < score <= 7)$	12	27.27%
$BelowAverage(4 < score <= 5.5)$	6	13.63%
$Poor(score <= 4)$	5	11.36%

TABLE 1. Quality Assessment

- *Result & Analysis:* Is the testing of the model has been on a standard benchmark data set or any random data set, with proper evaluation of performance measures and comparison with existing models?
- *Publication:* Does the study belong to a higher indexed journal or is from a conference? How many citations does the study have? Although we haven't given it much weight-age because a recent study may not have citations.

Thus, each article was given a score out of 10. The score was split as per the following values: 2 for novelty, 1.5 for publisher, 5 for Results & Analysis in which 2 was for data set, 2 for evaluation criteria used and 1 for the comparison with any of the existing technique and the rest 1.5 for technical writing.

3.5. **Data Extraction :** The aim of this phase was to summarize the information extracted from the studies with respect to the research questions. The idea was to map the studies to the research questions, that is, which study addressed which research question. Thus, data which was extracted from all the papers were details about author, year of publication, techniques used, dataset used for evaluation, the performance metrics used, the motivation and pros-cons of the method proposed. This information was then stored in a table to further synthesise it for the review.

3.6. **Data Synthesis :** The aim of the data synthesis phase was to summarize and interpret the information obtained from the data extraction phase. Different visualization techniques (tables, graphs, charts) were also used for interpretation of the resultant data. Thus to summarize, the research process adopted for this SLR generated the following information for critical analysis and review. To enhance the research review and filter the most significant and qualitative work, the search process and study selection was done twice; one with initial & expanded (alternatives and boolean expressions) search string and then re-run using cross-references from the initial studies retrieved. Consequently, 51 studies were initially extracted from the six selected electronic databases. Out of these 60, 52 studies (49 primary and 3 secondary) were considered as these were exclusive and did not contain any redundant information (extended versions or similar versions of work published). Based on the inclusion-exclusion criteria from these 52 only 45 were pertinent to our topic of interest (42 primary papers and 3 secondary papers). The search and selection phase was then repeated on the extracted studies based on cross-referencing. 4 papers were found to be relevant, but only 2 satisfied the inclusion-exclusion criteria.

The secondary studies did not propose any novel technique but reviewed the existing work, so though they were evaluated for final SLR discussions but were not subject to quality assessment. Hence a total of 44 papers (42 primary papers+2 cross-referenced) were subject to the qualitative assessment. All the studies with quality level greater than 4 were considered and we were left only with 39 primary studies out of 44 which eventually shaped the core of this review paper. In the final data extraction and synthesis phases the information retrieved from both primary (39) and secondary studies (3) [total 42] are coalesced to describe the existing findings, their extent and progress in the domain. The final output is a summarized critique to evaluate, extend, or establish implications for practice, identify gaps and inconsistencies, if any and provide directions for future research. The following paper depicts this summary.

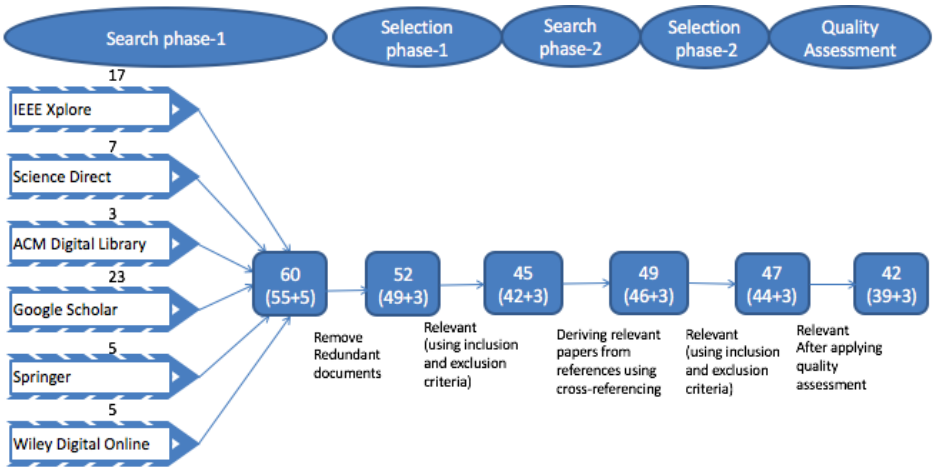


FIGURE 5. Systematic Literature Review Process.

4. **Literature Survey**

In this section, a brief idea about all the selected studies has been given in reverse chronological order in the form of a table. The table 2 contains the state-of-art of this fuzzy logic based ATS where all the primary studies are briefly reviewed based on publication year, author, dataset used, evaluation metrics, motivation of their work and lastly details and scope of the work. Motivation discusses the reason why the authors have proposed this method, and what were the limitation of the existing techniques that lead to this work. Details and scope section contains the basic overview of the technique and its pros and cons of the proposed technique. The Accuracy is given as per the original studies, whether they are evaluated using Precision (P), Recall (R), Fitness (F), ROUGUE -1 , ROUGE-2.

Sr. No.	Year	Author	Technique	Data set	Accuracy	Description
S-1	2017	A. Guran, M. Uysal, Y. Ekinci, C. B. Guran	Fuzzy Analytical Hierarchy Process (FAHP) [17]	Two different Turkish datasets (130 & 20 documents)	Fitness: 0.552	A hierarchy is generated of the features after calculating their weights. Genetic Algorithm is used as heuristic algorithm as it can handle inherent uncertainty and allows the human involvement. They used 15 features which are classified under 5 main features. The features are pair wisely compared to the main feature to calculate the weights.
S-2	2017	Muhammad Azhari, Y. J. Kumar	Adaptive Neuro-Fuzzy Inference System [4]	DUC 2002	Precision: 0.79, Recall: 0.77, Fitness: 0.78	Utilizing the benefits of both fuzzy logic and neural network, as fuzzy logic is knowledge-driven, whereas neural network is data-driven. It Performs better than Fuzzy logic and neural network. Evaluation was not done using ROUGE. LM backpropagation method is used in combination with Least-square Estimate model to estimate the parameters of membership function. It compares the model with Neural Network, Fuzzy Logic and optimized Fuzzy Logic and shows that ANFIS performs better than these models.
S-3	2017	Y. J. Kumar, F. J. Kang, O. S. Goh, A. Khan	Adaptive Neuro-Fuzzy Inference System [26]	DUC 2002	P :- 71.28, R :- 69.82, F :- 70.54	Utilizing the benefits of both fuzzy logic and neural network, as fuzzy logic is knowledge-driven, whereas neural network is data-driven. Performs better than Fuzzy logic and neural network. Evaluation should be done using ROUGE. LM backpropagation method is used in combination with Least-square Estimate model to estimate the parameters of membership function.
S-4	2016	R. Abbasi-ghalehtaki, H. Khotanlou, M.E. Eilpour	Artificial Bee Colony, Cellular Automata, PSO, GA, FL[1]	DUC 2002	ROUGE-1: 0.48685, ROUGE-2 : 0.22910	A hybrid technique which outperform other similar summarization techniques. Uses combination of CA and ABC for finding best diversity sentences. PSO and GA are used for assigning weights to features extracted. FL is used to score the Sentences.
S-5	2016	Jyoti Yadav, Dr. Yogesh Kumar Meena	Fuzzy Logic, Bushy Path, WordNet Synonyms [52]	DUC 2002	ROUGE1 (R): 0.4682, ROUGE1 (P): 0.4341, ROUGE2 (R) : 0.2449, ROUGE2 (P): 0.2255	Summary from three techniques are generated simultaneously. The sentences which come in all three are considered most important and then put into the summary, after that according to the length of the summary defined, the top scorer from all the three summaries are selected. Provides better result than individually used. Should be tested for long data set and for multi-document.
S-6	2016	Mehdi Jafari, A. M. Shabhabi, J. Wang, Y. Qin, X. Tao, M. Gheisari	Fuzzy Logic using both syntactic and semantic parameters [20]	50 random articles	F :- 0.59, P :- 0.6, R :- 0.58	A technique taking into consideration both the syntactic and semantic parameters for achieving high quality summary. Compared with MS word, Copernic, and Huang, the purposed method performed better than others. Not tested on the standard dataset, so cannot generalize the result.
S-7	2016	S. Chintaluri, R. P. Reddy, K. Nara.	Fuzzy Logic with Genetic Algorithm [1]	Documents related to Earth, Nature, Forest and Metadata	P :- 0.67, R :- 0.57, F :- 0.56	Genetic fuzzy systems are fuzzy systems constructed by using genetic algorithms, which mirrors the process of evolution to identify its structure and parameter. The main idea is to maintain a population of candidate solutions to the concrete problem being solved. It is being compared with Basic Fuzzy logic based model and the proposed method performed better than basic model.

Table 2: Summary of the Primary Studies

S-8	2015	R. P. Reddy, K. Nara.	Fuzzy Logic with Genetic Algorithm [43]	Documents related to Earth, Nature, Forest and Meta data	Exact values are not given	Genetic fuzzy systems are fuzzy systems constructed by using genetic algorithms, which mirrors the process of evolution to identify its structure and parameter. The main idea is to maintain a population of candidate solutions to the concrete problem being solved. It is being compared with Basic Fuzzy logic based model and General Statistical Method and the proposed method performed better than both the models.
S-9	2015	Farshad Kiyoumarsi	Fuzzy Logic, Vector approach [24]	DUC 2004 (100 Documents)	ROUGE1: 29.6, ROUGE2: 7.8, ROUGE3: 2.6, ROUGE4: 0.9, ROUGE L: 25.3, ROUGE W-1/2 :- 18.9	Analysed human summaries to understand why they perform better than automatic summaries. The cue features are taken in account also at paragraph and essay level not just on sentence level in fuzzy method. Shown that human summaries are more accurate than automated summaries. Fuzzy performs better than vector method.
S-10	2015	S. A. Babar, Pallavi D. Patil	Fuzzy Logic, Latent Semantic Analysis (LSA) [5]	10 datasets (small)	P :- 90.77572, R :- 44.36375, F :- 67.56974	A hybrid technique of LSA and Fuzzy logic. LSA is used for handling semantic relations of the text. Fuzzy logic with eight features is used for improving the summary. Result of both the techniques is combined to achieve more accurate summary using set operations. To be certain of the accuracy, system should be tested on large dataset.
S-11	2015	Pallavi D. Patil, P. M. Mane	Fuzzy Logic, Latent Semantic Analysis (LSA), Agglomerative K-means [41]	Random Dataset	P :- 89, R :- 43.6, F :- 66.3	Uses LSA and Fuzzy logic for single document summarization. For multi-document, agglomerative K-means algorithm is used. The term frequency of each cluster is assigned as the name of the cluster an given as input to LSA. 12 Overall Fitness measure of the proposed system results in slightly lesser value than LSA summary.
S-12	2014	S. A. Babar, S. A. Thorat	Fuzzy Logic, Latent Semantic Analysis (LSA) [6]	5 datasets with different length of summary	Avg Accuracy : 85.33, Time complexity: 80-94 msec	Hybrid of Fuzzy logic and LSA. Tested on 5 different datasets and compared with gold standard human generated summary. Proposed method performs better than only fuzzy-based summarization.
S-13	2014	R. Abbasighalehtaki, H. Khotanlou, M. Esmaeilpour	Fuzzy Logic, Cellular Learning Automata (CLA), Particle Swarm Optimization (PSO) [2]	DUC 2002 (100 documents)	ROUGE 1(avg-F) :-0.46622, ROUGE 2(avg F) :- 0.2075, ROUGE L (avg F) :- 0.43001	Two techniques were proposed, one using CLA for calculating similarity of sentences and the calculating the score of the sentences on the basis of statistical features. Second is a hybrid technique of CLA, PSO and fuzzy. CLA is used in feature extraction for calculating similarity. PSO is used for assigning weights to the features, and fuzzy is used for calculating the sentence score. Second method performs better than other compared methods except for H2-H1 method.
S-14	2014	Pallavi D. Patil, N. J. Kulkarni	Fuzzy Logic [40]	–	–	Uses Fuzzy method to generate Scores of sentences. Eight types of features are extracted. Triangular membership function is used. Method was not tested on any dataset.
S-15	2014	R.J. Shinde, S.H. R., S.S. J., S.R. Sagare	Fuzzy Logic [45]	Random dataset	compression ratio	Similar to the method proposed in [16]. Shows better result than Ms Word. Method was not tested compared to human generated summaries.

Table 2: Summary of the Primary Studies

S-16	2014	Y. J. Kumar, N. Salim, A. Abuobieda, A. T. Albaham	Generic-Case Based Reasoning (CBR), Fuzzy Logic [27]	DUC 2002	Accuracy:- 84.47%, ROUGE 1: 0.335, ROUGE 2: 0.128, ROUGE S: 0.096, ROUGE SU: 0.1009	Presented two techniques. Generic CBR, for finding cross-document relations from un-annotated text. A fuzzy model for ATS using Generic CBR. Both the methods performed better than other similar techniques when compared.
S-17	2014	S. Santhana Megala, A. Kavitha, A. Marimuthu	Fuzzy Logic, Neural Network [37]	50 Legal Judgement Documents	P :- 0.48629, R:- 0.41269, F :- 0.46823	They used 10 features for feature extraction process to improve the results. Comparison with neural network shows that fuzzy logic behaves better than neural network when the specific vocabulary is used depending upon the input documents.
S-18	2014	G. Padmapriya, K. Duraiswamy	Fuzzy Logic with Deep Learning Algorithm [39]	DUC 2002	P:- 0.37, R :- 0.86, F :- 0.50	Used some of documents to initially train the RBM, to get the adjust the weights of neural network to get only the sentences with minimum value of feature score. Uses the feature matrix defined on the number of sentences. Initially the fuzzy logic is used to categorize each sentence into the category after that RBM is used.
S-19	2014	V. E. Balas, S. Banerjee	Seeded Auto-Text Summarization [7]	–	–	It uses intra-textual ranking mechanism. Reduce the number of words to be considered for evaluation during pre-processing phase using the seed provided by user to reduce the cost and complexity of evaluation.
S-20	2013	A. R. Kulkarni, S. S. Apte	Fuzzy Logic [25]	2 sports news articles	Average fitness=0.71	Uses the same technique as Patil. Not tested on enough dataset to be said as good results.
S-21	2012	A. Ladekar, A. M. , P. Nipane, S. Tomar, Kavitha S.	Fuzzy Logic, Genetic Algorithm, Genetic Programming [32]	–	–	Proposes an optimized membership function and rule based fuzzy system with GA and GP. Fuzzy logic is given unstructured features of the text as input. The Membership function is optimized using GA. Rule sets are optimized using GP. The method is not evaluated on any dataset.
S-22	2012	R. S. Dixit, S. S. Apte	Fuzzy Logic [14]	30 documents from news based URL	Accuracy :- 81%, Position similarity :- 79%	Uses Fuzzy logic for calculating relevance score of each sentence on the basis of the values of eight features. Provides more intelligent summaries as compared to Ms Word and Copernic summarizer. Need to test on standard dataset of multiple domains.
S-23	2011	L. Suanmali, N. Salim, M. S. Binwahlan	Fuzzy Logic, Genetic Algorithm (GA), Semantic Role Labelling (SLR) [49]	DUC 2002 (100 documents)	ROUGE 1(P): 49.95%, ROUGE 1(R): 45.19%, ROUGE 1(F): 47.04%	Proposes a hybrid model for ATS using Fuzzy logic, GA, and SLR. GA is used for optimizing feature selection process and for also calculating the weights of each feature during training time. Fuzzy logic is used to handle uncertainties in the data and balance thee weight between more relevant and less relevant features. SLR captures the semantic data in the text and includes those in the summary. The score of each sentence by both fuzzy logic and SLR is added up to find the final score, on basis of which the sentences are extracted for automated summary.

Table 2: Summary of the Primary Studies

S-24	2010	M. S. Binwahlan, N. Salim, L. Suanmali	Maximal Marginal Importance, Particle Swarm Optimization, Fuzzy Logic [11]	DUC 2002 (100 Documents)	1st: ROUGE1: 44.94%, ROUGE2: 20.07%, ROUGE-L: 41.38%, 2nd: ROUGE1: 45.87%, ROUGE2: 20.42%, ROUGE-L 42.29%	Two models were proposed, one dominating the diversity measure, second not. In first the scores are calculated by three different methods: diversity, swarm diversity, and fuzzy swarm based. Different weights are assigned to all the three components to find the appropriate sentences from all the components. Second also takes three components, but in place of swarm diversity, it uses fuzzy swarm base instead of swarm diversity, and third component is replaced by swarm based. While the first is handling redundancy better than second, but the overall more accurate summary is being generated by the second method.
S-25	2010	S. Alzahrami, N. Salim, C.K. Kent	Fuzzy Swarm based Technique [3]	–	–	Text summarization solves multiple issues, it can handle cross language documents very easily. The redundancy in data can also be found with the use of TS. Improves the plagiarism detection process.
S-26	2010	F. Kyoomarsi, H. Khosravi, E. E., M. Davoudi	Fuzzy Logic, Word Net [29]	DUC 2003 (50 Documents)	ROUGE 1 :- 0.6124	Five features are taken in account including Word-net. Shown that fuzzy model with word net performs better than existing market tools for generating automated summary. Tested the model in two different scenarios.
S-27	2009	F. Kyoomarsi, H. K., E. E., P. K. D., A. Tajoddin	Fuzzy Logic [30]	10 Documents only	Tested by 5 humans. Avg accuracy :58%	They compared vector approach based methods with fuzzy logic. They first calculate the features scores and then used the MATLABs Fuzzy tool to calculate the final score on their basis.
S-28	2009	HH Hunag, HC Yang, YH kuo	Fuzzy logic, Rough Set [19]	DUC 2006	ROUGE-1 :0.40636, ROUGE 2:-0.08245	Proposed a hybrid approach of rough set and fuzzy logic for multi-document summarization. Tested with other 35 techniques. Performance comes in first one third techniques.
S-29	2009	L. Suanmali, N. S., M.S. Binwahlan	Fuzzy Logic [47]	30 documents	F:- 0.47873	To use human reasoning system. They used both single and multi-document summary generation.
S-30	2009	L. Suanmali , N. Salim, M. S. Binwahlan	Fuzzy Logic [48]	DUC 2002 (125 Documents)	F:- 0.47181	Same technique as above. Use triangular membership function. Tested on DUC to make results trustworthy.
S-31	2009	L. Suanmali, N. Salim, M.S. Binwahlan	Fuzzy Logic [46]	DUC 2002 (30 Documents)	F :- 0.47019	9 Features were selected instead of 8 in the above model. Gaussian Membership function has been used. Results do not improve.
S-32	2009	L. Suanmali, N. S., M. S. Binwahlan	Fuzzy Logic, PSO [10]	DUC 2002	ROUGE 1(F):- 0.45524, ROUGE 2(F):- 0.20847	Not every feature is of same importance, so to treat them accordingly, the PSO is used. PSO assigns the weights to each feature and then calculate the score of each token with its feature value and weight and pass it to FIS. Performs better than other models, but still only fuzzy also performed the same.
S-33	2008	L. Suanmali, N. S., M. S. Binwahlan	Fuzzy Logic [50]	DUC 2002 (6 documents)	F :- 0.50433	It was the first basic model of the techniques proposed in their rest five papers. It uses eight features and Bell membership function.

Table 2: Summary of the Primary Studies

S-34	2008	F. Kyoomarsi, H. K., E. E., P. K. D., A. Tajoddin	Fuzzy Logic [31]	Random 10 documents	Tested by Humans. Avg accuracy :77%	They compared vector approach based methods with fuzzy logic. They first calculate the features scores and then used the MATLABs Fuzzy tool to calculate the final score on their basis.
S-35	2006	Arman Kiani-B, M.-R. Akbarzadeh-T., M.H. Moeinzadeh	Fuzzy Logic [22]	3 news articles	Average F:-0.752	A novel technique for summarization to handle uncertainties. They proposed the use of fuzzy logic with triangular membership function on the six features. This was one of the basic method, whose limitations has been covered by the above models.
S-36	2006	Hsun-Hui Hunag, Horng-Chang Yang, Yau-Hwang kuo.	Fuzzy Logic, Rough sets, Semantic patterns [18]	8 articles from JAIR	Average ROUGE-1(F) :- 0.4620391	To remove the redundancy and uncertainty. Semantic of the words are taken to reduce the similar sentences with synonym words. Fuzzy set and rough set improves the process of removing uncertainty in the feature values extracted. The final score of the redundancy removed articles are calculated by FIS.
S-37	2006	Arman Kiani-B, M.-R. Akbarzadeh -T	Fuzzy Logic, Genetic Algorithm, Genetic Programming	3 news articles	F1 :- 0.728, F :- 0.961	GA improves the membership function of the FIS. GP improves the rule set according to the training data. The accuracy of a fuzzy machine depends only on three thing its input, which we are pre-processing to improve better results, rest of the two have been improved in this method. Performs better than other ATS techniques.
S-38	2005	Chang-Shing Lee, ZW Jian, LK Huang	Fuzzy Logic [33]	News articles	compression ratio was used for evaluation	Enhanced the FIS. Instead of the five layer standard fuzzy system, a new seven layer fuzzy system was proposed. Havent been used by any researcher again, not tested for accuracy of the summary.
S-39	2003	R. Witte, S. Bergler	Fuzzy Logic, ERSS [51]	DUC 2003	Not evaluated using standard measures	To resolve the co-reference resolution of the text words by reducing the uncertainty using Fuzzy logic. Used a POS tagger along with fuzzy logic and WordNet to handle the uncertainties in the co-reference text. Results are not that satisfactory and need complex heuristics.

Table 2: Summary of the Primary Studies

5. RESULTS AND DISCUSSION

In this section, we analyse the studies to attain the solutions of the research questions defined during the course of SLR. To comprehend the status of research in this field, we examined year-wise qualitative studies. Although the research in ATS started in late 1950s, but usage of fuzzy logic in ATS was first reported in twenty-first century. Rather more significant work in this field has been accounted for in the last 14 years. The following chart depicts the numbers of papers that have been published annually in this domain and indicate a positive trend and gained momentum due to promising results & increased applications.

Figure 6 represents only the 30 primary studies selected in the SLR process. 3 Secondary studies were also taken into account to apprehend other summarization techniques which used fuzzy logic for improving performance. According to the quality criteria defined in section 3.4, the percentage distribution of studies with respect to quality is shown in Fig.7. Now we discuss the findings and conclusions

of the review, mapping them to respective research questions.

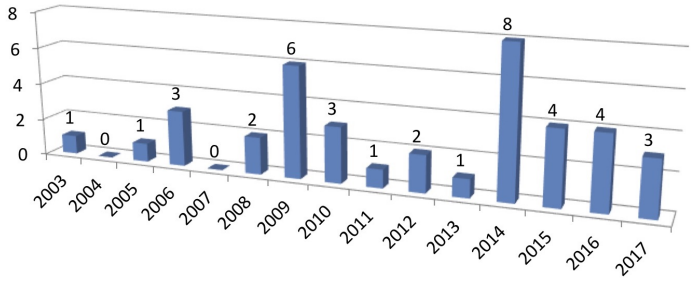


FIGURE 6. Year wise distribution of studies.

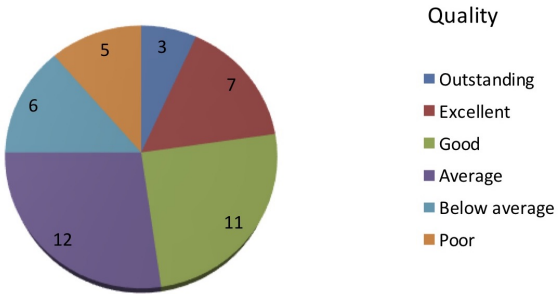


FIGURE 7. Distribution of studies according to the quality.

RQ1 was presented to establish the need of using Fuzzy Logic in Automatic Text Summarization. The basic model and implementation of Fuzzy logic in ATS has been illustrated in Section 2, whereas the section 4 covers the summary of pertinent studies, their motivation and benefits. The advantages of using fuzzy logic in ATS endorsed by the literature can thus be enlisted as:

- It handles the uncertainties in the input.
- It resembles the human reasoning system.
- Not everything in world can be defined in terms of zero and one, so provides more efficient ways to represent the feature values of sentences.
- It provides better way to calculate the sentence score using various types of membership functions.
- It handles the words better than other statistical techniques.

RQ2 intended to uncover the variety of fuzzy logic based techniques used in ATS. The literature survey illustrated in table 2 of Section 4 offers a complete coverage on studies using fuzzy logic for text summarization. Some hybrid techniques using fuzzy logic have been explored and the following table represents the techniques

Sr. No.	Journals	Number of Studies
1.	Swarm and Evolutionary conference (Elsevier)	1
2.	Information Processing and Management (Elsevier)	1
3.	Applied Soft Computing (Elsevier)	1
4.	International Journal of Computer science trends and technology	1
5.	International Journal of innovative research in advance engineering	2
6.	International Journal of Soft Computing and Information Technology	2
7.	International Journal of Computer Engineering	2
8.	IEEE Transactions on systems, MAN & Cybernets	1
9.	International Journal of Computer Science and Technology	1
10.	International Journal of Engineering Research & Applications	1
11.	Irarnian Journal of Fuzzy Systems	1

TABLE 3. Journals Covering the Studies on ATS using Fuzzy Logic

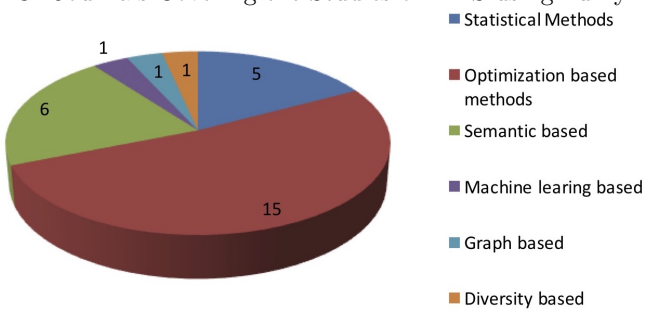


FIGURE 8. Classification of Hybrid models.

which have been used in combination with fuzzy logic for enhancing the results along with the number of studies conducted.

Sr. No.	Technique	Summarization Method	Number of Times
1.	Genetic Algorithm	Optimization based	6
2.	Genetic Programming	Optimization based	3
3.	Particle Swarm Optimization	Optimization based	4
4.	Artificial bee Colony	Optimization based	2
5.	Rough sets	Statistical based	2
6.	Cellular Learning Automata	Statistical based	2
7.	Agglomerative K-means	Statistical based	1
8.	Latent Semantic Analysis	Semantic based	3
9.	WordNet	Semantic based	3
10.	Maximal Marginal Information	Diversity based	1
11.	Case Based Reasoning	Machine Learning based	1
12.	Neural Network	Machine Learning Based	3
13.	Bushy Path	Graph Based	1

TABLE 4. Techniques used along with Fuzzy logic in ATS

Figure 8 shows that around 50% of the studies about hybrid techniques are using optimization based methods, as they enhance the performance of the summarizer as compared to other techniques. Also, most of the studies combine more than 2

techniques to describe a hybrid model. The idea is to generate finest summaries with a fuzzy based model optimized with a nature inspired technique. Moreover, it was observed that the best results were achieved by combining more than two summarization methods (as given in Fig 2) with fuzzy logic [15].

The third research question intended to compare the accuracy of different Fuzzy Logic Techniques used in Text Summarization. Not all the studies have been tested on the benchmarked dataset, rather some have been evalutated on small random data set. The distribution of these techniques according to the dataset used is shown in the following figure (Fig 9).Moreover, the techniques have not been evaluated using the same criteria and the standard evaluation tool for text summarization, ROUGE (Recall-Oriented Understudy for Gisting Evaluation), it contains different matrix for automatically evaluate the worth of a summary generated by comparing it with a human generated summary [34]. Some of the studies have been tested on other basis too, such as testing based on humans understanding, compression ratio, fitness value etc.

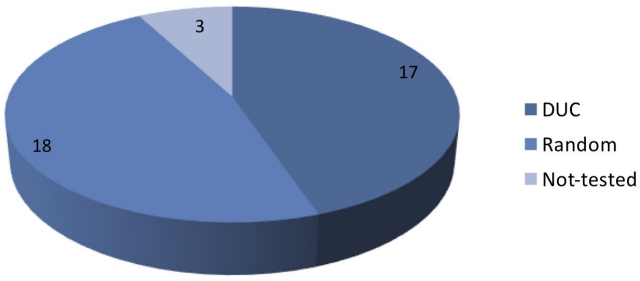


FIGURE 9. Studies distributed according to dataset used.

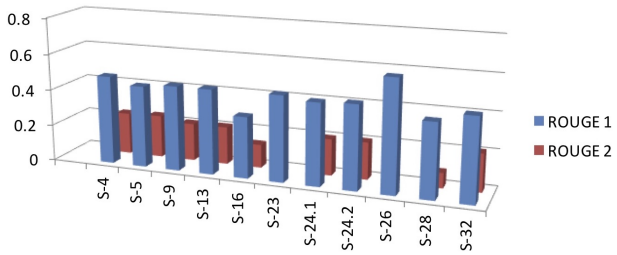


FIGURE 10. Comparison of Fuzzy based techniques.

The DUC (Document Understanding Conference) datasets [16] are the de-facto standard data sets that the NLP community uses for evaluating summarization systems. From the 17 studies on DUC, 13 of them were using DUC 2002. Some of

the studies had used other methods like Precision(P), Recall(R), and Fitness(F) for determining the quality of the summary produced by the model, So the comparision of all the models are not possible, although the comparision between these different matrices provided by Ravindra et al shows that ROUGE values except ROUGE-WLCS are equivalent to F-measure [42], but no other study has still endorsed this result, thats why we are comparing the results of only the studies evaluated using ROUGE score. The techniques proposed have been serially numbered in the summary table given at the beginning of this section. We use these serially numbers in the following bar-graph in fig 10 which represents the comparison of the techniques on the basis of ROUGE-1 & ROUGE-2. Though the techniques were tested on DUC but not all of them used the same set of documents and moreover the number of documents were also different. Thus, the comparison is not a benchmark result but still was adequate to answer the research question.

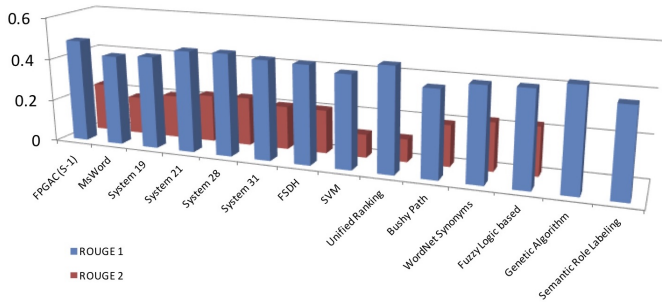


FIGURE 11. Comparison of Fuzzy based model with other text summarizers.

Figure 11 shows the comparison of the best fuzzy based model FPGAC with other models using their ROUGE values on DUC 2002 dataset. The latest method ANFIS is also showing superior results, but as it was evaluated using F-measure, we cannot compare it with the FPGAC. On examining figure 12 precisely, S-26 appears to give superior results with high ROUGE-1 value but it is evaluated using only 5 documents. S-4 on the whole surpasses S-32 and other summarizers as its evaluation was done using benchmark dataset with ROUGE-1 and ROUGE-2 both gives sounder result (except for S-32 for ROUGE-1) as shown in fig 11.

6. **Conclusion**

The evolution of Web from the Web of Documents to the Web of People (Social Web) to the Web of Data (Semantic Web) has multiplied the volume, velocity and variety of information available online. Finding useful, relevant, trending, interesting information from this garbage in-garbage out puddle has been a major focus of current research. Text summarization has emerged as one of the vital technique to handle this problem. The incredible ability of fuzzy inference systems to make logical assessment in an ambiguous and uncertain environment has made is

a trending choice for practical applications such as text summarization, that involve imprecision and uncertainty. In this paper, we have reviewed various studies on fuzzy-logic based text summarization from 2003 to 2017, published in conference proceedings and journals of high repute. The purpose was to evaluate the progress made so far, identify the trends and gaps in studies to ascertain the future scope of research within the domain. The following key-points were observed:

- Fuzzy logic is an attractive choice to achieve optimal summaries due to its resemblance to human reasoning. The goal of text summarization is to achieve superlative results comparable to human generated summaries and mapping the fuzzy logic inference mechanism gives the desired brainpower.
- It is promising to see the paradigm shift from conventional summarization methods to contemporary, novel intelligence based methods. Nearly 50% studies have been done with hybrid models of fuzzy logic with optimization methods, followed by equal number of studies done on hybrids of fuzzy-logic with statistical and semantic techniques respectively. Combinational hybrids using two or more conventional techniques with fuzzy-logic though have been reported but the sphere is an open research problem to achieve enhanced summarization results.
- Though the DUC (Document Understanding Conference) datasets are the de-facto standard data sets used for evaluating summarization systems but less than 50% studies have reportedly used it. This makes comparing the empirical results vague and non-uniform, thus identifying the need of more benchmarked studies and subsequent evaluation.

This literature review identified and compared various automatic extractive text summarization techniques which use fuzzy logic. The limitation of this work is that the techniques obtained across studies are not compared on a common dataset, though most of them have used the ROUGE-N metric for evaluation. The need of more standard studies on benchmark dataset thus exists. Moreover, no studies have been done to classify the use of type-1 and type-2 fuzzy within the domain, calling for an investigation in this direction. Also, during the search and review process we also discovered that so far no studies have been done to explore & see the impact of using fuzzy logic in abstractive text summarization, making it a significant avenue of research.

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Thermal performance of cascaded vapour compression absorption systems

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Abstract

In this paper, we propose four cascaded half effect, single effect, double effect and triple effect Lithium/Bromide vapour absorption–compression refrigeration systems using fifteen ecofriendly refrigerants such as hydrocarbons, HFC and HFO refrigerants and natural refrigerants to produce cooling capacity at -30 °C. The comparison of four cascaded systems were also carried out at -55ºC using HFC refrigerants with R717 refrigerant. It is found that cascaded vapour compression absorption systems significantly improve first and second law performances as compared to simple vapour absorption refrigeration system.

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Keywords: Cascaded Vapour Absorption Compression Refrigeration Systems, Performance Evaluation.

1. Introduction

The use of vapour absorption refrigeration system is a talented way towards utilizing waste heat from industrial processes. LiBr absorption refrigeration system and ammonia–water absorption refrigeration systems are commonly used for low temperature applications. Even though ammonia–water absorption refrigeration system is commonly used for freezing applications with temperatures lower than 0 °C [10-11].

The performance of NH_3H_2O system has low first law efficiency. When the refrigeration temperature is lower than -25 °C, the thermal performance dramatically decreases. We proposed cascaded half effect, single effect, double effect and triple effect Lithium/Bromide vapour absorption–compression refrigeration systems using fifteen ecofriendly refrigerants such as hydrocarbons, HFC and HFO refrigerants and natural refrigerants to produce cooling capacity at -30 °C.

The comparison of four cascaded systems were also carried out at -55ºC using HFC refrigerants with R717 refrigerant. It is found that cascaded vapour compression absorption systems significantly improve first and second law performances as compared to simple vapour absorption refrigeration systems.

2. Literature Review

A number of research work is devoted to thermodynamic, analyses of vapour absorption refrigeration systems

S.B. Riffat N. Shankland [1] described the integration of different types of absorption systems with vapour-compression systems. The performances of the single-effect and double-effect series and the double-effect parallel continuous absorption systems and their integration with vapour-compression systems have been carried out.

Kaushik and Arora [2-3] carried out the energy and energy analysis of single effect and series flow double effect water–lithium bromide absorption system and developed thermal computational model for parametric investigation. Their analysis involves the effect of generator, absorber and evaporator temperatures on the energetic and energetic performance. They concluded that the irreversibility is highest in the absorber in both systems as compared to other systems

Gomri [4] carried out comparative thermodynamic analysis between single effect and double effect absorption refrigeration systems and developed the computer program using thermodynamic properties based on energy balance equations and found that for each condenser and evaporator temperature, there is an optimum generator temperature where change in energy of single effect and double effect absorption refrigeration system is minimum. They also found that the COP of double effect system is approximately twice the COP of single effect system but there is marginal difference between the energetic efficiency of the system.

Yi Chena, et.al. [5] proposed a new absorption–compression refrigeration system to produce cooling energy at -30 °C to -

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40 °C and showed that the coefficient of performance of 0.277, which was approximately 50% higher than that of a conventional two-stage absorption refrigeration system. Fernández–Seara et al. [6] studied a cascade refrigeration system with a CO_2 compression vapour refrigeration system and an NH_3/H_2O absorption system at an evaporation temperature of -45°C. and found its first law efficiency in terms of COP. Garimella and Brown [7] developed a novel cascaded absorption–compression system that coupled a single-effect $LiBr/H_2O$ absorption cycle and a subcritical CO_2 vapor–compression cycle to generate low-temperature refrigerant (-40 °C). Rogdakis and Antonopoulos [8] studied a NH_3/H_2O absorption refrigeration system driven by waste heat and predicted the theoretical COP below 0.40 when the lowest temperature is in the range of -64 °C to -30 °C.

Kilic and Kaynakli [9] carried out first and second law thermodynamic analysis to analyze the performance of a single stage water lithium bromide absorption refrigeration system by varying some working parameters and developed a mathematical model based on energy method and found that the performance of the ARS increases with increasing generator and evaporator temperatures but decreases with increasing condenser and absorber temperatures. Also concluded that the highest energy loss occurs in generator regardless of operating conditions and therefore it is most important component of the system. R.S. Mishra [12] compared three cascade vapour compression systems cascaded with evaporator of LiBr-H_2O vapour absorption refrigeration system cascaded by condenser of vapour compression refrigeration system using ecofriendly refrigerants (i.e. R1234yf, R134a, R-32, R507a, R227ea, R236fa, R245fa , R717) carried out energy and exergy analysis of all three systems and found 122% first law efficiency enhancement using triple effect VARS cascaded with VCRS and 79.45% enhancement in second law efficiency using triple effect VARS cascaded with VCRS. Similarly exergy destruction is 56.60% using triple effect VARS cascaded with VCRS and 25.9% reduction using double effect VARS cascaded with VCRS as compared with single effect. R.S. Mishra [2019] carried out Thermal performances (first law efficiency, exergy destruction ratio & exergetic efficiency) of cascade single effect ammonia-water (NH3-H_20) vapour absorption refrigeration system coupled with vapour compression refrigeration using ecofriendly refrigerants in the low temperature cycle of VCRS system, The combined thermodynamic first law efficiency in terms of coefficient of performance ($COP_{_Overall}$), second law efficiency in terms of exergetic efficiency and exergy destruction ratio working with each of the following refrigerants in the cascaded vapour compression cycle R1234yf, R227ea, R236fa, R245fa, R143a,R134a, R32, R507 operating at (- 223 K) of evaporator temperature with temperature overlapping and evaporator temperature of vapour absorption refrigeration cycle working at 13.5 bar of highest generator pressure and 1.75 bar as lowest evaporator pressure have been presented and it is found thatR141b and R245fa gives better performance.

R.S. Mishra [13] found that the thermodynamic performances in the case of cascaded half effect vapour absorption refrigeration system coupled with vapour compression cycle is improved by 44.6% increment of first law efficiency (i.e. over all COP), 172.87% increment of second law efficiency (i.e. exergetic efficiency) of the half effect vapour absorption refrigeration cascaded with vapour compression cycle using HFC-134a, 42.87% enhancement in first law efficiency (COP) of 142.73% increment of second law efficiency using HFO-1234yf for -50^{o}C of evaporator temperature of VCRS. Similarly 72% reduction in exergy destruction ratio based on exergy of output of the half effect vapour absorption refrigeration cascaded with vapour compression cycle using HFC-134a and 70.4% reduction in exergy destruction ratio using HFO-1234yf ecofriendly refrigerant for -50^{o}C of evaporator temperature of VCRS. The performances of single effect cascaded vapour absorption refrigeration system coupled with vapour compression cycle significantly higher than cascaded half effect vapour absorption refrigeration coupled with vapour compression cycle.

3. Results and Discussions

Performance of four cascaded vapour compression-absorption refrigeration systems have been carried out using following input data.

Table-1(a) shows the thermal performances of simple half effect vapour absorption system with half effect cascade vapour absorption system using R134a,and it was found that Cascaded half effect gives better first law thermodynamic performance (COP) and second law thermodynamic performance in terms of exergetic efficiency than simple half effect vapour absorption refrigeration system. Table-1(b) shows the thermal performances of simple single effect vapour absorption system with single effect cascade vapour absorption system using R134a,and it was found that Cascade single effect gives better first law thermodynamic performance (COP) and second law thermodynamic performance in terms of exergetic efficiency than simple single effect vapour absorption refrigeration system. Table-1(c) shows the thermal performances of simple double effect vapour absorption system with double effect cascade vapour absorption system using R134a,and it was found that Cascade double effect gives better first law thermodynamic performance (COP) and second law thermodynamic performance in terms of exergetic efficiency than simple double effect vapour absorption refrigeration system

Table-1(a): Comparison between performance parameters of simple half effect VARS and half effect VARS with cascading.

Performance Parameters	Simple Half Effect VARS	Half Effect VARS with VCRS cascade using R134a
COP	0.4255	0.7152
EDR	5.419	1.257
Exergetic Efficiency	0.1558	0.4439

Table-1(b): Comparison between performance parameters of simple single effect VARS and single effect VARS with cascading

Performance Parameters	Simple Single Effect VARS	Single Effect VARS with VCRS cascade using R134a
COP	0.7496	1.193
EDR	4.19	1.862
Exergetic Efficiency	0.3628	0.3494

Table-1(c): Comparison between performance parameters of simple double effect VARS and double effect VARS with cascading.

Performance Parameters	Simple Double Effect VARS	Double Effect VARS with VCRS cascade using R134a
COP	1.201	1.781
$EDR_{_Rational}$	2.802	0.4243
Exergetic Efficiency	0.263	0.5757

Table-2: Comparison between performance Parameters of Simple tripple effect VARS and tripple effect VARS with Cascading.

Refrigerants	Simple Tripple Effect VARS	Tripple Effect VARS with VCRS cascade using R134a
COP	1.786	2.432
EDR	2.166	1.05
Exergetic Efficiency	0.3158	0.4879

Table-2 shows the thermal performances of triple effect vapour absorption system. it was found that triple effect gives better first law thermodynamic performance (COP) and second law thermodynamic performance in terms of exergetic efficiency than double effect and single effect & half effect vapour absorption refrigeration systems. Table-3(a) shows the thermal performances of simple half effect vapour absorption system with half effect cascade vapour absorption system using following eco-friendly refrigerants ,and it was found that cascade half effect gives better first law thermodynamic performance (COP) and second law thermodynamic performance in terms of exergetic efficiency than simple half effect vapour absorption refrigeration system the thermodynamic performances (i.e. coefficient of performance (COP) and exergetic efficiency (second law efficiency) using R245fa gives better thermodynamic performances as compared to R134a and R236fa used in cascade vapour compression-absorption refrigeration systems.

The thermodynamic performance performances using R227ea is found to be lowest in vapour -compression-absorption LiBr refrigeration system. Table-3(b) shows the thermal performances of simple single effect vapour absorption system with single effect cascade vapour absorption system using following eco-friendly refrigerants ,and it was found that cascade single effect gives better first law thermodynamic exergetic efficiency of cascaded triple effect vapour absorption-vapour compression refrigeration system is decreasing along with increasing exergy destruction ratio. Similarly the first law efficiency in terms of coefficient of performance (COP_VARS) is decreasing and second law efficiency in terms of exergetic efficiency of the triple effect performance (COP) and second law thermodynamic performance in terms of exergetic efficiency than simple single effect vapour absorption refrigeration system. The thermodynamic performances (i.e. coefficient of performance (COP) and exergetic efficiency (second law efficiency) using R245fa gives better thermodynamic performances as compared to R134a and R236fa used in single effect cascade vapour compression-absorption refrigeration systems. The thermodynamic performance performances using R227ea is found to be lowest in single effect vapour -compression-absorption LiBr refrigeration system. Table-3(c) shows the thermal performances of simple double effect vapour absorption system with double effect cascade vapour absorption system using following eco-friendly refrigerants ,and it was found that cascade double effect gives better first law thermodynamic performance (COP) and second law thermodynamic performance in terms of exergetic efficiency than simple double effect vapour absorption refrigeration system. The thermodynamic performances (i.e. coefficient of performance (COP) and exergetic efficiency (second law efficiency) using R245fa gives better thermodynamic performances as compared to R134a and R236fa used in double effect cascade vapour compression-absorption refrigeration systems. The thermodynamic performance performances using R227ea is found to be lowest in double effect vapour compression-absorption LiBr refrigeration system. Table-3(d) to Table-3(g) show the thermal performances of simple triple effect vapour absorption system with triple effect cascade vapour absorption system using twenty eco-friendly refrigerants ,and it was found that cascade triple effect gives better first law thermodynamic performance (COP) and second law thermodynamic performance in terms of exergetic efficiency than simple triple effect vapour absorption refrigeration system. The thermodynamic performances (i.e. coefficient of performance (COP) and exergetic efficiency (second law efficiency) using R245fa gives better thermodynamic performances as compared to R134a and R236fa used in double effect cascade vapour compression-absorption refrigeration systems. The thermodynamic performance performances using R407c is found to be lowest in triple effect vapour -compression-absorption LiBr refrigeration system. Table-4 shows the effect of condenser/absorber/ temperatures on thermal performances of cascaded vapour compression – triple effect vapour absorption refrigeration system using R134a eco-friendly refrigerants and simple triple effect LiBr vapour absorption refrigeration system and it is found that as condenser/absorber/ temperatures of triple effect vapour absorption is increasing, the first law efficiency in terms of coefficient of performance (COP) is decreasing and second law efficiency in terms of vapour absorption refrigeration system is decreasing along with increasing exergy destruction ratio of triple effect VARS as increasing generator temperature of vapour compression – triple effect vapour absorption refrigeration systemTable-5 shows the effect of generator temperature on thermal performances of cascaded vapour compression – triple effect

vapour absorption refrigeration system using R134a eco-friendly refrigerants and simple triple effect LiBr vapour absorption refrigeration system and it is found that as generator temperature of triple effect vapour absorption is increasing, the first law efficiency in terms of coefficient of performance (COP) is increasing and second law efficiency in terms of exergetic efficiency of cascaded triple effect vapour absorption-vapour compression refrigeration system is decreasing along with increasing exergy destruction ratio. Similarly the first law efficiency in terms of coefficient of performance (COP_VARS) is increasing and second law efficiency in terms of exergetic efficiency of the triple effect vapour absorption refrigeration system is increasing along with increasing exergy destruction ratio of triple effect vapour compression triple effect vapour absorption refrigeration system as increasing generator temperature of vapour compression triple effect vapour absorption refrigeration system. Table-6 shows the effect of evaporator temperature on thermal performances of cascaded vapour compression – triple effect vapour absorption refrigeration system using R134a eco-friendly refrigerants and simple triple effect LiBr vapour absorption refrigeration system and it is found that as evaporator temperature of triple effect vapour absorption is increasing, the first law efficiency in terms of coefficient of performance (COP) and second law efficiency in terms of exergetic efficiency of cascaded triple effect vapour absorption-vapour compression refrigeration system are increasing with increasing exergy destruction ratio . Similarly the first law efficiency in terms of coefficient of performance (COP_VARS) and second law efficiency in terms of exergetic efficiency of the triple effect vapour absorption refrigeration system are increasing with decreasing exergy destruction ratio of triple effect VARS as increasing evaporator temperature of vapour compression triple effect vapour absorption refrigeration system. The optimum exergetic efficiency of triple effect vapour absorption refrigeration system is to be found as 35.4% at 3^{o}C evaporator temperature while optimum exergetic efficiency of cascaded triple effect vapour absorption-compression refrigeration system is to be found as 35.4% at 4^{o}C evaporator temperature while the first law efficiency in terms of coefficient of performance (COP) cascaded system is found at 5^{0} evaporator temperature. Table-7 shows the variation of effectiveness of heat exchanger with first law efficiency, second law efficiency and exergy destruction ratio of triple effect vapour absorption refrigeration system and cascaded vapour compression - triple effect absorption refrigeration system, and it is found that first law efficiency in terms of coefficient of performance (COP) and second law efficiency in terms of exergetic efficiency of vapour absorption refrigeration system are increasing with increasing effectiveness of heat exchanger and exergy destruction ratio of vapour absorption refrigeration system is decreasing with increasing effectiveness of heat exchanger. Similarly that first law efficiency in terms of coefficient of performance (COP) and second law efficiency in terms of exergetic efficiency of cascaded-vapour compression triple stage vapour absorption refrigeration system are increasing with increasing effectiveness of heat exchanger and exergy destruction ratio of cascaded-vapour compression triple stage vapour absorption refrigeration system is decreasing with increasing effectiveness of heat exchanger. Table-8 shows the variation of temperature overlapping (Approach) with first law efficiency, second law efficiency and exergy destruction ratio of triple effect vapour absorption refrigeration system and cascaded vapour compression triple effect absorption refrigeration system, and it is found that first law efficiency in terms of coefficient of performance (COP) and second law efficiency in terms of exergetic efficiency of vapour absorption refrigeration system are decreasing with increasing temperature overlapping (Approach) and exergy destruction ratio of vapour absorption refrigeration system is increasing with increasing temperature overlapping (Approach).

Table-3(a): Comparison between thermal performances various eco-friendly refrigerants in half effect LiBr cascade vapour absorption refrigeration system.

Performance parameters	Simple Half Effect VARS	Half Effect VARS with VCRS cascade using R134a	Half Effect VARS with VCRS cascade using R1234ze	Half Effect VARS with VCRS cascade using R227ea	Half Effect VARS with VCRS cascade using R236fa	Half Effect VARS with VCRS cascade using R245fa
COP	0.4255	0.7152	0.7150	0.7133	0.7173	0.7175
EDR	5.419	1.257	1.291	1.306	1.274	1.237
Exergetic Efficiency	0.1558	0.4439	0.4366	0.4336	0.4398	0.4407

Table-3(b): Comparison between thermal performances various eco-friendly refrigerants in Single effect LiBr cascade vapour absorption refrigeration system.

Performance parameters	Simple Single Effect VARS	Single Effect VARS with VCRS cascade using R134a	Single Effect VARS with VCRS cascade using R1234ze	Single Effect VARS with VCRS cascade using R227ea	Single Effect VARS with VCRS cascade using R236fa	Single Effect VARS with VCRS cascade using R245fa
COP	0.7496	1.193	1.193	1.18	1.189	1.198
EDR	4.19	1.862	1.865	1.972	1.896	1.824
Exergetic Efficiency	0.3628	0.3494	0.3490	0.3378	0.3454	0.3541

Table-3(c): Comparison between thermal performances various eco-friendly refrigerants in Double effect LiBr cascaded vapour absorption refrigeration system.

Performance parameters	Simple Double Effect VARS	Double Effect VARS with VCRS cascade using R134a	Double Effect VARS with VCRS cascade using R1234ze	Double Effect VARS with VCRS cascade using R236fa	Double Effect VARS with VCRS cascade using R245fa
COP	1.201	1.781	1.780	1.773	1.79
$EDR_{_Rational}$	2.802	0.4243	0.4248	0.4294	0.1182
Exergetic Efficiency	0.263	0.5757	0.5752	0.5706	0.5818

Table-3(d): Comparison between thermal performances various eco-friendly refrigerants in triple effect LiBr cascaded vapour absorption refrigeration system

Performance parameters	Simple Tripple Effect VARS	Tripple Effect VARS with VCRS cascade using R134a	Tripple Effect VARS with VCRS cascade using R1234ze	Tripple Effect VARS with VCRS cascade using R245fa	Tripple Effect VARS with VCRS cascade using R236fa	Tripple Effect VARS with VCRS cascade using R227ea
COP	1.786	2.432	2.431	2.447	2.419	2.391
EDR	2.166	1.05	1.052	1.025	1.071	1.122
Exergetic Efficiency	0.3158	0.4879	0.4874	0.4939	0.4827	0.4718

Table-3(e): Comparison between thermal performances various eco-friendly refrigerants in triple effect LiBr cascade vapour absorption refrigeration system.

Performance parameters	R404a	R410a	R407c	R290	R600a	R600	R507a
COP	2.384	2.425	2.291	2.428	2.431	2.445	2.401
EDR	1.135	1.061	1.315	1.056	1.051	1.027	1.105
Exergetic Efficiency	0.4684	0.4851	0.4320	0.4863	0.4875	0.4933	0.4751

Table-3(f): Comparison between thermal performances various eco-friendly refrigerants in triple effect LiBr cascade vapour absorption refrigeration system.

Performance parameters	R123	R143a	R141b	R744	R717	R125	R1234yf
COP	2.455	2.406	2.469	2.299	2.429	2.381	2.420
EDR	1.01	1.096	0.9864	1.297	1.055	1.141	1.055
Exergetic Efficiency	0.4975	0.4773	0.4034	0.4353	0.4856	0.4670	0.4870

Table-3(g): Comparison between thermal performances various eco-friendly refrigerants in triple effect LiBr cascade vapour absorption refrigeration system.

Performance parameters	R134a	R1234ze	R245fa	R236fa	R227ea	R152a	R32
COP	2.432	2.431	2.447	2.419	2.391	2.446	2.418
EDR	1.05	1.052	1.025	1.071	1.122	1.026	1.073
Exergetic Efficiency	0.4879	0.4874	0.4939	0.4827	0.4718	0.4936	0.4823

Table-4: Effect of condenser/Absorber on thermal performances using R134a eco-friendly refrigerants in triple effect LiBr cascade vapour absorption refrigeration system.

Effect of condenser/Absorber Temperature	$COP_{_VARS}$	$EDR_{_VARS}$	Exergetic Efficiency	$COP_{_Cascade}$	$EDR_{Cascade}$	Exergetic $Efficiency_{_Cascade}$	$COP_{_VCRS}$
30	1.786	2.160	0.3158	1.998	1.044	0.4892	2.402
35	1.479	2.825	0.2614	1.758	1.212	0.4521	2.402

Table-5: Effect of generator temperature on thermal performances using R134a eco-friendly refrigerants in triple effect LiBr cascaded vapour absorption refrigeration system.

Effect of Generator Temperature	$COP_{_VARS}$	$EDR_{_VARS}$	Exergetic Efficiency	$COP_{_Cascade}$	$EDR_{Cascade}$	Exergetic efficiency_ Cascade	COP VCRS
170	1.769	2.058	0.3270	1.986	1.017	0.4958	2.402
175	1.780	2.110	0.3215	1.993	1.030	0.4926	2.402
180	1.786	2.166	0.3158	1.998	1.044	0.4892	2.402
185	1.790	2.225	0.3101	2.011	1.059	0.4856	2.402
190	1.792	2.286	0.3043	2.003	1.075	0.4820	2.402
195	1.793	2.349	0.2986	2.003	1.091	0.4783	2.402
200	1.792	2.413	0.293	2.003	1.107	0.4746	2.402

Table-6: Effect of evaporator temperature on thermal performances using R134a eco-friendly refrigerants in triple effect LiBr cascaded vapour absorption refrigeration system.

Effect of evaporator Temperature	COP_{VARS}	EDR_{VARS}	Exergetic Efficiency	$COP_{Cascade}$	$EDR_{Cascade}$	Exergetic Efficiency_Cascade	COP VCRS Decreasing
0	1.233	2.081	0.3299	1.636	1.128	0.470	2.916
1	1.348	1.898	0.3451	1.736	1.066	0.4841	2.844
2	1.442	1.838	0.3524	1.810	1.032	0.4921	2.774
3	1.520	1.825	0.3540	1.865	1.015	0.4962	2.706
4	1.586	1.845	0.3515	1.908	1.01	0.4976	2.641
5	1.644	1.892	0.3458	1.989	1.012	0.4971	2.579
6	1.696	1.962	0.3376	1.964	1.019	0.4953	2.518
7	1.743	2.053	0.3275	1.983	1.030	0.4926	2.459
8	1.786	2.166	0.3158	1.998	1.044	0.4892	2.402
9	1.826	2.302	0.3028	2.010	1.061	0.4852	2.347
10	1.864	2.464	0.2887	2.019	1.08	0.4808	2.294
15	2.028	3.86	0.2058	2.037	1.197	0.4553	2.050

Table-7: Effect of Heat Exchanger Effectiveness on thermal performances using R134a eco-friendly refrigerants in triple effect LiBr cascaded vapour absorption refrigeration system.

Effect of Heat Exchanger Effectiveness	COP_{VARS}	EDR_{VARS}	Exergetic Efficiency	$COP_{Cascade}$	$EDR_{Cascade}$	Exergetic $Efficiency_{Cascade}$	COP_{VCRS}
0.40	1.719	2.291	0.3039	1.948	1.076	0.4817	2.402
0.45	1.752	2.228	0.3097	1.973	1.060	0.4854	2.402
0.50	1.786	2.166	0.3158	1.998	1.044	0.4892	2.402
0.55	1.822	2.104	0.3222	2.025	1.028	0.4930	2.402
0.60	1.86	2.041	0.3288	2.051	1.012	0.4969	2.402
0.65	1.818	1.979	0.3356	2.079	0.9966	0.5008	2.402

Table-8: Effect of temperature overlapping (Approach) on thermal performances using R134a eco-friendly refrigerant in triple effect LiBr cascaded vapour absorption refrigeration system.

Approach	COP_{VARS}	EDR_{VARS}	Exergetic Efficiency	$COP_{Cascade}$ Decreasing	$EDR_{Cascade}$ increasing	Exergetic $Efficiency_{Cascade}$ Decreasing	COP VCRS Decreasing
0	1.786	2.166	0.3158	1.998	1.044	0.4892	2.402
2.5	1.786	2.166	0.3158	1.957	1.132	0.4691	2.268
5.0	1.786	2.166	0.3158	1.916	1.222	0.450	2.144
7.5	1.786	2.166	0.3158	1.876	1.317	0.4317	2.028
10	1.786	2.166	0.3158	1.837	1.815	0.4141	1.920
12.5	1.786	2.166	0.3158	1.799	1.518	0.3972	1.819
15	1.786	2.166	0.3158	1.762	1.625	0.3810	1.724

4. Conclusion

The following conclusions were drawn from present investigations.

(i) Triple effect gives better first law thermodynamic performance (COP) and second law thermodynamic performance in terms of exergetic efficiency than double effect and single effect & half effect vapour absorption refrigeration systems.

(ii) Cascaded half effect gives better first law thermodynamic performance (COP) and second law thermodynamic performance in terms of exergetic efficiency than simple half effect vapour absorption refrigeration system.

(iii) Cascaded single effect gives better first law thermodynamic performance (COP) and second law thermodynamic performance in terms of exergetic efficiency than simple single effect vapour absorption refrigeration system. the thermodynamic performances (i.e. coefficient of performance (COP) and exergetic efficiency (second law efficiency) using R245fa gives better thermodynamic performances as compared to R134a and R236fa used in single effect cascade vapour compression-absorption refrigeration systems.

(iv) The thermodynamic performance performances using R227ea is found to be lowest in single effect vapour - compression-absorption LiBr refrigeration system.

(v) Cascaded half effect gives better first law thermodynamic performance (COP) and second law thermodynamic performance in terms of exergetic efficiency than simple half effect vapour absorption refrigeration system.

(vi) Cascade single effect gives better first law thermodynamic performance (COP) and second law

thermodynamic performance in terms of exergetic efficiency than simple single effect vapour absorption refrigeration system.

(vii) Cascade double effect gives better first law thermodynamic performance (COP) and second law thermodynamic performance in terms of exergetic efficiency than simple double effect vapour absorption refrigeration system.

(viii) Cascade triple effect gives better first law thermodynamic performance (COP) and second law thermodynamic performance in terms of exergetic efficiency than simple triple effect vapour absorption refrigeration system.

(ix) The first law efficiency in terms of coefficient of performance (COP_VARS) is increasing and second law efficiency in terms of exergetic efficiency of the triple effect vapour absorption refrigeration system is increasing along with increasing exergy destruction ratio of triple effect vapour compression – triple effect vapour absorption refrigeration system as increasing generator temperature of vapour compression – triple effect vapour absorption refrigeration.

(x) The optimum exergetic efficiency of triple effect vapour absorption refrigeration system is to be found as 35.4% at 3^{o}C evaporator temperature while optimum exergetic efficiency of cascaded triple effect vapour absorption-compression refrigeration system is to be found as 35.4% at 4^{0}C evaporator temperature while the first law efficiency in terms of coefficient of performance (COP) cascaded system is found at 5^{o}C evaporator temperature.

(xi) The first law efficiency in terms of coefficient of performance (COP) and second law efficiency in terms of exergetic efficiency of vapour absorption refrigeration system are increasing with increasing effectiveness of heat exchanger and exergy destruction ratio of vapour absorption refrigeration system is decreasing with increasing effectiveness of heat exchanger.

(xii) The first law efficiency in terms of coefficient of performance (COP) and second law efficiency in terms of exergetic efficiency of cascaded-vapour compression triple stage vapour absorption refrigeration system are increasing with increasing effectiveness of heat exchanger and exergy destruction ratio of cascaded-vapour compression triple stage vapour absorption refrigeration system is decreasing with increasing effectiveness of heat exchanger.

(xiii) The first law efficiency in terms of coefficient of performance (COP) and second law efficiency in terms of exergetic efficiency of cascaded vapour compression-tripple effect absorption refrigeration system are decreasing with increasing temperature overlapping (Approach) and exergy destruction ratio of cascaded vapour absorption-compression refrigeration system is increasing with increasing temperature overlapping.

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ORIGINAL RESEARCH

Understanding Financial Inclusion in India: A Theoretical Framework Building Through SAP–LAP and Efficient IRP

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Abstract *The purpose of this paper is to analyse the current financial inclusion situation in India, identify the gaps and suggest some way forward to bridge these gaps. In this study, situation-actor-process (SAP) learning-action-performance (LAP) model is applied to present the comprehensive view on financial inclusion in India. Further, the interrelation between the various elements of SAP–LAP is established through efficient interpretive ranking process. The SAP–LAP model helps to better understand the current situation of financial inclusion and helps the 'actors' to initiate appropriate actions based on the 'learning' of the study. The study highlights the area where stakeholders need to focus for better inclusion of people under banking system. The paper is first of its kind which provides a systematic framework to study the financial inclusion in India using SAP–LAP framework.*

Keywords Efficient interpretive ranking process (IRP) · Financial inclusion · SAP–LAP framework

Introduction

In past few decades, poverty and income inequality have become a pertinent issue in developing nations (Mateut et al. 2006; Ravallion 2013; Alvaredo and Gasparini 2015). The role of financial inclusion has emerged significant in addressing the issue of poverty (Beck et al. 2007a; Chibba 2009; Demirguc-kunt et al. 2017). Initially, financial inclusion was perceived as inability or difficulty in accessing financial products and services (Leyshon and Thrift 1996; Sinclair 2001). Later, usage was emphasized with the access (Demirgüç-Kunt et al. 2008). Many studies corroborate financial inclusion with the individual as well as business growth (Chauvet and Jacolin 2017; Koomson and Ibrahim 2017). Notably, financial development leads to economic stability (Sahay et al. 2015; Demirguc-kunt et al. 2017; Kim et al. 2018). The household's access to finance has multifold implications like diversifying the loan portfolio of financial institutions, inculcating savings habits among poor customer and lowering the non-performing assets (NPAs) (Morgan and Pontines 2014). Therefore, the policymakers around the world are keen in developing strategies for financial inclusion.

While India has a long history of financial sector development, Reserve Bank of India (RBI) and the Government of India (GOI) intervened through various initiatives and programmes like bank nationalization, establishment of Regional Rural Banks (RRB), adoption of Service Area Approach (SSA), mandated target for Priority Sector Lending (PSL), relaxed branch licensing policy, etc. Many committees were also constituted to assess policy gaps and evolve initiatives with time (Rangarajan Committee 2008; Rajan 2015; Mohanty Committee 2015). The Economic Survey of India report 2016–2017 emphasized last-mile coverage is essential for financial inclusion (ESI 2016). Recently, the government introduced Pradhan Mantri Jan Dhan Yojana (PMJDY) a comprehensive financial inclusion programme to extend banking services at the doorstep of every household (PMJDY 2014). Besides this, there are a number of steps taken like payment and small bank, Jan Dhan-Aadhaar-Mobile (JAM) and Mudra loan scheme.

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Therefore, in the present scenario of financial inclusion drive, it is indispensable that a systematic framework is developed to investigate different facets of financial inclusion. Though the past studies are vast on financial inclusion, the literature seems limited in providing a theoretical model in general for financial inclusion in Indian context. Thus, this paper builds a conceptual model based on an analytical and interpretive process for strategic decision making. In this paper, we adopt the situation-actor-process–learning-action-performance (SAP–LAP) theoretical model of inquiry (Sushil 2000). 'Situation' presents the current scenario of the case. 'Actors' are the key contributors of the situation which function through various 'processes'. Based on the SAP model, the nexus of 'learning', 'actions' and 'performance' is studied. Further, we integrate expert's judgment to interpret the relationship among various elements of SAP–LAP through improved and modified interpretive ranking process (IRP) (Sushil 2017a). Thus, this study aims at the following two objectives:

- To build a broader theoretical framework of financial inclusion in India.
- To analyse the interactions among elements of SAP–LAP model and rank dominance of various actors and actions to improve the situation and better decision making by the stakeholders.

The rest of this paper is organized in three sections. (i) Based on review of literature, we first discuss SAP–LAP framework for theory building and later we built SAP–LAP framework on financial inclusion highlighting various issues and challenges faced in current scenario. (ii) In this section, we explore linkages among various elements of SAP–LAP model through efficient interpretive ranking process (IRP). (iii) Lastly, we present conclusion along with policy implications of this study.

SAP–LAP Framework

A conceptual model building through SAP–LAP is performed in two parts (Fig. 1) (Sushil 2000). The first part comprises SAP where 'situations' (S) are the manifestation of the present, past and the expected future in an organizational context. 'Situations' are handled by an actor(s) via process(es). 'Actors' (A) are the individual contributors, or group of members, which affect the situation and define an organizational culture to evolve business processes, which possess freedom of choice. At the outset, 'processes' (P) are the overall transformation steps that convert a set of inputs into outputs for dealing the current situation. The second part includes LAP which is synthesized based on SAP. Primarily, 'learnings' (L) are the outcomes from the situations, which help in further development of significant 'actions' (A*). These actions will lead to better 'performance' (P*) of the system. After all, the better performance strengthens the current situation (Sushil 2000).

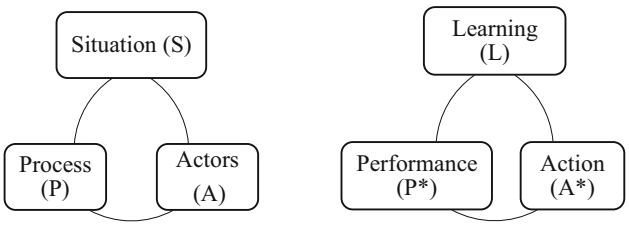


Fig. 1 SAP–LAP framework (Sushil 2000)

SAP–LAP framework is studied extensively in managing various supply-chain issues (Arshinder and Deshmukh 2007; Charan 2012; Garg and Deshmukh 2010; Kumar et al. 2012; Mahajan et al. 2013; Mangla et al. 2014). It is considered instrumental in diagnosing organizational socio-technical system for taking future course of actions by the management (Sahoo et al. 2011; Kulshreshtha et al. 2017). Ghosh and Sahney (2010) asserted the importance of SAP–LAP in studying the organizational socio-technical diagnosis of managerial retention in IT firm. Some other application of SAP–LAP includes in building Information Systems Flexibility in SME sector (Palanisamy 2012); planning and implementation of e-governance projects (Suri and Sushil 2012) and disaster management (Sushil 2017b).

SAP–LAP Framework: For the Theory Building of Financial Inclusion (FI) in Indian Context

In last few decades, financial inclusion has become essential for inclusive growth of a nation (Mohan 2006; Dixit and Ghosh 2013; Kapoor 2014). The extent of financial inclusion seems to vary from nation to nation (Demirgüç-Kunt et al. 2018). There are number of authors which studied determinants of financial inclusion (Bhanot et al. 2012; Kumar 2013; Fungáčová and Weill 2014; Kabakova and Plaksenkov 2018), financial inclusion measurement (Sarma 2008;Chakravarty and Pal 2010; Gupte et al. 2012; Cámara and Tuesta 2015), usage and access of financial services (Atanasova and Wilson 2003; Demirgüç-Kunt et al. 2008) and financial inclusion delivery mechanisms like SHGs (Venkataramany and Bhasin 2009; Swamy 2014), co-operative credit unions (Jones 2008) and microfinance (Setboonsarng and Parpiev 2013; Shankar 2013; Brown et al. 2016). In India, a contextual model was developed to present four scenarios of economic growth with financial inclusion (cornering the cake, growing cake, shrinking cake and vanishing cake) (Kapoor 2014).

Though there are a wide number of researches to explain the nature and extent of financial inclusions in different geographical and demographic contexts, a conceptual framework to provide a broader view for policy decision making in India

is desired. In this regard, we undertake an in-depth analysis through SAP–LAP framework. We first present situation, actors and various associated processes of financial inclusion. Later, learnings, actions and performance (LAP) are formed. For building SAP–LAP framework, the data were collected from both primary and secondary sources. The primary data were collated with the help of expert's opinion method. There are many studies which cite the significance of an expert's opinion as an efficient data collection method to build SAP–LAP framework (Singh and Kumar 2014; Kabra and Ramesh 2015). In total, sample size of 15 experts was selected, and the respondent's profile is summarized in Appendix 1. The interviews were conducted face to face with the expert. A semi-structured questionnaire was administrated following SAP–LAP model of inquiry (Sushil 2000) to understand the current situation, role of various actors, processes involved in implementing financial inclusion (Appendix 2). Later, learning-action-performance (LAP) as an interplay of SAP were studied. The questionnaire was kept open-ended for the better understanding of various aspects associated with the financial inclusion. Besides this, we encouraged experts to add any relevant information which was not asked in the questionnaire. All these responses were recorded and analysed for building SAP–LAP framework. The secondary data were collected from a variety of national and international websites, reports, publications and issues on financial inclusion. Consequently, the finding from both primary and secondary sources was collectively used to develop the model. The SAP–LAP framework for financial inclusion is presented below.

Situation

Financial inclusion has been important in addressing the millennium development goals (MDGs) through inclusive growth and poverty reduction (Chibba 2009). Numerous studies pinpointed the significance of financial development in reducing income disparity and poverty (Beck et al. 2007b; Inoue and Hamori 2012; Sehrawat and Giri 2016). In this regard, financial inclusion has emerged as a global priority (Hannig and Jansen 2010; Demirguc-kunt et al. 2017). As per the World Bank report on financial inclusion (Global Findex), around 1.7 billion adults are unbanked (50% living in developing countries), while India shares 21% of the world's unbanked population (Demirgüç-Kunt et al. 2018). Further, this report noticed an increase in formal account ownership in India due to large-scale adoption of biometric identification method. Though, the problem of inactive accounts and low usage of digital payment is still persistent. Previously, Reserve Bank of India (RBI) and the Government of India (GOI) took numerous steps to improve financial access to poor like lead bank scheme, priority sector lending, service area approach, nationalization of commercial banks, regional rural banks (RRB), etc.(Chakrabarty 2011). Some of the recent initiatives on financial inclusion are detailed in Appendix 3. At macro-level, financial inclusion is likely to impact the per capita income, demographics and legislative structure (Rojas-Suarez 2010; Park and Mercado 2015, 2018), while at micro-level, factors like physical access to financial services (Allen et al. 2016), financial literacy (Atkinson and Messy 2013; Klapper et al. 2015), voluntary lack of access (Demirgüç-Kunt and Klapper 2013) and low transactions rates (Chakrabarty 2013) seem to affect financial inclusion of individuals and businesses. In this study, based on experts' opinions we enlisted access and usage of banking services, financial literacy and institutional and regulatory interventions through various schemes and initiatives as key situational factors (Table 1).

Actors

Financial inclusion actors are studied in two parts, i.e. demand- and supply-side actors. As per experts' view, supply-side actors are mainly the decision makers in banks and government who influence the process of financial inclusion through innovative financial products and services, while the demand-side actors are the end-users. Financial intermediaries have fundamental role in economic growth and development of a nation (Levine et al. 2000; Mohan 2006). These financial intermediaries are largely the banks, NGOs, microfinance institutions, moneylenders and Self-Help Groups (SHGs). As financial inclusion has become a policy priority in almost all developing nations (Claessens 2006; Hannig and Jansen 2010), therefore, these economies are strategizing various policies interventions to improve the overall financial system.

The demand-side actors on the other hand are users or likely users of the financial services (Atkinson and Messy 2013). These end-users are mainly poor and disadvantageous people in the society (Leeladhar 2006; Thorat 2006; Chakrabarty 2011). In addition, there are some authors which described financially excluded not only being an individual but small and micro-firms too (Park and Mercado 2015; Demirgüç-Kunt et al. 2018).

Processes

There are various processes of delivering financial products and services to poor customers (Appendix 4). 'Microfinance' concept was based on the Grameen Model[1] which provides an opportunity to poor and low-income groups

[1] Grameen Model was initiated by Prof. Mohammed Yunus in 1976 in Bangladesh with a pilot project to promote microfinance for poor. Later, the model was given an independent bank status (*called Grameen Bank)* in 1983. The model encourages people to take group-based collateral-free loan (Yunus 2006).

Table 1 SAP–LAP variables and literature

	SAP–LAP variables	Literature
Situation		
S1	Access and usage of banking services	Demirgüç-Kunt et al. (2015), RBI (2017) and ESI (2016)
S2	Financial literacy	
S3	Institutional and regulatory interventions through various schemes and initiatives	
Actors		
A1	Government	Mohan (2006), Chatrath and Vallabh (2006) and Atkinson and Messy (2013)
A2	Banks	
A3	Poor and disadvantageous people	
A4	Non-banking financial companies	
Processes		
P1	Self-Help Groups (SHGs)-bank linkage	RBI (2011a, b)
P2	Business correspondents (BCs)	
P3	Microfinance-bank led programme	
P4	Simplified KYC norms	
P5	Bank branch authorization	
P6	Basic savings bank deposit accounts (BSBDAs)	
P7	General credit cards (GCC), Kisan credit cards (KCCs), etc.	
P8	Financial Stability Development Council (FSDC)	
Learnings		
	Demand-side learning	Cole et al. (2009), Brune et al. (2012), Hoyo et al. (2013), RBI (2014), Demirgüç-Kunt et al. (2015), Allgood and Walstad (2016) and Chiapa et al. (2016)
L1	Transit cost and time	
L2	Lack of money	
L3	Distance from the nearest bank	
L4	Lack of financial awareness and banking habits	
L5	Affordability and suitability of financial products and services	
L6	Socio-economic determinants affecting the exclusion (like age, income, gender, education, etc.)	
L7	Documentation issues	
L8	Attitude and perception of people	
L9	Collateral issue	
L10	Trust issues	
	Supply-side learnings	Claessens (2006), Chakrabarty (2012), Karpowicz (2016) and Amidžić et al. (2014)
L11	Institutional regulations and schemes	
L12	Business models of banks	
L13	Bank charges and fee	
L14	Poor infrastructure (both physical and financial)	
Actions		
A1*	Enunciating more on Information and Communication Technology (ICT)-based financing products and solutions	Cohen and Nelson (2011), Cnaan et al. (2012), Singh et al. (2014), Singh (2017), Jack and Suri (2011), Rillo and Miyamoto (2016), Anson (2016), ESI (2016) and RBI (2014)
A2*	Licensing more of differentiated banks	
A3*	Promoting micro-insurance sector	
A4*	Leveraging direct benefit transfer through Jan Dhan-Aadhaar-Mobile (JAM)	
A5*	Increasing number of post offices especially in rural areas	
A6*	Focusing more on financial literacy and training programmes	
A7*	Building infrastructure (both physical and financial) through collaboration	

Table 1 continued

	SAP–LAP variables	Literature
Performances		
P1*	Improved macro-economic conditions	Mohan (2006), Beck et al. (2007a), Demirgüç-Kunt et al. (2008), Demirgüç-Kunt and Klapper (2013) and Gwalani and Parkhi (2014)
P2*	Improved micro-economic conditions	
P3*	Safe and transparent financial transactions	
P4*	Last-mile coverage	
P5*	Increase in banking services utilization	

and micro-enterprises to access a wide range of financial services (like deposit, credit, remittance, insurance, etc.). There are two major microfinance delivery mechanisms in India, i.e. the SHG-bank linkage programme (SBLP) and Micro Finance Institutions (MFIs) model (RBI 2011a). SHG-bank linkage programme was launched by National Bank for Agriculture and Rural Development (NABARD) in 1992 to ensure income and livelihood to poor residing in rural areas. Self-Help Groups (SHGs) comprise small homogenous group of people organized for the purpose to extend small finance to poor, especially women (NABARD 2010). Also, the extant literature is abundant in highlighting the link between SHGs and financial systems (Basu and Srivastava 2005; Uma and Rupa 2013; Swamy 2014; Gupta and Chatterjee 2018). Similarly, microfinance institutions (MFI) model involves funding to poor individual or group by microfinance institutions (RBI 2011a). Later, RBI in 2005 took major steps by relaxing norms for Know Your Customer (KYC), no-frill account (or zero balance account), simplified bank branch authorization (RBI 2006). Consequently, the business correspondent model was also adopted by banks to extend banking-related services in far and remote places in rural areas (RBI 2011a). Furthermore, in recent time the diffusion of Information and Communication Technologies (ICTs) in banking sectors has enabled us to access financial services through numerous means like mobile phone, internet, automated teller machines (ATMs), etc.

Learning

Learning pertains to challenges and opportunities in the current system. In this study, taking account of experts' opinion we categorized learnings from situation-actor-process into two parts, i.e. demand- and supply-side learnings (Table 1):

(i) *Demand-side learnings* transit cost and time, lack of money, documentation issues, socio-economic status (like income, age, gender, occupation, asset ownership, etc.), trust issue, attitude and perception of people, collateral issue and lack of banking habits (due to lack of financial awareness, motivation, affordability and suitability of financial products and services)
(ii) *Supply-side learnings* poor infrastructure (both physical and financial), business models of banks, bank charges, institutional regulations and schemes, poor outreach and usage of banking services.

The demand-side learnings are associated with the end-beneficiaries or customers. The exclusion from financial services by poor can be voluntary or involuntary (Demirgüç-Kunt and Klapper 2013). The voluntary exclusion involves opting-out from banking services due to some religious or cultural disposition or lack of interest; on the other side, involuntary exclusion may happen due to market imperfection, insufficient income and banking services availability, etc. (Demirgüç-Kunt et al. 2015). In this regard, financial literacy is an important demand-side aspect, as increase in awareness on financial products and services stimulate the banking services utilization (Ardic et al. 2011; Ramakrishnan 2011). Some of socio-economic factors like education (Paramasivan and Ganeshkumar 2013; Clamara et al. 2014), gender (Ghosh and Vinod 2017) and income (Banerjee and Duflo 2007; Martínez et al. 2013) also affect the banking services utilization. Some authors mentioned documentational proof, affordability of financial products, lack of money, attitude and perception of bank personnel and trust as key issues of financial inclusion (Demirgüç-Kunt and Klapper 2013; Allen et al. 2016). Notably, the distance of nearest bank drives demand side, especially in remote and distant areas (Brune et al. 2012). In addition, zero fee and physical proximity to the bank led to high adoption and usage of banking facilities (Chiapa et al. 2016).

Supply-side learnings are the issues related to financial institutions in delivering affordable and appropriate financial services to poor. Majorly, supply side of financial inclusion is linked with market failure due to asymmetrical information (Claessens 2006), physical infrastructure (Karpowicz 2016), banking model, outreach and charges (Chakrabarty 2011). Amidžić et al. (2014) on measuring financial inclusion index reported three important supply-side indicators, i.e. outreach (geographic and demographic

penetration), usage (deposit and lending) and quality (disclosure requirement, dispute resolution and cost of usage). In rural context, the need to upscale digital, physical connectivity and innovative and affordable financial products were identified (RBI 2014).

Action

Based on experts' judgments on 'learnings', actions suggested are:

- *Enunciating more on Information and Communication Technology (ICT)-based financing products and solutions* (A_1*)
- *Licensing more of differentiated banks* (A_2*)
- *Promoting micro-insurance sector* (A_3*)
- *Leveraging direct benefit transfer schemes through JAM trinity* (A_4*)
- *Increasing the number of post offices, especially in rural areas* (A_5*)
- *Focusing more on financial literacy and training programmes* (A_6*)
- *Building infrastructure (both physical and financial) through collaboration* (A_7*)

Many studies have illustrated the significance of Information and Communication Technology (ICT)-based financial products and services like E-KYC, Immediate Payment System (IMPS), Micro-ATMs, Aadhaar Enabled Payment System (AEPS) and Aadhaar Payments Bridge System (APBS) in banking sector (Singh et al. 2014; Singh 2017). Mobile banking is an important ICT-based application which enables poor to access banking services in far places. In India, around 69% of adults reported having mobile phones, out of which a larger part has an inactive account (Demirgüç-Kunt et al. 2018). Differentiated banks (like payment bank and small banks) cater to the needs of a niche segment like small businesses, small and marginal farmers, workers in unorganized sector, etc. (RBI 2013). Recently, Government of India iterated linking JAM[2] trinity (Jan Dhan, Aadhaar and Mobile) with direct benefit transfer schemes[3] (DBTs) as a mechanism to promote financial inclusion (ESI 2016). Similarly, there are studies to accentuate the role of the post office (Rillo and Miyamoto 2016; Anson 2016), financial literacy (Ramakrishnan 2011) and better infrastructure (Lyons et al. 2017) in including poor and disadvantageous under banking ambit.

Performance

Consequently, this section discusses the most likely impact of these actions (Table 1). The impact on SAP as asserted by experts is discussed below:

- *Improved macro-economic conditions* (P_1*) The proposed actions can improve current macro-economic situations like economic growth, productivity, investment, etc.
- *Improved micro-economic conditions* (P_2*) Similarly, the suggestive actions are likely to implicit the micro-economic conditions of individuals and businesses.
- *Safe and transparent financial transactions* (P_3*) Inclusion of innovative ICT-based products and DBT schemes through JAM are expected to bring transparency and safety in the system as there are several schemes at state- and national-level benefits (or subsidiary) for the poor in India. Therefore, scaling-up DBT through JAM trinity may facilitate a fair financial transaction and plug to any financial leakage at the intermediate level.
- *Last-mile coverage* (P_4*) Various actions like differentiated banks, JAM trinity, post offices and ICT-based financial products have the potential to connect with people in far and unbanked rural places. Infrastructure development (both financial and physical) in place of poor connectivity of road, internet and mobile phone can play a crucial role in last-mile coverage.
- *Increase in banking services utilization* (P_5*) Actions proposed have potential to increase banking services utilization, especially the inclusion of more financial literacy programmes. Financial awareness enables customers to make better choices and motivate them to use more financial services and products.

Thus, SAP–LAP framework developed is demonstrated in Fig. 2. As it is likely to have interactions among various elements of the proposed theoretical framework, it is essential, from a policy point of view, that we examine inter-connectedness among variables in the model. There are a variety of qualitative techniques to assess these interactions and rank them accordingly. In this study, we have focused on efficient interpretive ranking process (IRP) to study linkage among some of the variables of SAP–LAP framework. The next section discusses SAP–LAP linkages through efficient interpretive ranking process (IRP) (Sushil 2017a).

[2] JAM stands for Pradhan Mantri Jan Dhan Yojana (PMJDY), Aadhaar and Mobile. Majorly, this trinity has potential to curb the financial leakage in government benefit schemes for poor and resolve the issue of last-mile coverage. (ESI 2016).

[3] Direct benefit transfer (DBT) was initiated by Government of India (GOI) in 2013 to transfer subsidiary from a scheme directly into account of beneficiaries (usually below poverty line) (Details of each such schemes can be retrieved at https://dbtbharat.gov.in/).

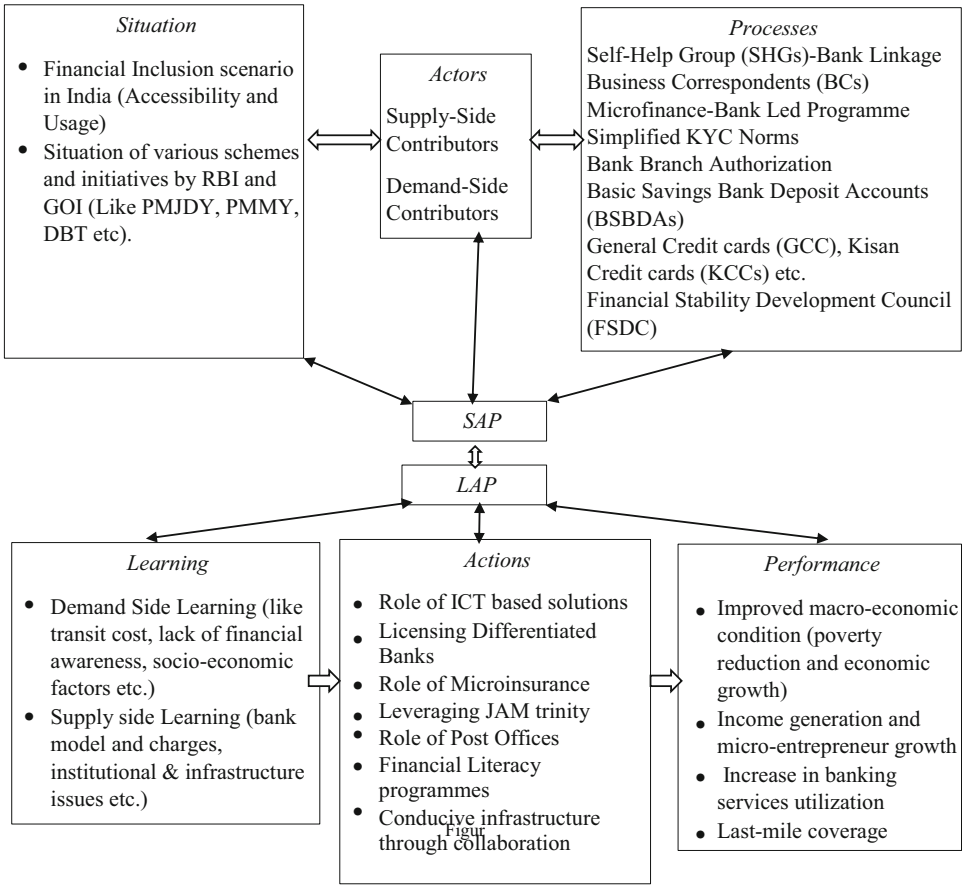


Fig. 2 SAP–LAP framework

SAP–LAP Linkages: Through Efficient Interpretive Ranking Process (IRP)

The linkages among elements of SAP–LAP framework are analysed through efficient interpretive ranking process (IRP). IRP is a multi-criterion decision-making technique significant for paired comparison in the interpretative matrix and intent to address the issue of rational choices and intuitive processes (Sushil 2009). A number of studies adopted IRP to study various linkages among variables of SAP–LAP in different contexts like risk mitigation in world class manufacturing(Haleem et al. 2012), green supply chain (Mangla et al. 2014), success of Tata Nano motors (Singh and Kumar 2014) and ICT issues in humanitarian supply-chain management (Kabra and Ramesh 2015; Gupta and Suri 2018). IRP involves broadly two types of interaction matrices, i.e. self-interaction matrix (SIM) and cross-interaction matrix (CIM) (Sushil 2009). This study employed an improved methodology for interpretive ranking process also referred as efficient interpretive ranking process (Sushil 2017a). Efficient IRP incorporates implicit and transitive dominance relationships which aid in reducing the number of interpretive comparisons. Previously, the efficient interpretive ranking process (IRP) methodology was implemented in multi-criteria decision-making problem related to customized products manufactured under different types of production systems, where dominance index was incorporated instead of net dominance (Sushil 2018).

As there are number of paired comparisons possible in SAP–LAP framework, we limit to analyse cross-interpretive matrices, of two types, i.e. 'actors' vs 'processes' and 'actions' vs 'performance'. The reason for selecting these matrices is to present the dominant actors and actions which influence processes and performance, respectively. Consequently, this will aid policymakers in prioritizing various actors and actions for financial inclusion.

In order to build the linkages among variables as recognized in SAP–LAP framework (Table 1), we recollected the experts' opinions. The experts were asked to prioritize the identified variables of 'actors over processes' and 'action over performance' on 5-point Likert scale. Later, the average value from the responses was assessed on interpretative matrix. The internal validity was also checked through the dominance system graph. The steps followed for efficient IRP methodology are mentioned as follows (Sushil 2017a):

Table 2 Cross-interaction matrix (CIM) and interpretive logic: actors versus processes

	P1	P2	P3	P4	P5	P6	P7	P8
Cross-interaction matrix (CIM)								
A1	1	0	1	1	0	0	1	1
A2	1	1	1	1	1	1	0	1
A3	1	0	1	1	0	1	1	1
A4	1	1	1	0	0	0	0	0
Interpretive matrix (or logic)								
A1	Promote various schemes to develop Micro-enterprises, especially for women	–	Policy interventions for MFI	Implement a new and innovative biometric-based method of identification	–	–	Supply fund	Supply fund
A2	Organizing and funding SHGs	Regulation and monitoring of BC	Refinancing of MFI	Facilitate or regulate the process of new bank branches	Regulation and monitoring of bank branch	Maintenance and regulation of bank account	–	Organizing financial literacy camps
A3	Demand for credit in SHGs and repayment efficiency	–	Demand for micro-loans by MFI and repayment efficiency	Affect bank account opening	–	Affect Utilization of BSBDA	Affect farm and non-farm credit needs	Increases banking services utilization
A4	Organizing and funding SHGs	Engaged as BC	Engaged as MFI	–	–	–	–	–

(Authors estimation)

(i) Firstly, two set of variables were identified from SAP–LAP framework, one which is to be ranked with the reference variable. We studied the relationship between two set of matrices, i.e. actors with processes and actions with performances.

(ii) In this step, we obtained cross-interaction matrices for the identified sets of variables. The relationship between the two variables were established through expert's opinion converted to binary values of either '1' (having relationship between the pair) or '0' (having no relationship between the pair). The cross-interaction matrices obtained are illustrated in Table 2 ('actors' vs processes) and Table 3 ('actions' vs performance).

(iii) The cross-interaction binary matrices were changed to cross-interpretive matrices by adding the 'contextual' interpretation for value '1' in the matrix (Tables 2, 3, respectively). For example, in Table 2, the interaction between A1 and P1 was construed as '*promote various micro-enterprises especially for women*'; similarly in Table 3, the interaction between A1 and P1 as '*facilitate growth through innovative and improved ICT*'.

(iv) Further, the cross-interpretive matrices were transformed into the dominating interaction matrices. A pair-wise comparison between the alternate (x) with the reference variable (y) was carried out. The following four possibilities were assessed (Appendices 5 to 8):

(a) *Implicit dominance* If an alternative (x) is having relationship ('1' entry) and the reference variable (y) is not having any relationship ('0' entry) for a positive criterion, then the alternative implicitly dominates the reference variable and vice versa in case of negative criterion.

(b) *Implicit non-dominance* If both the 'x' and 'y' have zero entries, then 'x' has implicit non-dominance over 'y'. In such case, we enter zero in x–y dominating interaction matrix for a paired comparison between alternative with respect to a criterion. For instance, in action vs performance, A2* has non-implicit dominance over A3* for performance P3*. The non-dominance can also happen when both the alternatives x and y have '1' entry in their cell for a particular criteria, but in the interpretive

Table 3 Cross-interaction matrix (CIM) and interpretive logic: actions versus performance

	P1*	P2*	P3*	P4*	P5*
Cross-interaction matrix (CIM)					
A1*	1	1	1	1	1
A2*	1	1	0	1	1
A3*	1	1	0	0	1
A4*	1	1	1	1	1
A5*	1	1	0	1	0
A6*	–	0	0	0	1
A7*	1	1	0	1	1
Interpretive matrix (or logic)					
A1*	Facilitate growth through innovative and improved ICT	Banks with better ICT methods can target more customer needs	Facilitate safe and transparent transactions	Provide solutions to places where banking services are inadequate and far	Reduce the transaction cost and motivate people
A2*	Long-term benefit	More utilization of formal loan which in turn can help in employment and income generation	–	Financial access at geographical distant and remote places	More customized financial products and services motivate people
A3*	Promote Insurance sector	Ensure accidental, health and agricultural losses, etc.	–	–	Benefits can motivate poor
A4*	Long-term benefit in overall growth and development	Ensure better wage and employment opportunities	Reduce the role of various intermediaries involved and bring transparency	Potential to better outreach to far and distant places	Benefits can motivate poor
A5*	Long-term benefit	Better saving products to poor	–	Provide solutions where banks are not available	–
A6*	–	–	–	–	Financial awareness
A7*	Long-term benefit	Better infrastructure for building banks and connectivity	–	Collaboration among various stakeholders can facilitate the last-mile coverage	Financial awareness

(Authors estimation)

cross-interaction matrix the interpretation is same for both the alternatives, in that case we consider the relationship as implicit non-dominance and enter '0' in the dominating interaction matrix (x–y cell).

(c) *Interpretive dominance* In case, when both alternatives x and y have '1' entry with different interpretations, expert's opinion is taken to assess the dominance of one alternative over other. Based on the expert's judgment, we enter '1' in an x–y cell *or* y–x cell if an alternative is dominating over the reference variable for a criterion. For example, in actor vs performance comparison, A2 has interpretive dominance over A1 for P3 (Appendices 5 and 7).

(d) *Transitive dominance* If there are three alternatives x, y and z each with '1' entries with different interpretations, then on comparison if x has a dominating interaction over y and y in turn has dominating interaction with z, then by transitivity x should also have a domination over z and '1' is entered in dominating interaction matrix (x–z cell). All interpretive and transitive interactions for each criterion were assessed.

(v) We repeated the step (iv) for all dominating interaction matrices; in total $n(n-1)/2$ entries for all types combined in the concerned dominating interaction matrix were studied (Appendices 6 and 8).

(vi) We estimated the overall dominance matrix [D] through the addition of all possible dominating interaction matrices, as mentioned in Eq. 1:

$$D = \sum_{x} D_x \tag{1}$$

Table 4 Different types of dominance interactions (actor vs processes)

Processes	Implicit dominance	Implicit non-dominance	Transitive dominance	Interpretive dominance	Total comparison	% Interpretive comparisons
P1	0	0	1	5	6	83.33
P2	4	2	0	0	6	–
P3	0	0	1	5	6	83.33
P4	3	0	0	3	6	50
P5	3	3	0	0	6	–
P6	4	1	0	1	6	16.67
P7	4	1	0	1	6	16.67
P8	3	0	0	3	6	50
Total	21	7	2	18	48	
Percentage	43.75	14.58	4.16	37.50		

(Authors estimation)

Table 5 Different types of dominance interactions (actions vs performance)

Performance	Implicit dominance	Implicit non-dominance	Transitive dominance	Interpretive dominance	Total comparison	% Interpretive comparisons
P1	6	12	0	3	21	14.28
P2	6	8	1	6	21	28.57
P3	10	11	0	0	21	0
P4	9	7	0	5	21	23.80
P5	6	5	1	9	21	42.85
Total	37	44	2	23	105	
Percentage	35.23	41.90	1.90	21.90		

(Authors estimation)

(vii) Subsequently, we calculated the number of all types of such paired comparisons with their respective percentages (Tables 4, 5).

(viii) Lastly, we calculated the rank for each ranking variable based on the dominance index (Sushil 2018). To measure the dominance index (DI_x), we first estimated the net dominance value (D-B) obtained by subtracting the number of case dominating (D) by the number of cases being dominated (B). Then, 'adjusted net dominance (AND_x)' was estimated by converting the highest net negative dominance as 'zero' and accordingly adjusting all other net dominance values. The computation of dominance index (DI_x) is as per Eq. 2:

$$(DI_x) = \left(\frac{\text{ANDx}}{\text{Total interactions (TI)}}\right) \times 100 \quad (2)$$

Thus, based on the dominance index (DI_x) value for each ranking variable respective rank is assigned (Tables 6, 7).

Discussions

Actors Versus Processes

Based on experts ranking, the interaction of actors with processes is represented in a binary and interpretive matrix in Table 2. We summarized 6 paired comparisons for each process (P1 to P8) (Table 4). The implicit dominance comparisons were found largest (43.75%) followed by interpretive dominance (37.50%), implicit non-dominance (14.58%) and transitive dominance (4.16%) comparisons. Later, the dominance index illustrated significance of 'Banks' (A2) in affecting most of the processes involved (Table 6). Banks (A2) function as a promoter, regulator and monitor for various processes of financial inclusion. Banks have authority to engage individual(s) or entity(s) like NGOs, NBFC, microfinance institutions (MFI) as a business facilitator and business correspondents for extending banking services (RBI 2006). Also, RBI liberalized bank branch authorization policy to encourage opening of new bank branches in unbanked rural areas

Table 6 Dominance index—ranking of actors w.r.t. processes

	A1	A2	A3	A4	D	Net dominance value (D-B)	Adjusted net dominance (AND)	Dominance index	Rank
A1	–	2	3	3	8	− 4	5	12.19	III
A2	6	–	4	5	15	8	17	41.46	I
A3	3	4	–	6	13	5	14	34.14	II
A4	3	1	1	–	5	− 9	0	00	IV
(B)[a]	12	7	8	14	41 (TI)				

(Authors estimation)

TI total interactions

[a]No. of cases being dominated

Table 7 Dominance matrix—ranking of actions w.r.t. performance

	A1*	A2*	A3*	A4*	A5*	A6*	A7*	(D)	Net dominance value (D-B)	Adjusted net dominance (AND)	Dominance index	Rank
A1*	–	5	5	0	2	4	2	18	16	28	45.16	I
A2*	0	–	1	0	1	2	1	5	− 5	7	11.29	V
A3*	0	0	–	0	1	2	1	4	− 10	2	3.22	VI
A4*	0	2	3	–	2	4	1	12	10	22	35.48	II
A5*	1	1	2	1	–	3	1	9	0	12	19.35	IV
A6*	1	1	1	1	1	–	1	6	− 12	0	00	VII
A7*	0	1	2	0	2	3	–	8	1	13	20.96	III
B[a]	2	10	14	2	9	18	7	62 (TI)				

(Authors estimation)

TI total interactions

[a]No. of cases being dominated

(RBI 2011a), while financial literacy centres (FLC) were initiated by banks to promote financial literacy mostly among farmers, SMEs, SHGs, senior citizens, etc. (RBI 2017).

The poor beneficiaries (A3) secured rank 'two' in this study, with dominance index of 34.14. The interaction between end-beneficiaries (A3) and various processes of financial inclusion (P1) are considered important for generating income and livelihood options. In this regard, there are many authors which emphasized the role of financial inclusion in increasing per capita income (Beck et al. 2008; Dupas and Robinson 2013). The role of government (A1) was ranked 'three'. Government exercises various roles ranging from a potential fund provider to an implementer and a promoter of schemes and programmes like biometric-based method of identification, micro-enterprises for women, etc. Indian government initiated unique identification (UID) number system, a biometric technology-based identification which facilitates documentation requirements for 'Know Your Customer (KYC)' norms by banks (RBI 2011b). Lastly, NBFCs (A4) were ranked 'four', non-banking financial companies (NBFC) play an important role in channelizing banking services in places of scarce financial access (RBI 2011a).

Actions Versus Performance

The cross-interaction matrix for action vs performance is presented in Table 3. There are 21 paired and 105 overall comparisons were studied (Table 5). There exist implicit non-dominance interactions (41.90%), the implicit dominance interactions (35.23%), interpretive dominance (21.90%) and transitive dominance (1.90%). However, the percentage of interpretive comparisons for each performance ranges between 14.28 and 42.85%. Further, when various actions were ranked based on dominance index, Information and Communication Technology (ICT)-based financing products and solutions (A1*) were ranked 'one' (with a dominance index of 45.16). ICT diffusion in the banking sector is associated with the economic growth (Shamim 2007; Kpodar and Andrianaivo 2011; Sassi and Goaied 2013). The innovative financial technologies like mobile money not only address the issue of limited financial access (Gosavi 2018), but also contribute towards the increase in overall performance of small and microenterprises (Islam et al. 2017), safety and security (Jack and Suri 2011; Mas and Morawczynski 2010), risk sharing and reduction in transaction cost (Jack and Suri 2014). Jan Dhan-Aadhaar-Mobile trinity (A4*) was ranked 'two'. The

significance of JAM in fostering direct benefit transfer schemes was also highlighted in Economic Survey of India 2016–2017 (ESI 2016). Direct benefit transfer schemes (DBTs) facilitate many society beneficial programmes by limiting any financial leakage involved in welfare delivery (Barnwal 2015). Further, building the physical infrastructure through collaboration (A7*) was ranked 'three'. The development of physical infrastructure like road, electricity, telecom, etc., is associated with the increase in access towards banking services in rural areas (Sarma and Pais 2008; Chakrabarty 2011). The role of post offices (A5*) was ranked 'four' considering the important role in addressing the issue of last-mile coverage, account ownership and financial access for various saving products (Anson et al. 2013). Licensing more of differentiated banks (A2*) was ranked 'fifth'. Differentiated banks have potential to ease in formal loan utilization by individuals and businesses, especially in geographical distant and remote places. Recently, micro-insurance (A3*) has emerged in the Indian context, which was ranked 'sixth'. Many empirical investigations have also asserted the significance of micro-insurance in escaping poverty, growth and well-being through the transfer of risk (Akotey and Adjasi 2014; Janzen and Carter 2018). Lastly, focusing more on financial literacy camps (A6*) was ranked.

Conclusion and Policy Implications

This study contributes to the extant literature by building a theoretical framework of SAP–LAP on financial inclusion in India. The linkage between various elements of SAP–LAP is interpreted through an integrated approach like efficient interpretive ranking process. Although there are many interactions possible between various elements in our theoretical model, we focussed to study two set of cross-interaction matrices, i.e. actors with processes and actions with performances. The findings suggest that the actors like banks dominate most of the processes involved with financial inclusion. Further, the potential actions like strengthening ICT-based financial products and services, leveraging Jan Dhan-Aadhaar-Mobile (JAM trinity) and building physical infrastructure through collaboration are significant in guiding the overall performance. The outcomes of this paper are likely to aid in better management of various actors and actions of financial inclusion.

This study offers many policy implications. The SAP–LAP framework on financial inclusion provides demand- and supply-side integrities of the financial inclusion. The ranks obtained through efficient Interpretive Ranking Process (IRP) of actors and actions may help the policymakers in improved decision making and strategizing key policies to increase access and usage of financial products and services. The role of banks is persuasive in almost all processes enlisted for financial inclusion as banks play a major role in executing, monitoring and regulating various financial products and services. Thus, the top management in banks should develop products based on the needs of poor. Similarly, building Information and Communication Technology network was reported as a critical action. The Government of India through various initiatives and collaborations should try to scale up the ICT infrastructure for better financial inclusion in far unbanked areas. Besides this, our research sensitizes stakeholders in sectors like insurance for micro-insurance, postal services, telecom for mobile banking and mobile money for innovative financial products and services, MSME for micro-enterprises development and microfinance institutions (MFI) for microfinance, etc.

Though, this study has some research limitations as we present a framework-based on expert opinions on financial inclusion; therefore, the model needs to be redefined before implementing in different contexts. The scope of financial inclusion is diverse in India, and it is likely that some of the aspects are not covered. Therefore, future researchers are prompted to take some real case examples along with a large empirical dataset.

Appendix 1

Respondent's Profile

Domain	Profile	Work experience	Number of respondents
Public Bank	General Manager	10–20 years	2
	Senior Manager	5–10 years	2
Private Bank	General Manager	10–20 years	2
	Senior Manager	5–10 years	2
Academician	Professor	20–25 years	4
Government	Consultant	10–15 years	3

Appendix 2

SAP–LAP Model of Inquiry

SAP–LAP	Questions
Situations	What is the current status of financial inclusion in India?
	What are the different initiatives adopted to promote and implement financial inclusion?
	What are the present issues faced by banks in providing financial products and services to the poor?
	What are the present issues faced by poor customers in utilizing financial products and services?
Actors	Who are the key actors in influencing the supply side of financial inclusion?
	Who are the key actors in influencing the demand side of financial inclusion?
Processes	What are the key processes adopted to promote financial inclusion of poor by the government?
	What are the key processes adopted by various banks to deliver financial products and services to the poor?
	What are the key processes through which monitoring of financial inclusion progress could be done?
Learning	What are the challenges with respect to the current situation?
	What are the challenges with respect to various processes of financial inclusion?
	What are the challenges faced by various actors in implementing financial inclusion?
Actions	What are the actions that need to be taken to address the challenges and issues impeding financial inclusion in the country?
Performance	How these proposed actions are going to affect the current scenario of financial inclusion?
	What will be the potential impact of these actions on key influencer or actors of financial inclusion?
	What will be the potential impact on various processes of financial inclusion?

Appendix 3

Highlights of Some Recent Initiatives by Government of India on FI

Pradhan Mantri Jan Dhan Yojana (PMJDY): PMJDY is a recent scheme to boost the financial inclusion in India. The earlier target of this scheme was to open 7.5 crore new bank accounts (PMJDY 2017)

Pradhan Mantri MUDRA Yojana (PMMY): PMMY is intended to promote financial inclusion by encouraging small and micro-enterprises to take up the loan. The loans are usually extended through various commercial banks, RRBs, microfinance institutions, etc. Based on the loan amount, the Mudra Loans have been classified under three categories 'Shishu' (up to INR 50,000), 'Kishore' (above INR 50,000 to up to 5 lakh) and 'Tarun' (above INR 5 lakh to up to 10 lakh) (PMMY 2016)

Direct Benefit Transfer schemes (DBTs): The role of Jan Dhan-Aadhaar-Mobile (JAM) is significant in affecting various direct money transfer schemes (DBTs) (ESI 2016)

Stand-Up India Scheme: The scheme aims at promoting the entrepreneurship especially among backward castes (Scheduled caste/scheduled tribe) and women by extending bank loan of INR 10 lakh to 1 crore. Credit Guarantee Fund for Stand-Up India (CGFSI) has been constituted under this scheme to promote collateral-free coverage (DoFS 2017)

Besides this, there are some recent social security schemes in insurance and pension sectors like Pradhan Mantri Jeevan Jyoti Bima Yojana (PMJJBY), Pradhan Mantri Suraksha Bima Yojana (PMSBY), Atal Pension Yojana (APY) and Pradhan Mantri Vaya Vandana Yojana which also facilitate the financial inclusion (DoFS 2017)

(Authors Compilation)

Appendix 4

Various Processes of Financial inclusion

Processes	Description
Bank led programme	*i) Self-Help Groups (SHGs)-bank linkage* In this mode, the banks extend a loan to SHG which is generally a group of 10–20 people usually poor or underprivileged. The bank provides the loan against the money deposited by them. SHG serve group guarantee of each other and take a collective decision in lending to any member *(ii) Business Correspondents (BCs)* In this mode, the BCs are enabled to extend banking services in far and remote areas of difficult financial access *(iii) Microfinance-bank led programme* Under this model, banks refinance the microfinance institutions which in turn extend micro-loans to the poor
Simplified KYC norms	RBI eased the Know Your Customer (KYC) requirement to address the documentation issues
Bank branch authorization	RBI liberalized the bank authorization policies especially in remote and rural areas. This permits the banks to open new branches without undergoing much authorization approval in those areas
Basic savings bank deposit accounts (BSBDAs)	RBI introduced no-frill accounts (zero or minimum balance account) in 2005. Later, it was replaced by basic saving bank deposit accounts (BSBDAs) with a facility of overdraft limit
General credit cards (GCC)	The general credit card provides a facility to people residing in rural and semi-urban to avail easy access of up to INR 25,000 without security
Kisan credit cards (KCCs)	These are the smart cards issued by banks helping farmers to avail their credit need timely
Mobile banking	Mobile banking is an innovative platform which enables the user to operate the banking services like paying bills, fund transfer, etc., on a mobile phone
Financial Stability Development Council (FSDC)	RBI revised norms for financial literacy centres (FLCs). The focus of this council is to promote financial inclusion through financial literacy

(*Source*: www.rbi.org)

Appendix 5

Interpretive logic—knowledge base-ranking of actors w.r.t. processes

Paired comparison	Interaction with process	Interpretive logic
A2 Dominating A4	P1	Banks have a predominate role in extending credit to SHGs for various entrepreneurial activities against group guarantee
A3 Dominating A1, A2 and A4	P1	Poor beneficiaries have more influence in SHG formation, repayment and demand for credit
A4 Dominating A1	P1	NBFCs work more closely in far and distant places in disbursing loans to SHGs
A2 Dominating A1	P3	Banks refinance various microfinance institutions to extend micro-loans to poor
A3 Dominating A2 and A4	P3	The demand for micro-loan by poor influences the borrowing from microfinance institutions
A4 Dominating A1 and A2	P3	NBFCs as microfinance institutions (MFI) disburse micro-loans more closely to the poor residing in far and unbanked places
A1 Dominating A3	P4	Government through various policy interventions for biometric authentication have significant influence in simplification of KYC (Know Your Customers) norms
A2 Dominating A1 and A3	P4	Banks have more influence in regulation and implementation of various KYC norms
A3 Dominating A2	P6	Poor beneficiaries (or end-users) impact more on the utilization of BSBDA
A1 Dominating A3	P7	Government through policies interventions impact on the dissemination of Kisan credit card, (KCC), general credit card, etc.
A1 Dominating A2, A3	P8	Government provides funding to create awareness for financial products and services for poor
A2 Dominating A3	P8	Banks has predominant role in promoting financial literacy through various awareness camps and programmes

Appendix 6

Pair-wise dominance of actors (A1 to A4) for different processes (P1 to P8)

(a) Dominating Interaction Matrix of Actors for Process P1 (with Fig. 1 Transitive interaction graph)

	A1	A2	A3	A4
A1		-	-	-
A2	1		-	1
A3	1	1		1
A4	1	-	-	

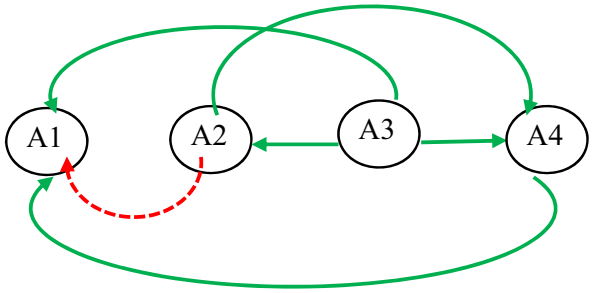


Figure 1

(b) Dominating Interaction Matrix of Actors for Process P2

	A1	A2	A3	A4
A1		-	0	-
A2	1		1	0
A3	-	-		-
A4	1	-	1	

(c) Dominating Interaction Matrix of Actors for Process P3 (with Fig. 2 Transitive interaction graph)

	A1	A2	A3	A4
A1		-	-	-
A2	1		-	-
A3	1	1		1
A4	1	1	-	

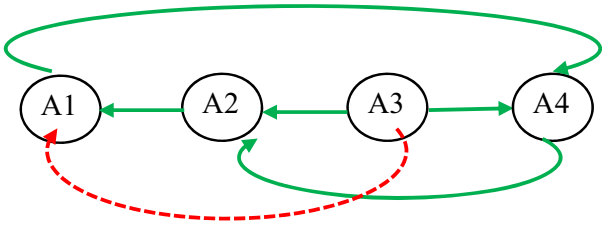


Figure 2

(d) Dominating Interaction Matrix of Actors for Process P4

	A1	A2	A3	A4
A1		-	1	1
A2	1		1	1
A3	-	-		1
A4	-	-	-	

(e) Dominating Interaction Matrix of Actors for Process P5

	A1	A2	A3	A4
A1			0	0
A2	1		1	1
A3	-	-		0
A4	-	-	-	

(f) Dominating Interaction Matrix of Actors for Process P6

	A1	A2	A3	A4
A1		-	-	0
A2	1			1
A3	1	1		1
A4	-	-	-	

(g) Dominating Interaction Matrix of Actors for Process P7

	A1	A2	A3	A4
A1		1	1	1
A2	-			0
A3	-	1		1
A4	-	-	-	

(h) Dominating Interaction Matrix of Actors for Process P8

	A1	A2	A3	A4
A1		1	1	1
A2	-		1	1
A3	-	-		1
A4	-	-	-	

Implicit Dominance

Implicit Non-Dominance

Interpretive Dominance

Transitive Dominance

Appendix 7

Interpretive logic—knowledge base-ranking of actions w.r.t. performances

Paired comparison	Interaction with process	Interpretive logic
A1* Dominating A2*	P1*	ICT-based financial products are more likely to impact the macro-economic conditions
A1* Dominating A2*	P2*	Similarly, ICT-based financial technology have more impact on improving the micro-economic conditions of individuals and businesses
	P4*	ICT-based products like mobile banking have potential to outreach larger masses in far and distant rural places
	P5*	ICT-based products provide ease in utilizing various banking services
A1* Dominating A3*	P1*	Although micro-insurance services have long-term benefit, the improvement in ICT-based products have more impact on overall growth and development
	P2*	Technology provides an opportunity to reach rural masses through a mobile phone; online banking with the business correspondent model has made banking services more accessible and easier
	P5*	ICT has the potential to ease in access and utilization of various financial services
A1* Dominating A7*	P3*	ICT-based platform provides more safe and transparent financial transactions
A2* Dominating A7*	P5*	Though micro-insurance instils saving and insurance towards accidental, health and agricultural losses, etc. However, differentiated banks on the other hand facilitate utilization of varieties of financial services like small deposit and lending, etc.
A3* Dominating A7*	P5*	The significance of micro-insurance programmes linked with banks has recently emerged in many sectors like various farm and entrepreneurial activities which in turn impact banking services utilization
A4* Dominating A2*	P2*	Jan Dhan-Aadhaar-Mobile (JAM) trinity has the potential to bring a large mass under the mainstream banking sector with direct cash payments to beneficiaries account
A4* Dominating A3*	P1*	JAM trinity is likely to impact the country's growth by raising banks saving fund and subsequent investment for development and employment
A4* Dominating A7*	P3*	JAM which involves mobile banking provides comparatively safe and transparent option for financial transactions
A5* Dominating A1*, A2*, A4* and A7*	P4*	Post offices in India provide one stop financial solutions to many services like payment collection on behalf of subscribers like electricity, telephone, etc., receiving benefits under various state and central government schemes particularly in remote areas
A5* Dominating A3*	P1*	Micro-insurance is an emerging sector in India, but post offices are wide spread and have become an access point to many financial services, which, in turn, most likely impact productivity and employability
	P2*	Post offices may play a significant role in providing financial service to financially excluded segment like less educated, poor, labourers, farmers, etc., particularly in rural areas
A6* Dominating A1*, A2*, A3*, A4* and A7*	P5*	Increasing financial literacy may improve utilization of various financial products and services
A7* Dominating A2*	P1*	Though differentiated banks target niche demographic segments, it may fail to sustain without infrastructure developments (like the road, internet, phone connectivity, etc.)
	P2*	Expanding infrastructure is most likely to increase the access to financial services by individuals and micro-enterprises
A7* Dominating A5*	P1*	Building financial infrastructure through collaboration may help to build macro-economic sphere by increasing the productivity of the firms
	P2*	A better physical infrastructure may help to disseminate banking services more easily to people living in far and unbanked places where even post offices are unavailable.

Appendix 8

Pair-wise dominance of actions (A1 to A7) for different performances (P1 to P5)

(a) Dominating Interaction Matrix of Action for Performance (P1*)

	A1*	A2*	A3*	A4*	A5*	A6*	A7*
A1*		1	1	0	0	1	0
A2*	-		0	0	0	1	0
A3*	-	-			0	1	0
A4*	-	-	1		0	1	0
A5*	-	-	-	-		1	0
A6*	-	-	-	-	-		
A7*	-	-	-	-	-	1	

(b) Dominating Interaction Matrix of Action for Performance (P2*) P3 (with Fig. 3 Transitive interaction graph)

	A1*	A2*	A3*	A4*	A5*	A6*	A7*
A1*		1	1	0	0	1	0
A2*	-		0	-	0	1	-
A3*	-	-			-	1	-
A4*	-	1	0		0	1	0
A5*	-	-	1	-		1	-
A6*	-	-	-	-	-		
A7*	-	1	1	-	1	1	

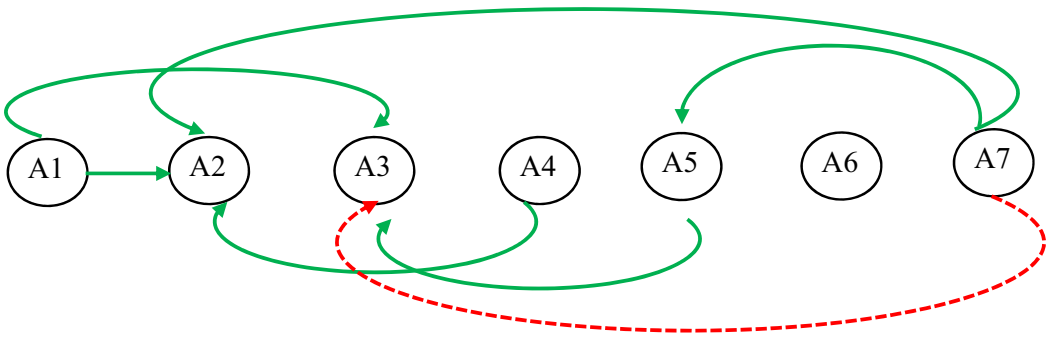


Figure 3

(c) Dominating Interaction Matrix of Action for Performance (P3*)

	A1*	A2*	A3*	A4*	A5*	A6*	A7*
A1*		1	1	0	1	1	1
A2*	-		0	-	0	0	0
A3*	-	-			0	0	0
A4*	-	1	1		1	1	1
A5*	-	-	-	-		0	0
A6*	-	-	-	-	-		0
A7*	-	-	-	-	-	-	

(d) Dominating Interaction Matrix of Action for Performance (P4*)

	A1*	A2*	A3*	A4*	A5*	A6*	A7*
A1*		1	1	0	-	1	0
A2*	-		1	0	-	0	0
A3*	-	-			-	0	-
A4*	-	-	1		-	1	0
A5*	1	1	1	1		1	1
A6*	-	-	-	-	-		-
A7*	-		1	-	-	1	

(e) Dominating Interaction Matrix of Action for Performance (P5*) P3 (with Fig. 4 Transitive interaction graph)

	A1*	A2*	A3*	A4*	A5*	A6*	A7*
A1*		1	1	0	1	-	1
A2*	-		0	0	1	-	1
A3*	-	-		0	1	-	1
A4*	-	-	-		1	-	0
A5*	-	-	-	-		-	-
A6*	1	1	1	1	1		1
A7*	-	-	-	-	1	-	

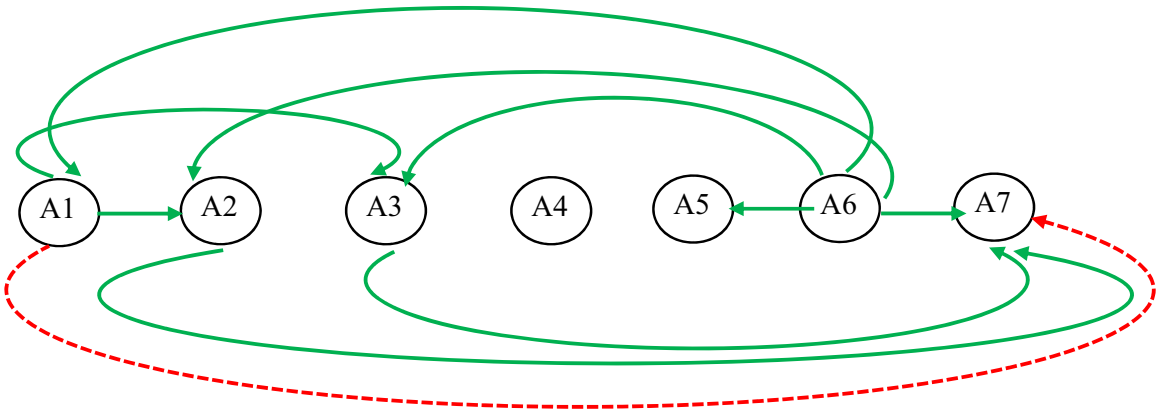


Figure 4

Implicit Dominance

Implicit Non-Dominance

Interpretive Dominance

Transitive Dominance

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Key Questions

1. How this study is useful in sensitizing various stakeholders for financial inclusion?
2. How the proposed model be used to increase the utilization of formal financial products and services in both rural and urban India?
3. What are the likely impact of various identified actors of financial inclusion in improving overall performance?



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